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Ján Andres

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Společná laboratoř optiky Československé akademie věd
a University Palackého v Olomouci

Vedoucí laboratoře: Antonín Novák, Doc., Ing., CSc.

SYMMETRY IN A CERTAIN SIMPLY PERTURBED HAMILTONIAN SYSTEM

JAN ANDRES

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Dedicated to Professor M. Laitoch on his 65th birthday

1. Recently an increasing attention has been paid to the study of the Lotka-Volterra system [1], namely

$$u' = \lambda u(1-v), \quad v' = -\rho v(1-u),$$

where λ, ρ are control parameters. As is well-known such a system can be transformed by means of $u = \exp x, v = \exp y$ to the form

$$x' = -g(y), \quad y' = h(x)$$

with $g(y) = \lambda(\exp y - 1), h(x) = \rho(\exp x - 1)$. Therefore especially in case, when $h(x) = -f(x), g(y) = -f(y)$ should be of interest in view of

$$\int_{x(0)}^{x(t)} f(s) ds + \int_{y(0)}^{y(t)} f(s) ds = \text{const.}$$

being the corresponding first integral. If the same hamilton-

nian system is considered under some small external forcing moreover, namely

$$\dot{x} = f(y) + \mu p(t), \quad \dot{y} = -f(x) + \nu q(t), \quad (1)$$

where μ, ν are the positive small parameters, then the natural question appears with respect to the solutions $[x(t), y(t)] \in (1)$, having the property

$$\lim_{t \rightarrow \infty} [|x(t)| - |y(t)|] = 0, \quad (2)$$

called here as an asymptotic symmetry: "are these solutions also stable in the sense of Lagrange?", i.e.

$$\limsup_{t \rightarrow \infty} [|x(t)| + |y(t)|] < \infty. \quad (3)$$

In the following text we give an affirmative answer to this problem, assuming

$$f(u) \operatorname{sgn} u \geq \delta \quad \text{for } |u| \geq R \quad (4)$$

or

$$f(u) \operatorname{sgn} u \leq -\delta \quad \text{for } |u| \geq R, \quad (4')$$

where δ, R are suitable positive constants and $f(u)$ is an everywhere continuous function as well as those of $p(t), q(t)$.

Replacing (4) or (4') by the restriction on the bounded and oscillatory function $f(u) = -f(x)$, we will furthermore show the solvability of our problem for the equation

$$\dot{x} = f(x) + \nu q(t), \quad (5)$$

originated from (1) in the special case of (2), namely $x(t) \equiv -y(t)$.

Hence let the prescribed assumptions hold throughout all the following text.

2. Corollary 1. Under (4) or (4') the following relation is satisfied for each solution $[x(t), y(t)]$ of (1):

$\limsup_{t \rightarrow \infty} \max [|x(t)|, |y(t)|] = \infty \Rightarrow \liminf_{t \rightarrow \infty} \min [|x(t)|, |y(t)|] \leq R,$
 provided μ, ν are sufficiently small.

P r o o f. We employ the Yoshizawa's technique [2, p.38] consisting of the construction of a Liapunov function $V(x,y)$ defined on R^2 , which satisfies the following conditions:

- (i) $\lim_{(|x|+|y|) \rightarrow \infty} V(x,y) = \infty,$
- (ii) $\exists R_0 > 0, \delta_0 > 0 \dots (|x|+|y|) > R_0 : \dots V^{(1)}(x,y) \leq -\delta_0,$

where

$$V^{(1)}(x,y) = \limsup_{\Delta t \rightarrow 0} \left\{ [V(x(t+\Delta t), y(t+\Delta t)) - V(x(t), y(t))] (\Delta t)^{-1} \right\} \quad (1)$$

and therefore ensures the uniform-ultimate boundedness of all solutions of (1).

Hence let us define

$$V(x,y) := \int_0^x f(s) ds + \int_0^y f(s) ds + \xi W(x,y),$$

where $W(x,y) := y \mathcal{R}_R(x) - x \mathcal{R}_R(y),$

$$\mathcal{R}_R(z) := \begin{cases} z & \dots \dots \dots \text{ for } |z| \leq R \\ R \operatorname{sgn} z & \dots \dots \dots \text{ for } |z| \geq R \end{cases}$$

and ξ be a suitable real, which magnitude will be specified later.

Since for $(x,y) \in R^2$ it is

$$|W(x,y)| \leq R [|x| + |y|] \quad (6)$$

and since (4) or (4') surely implies such $\xi \neq 0$ that

$$\liminf_{|x| \rightarrow \infty} \left| \frac{F(x)}{\xi R x} \right| > 1$$

or

$$\lim_{|x| \rightarrow \infty} \|F(x)\| - |\mathcal{E}R_x| = \infty, \quad (7)$$

where
$$F(x) := \int_0^x f(s) ds,$$

the relation (i) follows immediately from (6), (7), provided $|\mathcal{E}| < |\frac{\delta}{R}|$.

Now let us fix \mathcal{E} in the foregoing way and estimate $V'_{(1)}(x, y)$ from (ii):

$$V'_{(1)}(x, y) = \mu p(t)f(x) + \nu q(t)f(y) + \mathcal{E}W'_{(1)}(x, y),$$

where

$$W'_{(1)} = \begin{cases} R[f(y)-f(x)] + R[\nu q(t) + \mu p(t)] \dots\dots\dots x \geq R, y \leq -R \\ -Rf(x)+f(x)x-f(y)y-r+R \nu q(t) \dots\dots\dots x \geq R, |y| \leq R \\ -R[f(y)+f(x)] + R[-\mu p(t) + \nu q(t)] \dots\dots\dots x \geq R, y \geq R \\ -Rf(y)+f(y)y-f(x)x+r-R \mu p(t) \dots\dots\dots |x| \leq R, y \geq R \\ R[f(x)-f(y)] - R[\mu p(t) + \nu q(t)] \dots\dots\dots x \leq -R, y \geq R \\ Rf(x)-f(y)y+f(x)x-r-R \nu q(t) \dots\dots\dots x \leq -R, y \leq R \\ R[f(x)+f(y)] + R[\mu p(t) - \nu q(t)] \dots\dots\dots x \leq -R, y \leq -R \\ Rf(y)+f(y)y-f(x)x+r+R \mu p(t) \dots\dots\dots |x| \leq R, y \leq -R \end{cases}$$

and
$$r = \mu p(t)y + \nu q(t)x .$$

Letting

$$|p(t)| \in :P, \quad |q(t)| \in :Q \quad \text{for all } t, \quad (8)$$

we obtain with respect to (4) (the case (4') can be verified in an analogous way) for positive \mathcal{E} that

a) $|x| \geq R, |y| \geq R:$

$$\begin{aligned} \frac{V'_{(1)}(x, y)}{|\mathcal{E}|} &\leq -R [|f(x)| + |f(y)|] + |\mu p(t)| \left(R + \left| \frac{f(x)}{\mathcal{E}} \right| \right) + |\nu q(t)| X \\ &\quad X \left(R + \left| \frac{f(y)}{\mathcal{E}} \right| \right) \leq -|f(x)| \left(R - \mu \frac{P}{|\mathcal{E}|} \right) - |f(y)| \left(R - \nu \frac{Q}{|\mathcal{E}|} \right) + \\ &\quad + \mu PR + \nu QR, \end{aligned}$$

while for negative \mathcal{E} that

b) $|x| \geq R, |y| \leq R:$

$$\frac{V_{(1)}'(x, y)}{|\mathcal{E}|} \leq -|f(x)x| + |f(x)|(R + |\mu \frac{p(t)}{\mathcal{E}}|) + |x \nu q(t)| + |f(y)| x \\ x (|y| + |\frac{\nu q(t)}{\mathcal{E}}|) + |\mu p(t)y| + |\nu q(t)R| \leq -|f(x)x| + \\ + |f(x)|(R + |\mu \frac{p}{\mathcal{E}}|) + |x \nu Q| + |f(y)|(R + |\nu \frac{Q}{\mathcal{E}}|) + \nu QR + \mu PR,$$

c) $|x| \leq R, |y| \geq R:$

$$\frac{V_{(1)}'(x, y)}{|\mathcal{E}|} \leq -|f(y)y| + |f(y)|(R + |\nu \frac{q(t)}{\mathcal{E}}|) + |y \mu p(t)| + |f(x)| x \\ x (|x| + |\mu \frac{p(t)}{\mathcal{E}}|) + |\nu q(t)x| + |\mu p(t)R| \leq |f(y)y| + |f(y)| x \\ x (R + |\nu \frac{Q}{\mathcal{E}}|) + |y \mu P| + |f(x)|(R + |\mu \frac{P}{\mathcal{E}}|) + \nu QR + \mu PR.$$

It is evident that (ii) will be satisfied separately for a) or b) or c), provided $|\mathcal{E}| < \delta/R$ and μ, ν are small enough. Thus according to Yoshizawa's theorem the assertion of our corollary is implied immediately.

3. In this part we shall discuss the special case of (1) ($x := -y$), namely (5) under the restriction that $f(x)$ is bounded and oscillatory with isolated roots in the following sense: for each argument x they may be found such numbers $\beta_1 > \alpha_1 > x > \alpha_{-1} > \beta_{-1}$ that

$$f(\alpha_1) < 0, f(\beta_1) > 0, f(\alpha_{-1}) < 0, f(\beta_{-1}) > 0.$$

If the uniqueness condition is satisfied, then evidently, all the solutions of the equation resulting from (5) for $\nu = 0$, namely

$$x' + f(x) = 0$$

are bounded, which cannot be said about (5), if $\nu \neq 0$.

It will be very useful to be concerned still with the equation

$$x' + (-1)^k c_k(x-d) = (-1)^k k d_k + \nu q(t) - f_k(x) \quad (k\text{-integer}), \quad (9)$$

where $c_k > 0, d_k > 0, d$ are constants and $f_k(x)$ is such a continuous function for all x that

$$f(x) = f_L(x) + f_N(x), \quad (10)$$

$$f_L(x) = (-1)^k c_k(x-d) - k d_k \quad (f_N(x) = f_k(x)) \text{ in } x \in \langle x_{k-1}^*, x_k^* \rangle \quad (11)$$

that there always exists just one point $\bar{x}_k \in (x_{k-1}^*, x_k^*)$ with

$$f_L(\bar{x}_k) = f_N(\bar{x}_k) = 0. \quad (12)$$

Note. Conditions (10) - (12) may be fulfilled e.g. for

$$f(x) := \sin x$$

$$(f_L(x) := (-1)^k(x-k\pi), \max_{x \in \mathbb{R}^1} |f_N(x)| = (\frac{\pi}{2} - 1), x \in \langle -\frac{\pi}{2} + k\pi, -\frac{\pi}{2} + (k+1)\pi \rangle, \bar{x}_k = k\pi; k\text{-integer}).$$

Corollary 2. The condition

$$\min [d(x_{k-1}^*, \bar{x}_k), d(x_k^*, \bar{x}_k)] > \frac{\nu Q + F_k}{c_k}, \quad (14)$$

where $F_k := \max_{x \in \langle x_{k-1}^*, x_k^* \rangle} f_N(x)$, holding for $k = 0, \pm 2, \pm 4$ (cf. also

(8), (10) - (12)), implies the boundedness of all solutions of (5).

P r o o f. Let us assume on the contrary that $x(t)$ is such a divergent solution of (5) that

$$\limsup_{t \rightarrow \infty} x(t) = \infty$$

(the case, when $x(t)$ tends to " $-\infty$ " may be performed just in the same way).

Then there must exist the last point $T_1 \geq 0$ with $x(T_1) = x_{k-1}^*$ and the first point $T_2 \geq T_1$ with $x(T_2) = x_k^*$, where k -is even. It is clear that $x(t) \in \langle x_{k-1}^*, x_k^* \rangle$ ($T_1 \leq t \leq T_2$) can be represented by

$$x(t) = C \exp((-1)^{k+1} c_k t) + \int_0^t \exp((-1)^{k+1} c_k (t-\tau)) [y_q(t) - f_k(x(\tau))] d\tau + \frac{d_k}{c_k}$$

with a constant C .

However, as for $t \geq 0$ and k -even the following estimation holds:

$$|x(t)| \leq |C e^{-c_k t}| + \left| \frac{y_Q + F_k}{c_k} \right| + \left| k \frac{d_k}{c_k} \right|,$$

where $F_k := \max_{x \in \langle x_{k-1}^*, x_k^* \rangle} |f_N(x)|$, the existence of the point T_2 is

impossible with respect to (14), a contradiction. This completes the proof.

Note (continuation). (14) is satisfied for $f(x) = \sin x$, if

$$\mathcal{T}/2 > y_Q + F_k := (\mathcal{T}/2 - 1), \text{ i.e. if } y < 1/Q.$$

4. Theorem. If the solution $[x(t), y(t)]$ of (1) is asymptotically symmetrical according to (2) under (4) or (4'), then (3) is necessarily implied, provided μ, ν are sufficiently small. If $x(t) = -y(t)$ moreover, then (3) follows even for the bounded and in the above way oscillatory function $f(x)$, provided (14).

P r o o f. - follows immediately from the preceding two corollaries.

It can be seen from the proof of Corollary 1 that the first part of the assertion of our Theorem can be introduced in a more precise form, namely that the possible asymptotically symmetrical solutions of (1) are even uniformly ultimately bounded.

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SOUHRN

Symetrie v jistém jednoduše perturbovaném Hamiltonově systému

J a n A n d r e s

V poznámce je zkoumána otázka, zda pro řešení systému (1) (těsně svázaného s rovnicemi Lotky-Volterry) s vlastností (2) vždy platí (3), a to i v případě dostatečně malých spojitých vnějších poruch. Jsou nalezeny postačující podmínky, zaručující pozitivní odpověď na daný problém.

РЕЗЮМЕ

Симметрия в одной просто возмущенной системе Гамильтона

Я н А н д р е с

В заметке изучается вопрос, если свойство (2) принадлежало решениям системы (1) (тесно связанной с уравнениями Лотки-Вольтерры) влечет всегда за собой тоже (3), а даже в случае достаточно малых непрерывных внешних возмущений. Находятся достаточные условия, гарантирующие положительный ответ на данную проблему.

Author's address:

RNDr. Jan Andres, CSc.,
Laboratoř optiky ČSAV a UP
Gottwaldova 15
771 46 Olomouc
ČSSR (Czechoslovakia)
