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SOME REMARKS ON THE AUTOMORPHISM GROUP
OF A COMPACT GROUP ACTION

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1. H^s -AUTOMORPHISMS

Let M be a compact n -dimensional manifold without boundary and G a compact Lie group which acts in a transitive way on M . Let $\mu : G \times M \rightarrow M$ be the group action, and let $\mu_a(m) \stackrel{\text{def}}{=} \mu(a, m)$, for each $a \in G, m \in M$.

We denote by $\mathcal{D}^s(M)$ the space of all diffeomorphisms of M of Sobolev class H^s , i.e., $f \in \mathcal{D}^s(M)$ if and only if f is bijective and $f, f^{-1} : M \rightarrow M$ are of class H^s . It is known [2], [3] that $\mathcal{D}^s(M)$ is a topological group and for $s > (n/2) + 1$ it is a Hilbert manifold whose tangent space at e , the identity of $\mathcal{D}^s(M)$, is given by $T_e(M) = \mathcal{X}^s(M)$ = the space of all H^s -vector fields on M . Moreover, if X is in $\mathcal{X}^s(M)$, $s > (n/2) + 1$, and $\{f_t\}$ is its flow, then f_t is a C^1 curve in $\mathcal{D}^s(M)$. More details and proofs can be found in [2] and [3].

Throughout the paper we suppose that $s > (n/2) + 1$, and that the Riemannian metric on M is invariant under the action of G .

1.1. Definition ([2]). An automorphism of class H^s is a diffeomorphism $f : M \rightarrow M$ of class H^s which is G -invariant.

We denote by $\mathcal{D}_G^s(M)$ the group of all H^s -automorphisms of the action, namely:

$$\mathcal{D}_G^s(M) = \{f \in \mathcal{D}^s(M) \mid \forall a \in G, \mu_a \circ f = f \circ \mu_a\}.$$

1.2. Remark. It is not difficult to see that $\mathcal{D}_G^s(M)$ is a subgroup of $\mathcal{D}^s(M)$ and also a C^∞ -manifold, whose tangent space at e is given by $T_e \mathcal{D}_G^s(M) = \{X \in \mathcal{X}^s(M) \mid X \text{ commutes with all infinitesimal generators of } \mu\}$.

2. G -INVARIANT FORMS OF CLASS H^s

Let $H^s A^p(M)$ be the space of p -differential forms on M endowed with the H^s -topology, i.e., with the topology given by the inner product

$$(\alpha, \beta)_s = \int_M \alpha \wedge * \beta + \int_M (d + \delta)^s \alpha \wedge *(d + \delta)^s \beta,$$

where $\alpha, \beta \in H^s A^p(M)$, $*$: $H^s A^p(M) \rightarrow H^s A^{n-p}(M)$ is the “star” Hodge operator and $\delta : H^s A^p(M) \rightarrow H^{s-1} A^{p-1}(M)$ is the adjoint of d with respect to the inner product $(\cdot)_s$, given on p -forms by

$$\delta \stackrel{\text{def}}{=} (-1)^{(p+1)+1} * d *^{-1}.$$

The action of G on M determines in a natural way an action of G on $H^s A^p(M)$, and we have

2.1. Definition. $\omega \in H^s A^p(M)$ is G -invariant iff for each $a \in G$, the following equality holds:

$$\mu_a^* \omega = \omega.$$

We denote by $H^s A_G^p(M)$ the space of G -invariant p -forms on M of class H^s .

As in the non-equivariant case, there is a natural relation between $\mathcal{X}_G^s(M)$ and $H^s A_G^1(M)$:

2.2. Proposition. *There is an isomorphism between $\mathcal{X}_G^s(M)$ and $H^s A_G^1(M)$.*

Proof. Let X be a G -invariant H^s -vector field on M . Then we can associate with X an 1-form \tilde{X} , where

$$\tilde{X}(Y) \stackrel{\text{def}}{=} g(X, Y),$$

$Y \in \mathcal{X}^s(M)$ and g is the Riemannian structure on M . Since this correspondence is a bijective one, it is enough to verify that X is G -invariant. For each $a \in G$, we successively have

$$\begin{aligned} \mu_a^* \tilde{X}(Y) &= \tilde{X}(\mu_a' Y) = g(X, \mu_a' Y) = g(\mu_a' X, \mu_a' Y) = \\ &= \mu_a^* g(X, Y) = g(X, Y) = \tilde{X}(Y), \end{aligned}$$

and then $\tilde{X} \in H^s A_G^1(M)$.

q.e.d.

2.3. Theorem (*G -invariant version of Hodge decomposition theorem*). *Let $\omega \in H^s A_G^p(M)$. Then there are $\alpha \in H^{s+1} A_G^{p-1}(M)$, $\beta \in H^{s+1} A_G^{p+1}(M)$, $\gamma \in C^\infty A_G^p(M)$, $\Delta\gamma = 0$, such that*

$$\omega = d\alpha + \delta\beta + \gamma.$$

Furthermore, $d\alpha$, $\delta\beta$ and γ are H^s -orthogonal and hence uniquely determined.

Proof. By the classical Hodge theorem [2], there are $\alpha \in H^{s+1} A^{p-1}(M)$, $\beta \in H^{s+1} A^{p+1}(M)$ and $\gamma \in C^\infty A^p(M)$, $\Delta\gamma = 0$, such that

$$\omega = d\alpha + \delta\beta + \gamma.$$

Now using the invariance of the metric under the action of G and Watson’s theorem [5] we conclude that α, β, γ are G -invariant.

q.e.d.

2.4. Remark. We can also answer the following question. Given a G -invariant p -form ω , under what conditions is there a G -invariant p -form η such that the equation

$$\Delta\eta = \omega$$

is satisfied? The answer is : if and only if

$$(\gamma, \omega)_0 = 0$$

for every G -invariant harmonic form γ .

Indeed, suppose that $\omega = \Delta\eta$ and γ is harmonic. Then

$$(\gamma, \omega)_0 = (\gamma, \Delta\eta)_0 = (\Delta\gamma, \eta)_0 = (0, \eta)_0 = 0.$$

On the other hand, suppose ω is a G -invariant form satisfying $(\gamma, \omega) = 0$ for each G -invariant harmonic form γ . From the decomposition

$$\omega = d\alpha + \delta\beta + \gamma$$

we have, using the particular γ which is part of ω ,

$$\begin{aligned} 0 &= (\gamma, \omega)_0 = (\gamma, d\alpha)_0 + (\gamma, \delta\beta)_0 + (\gamma, \gamma)_0 = \\ &= (\delta\gamma, \alpha)_0 + (d\gamma, \beta)_0 + (\gamma, \gamma)_0 = (\gamma, \gamma)_0 ; \end{aligned}$$

hence $\gamma = 0$, $\omega = d\alpha + \delta\beta$.

We set $\eta = \mu + \gamma$ and try to solve $\Delta\mu = d\alpha$, $\Delta\gamma = \delta\beta$ separately. First we take

$$\Delta\mu = d\alpha.$$

Decomposing α we have

$$\begin{aligned} \alpha &= d\alpha_1 + \delta\beta_1 + \gamma_1, \\ d\alpha &= d\delta\beta_1. \end{aligned}$$

Further,

$$\begin{aligned} \beta_1 &= d\alpha_2 + \delta\beta_2 + \gamma_2, \\ d\delta\beta_1 &= d\delta d\alpha_2 = (d\delta + \delta d)(d\alpha_2) = \Delta(d\alpha_2), \\ d\alpha &= \Delta\mu \quad \text{with} \quad \mu = d\alpha_2. \end{aligned}$$

We find γ similarly.

For us, one of the most important consequences of the above theorem is the following

2.5. Proposition. *Let X be a G -invariant H^s -vector field on M . Then there are a unique G -invariant divergence free H^s -vector field Y and a G -invariant gradient H^s -vector field $\text{grad}(p)$ such that*

$$X = Y + \text{grad}(p).$$

Moreover, when setting $P(X) \stackrel{\text{def}}{=} Y$, P is a bounded linear operator from $\mathcal{X}_G^s(M)$ to the space of G -invariant vector fields with free divergence.

Proof. The first part is an immediate consequence of the above proposition. Indeed, in terms of the corresponding G -invariant 1-form \tilde{X} we write

$$\tilde{X} = d\alpha + \delta\beta + \gamma$$

and set $d\alpha = dp$, $\tilde{Y} = \delta\beta + \gamma$. Since $\delta^2 = 0$, $\delta\tilde{Y} = 0$ it follows that $\operatorname{div} Y = 0$. For the second part we can use the general technique of Ebin-Marsden [2].

q.e.d.

We close this section with a proposition which will be very useful in the next section:

2.6. Proposition. *Let ω be a G -invariant volume form on M . Then we have the isomorphism*

$$\{X \lrcorner \omega \mid X \in \mathcal{X}_G^s(M)\} \simeq H^{s+1} A_G^{n-1}(M).$$

Proof. By the classical theory of differential forms, for each $\alpha \in H^{s+1} A_G^{n-1}(M)$ there exists $X \in \mathcal{X}^s(M)$ such that $X \lrcorner \omega = \alpha$. Hence it is enough to prove that X is G -invariant. But for each $a \in G$ we successively have

$$X \lrcorner \omega = \alpha = \mu_a^* \alpha = \mu_a^*(X \lrcorner \omega) = \mu_a' X \lrcorner \omega,$$

and hence X is G -invariant.

q.e.d.

3. VOLUME PRESERVING AUTOMORPHISMS

Let ω be a G -invariant H^s -volume form on M and $\mathcal{D}_{G,\omega}^s(M)$ the subgroup of $\mathcal{D}_G^s(M)$ of all ω -preserving H^s -automorphisms:

$$\mathcal{D}_{G,\omega}^s(M) = \{f \in \mathcal{D}_G^s(M) \mid f^*\omega = \omega\}.$$

This group is important in the study of flows with various symmetries (e.g. a flow in \mathbb{R}^3 that is symmetric with respect to a given axis).

Now it is easy to see that $\mathcal{D}_{G,\omega}^s(M) = \mathcal{D}_\omega^s(M) \cap \mathcal{D}_G^s(M)$. Since this intersection is in general not transversal, it is not obvious that $\mathcal{D}_{G,\omega}^s(M)$ is a submanifold of $\mathcal{D}_G^s(M)$. However, we shall prove that this is the case. More precisely, we have

3.1. Theorem. $\mathcal{D}_{G,\omega}^s(M)$ is a closed Hilbert submanifold of $\mathcal{D}_G^s(M)$.

Proof. Using the G -invariant version of Hodge theorem we have that the cohomology class of ω ,

$$[\omega]_s = \omega + d(H^{s+1} A_G^{n-1}(M)),$$

is a closed affine subspace of $H^s A_G^n(M)$.

Define the map

$$\psi_G : f \in \mathcal{D}_G^{s+1}(M) \rightarrow \psi_G(f) \stackrel{\text{def}}{=} f^*(\omega) \in [\omega]_s.$$

It is easy to see that

$$\psi_G^{-1}(\omega) = \mathcal{D}_{G,\omega}^s(M),$$

and then $\mathcal{D}_{G,\omega}^s(M)$ is a C^∞ -submanifold of $\mathcal{D}_G^s(M)$ if we prove that ψ_G is a submersion. To this end it is enough to observe that

$$Te \psi_G(X) = d(X \lrcorner \omega),$$

and hence $Te \psi_G$ is onto by Proposition 2.6.

q.e.d.

In the sequel we shall try to understand other topological properties of the group $\mathcal{D}_G^s(M)$. We begin with a G -invariant version of the Moser theorem:

3.2. Theorem. *Let $\mathcal{V}_G^s(M) = \{\gamma \in H^s A_G^n(M) \mid \int_M \gamma > 0, \int_M \gamma = \int_M \omega\}$. Then there is a map $\chi_G, \chi_G : \mathcal{V}_G^s(M) \rightarrow \mathcal{D}_G^s(M)$ such that*

$$\psi_G \circ \chi_G = \text{identity}.$$

Proof. Let $v \in \mathcal{V}_G^s(M)$ and $v_t = tv + (1-t)\omega$, so that $v_t \in \mathcal{V}_G^s(M)$. Since $\int_M v = \int_M \omega$, we have $\omega - v = d\alpha$. Define X_t by $X_t \lrcorner v_t = \alpha$. Then it is easy to see that $X_t \in \mathcal{X}_G^s(M)$. Let $\{\varphi_t\}$ be the flow of X_t . Since X_t is G -invariant it follows that the flow $\{\varphi_t\}$ of X_t is G -invariant so that $\varphi_t \in \mathcal{D}_G^s(M)$. Now, it is enough to take

$$\chi_G(v) = \varphi_1^{-1},$$

and we obtain the desired result.

q.e.d.

Using the classical observation of R. Palais [4] that the topology of $\mathcal{D}_G^s(M)$ and $\mathcal{D}_G(M)$ (i.e. the group of C^∞ - G -invariant diffeomorphisms of M) is the same, we can deduce from the above theorem the following result.

3.3. Theorem. *(G -invariant version of Omori theorem). $\mathcal{D}_G(M)$ is diffeomorphic to $\mathcal{D}_{G,\omega}(M) \times \mathcal{V}_G(M)$. In particular, $\mathcal{D}_{G,\omega}(M)$ is a deformation retract of $\mathcal{D}_G(M)$.*

Proof. For the proof it is enough to observe that ϕ defined by

$$\phi(f, v) \stackrel{\text{def}}{=} f \circ \chi_G(v)$$

gives the desired diffeomorphism.

q.e.d.

In [1] W. Curtis showed that if the action of G is free, then there is a G -invariant spray on $\mathcal{D}_G(M)$. Using this result and the same technique as in [2] we can build a G -invariant spray on $\mathcal{D}_{G,\omega}(M)$. More precisely, we have

3.4. Theorem. *If Z_G is a G -invariant spray on $\mathcal{D}_G(M)$, then $S_G(X) \stackrel{\text{def}}{=} TP(Z_G \circ X)$ is a G -invariant spray on $\mathcal{D}_{G,\omega}(M)$, where P is defined as in Proposition 2.5.*

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