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Polynomial Structures with Double Roots^{*}

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Abstract

Our aim is to investigate integrability of a polynomial structures the characteristic polynomial of which has at most double real roots. The general case can be regarded as a “refinement” of the special case

$$h(h - I)^2(h^2 + I) = 0.$$

Key words: Projector, manifold, polynomial structure, integrability.

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We will formulate integrability conditions for a polynomial structure the characteristic polynomial of which has at most double roots. The well-known examples of such structures are almost tangent structures, or f -structures (almost contact structures) which satisfy $f^3 + f = 0$. The case of single roots was completely solved in [9], [11].

Suppose that all objects under consideration (manifolds, tensor fields etc.) are of the class C^∞ . The Nijehuis bracket (tensor) is denoted by $[\cdot, \cdot]$.

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1 Almost tangent structures

Recall some well-known facts. An *almost tangent structure* is given by a $(1, 1)$ -tensor field h of constant rank which is nilpotent, $h^2 = 0$. The integrability conditions were found by J. Lehmann-Lejeune, [7]. Note that the case $h^n = 0$ with $n \geq 3$ was not solved in general, it is more complicated from the technical point of view

At any point x of an almost tangent manifold the inclusion $\text{im } h_x \subseteq \ker h_x$ is satisfied. If the “dimension regularity” conditions $\dim \text{im } h = p$, $\dim \ker h = q$ with $p, q \geq 0$ real constants are satisfied then the image $\text{im } h$ (respectively the kernel $\ker h$) is a p -dimensional (respectively $(p + q)$ -dimensional) distribution, and $\dim M = m = 2p + q$. A frame $(x; X_1, \dots, X_m)$ is called *h -adapted* if $X_{i+p+q} = h(X_i)$, $i = 1, \dots, p$, X_{i+p+q} , $i = 1, \dots, p$ is a basis of $\text{im } h_x$ and X_{1+p}, \dots, X_m is a basis of $\ker h_x$. The matrix representation of $h_x \in \text{End}(T_x M)$ with respect to the h -adapted frame is of the form

$$\begin{pmatrix} \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{I} & \mathbf{0} & \mathbf{0} \end{pmatrix} \begin{matrix} \}p \\ \}q \\ \}p \end{matrix} \tag{1}$$

The family of all h -adapted frames form a G -structure for which G is a Lie subgroup of $GL(m, R)$ formed by all square (m, m) -matrices of the form

$$\begin{pmatrix} \mathbf{A}_{11} & \mathbf{0} & \mathbf{0} \\ \mathbf{A}_{21} & \mathbf{A}_{22} & \mathbf{0} \\ \mathbf{A}_{31} & \mathbf{A}_{32} & \mathbf{A}_{11} \end{pmatrix} \begin{matrix} \}p \\ \}q \\ \}p \end{matrix}$$

The almost tangent structure h is called *integrable* if the corresponding G -structure is integrable, i.e. if there are local “ h -adapted” coordinates on a nbd of each point with respect to which the matrix of h_x is (1). Another speaking the holonomic frame $(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_m})$ is h -adapted. For a nilpotent polynomial structure, $h^2 = 0$, the following conditions are equivalent, [6]:

- ker h is integrable, and $[h, h] = 0$;
- h is integrable;
- there exists a symmetric connection ∇ on M such that $\nabla h = 0$.

2 Complex almost product structures

If (D_1, \dots, D_t) is an almost product structure and J a complex structure¹ satisfying $JD_i = D_i$, $i = 1, \dots, t$, $(J; D_1, \dots, D_t)$ is a *complex almost product structure*. The structure $(J; D_1, \dots, D_t)$ is *integrable* if J can be written

¹A complex structure is an almost complex structure, $J^2 + I = 0$, satisfying the integrability condition $[J, J] = 0$.

locally in the form

$$J = \begin{pmatrix} \mathbf{0}_{n_1} & \mathbf{I}_{n_1} & & & \mathbf{0} \\ -\mathbf{I}_{n_1} & \mathbf{0}_{n_1} & & & \\ & & \ddots & & \\ & \mathbf{0} & & \mathbf{0}_{n_t} & \mathbf{I}_{n_t} \\ & & & -\mathbf{I}_{n_t} & \mathbf{0}_{n_t} \end{pmatrix}$$

where $\dim D_i = 2n_i$. Through the corresponding projectors P_i , the integrability condition can be reformulated as $[P_i, P_j] = [P_i, J] = 0$, [9].

3 Almost tangent almost product structures

In [10], the problem of simultaneous integrability of an almost tangent structure and a distribution was solved.

We will need here a generalization: a simultaneous integrability of an almost tangent and an almost product structure. Suppose that (D_1, \dots, D_t) is an almost product structure on M with projectors P_1, \dots, P_t , and at the same time, let M be endowed with an almost tangent structure g such that $(g - I)^2 = 0$. Let us assume that $g \circ P_i = P_i \circ g, i = 1, \dots, t$. Then

$$(g - I)D_i \subseteq D_i,$$

and $(g; D_1, \dots, D_t)$ will be called *an almost tangent almost product structure*. Let us use the notation

$$g_i = g|_{D_i}, \quad \dim \ker D_i = p_i + q_i, \quad \dim \operatorname{im} g_i = p_i, \\ \dim D_i = n_i, \quad n_i = 2p_i + q_i.$$

Now it is natural to define:

Definition 1 We say that $(g; D_1, \dots, D_t)$ is *integrable* if there are local coordinates such that g is represented by

$$g = \begin{pmatrix} \mathbf{I}_{p_1} & \mathbf{0} & \mathbf{0} \} p & & & \\ \mathbf{0} & \mathbf{I}_{q_1} & \mathbf{0} \} q & & & \mathbf{0} \\ \mathbf{I}_{p_1} & \mathbf{0} & \mathbf{I}_{p_1} \} p & & & \\ & & & \ddots & & \\ & & & & \mathbf{I}_{p_t} & \mathbf{0} & \mathbf{0} \} p \\ & \mathbf{0} & & & \mathbf{0} & \mathbf{I}_{q_t} & \mathbf{0} \} q \\ & & & & \mathbf{I}_{p_t} & \mathbf{0} & \mathbf{I}_{p_t} \} p \end{pmatrix} \tag{2}$$

where \mathbf{I}_s denotes a unit matrix of the type (s, s) .

By standard methods, we can prove the following [11].

Proposition 1 *An almost tangent almost product structure $(g; D_1, \dots, D_t)$ is integrable if and only if the following conditions are satisfied:*

- (i) $[P_i, P_j] = 0$ for $i, j = 1, \dots, t$,
- (ii) $[g, g] = 0$,
- (iii) $\ker(g - I)$ is integrable,
- (iv) $[P_i, g] = 0$ for $i = 1, \dots, t$.

4 The case $h(h - I)^2(h^2 + I) = 0$

Now let us consider a polynomial structure h satisfying

$$h(h - I)^2(h^2 + I) = 0. \tag{3}$$

Suppose that $D_1 = \ker h$, $D_2 = \ker(h - I)^2$, $D_3 = \ker(h^2 + I)$ are of constant ranks on M , $\dim D_1 = p$, $\dim D_2 = q$, $\dim D_3 = 2s$, where $q = 2k + l$, $p + q + 2s = m$. Then the tangent space is a Whitney sum $TM = D_1 \oplus D_2 \oplus D_3$. The corresponding projectors are $P_1 = (h - I)^2(h^2 + I)$, $P_2 = I - (h - I)^2(h^2 - \frac{1}{2}h + I)$, $P_3 = \frac{1}{2}h(h - I)^2$. It is natural to define

Definition 2 A polynomial structure h satisfying (3) on M is *integrable* if there are local coordinates with respect to which the matrix representation of h is

$$h = \begin{pmatrix} \mathbf{0}_p & & & & & \mathbf{0} \\ & I_k & \mathbf{0} & \mathbf{0} & & \\ & \mathbf{0} & I_l & \mathbf{0} & & \\ & I_k & \mathbf{0} & I_k & & \\ \mathbf{0} & & & & \mathbf{0} & I_s \\ & & & & -I_s & \mathbf{0} \end{pmatrix}. \tag{4}$$

The following technical lemma is useful in the next proof.

Lemma 1 *Let f be a $(1, 1)$ -tensor field satisfying $[f, f] = 0$. Then for any natural $a, b \geq 0$*

$$[f^a, f^b] = 0.$$

Theorem 1 *A polynomial structure (3) is integrable if and only if the following conditions are satisfied:*

- (i) $[h, h] = 0$,
- (ii) $\ker(h - I)$ is integrable.

Proof The conditions are necessary as it can be verified. So let them be satisfied. To prove that (D_1, D_2, D_3) is integrable we will verify $[P_i, P_j] = 0$, $i, j = 1, 2, 3$. Since the projectors are polynomials in h , the brackets $[P_i, P_j]$ can be expressed as linear combinations of terms of the form $[h^a, h^b]$ with natural exponents a, b . So all couples of projectors vanish. Now we can find local coordinates in a nbd of any point

$$(x_1, \dots, x_p, v_1, \dots, v_q, y_1, \dots, y_{2s})$$

such that

$$h = \begin{pmatrix} \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{F} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{G} \end{pmatrix},$$

where \mathbf{F} and \mathbf{G} are matrices of the type (p, p) and $(2s, 2s)$ respectively, depending on (x_1, \dots, x_{2s}) . Let us denote their entries by (F_j^i) or (G_k^r) , respectively. We will prove that \mathbf{F} depends in fact only on v_1, \dots, v_q and, \mathbf{G} depends on y_1, \dots, y_{2s} . Let $1 \leq i \leq p, 1 \leq j \leq q$. By (i)

$$0 = \frac{1}{2}[h, h] \left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial v_j} \right) = -h \left[\frac{\partial}{\partial x_i}, h \frac{\partial}{\partial v_j} \right] = -h \left[\frac{\partial}{\partial x_i}, F_j^t \frac{\partial}{\partial v_t} \right] = -h \left(\frac{\partial F_j^t}{\partial x_i} \cdot \frac{\partial}{\partial v_t} \right).$$

On D_2 , $(h - I)^2 = 0$ is satisfied. We obtain that $h|_{D_2}$ is an automorphism since $h(2I - h) = I$ on D_2 . It follows $\frac{\partial F_j^i}{\partial x_i} = 0$. The equality $\frac{\partial G_j^k}{\partial x_i} = 0$ can be proved for $1 \leq j \leq q, 1 \leq i \leq p$ in a similar way: h is an automorphism on D_3 since $h(-h) = I$ is satisfied on D_3 , and $\frac{1}{2}[h, h] \left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial y_k} \right) = -h \left(\frac{\partial G_j^k}{\partial x_i} \cdot \frac{\partial}{\partial y_k} \right)$.

Now let $1 \leq i \leq q, 1 \leq j \leq 2s$. It can be easily verified that $[h^2 + I, h] = 0$ follows as a consequence of our assumption $[h, h] = 0$. We evaluate

$$[h, h] \left(\frac{\partial}{\partial y_j}, \frac{\partial}{\partial v_i} \right) = 2 \left[h \frac{\partial}{\partial y_j}, h \frac{\partial}{\partial v_i} \right] - 2h \left[h \frac{\partial}{\partial y_j}, \frac{\partial}{\partial v_i} \right] - 2h \left[\frac{\partial}{\partial y_j}, h \frac{\partial}{\partial v_i} \right] = 0, \tag{5}$$

$$[h^2 + I, h] \left(\frac{\partial}{\partial y_j}, \frac{\partial}{\partial v_i} \right) = \left[h \frac{\partial}{\partial y_j}, (h^2 + I) \frac{\partial}{\partial v_i} \right] - (h^2 + I) \left[\frac{\partial}{\partial y_j}, h \frac{\partial}{\partial v_i} \right] - h \left[\frac{\partial}{\partial y_j}, (h^2 + I) \frac{\partial}{\partial v_i} \right]. \tag{6}$$

On $D_2 = \ker (h - I)^2$, the equality $h^2 + I = 2h$ is satisfied. So (6) can be written as $2[h \frac{\partial}{\partial y_j}, h \frac{\partial}{\partial v_i}] - (h^2 + I)[\frac{\partial}{\partial y_j}, h \frac{\partial}{\partial v_i}] - 2h[\frac{\partial}{\partial y_j}, h \frac{\partial}{\partial v_i}] = 0$. Combining

$$(5) \text{ and } (6) \text{ gives } -2h \left[h \frac{\partial}{\partial y_j}, \frac{\partial}{\partial v_i} \right] + (h^2 + I) \left[\frac{\partial}{\partial y_j}, h \frac{\partial}{\partial v_i} \right] = 0,$$

$$2h \left(\frac{\partial^k}{G_j} \frac{\partial}{\partial v_i} \cdot \frac{\partial}{\partial} y_k \right) + (h^2 + I) \left(\frac{\partial^r}{F_i} \frac{\partial}{\partial} y_j \cdot \frac{\partial}{\partial} v_r \right) = 0. \tag{7}$$

We apply the automorphism $h^2 + I$ on both sides of the equality (7) to obtain $(h^2 + I)^2 (\frac{\partial F_r}{\partial y_j} \cdot \frac{\partial}{\partial v_r}) = 0$ which gives $\frac{\partial F_r}{\partial y_j} = 0$ since $(h^2 + I)^2$ is again an automorphism. Similarly, an application of $(h - I)^2$ on (7) gives $h(h - I)^2 (\frac{\partial G_i^k}{\partial v_i} \cdot \frac{\partial}{\partial y_k}) = 0$. But $h(h - I)^2 | D_3$ is an automorphism since on $D_3 = \ker (h^2 + I)$, $h(h - I)^2 = h^3 - 2h^2 + h = -2h^2 = 2I$. It follows $\frac{\partial G_i^k}{\partial v_i} = 0$. By our assumptions and the above results, F is an integrable almost tangent structure on integral submanifolds of the distribution D_2 , and G is a complex structure on integral submanifolds of D_3 . So there exists a coordinate transformation $x_j = \varphi_j(v_1, \dots, v_q)$, $x_l = \varphi_l(y_1, \dots, y_{2s})$, where $p + 1 \leq j \leq p + q$, $p + q + 1 \leq l \leq p + q + 2s = m$ such that with respect to the corresponding holonomic frame, the matrix of h admits the desired form. \square

5 The general case

More generally, let us consider a polynomial structure (M, f) satisfying the polynomial equation with at most double real roots of the characteristic polynomial R

$$R(f) = \prod_{i=1}^r (f - b_i I) \prod_{j=1}^R (f - B_j)^2 \prod_{k=1}^s (f^2 + 2c_k f + d_k I) = 0, \tag{8}$$

$$b_i, B_j, c_k, d_k \in R, \quad c_i^2 - d_j < 0$$

with pairwise distinct factors. The decomposition of the tangent bundle is $TM = \bigoplus_{i=1}^r D'_i \oplus \bigoplus_{j=1}^R \tilde{D}_j \oplus \bigoplus_{k=1}^s D''_k$ where $D'_i = \ker (f - b_i I)$, $i = 1, \dots, r$, $\tilde{D}_j = \ker (f - B_j)^2$, $j = 1, \dots, R$, $D''_k = \ker (f^2 + 2c_k f + d_k I)$, $k = 1, \dots, s$ are distributions on M invariant under f , of constant dimensions, [9], $n'_i = \dim D'_i$, $m_j = \dim \tilde{D}_j$, $2n''_k = \dim D''_k$, $\sum n'_i = \tilde{n}$, $\sum m_j = \tilde{m}$, $\sum n''_k = \tilde{\tilde{n}}$, $\dim M = m = \tilde{m} + \tilde{n} + 2\tilde{\tilde{n}}$. We obtain an almost product structure

$$(D'_1, \dots, D'_r, \tilde{D}_1, \dots, \tilde{D}_R, D''_1, \dots, D''_s) \tag{9}$$

associated with f . Denote by P'_i, \tilde{P}_j, P''_k the corresponding projectors.

Let us define integrability of the structure (8). We can introduce an almost tangent structure on each \tilde{D}_j , $j = 1, \dots, R$, and an almost complex structure on each D''_k , $k = 1, \dots, s$ as follows. Denote $\tilde{f}_j = f | \tilde{D}_j$, $I_j = I | \tilde{D}_j$. The equality $(\tilde{f}_j - B_j I_j)^2 = 0$ can be written as $((\tilde{f}_j - B_j I_j + I_j) - I_j)^2 = 0$. So the formula $S_j = \tilde{f}_j - (B_j - 1)I_j$ defines an almost tangent structure S_j on \tilde{D}_j , and \tilde{f}_j can be evaluated by $\tilde{f}_j = S_j + (B_j - 1)I$. Similarly, $f''_k = f | D''_k$ satisfies $f''_k{}^2 + 2c_k f''_k + d_k I_k = 0$, and an almost complex structure J''_k is introduced on D''_k by $J''_k = \frac{1}{\sqrt{d_k - c_k^2}} (f''_k + c_k I_k)$. Obviously, $f''_k = \sqrt{d_k - c_k^2} J''_k - c_k I_k$.

- (i) The Nijenhuis brackets of all couples of projectors vanish.
(ii) $\ker(\Phi - I)$ is integrable, and $[\Phi, \Phi] = 0$.
(iii) $\{\tilde{P}_j, \Phi\} = 0$, $j = 1, \dots, R$, $\{P'_k, \Phi\} = 0$, $k = 1, \dots, s$.

Remark 1 The condition (i) is equivalent with integrability of the associated almost product structure (9); (iii) means integrability of $\tilde{D}_j \oplus D''$ and $\tilde{D} \oplus D''_k$.

Proof It can be verified that the above conditions are necessary. Let us prove that they are sufficient. By (i), there are local coordinates

$$(x_1, \dots, x_{\tilde{n}}, v_1, \dots, v_{\tilde{m}}, y_1, \dots, y_{2\tilde{n}})$$

in a nbd of any point such that $(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_{\tilde{n}}})$ form a basis of D'_1 etc., the middle part of the coordinate frame $(\frac{\partial}{\partial v})$ form a basis of \tilde{D} , and the last part $(\frac{\partial}{\partial y})$ is a basis of D'' . The endomorphisms $P'_i, \tilde{P}_j, P''_k, \Phi$ have representations

$$P'_i = \begin{pmatrix} 0_{n'_1} & 0 & & & 0 \\ 0 & I_{n'_1} & & & \\ & & \ddots & & \\ & & & I_{n'_r} & 0 \\ 0 & & & 0 & 0_{2\tilde{n}} \end{pmatrix},$$

$$\tilde{P}_j = \begin{pmatrix} 0_{\tilde{n}} & 0 & 0 \\ 0 & Q_j & 0 \\ 0 & 0 & 0_{2\tilde{n}} \end{pmatrix} \quad P''_k = \begin{pmatrix} 0_{\tilde{n}} & 0 & 0 \\ 0 & Q_{\tilde{m}} & 0 \\ 0 & 0 & P_k \end{pmatrix} \quad \Phi = \begin{pmatrix} 0_{\tilde{n}} & 0 & 0 \\ 0 & F & 0 \\ 0 & 0 & G \end{pmatrix}$$

where Q_j, F are (\tilde{m}, \tilde{m}) -matrices, and P_k, G are $(2\tilde{n}, 2\tilde{n})$ -matrices the entries of which are functions depending on $x_1, \dots, y_{2\tilde{n}}$. In the proof of Theorem 1, we found that F depends only on the coordinates $v_1, \dots, v_{\tilde{m}}$, while G depends on $y_1, \dots, y_{2\tilde{n}}$. In a similar way, we can verify that Q_j are matrix functions of variables $v_1, \dots, v_{\tilde{m}}$, and P_k are functions in $y_1, \dots, y_{2\tilde{n}}$. It suffices to use the equations

$$[P'_i, \tilde{P}_k] \left(\frac{\partial}{\partial} x^t, \frac{\partial}{\partial} v^t \right) = 0, \quad [P''_j, \tilde{P}_k] \left(\frac{\partial}{\partial} y^t, \frac{\partial}{\partial} v^t \right) = 0,$$

$$\text{where } \frac{\partial}{\partial x^t} \in D_i, \quad \frac{\partial}{\partial v^t} \in \tilde{D}, \quad \frac{\partial}{\partial y^t} \in D'',$$

$$[P'_i, P''_j] \left(\frac{\partial}{\partial} x^h, \frac{\partial}{\partial} y^t \right) = 0, \quad [\tilde{P}_i, P''_j] \left(\frac{\partial}{\partial} v^k, \frac{\partial}{\partial} y^t \right) = 0,$$

$$\text{where } \frac{\partial}{\partial x^h} \in D_i, \quad \frac{\partial}{\partial v^k} \in \tilde{D}, \quad \frac{\partial}{\partial y^t} \in D''.$$

The matrices of projectors P'_i indicate that they depend only on $x_1, \dots, x_{\tilde{n}}$. In a natural way, a coordinate neighborhood N is foliated into three systems of leaves. The leaves of the first foliation are given by $x_1 = \text{const}, \dots, y_{2\tilde{n}} = \text{const}$;

the second system of leaves is given by $x_1 = \text{const}, \dots, x_{\tilde{n}} = \text{const}, y_1 = \text{const}, \dots, y_{2\tilde{n}} = \text{const}$. The third foliation is defined by $x_1, \dots, v_{\tilde{m}}$ constant. We restrict Φ onto each leaf of the second family to obtain an integrable almost tangent structure independent of parameters x_i, y_j determining the leaf. At the same time, the restrictions of projectors \tilde{P}_k is independent of these parameters. By Proposition 1 we can find a coordinate transformation $\tilde{x}_{\tilde{n}+1} = \varphi_1(v_1, \dots, v_{\tilde{m}}), \tilde{v}_{\tilde{n}+\tilde{m}} = \varphi_{\tilde{m}}(v_1, \dots, v_{\tilde{m}})$ such that with respect to the new coordinate frame $\left(\frac{\partial}{\partial \tilde{x}_{\tilde{n}+1}}, \dots, \frac{\partial}{\partial x_{\tilde{n}+\tilde{n}}}\right)$,

$$F = \begin{pmatrix} I & 0 & 0 & & & \\ 0 & I & 0 & & 0 & \\ I & 0 & 0 & & & \\ & & & I & 0 & 0 \\ & 0 & & 0 & I & 0 \\ & & & I & 0 & 0 \end{pmatrix}.$$

Similarly, the restriction of Φ onto each leaf of the third foliation defines an integrable almost complex structure which is independent of the parameters x_i, v_k determining a leaf. The restrictions of P_j'' onto the leaves of this last foliation are also independent on the variables x_i, v_k . So there exists a coordinate transformation $\tilde{x}_{\tilde{n}+\tilde{m}+1} = \psi_1(y_1, \dots, y_{2\tilde{n}}), \tilde{x}_{\tilde{n}+\tilde{m}+2\tilde{n}} = \psi_{2\tilde{n}}(y_1, \dots, y_{2\tilde{n}})$ such that

$$G = \begin{pmatrix} 0 & I & & \\ -I & 0 & & 0 \\ & & 0 & I \\ & 0 & -I & 0 \end{pmatrix}.$$

Now it is obvious that the coordinate transformation

$$\begin{aligned} x'_i &= x_i, & 1 \leq i \leq \tilde{n}, \\ x'_{\tilde{n}+k} &= \varphi_k(v_1, \dots, v_{\tilde{m}}), & 1 \leq k \leq \tilde{m}, \\ x_{\tilde{n}+\tilde{m}+j} &= \psi_j(y_1, \dots, y_{2\tilde{n}}), & 1 \leq j \leq 2\tilde{n} \end{aligned}$$

yields a coordinate frame with respect to which in the representation of Φ , exactly blocks of the form

$$\mathbf{0}_{\tilde{n}}, \quad \begin{pmatrix} I & 0 & 0 \\ 0 & 0 & 0 \\ I & 0 & I \end{pmatrix}, \quad \text{and} \quad \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}$$

occur on the diagonal. It follows that f admits the desired matrix representation. \square

6 Polynomial structures and webs

A non-holonomic 3-web can be defined by a couple of $(1,1)$ -tensor fields P, B such that P is idempotent, $P^2 - P = 0, B$ is involutive, $B^2 - I = 0$, and

$PB + BP = B$. Web distributions are given by $\ker P$, $\ker(I - P)$, $\ker(B - I)$. They are integrable (and the web is holonomic) iff $\ker(B - I)$ is involutive and $[P, P] = 0$. The condition $[P, B] = 0$ is satisfied exactly for webs which are paratactical (the torsion tensor of which vanishes identically). A 3-web is parallelizable (equivalent with three systems of parallel r -planes in R^{2r}) iff all three couples of almost product structures formed by web-distributions are simultaneously integrable.

More generally, a non-holonomic $(n + 1)$ -web of dimension r on a nr -dimensional manifold can be described by a family of $(1, 1)$ -tensor fields $\{\overset{\alpha}{H}, \alpha, \beta = 1, \dots, n\}$ which satisfy $\sum_{\alpha} \overset{\alpha}{H} = I$, $\overset{\gamma}{H} \overset{\alpha}{H} = \delta_{\kappa}^{\gamma} \overset{\alpha}{H}$. The mappings with different indexis are nilpotents, and $\{\overset{\alpha}{H}\}$ is a family of mutually orthogonal projectors onto web distributions $D_{\alpha} = \text{im } \overset{\alpha}{H}$. The remaining distribution is given by $D_0 = \text{im } \overset{0}{H}$ where $\overset{0}{H} = \frac{1}{n} \sum_{\alpha, \beta} \overset{\alpha}{H}$ is the remaining projector. The kernels of the above projectors form a web of codimension r . We will discuss these examples on some other place.

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