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# ON THE EXISTENCE OF NON-LINEAR FRAMES 

Shah Jahan, Varinder Kumar, and S.K. Kaushik


#### Abstract

A stronger version of the notion of frame in Banach space called Strong Retro Banach frame (SRBF) is defined and studied. It has been proved that if $\mathcal{X}$ is a Banach space such that $\mathcal{X}^{*}$ has a SRBF, then $\mathcal{X}$ has a Bi-Banach frame with some geometric property. Also, it has been proved that if a Banach space $\mathcal{X}$ has an approximative Schauder frame, then $\mathcal{X}^{*}$ has a SRBF. Finally, the existence of a non-linear SRBF in the conjugate of a separable Banach space has been proved.


## 1. Introduction

Frames for Hilbert spaces were introduced by Duffin and Schaeffer [5] in the context of nonharmonic Fourier series. Frames now a days are widely used in various branches of mathematics and engineering. Feichtinger and Grochenig [6] generalized the notion of frame to Banach spaces and introduced the concept of atomic decomposition in a Banach space. Also, Grochenig [7] introduced a more general concept namely Banach frame for Banach spaces. For a nice and comprehensive survey of frames and related concepts one may refer to [1, 4].

Various other generalizations of frames for Banach spaces were defined and studied by many authors namely Schauder frames by Han and Larson 8 and also studied by Casazza et al. [2, 3], frames by Terekhin [17]. Banach frames in conjugate Banach spaces, called retro Banach frames, were introduced and studied by Jain et al. 9] and further studied in [13]. Approximative atomic decompositions in Banach spaces were studied in [10. Schauder frames in conjugate Banach spaces were defined and studied in [12] while approximative Schauder frames were studied in 11. The notion of Bi-Banach frame in a Banach space was defined and studied in [14] wherein they noted that a Schauder frame for a Banach space is a Bi-Banach frame but the converse is not true.

In the present paper, we shall consider a stronger notion of frame in a Banach space called strong Retro Banach frame (SRBF). It has been proved that if $\mathcal{X}$ is a Banach space such that $\mathcal{X}^{*}$ has a SRBF, then $\mathcal{X}$ has a Bi- Banach frame with some geometric property. Also, it has been proved that if a Banach space $\mathcal{X}$ has an approximative Schauder frame, then $\mathcal{X}^{*}$ has a SRBF. Finally, a result related to

[^0]the existence of a non-linear SRBF in the conjugate of a separable Banach space has been proved.

Throughout this paper $\mathcal{X}$ will denotes an infinite dimensional Banach space over the scalar field $\mathbb{K}(\mathbb{R}, \mathbb{C})$, $\mathcal{X}^{*}$ denotes the conjugate space of $\mathcal{X}$ and $L(\mathcal{X}, \mathcal{X})$ denote the Banach space of all continuous linear mappings of $\mathcal{X}$ into $\mathcal{X}$. For a sequence $\left\{x_{n}\right\} \in \mathcal{X}$ and $\left\{f_{n}\right\} \in \mathcal{X}^{*},\left[x_{n}\right]$ denotes the closed linear span of $\left\{x_{n}\right\}$ in the norm topology of $\mathcal{X}$ and $\left[\overline{f_{n}}\right]$ the closed linear span of $\left\{f_{n}\right\}$ in the weak star topology of $\mathcal{X}^{*}$. A sequence space $S$ is called a $B K$-space if it is a Banach space and the co-ordinate functionals are continuous on $S$. That is the relations $x_{n}=\left\{\alpha_{j}{ }^{(n)}\right\}$, $x=\left\{\alpha_{j}\right\} \in S, \lim _{n \rightarrow \infty} x_{n}=x$ imply $\lim _{n \rightarrow \infty} \alpha_{j}^{(n)}=\alpha_{j}(j=1,2,3, \ldots)$. Also, if $V \subseteq \mathcal{X}^{*}$, then we define $\gamma(v)=\inf _{\substack{x \in \mathcal{X} \\ x \neq 0}} \sup _{\substack{f \in v \\\|f\| \leq I}}\left|f\left(\frac{x}{\|x\|}\right)\right|$.

A sequence $\left\{x_{n}\right\} \subset \mathcal{X}$ is said to be a Markusevic basis (M-basis) for $\mathcal{X}$ if $\left\{x_{n}\right\}$ is complete in $\mathcal{X}$ and there exists a sequence $\left\{f_{n}\right\}$ in $\mathcal{X}^{*}$ biorthogonal to $\left\{x_{n}\right\}$, called an associated sequence of coefficient functional (a.s.c.f.), which is total on $\mathcal{X}$.
Definition 1.1 ( 9$]$ ). Let $\mathcal{X}$ be a Banach space and $\mathcal{X}_{d}$ be a BK-space. Let $\left\{x_{n}\right\} \subset \mathcal{X}$ and $J: \mathcal{X}_{d}^{*} \rightarrow \mathcal{X}^{*}$ be given. The pair $\left(\left\{x_{n}\right\}, J\right)$ is called a retro Banach frame for $\mathcal{X}^{*}$ with respect to $\mathcal{X}_{d}^{*}$ if
(a) $\left\{f\left(x_{n}\right)\right\} \in \mathcal{X}_{d}^{*}$, for all $f \in \mathcal{X}^{*}$.
(b) There exist positive constants $A$ and $B$ with $0<A \leq B<\infty$ such that

$$
\begin{equation*}
A\|f\|_{\mathcal{X}^{*}} \leq\left\|\left\{f\left(x_{n}\right)\right\}\right\|_{\mathcal{X}_{d}^{*}} \leq B\|f\|_{\mathcal{X}^{*}}, \quad \text { for all } \quad f \in \mathcal{X}^{*} . \tag{1.1}
\end{equation*}
$$

(c) $J$ is a bounded linear operator such that

$$
J\left(\left\{f\left(x_{n}\right)\right\}\right)=f, \quad \text { for all } \quad f \in \mathcal{X}^{*} .
$$

The constants $A$ and $B$ are called lower and upper bounds of the retro Banach frame $\left(\left\{x_{n}\right\}, J\right)$. The inequality (1.1) is called the retro Banach frame inequality.

A retro Banach frame $\left(\left\{x_{n}\right\}, J\right)$ is said to be exact if there exists a sequence $\left\{f_{n}\right\} \subset \mathcal{X}^{*}$ such that $f_{i}\left(x_{j}\right)=\delta_{i, j}$, for all $i, j \in \mathbb{N}$.
Definition 1.2. Let $\mathcal{X}$ be a Banach space with dual $\mathcal{X}^{*}$. A pair $\left(\left\{x_{n}\right\},\left\{f_{n}\right\}\right)$ (where $\left\{f_{n}\right\} \subset \mathcal{X}^{*}$ and $\left\{x_{n}\right\} \subset \mathcal{X}$ ) is called a Bi-Banach frame for $\mathcal{X}$ if there exist associated Banach spaces $\mathcal{X}_{d}$ and $\left(\mathcal{X}^{*}\right)_{d}$ and bounded linear operators $S: \mathcal{X}_{d} \rightarrow \mathcal{X}$, $T:\left(\mathcal{X}^{*}\right)_{d} \rightarrow \mathcal{X}^{*}$ such that $\left(\left\{f_{n}\right\}, S\right)$ is a Banach frame for $\mathcal{X}$ and $\left(\left\{x_{n}\right\}, T\right)$ is retro Banach frame for $\mathcal{X}^{*}$.

A Bi-Banach frame $\left(\left\{x_{n}\right\},\left\{f_{n}\right\}\right)$ is called tight if both the retro Banach frame $\left(\left\{x_{n}\right\}, T\right)$ and the Banach frame $\left(\left\{f_{n}\right\}, S\right)$ are tight.

The following results are stated in the form of lemmas which will be used in the subsequent work.

Lemma 1.3 ([16]). Let $\mathcal{X}$ be a Banach space and $\left\{f_{n}\right\} \subset \mathcal{X}^{*}$ be a sequence such that $\left\{x \in \mathcal{X}: f_{n}(x)=0, \forall n \in \mathbb{N}\right\}=\{0\}$. Then $\mathcal{X}$ is linearly isometric to the Banach space $\mathcal{X}_{d}=\left\{\left\{f_{n}(x)\right\}: x \in \mathcal{X}\right\}$, where the norm is given by $\left\|\left\{f_{n}(x)\right\}\right\|_{\mathcal{X}_{d}}=$ $\|x\|_{\mathcal{X}}, x \in \mathcal{X}$.

Lemma 1.4 ([16]). Let $\mathcal{X}$ be a separable normed linear space and let $\left\{x_{n}^{*}\right\}$ be a sequence in $\mathcal{X}^{*}$ such that $\frac{x_{n}^{*}}{\left\|x_{n}^{*}\right\|} \xrightarrow{w^{*}} 0$ and that for the linear subspace $\left[x_{n}^{*}\right]$ of $\mathcal{X}^{*}$, $\gamma\left(\left[x_{n}^{*}\right]\right) \geq 0$. Then there exist a norm $|\cdot|$ on $\mathcal{X}$ equivalent to the initial norm on $\mathcal{X}$ such that $(\mathcal{X},|\cdot|)$ is strictly convex and satisfies the following property

$$
\begin{equation*}
\text { If } \lim _{n \rightarrow \infty} f_{k}\left(x_{n}\right)=f_{k}\left(x_{0}\right)(k=1,2, \ldots), \quad \text { then } \quad \lim _{n \rightarrow \infty}\left|x_{n}\right| \geq\left|x_{0}\right| . \tag{1.2}
\end{equation*}
$$

## 2. Main result

Approximative Schauder frames in Banach spaces were studied in [11] and the notion of Bi-Banach frame was studied in [14]. In the following definition, we gave a stronger notion called Strong Retro Banach frame (SRBF). The idea of defining this notion is to correlate this notion with the existing notions like approximative Schauder frames and Bi-Banach frames.

Definition 2.1. Let $\left\{x_{n}\right\} \subset \mathcal{X}$ be an exact RBF for $\mathcal{X}^{*}$ with admissible sequence $\left\{f_{n}\right\} \subset \mathcal{X}^{*}$. Let $X_{n}=\left[x_{1}, x_{2}, \ldots, x_{n}\right], n \in \mathbb{N}$. If there exists a sequence $\left\{v_{n}\right\}$, where each $v_{n}: X_{n} \rightarrow X_{n}$ is a continuous linear mapping, such that $x=\lim _{n \rightarrow \infty} v_{n} \sum_{i=1}^{n} f_{i}(x) x_{i}, x \in \mathcal{X}$, then $\left(\left\{x_{n}\right\},\left\{f_{n}\right\},\left\{v_{n}\right\}\right)$ is called a strong RBF (or SRBF) for $\mathcal{X}^{*}$.

Remark 2.2. If we define $u_{n}: \mathcal{X} \rightarrow \mathcal{X}, n \in \mathbb{N}$ by

$$
u_{n}(x)=v_{n} \sum_{i=1}^{n} f_{i}(x) x_{i}, \quad n \in \mathbb{N}
$$

Then one may observe that if $\left(\left\{x_{n}\right\},\left\{f_{n}\right\},\left\{v_{n}\right\}\right)$ is a SRBF, then $\lim _{n \rightarrow \infty} u_{n}(x)=x$ and $\operatorname{dim} u_{n}(\mathcal{X})=\operatorname{dim}\left(v_{n} \sum_{i=1}^{n} f_{i}(x) x_{i}\right)(\mathcal{X}) \leq n<\infty$ and so $\left\{x_{n}\right\}$ is an approximative basis of $\mathcal{X}$.

In the following result, we prove that the existence of SRBF in the conjugate of a Banach space guarantees the existence of a Bi-Banach frame in the Banach space along with some geometric property.

Theorem 2.3. Let $X$ be a Banach space and $\left(\left\{x_{n}\right\},\left\{f_{n}\right\},\left\{v_{n}\right\}\right)$ be a SRBF for $\mathcal{X}^{*}$ with admissible sequence $\left\{f_{n}\right\} \subset \mathcal{X}^{*}$. Then $\left(\left\{x_{n}\right\},\left\{f_{n}\right\}\right)$ is a Bi-Banach frame for $\mathcal{X}$ such that $\gamma\left(\left[f_{n}\right]\right)>0$.

Proof. Clearly, by definition of $\operatorname{SRBF},\left\{x \in \mathcal{X}: f_{n}(x)=0\right.$, for all $\left.n \in \mathbb{N}\right\}=$ $\{0\}$. Therefore, by Lemma 1.3 there exists an associated Banach space $\mathcal{X}_{d}=$ $\left\{\left\{f_{n}(x)\right\} ; x \in \mathcal{X}\right\}$ with norm given by $\left\|\left\{f_{n}(x)\right\}\right\|_{\mathcal{X}_{d}}=\|x\|_{\mathcal{X}}, x \in \mathcal{X}$. Define $J: \mathcal{X}_{d} \rightarrow$ $\mathcal{X}$ by $J\left(\left\{f_{n}(x)\right\}\right)=x, x \in \mathcal{X}$. Then J is a bounded linear operator such that $\left(\left\{f_{n}\right\}, J\right)$ is a Banach frame for $\mathcal{X}$. Hence $\left(\left\{x_{n}\right\},\left\{f_{n}\right\}\right)$ is a Bi-Banach frame for $\mathcal{X}$. Let for each $n \in \mathbb{N}, v_{n}: X_{n} \rightarrow X_{n}$ be a continuous linear mapping given by $\lim _{n \rightarrow \infty} v_{n} \sum_{i=1}^{n} f_{i}(x) x_{i}=x$. Write $v_{n}\left(x_{j}\right)=\sum_{i=1}^{n} a_{j i}^{(n)} x_{i}, j=1,2, \ldots, n, n \in \mathbb{N}$, where
$a_{j i}^{(n)}=f_{i}\left(v_{n}\left(x_{j}\right)\right)$, for all $i, j=1,2,3, \ldots, n, n \in \mathbb{N}$. Thus

$$
v_{n}\left(\sum_{i=1}^{n} f_{i}(x) x_{i}\right)=\sum_{j=1}^{n}\left(\sum_{i=1}^{n} a_{i j}^{(n)} f_{i}(x)\right) x_{j}, \quad x \in \mathcal{X}, n \in \mathbb{N} .
$$

Define

$$
h_{n, j}=\sum_{i=1}^{n} a_{i j}^{(n)} f_{i}, \quad j=1,2,3, \ldots, n, n \in \mathbb{N} .
$$

Then $h_{n, i} \in\left[f_{i}\right]_{i=1}^{n}(j=1,2, \ldots, n ; n \in \mathbb{N})$. Hence, we conclude that $\gamma\left(\left[f_{n}\right]\right)>0$.

In the following result, we prove a weak duality type result.
Theorem 2.4. Let $\left(\left\{x_{n}\right\},\left\{f_{n}\right\},\left\{v_{n}\right\}\right)$ be a SRBF for $\mathcal{X}^{*}$ with admissible sequence $\left\{f_{n}\right\} \subset \mathcal{X}^{*}$. Then there exists a sequence of continuous linear mappings $\left\{\tau_{n}\right\}$ $\left(\tau_{n}: V_{n} \rightarrow V_{n}\right.$, where $\left.V_{n}=\left[f_{1}, f_{2}, \ldots, f_{n}\right], n \in \mathbb{N}\right)$ such that

$$
f(x)=\lim _{n \rightarrow \infty}\left(\tau_{n} \sum_{i=1}^{n} f\left(x_{i}\right) f_{i}\right)(x)
$$

Proof. For each $k=1,2,3, \ldots, n, n \in \mathbb{N}$, define $\tau_{n}: \operatorname{span}\left\{f_{1}, f_{2}, \ldots, f_{n}\right\} \rightarrow$ $\operatorname{span}\left\{f_{1}, f_{2}, \ldots, f_{n}\right\}$ by

$$
\tau_{n}\left(f_{k}\right)=\sum_{i=1}^{n} a_{i k}^{(n)} f_{i}=\sum_{i=1}^{n} f_{k}\left(v_{n}\left(x_{i}\right)\right) f_{i}
$$

Extend each $\tau_{n}$ to $\left[f_{1}, f_{2}, \ldots, f_{n}\right]$. Then

$$
\begin{aligned}
\left(\tau_{n} \sum_{i=1}^{n} f\left(x_{i}\right) f_{i}\right)(x) & =\sum_{i=1}^{n} f\left(x_{i}\right)\left(\tau_{n}\left(f_{i}\right)\right)(x) \\
& =\sum_{i=1}^{n}\left(\sum_{j=1}^{n} a_{j i}^{(n)} f_{j}(x)\right) f\left(x_{i}\right) \\
& =\sum_{i=1}^{n}\left(\sum_{j=1}^{n} f_{i}\left(v_{n}\left(x_{j}\right)\right) f_{j}(x)\right) f\left(x_{i}\right) \\
& =\sum_{i=1}^{n} v_{n}\left(\sum_{j=1}^{n} f_{i}\left(x_{j}\right) f_{j}(x)\right) f\left(x_{i}\right) \\
& =f\left(v_{n}\left(\sum_{i=1}^{n} f_{i}(x) x_{i}\right)\right) \\
& =\rightarrow f(x) \quad \text { as } \quad n \rightarrow \infty
\end{aligned}
$$

Approximative Schauder frames were defined and studied in [11. In the following result, we prove that if a Banach space $\mathcal{X}$ has an approximative Schauder frame, then its dual space has a SRBF.

Theorem 2.5. If a Banach space $\mathcal{X}$ has an approximative Schauder frame, then $\mathcal{X}^{*}$ has a SRBF.

Proof. Let $\left\{u_{n}\right\}$ be a sequence of finite rank continuous linear mapping from $\mathcal{X}$ to $\mathcal{X}$ such that $\lim _{n \rightarrow \infty} u_{n}(x)=x, x \in \mathcal{X}$. Let $\left\{x_{n}\right\}$ be a Markusevic basis for $\mathcal{X}$ with a.s.c.f. $\left\{f_{n}\right\} \subset \mathcal{X}^{*}$ such that

$$
\begin{equation*}
\bigcup_{n} u_{n}^{*}\left(\mathcal{X}^{*}\right) \subset\left[f_{n}\right] \tag{2.1}
\end{equation*}
$$

Since each $u_{n}$ is finite dimensional, we may write

$$
u_{n}(x)=\sum_{i=1}^{p_{n}} \psi_{n i}(x) \phi_{n i}, \quad x \in \mathcal{X}, n \in \mathbb{N}
$$

where $\left\{\phi_{n i}\right\}_{i=1}^{p_{n}}$ is a basis for $\left\{u_{n}(\mathcal{X})\right\}$ with associated sequence $\left\{\psi_{n i}\right\}_{i=1}^{p_{n}} \subset \mathcal{X}^{*}$. Let $\left\{g_{n i}\right\}_{i=1}^{p_{n}}$ be a sequence in $\mathcal{X}^{*}$ that is biorthogonal to $\left\{\phi_{n i}\right\}_{i=1}^{p_{n}}$. Then

$$
\begin{aligned}
u_{n}^{*}\left(g_{n j}\right)(x) & =g_{n j}\left(u_{n}(x)\right) \\
& =g_{n j}\left(\sum_{i=1}^{p_{n}} \psi_{n i}(x) \phi_{n_{i}}\right) \\
& =\sum_{i=1}^{p_{n}} \psi_{n i}(x) g_{n j}\left(\phi_{n_{i}}\right) \\
& =\psi_{n j}(x), \quad j=1,2, \ldots, p_{n} .
\end{aligned}
$$

Hence, $\psi_{n j} \in\left[f_{n}\right], j=1,2, \ldots, p_{n}, n \in \mathbb{N}$. Let $n \in \mathbb{N}$ be given. Then, for any $\epsilon>0$, there exists an integer $m_{n}(\epsilon)$ such that for each $i=1,2, \ldots, p_{n}$ one can find $\bar{\phi}_{n i} \in\left[x_{1}, x_{2}, \ldots, x_{m_{n}}\right]$ and $\bar{\psi}_{n i} \in\left[f_{1}, f_{2}, \ldots, f_{m_{n}}\right]$ such that

$$
\begin{equation*}
\left\|\phi_{n i}-\bar{\phi}_{n i}\right\|<\epsilon \quad \text { and } \quad\left\|\psi_{n i}-\bar{\psi}_{n i}\right\|<\epsilon, \quad i=1,2,3, \ldots, p_{n} . \tag{2.2}
\end{equation*}
$$

Write

$$
\bar{v}_{m_{n}}(x)=\sum_{i=1}^{p_{n}} \bar{\psi}_{n i}(x) \bar{\phi}_{n i}, \quad x \in \mathcal{X}
$$

Then

$$
\begin{aligned}
\left\|\bar{v}_{m_{n}}(x)-u_{n}(x)\right\| & =\left\|\sum_{i=1}^{p_{n}}\left(\bar{\psi}_{n i}(x)-\psi_{n i}(x)\right) \bar{\phi}_{n i}+\sum_{i=1}^{p_{n}} \psi_{n i}(x)\left(\bar{\phi}_{n i}-\phi_{n i}\right)\right\| \\
& \leq\left(\sum_{i=1}^{p_{n}}\left\|\bar{\psi}_{n i}-\psi_{n i}\right\|\left\|\bar{\phi}_{n i}\right\|+\sum_{i=1}^{p_{n}}\left\|\psi_{n i}\right\|\left\|\bar{\phi}_{n i}-\phi_{n i}\right\|\right)\|x\|, x \in \mathcal{X} .
\end{aligned}
$$

Therefore, by 2.2 , taking $\epsilon=\frac{1}{n}$ and $\left\{m_{n}\right\}$ to be an increasing sequence, we obtain

$$
\begin{equation*}
\left\|\bar{v}_{m_{n}}-u_{n}\right\|<\frac{1}{n} \tag{2.3}
\end{equation*}
$$

Now, observe that

$$
\begin{align*}
& f_{i}\left(x-\sum_{j=1}^{k} f_{j}(x) x_{j}\right)=0  \tag{2.4}\\
& \quad \text { for all } x \in \mathcal{X}, i=1,2, \ldots, m_{n} ; \quad k=m_{n}, m_{n}+1, \ldots
\end{align*}
$$

Also, $\bar{\psi}_{n i} \in\left[f_{1}, f_{2}, \ldots, f_{m_{n}}\right]$. So, for $x \in \mathcal{X}$, we have

$$
\begin{align*}
\bar{v}_{m_{n}}\left(\sum_{j=1}^{k} f_{j}(x) x_{j}\right) & =\sum_{i=1}^{p_{n}} \bar{\psi}_{n i}\left(\sum_{j=1}^{k} f_{j}(x) x_{j}\right) \bar{\phi}_{n i} \\
& =\sum_{i=1}^{p_{n}} \bar{\psi}_{n i}(x) \bar{\phi}_{n i} \\
& =\bar{v}_{m_{n}}(x), \quad \text { for all } \quad x \in \mathcal{X} \quad \text { and } \quad k \geq m_{n} \tag{2.5}
\end{align*}
$$

Therefore

$$
\begin{align*}
\lim _{n \rightarrow \infty} \bar{v}_{m_{n}}\left(\sum_{j=1}^{m_{n}} f_{j}(x) x_{j}\right)= & \lim _{n \rightarrow \infty} \bar{v}_{m_{n}}(x) \\
& =\lim _{n \rightarrow \infty} u_{n}(x) \\
& =x, \quad x \in \mathcal{X} . \tag{2.6}
\end{align*}
$$

Define a sequence $\left\{T_{n}\right\}$ by $T_{n}(x)=\sum_{i=1}^{n} f_{i}(x) x_{i}, n \in \mathbb{N}$. Write

$$
v_{k}=\left.T_{k}\right|_{\left[x_{1}, x_{2}, \ldots, x_{k}\right]}, \quad k=1,2, \ldots, m_{1}-1
$$

and

$$
v_{k}=\left.\bar{v}_{m_{n}}\right|_{\left[x_{1}, x_{2}, \ldots, x_{k}\right]}, \quad k=m_{n}, m_{n}+1, \ldots, m_{n}-1, \quad n=1,2,3 \ldots
$$

Then, each $v_{k}$ is a continuous linear mapping defined on $\left[x_{1}, x_{2}, \ldots, x_{k}\right]$ with range given by

$$
\begin{aligned}
v_{k}\left(\left[x_{1}, x_{2}, \ldots, x_{k}\right]\right) & =\left[x_{1}, x_{2}, \ldots, x_{k}\right] ; & k=1,2,3, \ldots, m_{1}-1 \\
v_{k}\left(\left[x_{1}, x_{2}, \ldots x_{k}\right]\right) & \subset\left[x_{1}, x_{2}, \ldots, x_{k}\right], & k=m_{n}, m_{n}+1, \ldots, m_{n+1}-1, \quad n \in \mathbb{N} .
\end{aligned}
$$

Using (2.5) and 2.6), we obtain $\lim _{n \rightarrow \infty} \bar{v}_{m_{n}}(x)=x$. Hence $\lim _{n \rightarrow \infty} v_{n}\left(\sum_{i=1}^{n} f_{i}(x) x_{i}\right)=$ $x$.

In view of the proof of Theorem 2.5, one may observe that existence of approximative Schauder frame in a Hilbert space is a sufficient condition for the space having Markusevic basis to have a SRBF. More precisely we have

Corollary 2.6. Let $\mathcal{H}$ be a Hilbert space with an approximative Schauder frame. Then every Markusevic basis of $\mathcal{H}$ give rise to a SRBF for $\mathcal{H}$.

In the following example, we show that in general, a SRBF do not have strong duality

Example 2.7. Let $\mathcal{X}$ be a Banach space with a Schauder basis and such that $\mathcal{X}^{*}$ is separable but fails to have approximative property. Let $\left\{x_{n}\right\}$ be a shrinking Markusevic basis of $\mathcal{X}$ with associated sequence of coefficient functional $\left\{f_{n}\right\} \subset \mathcal{X}^{*}$. Define

$$
u_{n}(x)=\sum_{i=1}^{n} f_{i}(x) x_{i}, \quad x \in \mathbb{N}
$$

Then $\left\{x_{n}\right\}$ is an approximative Schauder frame for $\mathcal{X}$ satisfying $\bigcup_{n=1}^{\infty} u_{n}{ }^{*}\left(\mathcal{X}^{*}\right) \subset$ $\left[f_{n}\right]$. Therefore $\left(\left\{x_{n}\right\},\left\{f_{n}\right\},\left\{v_{n}\right\}\right)$ is a SRBF for $\mathcal{X}^{*}$. However, $\mathcal{X}^{* *}$ has no SRBF.

One may observe that in Definition 2.1, each $v_{n}$ is linear. Now, we would like to drop this condition of linearity and in the process define non-linear SRBF.

Definition 2.8. A SRBF $\left(\left\{x_{n}\right\},\left\{f_{n}\right\},\left\{v_{n}\right\}\right)$ is called non-linear SRBF if each $v_{n}$ is continuous but not necessarily linear.

Finally, we prove the following result related to the existence of a non-linear SRBF.

Theorem 2.9. If $\mathcal{X}$ is a separable Banach Space, then $\mathcal{X}^{*}$ has a non-linear SRBF.
Proof. Let $\left\{x_{n}\right\}$ be a Markusevic basis with a sequence of coefficient functional $\left\{f_{n}\right\} \subset \mathcal{X}^{*}$ such that $\gamma\left(\left[f_{n}\right]\right)>0$. Then, by Lemma 1.4 there is a norm $|\cdot|$ on $\mathcal{X}$ that is equivalent to the original norm $\|\cdot\|$ on $\mathcal{X}$ such that $\mathcal{X}$ with this new norm $|\cdot|$ is strictly convex. Therefore, by [15, Corollary 3.3, page 110], for every finite dimensional subspace $\mathcal{G}$ of $\mathcal{X}$ and for every $x \in \mathcal{X} \backslash \mathcal{G}$, there is a unique $\pi_{\mathcal{G}}(x) \in \mathcal{G}$ such that $\left|x-\pi_{\mathcal{G}}(x)\right|=\operatorname{dist}(x, \mathcal{G})=\min _{x \in \mathcal{G}}|x-g|$ and such that the mapping $\pi_{\mathcal{G}}: \mathcal{X} \rightarrow \mathcal{G}$ is continuous (here note that, in general, $\pi_{\mathcal{G}}$ is non-linear). Let $\mathfrak{N}(a, b)$ denote a positive integer depending on $a$ and $b$. For each $n$, choose an increasing sequence of positive integers $\left\{m_{n}\right\}$ with $m_{1}=\mathfrak{N}(1,1), m_{2}=\mathfrak{N}\left(m_{1}, \frac{1}{2}\right)$, $m_{3}=\mathfrak{N}\left(m_{2}, \frac{1}{3}\right), \ldots, m_{n}=\mathfrak{N}\left(m_{n-1}, \frac{1}{n}\right)$, for all $n \geq 2$ and satisfying

$$
\operatorname{dist}\left(a,\left[x_{i}\right]_{i=m_{n-1}+1}^{m_{n}}\right) \leq\left(1+\frac{1}{n}\right) \operatorname{dist}\left(a,\left[x_{i}\right]_{i=m_{n-1}+1}^{\infty}\right)
$$

where $a \in\left[x_{i}\right]_{i=1}^{m_{n-1}}$. Define $\left\{v_{n}\right\}$ by $v_{k}=\left.T_{k}\right|_{\left[x_{1}, \ldots, x_{k}\right]}, k=1,2, \ldots, m_{1}-1$, where $T_{k}(x)=\sum_{i=1}^{k} f_{i}(x) x_{i}$ and for any $b=\sum_{i=1}^{k} a_{i} x_{i} \in\left[x_{i}\right]_{i=1}^{k}, \quad\left(k=m_{n}, m_{n}+\right.$ $1, \ldots, m_{n+1}-1 ; n \in \mathbb{N}$ )

$$
v_{k}(b)=\sum_{i=1}^{m_{n-1}} a_{i} x_{i}-\pi_{\mathcal{G}}\left(\sum_{i=1}^{m_{n-1}} a_{i} x_{i}\right)
$$

where $\mathcal{G}=\left[x_{i}\right]_{i=m_{n-1}+1}^{m_{n}}$. Then each $v_{n}$ is continuous (in general, non-linear) with range given by

$$
\begin{array}{ll}
v_{k}\left(\left[x_{1}, \ldots, x_{k}\right]\right)=\left[x_{1}, \ldots, x_{k}\right], & k=1,2,3, \ldots, m_{1}-1 \\
v_{k}\left(\left[x_{1}, \ldots, x_{k}\right]\right) \subset\left[x_{1}, \ldots, x_{k}\right], & \left(k=m_{n}, m_{n}+1, \ldots, m_{n+1}-1 ; n \in \mathbb{N}\right) .
\end{array}
$$

Let $x \in \mathcal{X}$ be any element. Then
$f_{i}\left(v_{k}\left(\sum_{j=1}^{k} f_{j}(x) x_{j}\right)\right)=f_{i}(x), i=1,2, \ldots, m_{n} ; k=m_{n}, m_{n}+1, \ldots, m_{n+1}-1 ; n \in \mathbb{N}$.
This gives

$$
\begin{equation*}
\lim _{k \rightarrow \infty} f_{i}\left(v_{k}\left(\sum_{j=1}^{k} f_{j}(x) x_{j}\right)\right)=f_{i}(x), \quad i=1,2, \ldots \tag{2.7}
\end{equation*}
$$

In view of Lemma 1.4, we have

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left|v_{k}\left(\sum_{i=1}^{k} f_{i}(x) x_{i}\right)\right| \geq|x| . \tag{2.8}
\end{equation*}
$$

Also, we have

$$
\begin{aligned}
v_{k}\left(\sum_{i=1}^{k} f_{i}(x) x_{i}\right) & =\left|\sum_{i=1}^{m_{n-1}} f_{i}(x) x_{i}-\pi_{\mathcal{G}} \sum_{i=1}^{m_{n-1}} f_{i}(x) x_{i}\right| \\
& =\operatorname{dist}\left(\sum_{i=1}^{m_{n-1}} f_{i}(x) x_{i}, \mathcal{G}\right) \\
& \leq\left(1+\frac{1}{n}\right) \operatorname{dist}\left(\sum_{i=1}^{m_{n-1}} f_{i}(x) x_{i},\left[x_{i}\right]_{i=m_{n-1}+1}^{\infty}\right) \\
& \leq\left(1+\frac{1}{n}\right)\left|\sum_{i=1}^{m_{n-1}} f_{i}(x) x_{i}+\left(x-\sum_{i=1}^{m_{n-1}} f_{i}(x) x_{i}\right)\right| \\
& =\left(1+\frac{1}{n}\right)|x|, \quad k=m_{n}, m_{n}+1, \quad m_{n+1}-1 ; n \in \mathbb{N} .
\end{aligned}
$$

Thus, by (2.8), we have

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left|v_{k}\left(\sum_{i=1}^{k} f_{i}(x) x_{i}\right)\right|=|x| \tag{2.9}
\end{equation*}
$$

Hence, we conclude that

$$
\lim _{k \rightarrow \infty}\left|v_{k}\left(\sum_{i=1}^{k} f_{i}(x) x_{i}\right)-x\right|=0
$$

Since $|\cdot|$ is equivalent to the initial norm of $\mathcal{X}$, we obtain

$$
\lim _{n \rightarrow \infty} v_{n}\left(\sum_{i=1}^{n} f_{i}(x) x_{i}\right)=x, \quad x \in \mathcal{X}
$$

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