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# DERIVATIONS ON THE NIJENHUIS-SCHOUTEN BRACKET ALGEBRA

Jiří Vanžura

This is an announcement of results. The proofs will appear elsewhere.

All structures appearing in this paper are of class  $C^\infty$ . Let  $M$  be a connected and paracompact orientable manifold,  $\dim M = m$ . As usual we denote by  $TM$  the tangent bundle of  $M$ , and by  $\Lambda^i TM$  its  $i$ -th exterior power. We set

$$L_i = \Gamma \Lambda^{i+1} TM \quad \text{for } -1 \leq i \leq m-1,$$

where  $\Gamma$  denotes the functor of sections over  $M$ . In order to avoid technical complications we set

$$L_i = 0 \quad \text{for } i < -1 \text{ or } i > m-1.$$

Obviously for any  $i \in \mathbb{Z}$   $L_i$  is a real vector space. To complete our notation we set

$$L = \sum_{i=-\infty}^{\infty} L_i.$$

If  $\alpha \in L_i$  we call  $\alpha$  homogenous element and write  $|\alpha| = i$ . Let us notice that  $L_{-1}$  is the vector space of functions on  $M$ , and  $L_0$  is the vector space of vector fields on  $M$ .

Using a result of Schouten [2], Nijenhuis [1] defined a bilinear mapping

$$[\ , \ ]: L \times L \rightarrow L$$

which is now called Nijenhuis-Schouten bracket. This bracket is characterized by the following properties (All elements are homogenous.):

- (a)  $[L_i, L_j] \subset L_{i+j}$
- (b)  $[\alpha, \beta] \approx -(-1)^{|\alpha| \cdot |\beta|} [\beta, \alpha]$
- (c)  $(-1)^{|\gamma| \cdot |\alpha|} [\alpha, [\beta, \gamma]] + (-1)^{|\alpha| \cdot |\beta|} [\beta, [\gamma, \alpha]] + (-1)^{|\beta| \cdot |\gamma|} [\gamma, [\alpha, \beta]] = 0$
- (d)  $[\alpha, f] \approx \iota_{df} \alpha$ , where  $f \in L_{-1}$  and  $\iota$  denotes the inner product operator.
- (e)  $[\alpha, \beta \wedge \gamma] = [\alpha, \beta] \wedge \gamma + (-1)^{|\alpha| \cdot |\beta|} \beta \wedge [\alpha, \gamma]$

The properties (b) and (c) show that  $L$  is a graded Lie algebra. Further using (b)-(e) we find easily that for  $X \in L_0$ ,  $\alpha \in L$  there is  $[X, \alpha] = \mathcal{L}_X \alpha$ , where  $\mathcal{L}_X$  denotes the Lie derivative. Consequently for  $X, Y \in L_0$   $[X, Y]$  is the ordinary Lie bracket.

Let us recall that a derivation of degree  $k \in \mathbf{Z}$  on  $L$  is a linear mapping  $D: L \rightarrow L$  such that

- (1)  $DL_i \subset L_{i+k}$
- (2)  $D[\alpha, \beta] = [D\alpha, \beta] + (-1)^{k \cdot |\alpha|} [\alpha, D\beta]$ .

A derivation  $D$  is called local if it has the following property: If  $\alpha \in L_i$ ,  $U \subset M$  is an open subset and  $\alpha|U = 0$ , then  $D\alpha|U = 0$ . We shall denote by  $\text{Der}_k$  the vector space of all local derivations of degree  $k$  on  $L$ . The goal of this paper is to describe  $\text{Der}_k$  for  $k \in \mathbf{Z}$ .

PROPOSITION 1.  $\text{Der}_k = 0$  for  $k < -1$ .

For the sake of formulation of the next propositions we shall recall some facts about the forms of higher order. By a  $k$ -form on  $M$  we shall mean a local skew-symmetric  $k$ -linear (over the reals) mapping

$$\omega: \underbrace{L_0 \times \dots \times L_0}_{k\text{-times}} \rightarrow L_{-1}.$$

( $\omega$  is called local if it has the following property: If  $X_1, \dots, X_k \in L_0$ ,  $U \subset M$  is an open subset, and  $X_1|U = 0$ , then  $\omega(X_1, \dots, X_k)|U = 0$ .) The usual formula

$$\begin{aligned} d\omega(X_1, \dots, X_{k+1}) &= \sum_{i=1}^{k+1} (-1)^{i+1} X_i \omega(X_1, \dots, \hat{X}_i, \dots, X_{k+1}) \\ &\quad + \sum_{i < j} (-1)^{i+j} \omega([X_i, X_j], X_1, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_{k+1}) \end{aligned}$$

defines the exterior derivative  $d\omega$  of  $\omega$ , which is a  $(k+1)$ -form (i.e. it is again local). Ordinary  $k$ -forms on  $M$  we shall call  $k$ -forms of order 0.

We shall fix a volume element  $\mu$  on  $M$  (i.e. an everywhere nonzero  $m$ -form of order 0). For any  $X \in L_0$  there exists a unique function, which we shall denote by  $\text{div} X$  such that

$$\mathcal{L}_X \mu = \text{div} X \cdot \mu,$$

where  $\mathcal{L}_X$  denotes the Lie derivative with respect to  $X$ . The linear mapping  $\text{div}: X \mapsto \text{div} X$  is a closed 1-form. (We remark that this is not a 1-form of order 0. In fact the order of  $\text{div}$  is 1.)

Obviously any derivation  $D \in \text{Der}_{-1}$  determines a 1-form  $\omega_D$  on  $M$  defined by the formula

$$\omega_D(X) = DX.$$

PROPOSITION 2. *If  $\dim M = 1$ , then the mapping  $D \mapsto \omega_D$  defines an isomorphism between  $\text{Der}_{-1}$  and the vector space of closed 1-forms on  $M$ .*

PROPOSITION 3. *If  $\dim M > 1$ , then the mapping  $D \mapsto \omega_D$  defines an isomorphism between  $\text{Der}_{-1}$  and the vector space consisting of all 1-forms*

$$\omega = c.\text{div} + \omega'$$

on  $M$ , where  $c \in \mathbf{R}$ , and  $\omega'$  is a closed 1-form of order 0.

PROPOSITION 4. *Let  $D \in \text{Der}_0$ . Then there exist unique  $X_D \in L_0$  and  $c \in \mathbf{R}$  such that*

$$D\alpha = \mathcal{L}_{X_D}\alpha + i c \alpha, \quad \alpha \in L_i, \quad -1 \leq i \leq m-1,$$

where  $\mathcal{L}_{X_D}$  denotes the Lie derivative with respect to  $X_D$ .

Conversely for any  $X \in L_0$  and  $c \in \mathbf{R}$  the formula

$$D\alpha = \mathcal{L}_X\alpha + i c \alpha, \quad \alpha \in L_i, \quad -1 \leq i \leq m-1$$

defines a derivation of degree 0 on  $L$ .

PROPOSITION 5. *Every derivation  $D \in \text{Der}_k$ ,  $k > 0$  is inner.*

## REFERENCES

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