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Czechoslovak Mathematical Journal, Vol. 27 (1977), No. 1, 114-115,116-117,118

Persistent URL: http://dml.cz/dmlcz/101449

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A MAP ASSOCIATED TO THE LEPAGIAN FORMS ON THE CALCULUS OF VARIATIONS IN FIBRED MANIFOLDS

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(Received April 3, 1975)

1. The role of the so called Lepagian differential forms in the calculus of variations is well known. The simplest form of this kind was introduced by E. CARTAN [1] (see also [3]). LEPAGE (see e.g. [7]) extended the theory to the variational integrals over *n*-dimensional domains in Euclidean spaces. Since then many authors formulated the foundations of the variational calculus in terms of the Lepagian forms. The concept proved to be useful for a modern, differential-geometric approach to the variational problems in fibred manifolds (see e.g. [2], [4], [5], [8]). Our remark to the theory of the Lepagian forms and Lepagian equivalents is based on a definition given by the author [5], [6], and concerns the first order variational problems, which are mostly used in practice. Unlike the Cartan fundamental form, the Lepagian equivalent we consider is not, in general, 1-horizontal (in the terminology of KoLÁŘ [4]). An example of a Lepagian equivalent for the second order variational problems can be found in [6].

2. Let us briefly recall the main notions of the variational theory used later on. We assume that we are given a smooth finite dimensional *fibred manifold* $\pi : Y \to X$ (a submersion) with an orientable *n*-dimensional base space X. Put $\mathscr{J}^0 Y = Y$ and denote by $\mathscr{J}^r Y$ the manifold of all *r*-jets of local sections of π , and by $\pi_r : \mathscr{J}^r Y \to X$ and $\pi_{rs} : \mathscr{J}^r Y \to \mathscr{J}^s Y$ ($0 \leq s \leq r$) the corresponding fibred manifolds defined by the natural projections of jets. We shall denote by R the field of real numbers.

The following spaces of forms, important for many variational considerations, are introduced in [5]: The space $\Omega^{n+1}(\mathscr{J}^1 Y)$ of all (n + 1)-forms defined on $\mathscr{J}^1 Y$, the space $\Omega_Y^{n+1}(\mathscr{J}^1 Y)$ of all π_{20} -horizontal (n + 1)-forms on $\mathscr{J}^1 Y$ (the Lagrangians), the space $\Omega^n(Y)$ of all *n*-forms on *Y*, and the space $\Omega_{Lep}(\mathscr{J}^1 Y)$ of the so called Lepagian forms, a subspace of the real vector space $\Omega_Y^n(\mathscr{J}^1 Y)$ of all π_{10} -horizontal *n*-forms on $\mathscr{J}^1 Y$. With these spaces we associate the maps $h_1: \Omega_{Lep}(\mathscr{J}^1 Y) \to \Omega_X^n(\mathscr{J}^1 Y)$ (a linear surjection), $\tilde{h}: \Omega^{n+1}(\mathscr{J}^1Y) \to \Omega^{n+1}(\mathscr{J}^2Y)$, and the Euler map of the calculus of variations [5], $E: \Omega^n_X(\mathscr{J}^1Y) \to \Omega^n_Y(J^2Y)$ with the diagram

$$\Omega_{\operatorname{Lep}}(\mathscr{J}^{1}Y) \xrightarrow{h_{1}} \Omega_{X}^{n}(\mathscr{J}^{1}Y)$$

$$\downarrow^{d} \qquad \qquad \downarrow^{E}$$

$$\Omega^{n+1}(\mathscr{J}^{1}Y) \xrightarrow{\hbar} \Omega_{Y}^{n+1}(\mathscr{J}^{2}Y)$$

being commutative. We note that the left arrow in the diagram means the exterior differentiation of forms. Moreover, it is known that $E(\lambda) = 0$ if and only if there is a (uniquely determined) *n*-form $\varrho_0 \in \Omega^n(Y)$ such that $h_1(\pi_{10}^* \varrho_0) = \lambda$ and $d\varrho_0 = 0$. If $\lambda \in \Omega_X^n(\mathscr{J}^1 Y)$ is an *n*-form then each $\varrho \in \Omega_{Lep}(\mathscr{J}^1 Y)$ such that $h_1(\varrho) = \lambda$ is called a *Lepagian equivalent* of λ . The map h_1 being a surjection, to each λ there exists a Lepagian equivalent.

An example of a Lepagian equivalent, often used in practice, the *Cartan funda*mental form [2], [3], [4], [8], is provided with the following. Let (x_i, y_{σ}) be some fibre coordinates on Y, $(x_i, y_{\sigma}, z_{i\sigma}, z_{ij\sigma})$ the corresponding fibre coordinates on $\mathscr{J}^2 Y$ $(1 \leq i \leq j \leq n, n = \dim X, 1 \leq \sigma \leq m, m = \dim Y - \dim X)$. Each *n*-form $\lambda \in \Omega_X^n(\mathscr{J}^1 Y)$ is expressed as

$$\lambda = \mathscr{L} \, \mathrm{d} x_1 \wedge \ldots \wedge \, \mathrm{d} x_n \, ,$$

where \mathscr{L} is a function of x_i , y_{σ} , $z_{i\sigma}$. The Cartan fundamental form is then defined by

$$\begin{split} \varrho &= \mathscr{L} \, \mathrm{d} x_1 \wedge \ldots \wedge \, \mathrm{d} x_n + \sum_{i,\sigma} \frac{\partial \mathscr{L}}{\partial z_{i\sigma}} \, \mathrm{d} x_1 \wedge \ldots \wedge \, \mathrm{d} x_{i-1} \wedge \\ & \wedge \left(\mathrm{d} y_{\sigma} - \sum_k z_{k\sigma} \, \mathrm{d} x_k \right) \wedge \, \mathrm{d} x_{i+1} \wedge \ldots \wedge \, \mathrm{d} x_n \, . \end{split}$$

We shall examine another type of Lepagian equivalents better adopted to the conditions for the Euler form $E(\lambda)$ of the Lagrangian λ to vanish.

3. The purpose of this paper is to prove the following

Theorem. There exists an R-linear map $l: \Omega_X^n(\mathcal{J}^1 Y) \to \Omega_{Lep}(\mathcal{J}^1 Y)$ satisfying the following conditions:

1) For each $\lambda \in \Omega^n_X(\mathscr{J}^1Y)$,

$$h_1(l(\lambda)) = \lambda$$
.

2) If $\varrho \in \Omega_Y^n(\mathscr{J}^1Y)$ is of the form $\pi_{10}^*\varrho_0$ for some $\varrho_0 \in \Omega^n(Y)$ then

$$l(h_1(\varrho)) = \varrho \; .$$

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3) If $\lambda \in \Omega_X^n(\mathscr{J}^1Y)$ is a π_1 -horizontal Lagrangian form then the corresponding Euler form is given by

$$E(\lambda) = \tilde{h}(\mathrm{d}\,l(\lambda))$$
.

The equalities

$$dl(\lambda) = 0, \quad E(\lambda) = 0$$

are either both true or both wrong.

Proof. Let us first suppose that we have an *n*-form $\varrho = \pi_{10}^* \varrho_0$, where $\varrho_0 \in \Omega^n(Y)$. In some fibre coordinates (x_i, y_σ) on Y and the corresponding fibre coordinates $(x_i, y_\sigma, z_{i\sigma})$ on $\mathscr{J}^1 Y$, we have

(1)
$$\varrho = g_0 \, \mathrm{d} x_1 \wedge \ldots \wedge \mathrm{d} x_n + \sum \frac{1}{r!} g_{\sigma_1 \ldots \sigma_r}^{s_1 \ldots s_r} \, \mathrm{d} x_1 \wedge \ldots \wedge \mathrm{d} x_{s_1 - 1} \wedge \ldots$$

$$dy_{\sigma_1} \wedge dx_{s_1+1} \wedge \ldots \wedge dx_{s_r-1} \wedge dy_{\sigma_r} \wedge dx_{s_r+1} \wedge \ldots \wedge dx_n$$

where $g_0, g_{\sigma_1...\sigma_r}^{s_1...s_r}$ are functions of x_i and y_{σ} , and we sum over all sequences $r, s_1, ...$..., $s_r, \sigma_1, ..., \sigma_r$ such that $1 \leq r \leq n, 1 \leq s_1 < ... < s_r \leq n, 1 \leq \sigma_1, ..., \sigma_r \leq m$. Then

$$h_1(\varrho) = \mathscr{K} \, \mathrm{d} x_1 \wedge \ldots \wedge \, \mathrm{d} x_n$$

where

$$\mathscr{K} = g_0 + \sum g_{\sigma_1 \dots \sigma_r}^{s_1 \dots s_r} \cdot z_{s_1 \sigma_1} \dots z_{s_r \sigma_r}$$

the range of the summation being the same as above. The following identities can be obtained by differentiating with respect to $z_{k\sigma}$ (see [5]):

(2)
$$g_{\nu_{1}...\nu_{n}}^{1...n} = \frac{\partial^{n} \mathscr{K}}{\partial z_{1\nu_{1}} \dots \partial z_{n\nu_{n}}},$$

...,

$$g_{\nu_{1}...\nu_{p}}^{s_{1}...s_{p}} = \frac{\partial^{p} \mathscr{K}}{\partial z_{s_{1}\nu_{1}} \dots \partial z_{s_{p}\nu_{p}}} - \sum g_{\sigma_{1}...\sigma_{j}}^{k_{1}...k_{j}} \frac{\partial^{p}}{\partial z_{s_{1}\nu_{1}} \dots \partial z_{s_{r}\nu_{p}}} (z_{k_{1}\sigma_{1}} \dots z_{k_{j}\sigma_{j}}),$$

...,

$$g_{0} = \mathscr{K} - \sum g_{\sigma_{1}...\sigma_{r}}^{s_{1}...s_{r}} \cdot z_{s_{1}\sigma_{1}} \dots z_{s_{r}\sigma_{r}}.$$

In the formula for $g_{v_1...v_p}^{s_1...s_p}$, we sum over all sequences satisfying $p + 1 \leq j \leq n$, $1 \leq k_1 < ... < k_j \leq n$, $1 \leq \sigma_1, ..., \sigma_j \leq m$. With the help of the formulas (2), we are able to reconstruct the *n*-form ϱ from the known expression for \mathcal{K} .

Let now λ be any *n*-form from the space $\Omega_X^n(\mathscr{J}^1Y)$. In our fibre coordinates,

$$\lambda = \mathscr{L} \, \mathrm{d} x_1 \wedge \ldots \wedge \mathrm{d} x_n \,,$$

where \mathscr{L} is a function depending on x_i , y_σ , $z_{i\sigma}$. Taking into account the preceding remark we define an *n*-form by the right-hand side of (1) setting

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$$(3) \quad g_{\sigma_{1}...\sigma_{n}}^{1...n} = \frac{1}{n!} \varepsilon_{k_{1}...k_{n}}^{1...n} \frac{\partial^{n} \mathscr{L}}{\partial z_{k_{1}\sigma_{1}} \dots \partial z_{k_{n}\sigma_{n}}},$$

$$\dots,$$

$$g_{\sigma_{1}...\sigma_{r}}^{s_{1}...s_{r}} = \frac{1}{r!} \varepsilon_{k_{1}...k_{r}}^{s_{1}...s_{r}} \left(\frac{\partial^{r} \mathscr{L}}{\partial z_{k_{1}\sigma_{1}} \dots \partial z_{k_{r}\sigma_{r}}} - \sum g_{\nu_{1}...\nu_{j}}^{l_{1}...l_{j}} \frac{\partial^{r}}{\partial z_{s_{1}\nu_{1}} \dots \partial z_{s_{r}\nu_{r}}} (z_{k_{1}\sigma_{1}} \dots z_{k_{j}\sigma_{j}}) \right),$$

$$\dots,$$

$$g_{0} = \mathscr{L} - \sum g_{\sigma_{1}...\sigma_{r}}^{s_{1}...s_{r}} \dots z_{s_{r}\sigma_{r}}.$$

In these formulas, $\varepsilon_{pqr...}^{ijk...}$ denotes the totally antisymmetric symbol equal to 1 when (pqr...) is an even permutation of (ijk...), -1 when (pqr...) is an odd permutation of (ijk...), and 0 in all the other cases. It follows from the definition that the coordinate expression for $l(\lambda)$ is invariant under coordinate changes which means that $l(\lambda) \in \Omega_{Y}^{n}(\mathscr{J}^{1}Y)$.

We shall show that the map $\lambda \to l(\lambda)$ satisfies all conditions of the theorem. First we are to prove that for each λ the *n*-form $l(\lambda)$ is Lepagian. We use for this purpose a coordinate formula for $\tilde{h}(d\varrho)$, where $\varrho \in \Omega_Y^n(\mathscr{J}^1Y)$, derived in [6]. If ϱ is expressed by (1), where g_0 and $g_{\sigma_1...\sigma_r}^{s_1...s_r}$ are functions of all variables $x_i, y_{\sigma}, z_{i\sigma}$, then

$$\tilde{h}(\mathrm{d}\varrho) = \left(\left(\frac{\partial \mathscr{K}}{\partial y_{\sigma}} - \mathrm{d}_{i} \mathscr{B}_{i\sigma} \right) \mathrm{d}y_{\sigma} + \left(\frac{\partial \mathscr{K}}{\partial z_{i\sigma}} - \mathscr{B}_{i\sigma} \right) \mathrm{d}z_{i\sigma} \right) \wedge \mathrm{d}x_{1} \wedge \ldots \wedge \mathrm{d}x_{n} ,$$

where \mathscr{K} is defined by

$$h_1(\varrho) = \mathscr{K} \, \mathrm{d} x_1 \wedge \ldots \wedge \, \mathrm{d} x_n$$

and

$$\mathcal{B}_{i\sigma} = \sum g^{s_1 \dots s_r}_{\sigma_1 \dots \sigma_r} \frac{\partial}{\partial z_{i\sigma}} (z_{s_1 \sigma_1} \dots z_{s_r \sigma_r}) \,.$$

The symbol d_i stands for the formal derivative operator [5]. By definition, ϱ is Lepagian if and only if

(4)
$$\mathscr{B}_{i\sigma} = \frac{\partial \mathscr{H}}{\partial z_{i\sigma}}$$

(see [6]).

To show that this condition is satisfied by $l(\lambda)$ we use the definition of q_0 and g^i_{σ} (3) obtaining

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which gives

$$\frac{\partial g_0}{\partial z_{i\sigma}} + \sum \frac{\partial g^{s_1...s_r}_{\sigma_1...\sigma_r}}{\partial z_{i\sigma}} \, z_{s_1\sigma_1} \dots \, z_{s_r\sigma_r} = 0 ,$$

proving (4). This means that the *n*-form $l(\lambda)$ is Lepagian.

It remains to prove the equalities 1)-3) of the theorem. The first two of them are easy consequences of the definition of $l(\lambda)$. Since $l(\lambda)$ is Lepagian, the equality $E(\lambda) =$ $= \tilde{h}(dl(\lambda))$ follows from the diagram of section 2. If $dl(\lambda) = 0$ then this equality immediately implies $E(\lambda) = 0$. To prove the converse let us assume that $E(\lambda) = 0$. Then there is a unique $\varrho_0 \in \Omega^n(Y)$ such that $h_1(\pi_{10}^*\varrho_0) = \lambda$ and $d\varrho_0 = 0$ (see section 2). According to 2), $l(\lambda) = l(h_1(\pi_{10}^*\varrho_0)) = \pi_{10}^*\varrho_0$ ad we get $dl(\lambda) = 0$. This completes the proof.

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