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# ON AN INTEGRAL OPERATOR IN THE SPACE OF FUNCTIONS WITH BOUNDED VARIATION 

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## 1. BASIC NOTATIONS

Let $R^{n}$ be the $n$-dimensional real vector space. Let $A=\left(a_{i j}\right), i=1, \ldots, k$, $j=1, \ldots, l$ be a $k \times l$-matrix $\left(a_{i j}\right.$ is the element of $A$ from the $i$-th row and $j$-th column). By $\boldsymbol{A}^{\prime}$ let us denote the transposed matrix of $\boldsymbol{A}$. For a $k \times l$-matrix $A$ we define the number $\|\boldsymbol{A}\|=\max _{i=1, \ldots, k} \sum_{j=1}^{l}\left|a_{i j}\right|$. The elements $\mathbf{x}$ of $R^{n}$ are column vectors (i.e. $n \times 1$-matrices). $\|\cdot\|$ is a norm in $R^{n}$. The space of all $n \times n$-matrices let be denoted by $L\left(R^{n} \rightarrow R^{n}\right) .\|$.$\| is a norm in L\left(R^{n} \rightarrow R^{n}\right)$ (the obvious operator norm corresponding to the given norm in $R^{n}$ ). We have evidently $\left\|A^{\prime}\right\| \leqq n\|A\|,\left\|x^{\prime}\right\| \leqq$ $\leqq n\|\mathrm{x}\|$ for $A \in L\left(R^{n} \rightarrow R^{n}\right), \mathrm{x} \in R^{n}$ respectively.

Let $\langle a, b\rangle \subset R=R^{1}$ be a bounded closed interval, $a<b$. For a given vector function $\mathbf{x}(t), \mathbf{x}:\langle a, b\rangle \rightarrow R^{n}$ we define the (total) variation of $\mathbf{x}$ on $\langle a, b\rangle$ as usual:

$$
\operatorname{var}_{a}^{b} x=\sup _{D} \sum_{i=1}^{m}\left\|x\left(t_{i}\right)-x\left(t_{i-1}\right)\right\|
$$

where the supremum is taken over all finite decompositions $D: a=t_{0}<t_{1}<\ldots$ $\ldots<t_{m}=b$ of $\langle a, b\rangle$.

We denote

$$
V_{n}(a, b)=\left\{\mathrm{x}:\langle a, b\rangle \rightarrow R^{n} ; \operatorname{var}_{a}^{b} \mathrm{x}<+\infty\right\} .
$$

If no misunderstanding may occur, we write simply $V_{n}$ instead of $V_{n}(a, b)$. If $n=1$ we write $V(a, b)$ or $V$ instead of $V_{1}(a, b)$ or $V_{1}$.

The following statement is obvious: $x \in V_{n}(a, b)$ if and only if $x_{i} \in V(a, b)$ for all $i=1, \ldots, n, \mathbf{x}^{\prime}=\left(x_{1}, \ldots, x_{n}\right)$. The inequality

$$
\begin{equation*}
\operatorname{var}_{a}^{b} x_{i} \leqq \operatorname{var}_{a}^{b} x \tag{1,1}
\end{equation*}
$$

is satisfied for all $i=1,2, \ldots, n$.

For $\mathbf{x} \in V_{n}(a, b)$ the limits $\lim _{\tau \rightarrow t^{+}} \mathbf{x}(\tau)=\mathbf{x}(t+), \lim _{\tau \rightarrow t^{-}} \mathbf{x}(\tau)=\mathbf{x}(t-)$ exist for all $t \in\langle a, b\rangle$. We use the notations

$$
\begin{gathered}
\Delta^{+} x(t)=x(t+)-x(t), \quad \Delta^{-} x(t)=x(t)-x(t-), \\
\Delta x(t)=x(t+)-x(t-)=\Delta^{+} x(t)+\Delta^{-} x(t)
\end{gathered}
$$

## 2. THE INTEGRAL

For our purpose we use the concept of the generalized Perron-Stieltjes integral introduced by J. Kurzweil in [1].

Let $f:\langle a, b\rangle \rightarrow R, g:\langle a, b\rangle \rightarrow R$ be given. If $g(t)$ is not defined for $t<a$ and $t>b$ then we suppose that $g(t)=g(a)$ for $t<a$ and $g(t)=g(b)$ for $t>b$. For $\langle c, d\rangle \subset\langle a, b\rangle$ we denote

$$
\int_{c}^{d} f(t) \mathrm{d} g(t)=\int_{c}^{d} \mathrm{D} f(\tau) g(t)
$$

where the right hand side is the Kurzweil integral ([1]) of the function $U(\tau, t)=$ $=f(\tau) g(t)$. In [1] the following is shown:

If $f:\langle a, b\rangle \rightarrow R$ is finite and $g \in V(c, d)$ then the integral $\int_{c}^{d} f(t) \mathrm{d} g(t)$ exists if and only if the Perron-Stieltjes integral (P.S.) $\int_{c}^{d} f(t) \mathrm{d} g(t)$ exists (in the usual sense) and both integrals are equal.

Further we have: If $f, g:\langle a, b\rangle \rightarrow R,\langle c, d\rangle \subset\langle a, b\rangle, f \in V(c, d), g \in V(c, d)$ then the integral $\int_{c}^{d} f(t) \mathrm{d} g(t)$ exists.

This follows essentially from the same statement which holds for the PerronStieltjes integral and the above quoted equivalence of both concepts of integral.

If $|f(t)| \leqq M$ for $t \in\langle a, b\rangle$ and $g \in V(c, d),\langle c, d\rangle \subset\langle a, b\rangle$ then

$$
\left|f(\tau)\left(g\left(t_{2}\right)-g\left(t_{1}\right)\right)\right| \leqq M \operatorname{var}_{t_{1}}^{t_{2}} g \leqq M\left|\operatorname{var}_{c}^{t_{2}} g-\operatorname{var}_{c}^{t_{1}} g\right|
$$

for all $t_{1}, t_{2}, \tau \in\langle c, d\rangle$. From this inequality and from Lemma 2,1 in [3] the following proposition immediately follows:

If $f:\langle a, b\rangle \rightarrow R,|f(t)| \leqq M$ for all $t \in\langle a, b\rangle, g \in V(c, d)$ and if $\int_{c}^{d} f(t) \mathrm{d} g(t)$ exists, then

$$
\begin{equation*}
\left|\int_{c}^{d} f(t) \mathrm{d} g(t)\right| \leqq M \int_{c}^{d} \mathrm{~d}\left(\operatorname{var}_{c}^{t} g\right)=M \operatorname{var}_{c}^{d} g . \tag{2,1}
\end{equation*}
$$

If $f \in V(a, b)$ then obviously the inequality $|f(t)| \leqq|f(a)|+\operatorname{var}_{a}^{b} f$ holds for all $t \in\langle a, b\rangle$. Let $g \in V(c, d),\langle c, d\rangle \subset\langle a, b\rangle$. By $(2,1)$ we obtain

$$
\begin{equation*}
\left|\int_{c}^{d} f(t) \mathrm{d} g(t)\right| \leqq\left(|f(a)|+\operatorname{var}_{a}^{b} f\right) \operatorname{var}_{c}^{d} g \tag{2,2}
\end{equation*}
$$

From $(2,2)$ we can easily obtain that for $f, g \in V(a, b)$ the function $\int_{a}^{t} f(\tau) \mathrm{d} g(\tau)$ : $:\langle a, b\rangle \rightarrow R$ belongs to $V(a, b)$, namely, the inequality

$$
\operatorname{var}_{a}^{b}\left(\int_{a}^{t} f(\tau) \mathrm{d} g(\tau)\right) \leqq\left(|f(a)|+\operatorname{var}_{a}^{b} f\right) \operatorname{var}_{a}^{b} g<+\infty
$$

holds.

Proposition 2,1. Let $f, g \in V(a, b)$. For $\alpha \in\langle a, b\rangle, t \in\langle a, b\rangle$ we define $\psi_{\alpha}^{+}(t)=0$ for $t \leqq \alpha, \psi_{\alpha}^{+}(t)=1$ for $\alpha<t$ if $\alpha<b$ and $\psi_{\alpha}^{-}(t)=0$ for $t<\alpha$ if $a<\alpha, \psi_{\alpha}^{-}(t)=1$ for $\alpha \leqq t$.

Then we have

$$
\begin{align*}
& \int_{a}^{b} \psi_{\alpha}^{+}(t) \mathrm{d} g(t)= \begin{cases}g(b)-g(\alpha+) & \text { if } \alpha<b \\
0 & \text { if } \alpha=b\end{cases}  \tag{2,3}\\
& \int_{a}^{b} \psi_{\alpha}^{-}(t) \mathrm{d} g(t)= \begin{cases}g(b)-g(\alpha-) & \text { if } a<\alpha \\
g(b)-g(a) & \text { if } a=\alpha\end{cases}
\end{align*}
$$

and

$$
\begin{align*}
& \int_{a}^{b} f(t) \mathrm{d} \psi_{a}^{+}(t)=\left\{\begin{array}{lll}
f(\alpha) & \text { if } \alpha<b \\
0 & \text { if } \alpha=b
\end{array}\right.  \tag{2,4}\\
& \int_{a}^{b} f(t) \mathrm{d} \psi_{\alpha}^{-}(t)=\left\{\begin{array}{lll}
f(\alpha) & \text { if } \alpha>a \\
0 & \text { if } \alpha=a
\end{array}\right.
\end{align*}
$$

Proof. If $\alpha=b$ then $\int_{a}^{b} \psi_{a}^{+}(t) \mathrm{d} g(t)=\int_{a}^{b} 0 . \mathrm{d} g(t)=0$. Let $\alpha<b$. Then we have

$$
\int_{a}^{b} \psi_{a}^{+}(t) \mathrm{d} g(t)=\int_{a}^{\alpha+\delta} \psi_{a}^{+}(t) \mathrm{d} g(t)+g(b)-g(\alpha+\delta)
$$

for all $0<\delta<b-\alpha$ because

$$
\int_{a+\delta}^{b} \psi_{a}^{+}(t) \mathrm{d} g(t)=\int_{a+\delta}^{b} \mathrm{~d} g(t)=g(b)-g(\alpha+\delta)
$$

By Theorem 1, 3, 6 [1] there is

$$
\lim _{\delta \rightarrow 0+} \int_{a}^{\alpha+\delta} \psi_{\alpha}^{+}(t) \mathrm{d} g(t)=\int_{a}^{\alpha} \psi_{\alpha}^{+}(t) \mathrm{d} g(t)+\lim _{\delta \rightarrow 0+} \psi_{\alpha}^{+}(\alpha)[g(\alpha+\delta)-g(\alpha)]=0
$$

since $\int_{a}^{\alpha} \psi_{a}^{+}(t) \mathrm{d} g(t)=\int_{a}^{\alpha} 0 \mathrm{~d} g(t)=0$ and $\psi_{a}^{+}(\alpha)=0$. For $\delta \rightarrow 0+$ so we obtain the first equation from $(2,3)$. The second one can be proved similarly.

We verify for example the second formula from (2,4). The first one can be verified in a similar manner. If $\alpha=a$ then $\psi_{\alpha}^{-}(t)=1$ in $\langle a, b\rangle$. For every $0<\delta<b-a$ we have $f\left(\tau_{0}\right)\left(\psi_{a}^{-}(\tau)-\psi_{a}^{-}\left(\tau_{0}\right)\right)=0$ for each $\tau_{0} \in\langle a+\delta, b\rangle$ and $\tau_{0}-\delta<\tau<$ $<+\infty$. By Lemma 1, 3, 1[1] we obtain therefore $\int_{a+\delta}^{b} f(t) d \psi_{a}^{-}(t)=0$. This implies

$$
\int_{a}^{b} f(t) \mathrm{d} \psi_{a}^{-}(t)=\int_{a}^{a+\delta} f(t) \mathrm{d} \psi_{a}^{-}(t)
$$

for each $0<\delta<b-a$ and by Theorem 1, 3, 6 [1] we have

$$
\int_{a}^{b} f(t) \mathrm{d} \psi_{a}^{-}(t)=f(a) \Delta^{+} \psi_{a}^{-}(a)=0
$$

Let $a<\alpha \leqq b$. By the same reason as above we have $\int_{a}^{b} f(t) \mathrm{d} \psi_{a}^{-}(t)=\int_{a-\delta}^{\alpha+\delta} f(t)$. . $\mathrm{d} \psi_{a}^{-}(t)$ if $\alpha<b$ and $\int_{a}^{b} f(t) \mathrm{d} \psi_{\alpha}^{-}(t)=\int_{\alpha-\delta}^{b} f(t) \mathrm{d} \psi_{a}^{-}(t)$ if $\alpha=b$ for all sufficiently small $\delta>0$. Using Theorem 1, 3, 6 [1] we can evaluate

$$
\begin{aligned}
& \lim _{\delta \rightarrow 0+} \int_{\alpha-\delta}^{\alpha+\delta} f(t) \mathrm{d} \psi_{\alpha}^{-}(t)=\lim _{\delta \rightarrow 0+}\left(\int_{\alpha-\delta}^{\alpha}+\int_{\alpha}^{\alpha+\delta}\right) f(t) \mathrm{d} \psi_{\alpha}^{-}(t)= \\
& \quad=f(\alpha) \Delta^{-} \psi_{\alpha}^{-}(\alpha)+f(\alpha) \Delta^{+} \psi_{\alpha}^{-}(\alpha)=f(\alpha) \Delta \psi_{\alpha}^{-}(\alpha)=f(\alpha)
\end{aligned}
$$

if $\alpha<b$ and similarly

$$
\lim _{\delta \rightarrow 0+} \int_{a-\delta}^{b} f(t) \mathrm{d} \psi_{a}^{-}(t)=f(b) \Delta^{-} \psi_{b}^{-}(b)=f(b)
$$

if $\alpha=b$. Therefore the second equation in $(2,4)$ holds.
Corollary 2,1. If $\alpha \in\langle a, b\rangle, \psi_{a}(t)=0$ for $t \in\langle a, b\rangle, t \neq \alpha, \psi_{a}(\alpha)=1, g \in V(a, b)$ then we have by $(2,3)$

$$
\begin{equation*}
\int_{a}^{b} \psi_{a}(t) \mathrm{d} g(t)=g(\alpha+)-g(\alpha-)=\Delta g(\alpha) \tag{2,5}
\end{equation*}
$$

since $\psi_{a}(t)=\psi_{a}^{-}(t)-\psi_{a}^{+}(t)$ for $t \in\langle a, b\rangle$.
Let a countable set $\left(t_{1}, t_{2}, \ldots\right)$ of points in $\langle a, b\rangle$ be given, $t_{i} \neq t_{j}$ for $i \neq j$ and let us have two sequences $c_{i}^{+}, c_{i}^{-}, i=1,2, \ldots$ of real numbers such that the series $\sum_{a \leqq t_{i}<b} c_{i}^{+}, \sum_{a<t_{i} \leqq b} c_{i}^{-}$converge absolutely. The function

$$
g_{B}(t)=\sum_{a \leqq t_{i}<t} c_{i}^{+}+\sum_{a<t_{i} \leqq t} c_{i}^{-}
$$

will be called a break function in $\langle a, b\rangle$. For this break function $g_{B}(t)$ we have evidently

$$
\operatorname{var}_{a}^{b} g_{B}=\sum_{a<t_{i} \leqq b}\left|c_{i}^{-}\right|+\sum_{a \leq t_{i}<b}\left|c_{i}^{+}\right|<+\infty
$$

$\Delta^{+} g_{B}(t)=\Delta^{-} g_{B}(t)=0$ if $t \neq t_{i}, i=1,2, \ldots$ and $\Delta^{+} g_{B}\left(t_{i}\right)=c_{i}^{+}, \Delta^{-} g_{B}\left(t_{i}\right)=c_{i}^{-}$, $i=1,2, \ldots$

Using the functions $\psi_{\alpha}^{+}$and $\psi_{\alpha}^{-}$introduced in Proposition 2,1 we can evidently express the break function in the form

$$
\begin{aligned}
g_{B}(t) & =\sum_{i=1}^{\infty}\left[c_{i}^{+} \psi_{t_{i}}^{+}(t)+c_{i}^{-} \psi_{t_{i}}^{-}(t)\right]= \\
& =\sum_{i=1}^{\infty}\left[\Delta^{+} g_{B}\left(t_{i}\right) \psi_{t_{i}}^{+}(t)+\Delta^{-} g_{B}\left(t_{i}\right) \psi_{t_{i}}^{-}(t)\right] .
\end{aligned}
$$

Remark 2,1. The notion of a break function can be similarly introduced for $n$ vector functions too; for this case it is sufficient to take $c_{i}^{+} \in R^{n}, c_{i}^{-} \in R^{n}$ and repeat the above procedure where instead of $|$.$| should be written \|$.$\| .$

Proposition 2,2. Let $g_{B} \in V(a, b)$ be a break function. If $f \in V(a, b)$ then

$$
\begin{equation*}
\int_{a}^{b} f(t) \mathrm{d} g_{B}(t)=f(a) \Delta^{+} g_{B}(a)+\sum_{a<\tau<b} f(\tau) \Delta g_{B}(\tau)+f(b) \Delta^{-} g_{B}(b) \tag{2,6}
\end{equation*}
$$

Proof. Since $g_{B}$ is a break function there exists a sequence $\left\{t_{i}\right\}, t_{i} \in\langle a, b\rangle, t_{i} \neq t_{j}$ for $i \neq j$ such that

$$
g_{B}(t)=\sum_{i=1}^{\infty}\left[\Delta^{+} g_{B}\left(t_{i}\right) \psi_{t_{i}}^{+}(t)+\Delta^{-} g_{B}\left(t_{i}\right) \psi_{t_{i}}^{-}(t)\right] .
$$

We put

$$
g_{B}^{N}(t)=\sum_{i=1}^{N}\left[\Delta^{+} g_{B}\left(t_{i}\right) \psi_{t_{i}}^{+}(t)+\Delta^{-} g_{B}\left(t_{i}\right) \psi_{t_{i}}^{-}(t)\right]
$$

We have

$$
\begin{aligned}
\operatorname{var}_{a}^{b}\left(g_{B}-g_{B}^{N}\right)= & \operatorname{var}_{a}^{b}\left(\sum_{i=N+1}^{\infty}\left[\Delta^{+} g\left(t_{i}\right) \psi_{t_{i}}^{+}(t)+\Delta^{-} g\left(t_{i}\right) \psi_{t_{i}}^{-}(t)\right]=\right. \\
& =\sum_{i=N+1}^{\infty}\left[\left|\Delta^{+} g\left(t_{i}\right)\right|+\left|\Delta^{-} g\left(t_{i}\right)\right|\right]
\end{aligned}
$$

The relation $g \in V(a, b)$ implies the convergence of the series $\sum_{i=1}^{\infty}\left[\left|\Delta^{+} g\left(t_{i}\right)\right|+\right.$ $\left.+\left|\Delta^{-} g\left(t_{i}\right)\right|\right]$ and therefore we have

$$
\lim _{N \rightarrow \infty} \operatorname{var}_{a}^{b}\left(g_{B}-g_{B}^{N}\right)=0
$$

Hence by $(2,2)$ we obtain

$$
\lim _{N \rightarrow \infty}\left|\int_{a}^{b} f(t) \mathrm{d} g_{B}(t)-\int_{a}^{b} f(t) \mathrm{d} g_{B}^{N}(t)\right| \leqq \lim _{N \rightarrow \infty}\left[|f(a)|+\operatorname{var}_{a}^{b} f\right] \operatorname{var}_{a}^{b}\left(g_{B}-g_{B}^{N}\right)=0
$$

i.e.

$$
\begin{equation*}
\int_{a}^{b} f(t) \mathrm{d} g_{B}(t)=\lim _{N \rightarrow \infty} \int_{a}^{b} f(t) \mathrm{d} g_{B}^{N}(t) \tag{2,7}
\end{equation*}
$$

Using ( 2,4 ) we have

$$
\begin{aligned}
\int_{a}^{b} f(t) \mathrm{d} g_{B}^{N}(t) & =\sum_{i=1}^{N} \int_{a}^{b} f(t) \mathrm{d}\left[\Delta^{+} g_{B}\left(t_{i}\right) \psi_{t_{i}}^{+}(t)+\Delta^{-} g_{B}\left(t_{i}\right) \psi_{t_{i}}^{-}(t)\right]= \\
& =\sum_{i=1}^{N}\left[\Delta^{+} g_{B}\left(t_{i}\right) \int_{a}^{b} f(t) \mathrm{d} \psi_{t_{i}}^{+}(t)+\Delta^{-} g_{B}\left(t_{i}\right) \int_{a}^{b} f(t) \mathrm{d} \psi_{t_{i}}^{-}(t)\right]= \\
& =\sum_{i=1}^{N}\left[\Delta^{+} g_{B}\left(t_{i}\right) f\left(t_{i}\right)+\Delta^{-} g_{B}\left(t_{i}\right) f\left(t_{i}\right)\right]= \\
& =\sum_{i=1}^{N} f\left(t_{i}\right)\left[\Delta^{+} g_{B}\left(t_{i}\right)+\Delta^{-} g_{B}\left(t_{i}\right)\right] .
\end{aligned}
$$

This and $(2,7)$ give $(2,6)$ and Proposition 2,2 is proved.
Corollary 2,2. If $g \in V(a, b)$ is a break function such that $\Delta g(t)=0$ for all $t \in$ $\epsilon(a, b), \Delta^{+} g(a)=\Delta^{-} g(b)=0$ then $\int_{a}^{b} f(t) \mathrm{d} g(t)=0$ for all $f \in V(a, b)$.

The proof follows immediately from $(2,6)$.
In [2] the following theorem on integration by parts is proved:
Let $f, g \in V(a, b)$ then for any interval $\langle c, d\rangle \subset\langle a, b\rangle$ we have

$$
\begin{gather*}
\int_{c}^{d} f(t) \mathrm{d} g(t)+\int_{c}^{d} g(t) \mathrm{d} f(t)=  \tag{2,8}\\
=f(d) g(d)-f(c) g(c)-\sum_{c \leqq \tau<d} \Delta^{+} f(\tau) \Delta^{+} g(\tau)+\sum_{c<\tau \leqq d} \Delta^{-} f(\tau) \Delta^{-} g(\tau) .
\end{gather*}
$$

Let $\mathbf{z}, \mathbf{w} \in V_{n}(a, b)$; we denote for $\langle c, d\rangle \subset\langle a, b\rangle$

$$
\int_{c}^{d} \mathbf{z}^{\prime}(t) \mathrm{d} w(t)=\int_{c}^{d} \mathrm{~d}\left[\mathbf{w}^{\prime}(t)\right] \mathbf{z}(t)=\sum_{i=1}^{n} \int_{c}^{d} z_{i}(t) \mathrm{d} w_{i}(t)
$$

Using this notation and the integration by parts formula $(2,8)$ we can easily derive the integration by parts formula for $n$-vector functions $\mathbf{z}, \mathbf{w} \in V_{n}(a, b),\langle c, d\rangle \subset$ $c\langle a, b\rangle$ in the form

$$
\begin{align*}
& \int_{c}^{d} \mathbf{z}^{\prime}(t) \mathrm{d} w(t)+\int_{c}^{d} \mathbf{w}^{\prime}(t) \mathrm{d} \mathbf{z}(t)=\int_{c}^{d} \mathbf{z}^{\prime}(t) \mathrm{d} w(t)+\int_{c}^{d} \mathrm{~d}\left[\mathbf{z}^{\prime}(t)\right] \mathbf{w}(t)=  \tag{2,9}\\
= & \mathbf{z}^{\prime}(d) \mathbf{w}(d)-\mathbf{z}^{\prime}(c) w(c)-\sum_{c \leqq \tau<d} \Delta^{+} \mathbf{z}^{\prime}(\tau) \Delta^{+} w(\tau)+\sum_{c<\tau \leqq d} \Delta^{-} \mathbf{z}^{\prime}(\tau) \Delta^{-} w(\tau) .
\end{align*}
$$

Remark 2,2. In a similar manner can be obtained the result of Corollary 2,2 for $n$-vector functions: If $\mathbf{w} \in V_{n}(a, b)$ is a break function (cf. Remark 2,1) such that $\Delta \mathbf{w}(t)=0$ for all $t \in(a, b), \Delta^{+} \mathbf{w}(a)=\Delta^{-} \mathbf{w}(b)=0$ then $\int_{a}^{b} \mathbf{z}^{\prime}(t) \mathrm{d} \mathbf{w}(t)=0$ for all $\mathbf{z} \in V_{n}(a, b)$.

Now let a nondegenerate interval $I=\langle a, b\rangle \times\langle c, d\rangle$ in $R^{2}$ be given; $K(s, t): I \rightarrow$ $\rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ let be a matrix function defined on the interval $I$. The elements of the matrix $K(s, t)$ are denoted by $k_{i j}(s, t)$, i.e. $K(s, t)=\left(k_{i j}(s, t)\right), i, j=1,2, \ldots, n$.

For a given subinterval $J=\langle\bar{a}, \bar{b}\rangle \times\langle\bar{c}, \vec{d}\rangle \subset I$ we set $m_{\boldsymbol{K}}(J)=K(\bar{b}, \bar{d})-$ $-\boldsymbol{K}(\bar{b}, \bar{c})-\boldsymbol{K}(\bar{a}, \bar{d})+\boldsymbol{K}(\bar{a}, \bar{c}) \in L\left(R^{n} \rightarrow R^{n}\right)$ and define

$$
\begin{equation*}
v_{I}(\boldsymbol{K})=\sup \sum_{i}\left\|m_{\boldsymbol{K}}\left(J_{i}\right)\right\| \tag{2,10}
\end{equation*}
$$

where the supremum is taken over all finite systems of subintervals $J_{i} \subset I$ such that for the interiors $J_{i}^{0}$ of $J_{i}$ (in the topology of $R^{2}$ ) we have $J_{i}^{0} \cap J_{j}^{0}=\emptyset$ when $i \neq j$. The norm $\|$.$\| used in (2,10)$ is the operator norm in $L\left(R^{n} \rightarrow R^{n}\right)$ (see Sec. 1.).

The number $v_{I}(K)$ established in $(2,10)$ is a kind of twodimensional variation of the matrix function $K(s, t)$ in the interval $I$. This notion of a twodimensional variation is considered in the book of T. H. Hildebrandt [5] (for the case $n=1$ ).

For a real function $k(s, t): I \rightarrow R$ we can define the number $v_{I}(k)$ as above if we take $n=1$. The properties of our operator norm imply

$$
\begin{equation*}
v_{I}\left(k_{i j}\right) \leqq v_{I}(\boldsymbol{K}) \tag{2,11}
\end{equation*}
$$

for all $i, j=1,2, \ldots, n$.
If $I_{j} \subset I$ is a rectangle for each $j=1,2, \ldots, m$ and $I_{i}^{0} \cap I_{k}^{0}=\emptyset$ for $j \neq k$, then we can define the number $v_{I_{j}}(K)$ for each $j=1,2, \ldots, m$ as above and by definition we easily obtain

$$
\begin{equation*}
\sum_{j=1}^{m} v_{I_{j}}(K) \leqq v_{I}(K) \tag{2,12}
\end{equation*}
$$

We define as usual

$$
\operatorname{var}_{c}^{d} K(s, .)=\sup \sum_{i}\left\|K\left(s, t_{i}\right)-K\left(s, t_{i-1}\right)\right\|
$$

for fixed $s \in\langle a, b\rangle$ and

$$
\operatorname{var}_{a}^{b} K(., t)=\sup \sum_{j}\left\|K\left(s_{j}, t\right)-K\left(s_{j-1}, t\right)\right\|
$$

for fixed $t \in\langle c, d\rangle$ where the supremums are taken over all finite decompositions of the interval $\langle c, d\rangle,\langle a, b\rangle$ respectively.

The properties of the used operator norm imply

$$
\begin{align*}
\operatorname{var}_{c}^{d} k_{i j}(s, .) & \leqq \operatorname{var}_{c}^{d} K(s, .),  \tag{2,13a}\\
\operatorname{var}_{a}^{b} k_{i j}(., t) & \leqq \operatorname{var}_{a}^{b} K(., t) \tag{2,13b}
\end{align*}
$$

for any $i, j=1,2, \ldots, n, s \in\langle a, b\rangle, t \in\langle c, d\rangle$.

For any $s, s_{0} \in\langle a, b\rangle, t_{j-1}, t_{j} \in\langle c, d\rangle$ we have

$$
\left\|K\left(s, t_{j}\right)-K\left(s, t_{j-1}\right)\right\| \leqq\left\|m_{K}\left(J_{j}\right)\right\|+\left\|K\left(s_{0}, t_{j}\right)-K\left(s_{0}, t_{j-1}\right)\right\|
$$

where $J_{i}=\left\langle s_{0}, s\right\rangle \times\left\langle t_{j-1}, t_{j}\right\rangle$. Hence for each decomposition $D: c=t_{0}<$ $<t_{1}<\ldots\left\langle t_{m}=d\right.$ of the interval $\langle c, d\rangle$ the inequality

$$
\begin{gathered}
\sum_{j=1}^{m}\left\|\boldsymbol{K}\left(s, t_{j}\right)-\boldsymbol{K}\left(s, t_{j-1}\right)\right\| \leqq \sum_{j=1}^{m}\left\|m_{\boldsymbol{K}}\left(J_{j}\right)\right\|+ \\
+\sum_{j=1}^{m}\left\|\boldsymbol{K}\left(s_{0}, t_{j}\right)-\boldsymbol{K}\left(s_{0}, t_{j-1}\right)\right\| \leqq v_{I}(\boldsymbol{K})+\operatorname{var}_{c}^{d} \boldsymbol{K}\left(s_{0}, \cdot\right)
\end{gathered}
$$

holds; therefore

$$
\begin{equation*}
\operatorname{var}_{c}^{d} K(s, .) \leqq v_{I}(K)+\operatorname{var}_{c}^{d} K\left(s_{0}, .\right) \tag{2,14a}
\end{equation*}
$$

for each $s \in\langle a, b\rangle$. Similarly can be proved for $t_{0} \in\langle c, d\rangle$ the inequality

$$
\begin{equation*}
\operatorname{var}_{a}^{b} K(., t) \leqq v_{I}(K)+\operatorname{var}_{a}^{b} K\left(., t_{0}\right) \tag{2,14b}
\end{equation*}
$$

which holds for each $t \in\langle c, d\rangle$.
Therefore, if we suppose that $v_{I}(K)<+\infty, \operatorname{var}_{c}^{d} K\left(s_{0},.\right)<+\infty$ for some $s_{0} \in$ $\in\langle a, b\rangle$ then we have $\operatorname{var}_{c}^{d} K(s,)<.+\infty$ for all $s \in\langle a, b\rangle$ and symmetrically if $v_{I}(K)<+\infty, \operatorname{var}_{a}^{b} K\left(., t_{0}\right)<+\infty$ for some $t_{0} \in\langle c, d\rangle$, then $\operatorname{var}_{a}^{b} K(., t)<+\infty$ for all $t \in\langle c, d\rangle$.

Let us put

$$
\begin{equation*}
\varphi(\sigma)=v_{\langle a, \sigma\rangle \times\langle c, d\rangle}(K) \tag{2,15a}
\end{equation*}
$$

for $\sigma \in\langle a, b\rangle ; \varphi(\sigma):\langle a, b\rangle \rightarrow R$ is evidently a nondecreasing function in $\langle a, b\rangle$, $\varphi(a)=0, \varphi(b)=v_{I}(K)$. In the same way we can define

$$
\begin{equation*}
\psi(\tau)=v_{\langle a, b\rangle \times\langle c, \tau\rangle}(K) \tag{2,15b}
\end{equation*}
$$

for $\tau \in\langle c, d\rangle ; \psi(\tau):\langle c, d\rangle \rightarrow R$ is nondecreasing, $\psi(c)=0, \psi(d)=v_{I}(K)$.
Note that for an arbitrary decomposition of the interval $\langle a, b\rangle: a=s_{0}<s_{1}<\ldots$ $\ldots<s_{1}=b$ and any two points $t_{1}, t_{2} \in\langle c, d\rangle$ we have

$$
\begin{aligned}
& \left|\operatorname{var}_{c}^{t_{2}}\left(\boldsymbol{K}\left(s_{i}, .\right)-\boldsymbol{K}\left(s_{i-1}, .\right)\right)-\operatorname{var}_{c}^{t_{1}}\left(\boldsymbol{K}\left(s_{i}, .\right)-K\left(s_{i-1}, .\right)\right)\right|= \\
& \quad=\left|\operatorname{var}_{t_{1}}^{t_{2}}\left(\boldsymbol{K}\left(s_{i}, .\right)-K\left(s_{i-1}, .\right)\right)\right| \leqq v_{\left\langle s_{i-1}, s_{i}\right\rangle \times\left\langle t_{1}, t_{2}\right\rangle}(\boldsymbol{K})
\end{aligned}
$$

for $i=1,2, \ldots, l$, i.e.

$$
\begin{align*}
& \left|\sum_{i=1}^{l}\left[\operatorname{var}_{c}^{t_{2}}\left(K\left(s_{i}, .\right)-K\left(s_{i-1}, .\right)\right)-\operatorname{var}_{c}^{t_{1}}\left(K\left(s_{i}, .\right)-K\left(s_{i-1}, .\right)\right)\right]\right| \leqq  \tag{2,16a}\\
& \quad \leqq \sum_{i=1}^{l} v_{\left\langle s_{i-1}, s_{i}\right\rangle \times\left\langle t_{1}, t_{2}\right\rangle}(K) \leqq v_{\langle a, b\rangle \times\left\langle t_{1}, t_{2}\right\rangle}(K) \leqq\left|\psi\left(t_{2}\right)-\psi\left(t_{1}\right)\right|
\end{align*}
$$

Symmetrically for an arbitrary decomposition $c=t_{0}<t_{1}<\ldots<t_{m}=d$ and any two points $s_{1}, s_{2} \in\langle a, b\rangle$ it is

$$
\begin{align*}
&\left|\sum_{j=1}^{m}\left[\operatorname{var}_{a}^{s_{2}}\left(K\left(., t_{j}\right)-K\left(., t_{j-1}\right)\right)-\operatorname{var}_{a}^{s_{1}}\left(K\left(., t_{j}\right)-K\left(., t_{j-1}\right)\right)\right]\right| \leqq  \tag{2,16b}\\
& \leqq\left|\varphi\left(s_{2}\right)-\varphi\left(s_{1}\right)\right|
\end{align*}
$$

Lemma 2,1. Let $K(s, t): I=\langle a, b\rangle \times\langle c, d\rangle \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfy $v_{I}(K)<+\infty$ and $\operatorname{var}_{c}^{d} K\left(s_{*},.\right)<+\infty$ for some $s_{*} \in\langle a, b\rangle$. Let further for some $s_{0} \in\langle a, b\rangle$

$$
\begin{equation*}
\lim _{s \rightarrow s_{0}^{+}}\left\|K(s, t)-K\left(s_{0}, t\right)\right\|=0 \tag{2,17}
\end{equation*}
$$

or

$$
\lim _{s \rightarrow s_{0}-}\left\|K(s, t)-K\left(s_{0}, t\right)\right\|=0
$$

for all $t \in\langle c, d\rangle$ then

$$
\begin{equation*}
\lim _{s \rightarrow s_{0}+} \varphi(s)=\varphi\left(s_{0}\right), \quad \lim _{s \rightarrow s_{0}-} \varphi(s)=\varphi\left(s_{0}\right) \tag{2,18}
\end{equation*}
$$

respectively where $\varphi:\langle a, b\rangle \rightarrow R$ is the function defined in (2,15a). (If $s_{0}=a$ ( $s_{0}=b$ ) then we consider the first (second) case only.)

Proof. We prove the first case only, the other one is symmetric. The function $\varphi$ is nondecreasing, i.e. $\varphi(s)-\varphi\left(s_{0}\right) \geqq 0$ for $s \geqq s_{0}$. Let us suppose that our Lemma is not valid and that there is a number $\eta>0$ such that for all $s>s_{0}$ we have

$$
\begin{equation*}
\varphi(s)-\varphi\left(s_{0}\right) \geqq \eta>0 \tag{2,19}
\end{equation*}
$$

By definition of $\varphi(s)$ there exists a finite system of intervals $J_{l} \subset\langle a, s\rangle \times\langle c, d\rangle$, $J_{l}^{0} \cap J_{j}^{0}=\emptyset, l \neq j$ such that

$$
\sum_{l}\left\|m_{K}\left(J_{l}\right)\right\|>\varphi(s)-\frac{\eta}{8}
$$

We put $I_{l}^{*}=J_{l} \cap\left\langle a, s_{0}\right\rangle \times\langle c, d\rangle$ and $I_{l}=J_{l} \cap\left\langle s_{0}, s\right\rangle \times\langle c, d\rangle$. Obviously

$$
\left\|m_{\kappa}\left(J_{l}\right)\right\| \leqq\left\|m_{\kappa}\left(I_{l}^{*}\right)\right\|+\left\|m_{\kappa}\left(I_{l}\right)\right\|
$$

and

$$
\sum_{l}\left\|m_{\kappa}\left(I_{l}\right)\right\| \leqq \varphi\left(s_{0}\right)
$$

Hence

$$
\sum_{l}\left\|m_{\kappa}\left(I_{l}\right)\right\|+\sum_{l}\left\|m_{K}\left(I_{l}^{*}\right)\right\|-\varphi\left(s_{0}\right)>\varphi(s)-\varphi\left(s_{0}\right)-\frac{\eta}{8}
$$

and we obtain

$$
\begin{equation*}
\sum_{l}\left\|m_{\kappa}\left(I_{l}\right)\right\|>\varphi(s)-\varphi\left(s_{0}\right)-\frac{\eta}{8} \tag{2,20}
\end{equation*}
$$

At the same time $I_{l}$ is a finite system of intervals in $\left\langle s_{0}, s\right\rangle \times\langle c, d\rangle$ and $I_{l}^{0} \cap I_{j}^{0}=\emptyset$ for $j \neq l$.

Let $0<\delta<s-s_{0}$ and put $\tilde{I}_{l}=I_{l} \cap\left\langle s_{0}, s_{0}+\delta\right\rangle \times\langle c, d\rangle, \tilde{I}_{l}=I_{l} \cap\left\langle s_{0}+\right.$ $+\delta, s\rangle \times\langle c, d\rangle$. If for example $I_{l}=\left\langle s_{0}, s_{0}+\delta\right\rangle \times\left\langle t^{\prime}, t^{\prime \prime}\right\rangle$ then we have

$$
\begin{gathered}
\left\|m_{\boldsymbol{K}}^{\cdot}\left(\hat{I}_{t}\right)\right\|=\left\|\boldsymbol{K}\left(s_{0}+\delta, t^{\prime \prime}\right)-K\left(s_{0}+\delta, t^{\prime}\right)-\boldsymbol{K}\left(s_{0}, t^{\prime \prime}\right)+\boldsymbol{K}\left(s_{0}, t^{\prime}\right)\right\| \leqq \\
\leqq\left\|\boldsymbol{K}\left(s_{0}+\delta, t^{\prime \prime}\right)-\boldsymbol{K}\left(s_{0}, t^{\prime \prime}\right)\right\|+\left\|\boldsymbol{K}\left(s_{0}+\delta, t^{\prime}\right)-\boldsymbol{K}\left(s_{0}, t^{\prime}\right)\right\|
\end{gathered}
$$

and we see that a choice of sufficiently small $\delta>0$ implies by $(2,17)$ that $\left\|m_{K}\left(\hat{I}_{l}\right)\right\|$ is arbitrarily small. This procedure can be repeated for all possible forms of $\hat{I}_{l}$ in a similar manner. Hence for sufficiently small $\delta>0$ we can obtain

$$
\sum_{l}\left\|m_{\kappa}\left(\hat{I}_{l}\right)\right\|<\frac{\eta}{8}
$$

This inequality together with $\sum_{l}\left\|m_{\kappa}\left(I_{l}\right)\right\| \leqq \sum_{l}\left\|m_{K}\left(\hat{I}_{l}\right)\right\|+\sum_{l}\left\|m_{\kappa}\left(\tilde{I}_{l}\right)\right\|$ and $(2,20)$ implies

$$
\begin{equation*}
\sum_{l}\left\|m_{\kappa}\left(\tilde{I}_{l}\right)\right\|>\varphi(s)-\varphi\left(s_{0}\right)-\frac{\eta}{4} . \tag{2,21}
\end{equation*}
$$

As $(2,19)$ is assumed there is a finite system of intervals $I_{k}^{* *} \subset\left\langle a, s_{0}+\delta\right\rangle \times\langle c, d\rangle$, $\left(I_{k}^{* *}\right)^{0} \cap\left(I_{j}^{* *}\right)^{0}=\emptyset$ for $j \neq k$ such that

$$
\sum_{k}\left\|m_{K}\left(I_{k}\right)\right\|-\varphi(s)>\frac{\eta}{2} .
$$

From this and from $(2,21)$ we have

$$
\begin{equation*}
\sum_{l}\left\|m_{\boldsymbol{K}}\left(\tilde{I}_{l}\right)\right\|+\sum_{k}\left\|m_{\kappa}\left(I_{k}^{* *}\right)\right\|-\varphi\left(s_{0}\right)>\varphi(s)-\varphi\left(s_{0}\right)+\frac{\eta}{4} . \tag{2,22}
\end{equation*}
$$

Since the union of intervals $\tilde{I}_{l}$ and $I_{k}^{* *}$ forms a finite system of intervals in $\langle a, s\rangle \times$ $\times\langle c, d\rangle$ with mutually disjoint interiors, we obtain from $(2,22)$ by definition of $\varphi(s)$ the contradictory inequality $\varphi(s)-\varphi\left(s_{0}\right)>\varphi(s)-\varphi\left(s_{0}\right)+\eta / 4$. Thus our Lemma is proved.

Remark 2,3. By definition we have for $s_{0} \in\langle a, b\rangle, 0<\delta<b-s_{0}$

$$
\begin{equation*}
\operatorname{var}_{c}^{d}\left(K\left(s_{0}+\delta, .\right)-K\left(s_{0}, .\right)\right) \leqq v_{\left\langle s_{0}, s_{0}+\delta\right\rangle \times\langle c, d\rangle}(K) \leqq \varphi\left(s_{0}+\delta\right)-\varphi\left(s_{0}\right) \tag{i}
\end{equation*}
$$

where $\varphi$ is given in $(2,15$ a). Hence if the first equation in $(2,17)$ holds, we have by $(2,18)$

$$
\lim _{\delta \rightarrow 0+} \operatorname{var}_{c}^{d}\left(K\left(s_{0}+\delta, .\right)-K\left(s_{0}, .\right)\right)=0
$$

If an arbitrary $K(s, t):\langle a, b\rangle \times\langle c, d\rangle \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ is given with $v_{I}(K)<+\infty$, $\operatorname{var}_{c}^{d} K\left(s_{*},.\right)<+\infty$ for some $s_{*} \in\langle a, b\rangle$ and $\lim _{s \rightarrow s^{+}} K(s, t)=K\left(s_{0}+, t\right)$ exists for every $t \in\langle c, d\rangle$ then we can define $K^{\circ}(s, t) \stackrel{=}{=} K(s, t)$ if $(s, t) \in I=\langle a, b\rangle \times$
$\times\langle c, d\rangle, s \neq s_{0}, K^{\circ}\left(s_{0}, t\right)=K\left(s_{0}+, t\right)$. Easily can be obtained $v_{I}\left(K^{\circ}\right)<+\infty$ and $\operatorname{var}_{c}^{d} K^{\circ}\left(s_{* *},.\right)<+\infty$ for some $s_{* *} \in\langle a, b\rangle$. We have further evidently $\lim _{s \rightarrow s_{0}+}\left\|\boldsymbol{K}^{\circ}(s, t)-K^{\circ}\left(s_{0}, t\right)\right\|=0$ for every $t \in\langle c, d\rangle$ and in the same way as above we obtain
(ii)

$$
\begin{aligned}
& \lim _{\delta \rightarrow 0+} \operatorname{var}_{c}^{d}\left(K^{\circ}\left(s_{0}+\delta, .\right)-K^{\circ}\left(s_{0}, .\right)\right)= \\
= & \lim _{\delta \rightarrow 0+} \operatorname{var}_{c}^{d}\left(K\left(s_{0}+\delta, .\right)-K\left(s_{0}+, .\right)\right)=0 .
\end{aligned}
$$

A similar appointment gives the same result for left hand side limits. This implies the following

Corollary 2,3. If for $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right), v_{I}(K)\left\langle+\infty, \operatorname{var}_{c}^{d} K\left(s_{*},.\right)<+\infty\right.$ for some $s_{*} \in\langle a, b\rangle$ and if $\lim _{s \rightarrow s_{0}+} K(s, t)=K\left(s_{0}+, t\right)$ exists for any $t \in\langle c, d\rangle$ then we have

$$
\operatorname{var}_{c}^{d}\left(K\left(s_{0}+, .\right)-K\left(s_{0}, .\right)\right)=\operatorname{var}_{c}^{d} \Delta^{+} K\left(s_{0}, .\right) \leqq \varphi\left(s_{0}+\right)-\varphi\left(s_{0}\right)=\Delta^{+} \varphi\left(s_{0}\right) .
$$

## (A similar statement for left hand side limits holds.)

Proof. For any $\delta>0$ we have

$$
\begin{gathered}
\operatorname{var}_{c}^{d}\left(\boldsymbol{K}\left(s_{0}+, .\right)-\boldsymbol{K}\left(s_{0}, .\right)\right)= \\
=\operatorname{var}_{c}^{d}\left(\boldsymbol{K}\left(s_{0}+\delta, .\right)-\boldsymbol{K}\left(s_{0}, .\right)+\boldsymbol{K}\left(s_{0}+, .\right)-\boldsymbol{K}\left(s_{0}+\delta, .\right) \leqq\right. \\
\leqq \operatorname{var}_{c}^{d}\left(\boldsymbol{K}\left(s_{0}+\delta, .\right)-\boldsymbol{K}\left(s_{0}, .\right)\right)+\operatorname{var}_{c}^{d}\left(\boldsymbol{K}\left(s_{0}+\delta, .\right)-\boldsymbol{K}\left(s_{0}+, .\right)\right) \leqq \\
\leqq \varphi\left(s_{0}+\delta\right)-\varphi\left(s_{0}\right)+\operatorname{var}_{c}^{d}\left(\boldsymbol{K}\left(s_{0}+\delta, .\right)-\boldsymbol{K}\left(s_{0}+, .\right)\right) .
\end{gathered}
$$

Hence by the limiting process $\delta \rightarrow 0+$ we obtain our inequality by means of (i) and (ii).

Now we define integrals of vector functions. If an $n$-vector $U(\tau, t)=\left(U_{1}(\tau, t), \ldots\right.$, $\ldots, U_{n}(\tau, t)$ ) is given, $\mathbf{U}(\tau, t): S \rightarrow R^{n}, S=\left\{(\tau, t) \in R^{2} ; c \leqq \tau \leqq d, \tau-\delta(\tau) \leqq t \leqq\right.$ $\leqq \tau+\delta(\tau), \delta(\tau)>0$ for every $\tau \in\langle c, d\rangle\}$ then by definition (cf. [1])

$$
\int_{c}^{d} \mathrm{D} U(\tau, t)=\left(\int_{c}^{d} \mathrm{D} U_{1}(\tau, t), \ldots, \int_{c}^{d} \mathrm{D} U_{n}(\tau, t)\right) .
$$

Given $\mathrm{x}:\langle c, d\rangle \rightarrow R^{n}$, we put for any $s \in\langle a, b\rangle$

$$
U(\tau, t)=K(s, t) x(\tau)=\left(\sum_{j=1}^{n} k_{1 j}(s, t) x_{j}(\tau), \ldots, \sum_{j=1}^{n} k_{n j}(s, t) x_{j}(\tau)\right)^{\prime}
$$

and denote

$$
\begin{gathered}
\int_{c}^{d} \mathrm{~d}_{t}[K(s, t)] \mathbf{x}(t)=\int_{c}^{d} \mathrm{D} U(\tau, t)= \\
=\left(\int _ { c } ^ { d } \mathrm { D } \left(\sum_{j=1}^{n} k_{1 j}(s, t) x_{j}(\tau), \ldots, \int_{c}^{d} \mathrm{D}\left(\sum_{j=1}^{n} k_{n j}(s, t) x_{j}(\tau)\right)^{\prime}=\right.\right. \\
=\left(\sum_{j=1}^{n} \int_{c}^{d} x_{j}(t) \mathrm{d}_{t} k_{1 j}(s, t), \ldots, \sum_{j=1}^{n} \int_{c}^{d} x_{j}(t) \mathrm{d}_{t} k_{n j}(s, t)\right)^{\prime} .
\end{gathered}
$$

Remark 2,4. For this definition we need to know the values $K(s, t)$ for $t<c$, $t>d$. We suppose therefore $\boldsymbol{K}(s, t)=\boldsymbol{K}(s, c)$ for $t<c$ and $\boldsymbol{K}(s, t)=\boldsymbol{K}(s, d)$ for $t>d$.

For $\boldsymbol{y}:\langle a, b\rangle \rightarrow R^{n}$ we define in a similar manner the integral $\int_{a}^{b} \mathrm{~d}_{s}[K(s, t)] \boldsymbol{y}(s)$ and as above we suppose $\boldsymbol{K}(s, t)=\boldsymbol{K}(a, t)$ for $s<a$ and $K(s, t)=\dot{K}(b, t)$ for $s>b$.

Proposition 2,3. Let $K(s, t): I=\langle a, b\rangle \times\langle c, d\rangle \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ be given and let $K(s, t)=K(s, c)$ for $t<c, K(s, t)=K(s, d)$ for $t>d$. Let us suppose that $v_{I}(K)<+\infty$ and $\operatorname{var}_{c}^{d} K\left(s_{0},.\right)<+\infty$ for some $s_{0} \in\langle a, b\rangle$.
If $\mathbf{x}(t) \in V_{n}(c, d)$ then the integral $\int_{c}^{d} \mathrm{~d}_{t}[K(s, t)] \mathbf{x}(t)$ exists for any $s \in\langle a, b\rangle$. The inequality

$$
\begin{equation*}
\left\|\int_{c}^{d} \mathrm{~d}_{t}[K(s, t)] x(t)\right\| \leqq \sup _{t \in\langle c, d\rangle}\|x(t)\| \cdot \operatorname{var}_{c}^{d} K(s, .) \tag{2,23}
\end{equation*}
$$

holds for any $s \in\langle a, b\rangle$. Further we have

$$
\begin{equation*}
\operatorname{var}_{a}^{b}\left(\int_{c}^{d} \mathrm{~d}_{\mathrm{t}} K(s, t) \mathrm{x}(t)\right) \leqq \int_{c}^{d}\|\mathrm{x}(t)\| \mathrm{d} \psi(t) \leqq \sup _{t \in\langle c, d\rangle}\|\mathrm{x}(t)\| \cdot v_{I}(K) \tag{2,24}
\end{equation*}
$$

where the function $\psi$ is defined in $(2,15 \mathrm{~b})$. Thus the integral $\int_{c}^{d} \mathrm{~d}_{t}[K(s, t)] \times(t)$ as a function of the variable s belongs to $V_{n}(a, b)$.

Proof. By the assumption and by (2,14a) we obtain $\operatorname{var}_{c}^{d} K(s,)<.+\infty$ for all $s \in\langle a, b\rangle$; this implies the existence of the integral $\int_{c}^{d} \mathrm{~d}_{t}[K(s, t)] \mathbf{x}(t)$ for any $s \in$ $\epsilon\langle a, b\rangle$. Further we have for each $s \in\langle a, b\rangle$

$$
\begin{gathered}
\left\|\boldsymbol{K}\left(s, t_{2}\right) \mathbf{x}(\tau)-\boldsymbol{K}\left(s, t_{1}\right) \mathbf{x}(\tau)\right\| \leqq\|\mathbf{x}(\tau)\| \cdot \operatorname{var}_{t_{1}}^{t_{2}} \boldsymbol{K}(s, .) \leqq \\
\leqq\|\mathbf{x}(\tau)\| \cdot\left|\operatorname{var}_{c}^{t_{2}} \boldsymbol{K}(s, .)-\operatorname{var}_{c}^{t_{1}} \boldsymbol{K}(s, .)\right|
\end{gathered}
$$

for any $t_{1}, t_{2}$ and for $\tau \in\langle c, d\rangle$. Hence Lemma 2,1 [3] implies

$$
\left\|\int_{c}^{d} \mathrm{~d}_{t}[K(s, t)] x(t)\right\| \leqq \int_{c}^{d}\|x(t)\| \mathrm{d}\left(\operatorname{var}_{c}^{t} K(s, .)\right)
$$

and by $(2,1)$ we obtain $(2,23)$.

Let an arbitrary finite decomposition $a=s_{0}<s_{1}<\ldots<s_{l}=b$ of the interval $\langle a, b\rangle$ be given. We have

$$
\begin{gathered}
\sum_{i=1}^{l}\left\|\int_{c}^{d} \mathrm{~d}_{t}\left[K\left(s_{i}, t\right)-K\left(s_{i-1}, t\right)\right] \mathrm{x}(t)\right\| \leqq \\
\leqq \sum_{i=1}^{l} \int_{c}^{d}\|\mathrm{x}(t)\| \mathrm{d}\left(\operatorname{var}_{c}^{t}\left[K\left(s_{i}, .\right)-K\left(s_{i-1}, .\right)\right]\right) \leqq \\
\leqq
\end{gathered} \int_{c}^{d}\|\mathrm{x}(t)\| \mathrm{d}\left(\sum_{i=1}^{l} \operatorname{var}_{c}^{t}\left[K\left(s_{i}, .\right)-K\left(s_{i-1}, .\right)\right]\right) .
$$

From this inequality we obtain using (2,16a) and Lemma 2,1 [3] the inequality

$$
\sum_{i=1}^{l}\left\|\int_{c}^{d} \mathrm{~d}_{t}\left[K\left(s_{i}, t\right)-K\left(s_{i-1}, t\right)\right] x(t)\right\| \leqq \int_{c}^{d}\|x(t)\| \mathrm{d} \psi(t)
$$

Passing to the supremum on the left hand side in this inequality we obtain immediately the first inequality in $(2,24)$. The other one follows from the relation $\int_{c}^{d} d \psi(t)=$ $=\psi(d)-\psi(c)=v_{I}(K)$ and from $(2,1)$. Therefore we have $\int_{c}^{d} \mathrm{~d}_{t}[K(s, t)] \mathbf{x}(t) \in$ $\in V_{n}(a, b)$.

Remark 2,5. A similar proposition can also be proved for $y \in V_{n}(a, b)$ and the integral $\int_{a}^{b} \mathrm{~d}_{s}[K(s, t)] \boldsymbol{Y}(s)$.

Lemma 2,2. Let $k(s, t): I=\langle a, b\rangle \times\langle c, d\rangle \rightarrow R$ be given. Suppose that $k(s, t)=$ $=k(a, t)$ for $s<a, k(s, t)=k(b, t)$ for $s>b, k(s, t)=k(s, c)$ for $t<c$ and $k(s, t)=k(s, d)$ for $t>d$. Further let $v_{1}(k)<+\infty, \operatorname{var}_{c}^{d} k\left(s_{0},.\right)<+\infty$ for some $s_{0} \in\langle a, b\rangle$ and $\operatorname{var}_{a}^{b} k\left(., t_{0}\right)<+\infty$ for some $t_{0} \in\langle c, d\rangle$. If $f(s) \in V(a, b), g \in V(c, d)$ then

$$
\begin{equation*}
\int_{c}^{d} g(t) \mathrm{d}_{t}\left(\int_{a}^{b} f(s) \mathrm{d}_{s}[k(s, t)]\right)=\int_{a}^{b} f(s) \mathrm{d}_{s}\left(\int_{c}^{d} g(t) \mathrm{d}_{t}[k(s, t)]\right) \tag{2,25}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{c}^{d} g(t) \mathrm{d}_{t}\left(\int_{a}^{b} k(s, t) \mathrm{d} f(s)\right)=\int_{a}^{b}\left(\int_{c}^{d} g(t) \mathrm{d}_{t}[k(s, t)]\right) \mathrm{d} f(s) \tag{2,26}
\end{equation*}
$$

hold and the integrals on both sides of $(2,25)$ and $(2,26)$ exist.
Proof. By Proposition 2,3 we have $\int_{a}^{b} f(s) \mathrm{d}_{s}[k(s, t)] \in V(c, d), \int_{c}^{d} g(t) \mathrm{d}_{t}[k(s, t)] \in$ $\in V(a, b)$ and the existence of the integrals on both sides of $(2,25)$ follows from this fact immediately.

Let us put $f(s)=\psi_{\alpha}^{+}(s), g(t)=\psi_{\beta}^{-}(t)$ for $\alpha \in\langle a, b\rangle, \beta \in\langle c, d\rangle$ (cf. Proposition $2,1)$. Using ( 2,3 ) from Proposition 2,1 we obtain by easy computation

$$
\begin{gathered}
\left(\int_{c}^{d} g(t) \mathrm{d}_{t} \int_{a}^{b} f(s) \mathrm{d}_{s}[k(s, t)]\right)=k(b, d)-k(b, \beta-)-k(\alpha+, d)+k(\alpha+, \beta-)= \\
=\int_{a}^{b} f(s) \mathrm{d}_{s}\left(\int_{c}^{d} g(t) \mathrm{d}_{t}[k(s, t)]\right)
\end{gathered}
$$

i.e. $(2,25)$ holds for this choice of $f$ and $g$. We note that the term $k(\alpha+, \beta-)$ in the above computation is in one case obtained as $\lim _{t \rightarrow \beta-} \lim _{s \rightarrow \alpha+} k(s, t)$ and as $\lim _{s \rightarrow \alpha+} \lim _{t \rightarrow \beta-} k(s, t)$ in the other one. By Theorem III. 5.3 in [5] both iterated limits are equal since by assumption the existence of all quadrantal limits in any point of $I$ is quaranted. Similarly it can be proved by direct computation that $(2,25)$ is true if $f(s)$ equals $\psi_{a}^{-}(s)$ or $\psi_{\alpha}^{+}(s)$ and $g(t)$ equals $\psi_{\beta}^{+}(t)$ or $\psi_{\beta}^{-}(t)$ for some $\alpha \in\langle a, b\rangle, \beta \in\langle c, d\rangle$ (c.f. Proposition 2,1). Hence from the linearity of the integral we obtain that $(2,25)$ holds if $f(s), g(t)$ are step functions because it is clear that every step function can be expressed as a finite linear combination of functions of the type $\psi_{\alpha}^{+}$and $\psi_{\alpha}^{-}$. It is known that if $f \in V(a, b)$ and $g \in V(c, d)$ then there exist sequences $\left\{f_{l}(s)\right\} f_{l}:\langle a, b\rangle \rightarrow R$ and $\left\{g_{l}(t)\right\}, g_{l}:\langle c, d\rangle \rightarrow R, l=1,2, \ldots, f_{l}, g_{l}$ are step functions such that $\lim _{l \rightarrow \infty} f_{l}(s)=$ $=f(s), \lim _{l \rightarrow \infty} g_{l}(t)=g(t)$ uniformly in $\langle a, b\rangle,\langle c, d\rangle$ respectively. We denote

$$
\begin{aligned}
& I_{1, l}=\int_{c}^{d} g_{l}(t) \mathrm{d}_{t}\left(\int_{a}^{b} f_{l}(s) \mathrm{d}_{s}[k(s, t)]\right), \\
& \mathrm{I}_{2, l}=\int_{a}^{b} f_{l}(s) d_{s}\left(\int_{c}^{d} g_{l}(t) \mathrm{d}_{t}[k(s, t)]\right)
\end{aligned}
$$

since $(2,25)$ holds for step functions we have

$$
\begin{equation*}
I_{1, l}=I_{2, l} \text { for every } l=1,2, \ldots \tag{2,27}
\end{equation*}
$$

Further by $(2,2)$ and $(2,24)$ we have

$$
\begin{aligned}
& \left\lvert\, \begin{array}{ll}
\left|\int_{c}^{d} g(t) \mathrm{d}_{t}\left(\int_{a}^{b} f(s) \mathrm{d}_{s}[k(s, t)]\right)-I_{1, l}\right| \leqq\left|\int_{c}^{d}\left(g(t)-g_{l}(t)\right) \mathrm{d}_{t}\left(\int_{a}^{b} f(s) \mathrm{d}_{s}[k(s, t)]\right)\right|+ \\
& +\left|\int_{c}^{d} g_{l}(t) \mathrm{d}_{t}\left(\int_{a}^{b}\left(f(s)-f_{l}(s)\right) \mathrm{d}_{s}[k(s, t)]\right)\right| \leqq \\
& \leqq \sup _{t \in\langle c, d\rangle}\left|g(t)-g_{l}(t)\right| \operatorname{var}_{c}^{d}\left(\int_{a}^{b} f(s) \mathrm{d}_{s}[k(s, .)]\right)+ \\
& +\sup _{t \in\langle c, d\rangle}\left|g_{l}(t)\right| \operatorname{var}_{c}^{d}\left(\int_{a}^{b}\left(f(s)-f_{l}(s)\right) \mathrm{d}_{s}[k(s, .)]\right) \leqq \\
\leqq\left[\sup _{t \in\langle c, d\rangle}\left|g(t)-g_{l}(t)\right|\left(|f(a)|+\operatorname{var}_{a}^{b} f\right)+\sup _{t \in\langle c, d\rangle}\left|g_{l}(t)\right| \sup _{s \in\langle a, b\rangle}\left|f(s)-f_{l}(s)\right|\right] v_{l}(k)
\end{array}\right.
\end{aligned}
$$

and therefore

$$
\lim _{t \rightarrow \infty} I_{1, l}=\int_{c}^{d} g(t) \mathrm{d}_{t}\left(\int_{a}^{b} f(s) \mathrm{d}_{s}[k(s, t)]\right)
$$

Similarly it also holds ,

$$
\lim _{l \rightarrow \infty} I_{2, l}=\int_{a}^{b} f(s) \mathrm{d}_{s}\left(\int_{c}^{d} g(t) \mathrm{d}_{t}[k(s, t)]\right)
$$

In this way $(2,27)$ implies $(2,25)$ for arbitrary $f \in V(a, b), g \in V(c, d)$.

The integral on the right hand side of $(2,26)$ exists evidently $\left(\int_{c}^{d} g(t) \mathrm{d}_{t}[k(s, t)] \in\right.$ $\in V(a, b))$. It can be easily proved that the inequality

$$
\operatorname{var}_{c}^{d}\left(\int_{a}^{b} k(s, .) \mathrm{d} f(s)\right) \leqq\left[v_{I}(k)+\operatorname{var}_{c}^{d} k\left(s_{0}, .\right)\right] \operatorname{var}_{a}^{b} f<+\infty
$$

holds. Thus $\int_{a}^{b} k(s, t) \mathrm{d} f(s) \in V(c, d)$ and the integral on the left hand side of $(2,26)$ also exists.

The equality $(2,26)$ holds if we set $g(t)=\psi_{\alpha}^{+}(t)$ (cf. Proposition 2,1 ). In fact we have by $(2,3)$

$$
\int_{c}^{d} \psi_{\alpha}^{+}(t) \mathrm{d}_{t}[k(s, t)]=k(s, d)-k(s, \alpha+) .
$$

Hence

$$
\int_{a}^{b}\left(\int_{c}^{d} \psi_{a}^{+}(t) \mathrm{d}_{t}[k(s, t)]\right) \mathrm{d} f(s)=\int_{a}^{b}(k(s, d)-k(s, \alpha+)) \mathrm{d} f(s) .
$$

By $(2,3)$ we have also

$$
\int_{c}^{d} \psi_{a}^{+}(t) \mathrm{d}_{t}\left(\int_{a}^{b} k(s, t) \mathrm{d} f(s)\right)=\int_{a}^{b}(k(s, d)-k(s, \alpha+)) \mathrm{d} f(s) .
$$

Therefore

$$
\int_{a}^{b}\left(\int_{c}^{d} \psi_{a}^{+}(t) \mathrm{d}_{t}[k(s, t)]\right) \mathrm{d} f(s)=\int_{c}^{d} \psi_{\alpha}^{+}(t) \mathrm{d}_{t}\left(\int_{a}^{b} k(s, t) \mathrm{d} f(s)\right) .
$$

Similarly can be proved that $(2,26)$ holds if $g(t)=\psi_{\alpha}^{-}(t)$ and we obtain that $(2,26)$ holds for every step function $g(t)$. Let for $g \in V(c, d)$ a sequence of step functions $g_{l}:\langle c, d\rangle \rightarrow R$ be given, $\lim _{l \rightarrow \infty} g_{l}(t)=g(t)$ uniformly in $\langle c, d\rangle$. Then we have
$\left|\int_{c}^{d}\left(g(t)-g_{l}(t)\right) \mathrm{d}_{t}\left(\int_{a}^{b} k(s, t) \mathrm{d} f(s)\right)\right| \leqq \sup _{t \in\langle c, d\rangle}\left|g(t)-g_{l}(t)\right|\left(v_{l}(k)+\operatorname{var}_{c}^{d} k\left(s_{0},.\right)\right) \operatorname{var}_{a}^{b} f$
and

$$
\begin{aligned}
& \left|\int_{a}^{b}\left(\int_{c}^{d}\left(g(t)-g_{l}(t)\right) \mathrm{d}_{t}[k(s, t)]\right) \mathrm{d} f(s)\right| \mid \leqq \\
\leqq & \sup _{t \in\langle c, d\rangle}\left|g(t)-g_{l}(t)\right|\left(v_{l}(k)+\operatorname{var}_{c}^{d} k\left(s_{0}, .\right)\right) \operatorname{var}_{a}^{b} f .
\end{aligned}
$$

Thus in the same way as in the case of $(2,25)$ we obtain that $(2,26)$ holds for any $g \in V(c, d)$.

Let us now denote

$$
\langle\mathbf{z}, \mathbf{w}\rangle_{(c, d)}=\int_{c}^{d} \mathbf{z}^{\prime}(t) \mathrm{d} w(t)=\int_{c}^{d} \mathrm{~d}\left[w^{\prime}(t)\right] \mathbf{z}(t)=\sum_{j=1}^{n} \int_{c}^{d} z_{j}(t) \mathrm{d} w_{j}(t)
$$

if $\mathbf{z}, \mathbf{w} \in V_{n}(c, d)$ and

$$
\langle z, w\rangle_{(a, b)}=\int_{a}^{b} z^{\prime}(s) \mathrm{d} w(s)=\int_{a}^{b} \mathrm{~d}\left[w^{\prime}(s)\right] z(s)=\sum_{j=1}^{n} \int_{a}^{b} z_{j}(s) \mathrm{d} w_{j}(s)
$$

if $\mathbf{z}, \mathbf{w} \in V_{\boldsymbol{n}}(a, b)$.
Proposition 2,4. Let $K(s, t): I=\langle a, b\rangle \times\langle c, d\rangle \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ be given and let $K(s, t)$ be extended for $s<a, s\rangle b, t<c, t\rangle d$ as in Remark 2,4. Let us suppose that $v_{l}(K)<+\infty$, $\operatorname{var}_{c}^{d} K\left(s_{0},.\right)<+\infty$ for some $s_{0} \in\langle a, b\rangle, \operatorname{var}_{a}^{b} K\left(., t_{0}\right)<$ $<+\infty$ for some $t_{0} \in\langle c, d\rangle$. Let $\mathbf{x} \in V_{n}(c, d), \mathbf{y} \in V_{n}(a, b)$. Then

$$
\begin{equation*}
\left\langle\mathbf{y}, \int_{c}^{d} \mathrm{~d}_{t}[\boldsymbol{K}(., t)] \mathbf{x}(t)\right\rangle_{(a, b)}=\left\langle\mathbf{x}, \int_{a}^{b} \mathrm{~d}_{s}\left[\boldsymbol{K}^{\prime}(s, .)\right] \boldsymbol{y}(s)\right\rangle_{(c, d)} \tag{2,28}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\langle\int_{c}^{d} \mathrm{~d}_{t}[K(., t)] \mathbf{x}(t), \boldsymbol{y}\right\rangle_{(a, b)}=\left\langle\mathbf{x}, \int_{a}^{b} K^{\prime}(s, .) \mathrm{d} \mathbf{y}(s)\right\rangle_{(c, d)} . \tag{2,29}
\end{equation*}
$$

Proof. By (1.1), (2,11), (2,13a), (2,13b) all assumptions of Lemma 2,2 are satisfied for $k_{i j}(s, t), x_{l}(t), y_{m}(s), i, j, l, m=1, \ldots, n$. Therefore from $(2,25)$ we obtain

$$
\begin{equation*}
\int_{a}^{b} y_{m}(s) \mathrm{d}_{s}\left(\int_{c}^{d} x_{l}(t) \mathrm{d}_{t}\left[k_{i j}(s, t)\right]\right)=\int_{c}^{d} x_{l}(t) \mathrm{d}_{t}\left(\int_{a}^{b} y_{m}(s) \mathrm{d}_{s}\left[k_{i j}(s, t)\right]\right) \tag{2,30}
\end{equation*}
$$

for every $i, j, l, m=1,2, \ldots, n$. Hence

$$
\begin{aligned}
\left\langle\mathbf{y}, \int_{c}^{d} \mathrm{~d}_{t}\right. & {[K(., t)] x(t)\rangle_{(a, b)}=\int_{a}^{b} y^{\prime}(s) \mathrm{d}_{s}\left(\int_{c}^{d} \mathrm{~d}_{t}[K(s, t)] x(t)\right)=} \\
& =\sum_{i=1}^{n} \int_{a}^{b} y_{i}(s) \mathrm{d}_{s}\left(\sum_{j=1}^{n} \int_{c}^{d} x_{j}(t) \mathrm{d}_{t}\left[k_{i j}(s, t)\right]\right)= \\
& =\sum_{i=1}^{n} \sum_{j=1}^{n} \int_{a}^{b} y_{i}(s) \mathrm{d}_{s}\left(\int_{c}^{d} x_{j}(t) \mathrm{d}_{t}\left[k_{i j}(s, t)\right]\right)= \\
& =\sum_{i=1}^{n} \sum_{j=1}^{n} \int_{c}^{d} x_{j}(t) \mathrm{d}_{t}\left(\int_{a}^{b} y_{i}(s) \mathrm{d}_{s}\left[k_{i j}(s, t)\right]\right)= \\
& =\sum_{j=1}^{n} \int_{c}^{d} x_{j}(t) d_{t}\left(\sum_{i=1}^{n} \int_{a}^{b} y_{i}(s) \mathrm{d}_{s}\left[k_{i j}(s, t)\right]\right)= \\
= & \int_{c}^{d} \mathbf{x}^{\prime}(t) \mathrm{d}_{t}\left(\int_{a}^{b} \mathrm{~d}_{s}\left[K^{\prime}(s, t)\right] \mathbf{y}(s)\right)= \\
= & \left\langle\mathbf{x}, \int_{a}^{b} \mathrm{~d}_{s}\left[K^{\prime}(s, .)\right] \mathbf{y}(s)\right\rangle_{(c, d)} .
\end{aligned}
$$

Thus the equality $(2,28)$ is proved.

From $(2,26)$ we have

$$
\begin{equation*}
\int_{c}^{d} x_{l}(t) \mathrm{d}_{t}\left(\int_{a}^{b} k_{i j}(s, t) \mathrm{d} y_{m}(s)\right)=\int_{a}^{b}\left(\int_{c}^{d} x_{l}(t) \mathrm{d}_{[ }\left[k_{i j}(s, t)\right]\right) \mathrm{d} y_{m}(s) \tag{2,31}
\end{equation*}
$$

for every $i, j, l, m=1,2, \ldots, n$. Hence

$$
\begin{aligned}
& \quad\left\langle\int_{c}^{d} \mathrm{~d}_{t}[K(., t)] x(t), \boldsymbol{y}\right\rangle_{(a, b)}= \\
& =\sum_{i=1}^{n} \int_{a}^{b}\left(\sum_{j=1}^{n} \int_{c}^{d} x_{j}(t) \mathrm{d}_{t}\left[k_{i j}(s, t)\right]\right) \mathrm{d} y_{i}(s)= \\
& =\sum_{i=1}^{n} \sum_{j=1}^{n} \int_{a}^{b}\left(\int_{c}^{d} x_{j}(t) \mathrm{d}_{t}\left[k_{i j}(s, t)\right]\right) \mathrm{d} y_{i}(s)= \\
& =\sum_{i=1}^{n} \sum_{j=1}^{n} \int_{c}^{d} x_{j}(t) \mathrm{d}_{t}\left(\int_{a}^{b} k_{i j}(s, t) \mathrm{d} y_{i}(s)\right)= \\
& =\sum_{j=1}^{n} \int_{c}^{d} x_{j}(t) \mathrm{d}_{t}\left(\sum_{i=1}^{n} \int_{a}^{b} k_{i j}(s, t) \mathrm{d} y_{i}(s)\right)= \\
& =\int_{c}^{d} x^{\prime}(t) \mathrm{d}_{t}\left(\int_{a}^{b} K^{\prime}(s, t) \mathrm{d} y(s)\right)=\left\langle\mathbf{x}, \int_{a}^{b} K^{\prime}(s, .) \mathrm{d} y(s)\right\rangle_{(c, d)}
\end{aligned}
$$

and $(2,29)$ is also proved.
Remark 2,6 . The equality $(2,30)$ (resp. $(2,31)$ ) enables us also to derive the following relations which are symmetric to the relations $(2,28)$ (resp. $(2,29)$ )

$$
\begin{equation*}
\left\langle x, \int_{a}^{b} \mathrm{~d}_{s}[K(s, .)] \mathbf{y}(s)\right\rangle_{(c, d)}=\left\langle\boldsymbol{y}, \int_{c}^{d} \mathrm{~d}_{t} K^{\prime}(., t) x(t)\right\rangle_{(a, b)} \tag{2,32}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\langle\int_{a}^{b} \mathrm{~d}_{s}[K(s, .)] \boldsymbol{y}(s), \boldsymbol{x}\right\rangle_{(c, d)}=\left\langle\boldsymbol{y}, \int_{c}^{d} K^{\prime}(., t) \mathrm{d} \mathbf{x}(t)\right\rangle_{(a, b)} . \tag{2,33}
\end{equation*}
$$

We note that $(2,29)$ can be written in the form

$$
\int_{a}^{b} \mathrm{~d} y^{\prime}(s)\left(\int_{c}^{d} \mathrm{~d}_{t} K(s, t) x(t)\right)=\int_{c}^{d} \mathrm{~d}_{t}\left[\int_{a}^{b} \mathrm{~d}^{\prime}(s) K(s, t)\right] x(t) .
$$

3. OPERATORS $\int_{0}^{1} \mathrm{~d}_{\mathrm{t}}[\boldsymbol{K}(s, t)] \mathbf{x}(t)$ AND $\int_{0}^{1} \boldsymbol{K}(s, t) \mathrm{d} \mathbf{x}(t)$ IN THE SPACE $V_{n}$

In the sequel we denote $V_{n}=V_{n}(0,1)$. For $\mathrm{x} \in V_{n}$ we denote

$$
\begin{equation*}
\|\mathbf{x}\|_{V_{n}}=\|\mathbf{x}(0)\|+\operatorname{var}_{0}^{1} \mathbf{x} \tag{3,1}
\end{equation*}
$$

$\|\cdot\|_{V_{n}}$ is the usual norm in $V_{n}, V_{n}$ with this norm forms a Banach space.
Let $K(s, t): I=\langle 0,1\rangle \times\langle 0,1\rangle \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ be given. Let us suppose that $K(s, t)=K(s, 0)$ for $t<0$ and $K(s, t)=K(s, 1)$ for $t>1$.

Further we assume in this section that

$$
\begin{equation*}
v(\boldsymbol{K})=v_{I}(\boldsymbol{K})<+\infty \tag{3,2}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{var}_{0}^{1} K(0, .)<+\infty \tag{3,3}
\end{equation*}
$$

Proposition 2,3 quarantees for every $\mathbf{x} \in V_{n}, \mathbf{x}^{\prime}(t)=\left(x_{1}(t), \ldots, x_{n}(t)\right)$ the existence of the integral

$$
\begin{equation*}
\int_{0}^{1} d_{t}[K(s, t)] x(t)=y(s), \quad s \in\langle 0,1\rangle \tag{3,4}
\end{equation*}
$$

By $(2,24)$ from the same Proposition we obtain the inequality

$$
\begin{equation*}
\operatorname{var}_{0}^{1} \mathbf{Y}=\operatorname{var}_{0}^{1}\left(\int_{0}^{1} \mathrm{~d}_{t}[K(s, t)] \times(t)\right) \leqq\|x\|_{V_{n}} v(K) \tag{3,5}
\end{equation*}
$$

The map

$$
\begin{equation*}
K x=y \tag{3,6}
\end{equation*}
$$

( y is determined by $(3,4)$ ) is evidently a linear operator on the space $V_{n}$ because $(3,5)$ implies $\mathbf{y} \in V_{n}$.

Further it is

$$
\begin{aligned}
\|\boldsymbol{K} x\|_{V_{n}}= & \|\boldsymbol{Y}(0)\|+\operatorname{var}_{0}^{1} \mathbf{y} \leqq\left\|\int_{0}^{1} \mathrm{~d}_{t}[K(0, t)] \mathbf{x}(t)\right\|+\|\mathbf{x}\|_{V_{n}} v(K) \leqq \\
& \leqq \sup _{t \in\langle 0,1\rangle}\|\mathbf{x}(t)\| \operatorname{var}_{0}^{1} K(0, .)+\|\mathbf{x}\|_{V_{n}} v(\boldsymbol{K})
\end{aligned}
$$

and therefore

$$
\begin{equation*}
\|\boldsymbol{K} \mathbf{x}\|_{V_{n}} \leqq\left(\operatorname{var}_{0}^{1} K(0, .)+v(K)\right)\|\boldsymbol{x}\|_{V_{r}} \tag{3,7}
\end{equation*}
$$

i.e. $K: V_{n} \rightarrow V_{n}$ is a continuous linear operator on $V_{n}$.

Theorem 3,1. The linear operator $K: V_{n} \rightarrow V_{n}$ from $(3,6)$ is completely continuous if $(3,2)$ and $(3,3)$ is satisfied.

Proof. We denote by $B=\left\{x \in V_{n} ;\|x\|_{V_{n}}<1\right\}$ the unit ball in $V_{n}$. Let a sequence $\mathbf{x}^{l}, l=1,2, \ldots$ be given such that $\mathbf{x}^{l} \in B$ for $l=1,2, \ldots$ By Helly's Choice Theorem it is possible to select from the sequence $\boldsymbol{x}^{\boldsymbol{l}}$ a subsequence $\boldsymbol{x}^{l_{k}}$ such that

$$
\lim _{k \rightarrow \infty} x^{l_{k}}(t)=x^{*}(t)
$$

for any $t \in\langle 0,1\rangle$ so that at the same time $\operatorname{var}_{0}^{1} \mathbf{x}^{*} \leqq 1$ (i.e. $\mathbf{x}^{*} \in V_{n}$ ). We put $\boldsymbol{z}^{k}(t)=$ $=\mathbf{x}^{l_{k}}(t)-\mathbf{x}^{*}(t)$ for $t \in\langle 0,1\rangle$. Evidently $z^{k} \in V_{n}$ for all $k=1,2, \ldots,\left\|z^{k}\right\|_{V_{n}} \leqq$ $\leqq\left\|\boldsymbol{x}^{I_{k}}\right\|_{V_{n}}+\left\|\mathbf{x}^{*}(0)\right\|+\operatorname{var}_{0}^{1} \mathbf{x}<3$ and

$$
\begin{equation*}
\lim _{k \rightarrow \infty} z^{k}(t)=0 \quad \text { for all } \quad t \in\langle 0,1\rangle \tag{3,8}
\end{equation*}
$$

$(2,24)$ implies

$$
\operatorname{var}_{0}^{1}\left(\int_{0}^{1} \mathrm{~d}_{t}[K(s, t)] \mathbf{z}^{k}(t)\right) \leqq \int_{0}^{1}\left\|\mathbf{z}^{k}(t)\right\| \mathrm{d} \psi(t)
$$

where $\psi:\langle 0,1\rangle \rightarrow R$ is a nondecreasing function $\psi(0)=0, \psi(1)=v(K)$ (cf. $(2,15 b)$ where $\langle a, b\rangle=\langle c, d\rangle=\langle 0,1\rangle$ ). Clearly $0 \leqq\left\|\mathbf{z}^{k}(t)\right\| \leqq 3$ for $t \in\langle 0,1\rangle$ and the function $\left\|z^{k}(t)\right\|$ belongs to $V(0,1)$ for all $k=1,2, \ldots$, hence the integral $\int_{0}^{1}\left\|z^{k}(t)\right\| \mathrm{d} \psi(t)$ exists (as Kurzweil integral or equivalently as Perron-Stieltjes integral). The Dominated Convergence Theorem for the Perron-Stieltjes integral implies

$$
\lim _{k \rightarrow \infty} \int_{0}^{1}\left\|\mathbf{z}^{k}(t)\right\| \mathrm{d} \psi(t)=0
$$

Hence we have

$$
\begin{equation*}
\lim _{k \rightarrow \infty} \operatorname{var}_{0}^{1}\left(\int_{0}^{1} \mathrm{~d}_{t}[K(s, t)] x^{l_{k}}(t)-\int_{0}^{1} \mathrm{~d}_{t}[K(s, t)] x^{*}(t)\right)=0 . \tag{3,9}
\end{equation*}
$$

Similarly we can show that

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|\int_{0}^{1} \mathrm{~d}_{t}[K(0, t)] x^{l_{k}}(t)-\int_{0}^{1} \mathrm{~d}_{t}[K(0, t)] x^{*}(t)\right\|=0 \tag{3,10}
\end{equation*}
$$

From $(3,9)$ and $(3,10)$ we have

$$
\lim _{k \rightarrow \infty}\left\|\int_{0}^{1} \mathrm{~d}_{t}[K(s, t)] \mathrm{x}^{l_{k}(t)-y^{*}(s)}\right\|_{V_{n}}=0
$$

where $y^{*}(s)=\int_{0}^{1} \mathrm{~d}_{t}[K(s, t)] \mathrm{x}^{*}(t) \in V_{n}$ since $\mathrm{x}^{*} \in V_{n}$. Hence we conclude that the image of the unit ball $B$ is precompact in $V_{n}$ and consequently the operator $K$ is completely continuous.

We shall derive now some special analytic properties of the operator $K$ if $K(s, t)$ : $: I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfies some additional assumptions.

Proposition 3,1. Let $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfy $(3,2)$ and $(3,3), x \in V_{n}$. Let further for some $s_{0} \in\langle 0,1\rangle$

$$
\lim _{s \rightarrow s_{0}^{+}}\left\|K(s, t)-K\left(s_{0}, t\right)\right\|=0 \quad \text { or } \lim _{s \rightarrow s_{0}-}\left\|K(s, t)-K\left(s_{0}, t\right)\right\|=0
$$

for all $t \in\langle 0,1\rangle$. Then

$$
\lim _{s \rightarrow s_{0}+} y(s)=y\left(s_{0}\right), \lim _{s \rightarrow s_{0}-} y(s)=y\left(s_{0}\right)
$$

respectively where $y \in V_{n}$ is given in $(3,4)$.
Proof. The statement follows in an easy way from the inequality $($ see $(2,23)$ from Proposition 2,3 and (2,15a))

$$
\begin{gathered}
\left\|\boldsymbol{Y}(s)-\boldsymbol{y}\left(s_{0}\right)\right\|=\left\|\int_{0}^{1} \mathrm{~d}_{t}\left[K(s, t)-K\left(s_{0}, t\right)\right] \mathbf{x}(t)\right\| \leqq \\
\leqq\|x\|_{V_{n}} \operatorname{var}_{0}^{1}\left(\boldsymbol{K}(s, .)-K\left(s_{0}, .\right)\right) \leqq\|x\|_{V_{n}}\left|\varphi(s)-\varphi\left(s_{0}\right)\right|
\end{gathered}
$$

and from Lemma 2,1.
Corollary 3,1. If $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfies $(3,2),(3,3)$ and $K(s, t)$ is continuous in the variable sfor any $t \in\langle 0,1\rangle$ then the vector function $y(s):\langle 0,1\rangle \rightarrow R^{n}$ from $(3,4)$ is continuous for any $\mathbf{x} \in V_{n}$, i.e. $K$ maps $V_{n}$ into $C V_{n}$ (the space of continuous n-vector functions with bounded variation).

Lemma 3,1. Let $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfy $(3,2)$ and $(3,3), x \in V_{n}$. Let $s_{0} \in$ $\in\langle 0,1\rangle$. If the limit

$$
\begin{equation*}
\lim _{s \rightarrow s_{0}+} K(s, t)=K\left(s_{0}+, t\right) \quad \text { or } \lim _{s \rightarrow s_{0}-} K(s, t)=K\left(s_{0}-, t\right) \tag{3,11}
\end{equation*}
$$

exists for all $t \in\langle 0,1\rangle$ then we have

$$
\begin{align*}
& y\left(s_{0}+\right)=\lim _{s \rightarrow s_{0}+} y(s)=\int_{0}^{1} d_{t}\left[K\left(s_{0}+, t\right)\right] x(t),  \tag{3,12}\\
& y\left(s_{0}-\right)=\lim _{s \rightarrow s_{0}-} y(s)=\int_{0}^{1} d_{t}\left[K\left(s_{0}-, t\right)\right] x(t)
\end{align*}
$$

respectively.

$$
y\left(s_{0}+\right)-\int_{0}^{1} \mathrm{~d}_{t}\left[K\left(s_{0}+, t\right)\right] x(t)=\lim _{s \rightarrow s_{0}+} \int_{0}^{1} \mathrm{~d}_{t}\left[K(s, t)-K\left(s_{0}+, t\right)\right] x(t)=0
$$

because for $\delta>0$

$$
\left\|\int_{0}^{1} \mathrm{~d}_{t}\left[K\left(s_{0}+\delta, t\right)-K\left(s_{0}+, t\right)\right] \mathbf{x}(t)\right\| \leqq\|\mathbf{x}\|_{V_{n}} \operatorname{var}_{0}^{1}\left(K\left(s_{0}+\delta, .\right)-K\left(s_{0}+, .\right)\right)
$$

and by Corollary 2, 3 it is

$$
\lim _{\delta \rightarrow 0+} \operatorname{var}_{0}^{1}\left(\boldsymbol{K}\left(s_{0}+\delta, .\right)-\boldsymbol{K}\left(s_{0}+, .\right)\right)=0
$$

The second statement can be proved similarly.
Remark 3,1. If we suppose that $\operatorname{var}_{0}^{1} \boldsymbol{K}\left(., t_{\boldsymbol{*}}\right)<+\infty$ for some $t_{*} \in\langle 0,1\rangle$ for $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ in addition to the conditions $(3,2),(3,3)$ then $\operatorname{var}_{0}^{1} K(., t)<$ $<+\infty$ for all $t \in\langle 0,1\rangle$ and the limits $(3,11)$ exist for all $s_{0} \in\langle 0,1\rangle$ and all $t \in$ $\in\langle 0,1\rangle$, and $(3,12)$ holds for all $s_{0} \in\langle 0,1\rangle$.

Proposition 3,2. Let $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfy $(3,2)$ and $(3,3)$. If $K(s, t)$ is for every $t \in\langle 0,1\rangle$ regular at $s_{0} \in\langle 0,1\rangle$, i.e. the limits $(3,11)$ exist for every $t \in\langle 0,1\rangle$ and

$$
\begin{equation*}
K\left(s_{0}+, t\right)+K\left(s_{0}-, t\right)-2 K\left(s_{0}, t\right)=0 \tag{3,13}
\end{equation*}
$$

for all $t \in\langle 0,1\rangle$ then

$$
\begin{equation*}
\mathbf{y}\left(s_{0}+\right)+\mathbf{y}\left(s_{0}-\right)-2 \mathbf{y}\left(s_{0}\right)=0, \tag{3,14}
\end{equation*}
$$

i.e. $y(s)$ is a regular function at $s_{0} \in\langle 0,1\rangle$.

Proof follows immediately from Lemma 3,1.

Corollary 3,2. If $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfies $(3,2),(3,3)$, the limits $(3,11)$ exist for every $s_{0} \in\langle 0,1\rangle$ and $t \in\langle 0,1\rangle$ and $(3,13)$ holds for every $t \in\langle 0,1\rangle$ then the $n$-vector function $y(s):\langle 0,1\rangle \rightarrow R^{n}$ from $(3,4)$ is regular for any $x \in V_{n}$ (this means that $(3,22)$ holds for all $\left.s_{0} \in\langle 0,1\rangle\right)$, i.e. the operator $K$ maps $V_{n}$ into the space $R V_{n}$ of all regular n-vector functions of bounded variation.

Proposition 3,3. Let $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfy $(3,2),(3,3)$ and

$$
\begin{equation*}
\operatorname{var}_{0}^{1} K(., 0)<+\infty \tag{3,15}
\end{equation*}
$$

If $\alpha, \beta \in\langle 0,1\rangle$ then for $\mathbf{x} \in V_{n}$ the expressions

$$
\begin{align*}
& \boldsymbol{K}_{1} \mathbf{x}=\boldsymbol{K}(s, \alpha) \mathbf{x}(\beta)=\mathbf{y}_{1}(s),  \tag{3,16}\\
& \boldsymbol{K}_{2} \mathbf{x}=\Delta_{t}^{+} \boldsymbol{K}(s, \alpha) \Delta^{+} \mathbf{x}(\beta)=\mathbf{y}_{2}(s), \\
& \boldsymbol{K}_{3} \mathbf{x}=\Delta_{t}^{-} \boldsymbol{K}(s, \alpha) \Delta^{-} \mathbf{x}(\beta)=\mathbf{y}_{3}(s)
\end{align*}
$$

define completely continuous operators on $V_{n}$.
Proof. We have (by ( $2,14 \mathrm{~b}$ ))

$$
\begin{aligned}
\left\|\boldsymbol{K}_{1} \mathbf{x}\right\|_{V_{n}} & =\|\boldsymbol{K}(0, \alpha) \mathbf{x}(\beta)\|+\operatorname{var}_{0}^{1}(\boldsymbol{K}(., \alpha) \mathbf{x}(\beta)) \leqq \\
& \leqq\left\{\|\boldsymbol{K}(0, \alpha)\|+\operatorname{var}_{0}^{1} \boldsymbol{K}(., \alpha)\right\}\|\mathbf{x}(\beta)\| \leqq \\
& \leqq\left\{\|\boldsymbol{K}(0, \alpha)\|+\operatorname{var}_{0}^{1} \boldsymbol{K}(., 0)+v(\boldsymbol{K})\right\}\|\mathbf{x}\|_{V_{n}} .
\end{aligned}
$$

Further it is (cf. Corollary 2,3)

$$
\begin{aligned}
\left\|\boldsymbol{K}_{2} \mathbf{x}\right\|_{\boldsymbol{V}_{n}} & \leqq\left\|\Delta^{+} \boldsymbol{K}(0, \alpha)\right\|\left\|\Delta^{+} \boldsymbol{x}(\beta)\right\|+\operatorname{var}_{0}^{1} \Delta_{\mathbf{t}}^{+} \boldsymbol{K}(., \alpha)\left\|\Delta^{+} \boldsymbol{x}(\beta)\right\|= \\
& =\left\{\operatorname{var}_{0}^{1} \boldsymbol{K}(0, .)+v(\boldsymbol{K})\right\}\left\|\Delta^{+} \mathbf{x}(\beta)\right\| \leqq \\
& \leqq\left\{\operatorname{var}_{0}^{1} \boldsymbol{K}(0, .)+v(\boldsymbol{K})\right\}\|\mathbf{x}\|_{\boldsymbol{V}_{n}}
\end{aligned}
$$

and similarly

$$
\left\|\boldsymbol{K}_{3} \mathbf{x}\right\|_{\boldsymbol{V}_{n}} \leqq\left\{\operatorname{var}_{0}^{1} \boldsymbol{K}(0, .)+v(\boldsymbol{K})\right\}\left\|\Delta^{-} \mathbf{x}(\beta)\right\| \leqq\left\{\operatorname{var}_{0}^{1} \boldsymbol{K}(0, .)+v(\boldsymbol{K})\right\}\|\mathbf{x}\|_{\boldsymbol{V}_{n}} .
$$

Let $B$ be the unit ball in the space $V_{n}$ and let $x_{l} \in B, l=1,2, \ldots$ be given. The sequence $x_{l}(\beta)\left(\Delta^{+} x_{l}(\beta), \Delta^{-} x_{l}(\beta)\right)$ is bounded in $R^{n}$. Hence there is a point $z(\beta)$ $\left(\mathbf{z}^{+}(\beta), \mathbf{z}^{-}(\beta)\right)$ in $\boldsymbol{R}^{n}$ and a subsequence $\boldsymbol{x}_{l_{j}}(\beta)\left(\Delta^{+} \boldsymbol{x}_{l_{j}}(\beta), \Delta^{-} \boldsymbol{x}_{l_{j}}(\beta)\right)$ such that $\lim _{j \rightarrow \infty} \boldsymbol{x}_{l_{j}}(\beta)=\boldsymbol{z}(\beta)\left(\lim _{j \rightarrow \infty} \Delta^{+} \boldsymbol{x}_{l_{j}}(\mathrm{~b})=\mathbf{z}^{+}(\beta), \lim _{j \rightarrow \infty} \Delta^{-} \boldsymbol{x}_{l_{j}}(\beta)=\mathbf{z}^{-}(\beta)\right)$.

Let us set $\boldsymbol{y}_{1}^{*}(s)=K(s, \alpha) \mathbf{z}(\beta) \in V_{n}$, then we have
$\left\|\boldsymbol{K}_{1} \mathbf{x}_{l_{j}}-\boldsymbol{y}_{1}^{*}\right\|_{v_{n}} \leqq\left\{\boldsymbol{K}(0,0)+\operatorname{var}_{0}^{1} \boldsymbol{K}(0,)+.\operatorname{var}_{0}^{1} \boldsymbol{K}(., 0)+v(\boldsymbol{K})\right\}\left\|\mathbf{x}_{l_{j}}(\beta)-\mathbf{z}(\beta)\right\|$, hence $\lim _{j \rightarrow \infty}\left\|K_{1} x_{l_{j}}-\boldsymbol{y}_{1}^{*}\right\|_{V_{n}}=0$, i.e. the operator $K_{1}$ maps B into precompact set and therefore $K_{1}$ is completely continuous.

By setting $\boldsymbol{Y}_{2}^{*}(s)=\Delta_{t}^{+} \boldsymbol{K}(s, \alpha) \mathbf{z}^{+}(\beta)$ we obtain

$$
\left\|K_{2} x_{l_{j}}-\boldsymbol{y}_{2}^{*}\right\|_{V_{n}} \leqq\left\{\Delta_{t}^{+} K(0, \alpha)+\operatorname{var}_{0}^{1} \Delta_{t}^{+} K(., \alpha)\right\} \Delta^{+} \boldsymbol{x}_{l_{j}}(\beta)-z^{+}(\mathrm{b}) \|,
$$

hence $\lim _{j \rightarrow \infty}\left\|K_{2} \mathbf{x}_{l_{j}}-\mathbf{y}_{2}^{*}\right\|_{V_{n}}=0$ and $K_{2}$ is a completely continuous operator. Similarly the complete continuity of $\boldsymbol{K}_{\mathbf{3}}$ can be obtained.

Proposition 3,4. If $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfies $(3,2),(3,3)$ and $(3,15)$ then the series

$$
\begin{equation*}
\sum_{0 \leqq \tau<1} \Delta_{t}^{+} K(s, \tau) \Delta^{+} \mathbf{x}(\tau), \quad \sum_{0<\tau \leqq 1} \Delta_{t}^{-} K(s, \tau) \Delta^{-} \mathbf{x}(\tau) \tag{3,17}
\end{equation*}
$$

define completely continuous operators on $V_{n}$.
Proof. For any $t^{\prime}, t^{\prime \prime} \in\langle 0,1\rangle$ and all $s \in\langle 0,1\rangle$ we have

$$
\begin{aligned}
& \left\|\boldsymbol{K}\left(s, t^{\prime}\right)-K\left(s, t^{\prime \prime}\right)\right\| \leqq\left\|K\left(0, t^{\prime}\right)-K\left(0, t^{\prime \prime}\right)\right\|+ \\
& +\left\|\boldsymbol{K}\left(s, t^{\prime}\right)-\boldsymbol{K}\left(0, t^{\prime}\right)-\boldsymbol{K}\left(s, t^{\prime \prime}\right)+\boldsymbol{K}\left(0, t^{\prime \prime}\right)\right\| \leqq \\
\leqq & \left|\operatorname{var}_{0}^{r^{\prime}} \boldsymbol{K}(0, .)-\operatorname{var}_{0}^{\mathrm{r}^{\prime \prime}} \boldsymbol{K}(0, .)\right|+v_{\langle 0,1\rangle \times\left\langle t^{\prime}, t^{\prime \prime}\right\rangle}(\boldsymbol{K}) \leqq \\
\leqq & \left|\operatorname{var}_{0}^{t^{\prime}} \boldsymbol{K}(0, .)-\operatorname{var}_{0}^{t^{\prime \prime}} \boldsymbol{K}(0, .)\right|+\left|\psi\left(t^{\prime}\right)-\psi\left(t^{\prime \prime}\right)\right|
\end{aligned}
$$

(cf. $(2,15 \mathrm{~b})$ for $\psi$ ). This implies that the set of discontinuities of $\boldsymbol{K}(s, t)$ in the variable $t$ lies on a denumerable family of lines parallel to the $s$-axis: $t=t_{l}, l=1,2, \ldots$ since $\operatorname{var}_{0}^{1} K(0,$.$) and \psi(t)$ are functions $(\langle 0,1\rangle \rightarrow R)$ of bounded variation. In this way it is possible to rewrite the first expression from $(3,17)$ in the form

$$
\begin{equation*}
\sum_{l=1}^{\infty} \Delta_{t}^{+} K\left(s, t_{l}\right) \Delta^{+} x\left(t_{l}\right) \tag{3,18}
\end{equation*}
$$

and similarly the second one.
The operator $(3,18)$ is defined as the limit of the sequence of operators $U_{N}: V_{n} \rightarrow V_{n}$ where

$$
\begin{equation*}
U_{N} x=\sum_{l=1}^{N} \Delta_{t}^{+} K\left(s, t_{l}\right) \Delta_{t}^{+} x\left(t_{l}\right), \tag{3,19}
\end{equation*}
$$

i.e.

$$
U \mathbf{x}=\sum_{l=2}^{\infty} \Delta_{t}^{+} K\left(s, t_{l}\right) \Delta^{+} x\left(t_{l}\right)=\lim _{N \rightarrow \infty} U_{N} x .
$$

By Proposition 3,3 for any integer $N$ the operator $\boldsymbol{U}_{N}$ from $(3,19)$ is completely continuous because $\boldsymbol{U}_{N}$ is a finite sum of completely continuous operators.
Let us denote $\left[V_{n} \rightarrow V_{n}\right.$ ] the space of all linear operators acting on $V_{n},\left[V_{n} \rightarrow V_{n}\right]$ is a normed linear space with the norm

$$
\|U\|_{\left[V_{n} \rightarrow V_{n}\right]}=\sup _{\|\times\|_{V_{n}}=1}\left\|U X_{\|}\right\|_{V_{n}} .
$$

The completeness of $V_{n}$ implies that the space $\left[V_{n} \rightarrow V_{n}\right]$ is complete. Further we have

$$
\begin{gathered}
\left\|U_{M} x-U_{N} x\right\|_{V_{n}}=\left\|\sum_{l=N_{+1}}^{M} \Delta_{t}^{+} K\left(s, t_{1}\right) \Delta^{+} x\left(t_{1}\right)\right\|_{V_{n}}= \\
=\left\|\sum_{l=N+1}^{M} \Delta_{t}^{+} K\left(0, t_{l}\right) \Delta^{+} x\left(t_{l}\right)\right\|+\operatorname{var}_{0}^{1} \sum_{l=N+1}^{M} \Delta_{t}^{+} K\left(., t_{l}\right) \Delta^{+} x\left(t_{l}\right) \leqq \\
\leqq \operatorname{var}_{0}^{1} x\left(\sum_{l=N+1}^{M}\left\|\Delta_{t}^{+} K\left(0, t_{l}\right)\right\|+\sum_{l=N+1}^{M} \operatorname{var}_{0}^{1} \Delta_{t}^{+} K\left(., t_{l}\right)\right) .
\end{gathered}
$$

Hence

$$
\begin{equation*}
\left\|U_{M}-U_{N}\right\|_{\left[V_{n} \rightarrow V_{n}\right]} \leqq \sum_{t=N+1}^{M}\left\|\Delta_{t}^{+} K\left(0, t_{l}\right)\right\|+\sum_{t=N+1}^{M} \operatorname{var}_{0}^{1} \Delta_{t}^{+} K\left(., t_{l}\right) . \tag{3,20}
\end{equation*}
$$

The assumption $(3,3)$ yields the convergence of the series $\sum_{i=1}^{\infty}\left\|\Delta_{t}^{+} K\left(0, t_{l}\right)\right\|$. Further we have (cf. Corollary 2,3)

$$
\operatorname{var}_{0}^{1} \Delta_{t}^{+} K\left(., t_{l}\right) \leqq \psi\left(t_{l}+\right)-\psi\left(t_{l}\right)=\Delta^{+} \psi\left(t_{l}\right)
$$

where $\psi:\langle 0,1\rangle \rightarrow R$ is a non-decreasing function, $\psi(0)=0, \psi(1)=v(K)$. Since the series $\sum_{l=1}^{\infty} \Delta^{+} \psi\left(t_{l}\right)$ evidently converges we obtain that the series $\sum_{i=1}^{\infty} \operatorname{var}_{0}^{1} \Delta_{t}^{+} K\left(., t_{l}\right)$ converges as well. This implies by $(3,20)$ that $\boldsymbol{U}_{N}, N=1,2, \ldots$ forms a fundamental sequence in the (complete) Banach space $\left[V_{n} \rightarrow V_{n}\right]$ and that $\lim _{N \rightarrow \infty} \boldsymbol{U}_{N}=\boldsymbol{U}$ exists, hence the operator

$$
\boldsymbol{U x}=\sum_{l=1}^{\infty} \Delta_{t}^{+} \boldsymbol{K}\left(s, t_{\boldsymbol{l}}\right) \Delta^{+} \mathbf{x}\left(t_{l}\right)=\sum_{0 \leqq \tau<1} \Delta_{t}^{+} \boldsymbol{K}(s, \tau) \Delta^{+} \mathbf{x}(\tau)
$$

is completely continuous. The proof of complete continuity of the second operator in $(3,17)$ can be carried out in the same manner.

Theorem 3,2. If $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfies $(3,2),(3,3)$ and $(3,15)$ then the expression

$$
\begin{equation*}
\int_{0}^{1} K(s, t) \mathrm{d} \mathbf{x}(t)=\hat{\mathbf{R}} \mathbf{x}, \quad \mathbf{x} \in V_{n} \tag{3,20}
\end{equation*}
$$

defines a completely continuous operator on $V_{n}$.
Proof. Using the integration by parts formula $(2,9)$ for row vectors of $\boldsymbol{K}(s, t)$ for any $s \in\langle 0,1\rangle$ we can write

$$
\begin{gathered}
\int_{0}^{1} K(s, t) \mathrm{d} x(t)=-\int_{0}^{1} \mathrm{~d}_{\mathrm{t}}[K(s, t)] \mathbf{x}(t)+K(s, 1) \times(1)-K(s, 0) \times(0)- \\
-\sum_{0 \leq \tau<1} \Delta_{t}^{+} K(s, \tau) \Delta^{+} \mathbf{x}(\tau)+\sum_{0<\tau \leq 1} \Delta_{t}^{-} K(s, \tau) \Delta^{-} \mathbf{x}(\tau) .
\end{gathered}
$$

By Theorem 3,1, Propositions 3,3 and 3,4 we see from this expression that the operator $\hat{\boldsymbol{K}}$ from $(3,20)$ is a linear combination of completely continuous operators and we obtain in this way our Theorem.

Remark 3,2. We note that for the operator $\hat{\boldsymbol{K}}: V_{n} \rightarrow V_{n}$ given in $(3,20)$ it is possible to derive further analytic properties (continuity, regularity of the result of the operation) if some additional conditions for $K(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ are assumed. This can be made if we employ the properties of our integral.

## 4. AUXILIARY STATEMENT FROM FUNCTIONAL ANALYSIS

In this Section we give a simple general statement based on the well known Riesz theory from functional analysis which will be useful in our considerations about Fredholm-Stieltjes integral equations in Section 5.

Let $X, Y$ be normed spaces with the norms $\|\cdot\|_{X},\|\cdot\|_{Y}$ respectively. By $X^{\prime}, Y^{\prime}$ we denote the dual spaces to $X, Y$ respectively. Let a bilinear form $\langle x, y\rangle$ on $X \times Y$ be given which separates points of $X$, i.e.
(i) for $x \in X, x \neq 0$ there exists $y \in Y$ such that $\langle x, y\rangle \neq 0$
and which separates points of $Y$, i.e.
(ii) for $y \in Y, y \neq 0$ there exists $x \in X$ such that $\langle x, y\rangle \neq 0$.

Further we assume that

$$
\begin{equation*}
|\langle x, y\rangle| \leqq C\|x\|_{X}\|y\|_{\boldsymbol{Y}} \tag{4,1}
\end{equation*}
$$

for any $x \in X, y \in Y$ where $C \geqq 0$ is a constant.
For any fixed $y \in Y$ we denote by $[y]$ the linear functional on $X$ which corresponds to $y \in Y$ in terms of the bilinear form 〈., .〉; [y] is defined by the relation

$$
\begin{equation*}
[y](x)=\langle x, y\rangle . \tag{4,2}
\end{equation*}
$$

The inequality $(4,1)$ quarantees the continuity of $[y]$, i.e. we have $[y] \in X^{\prime}$.
We denote by $[Y]$ the linear set in $X^{\prime}$ of all continuous linear functionals of the form (4,2).

Since the bilinear form $\langle x, y\rangle$ separates points of $Y$ we have $[y]=0 \in X^{\prime}([y] \in$ $\in[Y])$ if and only if $y=0(y \in Y)$, i.e. $[y] \neq[\tilde{y}]$ if and only if $y \neq \tilde{y}, y, \tilde{y} \in Y$.

In this way a one-to-one correspondence between elements of $Y$ and $[Y]$ is given, in other words we have a one-to-one correspondence between the space $Y$ and its immersion $[Y]$ into $X^{\prime}$ which is given by the bilinear form $\langle x, y\rangle$.

For a set $M \subset Y$ we denote by $[M]$ the set of all elements in $X^{\prime}$ which are determined by an element in $M$, i.e.

$$
[M]=\left\{f \in X^{\prime} ; f=[y], y \in M\right\} .
$$

In the same way for any fixed $x \in X$ a continuous linear functional $[x] \in Y^{\prime}$ is given and we have a one-to-one correspondence between $X$ and $[X] \subset Y^{\prime}$. This follows from the fact that the bilinear form $\langle x, y\rangle$ separates points of $X$.

For a given operator $K: X \rightarrow X$ we denote by $K^{*}: X^{\prime} \rightarrow X^{\prime}$ the adjoint operator which is defined by the obvious relation $f(K x)=K^{*} f(x)$ for $f \in X^{\prime}, x \in X$ (similarly for operators $\boldsymbol{L}: Y \rightarrow Y$ ). If a linear operation $\boldsymbol{T}: X \rightarrow X$ is given then $T^{-1}(0)$ means the null - space of this operator, i.e.

$$
T^{-1}(0)=\{x \in X ; \quad T x=0\}
$$

Proposition 4,1. Let $X, Y$ be normed spaces, $K: X \rightarrow X, L: Y \rightarrow Y$ completely continuous operators in $X, Y$ respectively. Further let $\langle x, y\rangle$ be a bilinear form on $X \times Y$ which separates points of $X$ and $Y$ such that for any $x \in X, y \in Y$ the inequality $(4,1)$ holds, and let

$$
\begin{equation*}
\langle\boldsymbol{K} x, y\rangle=\langle x, L y\rangle \tag{4,3}
\end{equation*}
$$

for any $x \in X, y \in Y$.
We denote $T=I_{X}-K, S=I_{Y}-L, T^{*}=I_{X^{\prime}}-K^{*}, S^{*}=I_{Y^{\prime}}-L^{*}\left(I_{X}, I_{Y}\right.$, $I_{X^{\prime}}, I_{Y^{\prime}}$ are the identity operators in $X, Y, X^{\prime}, Y^{\prime}$ respectively). Then we have

$$
\begin{equation*}
\operatorname{dim} T^{-1}(0)=\operatorname{dim} T^{*-1}(0)=\operatorname{dim} S^{-1}(0)=\operatorname{dim} S^{*-1}(0)=r \tag{4,4}
\end{equation*}
$$

wherer $r$ is a nonnegative integer (by dim the dimension of a linear set is denoted) and

$$
\begin{equation*}
T^{*-1}(0) \subset[Y], \quad S^{*-1}(0) \subset[X] . \tag{4,5}
\end{equation*}
$$

Proof. We have (see VIII. 2 in [6]): The equation

$$
\begin{equation*}
\boldsymbol{T} x=x-K x=\tilde{x}, \quad \tilde{x} \in X \tag{4,6}
\end{equation*}
$$

has a solution $x \in X$ if and only if for any solution $f \in X^{\prime}$ of the equation

$$
\begin{equation*}
\boldsymbol{T}^{*} f=f-\boldsymbol{K}^{*} f=0 \tag{4,7}
\end{equation*}
$$

the relation

$$
\begin{equation*}
f(\tilde{x})=0 \tag{4,8}
\end{equation*}
$$

holds and the dimension of the linear set

$$
\boldsymbol{T}^{-1}(0)=\{x \in X ; \boldsymbol{T} x=x-\boldsymbol{K} x=0\}
$$

is finite and equal to the dimension of the linear set

$$
T^{*-1}(0)=\left\{f \in X^{\prime} ; T^{*} f=f-K^{*} f=0\right\}
$$

i.e. we have

$$
\begin{equation*}
\operatorname{dim} \boldsymbol{T}^{-1}(0)=\operatorname{dim} \boldsymbol{T}^{*-1}(0)=r \tag{4,9}
\end{equation*}
$$

Observe that $(4,3)$ can be written in the form $[y](K x)=[\boldsymbol{L} y](x)$ hence we have

$$
\begin{equation*}
\boldsymbol{K}^{*}[y]=[\boldsymbol{L} y] \tag{4,10}
\end{equation*}
$$

for any functional $[y] \in[Y] \subset X^{\prime}$. Further by $(4,10)$ it is

$$
\begin{gathered}
\boldsymbol{T}^{*-1}(0) \cap[Y]=\left\{[y] \in[Y] ; \boldsymbol{T}^{*}[y]=[y]-\boldsymbol{K}^{*}[y]=[y]-[\boldsymbol{L} y]=\right. \\
=[y-L y]=0\}=[\{y \in Y ; S y=y-L y=0\}]=\left[\boldsymbol{S}^{-1}(0)\right]
\end{gathered}
$$

and evidently

$$
\begin{equation*}
\operatorname{dim}\left[S^{-1}(0)\right]=\operatorname{dim}\left(T^{*-1}(0) \cap[Y]\right)=p \leqq r . \tag{4,11}
\end{equation*}
$$

With respect to the one-to-one correspondence between $Y$ and $[Y$ ] we have evidently

$$
\begin{equation*}
\operatorname{dim}\left[S^{-1}(0)\right]=\operatorname{dim} S^{-1}(0)=p \tag{4,12}
\end{equation*}
$$

Since $L: Y \rightarrow Y$ is a completely continuous operator, the Riesz theory yields

$$
\begin{equation*}
\operatorname{dim} S^{-1}(0)=\operatorname{dim} S^{*-1}(0)=\mathrm{p} \tag{4,13}
\end{equation*}
$$

The equation $(4,3)$ can be also rewritten in the form

$$
[x](\boldsymbol{L} y)=[\boldsymbol{K} x](y)
$$

for all $x \in X, y \in Y$, i.e. we have

$$
\begin{equation*}
\boldsymbol{L}^{*}[x]=[\boldsymbol{K} x] \tag{4,14}
\end{equation*}
$$

for any functional $[x] \in[X] \subset Y^{\prime}$.
Analoguously as above we obtain by $(4,14)$

$$
\begin{gathered}
S^{*-1}(0) \cap[X]= \\
=\left\{[x] \in[X] ;[x]-L^{*}[x]=[x]-[K x]=[x-K x]=0\right\}=\left[T^{-1}(0)\right] .
\end{gathered}
$$

Hence (by $(4,13)$ ) we have

$$
\begin{equation*}
\operatorname{dim}\left[\boldsymbol{T}^{-1}(0)\right]=\operatorname{dim}\left(S^{*-1}(0) \cap[X]\right)=q \leqq p \tag{4,15}
\end{equation*}
$$

Further we have evidently by $(4,9)$

$$
q=\operatorname{dim}\left[T^{-1}(0)\right]=\operatorname{dim} T^{-1}(0)=r .
$$

From this equality together with $(4,11)$ and $(4,15)$ we obtain $r=p$; thus $(4,9)$ and $(4,11)$ imply

$$
\operatorname{dim} T^{*-1}(0)=\operatorname{dim}\left(T^{*-1}(0) \cap[Y]\right)=r
$$

and hence we have

$$
T^{*-1}(0) \subset[Y] .
$$

The second relation from $(4,5)$ can be derived similarly.
Proposition 4,1 enables us to derive the following

Theorem 4,1. Let the assumptions of Proposition 4,1 be satisfied. Then either the equation

$$
\begin{equation*}
T x=x-K x=\tilde{x}, \quad \tilde{x} \in X \tag{4,16}
\end{equation*}
$$

admits a unique solution $x \in X$ for any $\tilde{x} \in X$, in particular $x=0$ for $\tilde{x}=0$; or the homogeneous equation

$$
\begin{equation*}
x-K x=0 \tag{4,17}
\end{equation*}
$$

admits $r$ linearly independent solutions $x_{1}, \ldots, x_{r}$ in $X$.
In the first case the equation

$$
\begin{equation*}
\boldsymbol{S} y=y-L y=\tilde{y}, \quad \tilde{y} \in Y \tag{4,18}
\end{equation*}
$$

has also a unique solution $y \in Y$ for any $\tilde{y} \in Y$. In the second case the equation

$$
\begin{equation*}
y-L y=0 \tag{4,19}
\end{equation*}
$$

admits $r$ linearly independent solutions $y_{1}, \ldots, y_{r}$ in $Y$. Moreover in the second case the equation $(4,16)$ has a solution in $X$ if and only if

$$
\begin{equation*}
\langle\tilde{x}, y\rangle=0 \tag{4,20}
\end{equation*}
$$

for any solution $y \in Y$ of $(4,19)$ and symmetrically $(4,18)$ has a solution in $Y$ if and only if

$$
\begin{equation*}
\langle x, \tilde{y}\rangle=0 \tag{4,21}
\end{equation*}
$$

for any solution $x \in X$ of $(4,17)$.
Proof. The first part of this theorem corresponds to the case when $r=0$ in $(4,4)$ from Proposition 4,1. The result of this part is a consequence of the well known Riesz theory of completely continuous operators (cf. 11.3 in [4] or Chapter VIII. in [6]).

For the second part of the theorem we have $r>0$ in Proposition 4,1. Using the duality theory for completely continuous operators in normed spaces (see [6], VIII. 2) we know that $(4,16)$ has a solution if and only if $f(\tilde{x})=0$ for any functional $f \in \boldsymbol{T}^{*-1}(0)=\left\{f \in X^{\prime} ; f-K^{*} f=0\right\}\left(K^{*}\right.$ is the adjoint operator to $\left.\boldsymbol{K}\right)$. From $(4,5)$ we have $T^{*-1}(0) \subset[Y]$ and $(4,3)$ implies $K^{*}[y]=[L y]$ for any $[y] \in[Y]$. Hence $(4,16)$ has a solution if and only if $[y](\tilde{x})=\langle\tilde{x}, y\rangle=0$ for any $[y]$ from the set

$$
\begin{aligned}
& \left\{[y] \in[Y] ;[y]-K^{*}[y]=[y-L y]=0\right\}= \\
& \quad=[\{y \in Y ; S y=y-L y=0\}]=\left[S^{-1}(0)\right]
\end{aligned}
$$

Further evidently $[y] \in\left[S^{-1}(0)\right]$ if and only if $y$ is a solution of $(4,19)$ and we obtain in this way the result of the second part of the Theorem for Eq. $(4,16)$. The result for Eq. $(4,18)$ can be derived similarly.

Remark 4,1. The following statement is an easy consequence of Theorem 4,1: If $(4,20)$ for all solutions of $(4,19)$ is satisfied then the general solution $x \in X$ of $(4,16)$ is written as

$$
x=\hat{x}+\sum_{l=1}^{r} c_{l} x_{l}
$$

where $\hat{x}$ is a particular solution of $(4,18), x_{1}, \ldots, x_{r}$ are the linearly independent solutions of $(4,17)$ (the base of $\left.T^{-1}(0)\right)$ and $c_{1}, \ldots, c_{r}$ are arbitrary constants. A similar statement for the general solution of $(4,18)$ also holds.

## 5. ALTERNATIVE FOR FREDHOLM-STIELTJES INTEGRAL EQUATIONS IN $\boldsymbol{V}_{\boldsymbol{n}}$

We denote by $S_{n}$ the set of all break functions $\mathbf{w}$ in the Banach space space $V_{n}=$ $=V_{n}(0,1)$ such that $\Delta w(t)=w(t+)-w(t-)=0$ for all $t \in(0,1), \Delta^{+} w(0)=$ $=\Delta^{-} w(1)=0$. Obviously $S_{n}$ is a linear set in $V_{n}$. The set $S_{n}$ is closed in $V_{n}$. In fact, if $\mathbf{w} \in V_{n}$ is an adherent point of $S_{n}$ then there exists a sequence $\mathbf{w}_{l} \in S_{n}, l=1,2, \ldots$ such that $\lim _{l \rightarrow \infty}\left\|\boldsymbol{w}_{l}-w\right\|_{V_{n}}=0$. For any $t \in(0,1)$ and $l=1,2, \ldots$ we have

$$
\|\Delta \mathbf{w}(t)\|=\left\|\Delta \mathbf{w}(t)-\Delta \mathbf{w}_{l}(t)\right\| \leqq\left\|\mathbf{w}_{l}-\mathbf{w}\right\|_{V_{n}}
$$

thus $\Delta w(t)=0$. Similarly $\Delta^{+} w(0)=\Delta^{-} w(1)=0$.
The convergence in $V_{n}$ implies that $w_{l}$ converges uniformly on $\langle 0,1\rangle$ to $w$. Let $A \subset\langle 0,1\rangle$ be the union of all discontinuity points of $\mathbf{w}_{l}, l=1,2, \ldots$ and $\mathbf{w} ; A$ is a countable set. Any $\boldsymbol{w}_{l}$ is a constant function in $\langle 0,1\rangle-A$. The uniform convergence implies that $\mathbf{w}$ is a constant function in $\langle 0,1\rangle-A$ and hence we have $\boldsymbol{w} \in S_{n}$.

Let us consider the quotient space $V_{n} / S_{n}$. An element of $V_{n} / S_{n}$ is a class of functions in $V_{n}$ such that their difference belongs to $S_{n}$. Elements of $V_{n} / S_{n}$ let be denoted by capitals. The canonical mapping of $V_{n}$ onto $V_{n} / S_{n}$ let be denoted by $\varkappa$; for $\varphi \in V_{n}$ we have $x(\varphi)=\varphi+S_{n}=\Phi \in V_{n} / S_{n}$. Any element $\varphi \in V_{n}$ for which $\chi(\varphi)=\Phi$ will be called a representant of the class $\Phi \in V_{n} / S_{n}$.

The space $V_{n} / S_{n}$ forms a Banach space with the norm

$$
\begin{equation*}
\|\Phi\|_{V_{n} / S_{n}}=\inf _{\varphi \in \phi}\|\varphi\|_{V_{n}}=\inf _{x(\varphi)=\phi}\|\varphi\|_{V_{n}}=\inf _{\varphi \in \phi} \operatorname{var}_{0}^{1} \varphi . \tag{5,1}
\end{equation*}
$$

We have evidently

$$
\begin{equation*}
\|\Phi\|_{V_{n} / S_{n}} \leqq \operatorname{var}_{0}^{1} \varphi \tag{5,2}
\end{equation*}
$$

for all $\varphi \in V_{n}, \chi(\varphi)=\Phi$.
Theorem 5,1. If $K(s, t): I=\langle 0,1\rangle \times\langle 0,1\rangle \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfies $v(K)<+\infty$, $\operatorname{var}_{0}^{1} K(0,)<.+\infty, \operatorname{var}_{0}^{1} K(., 0)<+\infty$ then the expression

$$
\begin{equation*}
L \Phi=\varkappa\left(\int_{0}^{1} K^{\prime}(s, t) \mathrm{d} \varphi(s)\right), \quad \varphi \in V_{n}, \quad \chi(\varphi)=\Phi \tag{5,3}
\end{equation*}
$$

defines a completely continuous linear operator on the Banach space $V_{n} / S_{n}$.

Proof．Let $B\left(V_{n} / S_{n}\right)=\left\{\Phi \in V_{n} / S_{n} ;\|\Phi\|_{V_{n} / S_{n}} \leqq 1\right\}$ be the unit ball in $V_{n} / S_{n}$ ．Let

$$
. A=\left\{\Phi \in V_{n} / S_{n} ; \Phi=\chi(\varphi), \varphi \in V_{n}, \varphi(0)=0, \operatorname{var}_{0}^{1} \varphi \leqq 1\right\} ;
$$

according to $(5,2)$ it is $B\left(V_{n} \mid S_{n}\right) \subset A$ ．Let $\Phi_{l} \in B\left(V_{n} \mid S_{n}\right), l=1,2, \ldots$ then there exist $\varphi_{l} \in V_{n}$ with $\operatorname{var}_{0}^{1} \varphi_{l} \leqq 1, \varphi_{l}(0)=0, l=1,2, \ldots$ such that $\chi\left(\varphi_{l}\right)=\Phi_{l}$ ．The matrix $K^{\prime}(s, t): I \rightarrow L\left(R^{n} \rightarrow R^{n}\right)$ satisfies evidently all conditions of Theorem 3,2 hence the operator $\int_{0}^{1} K^{\prime}(s, t) \mathrm{d} \varphi(s)$ is completely continuous in $V_{n}$ ．This implies that there exist $\mathbf{z} \in V_{n}$ and a subsequence $\varphi_{I_{j}}, j=1,2, \ldots$ such that

$$
\lim _{j \rightarrow \infty}\left\|\int_{0}^{1} \boldsymbol{K}^{\prime}(s, t) \mathrm{d} \varphi_{l_{j}}(s)-\mathbf{z}(t)\right\|_{V_{n}}=0
$$

i．e．

$$
\lim _{j \rightarrow \infty} \operatorname{var}_{0}^{1}\left(\int_{0}^{1} K^{\prime}(s, t) \mathrm{d} \varphi_{l^{\prime}}(s)-\mathbf{z}(t)\right)=0
$$

From（5，2）we have

$$
\lim _{j \rightarrow \infty}\left\|\boldsymbol{L} \boldsymbol{\Phi}_{l_{j}}-\chi(\mathbf{z})\right\|_{\boldsymbol{V}_{n} / s_{n}} \leqq \lim _{j \rightarrow \infty} \operatorname{var}_{0}^{1}\left(\int_{0}^{1} \boldsymbol{K}^{\prime}(s, t) \mathrm{d} \boldsymbol{\varphi}_{l_{j}}(s)-\mathbf{z}(t)\right)=0
$$

and in this way we obtain the complete continuity of $L: V_{n} / S_{n} \rightarrow V_{n} / S_{n}$ ．
Let further $\mathbf{x} \in V_{n}, \Phi \in V_{n} / S_{n}$ ．We denote

$$
\begin{equation*}
\langle\boldsymbol{x}, \Phi\rangle=\langle\boldsymbol{x}, \boldsymbol{\varphi}\rangle_{(0,1)}=\int_{0}^{1} \mathbf{x}^{\prime}(t) \mathrm{d} \varphi(t) \tag{5,4}
\end{equation*}
$$

where $\varphi \in V_{n}, \chi(\varphi)=\Phi$ ．The expression $\langle\boldsymbol{x}, \boldsymbol{\Phi}\rangle$ is independent of the choice of the representant $\varphi$ of the class $\boldsymbol{\Phi}$ ．Indeed，if we have $\varphi^{\circ} \in V_{n}, \chi\left(\varphi^{\circ}\right)=\boldsymbol{\Phi}$ then（cf．Remark 2，2）

$$
\left\langle x, \varphi-\varphi^{\circ}\right\rangle_{(0,1)}=\int_{0}^{1} x^{\prime}(t) \mathrm{d}\left(\varphi(t)-\varphi^{\circ}(t)\right)=0
$$

because $\varphi-\varphi^{\circ} \in S_{n}$ ．The expression $\left\langle.\right.$, ．〉 from $(5,4)$ is a bilinear form on $V_{n} \times$ $\times V_{n} / S_{n}$ and the following lemma holds：

Lemma 5，1．The bilinear form 〈．，．〉 from（5，4）separates points of $V_{n}$ and $V_{n} / S_{n}$ （cf．（i）and（ii）in Section 4．）．

Proof．（i）Let $\dot{x} \in V_{n}, \mathbf{x} \neq 0$ ．Then there exists $\alpha \in\langle 0,1\rangle$ such that $\mathbf{x}(\alpha) \neq 0$ ， i．e．there is an index $i=1, \ldots, n$ such that $x_{i}(\alpha) \neq 0$ ．We define $\varphi(t) \in V_{n}$ as follows： $\varphi_{k}(t)=0$ for $t \in\langle 0,1\rangle, k \neq i, \varphi_{i}(t)=0$ for $0 \leqq t<\alpha, \varphi_{i}(t)=1$ for $\alpha \leqq t \leqq 1$ provided $\alpha>0$ ；if $\alpha=0$ then we set $\varphi_{i}(0)=1, \varphi_{i}(t)=0,0<t \leqq 1$ ．Let us put $\boldsymbol{\Phi}=x(\boldsymbol{\varphi})$ ．Then Proposition 2，1 yields $\langle\boldsymbol{x}, \boldsymbol{\Phi}\rangle=\int_{0}^{1} x_{i}(t) \mathrm{d} \varphi_{i}(t)=x_{i}(\alpha) \neq 0$ in the case $\alpha>0$ and similarly $\langle\mathbf{x}, \Phi\rangle=-x_{i}(0) \neq 0$ if $\alpha=0$ ．Hence $\langle.,$.$\rangle separates$ points of $V_{n}$ ．
(ii) Let $\Phi \neq 0$ (i.e. $\Phi \neq S_{n}$ ). For any $\varphi \in V_{n}, x(\varphi)=\Phi$ it holds either

1) there exists an $\alpha \in(0,1)$ such that $\varphi_{i}(\alpha+) \neq \varphi_{i}(\alpha-)$ for some $i=1,2, \ldots, n$ or
2) for each $\alpha \in(0,1)$ it is $\varphi(\alpha+)=\varphi(\alpha-)$ and there exist two points $\beta, \gamma \in\langle 0,1\rangle$, $\beta<\gamma$ such that $\varphi_{i}(\beta) \neq \varphi_{i}(\gamma)$ for some $i=1, \ldots, n$ where $\beta, \gamma$ are points of continuity of $\varphi_{i}(t)$, i.e. $\varphi_{i}(\beta)=\varphi_{i}(\beta-), \varphi_{i}(\gamma)=\varphi_{i}(\gamma-)$.

In the case 1) we set $x_{i}(t)=0$ for $t \in\langle 0,1\rangle, t \neq \alpha, x_{i}(\alpha)=1, x_{j}(t)=0$ for $t \in\langle 0,1\rangle$ if $j \neq i$. Then Corollary 2,1 yields

$$
\langle\mathbf{x}, \Phi\rangle=\int_{0}^{1} x_{i}(t) \mathrm{d} \varphi_{i}(t)=\varphi_{i}(\alpha+)-\varphi_{i}(\alpha-) \neq 0 .
$$

In the case 2) it suffices to set $x_{i}(t)=1$ for $t \in\langle\beta, \gamma\rangle, x_{i}(t)=0$ for $t \in\langle 0,1\rangle-$ $-\langle\beta, \gamma\rangle, x_{j}(t)=0$ for $t \in\langle 0,1\rangle, j \neq i$. Then we obtain from Proposition 2,1

$$
\langle\boldsymbol{x}, \Phi\rangle=\int_{0}^{1} x_{i}(t) \mathrm{d} \varphi_{i}(t)=\varphi_{i}(\gamma)-\varphi_{i}(\beta) \neq 0
$$

Hence $\langle.$, . $\rangle$ separates points of $V_{n} \mid S_{n}$.
Remark 5,1 . Since the bilinear form $\langle.,$.$\rangle separates points of V_{n} / S_{n}$ we can subjoin the following addition to Corollary 2,2: If $g \in V(a, b)$ and $\int_{a}^{b} f(t) \mathrm{d} g(t)=0$ for all $f \in V(a, b)$ then necessarily $g \in S(a, b)$, i.e. $\Delta g(t)=0$ for all $t \in(a, b), \Delta^{+} g(a)=$ $=\Delta^{-} g(b)=0$. This means that if $g \in V(a, b)$ then $\int_{a}^{b} f(t) \mathrm{d} g(t)=0$ for every $f \in$ $\in V(a, b)$ if and only if $g \in S(a, b)$.

Since $\langle\boldsymbol{x}, \boldsymbol{\Phi}\rangle$ from (5,4) is independent of the choice of $\varphi \in V_{n}, x(\varphi)=\boldsymbol{\Phi}$ and

$$
\left|\int_{0}^{1} \mathbf{x}^{\prime}(t) \mathrm{d} \varphi(t)\right| \leqq \sup _{t \in\langle 0,1\rangle}\left\|\mathbf{x}^{\prime}(t)\right\| \operatorname{var}_{0}^{1} \varphi \leqq n\|\mathbf{x}\|_{V_{n}} \operatorname{var}_{0}^{1} \varphi
$$

holds we have

$$
\begin{equation*}
|\langle\boldsymbol{x}, \boldsymbol{\Phi}\rangle| \leqq n\|\boldsymbol{x}\|_{V_{n}} \inf _{x(\varphi)=\phi} \operatorname{var}_{0}^{1} \varphi=n\|\mathbf{x}\|_{V_{n}}\|\boldsymbol{\Phi}\|_{V_{n} / S_{n}} \tag{5,5}
\end{equation*}
$$

Theorem 5,2. Let $K(s, t): I=\langle 0,1\rangle \times\langle 0,1\rangle \rightarrow L\left(R^{n} \rightarrow R^{n}\right), v(K)<+\infty$, $\operatorname{var}_{0}^{1} \boldsymbol{K}(0,)<.+\infty, \operatorname{var}_{0}^{1} \boldsymbol{K}(., 0)<+\infty$.

Then either the Fredholm-Stieltjes integral equation

$$
\begin{equation*}
\mathbf{x}(s)-\int_{0}^{1} \mathrm{~d}_{t}[\boldsymbol{K}(s, t)] \mathbf{x}(t)=\mathbf{x}^{\circ}(s), \quad \mathbf{x}^{\circ} \in V_{n} \tag{5,6}
\end{equation*}
$$

admits a unique solution for any $\mathbf{x}^{\circ} \in V_{n}$ or the homogeneous equation

$$
\begin{equation*}
x(s)-\int_{0}^{1} d_{t}[K(s, t)] x(t)=0 \tag{5,7}
\end{equation*}
$$

admits $r$ linearly independent solutions $\mathbf{x}_{1}, \ldots, \mathbf{x}_{r} \in V_{n}$.

In the first case the equation

$$
\begin{equation*}
\varphi(t)-\int_{0}^{1} K^{\prime}(s, t) \mathrm{d} \varphi(s)=\varphi^{\circ}(t), \quad \varphi^{\circ} \in V_{n} \tag{5,8}
\end{equation*}
$$

has a solution for any $\varphi^{\circ} \in V_{n}$ (this solution is not necessarily unique). In the second case the equation $(5,6)$ has a solution in $V_{n}$ if and only if

$$
\begin{equation*}
\left\langle\mathbf{x}^{\circ}, \varphi\right\rangle_{(0,1)}=\int_{0}^{1} \mathbf{x}^{\prime}(t) \mathrm{d} \varphi(t)=0 \tag{5,9}
\end{equation*}
$$

for any solution $\varphi \in V_{n}$ of the equation

$$
\begin{equation*}
\varphi(t)-\int_{0}^{1} K^{\prime}(s, t) \mathrm{d} \varphi(s)=0 \tag{5,10}
\end{equation*}
$$

and symmetrically $(5,8)$ has a solution if and only if

$$
\begin{equation*}
\left\langle\boldsymbol{x}, \varphi^{\circ}\right\rangle_{(0,1)}=\int_{0}^{1} \boldsymbol{x}^{\prime}(t) \mathrm{d} \varphi^{\circ}(t)=0 \tag{5,11}
\end{equation*}
$$

for any solution $\mathrm{x} \in V_{n}$ of the equation $(5,7)$.
Proof. By Theorems 3,1 and 5,1 the operators

$$
\begin{gathered}
K \mathbf{x}=\int_{0}^{1} \mathrm{~d}_{t}[K(s, t)] \mathbf{x}(t): V_{n} \rightarrow V_{n}, \quad \chi(\varphi)=\Phi, \\
\boldsymbol{L} \boldsymbol{\Phi}=\varkappa\left(\int_{0}^{1} K^{\prime}(s, t) \mathrm{d} \varphi(s)\right): V_{n} / S_{n} \rightarrow V_{n} / S_{n}
\end{gathered}
$$

are completely continuous. $\langle.,$.$\rangle from (5,4) represents a bilinear form on V_{n} \times V_{n} / S_{n}$ which separates points of $V_{n}$ and $V_{n} / S_{n}$ (cf. Lemma 5,1 ) and $(5,5)$ holds.

Further by $(2,28)$ we have

$$
\begin{gathered}
\langle\boldsymbol{K x}, \boldsymbol{\Phi}\rangle=\langle\boldsymbol{K} \boldsymbol{x}, \boldsymbol{\varphi}\rangle_{(0,1)}=\left\langle\int_{0}^{1} \mathrm{~d}_{t}[\boldsymbol{K}(., t)] \mathrm{d} \mathbf{x}(t), \boldsymbol{\varphi}\right\rangle_{(0,1)}= \\
=\left\langle\mathbf{x}, \int_{0}^{1} \boldsymbol{K}^{\prime}(s, .) \mathrm{d} \boldsymbol{\varphi}(s)\right\rangle_{(0,1)}=\left\langle\mathbf{x}, \varkappa\left(\int_{0}^{1} \boldsymbol{K}^{\prime}(s, .) \mathrm{d} \boldsymbol{\varphi}(s)\right)\right\rangle=\langle\mathbf{x}, \boldsymbol{L} \boldsymbol{\Phi}\rangle
\end{gathered}
$$

for any $\mathbf{x} \in V_{n}, \Phi \in V_{n} / S_{n}$. All assumptions of Theorem 4,1 are satisfied and using this Theorem we obtain the first part of Theorem $5,2 \mathrm{viz}$. (the alternative for Eq. $(5,6)$ resp. (5,7)). Further by Theorem 4,1 the equation

$$
\begin{equation*}
\Phi-L \Phi=\Phi^{\circ}, \quad \Phi^{\circ} \in V_{n} / S_{n} \tag{5,12}
\end{equation*}
$$

has a unique solution for any $\Phi^{\circ} \in V_{n} / S_{n}$. For an arbitrary $\varphi^{\circ} \in V_{n}$ we denote $\Phi^{\circ}=$ $=x\left(\varphi^{\circ}\right) \in V_{n} / S_{n}$. Let $\varphi \in V_{n}$ be a representant of the (unique) solution of $(5,12)$ with this $\Phi^{\circ}$. Then we have

$$
\varkappa\left(\varphi-\int_{0}^{1} K^{\prime}(s, .) \mathrm{d} \varphi(s)\right)=\chi\left(\varphi^{\circ}\right),
$$

i.e.

$$
\left.\varkappa\left(\varphi-\int_{0}^{1} K^{\prime}(s, .) \mathrm{d} \varphi(s)-\varphi^{\circ}\right)\right)=0 \in V_{n} \mid S_{n} .
$$

Hence

$$
\varphi(t)-\int_{0}^{1} K^{\prime}(s, t) \mathrm{d} \varphi(s)-\varphi^{\circ}(t)=w(t) \in S_{n}
$$

for all $t \in\langle 0,1\rangle$. Since $\int_{0}^{1} \boldsymbol{K}^{\prime}(s, t) \mathrm{d} \varphi(s)=\int_{0}^{1} \boldsymbol{K}^{\prime}(s, t) \mathrm{d}(\varphi(s)-\boldsymbol{w}(s))$ we have

$$
\varphi(t)-w(t)-\int_{0}^{1} K^{\prime}(s, t) \mathrm{d}(\varphi(s)-w(s))=\varphi^{\circ}(t)
$$

for all $t \in\langle 0,1\rangle$, i.e. the function $\varphi-\mathbf{w} \in V_{n}$ is a solution of Eq. $(5,8)$. (The unicity of $\boldsymbol{w} \in S_{n}$ is not quaranteed.)

For the second case we know by Theorem 4,1 that (5,6 has a solution if and only if for any solution $\Phi \in V_{n} / S_{n}$ of the equation

$$
\begin{equation*}
\Phi-L \Phi=0 \tag{5,13}
\end{equation*}
$$

we have $\left\langle\mathbf{x}^{\circ}, \boldsymbol{\Phi}\right\rangle=0$.
Obviously the following assertion holds: for any solution $\Phi \in V_{n} / S_{n}$ of Eq. $(5,13)$ there is a $\varphi \in V_{n}, \chi(\varphi)=\Phi$ such that $\varphi$ is a solution of $(5,10)$. In fact, for any representant $\psi \in V_{n}$ of $\Phi(\varkappa(\psi)=\Phi)$ we have

$$
\begin{gathered}
x\left(\psi-\int_{0}^{1} K^{\prime}(s, .) \mathrm{d} \psi(s)\right)=0 \in V_{n} / S_{n}, \text { i.e. } \\
\psi(t)-\int_{0}^{1} K^{\prime}(s, t) \mathrm{d} \psi(s)=w(t) \in S_{n}
\end{gathered}
$$

If we set $\varphi=\psi-\mathbf{w}$, then $x(\varphi)=\chi(\psi)=\boldsymbol{\Phi}$ and $\varphi$ is a solution of $(5,10)$. It is easy to prove also the converse statement: If $\varphi \in V_{n}$ is a solution of $(5,10)$, then $\Phi=\varkappa(\varphi)$ is a solution of $(5,13)$.

Since $\langle\boldsymbol{x}, \boldsymbol{\Phi}\rangle=\langle\boldsymbol{x}, \boldsymbol{\varphi}\rangle_{(0,1)}$ is independent of the choice of the representant $\varphi \in V_{n}, \chi(\varphi)=\Phi$, we conclude that in the second case $(5,6)$ has a solution if and only if $\left\langle\mathbf{x}^{\circ}, \varphi\right\rangle_{(0,1)}=\int_{0}^{1} \mathbf{x}^{\circ}(t) \mathrm{d} \varphi(t)=0$ for all solutions of Eq. $(5,10)$. The symmetrical statement about Eq. $(5,8)$ can be proved similarly.

Remark 5,2. Theorem 5,2 is a Fredholm type theorem for Fredholm-Stieltjes integral equations $(5,6)$. Let us mention that Eq. $(5,8)$ as well as the equation $\boldsymbol{\Phi}$ -$-\boldsymbol{L} \boldsymbol{\Phi}=\boldsymbol{\Phi}_{0}^{\circ}$ are not the adjoint equations to $(5,6)$ in the usual sense. We have not a satisfactory description of the dual space $V_{n}^{\prime}$ to $V_{n}$ which would make it possible to derive the analytic form of the adjoint operator $\boldsymbol{K}^{*}$. Nevertheless conditions for solvability of Eq. $(5,6)$ are obtained in a form which is closely related to the well known Fredholm alternative for Fredholm integral equations of the second kind in $L_{2}$ - spaces.

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