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EXISTENCE THEOREM FOR A GENERALIZED HAMMERSTEIN TYPE
EQUATION

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Abstract: An existence theorem is obtained for a generalized Hammerstein type equation.

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In [4] Browder has obtained an existence theorem for a generalized Hammerstein type equation

$$(1) \quad \mu + \sum_{i=1}^m A_i F_i \mu = 0$$

where each A_i is a linear operator from a function space X to its dual space X^* and F_i is a nonlinear operator from X^* to X . Each linear operator A_i is assumed to be angle-bounded and the nonlinear operators F_1, F_2, \dots, F_m satisfy a condition of the type

$$(2) \quad \sum_{i=1}^m (F_i(\mu) - F_i(\nu), \mu_i - \nu_i) \geq -c \sum_{i=1}^m \|\mu_i - \nu_i\|_{X^*}^2$$

where c is some constant and $\mu = \sum_{i=1}^m \mu_i, \nu = \sum_{i=1}^m \nu_i$.

Condition (2), though a natural generalization of the monotonicity condition, is rather hard to verify. In this paper we weaken this condition on the operators F_1, \dots, F_m by assuming additional hypothesis of compactness on the linear operators A_j . In the application of this theory to the case where the A_j are integral operators, the assumption of compactness is a natural one.

We now introduce the following definitions:

Let X be a real Banach space, X^* its dual and let (w, μ) denote the duality pairing between the elements w in X^* and μ in X .

Definition 1. A mapping T from X to X^* is said to be of the type (M) if the following conditions hold:

(M₁) - If a sequence $\{\mu_m\}$ in X converges weakly to an element μ in X (written $\mu_m \rightharpoonup \mu$), the sequence $T\mu_m \rightarrow w$ in X^* and $\limsup (T\mu_m, \mu_m) \leq (w, \mu)$, then $T\mu = w$.

(M₂) - T is continuous from finite dimensional subspaces of X to the space X^* endowed with the weak*-topology.

It should be observed that if T is monotone and continuous then T is of type (M) [2]. The concept of mappings of type (M) was first introduced by Brezis [2] using filters and later used by de Figueiredo and Gupta in [5].

Definition 2. If T is a bounded monotone linear map of X into X^* , then T is said to be angle-bounded

with constant $\alpha \geq 0$ if for all u, v in X

$$|(Tu, v) - (Tv, u)| \leq 2\alpha \{(Tu, u)\}^{1/2} \{(Tv, v)\}^{1/2} .$$

It is clear that every monotone map T which is symmetric is angle-bounded with $\alpha = 0$. In proving existence theorem we shall appeal to Proposition 3 of [5] and Theorem 4 of [3] which we now state.

Proposition 1 (de Figueiredo and Gupta). Let X be a reflexive Banach space and T be a bounded mapping of type (M) from X to X^* . Suppose that the mapping T satisfies the following condition:

There exists $R > 0$ such that

$$(3) \quad (Tx, x) > 0 \text{ for } \|x\| > R .$$

Then the range of T is all of X^* .

Theorem 1 (Browder and Gupta). Let X be a Banach space, X^* its dual, T a bounded linear mapping of X into X^* which is monotone and angle-bounded. Then there exists a Hilbert space H , a continuous linear mapping S of X into H with S^* injective and a bounded skew-symmetric linear mapping B of H into H such that $T = S^*(I+B)S$ and the following inequalities hold:

(i) $\|B\| \leq \alpha$, with α the constant of angle-boundedness of T

(ii) $\|S\|^2 \leq R$ if and only if for all u in X ,

$$(Tu, u) \leq R \|u\|_X^2$$

(iii) $[(I+B)^{-1}h, h]_H \geq (1 + \alpha^2)^{-1} \|h\|_H^2$ for

all λ in H .

We are now in a position to state and prove our existence theorem.

Theorem 2. Let X be a Banach space and X^* its dual. Let $\{K_1, \dots, K_m\}$ be a finite family of bounded, linear, monotone and compact operators from X to X^* with constant of angle-boundedness $\alpha \geq 0$ and $\|K_i\| \leq K_0$ for each i . Let $\{F_1, \dots, F_m\}$ be a corresponding finite family of continuous, bounded nonlinear operators from X^* to X which satisfy the following condition:

For every m -tuple $\{\mu_1, \mu_2, \dots, \mu_m\}$

$$(4) \quad \sum_{i=1}^m (F_i(\mu), \mu_i) \geq -c \sum_{i=1}^m \|\mu_i\|_{X^*}^2 + \sum_{i=1}^m (F_i(0), \mu_i)$$

where $\mu = \sum_{i=1}^m \mu_i$ and $c < (1 + \alpha^2)^{-1} K_0^{-1}$.

Then the equation

$$(5) \quad \mu + \sum_{i=1}^m K_i F_i \mu = 0$$

has a solution in X^* .

Proof: We first prove the following lemma.

Lemma 1. Let T be a continuous mapping from X to X^* such that $T = T_1 + T_2$ where T_1 satisfies the condition

$$(6) \quad (T_1 x - T_1 y, x - y) \geq \phi(\|x - y\|) \quad \text{for all } x, y$$

$$\phi(\kappa) \geq 0, \quad \phi(\kappa) = 0 \quad \text{iff } \kappa = 0$$

and T_2 is compact.

Then T is of type (M) .

Proof: Since T is continuous, it suffices to show that T satisfies condition (M_1) of Definition 1. Let $u_m \rightarrow u$ and $Tu_m \rightarrow w$ and $\limsup (Tu_m, u_m) \leq (w, u)$. Then we have

$$\begin{aligned} c(\|u_m - u\|) &\leq (T_1 u_m - T_1 u, u_m - u) \\ &= (Tu_m - Tu, u_m - u) - (T_2 u_m - T_2 u, u_m - u) \\ &= (Tu_m, u_m) - (Tu_m, u) - (Tu, u_m - u) - (T_2 u_m - T_2 u, u_m - u) . \end{aligned}$$

Since $u_m \rightarrow u$ and T_2 is compact, there exists a subsequence (which in turn will be denoted by u_m) such that $T_2 u_m \rightarrow y$. So we have

$$\begin{aligned} \limsup c(\|u_m - u\|) &\leq \limsup (Tu_m, u_m) - (w, u) \\ &\leq (w, u) - (w, u) \\ &\leq 0 \end{aligned}$$

which implies that $u_m \rightarrow u$. Since T is continuous $Tu_m \rightarrow Tu = w$, i.e. T satisfies condition (M_1) of Definition 1.

We now proceed to prove the main theorem. Since each K_i is angle-bounded, by Theorem 2 for each i there exists a Hilbert space H_i , a continuous linear mapping $S_i : X \rightarrow H_i$ with S_i^* injective and a bounded linear skew-symmetric mapping B_i of H_i to H_i such that

$$(7) \quad K_i = S_i^* (I + B_i) S_i, \quad \|B_i\| \leq \alpha, \quad \|S_i\|^2 \leq K_0$$

and $[(I + B_i)^{-1} h_i, h_i]_{H_i} \geq (1 + \alpha^2)^{-1} \|h_i\|_{H_i}^2$ for all h_i in H_i .

We form a Hilbert space H , as the orthogonal direct sum

$H = \sum_{i=1}^m \oplus H_i$. An element h of H is an m -tuple $\{h_1, \dots, h_m\}$ with h_i in H_i , while $\|h\|_H^2 = \sum_{i=1}^m \|h_i\|_{H_i}^2$.

We define a mapping $S: X \rightarrow H$ by

$$Su = \{S_1 u, S_2 u, \dots, S_m u\}.$$

Then $S^* h = \sum_{i=1}^m S_i^* h_i$, $h = \{h_1, \dots, h_m\}$.

If u is a solution of (5), then (7) gives

$$(8) \quad u + \sum_{i=1}^m S_i^* (I + B_i) S_i F_i u = 0.$$

Since S^* is injective, there exists a unique h in H such that

$$(9) \quad S^* h + \sum_{i=1}^m S_i^* (I + B_i) F_i S^* h = 0$$

which implies that

$$(10) \quad h + \sum_{i=1}^m (I + B_i) S_i F_i S^* h = 0.$$

Taking projections we get

$$(11) \quad h_i + (I + B_i) S_i F_i S^* h = 0, \quad i = 1, 2, \dots, m$$

$$(12) \quad (I + B_i)^{-1} h_i + S_i F_i S^* h = 0, \quad i = 1, 2, \dots, m.$$

This can be written as an operator equation

$$Th \equiv T_1 h + T_2 h = 0 \text{ in } H,$$

where

$$(T_1 h)_i = (I + B_i)^{-1} h_i$$

$$(T_2 h)_i = S_i F_i S^* h .$$

(7) gives

$$\begin{aligned} [T_1 h, h]_H &= \sum_{i=1}^m [(I + B_i)^{-1} h_i, h_i]_{H_i} \\ &\geq (1 + a^2)^{-1} \sum_{i=1}^m \|h_i\|^2 \\ &= (1 + a^2)^{-1} \|h\|_H^2 , \end{aligned}$$

i.e.

$$(13) \quad [T_1 h, h]_H \geq (1 + a^2)^{-1} \|h\|_H^2 .$$

Also using (4) and (7) we get

$$\begin{aligned} [Th, h] &= [T_1 h, h] + [T_2 h, h] \\ &= \sum_{i=1}^m [(I + B_i)^{-1} h_i, h_i]_{H_i} + \sum_{i=1}^N [S_i F_i S^* h, h_i]_{H_i} \\ &\geq (1 + a^2)^{-1} \|h\|_H^2 + \sum_{i=1}^m (F_i(S^* h), S_i^* h_i) \\ &\geq (1 + a^2)^{-1} \|h\|_H^2 - c \sum_{i=1}^m \|S_i^* h_i\|^2 + \sum_{i=1}^m (F_i(0), S_i^* h_i) \\ &\geq (1 + a^2)^{-1} \|h\|_H^2 - c K_0 \sum_{i=1}^m \|h_i\|^2 - \sum_{i=1}^m \|F_i(0)\| \|S_i^* h_i\| \\ &\geq (1 + a^2)^{-1} \|h\|_H^2 - c K_0 \|h\|_H^2 - \left(\sum_{i=1}^m \|F_i(0)\|^2 \right)^{1/2} \left(\sum_{i=1}^m \|S_i^* h_i\|^2 \right)^{1/2} \\ &\geq [(1 + a^2)^{-1} - c K_0] \|h\|_H^2 - \left(\sum_{i=1}^m \|F_i(0)\|^2 \right)^{1/2} K_0^{1/2} \left(\sum_{i=1}^m \|h_i\|_H^2 \right)^{1/2} \\ &= [(1 + a^2)^{-1} - c K_0] \|h\|_H^2 - \left(\sum_{i=1}^m \|F_i(0)\|^2 \right)^{1/2} K_0^{1/2} \|h\|_H \\ &= \left[c_0 - \left(\sum_{i=1}^m \frac{\|F_i(0)\|^2}{\|h_i\|_H^2} \right)^{1/2} K_0^{1/2} \right] \|h\|_H^2 \end{aligned}$$

where $c_0 = (1 + \alpha^2)^{-1} - cK_0 > 0$ by assumption on the constants. Hence there exists $R > 0$ such that $[Th, h] > 0$ for all $\|h\|_H > R$.

Since each K_i is compact, by Amann [1] each S_i in the splitting (7) is compact and therefore T_2 is compact. Thus the continuous operator T is the sum of the operator T_1 and T_2 where T_1 is linear and satisfies (6) and T_2 is compact. Therefore by Lemma 1 T is of typ (M). Furthermore T is bounded because each S_i and F_i is bounded and satisfies the condition that $[Th, h] > 0$ for $\|h\|_H > R > 0$. So it follows by Proposition 1 that there exists a solution h in H of (10). This implies that S^*h is a solution of (8) and therefore of (5). This completes the proof.

Remark. Our Lemma 1 is similar to the Proposition 1.1 of [6] with the exception that our hypotheses are different.

R e f e r e n c e s

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