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COMPUTING THE DETERMINANTAL REPRESENTATIONS OF HYPERBOLIC FORMS

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Dedicated to the memory of Professor Miroslav Fiedler

Abstract. The numerical range of an $n \times n$ matrix is determined by an n degree hyperbolic ternary form. Helton-Vinnikov confirmed conversely that an n degree hyperbolic ternary form admits a symmetric determinantal representation. We determine the types of Riemann theta functions appearing in the Helton-Vinnikov formula for the real symmetric determinantal representation of hyperbolic forms for the genus g = 1. We reformulate the Fiedler-Helton-Vinnikov formulae for the genus g = 0, 1, and present an elementary computation of the reformulation. Several examples are provided for computing the real symmetric matrices using the reformulation.

Keywords: determinantal representation; hyperbolic form; Riemann theta function; numerical range

MSC 2010: 14Q05, 15A60

1. INTRODUCTION

Let T be an $n \times n$ complex matrix. The numerical range of T is defined as the set

$$W(T) = \{ \xi^* T \xi \colon \xi \in \mathbb{C}^n, \ \xi^* \xi = 1 \}.$$

The range W(T) is a convex set due to the famous Toeplitz-Hausdorff theorem. Kippenhahn [12] characterized W(T) as the convex hull of the real affine part of the

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dual projective curve of $F_T(x, y, z) = 0$, where the real ternary form associated with T is given by

$$F_T(x, y, z) = \det(x\Re(T) + y\Im(T) + zI_n),$$

and $\Re(T) = (T + T^*)/2$, $\Im(T) = (T - T^*)/(2i)$. Obviously, the equation $F_T(x_0, y_0, z) = 0$ in z has only real roots for any $(x_0, y_0) \in \mathbb{R}^2$ and $F_T(0, 0, 1) \neq 0$. The form $F_T(x, y, z)$ possessing this real roots property is called *hyperbolic* with respect to e = (0, 0, 1). Lax in [13] conjectured that an arbitrary ternary hyperbolic form F(x, y, z) with respect to $e = (e_1, e_2, e_3) \in \mathbb{R}^3$, $e \neq 0$, admits a determinantal representation, i.e.,

$$F(x, y, z) = c \det(xM_1 + yM_2 + zM_3)$$

for some real symmetric matrices M_1, M_2, M_3 with positive definiteness of $e_1M_1 + e_2M_2 + e_3M_3$, and $c \neq 0$. Independently, Fiedler in [8] made a similar conjecture under a relaxing condition that M_1, M_2, M_3 are Hermitian instead. Fiedler in [7] proved that the Lax conjecture is true provied that F(x, y, z) = 0 is a rational curve. Recently, Helton and Vinnikov in [10] confirmed that the Lax conjecture is true by using Riemann's theta functions. Based on the confirmation of the Lax conjecture, the authors of this paper in [4] proved that the *c*-numerical range of an $n \times n$ matrix T is reduced to the classical numerical range of an $m \times m$ matrix A, such that $W_c(T) = W(A)$ for some $m \leq n!$, and Helton and Spitkovsky in [9] proved that any matrix T has a symmetric matrix S satisfying W(T) = W(S).

The construction of real symmetric matrices from the Helton-Vinnikov theorem has attracted attention in studying the numerical range of matrices. One case, for instance, ask, whether the complex symmetric matrix S obtained by the Helton-Vinnikov formula from $F_T(x, y, z)$ is unitarily similar to a given matrix T. This question motivated us to compute explicitly the real symmetric matrices of the determinantal representation. In Section 2, we reformulate the formulae in [7], [10] for real symmetric matrices of the determinantal representations of hyperbolic forms with genus g = 0 or 1. Notice that the entries of the symmetric matrices M_j in the Lax conjecture have to be real. The Riemann theta functions in the Helton-Vinnikov formula may produce imaginary symmetric matrices. We determine the types of Riemann theta functions which lead to real symmetric expressions in the elliptic curve case. In Sections 3 and 4, we present concrete examples of 3×3 and 4×4 matrices, and compute the real symmetric matrices using the reformulation which illustrate the means of the Helton-Vinnikov formula for studying the numerical range of matrices.

2. Main theorems

Let F(x, y, z) be an irreducible ternary form of degree $n \ge 3$. A point $P_0 = (x_0, y_0, z_0)$ of the complex projective curve

$$\mathcal{V}_{\mathbb{C}}(F) = \{ [x, y, z] \in \mathbb{CP}^2 \colon F(x, y, z) = 0 \}$$

is called a singular point if

$$\frac{\partial F}{\partial x}(x_0, y_0, z_0) = \frac{\partial F}{\partial y}(x_0, y_0, z_0) = \frac{\partial F}{\partial z}(x_0, y_0, z_0) = 0$$

We sometimes abbreviate the complex projective curve $\mathcal{V}_{\mathbb{C}}(F)$ as F(x, y, z) = 0. For a singular point $P_0 = (x_0, y_0, z_0), z_0 \neq 0$, consider two functions

$$f(X,Y) = F(x_0 + X, y_0 + Y, z_0), \quad f_Y(X,Y) = F_Y(x_0 + X, y_0 + Y, z_0)$$

The Taylor series of these functions define an ideal (f, f_Y) of the ring $\mathbf{C}[[X, Y]]$ of formal power series in X, Y. We define

$$\delta(P_0) = \frac{1}{2} \left(\dim \left(\frac{\mathbf{C}[[X, Y]]}{(g, g_Y)} \right) - m + s \right),$$

where m is the multiplicity of P_0 and s is the number of irreducible analytic branches of the curve $\mathcal{V}_{\mathbb{C}}(F)$ near (x_0, y_0, z_0) . The number $\delta(P_0)$ is always a non-negative integer (cf. [14]). The genus of the curve F(x, y, z) = 0 is given by

$$g(F) = \frac{1}{2}(n-1)(n-2) - \sum_{j=1}^{k} \delta(P_j),$$

where P_1, \ldots, P_k are singular points of the curve F(x, y, z) = 0. An irreducible curve is called a rational curve or an elliptic curve if its genus is g = 0 or g = 1, respectively. A rational curve has a rational function parametrization, and an elliptic curve can be parametrized by an elliptic function and its derivative (cf. [17]).

In the formulation of the Helton-Vinnikov theorem, the following two objects play a crucial role:

- (i) The Riemann theta functions on a complex torus C^g/Γ, where Γ is a lattice in C^g.
- (ii) The Abel-Jacobi map φ of an irreducible algebraic curve with genus g to its corresponding Abel-Jacobi variety \mathbb{C}^g/Γ .

An accurate numerical computation method of the Riemann theta functions for $g \ge 1$ and a program to calculate a basis of Γ for an algebraic curve can be found in [5] and [6], respectively. In this paper, we mainly deal with two cases: g = 0 and g = 1. The first reason is that the general theory of Abel functions and Riemann theta functions for $g \ge 2$ is rather complicated. In contrast to this, for g = 1, the complex torus \mathbb{C}^g/Γ has an abelian fundamental group, and the Riemann functions have a single main variable. Shortly, the case g = 1 is more treatable. The second reason is more important from the viewpoint of developing the theory of numerical range. In [3], the authors of this paper proved that any irreducible curve $\mathcal{V}_{\mathbb{C}}(F)$ associated with a weighted shift matrix has genus $g \ge 1$, and in [1], they showed that the *j*-invariant of an irreducible elliptic curve associated with a 3×3 or 4×4 matrix is real and greater than or equal to 1. There are many tools for computing Riemann theta functions on a Riemann surface with g = 1. We used Mathematica (cf. [18]) to implement the numerical computations.

In the rest of this paper, we assume a real ternary form F(x, y, z) of degree *n* satisfying the following conditions:

- (F1) F(x, y, z) is hyperbolic with respect to e = (0, 0, 1) and F(0, 0, 1) = 1.
- (F2) F(x, y, z) is irreducible.
- (F3) The *n* real intersection points of the complex projective curve F(x, y, z) = 0and the line x = 0 are distinct non-singular points Q_1, \ldots, Q_n with coordinates $Q_j = (0, 1, -\beta_j)$, where $\beta_j \neq 0$.

According to the determinantal representation theorem [7], [10], there exist real symmetric matrices B and C of dimension n such that

(2.1)
$$F(x, y, z) = \det(zI_n + yB + xC),$$

where $B = \text{diag}(\beta_1, \ldots, \beta_n)$, and the diagonal entries c_{jj} of the real symmetric matrix C are given by

(2.2)
$$c_{jj} = \beta_j \frac{F_x(0, 1, -\beta_j)}{F_y(0, 1, -\beta_j)}$$

The crucial problem is the construction of the off-diagonal entries of C. If g = 0, 1, we denote by Q'_j the point on the parameter space (the real line for g = 0, the complex torus for g = 1) corresponding to Q_j . In the expression (2.1), if we replace C by

$$\widetilde{C} = \operatorname{diag}(\eta_1, \eta_2, \dots, \eta_n) C \operatorname{diag}(\eta_1, \eta_2, \dots, \eta_n)$$

 $(\eta_1, \eta_2, \ldots, \eta_n = \pm 1)$, we have another determinantal representation

$$F(x, y, z) = \det(zI_n + yB + x\widetilde{C}).$$

The choice of the sign pattern of the off-diagonal entries of C is determined for the case g = 0, and is open for g = 1. We reformulate Fiedler formula ([7], Theorem 1), for the determinantal representation if g = 0.

Theorem 2.1. Let F(t, x, y) be a ternary form of degree *n* satisfying conditions (F1)–(F3). Assume the genus of the complex projective curve F(x, y, z) = 0 is 0. Then the off-diagonal entries of *C* in the determinantal representation (2.1) are given by

(2.3)
$$c_{jk} = \varepsilon \frac{\beta_k - \beta_j}{Q'_k - Q'_j} \frac{1}{\sqrt{\left(d\left(\frac{R_1}{R_2}\right)(Q'_j)\right)\left(d\left(\frac{R_1}{R_2}\right)(Q'_k)\right)}}$$

where

$$x = R_1(s) = \frac{u(s)}{w(s)}, \quad y = R_2(s) = \frac{v(s)}{w(s)}$$

are real rational functions parametrizing the affine part F(x, y, 1) = 0, and $\varepsilon \in \{+1, -1\}$ satisfies $\varepsilon u'(Q'_j)v(Q'_j) > 0$ for all j.

Proof. It is shown in [7], Theorem 1, that we can choose $\varepsilon \in \{+1, -1\}$ such that $\varepsilon u'(Q'_i)v(Q'_i) > 0$ for all j. Further, we compute that

$$\frac{1}{\mathrm{d}\binom{R_1}{R_2}(Q'_j)} = \frac{1}{\mathrm{d}\binom{u}{v}(Q'_j)} = \frac{v(Q'_j)^2}{u'(Q'_j)v(Q'_j) - u(Q'_j)v'(Q'_j)} = \frac{v(Q'_j)}{u'(Q'_j)},$$

and hence the formula (2.3) essentially coincides with the formula obtained in [7], Theorem 1. $\hfill \Box$

The formulation in Theorem 2.1 is just a slight modification of Fiedler formula. This reformulation is be consistent with the formula pattern in Theorem 2.4 for the case g = 1.

The Helton-Vinnikov Formula in [10], Theorem 2.2 (see also [15], Theorem 6), for a hyperbolic form with genus g reads as follows:

Theorem 2.2. Let F(x, y, z) be a ternary form of degree *n* satisfying conditions (F1)–(F3). Assume the genus of the complex projective curve F(x, y, z) = 0 is $g \ge 1$. Then the off-diagonal entries of *C* in the determinantal representation (2.1) are given by

$$c_{jk} = \frac{\beta_k - \beta_j}{\theta[\delta](0)} \frac{\theta[\delta](\varphi(Q_k) - \varphi(Q_j), S)}{E(\varphi(Q_k), \varphi(Q_j))} \frac{1}{\sqrt{\mathrm{d}(\frac{x}{y})(Q'_j)}\sqrt{\mathrm{d}(\frac{x}{y})(Q'_k)}},$$

where $\theta[\delta](\cdot, \cdot)$ is a Riemann theta function with an even characteristic δ , $E(\cdot, \cdot)$ is the prime form on the Jacobi-variety given as a constant multiple of a Riemann theta function $\theta[\varepsilon](\cdot, \cdot)$ with an odd characteristic ε , the two Riemann theta functions are defined for $(z, S) \in \mathbb{C}^g \times \mathcal{H}_g$, the matrix S is determined by the curve $\mathcal{V}_{\mathbb{C}}(F)$, φ is the Abel-Jacobi map from $\mathcal{V}_{\mathbb{C}}(F)$ into the Jacobian variety, and Q'_j is the point on the Riemann surface corresponding to Q_j . Symbol \mathcal{H}_g denotes the set of the $g \times g$ Riemann matrices, i.e., symmetric matrices whose imaginary parts are positive definite.

The Helton-Vinnikov formula in Theorem 2.2 involves computing the Riemann theta functions and Abel-Jacobi maps. The Riemann theta functions are explicit, but the non-explicitness arises because of the complexity in computation when the genus satisfies $g \ge 2$. For instance, we have a quartic curve with integral coefficients and g = 2 for which the computation of the Riemann matrix S is not possible by the usual software. We restrict our attention to the case g = 1, and reformulate Theorem 2.2 using Riemann theta functions with a single main variable, and the Weierstrass canonical forms of non-singular cubic curves.

Let F(t, x, y) be a ternary form satisfying conditions (F1)–(F3) with genus g = 1, i.e., $\mathcal{V}_{\mathbb{C}}(F)$ is an elliptic curve. Then there is a real birational transformation Φ for which $\Phi(\mathcal{V}_{\mathbb{C}}(F))$ is a non-singular cubic curve of the Weierstrass standard form

$$Y^2 Z = 4X^3 - g_2 X^2 Z - g_3 Z^3$$

for some real constants g_2 , g_3 such that $g_2^3 - 27g_3^2 > 0$. The complex affine algebraic curve $Y^2 = 4X^3 - g_2X - g_3$ is parametrized as

$$X = \mathcal{P}(s: g_2, g_3), \quad Y = \mathcal{P}'(s: g_2, g_3),$$

where $\mathcal{P}(s: g_2, g_3)$ and $\mathcal{P}'(s: g_2, g_3)$ are the Weierstrass *P*-functions and its derivative with parameters g_2, g_3 satisfying the differential equation

$$\left(\frac{\mathrm{d}\mathcal{P}'}{\mathrm{d}s}\right)^2 = 4\mathcal{P}^3(s:\ g_2,g_3) - g_2\mathcal{P}(s:\ g_2,g_3) - g_3.$$

The meromorphic function $\mathcal{P}(s: g_2, g_3)$ on the Gaussian plane \mathbb{C} has two linearly independent half-periods ω_1 and ω_2 in the sense that

$$\mathcal{P}(s+2\omega_1: g_2, g_3) = \mathcal{P}(s: g_2, g_3)$$
 and $\mathcal{P}(s+2\omega_2: g_2, g_3) = \mathcal{P}(s: g_2, g_3),$

where ω_1 is a positive real number and w_2 is a purely imaginary number with $\Im(\omega_2) > 0$ (cf. [1]). The τ -invariant of the curve $\mathcal{V}_{\mathbb{C}}(F)$ is defined by $\tau = \omega_2/\omega_1$.

The real affine part F(x, y, 1) = 0 of the curve $\mathcal{V}_{\mathbb{C}}(F)$ is then parametrized as

(2.4) {
$$(x, y, 1) = (R_1(\mathcal{P}(u), \mathcal{P}'(u)), R_2(\mathcal{P}, \mathcal{P}'(u)), 1)$$
: $\Im(u) = 0, \ 0 < \Re(u) < 2\omega_1 \text{ or}$
 $\Im(u) = \Im(\omega_2), \ 0 \leqslant \Re(u) \leqslant 2\omega_1$ }

by real rational functions R_1, R_2 of \mathcal{P} and \mathcal{P}' over the torus \mathbb{T} . This parametrization $s \mapsto (x, y, 1)$ is the inverse of the Abel-Jacobi map $\varphi \colon \mathcal{V}_{\mathbb{C}}(F) \to \operatorname{Jac}(X)$.

Denote by \mathcal{H} the upper half-plane $\mathcal{H} = \{z \in \mathbb{C} : \Im(z) > 0\}$. The *Riemann theta* function is the holomorphic function on $\mathbb{C} \times \mathcal{H}$ defined by the exponential series

$$\theta(u,\tau) = \sum_{m \in \mathbb{Z}} \exp(\pi i (m^2 \tau + 2mu)),$$

which is quasi-periodic with respect to the lattice $\mathbb{Z} + \tau \mathbb{Z} \subset \mathbb{C}$:

$$\theta(u+m+\tau n,\tau) = \exp(\pi i(-2nu-n^2\tau))\,\theta(u,\tau)$$

for all integers m, n. We consider four Riemann theta functions $\theta[\varepsilon](u)$ with characteristics ε defined as

$$\theta[\varepsilon](u,\tau) = \exp(\pi i (a^2\tau + 2au + 2ab))\theta(u + \tau a + b,\tau)$$

for $\varepsilon = a + \tau b$ with

$$(a,b) = (0,0), \left(\frac{1}{2},0\right), \left(0,\frac{1}{2}\right), \left(\frac{1}{2},\frac{1}{2}\right)$$

Using the parameter $q = \exp(i\pi\tau)$, we have

$$\theta(u, [q]) = \theta(u, \tau) = \sum_{m \in \mathbb{Z}} q^{m^2} \exp(2m\pi i u).$$

The four Riemann theta functions are also denoted as

$$\begin{aligned} \theta_1(u,[q]) &= -\theta \Big[\frac{1}{2}, \frac{1}{2} \Big](u,\tau) = 2q^{1/4} \sum_{m=0}^{\infty} q^{(m+1)m} \sin((2m+1)\pi u), \\ \theta_2(u,[q]) &= \theta \Big[\frac{1}{2}, 0 \Big](u,\tau) = 2q^{1/4} \sum_{m=0}^{\infty} q^{(m+1)m} \cos((2m+1)\pi u), \\ \theta_3(u,[q]) &= \theta \big[0, 0 \big](u,\tau) = \theta(u,\tau) = 1 + 2 \sum_{m=1}^{\infty} q^{m^2} \cos(2m\pi u), \\ \theta_4(u,[q]) &= \theta \Big[0, \frac{1}{2} \Big](u,\tau) = 1 + 2 \sum_{m=1}^{\infty} (-1)^m q^{m^2} \cos(2m\pi u). \end{aligned}$$

For references on the Weierstrass P-functions and Riemann theta functions, one may see, for instance, [11], [17].

Theorem 2.3. The four Riemann theta functions θ_{δ} , $\delta = 1, 2, 3, 4$, are quasiperiodic, and the elliptic functions θ_{δ}/θ_1 , $\delta = 2, 3, 4$ have respective double periods 1, 2τ ($\delta = 2$), 2, 2τ ($\delta = 3$), 2, τ ($\delta = 4$). Moreover, the function θ_4/θ_1 takes on real values on the real part of the Jacobian variety, and the functions θ_2/θ_1 , θ_3/θ_1 take on real values or purely imaginary values depending on the two connected components of the real part of the Jacobi variety.

Proof. Direct computations show that

$$\begin{split} \theta_1(u+1,[q]) &= -\theta_1(u,[q]), \quad \theta_1(u+\tau,[q]) = -q^{-1}\exp(-2\pi i u)\theta_1(u,[q]), \\ \theta_2(u+1,[q]) &= -\theta_2(u,[q]), \quad \theta_2(u+\tau,[q]) = q^{-1}\exp(-2\pi i u)\theta_2(u,[q]), \\ \theta_3(u+1,[q]) &= \theta_3(u,[q]), \quad \theta_3(u+\tau,[q]) = q^{-1}\exp(-2\pi i u)\theta_3(u,[q]), \\ \theta_4(u+1,[q]) &= \theta_4(u,[q]), \quad \theta_4(u+\tau,[q]) = -q^{-1}\exp(-2\pi i u)\theta_4(u,[q]). \end{split}$$

Thus the functions θ_{δ}/θ_1 , $\delta = 2, 3, 4$, are elliptic functions with double periods 1, 2τ ($\delta = 2$), 2, 2τ ($\delta = 3$), 2, τ ($\delta = 4$).

Suppose that τ is a purely imaginary number. Then the four functions $\theta_{\delta}(u, [q])$ take on real values on the real line. On the line $\Im(z) = \Im(\tau)/2$, we have

$$\frac{\theta_4}{\theta_1}\left(u+\frac{\tau}{2}\right) = \frac{\theta_1}{\theta_4}(u),$$

and

$$\frac{\theta_2}{\theta_1}\left(u+\frac{\tau}{2}\right) = -\mathrm{i}\frac{\theta_3}{\theta_4}(u), \quad \frac{\theta_3}{\theta_1}\left(u+\frac{\tau}{2}\right) = -\mathrm{i}\frac{\theta_2}{\theta_4}(u)$$

for any $u \in \mathbb{R}$. Hence, θ_2/θ_1 , θ_3/θ_1 take on either real or purely imaginary values on the real part of the Jacobi variety.

Using the notation of Theorem 2.3, we reformulate the Helton-Vinnikov Formula in [10], Theorem 2.2, (cf. [15], Theorem 6) for g = 1, and determine the types of Riemann theta functions which lead to real symmetric determinantal representations.

Theorem 2.4. Let F(t, x, y) be a ternary form of degree *n* satisfying conditions (F1)–(F3). Assume the genus of the complex projective curve F(x, y, z) = 0 is 1, and $x = R_1(\mathcal{P}(u), \mathcal{P}'(u)), y = R_2(\mathcal{P}, \mathcal{P}'(u))$ parametrize the elliptic curve $\mathcal{V}_{\mathbb{C}}(F)$ in (2.4). Let $Q'_j = \varphi(Q_j)$ be the point of the torus \mathbb{T} corresponding to the point $Q_j \in \mathcal{V}_{\mathbb{C}}(F)$. For $\delta = 2, 3$, the matrix C in the determinantal representation (2.1) is real symmetric, and its off-diagonal entries are given by

(2.5)
$$c_{jk} = \frac{(\beta_k - \beta_j)\theta'_1(0)}{2\omega_1 \theta_\delta(0)} \frac{\theta_\delta((Q'_k - Q'_j)/2\omega_1)}{\theta_1((Q'_k - Q'_j)/2\omega_1)} \frac{1}{\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q'_j)}\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q'_k)}}$$

Proof. We use a non-normalized Jacobi variety $\mathbb{C}/(\mathbb{Z}\mathbb{Z}\omega_1 + 2\mathbb{Z}\omega_2)$ in place of the normalized Jacobi variety $\mathbb{C}/(\mathbb{Z}+\tau\mathbb{Z})$ for $\tau = \omega_2/\omega_1$. According to this frame, we easily use the Weierstrass *P*-function to express the inverse of the Abel-Jacobi map φ . By this parameter change, a new factor $1/(2\omega_1)$ appears in the formulation (2.5). For g = 1, the Riemann theta function with an odd characteristic is uniquely given by $\theta_1(\cdot)$. As the prime form $E(\cdot, \cdot)$, it generates the term $\theta_1((Q'_k - Q'_j)(2\omega_1)^{-1})/\theta'_1(0)$ in (2.5). The Riemann theta function $\theta[\delta](\cdot)$ with an even characteristic appearing in (2.5), is given by θ_2, θ_3 or θ_4 .

We claim that $\delta = 4$ produces an imaginary C in (2.1). For a real parameter θ , we consider the equation $F(-\cos\theta, -\sin\theta, z) = 0$ in z. By the hyperbolicity of F(x, y, z), this equation has n real roots $z_i(\theta)$ counting multiplicities. In particular, for $\theta = -\pi/2$, the *n* distinct real roots are $Q_j = (0, 1, -\beta_j), j = 1, 2, \dots, n$. By the Helton-Vinnikov theorem and Rellich's theorem, the roots $z_i(\theta)$ of the equation depend analytically on θ . Every real point of the curve $\mathcal{V}_{\mathbb{C}}(F)$ is joined to some Q_i . By a birational transformation, each point Q_j is mapped to Q'_j on a non-singular cubic curve, and the curve $z_i(\theta)$ is mapped to the real part of the cubic curve consisting of a pseudo line and an oval. The image of $z_i(\theta)$ covers the real part of the cubic curve except for a finite number of points. There are $j \neq k$ for which Q'_j lies on the pseudo line and Q'_k lies on the oval. We use the same symbol Q'_i for the point on the non-normalized torus $\mathbb{C}/(2\omega_1\mathbb{C}+2\omega_2\mathbb{Z})$ corresponding to the point Q'_j on the cubic curve. Then $\Im(Q'_i) = 0$ and $\Im(Q'_k) = \Im(\omega_2)$, and thus $\sqrt{\mathrm{d}(x/y)(Q'_i)}\sqrt{\mathrm{d}(x/y)(Q'_k)}$ is purely imaginary. Hence, the entries c_{jk} in (2.5) are real if and only if the ratio $\theta_{\delta}((Q'_k-Q'_j)(2\omega_1)^{-1})/\theta_1((Q'_k-Q'_j)(2\omega_1)^{-1}))$ of a purely imaginary value. This happens only for $\delta = 2, 3$, by Theorem 2.3, since $\Im(Q'_k - Q'_i) = \Im(\omega_2)$. The case $\delta = 4$ results in complex entries of C.

Remarks. 1. Applying the formulae mentioned in the proof of Theorem 2.3, we find that the function θ_{δ}/θ_1 on the normalized torus $\mathbb{C}/(\mathbb{Z} + \tau\mathbb{Z})$ is defined up to multiplicative constants ± 1 .

2. For g = 1, the advantage of the formulation (2.5) is that the torus \mathbb{C}^g/Γ is a one-dimensional analytic manifold which is realized as a complex projective curve $\mathcal{V}_{\mathbb{C}}(G)$ for some ternary form G using a birational transformation.

3. Plaumann et al. mentioned in [15], page 270, that they do not know why sometimes the off-diagonal entries of C are wrong by a constant factor when applying the Helton-Vinnikov formula. The authors of this paper are not able to fix their problem, but the formulation in Theorem 2.4 for g = 1 has no such trouble.

4. It is also shown in [15], Theorem 7, that for a smooth curve $\mathcal{V}_{\mathbb{C}}(f)$ there are 2^g real positive definite representations. We prove in Theorem 2.4 that for an elliptic curve (g = 1) with singular points (non-smooth), there are $2 = 2^g$ real positive definite representations.

In Theorems 2.1 and 2.4, we use a parametrization of an irreducible projective algebraic curve F(x, y, z) = 0. An irreducible curve F(x, y, z) = 0 is transformed into an algebraic curve G(x, y, z) = 0 for which every singular point $(x_0, y_0, z_0) \neq (0, 0, 0)$ of G(x, y, z) = 0 has pairwise distinct tangents by successive Cremona transformations (cf. [16], Theorem 7.4). Such a birational transformation preserves the genus of the curve. We assume that G(x, y, z) is an irreducible homogeneous polynomial of degree n, the curve G(x, y, z) = 0 has ordinary multiple points of multiplicities m_1, \ldots, m_k and has no singular points other than the ordinary ones. Then the genus g of G(x, y, z) = 0 is given by

(2.6)
$$g = \frac{1}{2}(n-1)(n-2) - \frac{1}{2}\sum_{j=1}^{k} m_j(m_j-1)$$

(cf. [16]). The number g can be evaluated by the function 'genus' of algcurves package in Maple. For g = 0, the method of constructing a parametrization of the curve G(x, y, z) = 0 as x = u(s), y = v(s), z = w(s) of degree at most n is given in [16], pages 67–68. For g = 1, the curve G(x, y, z) = 0 is transformed into the Weierstrass canonical form

$$-y^2z + 4x^3 - g_2xz^2 - g_3 = 0$$

with $g_2^3 - 27g_3^2 \neq 0$. The affine curve G(x, y, 1) = 0 is then expressed as

$$x = R_1(\mathcal{P}, \mathcal{P}'), \quad y = R_2(\mathcal{P}, \mathcal{P}')$$

by some rational functions R_1 , R_2 of two variables (cf. [16], page 72, [17], pages 489–493). The Riemann theta functions $\theta_{\delta}(u, [q]), \delta = 1, 2, 3, 4$, can be numerically computed using Mathematica function 'EllipticTheta [$\delta, \pi u, q$]' (cf. [18]).

3. Computing rational curves

We explain the formula in Theorem 2.1 by practical computation on an algebraic curve with genus g = 0. Consider a typical roulette curve defined by a trigonometric polynomial

$$\varphi(\theta) = \exp(2i\theta) + \frac{4}{5}\exp(-i\theta).$$

The determinantal representation of this curve has been studied in [2]. We apply Theorem 2.1 to find the real symmetric matrices B and C. By using a parameter $s = \tan(\theta)/2$, this roulette curve is parametrized as

$$x = \Re(\varphi(\theta)) = \frac{u(s)}{w(s)}, \quad y = \Im(\varphi(\theta)) = \frac{v(s)}{w(s)},$$

where

$$u(s) = \frac{1}{5}(s^2 + 6s + 3)(s^2 - 6s + 3),$$

$$v(s) = -\frac{4}{5}(7s^2 - 3)s,$$

$$w(s) = (s^2 + 1)^2,$$

and the roulette curve as an affine curve F(x, y, 1) = 0 is parametrized as

$$L_1(x,s) = -(s^2+1)^2 x + \frac{1}{5}(s^2+6s+3)(s^2-6s+3) = 0,$$

$$L_2(y,s) = -(s^2+1)^2 y - \frac{4}{5}(7s^2-3)s = 0.$$

By taking the resultant of $L_1(x, s)$ and $L_2(y, s)$ with respect to s, we obtain the equation F(x, y, 1) = 0 of the roulette curve which, in homogeneous form, is expressed as

$$F(x,y,z) = \frac{15,625}{729}(x^2 + y^2)^2 - \frac{20,000}{729}(x^3z - 3xy^2z) - \frac{550}{27}(x^2 + y^2)z^2 + z^4.$$

Solving the equation $F(0, 1, -\beta_j) = 0$, we find that the matrix B is given by

$$B = \operatorname{diag}\left(\frac{5}{9}(-3+2\sqrt{6}), -\frac{5}{9}(3+2\sqrt{6}), \frac{5}{9}(3+2\sqrt{6}), -\frac{5}{9}(-3+2\sqrt{6})\right).$$

The corresponding points $Q'_j = s$ of the real line are characterized as

$$(s^{2} + 6s + 3)(s^{2} - 6s + 3) = 0, \quad -\frac{v(s)}{w(s)} = -\frac{1}{\beta_{j}}.$$

It follows that

$$Q'_1 = 3 + \sqrt{6}, \quad Q'_2 = 3 - \sqrt{6}, \quad Q'_3 = -3 + \sqrt{6}, \quad Q'_4 = -3 - \sqrt{6}.$$

We conclude by (2.3) that the matrix C and its entries are

$$C = \begin{bmatrix} -c_{22} & c_{12} & c_{13} & c_{14} \\ c_{12} & c_{22} & c_{23} & c_{13} \\ c_{13} & c_{23} & c_{22} & c_{12} \\ c_{14} & c_{13} & c_{12} & -c_{22} \end{bmatrix},$$

where

$$c_{22} = \frac{25\sqrt{2}}{9\sqrt{3}}, \quad c_{12} = -\frac{5\sqrt{10}}{9\sqrt{3}}, \quad c_{13} = \frac{5\sqrt{5}}{9\sqrt{6}},$$
$$c_{14} = -\frac{5}{9\sqrt{6}}\sqrt{73 + 28\sqrt{6}}, \quad c_{23} = \frac{5}{9\sqrt{6}}\sqrt{73 - 28\sqrt{6}}.$$

4. Computing elliptic curves

In the paper [1], the so-called *j*-invariant of an irreducible elliptic curve associated with the following 4×4 matrix is explicitly formulated. The 4×4 cyclic weighted shift matrix is

$$S = \begin{bmatrix} 0 & a_1 & 0 & 0 \\ 0 & 0 & a_2 & 0 \\ 0 & 0 & 0 & a_2 \\ a_1 & 0 & 0 & 0 \end{bmatrix},$$

where $a_1 = \sqrt{2}k(1-s^2)/(1+s^2)$, $a_2 = \sqrt{2}k(2s)/(1+s^2)$ for $0 < k, 0 < s < \sqrt{2}$. Then

$$(s^{2}+1)^{4}F_{S}(x,y,z) = (s^{2}+1)^{4}z^{4} - 2k^{2}(s^{2}+1)^{4}(x^{2}+y^{2})z^{2} + 16k^{4}s^{2}(s^{2}-1)^{2}(x^{2}+y^{2})^{2}.$$

This form is hyperbolic with respect to (0, 0, 1), and has two ordinary double points at (0, 1, 0) and (1, 0, 0). Accordingly, by the genus formula (2.6), $g(F_S) = 1$.

The curve $F_S(x, y, z) = 0$ intersects the line x = 0 at four distinct points $(0, 1, -\beta_j)$ with

$$\beta_1 = \sqrt{2k} \frac{1-s^2}{1+s^2}, \quad \beta_2 = -\beta_1, \quad \beta_3 = \sqrt{2k} \frac{2s}{1+s^2}, \quad \beta_4 = -\beta_3.$$

Then the diagonal matrix is $B = \text{diag}(\beta_1, \beta_2, \beta_3, \beta_4)$. The quartic form $F_S(x, y, z)$ has a rather simple symmetric determinantal representation

$$F(x, y, z) = \det(zI_4 + yB + xA_1),$$

where

$$A_{1} = \begin{bmatrix} 0 & 0 & \varepsilon a_{13} & a_{14} \\ 0 & 0 & \varepsilon a_{14} & a_{13} \\ \varepsilon a_{13} & a_{14} & 0 & 0 \\ \varepsilon a_{14} & a_{13} & 0 & 0 \end{bmatrix}$$

with

$$a_{13} = \frac{k(1+2s-s^2)}{\sqrt{2}(1+s^2)}, \quad a_{14} = \frac{k(1-2s-s^2)}{\sqrt{2}(1+s^2)}, \quad \varepsilon = \pm 1$$

For $k = 1/\sqrt{2}$ and s = 1/5, we have $a_{13} = \varepsilon 17/26$, $a_{14} = 7/26$. Another symmetric determinantal representation is given by

$$F_S(x, y, z) = \det(zI_4 + yB + xA_2),$$

where

$$A_{2} = \begin{bmatrix} 0 & \varepsilon a_{12} & \eta a_{13} & 0 \\ \varepsilon a_{12} & 0 & 0 & -\eta a_{13} \\ \eta a_{13} & 0 & 0 & \varepsilon a_{34} \\ 0 & -\eta a_{13} & \varepsilon a_{34} & 0 \end{bmatrix}$$

with

$$a_{12} = \frac{2\sqrt{2ks(1-2s-s^2)}}{(1+2s-s^2)(1+s^2)},$$

$$a_{13} = \frac{2\sqrt{2k}\sqrt{s(1-s^2)}}{1+2s-s^2},$$

$$a_{34} = -\frac{\sqrt{2k(1-s^2)(1-2s-s^2)}}{(1+2s-s^2)(1+s^2)}$$

 $\varepsilon, \eta = \pm 1$. For $k = 1/\sqrt{2}$ and s = 1/5, we have $a_{12} = 35/221$, $a_{34} = -84/221$, $a_{13} = 2\sqrt{30}/17$.

Now, we explain the computation of the formula in Theorem 2.4. To parametrize the curve $\mathcal{V}_{\mathbb{C}}(F_S)$ using elliptic functions, we introduce new variables U, V, W by

$$U = k(x^2 - y^2), \quad V = \frac{z(z - kx + ky)}{k}, \quad W = (z + kx - ky)(x + y).$$

The inverse of this birational transformation is given by

$$x = \frac{1}{2k}(2U^2 + UV - 3UW + W^2), \quad y = \frac{1}{2k}(2U^2 - UV - 3UW + W^2), \quad z = V(W - U).$$

The quartic curve $F_S(x, y, z) = 0$ is birationally transformed into the non-singular cubic curve G(U, V, W) = 0 where

$$\begin{split} G(U,V,W) &= (s^2+1)^4 W^3 - 4(s^2+1)^4 U W^2 + (5s^8+4s^6+62s^4+4s^2+5) U^2 W \\ &- 2(s^4-6s^2+1) U^3 - (s^2+1)^4 V^2 W. \end{split}$$

We perform numerical computations for $k = 1/\sqrt{2}$, s = 1/5. The points Q_j on the curve $F_S(x, y, z) = 0$ are transformed into the points

$$[Q_1] = \left(1, -\frac{50}{169} + \frac{5\sqrt{2}}{13}, 1 + \frac{5\sqrt{2}}{13}\right), \quad [Q_2] = \left(1, -\frac{50}{169} - \frac{5\sqrt{2}}{13}, 1 - \frac{5\sqrt{2}}{13}\right),$$
$$[Q_3] = \left(1, -\frac{288}{169} + \frac{12\sqrt{2}}{13}, 1 + \frac{12\sqrt{2}}{13}\right), \quad [Q_4] = \left(1, -\frac{288}{169} - \frac{12\sqrt{2}}{13}, 1 - \frac{12\sqrt{2}}{13}\right)$$

on the curve

$$G(U, V, W) = 16 (28,561W^3 - 114,244UW^2 + 128,405U^2W - 28,322U^3 - 28,561V^2W) = 0.$$

By the transformation

$$U = -\widetilde{U} + \frac{128,405}{84,966}W, \quad V = \frac{119}{169\sqrt{2}}\widetilde{V},$$

the cubic curve G(U, V, W) = 0 turns into the Weierstrass canonical form

$$-\tilde{V}^2W + 4\tilde{U}^3 - g_2\tilde{U}W^2 - g_3W^3 = 0$$

with

$$g_2 = \frac{6,780,988,321}{601,601,763}, \quad g_3 = -\frac{556,790,665,176,719}{76,673,543,092,587}$$

Thus the affine algebraic curve $F_S(x, y, 1) = 0$ is parametrized as

$$\begin{aligned} x &= R_1(u) = \frac{1}{10,110,954(84,966\mathcal{P}(u) - 43,439)\mathcal{P}'(u)} \\ &\times \left(-5,055,477\sqrt{2}(84,966\mathcal{P}(u) - 128,405)\mathcal{P}'(u) \right. \\ &+ 676(42,483\mathcal{P}(u) - 42,961)(84,966\mathcal{P}(u) - 43,439)\right), \end{aligned}$$
$$\begin{aligned} y &= R_2(u) = \frac{1}{10,110,954(84,966\mathcal{P}(u) - 43,439)\mathcal{P}'(u)} \\ &\times \left(5,055,477\sqrt{2}(84,966\mathcal{P}(u) - 128,405)\mathcal{P}'(u) \right. \\ &+ 676(4,2483\mathcal{P}(u) - 42,961)(84,966\mathcal{P}(u) - 43,439)\right). \end{aligned}$$

The half-periods of the Weierstrass P-function are approximately

$$\omega_1 = 1.849,847,0, \quad \omega_2 = 0.921,393,5i.$$

Their ratio $\tau = \omega_2/\omega_1$ is approximately 0.498,091,74i.

The cubic curve $-\widetilde{V}^2 + 4\widetilde{U}^3 - g_2\widetilde{U} - g_3 = 0$ is parametrized as

$$\widetilde{U} = \mathcal{P}(u, \{g_2, g_3\}), \quad \widetilde{V} = \mathcal{P}'(u, \{g_2, g_3\})$$

The cubic and the line $\widetilde{V}=0$ intersect at

$$(\widetilde{U}_1, 0) = \left(\frac{42,961}{42,483}, 0\right), \quad (\widetilde{U}_2, 0) = \left(\frac{78,719}{84,966}, 0\right), \quad (\widetilde{U}_3, 0) = \left(-\frac{16,4641}{84,966}, 0\right).$$

These three points correspond respectively to points $\omega_1, \omega_1 + \omega_2, \omega_2$ on the torus $\mathbb{C}/(2\omega_1\mathbb{Z} + 2\omega_2\mathbb{Z})$. The points Q_j are transformed into the points

$$\begin{split} \widetilde{Q}_1 &= \left(\frac{7,739}{84,966} + \frac{65\sqrt{2}}{119}, \frac{28,470}{14,161} - \frac{16,900\sqrt{2}}{14,161}, 1\right), \\ \widetilde{Q}_2 &= \left(\frac{7,739}{84,966} - \frac{65\sqrt{2}}{119}, -\frac{28,470}{14,161} - \frac{16,900\sqrt{2}}{14,161}, 1\right), \\ \widetilde{Q}_3 &= \left(\frac{249,071}{84,966} - \frac{156\sqrt{2}}{119}, -\frac{142,584}{14,161} + \frac{97,344\sqrt{2}}{14,161}, 1\right), \\ \widetilde{Q}_4 &= \left(\frac{249,071}{84,966} + \frac{156\sqrt{2}}{119}, \frac{142,584}{14,161} + \frac{97,344\sqrt{2}}{14,161}, 1\right) \end{split}$$

on the cubic curve $-\widetilde{V}^2W + 4\widetilde{U}^3 - g_2\widetilde{U}W^2 - g_3 = 0.$

The two points $\widetilde{Q}_3, \widetilde{Q}_4$ lie on the pseudo line of the real part of the cubic curve, and the two points $\widetilde{Q}_1, \widetilde{Q}_2$ lie on the oval of the real part of the cubic curve. Under the elliptic curve group operation

$$(\mathcal{P}(u_1), \mathcal{P}'(u_1)) + (\mathcal{P}(u_2), \mathcal{P}'(u_2)) = (\mathcal{P}(u_1 + u_2), \mathcal{P}'(u_1 + u_2)),$$

the points \widetilde{Q}_j satisfy

$$2\widetilde{Q}_1 = 2\widetilde{Q}_2 = 2\widetilde{Q}_3 = 2\widetilde{Q}_4 = \left(\frac{128,405}{84,966}, \frac{169\sqrt{2}}{119}\right).$$

We also have

$$2\left(\frac{128,405}{84,966},\frac{169\sqrt{2}}{119}\right) = \left(\frac{42,961}{42,483},0\right)$$

Then we find that the point of the torus $\mathbb{C}/(2\omega_1\mathbb{Z}+2\omega_2\mathbb{Z})$ corresponding to $2\widetilde{Q}_j$ is $3/2\omega_1$. Each difference $\widetilde{Q}_j - \widetilde{Q}_k$ $(j \neq k)$ satisfies

$$2(\widetilde{Q}_j - \widetilde{Q}_k) = 0$$

with respect to the elliptic curve group structure. By computing the tangent line passing through $\widetilde{Q}_j, \widetilde{Q}_k$, we find that

$$\begin{split} \widetilde{Q}_2 - \widetilde{Q}_1 &= \widetilde{Q}_4 - \widetilde{Q}_3 = (\widetilde{U}_1, 0), \\ \widetilde{Q}_3 - \widetilde{Q}_2 &= \widetilde{Q}_4 - \widetilde{Q}_1 = (\widetilde{U}_2, 0), \\ \widetilde{Q}_3 - \widetilde{Q}_1 &= \widetilde{Q}_4 - \widetilde{Q}_2 = (\widetilde{U}_3, 0). \end{split}$$

Using these relations, we find that the respective points on the torus $\mathbb{C}/(2\omega_1\mathbb{Z}+2\omega_2\mathbb{Z})$ and the normalized torus $\mathbb{C}/(\mathbb{Z}+\tau\mathbb{Z})$ are

$$Q'_1 = \frac{3}{4}\omega_1 + \omega_2, \quad Q'_2 = \frac{7}{4}\omega_1 + \omega_2, \quad Q'_3 = \frac{3}{4}\omega_1, \quad Q'_4 = \frac{7}{4}\omega_1,$$

and

$$Q_1'' = \frac{3}{8} + \frac{1}{2}\tau, \quad Q_2'' = \frac{7}{8} + \frac{1}{2}\tau, \quad Q_3'' = \frac{3}{8}, \quad Q_4'' = \frac{7}{8}.$$

Then the even Riemann theta functions θ_2 , θ_3 , θ_4 on the normalized Jacobi variety $\mathbb{C}/(\mathbb{Z} + \mathbb{Z}\tau)$ satisfy the equations

$$\begin{split} \theta_2(Q_2''-Q_1'') &= \theta_2(Q_4''-Q_3'') = \theta_2\left(\frac{1}{2}\right) = 0, \\ \theta_3(Q_1''-Q_4'') &= \theta_3\left(-\frac{1}{2}+\frac{\tau}{2}\right) = 0, \\ \theta_3(Q_2''-Q_3'') &= \theta_3\left(\frac{1}{2}+\frac{\tau}{2}\right) = 0, \\ \theta_4(Q_1''-Q_3'') &= \theta_4(Q_2''-Q_4'') = \theta_4\left(\frac{\tau}{2}\right) = 0. \end{split}$$

The elliptic functions θ_{δ}/θ_1 over the normalized Jacobi variety take on the following approximate values at the points $Q''_j - Q''_k$:

$$\begin{aligned} \frac{\theta_2}{\theta_1}(Q_3''-Q_1'') &= \frac{\theta_2}{\theta_1}(Q_4''-Q_2'') = \frac{\theta_2}{\theta_1}\left(-\frac{\tau}{2}\right) = 2.428,571,4i \approx \frac{17}{7} i, \\ \frac{\theta_2}{\theta_1}(Q_4''-Q_1'') &= \frac{\theta_2}{\theta_1}(Q_3''-Q_2'') = \frac{\theta_2}{\theta_1}\left(\pm\frac{1}{2}-\frac{\tau}{2}\right) = 0.411,764,71i \approx \frac{7}{17} i, \\ \frac{\theta_3}{\theta_1}(Q_2''-Q_1'') &= \frac{\theta_3}{\theta_1}(Q_4''-Q_3'') = \frac{\theta_3}{\theta_1}\left(\frac{1}{2}\right) = 0.414,778,33, \\ \frac{\theta_3}{\theta_1}(Q_3''-Q_1'') &= \frac{\theta_3}{\theta_1}(Q_4''-Q_2'') = \frac{\theta_3}{\theta_1}\left(-\frac{\tau}{2}\right) = 2.410,926,4i, \\ \frac{\theta_4}{\theta_1}(Q_2''-Q_1'') &= \frac{\theta_4}{\theta_1}(Q_4''-Q_3'') = \frac{\theta_4}{\theta_1}\left(\frac{1}{2}\right) = 1.007,318,8, \\ \frac{\theta_4}{\theta_1}(Q_4''-Q_1'') &= \frac{\theta_4}{\theta_1}\left(-\frac{1}{2}-\frac{\tau}{2}\right) = -0.992,734,38, \\ \frac{\theta_4}{\theta_1}(Q_4''-Q_1'') &= \frac{\theta_4}{\theta_1}\left(\frac{1}{2}-\frac{\tau}{2}\right) = 0.992,734,38. \end{aligned}$$

The numerical values of $\theta_1(0)$, $\theta_2(0)$, $\theta_3(0)$, $\theta_4(0)$ are given respectively by

3.693,259,2, 1.411,753,8, 1.422,086,2, 0.585,564,89.

The values $d(R_1/R_2)(Q'_j)$ are given numerically by

$$d\left(\frac{R_1}{R_2}\right)(Q_1') = d\left(\frac{R_1}{R_2}\right)(Q_2') = -d\left(\frac{R_1}{R_2}\right)(Q_3') = -d\left(\frac{R_1}{R_2}\right)(Q_4') = 1.414,213,6.$$

We then find that both the values

$$\frac{\theta_1'(0)}{2\omega_1\theta_2(0)} \frac{1}{\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q_1')}\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q_3')}}, \quad \frac{\theta_1'(0)}{2\omega_1\theta_2(0)} \frac{1}{\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q_1')}\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q_4')}},$$

are approximated by -0.500,000,000 i.

Now, for the main diagonals of C, it can be easily deduced from (2.2) that $c_{11} = c_{22} = c_{33} = c_{44} = 0$ for $\delta = 2, 3, 4$. We have the equations

$$\beta_3 - \beta_1 = \frac{12}{13} - \frac{5}{13} = \frac{7}{13}, \quad \beta_4 - \beta_2 = -(\beta_3 - \beta_1) = -\frac{7}{13}, \\ \beta_4 - \beta_1 = -\frac{12}{13} - \frac{5}{13} = -\frac{17}{13}, \quad \beta_3 - \beta_2 = -(\beta_4 - \beta_1) = \frac{17}{13},$$

and

$$\begin{pmatrix} \frac{\theta_{\delta}}{\theta_1} \end{pmatrix} (Q_3'' - Q_1'') = \begin{pmatrix} \frac{\theta_{\delta}}{\theta_1} \end{pmatrix} (Q_4'' - Q_2''), \quad \delta = 2, 3, 4,$$
$$\begin{pmatrix} \frac{\theta_{\delta}}{\theta_1} \end{pmatrix} (Q_4'' - Q_1'') = \varepsilon_{\delta} \begin{pmatrix} \frac{\theta_{\delta}}{\theta_1} \end{pmatrix} (Q_3'' - Q_2''),$$

where $\varepsilon_2 = \varepsilon_3 = 1$, $\varepsilon_1 = -1$, and

$$\sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_1')}\sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_3')} = \sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_2')}\sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_4')}$$
$$= \sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_1')}\sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_4')} = \sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_2')}\sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_3')}.$$

For $\delta = 2, 3$, we have that $c_{23} = -c_{14}, c_{24} = -c_{13}$.

Suppose that $\delta = 2$. Then

$$\theta_2(Q_2'' - Q_1'') = \theta_2(Q_4'' - Q_3'') = 0$$

and $c_{12} = c_{34} = 0$. This implies that $c_{24} = -c_{13}$, $c_{23} = -c_{13}$, and

$$c_{13} = \frac{i}{2} \times (\beta_3 - \beta_1) \times \frac{\theta_2}{\theta_1} (Q_3'' - Q_1'') = \frac{i}{2} \times \frac{7}{13} \times \frac{17i}{7} = -\frac{17}{26},$$

$$c_{14} = \frac{i}{2} \times (\beta_4 - \beta_1) \times \frac{\theta_2}{\theta_1} (Q_4'' - Q_1'') = \frac{i}{2} \times \left(-\frac{17}{13}\right) \times \frac{7i}{17} = \frac{7}{26}.$$

The formula (2.5) then produces a real symmetric matrix

$$C = \begin{bmatrix} 0 & 0 & -\frac{17}{26} & \frac{7}{26} \\ 0 & 0 & -\frac{7}{26} & \frac{17}{26} \\ -\frac{17}{26} & -\frac{7}{26} & 0 & 0 \\ \frac{7}{26} & \frac{17}{26} & 0 & 0 \end{bmatrix}$$

admitting the representation $F_S(x, y, z) = \det(zI_4 + yB + xC).$

Suppose that $\delta = 3$. Then $\theta_3(Q''_4 - Q''_1) = \theta_3(Q''_3 - Q''_2) = 0$ and $c_{14} = c_{23} = 0$. By the relations

$$\frac{\theta_3}{\theta_1}(Q_4'' - Q_3'') = \frac{\theta_3}{\theta_1}(Q_2'' - Q_1'')$$

and

$$\sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_1')}\sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_2')} = \sqrt{2}, \quad \sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_3')}\sqrt{\mathrm{d}\left(\frac{R_1}{R_2}\right)(Q_4')} = -\sqrt{2},$$

we have

$$c_{12} = -\frac{\beta_2 - \beta_1}{\beta_4 - \beta_3} c_{34} = -\frac{5}{12} c_{34}.$$

Numerical computation, yields that

$$\frac{\theta_1'(0)}{2\omega_1\theta_3(0)} \times \frac{\theta_3(Q_4'' - Q_3'')}{\theta_1(Q_4'' - Q_3'')} \times \frac{1}{\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q_3')}\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q_4')}} \approx -0.205,882,35,$$

which is approximately -7/34, and thus

$$c_{34} = (\beta_4 - \beta_3) \times \frac{7}{34} = \frac{13}{24} \times \frac{7}{34} = \frac{84}{221}$$

We also have

$$\frac{\theta_1'(0)}{2\omega_1\,\theta_3(0)} \times \frac{\theta_3(Q_3'' - Q_1'')}{\theta_1(Q_3'' - Q_1'')} \times \frac{1}{\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q_1')}\sqrt{\mathrm{d}(\frac{R_1}{R_2})(Q_3')}} \approx -1.196,704,7,$$

which is approximately $-26\sqrt{30}/119$, and the value leads to

$$c_{13} = (\beta_3 - \beta_1) \times \left(-\frac{26\sqrt{30}}{119}\right) = -\frac{2\sqrt{30}}{17}$$

The formula (2.5) produces another real symmetric matrix

$$C = \begin{bmatrix} 0 & -\frac{35}{221} & -2\frac{\sqrt{30}}{17} & 0\\ -\frac{35}{21} & 0 & 0 & \frac{2\sqrt{30}}{7}\\ -\frac{2\sqrt{30}}{17} & 0 & 0 & \frac{84}{221}\\ 0 & \frac{2\sqrt{30}}{17} & \frac{84}{221} & 0 \end{bmatrix}$$

satisfying the representation $F(x, y, z) = \det(zI_4 + yB + xC)$.

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