

Alois Švec

On the second covariant derivative of a vector field

Czechoslovak Mathematical Journal, Vol. 17 (1967), No. 1, 77–78

Persistent URL: <http://dml.cz/dmlcz/100761>

Terms of use:

© Institute of Mathematics AS CR, 1967

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://dml.cz>

ON THE SECOND COVARIANT DERIVATIVE OF A VECTOR FIELD*)

ALOIS ŠVEC, Praha

(Received November 17, 1965)

We shall here introduce a geometrical signification of the operator $\nabla_X \nabla_Y K$, K being a fixed vector field. The proofs of the theorems are routine, and they are omitted.

1. Let B be a differentiable n -dimensional manifold with a linear connection Γ . Let $\tilde{\Gamma}$ be the affine connection canonically associated to Γ . K being a vector field on B , let $\tilde{\Gamma}_K$ be the affine connection associated to Γ and the tensor field ∇K ; see [1, p. 74]. Suppose $T = 0$, T being the torsion tensor of the connection $\tilde{\Gamma}$.

Let A^n be the tangent affine space of B at a fixed point $b \in B$, and let $\gamma : (-1, 1) \rightarrow B$ be a differentiable curve on B through the point b ; suppose, for example, $\gamma(0) = b$. Denote by $\gamma^* : (-1, 1) \rightarrow A^n$ (or $\gamma_K^* : (-1, 1) \rightarrow A^n$) the development of γ into A^n with respect to $\tilde{\Gamma}$ (or $\tilde{\Gamma}_K$ resp.).

Lemma. *There is a unique affine collineation $C_K : A^n \rightarrow A^n$ with the following property: γ being an arbitrary differentiable curve on B through the point b , we have $j_1(\gamma^*)(0) = j_1(C_K \gamma_K^*)(0)$; here, $j_s(F)(p)$ denotes the s -jet of the map F at the point p .*

Consider the tensor L_K of the type (1,2) given by $L_K(X, Y) = \nabla_Y \nabla_X K$. The geometrical significance of this tensor is given by the following

Theorem 1. *Let V_b be a fixed tangent vector of B at b , and let γ be any curve in B through b such that its development γ^* into A^n with respect to $\tilde{\Gamma}$ is tangent to V_b at the point b . Three cases are possible:*

(a) $L_K(V_b, V_b) = 0$, and we have $j_2(\gamma^*)(0) = j_2(C_K \gamma_K^*)(0)$.

(b) $L_K(V_b, V_b) = \alpha V_b$, α a real number $\neq 0$. We have $j_2(\gamma^*)(0) \neq j_2(C_K \gamma_K^*)(0)$, but there are neighborhoods $\Omega, \Omega' \subset (-1, 1)$ of 0 and a map $\mu : \Omega \rightarrow \Omega'$; $\mu(0) = 0$, $\mu'(0) \neq 0$; such that

$$(*) \quad j_2(\gamma^*|_{\Omega}) = j_2(C_K \gamma_K^* \mu)(0),$$

$\gamma^*|_{\Omega}$ being the restriction of γ^* on Ω .

*) This work was partly supported by the National Science Foundation through research projects at Brandeis University (Waltham, Mass., U.S.A.).

(c) The vectors $L_K(V_b, V_b) = V_b^*$ and V_b are linearly independent. There is no map μ such that (*) is valid. Let $A^{n-1} \subset A^n$ be any hyperplane such that its vector space does not contain the vectors V_b and V_b^* , and let us denote by $\pi: A^n \rightarrow A^{n-1}$ the projection of A^n onto A^{n-1} in the direction of V_b^* . We have $j_2(\pi\gamma^*)(0) = j_2(\pi C_K \gamma_K^*)(0)$.

2. In this section, we present two theorems concerning the possible decomposition of the operator $L_K(X, Y)$.

Let U be a fixed vector field on B . Denote by M_U the set of vector fields K on B with the following property: $K \in M_U$ if and only if the vector fields U and $L_K(X, Y)$ are linearly dependent for any vector fields X, Y on B .

Theorem 2. Let $K_1, K_2 \in M_U$. If $L_{K_1}(K_2, V) = L_{K_2}(K_1, V)$ or if $\nabla_U U$ and U are linearly dependent for each vector field V on B , then $[K_1, K_2] \in M_U$.

Further, let T be a fixed tensor field of the type (1,1) on B . Denote by N_T the set of all vector fields K on B with the following property: $K \in N_T$ if and only if the vector fields $T(V)$ and $L_K(V, V)$ are linearly dependent for each vector field V on B .

Theorem 3. Let $K_1, K_2 \in N_T$. If $L_{K_1}(K_2, V) = L_{K_2}(K_1, V)$ or $[(\nabla_U T)(V), T(V)] = 0$ for any vector fields U, V on B , then $[K_1, K_2] \in N_T$.

3. Finally, a result for compact Riemannian manifolds B based on the well known integral formula:

Theorem 4. Let g be a Riemannian metric on B and Γ be the associated connection. Let K be a vector field on B such that $L_K(V, V) = f(V, V)K$ for each vector field V on B , $f(V, W)$ being a real-valued bilinear function. If $f(V, V) \geq 0$ for each vector field V on B and B is compact, we have $\nabla K = 0$. Moreover, if $f(V, V) = 0$ implies $V = 0$ we have $K = 0$.

Bibliography

[1] K. Nomizu: Lie groups and differential geometry, Publ. of Math. Soc. of Japan, 1956.

Author's address: Praha 8 - Karlín, Sokolovská 83, ČSSR (Matematicko-fyzikální fakulta Karlovy university).

Резюме

ОБ ВТОРОЙ КОВАРИАНТНОЙ ПРОИЗВОДНОЙ ВЕКТОРНОГО ПОЛЯ

АЛОИС ШВЕЦ (Alois Švec), Прага

Дается геометрическое значение оператора $\nabla_Y \nabla_X K$, где K — данное векторное поле.