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TWO APPLICATIONS OF AN INTEGRAL FORMULA

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We are going to present two consequences of a general integral formula presented in [1].

1. Harmonic mappings of Riemannian manifolds

Be given a Riemannian manifold (M, ds^2) , $\dim M = m$. In a suitable domain $U \subset M$, let us write $(i, j, \dots = 1, \dots, m)$

$$ds^2 = \sum_i (\omega^i)^2, \quad (1.1)$$

ω^i being linearly independent 1-forms on U . Then there are on U 1-forms ω_i^j such that

$$d\omega^i = \sum_j \omega^j \wedge \omega_i^j, \quad \omega_i^i + \omega_i^i = 0; \quad (1.2)$$

the forms ω_i^j are uniquely determined by (1.2). The components of the curvature tensor be introduced by

$$d\omega_i^j = \sum_k \omega_k^j \wedge \omega_k^i - \frac{1}{2} R_{ikl}^j \omega^k \wedge \omega^l, \quad R_{ikl}^j + R_{ilk}^j = 0; \quad (1.3)$$

they satisfy the symmetry relations

$$R_{ikl}^j + R_{jkl}^i = 0, \quad R_{ikl}^j = R_{kij}^l, \quad R_{ikl}^j + R_{ilj}^k + R_{ijl}^k = 0. \quad (1.4)$$

Let v_1, \dots, v_m be the field of orthonormal frames on U dual to the field of coframes $\omega^1, \dots, \omega^m$. Denote by $K(v_i, v_j)$, $i \neq j$, the sectional curvature of the 2-plane $\{v_i, v_j\}$; of course, $K(v_i, v_j) = R_{ijj}^i$.

Further, be given another Riemannian manifold $(N, d\sigma^2)$, $\dim N = n$, and a mapping $f: M \rightarrow N$. Consider a neighbourhood $V \subset N$ such that $f(U) \subset V$ and there are 1-forms φ^α ($\alpha, \beta, \dots = 1, \dots, n$) satisfying

$$d\sigma^2 = \sum_\alpha (\varphi^\alpha)^2. \quad (1.5)$$

Let

$$\tau^\alpha = f^* \varphi^\alpha = \sum_i A_i^\alpha \omega^i, \quad \tau_\alpha^\beta = f^* \varphi_\alpha^\beta. \quad (1.6)$$

The exterior differentiation of (1.6₁) yields

$$\sum_i (dA_i^\alpha - \sum_j A_j^\alpha \omega_i^j + \sum_\beta A_i^\beta \tau_\beta^\alpha) \wedge \omega^i = 0, \quad (1.7)$$

and, according to E. Cartan's lemma, we get the existence of functions A_{ij}^α on U satisfying

$$dA_i^\alpha - \sum_j A_j^\alpha \omega_i^j + \sum_\beta A_i^\beta \tau_\beta^\alpha = \sum_j A_{ij}^\alpha \omega^j, \quad A_{ij}^\alpha = A_{ji}^\alpha. \quad (1.8)$$

A further exterior differentiation implies

$$\begin{aligned} \sum_j (dA_{ij}^\alpha - \sum_k A_{ik}^\alpha \omega_j^k - \sum_k A_{kj}^\alpha \omega_i^k + \sum_\beta A_{ij}^\beta \tau_\beta^\alpha) \wedge \omega^j = \\ = \frac{1}{2} \sum_{j,k} (\sum_l A_l^\alpha R_{ljk}^i - \sum_{\beta,\gamma,\delta} A_l^\beta A_j^\gamma A_k^\delta S_{\beta\gamma\delta}^\alpha) \omega^j \wedge \omega^k, \end{aligned} \quad (1.9)$$

$S_{\beta\gamma\delta}^\alpha$ being the components of the curvature tensor of $(N, d\sigma^2)$. Thus there are functions A_{ijk}^α such that

$$dA_{ij}^\alpha - \sum_k A_{ik}^\alpha \omega_j^k - \sum_k A_{kj}^\alpha \omega_i^k + \sum_\beta A_{ij}^\beta \tau_\beta^\alpha = \sum_k A_{ijk}^\alpha \omega^k, \quad A_{ijk}^\alpha = A_{jik}^\alpha, \quad (1.10)$$

$$A_{ijk}^\alpha - A_{ikj}^\alpha = \sum_l A_l^\alpha R_{likj}^i - \sum_{\beta,\gamma,\delta} A_l^\beta A_k^\gamma A_j^\delta S_{\beta\gamma\delta}^\alpha. \quad (1.11)$$

Let us consider on U the 1-forms

$$\varphi_1 = \sum_{\alpha,i,j} A_i^\alpha A_{ij}^\alpha \omega^j, \quad \varphi_2 = \sum_{\alpha,i,j} A_j^\alpha A_{ii}^\alpha \omega^j. \quad (1.12)$$

It is easy to see that the forms (1.12) are globally defined over all of M . The usual $*$ -operator be defined by

$$*\omega^i = (-1)^{i+1} \omega^1 \wedge \dots \wedge \omega^{i-1} \wedge \omega^{i+1} \wedge \dots \wedge \omega^n, \quad (1.13)$$

$$\text{i.e., } d\omega := \omega^1 \wedge \dots \wedge \omega^n = \omega^i \wedge *\omega^i.$$

Now,

$$d*\varphi_1 = \sum_{\alpha,i,j} \{(A_{ij}^\alpha)^2 + A_i^\alpha A_{jj}^\alpha\} d\omega, \quad (1.14)$$

$$d*\varphi_2 = \sum_{\alpha,i,j} (A_{ii}^\alpha A_{jj}^\alpha + A_i^\alpha A_{jj}^\alpha) d\omega,$$

and, according to (1.11),

$$d*(\varphi_1 - \varphi_2) = \sum_{\alpha,i,j} \{(A_{ij}^\alpha)^2 - A_{ii}^\alpha A_{jj}^\alpha + \sum_k A_i^\alpha A_k^\alpha R_{kji}^i - \sum_{\beta,\gamma,\delta} A_j^\beta A_i^\gamma A_j^\delta S_{\beta\gamma\delta}^\alpha\} d\omega. \quad (1.15)$$

Let us turn our attention to the geometrical interpretation of the above introduced invariants. Let $p \in U \subset M$ be a given point. The Euclidean connection on M or N resp. is given by

$$\begin{aligned} \nabla m = \sum_i \omega^i v_i, \quad \nabla v_i = \sum_j \omega_j^i v_j \quad \text{or} \\ \nabla^* n = \sum_\alpha \varphi^\alpha w_\alpha, \quad \nabla^* w_\alpha = \sum_\beta \varphi_\alpha^\beta w_\beta \quad \text{resp.;} \end{aligned} \quad (1.16)$$

here, w_1, \dots, w_n is the dual basis to $\varphi^1, \dots, \varphi^n$. Evidently,

$$df_p(v_i) = A_i^\alpha w_\alpha. \quad (1.17)$$

Let $v \in T_p(M)$ be a non-zero vector. Choose a curve $\gamma : (-\varepsilon, \varepsilon) \rightarrow M$ such that $\gamma(0) = p$; let s be its arc and v its tangent vector at p . Denote by $\gamma^* = f \circ \gamma : (-\varepsilon, \varepsilon) \rightarrow N$ the corresponding curve. Then it is easy to see that

$$\frac{\nabla^* n}{ds^2} - df_p \left(\frac{\nabla^2 m}{ds^2} \right) = \frac{L(v)}{|v|^2}, \quad (1.18)$$

where $|v|^2 = \sum_i (\omega^i(v))^2$ and

$$L(v) = A_{ij}^\alpha(p) \omega^i(v) \omega^j(v) w_\alpha(f(p)). \quad (1.19)$$

This gives the geometrical interpretation of the quadratic mapping

$$L : T_p(M) \rightarrow T_{f(p)}(N). \quad (1.20)$$

Let $L(\cdot, \cdot)$ be the corresponding bilinear mapping.

At p , let us choose an orthonormal frame v_i , let w_α be an orthonormal frame at $f(p)$. Then

$$L(v_i, v_j) = A_{ij}^\alpha w_\alpha \quad (1.21)$$

and the expressions

$$\sum_{i,j} |L(v_i, v_j)|^2 = \sum_{i,j,\alpha} (A_{ij}^\alpha)^2, \quad \left| \sum_i L(v_i) \right|^2 = \sum_{\alpha,i,j} A_{ii}^\alpha A_{jj}^\alpha \quad (1.22)$$

do not depend on the choice of the frames v_i and w_α . In the same way, the vector

$$t = \sum_i L(v_i) \quad (1.23)$$

is invariant; the mapping

$$t : M \rightarrow T(N), \quad t(p) \in T_{f(p)}(N) \quad (1.24)$$

is the so-called tension field. The mapping $f : M \rightarrow N$ is said to be harmonic if $t = 0$ for each $p \in M$.

The frames (v_1, \dots, v_m) and (w_1, \dots, w_n) at p and $f(p)$ resp. are called adapted to f if

$$\begin{aligned} df_p(v_i) &= A_i w_i && \text{for } i = 1, \dots, m \text{ in the case } m \leq n \text{ and} \\ df_p(v_\alpha) &= A_\alpha w_\alpha && \text{for } \alpha = 1, \dots, n, \\ df_p(v_\varrho) &= 0 && \text{for } \varrho = n + 1, \dots, m \text{ in the case } m > n. \end{aligned} \quad (1.25)$$

Thus, we may always write (25₁) setting $w_i = 0$ for $i > n$. The adapted bases exist for each couple $(p, f(p))$. In the adapted bases, we have

$$\sum_{\alpha,i,j} \sum_k A_i^\alpha A_k^\alpha R_{jji}^k = \sum_i (A_i)^2 \sum_{j \neq i} K(v_j, v_i), \quad (1.26)$$

$$\sum_{\alpha,i,j} \sum_{\beta,\gamma,\delta} A_j^\alpha A_i^\beta A_i^\gamma A_j^\delta S_{\beta\gamma\delta}^\alpha = 2 \sum_{i \neq j} (A_i A_j)^2 K^*(w_i, w_j). \quad (1.27)$$

Further,

$$\varphi_1(v_i) = \sum_j \langle df(v_j), L(v_i, v_j) \rangle, \quad \varphi_2(v_i) = \langle df(v_i), t \rangle, \quad (1.28)$$

\langle, \rangle being the scalar product in $T_{f(p)}(N)$.

Choosing for each couple $(p, f(p))$ the adapted bases, we have the integral formula

$$\begin{aligned} \int_{\partial M} * (\varphi_1 - \varphi_2) &= \int_M \left\{ \sum_{i,j} |L(v_i, v_j)|^2 - |t|^2 + \right. \\ &+ \sum_i (A_i)^2 \sum_{j \neq i} K(v_j, v_i) - 2 \sum_{i \neq j} (A_i A_j)^2 K^*(w_i, w_j) \left. \right\} dv. \end{aligned} \quad (1.29)$$

Thus we get the following

Theorem. Let M, N be Riemannian manifolds and $f: M \rightarrow N$ a harmonic mapping. Let N have non-positive sectional curvatures and let M have, at each point $p \in M$ and for each unit vector $v \in T_p(M)$ the following property: v_1, \dots, v_{m-1}, v being an orthonormal basis of $T_p(M)$, we have $\sum_{r=1, \dots, m-1} K(v, v_r) > 0$. Let $\varphi_1 = \varphi_2$ on the boundary ∂M of M . Then f is a constant mapping.

2. Holomorphic curves in the Hermitian plane

Be given a Hermitian plane H^2 and let $m: D \rightarrow H^2$ be a holomorphic curve, $D \subset \mathcal{C}$ being a bounded domain. To each its point $m(d)$, $d \in D$, let us associate an orthonormal frame $\{m, w_1, w_2\}$. Then we have the equations

$$\begin{aligned} dm &= \tau^1 w_1 + \tau^2 w_2, \\ dw_1 &= \tau_1^1 w_1 + \tau_1^2 w_2, \quad dw_2 = \tau_2^1 w_1 + \tau_2^2 w_2; \end{aligned} \quad (2.1)$$

clearly $(i, j, \dots = 1, 2)$

$$\tau_i^j + \bar{\tau}_j^i = 0, \quad (2.2)$$

$$d\tau^i = \tau^j \wedge \tau_j^i, \quad d\tau_i^j = \tau_i^k \wedge \tau_k^j. \quad (2.3)$$

Let us restrict ourselves to the tangent frames satisfying

$$\tau^2 = 0. \quad (2.4)$$

By successive exterior differentiations we get the existence of functions $R, S, T, U: D \rightarrow \mathcal{C}$ such that

$$\tau_1^2 = R\tau^1, \quad (2.5)$$

$$dR + R(\tau_2^2 - 2\tau_1^1) = S\tau^1, \quad (2.6)$$

$$dS + S(\tau_2^2 - 3\tau_1^1) + 3R^2 \bar{R}\bar{\tau}^1 = T\tau^1, \quad (2.7)$$

$$dT + T(\tau_2^2 - 4\tau_1^1) + 10R\bar{R}S\bar{\tau}^1 = U\tau^1. \quad (2.8)$$

Let us consider another field of orthonormal frames

$$u_1 = e^{i\alpha} w_1, \quad u_2 = e^{i\beta} w_2; \quad \alpha, \beta: D \rightarrow \mathcal{R}; \quad (2.9)$$

let us write

$$dm = \varphi^1 u_1, \quad du_1 = \varphi_1^1 u_1 + \varphi_1^2 u_2, \quad du_2 = \varphi_2^1 u_1 + \varphi_2^2 u_2. \quad (2.10)$$

Then it is easy to see that

$$\varphi^1 = e^{-i\alpha} \tau^1, \quad (2.11)$$

$$\varphi_1^1 = \tau_1^1 + i d\alpha, \quad \varphi_2^2 = \tau_2^2 + i d\beta, \quad \varphi_1^2 = e^{i(\alpha-\beta)} \tau_1^2. \quad (2.12)$$

Write

$$\varphi_1^2 = R' \varphi_1, \quad (2.13)$$

$$dR' + R'(\varphi_2^2 - 2\varphi_1^1) = S' \varphi^1, \quad (2.14)$$

$$dS' + S'(\varphi_2^2 - 3\varphi_1^1) + 3R'^2 \bar{R}' \bar{\varphi}^1 = T' \varphi^1, \quad (2.15)$$

$$dT' + T'(\varphi_2^2 - 4\varphi_1^1) + 10R' \bar{R}' S' \bar{\varphi}^1 = U' \varphi^1. \quad (2.16)$$

Then

$$\begin{aligned} R' &= e^{i(2\alpha-\beta)} R, & S' &= e^{i(3\alpha-\beta)} S, \\ T' &= e^{i(4\alpha-\beta)} T, & U' &= e^{i(5\alpha-\beta)} U. \end{aligned} \quad (2.17)$$

The mappings $B^{(k)}: T_m \rightarrow N_m$ be introduced by

$$\begin{aligned} B(zw_1) &= z^2 R w_2, & B^{(1)}(zw_1) &= z^3 S w_2, \\ B^{(2)}(zw_1) &= z^4 T w_2; & z &\in \mathcal{C}. \end{aligned} \quad (2.18)$$

These mappings are invariant. Indeed: Let $w = zw_1 = z' u_1$, then $z' = e^{-i\alpha} z$ and $z'^2 R' u_2 = z^2 R w_2$; similarly for $B^{(k)}$. Let $S^1 = \{w \in T_m; \langle w, w \rangle = 1\}$, i.e., $S^1 = \{zw_1; |z|^2 = 1\}$. Then $B^{(k)}(S^1)$ is a circle; the radius of $B(S^1)$ is equal to $|R|^{1/2}$, the radius of $B^{(1)}(S^1)$ is equal to $|S|^{1/2}$, etc. The geometrical interpretation of the mappings $B^{(k)}$ will be presented later on.

The area element of m is given by

$$do = \frac{1}{2} i \tau^1 \wedge \bar{\tau}^1. \quad (2.19)$$

The Hodge operator be introduced by

$$\ast \tau^1 = -i \tau^1, \quad \ast \bar{\tau}^1 = i \bar{\tau}^1. \quad (2.20)$$

Let $f: D \rightarrow \mathcal{R}$ be a function. Then its Laplacian Δf is given, as usually, by

$$\Delta f do = d \ast df. \quad (2.21)$$

The straightforward calculations lead to ($n \geq 1$)

$$d |R|^{2n} = 2n |R|^{2n-2} \operatorname{Re}(\bar{R} S \tau^1), \quad (2.22)$$

$$\Delta |R|^{2n} = 4n |R|^{2n-2} (n |S|^2 - 3 |R|^4), \quad (2.23)$$

$$d |S|^{2n} = 2n |S|^{2n-2} \operatorname{Re}\{(\bar{S} T - 3 S R \bar{R}^2) \tau^1\}, \quad (2.24)$$

$$\Delta |S|^{2n} = 4n\{|S|^{2n-2}(n|T|^2 - 16|S|^2|R|^2 + 9n|R|^6) - 6(n-1)|S|^{2n-4}|R|^2\operatorname{Re}(S^2RT)\}. \quad (2.25)$$

Especially,

$$\begin{aligned} \Delta |R|^2 &= 4(|S|^2 - 3|R|^4), \\ \Delta |R|^4 &= 8|R|^2(2|S|^2 - 3|R|^4), \\ \Delta |S|^2 &= 4(|T|^2 - 16|S|^2|R|^2 + 9|R|^6) \end{aligned} \quad (2.26)$$

and

$$\Delta(|S|^2 + 4|R|^4) = 4(|T|^2 - 15|R|^6). \quad (2.27)$$

Lemma. Let $S = 0$ on D . Then $m(D)$ is a part of a straight line of H^2 .

Proof. The equation (2.7) implies $R = 0$. QED.

Theorem. Let $S = 0$ on ∂D and

$$3|R|^4 \geq |S|^2 \quad \text{on } D. \quad (2.28)$$

Then $m(D)$ is a part of a straight line of H^2 .

Proof. Obviously, $\int_{\partial D} |R|^{2n} = 0$ on ∂D . From the integral formula

$$0 = \int_M \Delta |R|^2 \, dv \quad (2.29)$$

we get, because of (2.26),

$$3|R|^4 = |S|^2 \quad \text{on } D. \quad (2.30)$$

The integral formula

$$\int_{\partial M} *d|R|^4 = 8 \int_M |R|^2(2|S|^2 - 3|R|^4) \, dv \quad (2.31)$$

reduces to

$$0 = \int_M |R|^6 \, dv, \quad (2.32)$$

and we get $R = 0$. QED.

The formulas (2.23), (2.25), (2.27) imply new characterizations of straight lines of H^2 . It is sufficient to suppose $S = 0$ on ∂D and, for ex.,

$$14|R|^6 \geq |T|^2 \quad (2.33)$$

or

$$|T|^2 \geq 8|R|^2(2|S|^2 - |R|^4) \quad (2.34)$$

on D ; see (2.27) and (2.26₃).

Now, the geometrical description of the mappings $B^{(k)}$ is given in [1]. To do this, let us consider H^2 as a space over \mathfrak{m} , i.e., H^2 becomes E^4 . Write

$$\begin{aligned} v_1 &= w_1, & v_2 &= iw_1, & v_3 &= w_2, & v_4 &= iw_2, \\ \tau^1 &= \omega^1 + i\omega^2, & \tau^2 &= \omega^3 + i\omega^4, & \tau_1^1 &= \omega_1^3 + i\omega_1^4, \\ & & \tau_1^1 &= i\omega_1^2, & \tau_2^2 &= i\omega_3^4, \end{aligned} \quad (2.35)$$

i.e.,

$$\begin{aligned}
dm &= \omega^1 v_1 + \omega^2 v_2, \\
dv_1 &= \omega_1^2 v_2 + \omega_1^3 v_3 + \omega_1^4 v_4, \\
dv_2 &= -\omega_1^2 v_1 - \omega_1^4 v_3 + \omega_1^3 v_4, \\
dv_3 &= -\omega_1^3 v_1 + \omega_1^4 v_2 + \omega_3^4 v_4, \\
dv_4 &= -\omega_1^4 v_1 - \omega_1^3 v_2 - \omega_3^4 v_3,
\end{aligned} \tag{2.36}$$

and

$$\omega_1^3 = R_1 \omega^1 - R_2 \omega^2, \quad \omega_1^4 = R^2 \omega^1 + R_1 \omega^2 \tag{2.37}$$

with $R_1 = \text{Re } R$, $R_2 = \text{Im } R$. In E^4 , consider a general surface

$$\begin{aligned}
dn &= \varrho^1 v_1 + \varrho^2 v_2, \\
dv_1 &= \varrho_1^2 v_2 + \varrho_1^3 v_3 + \varrho_1^4 v_4, \\
dv_2 &= -\varrho_1^2 v_1 + \varrho_2^3 v_3 + \varrho_2^4 v_4, \\
dv_3 &= -\varrho_1^3 v_1 - \varrho_2^3 v_2 + \varrho_3^4 v_4, \\
dv_4 &= -\varrho_1^4 v_1 - \varrho_2^4 v_2 - \varrho_3^4 v_3,
\end{aligned} \tag{2.38}$$

with

$$\begin{aligned}
\varrho_1^3 &= a_1 \varrho^1 + a_2 \varrho^2, & \varrho_2^3 &= a_2 \varrho^1 + a_3 \varrho^2, \\
\varrho_1^4 &= b_1 \varrho^1 + b_2 \varrho^2, & \varrho_2^4 &= b_2 \varrho^1 + b_3 \varrho^2,
\end{aligned} \tag{2.39}$$

$$\begin{aligned}
da_1 - 2a_2 \varrho_1^2 - b_1 \varrho_3^4 &= \alpha_1 \varrho^1 + \alpha_2 \varrho^2, \\
da_2 + (a_1 - a_3) \varrho_1^2 - b_2 \varrho_3^4 &= \alpha_2 \varrho^1 + \alpha_3 \varrho^2, \\
da_3 + 2a_2 \varrho_1^2 - b_3 \varrho_3^4 &= \alpha_3 \varrho^1 + \alpha_4 \varrho^2, \\
db_1 - 2b_2 \varrho_1^2 + a_1 \varrho_3^4 &= \beta_1 \varrho^1 + \beta_2 \varrho^2, \\
db_2 + (b_1 - b_3) \varrho_1^2 + a_2 \varrho_3^4 &= \beta_2 \varrho^1 + \beta_3 \varrho^2, \\
db_3 + 2b_2 \varrho_1^2 + a_3 \varrho_3^4 &= \beta_3 \varrho^1 + \beta_4 \varrho^2.
\end{aligned} \tag{2.40}$$

Then it is known [1] that, for

$$\begin{aligned}
\Phi &= (a_1 \alpha_3 + a_2 \alpha_4 - a_2 \alpha_2 - a_3 \alpha_3 + b_1 \beta_3 + b_2 \beta_4 - b_2 \beta_2 - b_3 \beta_3) \varrho^1 + \\
&\quad + (a_2 \alpha_1 + a_3 \alpha_2 - a_1 \alpha_2 - a_2 \alpha_3 + b_2 \beta_1 + b_3 \beta_2 - b_1 \beta_2 - b_2 \beta_3) \varrho^2,
\end{aligned}$$

we have

$$\begin{aligned}
\int_{\partial N}^* \Phi &= \int_N [2(\alpha_1 \alpha_3 + \alpha_2 \alpha_4 - \alpha_2^2 - \alpha_3^2 + \beta_1 \beta_3 + \beta_2 \beta_4 - \beta_2^2 - \beta_3^2) - \\
&\quad - \{(a_1 - a_3)^2 + 4a_2^2 + (b_1 - b_3)^2 + 4b_2^2\} (a_1 a_3 - a_2^2 + b_1 b_3 - b_2^2) + \\
&\quad + 2\{b_2(a_1 - a_3) + a_2(b_3 - b_1)\}^2] dv.
\end{aligned} \tag{2.42}$$

In our case, (2.42) is identical with

$$\int_{\partial N}^* d|R|^2 = \int_N \Delta |R|^2 dv. \tag{2.43}$$

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SOUHRN

DVĚ APLIKACE JEDNÉ INTEGRÁLNÍ FORMULE

ALOIS ŠVEC

V práci jsou vyloženy aplikace integrální formule [1] na teorii harmonických zobrazení a na teorii křivky v hermiteovské rovině.

РЕЗЮМЕ

ДВА ПРИМЕНЕНИЯ ОДНОЙ ИНТЕГРАЛЬНОЙ ФОРМУЛЫ

АЛОИС ШВЕЦ

В работе излагаются приложения интегральной формулы [1] на теорию гармонических отображений и на теорию кривых в пространствах Эрмита.