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## OSCILLATORY PROPERTIES OF SOLUTIONS TO A DIFFERENTIAL INCLUSION OF ORDER n

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The aim of this paper is to investigate the oscillatory as well as the nonoscillatory solutions and their asymptotic behaviour, of the differential inclusion

(E) 
$$L_n x(t) \in F(t, x(\varphi(t))), n > 1$$

where  $L_n x(t)$  is the n-th quasiderivative of x(t) with respect to the continuous functions  $a_i(t): J = [t_0, \infty) \to (0, \infty), i = 0, 1, ..., n, L_0 x(t) = a_0(t)x(t), L_i x(t) = a_i(t)(L_{i-1}x(t))', \int_{i}^{\infty} a_i^{-1}(t) dt = \infty; F(t, x): J \times \mathbb{R} \to \{\text{nonempty convex compact} \text{ subsets of } \mathbb{R}\}, \mathbb{R} = (-\infty, \infty); \varphi: J \to \mathbb{R}$  a continuous function such that  $\lim \varphi(t) = \infty$  as  $t \to \infty$ .

Under a solution x(t) of (E) we will understand a solution existing on some ray  $[T_x, \infty)$  such that

$$\sup\{|x(t)|:t_1\leqslant t<\infty\}>0 \text{ for any } t_1>T_x.$$

We will assume existence of such solutions.

Notation. F(t, x)x > 0 (< 0) means yx > 0 (< 0) for each  $y \in F(t, x)$ ; if  $h: J \times \mathbb{R} \to \mathbb{R}$ , then  $F(t, x) \ge (\leqslant) h(t, x)$  means:  $y \ge (\leqslant) h(t, x)$  for each  $y \in F(t, x)$ . If  $B \subset \mathbb{R}$  then  $||B|| = \inf\{|x|: x \in B\}$ .

The following basic assumptions will be used:

- 1° F(t, x) is upper semicontinuous on  $J \times \mathbf{R}$ ;
- 2° F(t,0) = 0 for each  $t \in J$ ;
- 3° F(t, x)x < 0 for each  $(t, x) \in J \times \mathbb{R}, x \neq 0$ ;
- or 4° F(t, x)x > 0 for each  $(t, x) \in J \times \mathbb{R}, x \neq 0$ .

The notions of oscillatory and nonoscillatory solutions will be used in the usual sense.

Consider the inclusion (E) and assume that the assumptions  $1^{\circ}-4^{\circ}$  are satisfied. Let x(t) be a nonoscillatory solution of (E). Then from the assumption  $\lim \varphi(t) = \infty$  as  $t \to \infty$  it follows the existence of such  $t_1 \ge t_0$  that  $x(\varphi(t)) \ne 0$  on  $[t_1, \infty)$ . Taking into consideration the assumptions 1°-4° we get that  $x(t)L_nx(t) \ne 0$  on  $[t_1,\infty)$ . Therefore,  $x(t)L_nx(t) > 0$  if 1°, 2°, 4° are satisfied and  $x(t)L_nx(t) < 0$  if 1°, 2°, 3° are satisfied on  $[t_1,\infty)$ . This implies that there exists  $t_2 \ge t_1$  such that each  $L_ix(t)$ ,  $i = 0, 1, \ldots, n$ , has a constant sign on  $[t_2,\infty)$ . Therefore, each  $L_ix(t)$ ,  $i = 0, 1, \ldots, n-1$ , is monotone on  $[t_2,\infty)$ , and  $\lim L_ix(t)$  as  $t\to\infty$ ,  $i = 0, 1, \ldots, n-1$ , exists in the extended sense, i.e.  $\lim |L_ix(t)|$  is finite or  $\infty$  as  $t\to\infty$  and  $i = 0, 1, \ldots, n-1$ . More detailed considerations [1] lead to the following result: For the nonoscillatory solutions of (E) the following two cases are posible:

- a)  $\lim_{t\to\infty} |L_i x(t)| = \infty$  for i = 0, 1, ..., n-1;
- b) there exists  $k \in \{0, 1, ..., n-1\}$  such that  $\lim_{t \to \infty} L_k x(t)$  is finite,  $\lim_{t \to \infty} L_i x(t) = \infty \cdot \operatorname{sgn} x(t), i = 0, 1, ..., k-1,$  $\lim_{t \to \infty} L_i x(t) = 0, i = k+1, ..., n-1.$

Remark 1. The case a) can occour only if the assumptions  $1^{\circ}$ ,  $2^{\circ}$ ,  $4^{\circ}$  are satisfied.

In fact, if the assumptions 1°, 2°, 3° are satisfied then  $x(t)L_nx(t) < 0$ . Therefore, if x(t) > 0 then  $L_{n-1}x(t)$  descreases and must be ultimately positive. If x(t) < 0 then  $L_{n-1}x(t)$  increases and must be ultimately negative. Thus  $|\lim_{t\to\infty} L_{n-1}x(t)| < \infty$ .

These considerations show that the set of all nonoscillatory solutions of (E) can be divided into disjoint classes in the following way.

**Definition 1.** We will say that a nonoscillatory solution x(t) of (E) belongs to the class  $V_n$  if the case a) occurs. We will say that a nonoscillatory solution x(t) of (E) belongs to the class  $V_k$ ,  $k \in \{0, 1, ..., n-1\}$ , if the case b) occurs.

In the sequel we will use the following notation and lemmas: Let  $t_0 \leq c < t < \infty$ . Then

$$P_{0}(t, c) = 1,$$

$$P_{i}(t, c) = \int_{c}^{t} a_{1}^{-1}(s_{1}) \int_{c}^{s_{1}} a_{2}^{-1}(s_{2}) \dots \int_{c}^{s_{i-1}} a_{i}^{-1}(s_{i}) ds_{i} \dots ds_{1},$$

$$i = 1, 2, \dots, n-1;$$

$$Q_{n}(t, c) = 1,$$

$$Q_{j}(t, c) = \int_{c}^{t} a_{n-1}^{-1}(s_{n-1}) \int_{c}^{s_{n-1}} a_{n-2}^{-1}(s_{n-2}) \dots \int_{c}^{s_{j+1}} a_{j}^{-1}(s_{j}) ds_{j} \dots ds_{n-1},$$

$$j = 1, 2, \dots, n-1.$$

It is easy to see that

$$\lim_{t\to\infty} P_i(t,c) = \infty, \ \lim_{t\to\infty} Q_i(t,c) = \infty, \text{ for } i = 1, 2, \ldots, n-1,$$

and taking into account the properties of  $a_i(t)$ , by the l'Hospital rule we get

$$\lim_{t \to \infty} P_i(t,c) P_j^{-1}(t,c) = 0 \text{ for } 0 \leq i < j \leq n-1,$$
$$\lim_{t \to \infty} Q_j(t,c) Q_i^{-1}(t,c) = 0 \text{ for } 0 < i < j \leq n-1.$$

Lemma 1 ([1], Lemma 4). Let z(t) be such that  $z(t) \neq 0$  on  $[t_1, \infty)$  and  $L_n z(t)$  exists on  $[t_1, \infty)$ . Let  $z(t)L_n z(t) \leq 0$  on  $[t_1, \infty)$ , where the equality may eventually hold at isolated points. Let  $k \in \{0, 1, ..., n-1\}$  be such that b) is fulfilled. Then there exists a  $T_1 \geq t_1$  such that sgn  $z(t) = \operatorname{sgn} L_k z(t)$  for  $t \geq T_1$ .

If n + k is even then  $|L_k z(t)|$  increases on  $[T_1, \infty)$  and there exist two constants  $0 < c_1 < c_2$  such that for  $t > T_1$ 

$$0 < c_1 < |L_k z(t)| < c_2$$

and

$$0 < c_1 < \lim_{t \to \infty} \left| L_0 z(t) P_k^{-1}(t,c) \right| < c_2, \ \lim_{t \to \infty} L_0 z(t) P_{k+1}^{-1}(t,c) = 0.$$

If n + k is odd then  $|L_k z(t)|$  descreases on  $[T_1, \infty)$  and there exists a constant c > 0 such that we have

$$0 < |L_k z(t)| < c \text{ for } t > T_1, 0 \leq \lim_{t \to \infty} |L_0 z(t) P_k^{-1}(t, c)| < c, \lim_{t \to \infty} L_0 z(t) P_{k+1}^{-1}(t, c) = 0.$$

Lemma 2 ([1], Lemma 6). Let z(t) be such that  $z(t) \neq 0$  and  $L_n z(t)$  exists, both on  $[t_1, \infty)$ . Let  $z(t)L_n z(t) \ge 0$  for  $t \ge t_1$ , where the equality may hold at isolated points. Let  $k \in \{0, 1, ..., n-1\}$  be such that b) is fulfilled. Then there exists a  $T_1 \ge t_1$  such that sgn  $z(t) = \operatorname{sgn} L_k z(t)$  for  $t > T_1$ .

If n + k is odd then  $|L_k z(t)|$  increases on  $[T_1, \infty)$  and there exist two constants  $0 < c_1 < c_2$  such that

$$0 < c_1 < |L_k z(t)| < c_2 \text{ for } t > T_1$$

and

$$0 < c_1 < \lim_{t \to \infty} \left| L_0 z(t) P_k^{-1}(t,c) \right| < c_2, \lim_{t \to \infty} L_0 z(t) P_{k+1}^{-1}(t,c) = 0.$$

If n + k is even then  $|L_k z(t)|$  descreases on  $[T_1, \infty)$  and there exists a constant  $c_3 > 0$  such that

$$0 < |L_k z(t)| < c_3 \text{ for } t > T_1, 0 \le \lim_{t \to \infty} |L_0 z(t) P_k^{-1}(t, c)| < c_3, \lim_{t \to \infty} L z(t) P_{k+1}^{-1}(t, c) = 0.$$

**Lemma 3** ([2], Lemma 3). Let  $x(t) \in V_k$ ,  $k \in \{0, 1, ..., n-1\}$ . Then

$$\lim_{t\to\infty} L_0 \boldsymbol{x}(t) P_{\boldsymbol{k}}^{-1}(t,c) = \lim_{t\to\infty} L_{\boldsymbol{k}} \boldsymbol{x}(t) = c_{\boldsymbol{k}}$$

If  $c_k \neq 0$  then there exist constants  $\alpha_k > 0$ ,  $\beta_k > 0$  and  $T'_k > t_0$  such that

(1) 
$$\alpha_k a_0^{-1}(t) P_k(t,c) \leq |x(t)| \leq \beta_k a_0^{-1}(t) P_k(t,c), \ t > T'_k.$$

We will consider two problems. The first problem is to find conditions which guarantee that  $\lim L_k x(t) = 0$  as  $t \to \infty$  for each  $x(t) \in V_k$ ,  $k \in \{0, 1, \ldots, n-1\}$ . The second problem is to state conditions which guarantee that the class  $V_k$ ,  $k \in \{0, 1, \ldots, n-1\}$ , is empty. These problems were discussed in [1], [2], [3] if instead of the inclusion (E) we have a differential equation.

**Theorem 1.** Let the assumptions 1°-4° be satisfied. Let  $G(t, u): Jx[0, \infty) \rightarrow [0, \infty)$  be a continuous and nondecreasing function in u for each fixed  $t \in J$ , such that

$$G(t, |\mathbf{x}|) \leq ||F(t, \mathbf{x})||, \ \mathbf{x} \in \mathbf{R}$$

Let  $k \in \{0, 1, \ldots, n-1\}$ . Suppose that

(2) 
$$\int_{t}^{\infty} a_{n}^{-1}(s)Q_{k+1}(s,t)G(s,\alpha a_{0}^{-1}(\varphi(s))P_{k}(\varphi(s),c)) ds = \infty$$

for all  $t \ge T_k$  such that  $\varphi(s) > c$  for  $s > T_k \ge T'_k$ ,  $c \ge t_0$ , and for each  $\alpha > 0$ , or

(3) 
$$\lim_{t \to \infty} \sup \int_{t}^{\infty} a_n^{-1}(s) Q_{k+1}(s,t) G(s, \alpha a_0^{-1}(\varphi(s)) P_k(\varphi(s), c)) \, \mathrm{d}s > 0$$

for each  $\alpha > 0$ .

Then for each  $x(t) \in V_k$  we have  $\lim L_k x(t) = 0$  as  $t \to \infty$ .

Proof. Let  $x(t) \in V_k$ ,  $k \in \{0, 1, ..., n-1\}$  and let  $\lim L_k x(t) = c_k \neq 0$  as  $t \to \infty$ . Then

$$0 \leq G(t, |\boldsymbol{x}(\varphi(t))|) \leq ||F(t, \boldsymbol{x}(\varphi(t)))||, t > T_{\boldsymbol{k}},$$

and

(4) 
$$0 \leqslant G(t, |x(\varphi(t))|) \leqslant |L_n x(t)|, \ t > T_k.$$

Assume that  $T_k$  is such that for  $t \ge T_k$ , x(t) has a constant sign, sgn  $x(t) = \text{sgn } L_k x(t)$  for  $t \ge T_k$  and (1) from Lemma 3 holds. Then the successive integrations on  $[t, \infty)$ ,

 $t > T_k$ , of (4), by virtue of the fact that  $\lim L_i x(t) = 0$  as  $t \to \infty$ , i = k + 1, ..., n - 1, give

$$0 \leqslant \int_{t}^{\infty} a_n^{-1}(s) Q_{k+1}(s,t) G(s, |x(\varphi(s))|) \, \mathrm{d}s \leqslant |L_k x(t) - c_k|.$$

From Lemma 3 we have

$$|x(\varphi(t))| \ge \alpha_k a_0^{-1}(\varphi(t)) P_k(\varphi(t), c).$$

Therefore, G(t, u) being nondecreasing, we get

$$0 \leqslant \int_{t}^{\infty} a_n^{-1}(s) Q_{k+1}(s,t) G\left(s, \alpha a_0^{-1}(\varphi(s)) P_k(\varphi(s),c)\right) \mathrm{d}s \leqslant \left| L_k x(t) - c_k \right|.$$

The expression on the right-hand side is bounded. This leads to a contradiction with (2). If (3) is satisfied then we have once more a contradiction, because  $\lim |L_k x(t) - c_k| = 0$  as  $t \to \infty$ .

**Theorem 2.** Let all assumptions of Theorem 1 be satisfied. Then, provided the assumptions 1°, 2°, 3° are satisfied, the sets  $V_k$  for n + k even are empty. If the assumptions 1°, 2°, 4° are satisfied then the sets  $V_k$  for n + k odd are empty.

Proof follows from Theorem 1 and from Lemma 1 and 2, respectively. Denote

$$\gamma(t) = \sup \left\{ s \geqslant t_0 : \varphi(s) \leqslant t 
ight\} ext{ for all } t \geqslant t_0$$

and

$$m(t) = \max\{\gamma(t), t\}, \ t \ge t_0.$$

We see that  $m(t) \ge t$ . From the continuity of  $\varphi(t)$  we get  $\varphi(s) > t$  for  $s > \gamma(t)$  and  $\varphi(s) \ge t$  for  $s \ge m(t)$ ,  $t \ge t_0$ . Evidently  $\lim m(t) = \infty$  as  $t \to \infty$ .

Consider the class  $V_k$ ,  $k \in \{0, 1, ..., n-1\}$ . Form the properties of the set  $V_k$  we get that  $\lim_{k \to \infty} L_{n-1}x(t)$  as  $t \to \infty$  is finite for each  $x(t) \in V_k$ . Then by virtue of the assumptions of Theorem 1, (4) yields

(5) 
$$0 \leqslant \int_{t}^{\infty} a_n^{-1}(s) G(s, |x(\varphi(s))|) \, \mathrm{d}s \leqslant |L_{n-1}x(t)| < \infty.$$

Our forthcoming considerations are based on this fact. Successive integration of (5), together with the fact that  $\lim L_i x(t) = 0$  as  $t \to \infty$ , i = k, k + 1, ..., n - 1, give

(6) 
$$0 \leqslant \int_{t}^{\infty} a_n^{-1}(s)Q_{k+1}(s,t)G(s, |x(\varphi(s))|) \,\mathrm{d}s \leqslant |L_k x(t)|.$$

a) Assume that  $x(t) \in V_k$ , x(t) > 0 for  $t > t_3$ , k > 0, where  $t_3$  is such that  $L_i x(t)$ , i = 0, 1, ..., n - 1, has a constant sign. Then  $L_k x(t) > 0$  for  $t > t_3$  and the integration of (6) between u and  $v, t_3 \leq u < v$ , and the application of Fubini's theorem yield

(7)  

$$0 \leq \int_{u}^{v} a_{n}^{-1}(s)G(s, |x(\varphi(s))|) \int_{u}^{s} a_{k}^{-1}(t)Q_{k+1}(s, t) dt ds$$

$$+ \int_{u}^{\infty} a_{n}^{-1}(s)G(s, |x(\varphi(s))|) \int_{u}^{v} a_{k}^{-1}(t)Q_{k+1}(s, t) dt ds$$

$$\leq L_{k-1}x(v) - L_{k-1}x(u) \leq L_{k-1}x(v)$$

because  $L_{k-1}x(t) > 0$  for  $t > t_3$ . It follows from the definiton of  $Q_{k+1}(s,t)$  than for  $t \leq v \leq s$ 

$$Q_{k+1}(s,t) \ge Q_{k+1}(v,t).$$

Therefore, from (7) we get

(8) 
$$0 \leqslant \int_{u}^{v} a_{k}^{-1}(t)Q_{k+1}(v,t) \mathrm{d}t \int_{v}^{\infty} a_{n}^{-1}(s)G(s, |x(\varphi(s))|) \mathrm{d}s \leqslant L_{k-1}x(v).$$

Repeating this procedure (k-1)-times, we get

(9)  
$$0 \leq \int_{u}^{v} a_{1}^{-1}(t_{1}) \int_{u}^{t_{1}} a_{2}^{-1}(t_{2}) \dots \int_{u}^{t_{k-1}} a_{k}^{-1}(t_{k}) Q_{k+1}(t_{k-1}, t_{k}) \mathrm{d}w_{k}$$
$$\cdot \int_{v}^{\infty} a_{n}^{-1}(s) G(s, |x(\varphi(s))|) \mathrm{d}s \leq L_{0}x(v)$$

for  $t_3 \leq u < v$ , where  $dw_k = dt_k dt_{k-1} \dots dt_1$ . Denote

(10) 
$$R_k(v,u) = \int_{u}^{v} a_1^{-1}(t_1) \int_{u}^{t_1} a_2^{-1}(t_2) \dots \int_{u}^{t_{k-1}} a_k^{-1}(t_k) Q_{k+1}(t_{k-1},t_k) \, \mathrm{d}w_k .$$

Then we have

(11) 
$$0 \leq R_k(v, u) \int_{v}^{\infty} a_n^{-1}(s) G(s, |x(\varphi(s))|) ds \leq L_0 x(v), t_3 \leq u < v.$$

The monotonicity of G and the properties of m(t) yield

(12)  
$$|L_0x(v)| \ge R_k(v,u) \int_{m(v)}^{\infty} a_n^{-1}(s)G(s, |x(\varphi(s))|) ds$$
$$= R_k(v,u) \int_{m(v)}^{\infty} a_n^{-1}(s)G(s, a_0^{-1}(\varphi(s)) |L_0x(\varphi(s))|) ds.$$

But  $|L_0 x(t)|$  is nondecreasing,  $\varphi(s) \ge v$  for  $s \ge m(v)$  and G(t, z) is nondecreasing in z. Therefore, (12) implies

(13) 
$$|L_0 \boldsymbol{x}(\boldsymbol{v})| \ge R_k(\boldsymbol{v},\boldsymbol{u}) \int_{\boldsymbol{m}(\boldsymbol{v})}^{\infty} a_n^{-1}(s) G(s, a_0^{-1}(\varphi(s)) |L_0 \boldsymbol{x}(\boldsymbol{v})|) \, \mathrm{d}s.$$

for  $t_3 \leq u < v$ . Once more by virtue of the monotonicity of G(t, z) we get

$$\int_{m(v)}^{\infty} a_n^{-1}(s) G(s, a_0^{-1}(\varphi(s)) | L_0 x(v) |) ds$$
  
$$\geqslant \int_{m(v)}^{\infty} a_n^{-1}(s) G(s, a_0^{-1}(\varphi(s)) R_k(v, u) \int_{m(v)}^{\infty} a_n^{-1}(\tau) G(\tau, a_0^{-1}(\varphi(\tau)) | L_0 x(v) |) d\tau ds.$$

Denote

(14) 
$$p(v) = \int_{m(v)}^{\infty} a_n^{-1}(s) G(s, a_0^{-1}(\varphi(s)) | L_0 x(v) |) ds$$

Then we have

(15) 
$$p(v) \ge \int_{m(v)}^{\infty} a_n^{-1}(s) G\left(s, a_0^{-1}(\varphi(s)) R_k(v, u) p(v)\right) \mathrm{d}s.$$

From (5) and (14) we obtain

$$|L_{n-1}x(m(v))| \ge \int_{m(v)}^{\infty} a_n^{-1}(s)G(s, |x(\varphi(s))|) ds$$
$$\ge \int_{m(v)}^{\infty} a_n^{-1}(s)G(s, a_0^{-1}(\varphi(s))|L_0x(v)|) ds = p(v) \ge 0$$

and

$$0 \leq \lim_{v \to \infty} p(v) \leq \lim_{v \to \infty} L_{n-1} x(m(v)) = 0.$$

Thus

(16) 
$$\lim_{v\to\infty}p(v)=0.$$

b) Let  $x(t) \in V_k$ , x(t) < 0 for  $T \ge t_3$ , k > 0. Then  $\operatorname{sgn} L_k x(t) = \operatorname{sgn} x(t) = -1$ and from (6) we get

$$0 \leqslant \int_{t}^{\infty} a_n^{-1}(s) Q_{k+1}(s,t) G(s, |(\varphi(s))|) \, \mathrm{d}s \leqslant -L_k x(t), \ t \geqslant t_3.$$

Similar considerations as in the case a) lead to the inequalities (13), (15) and equality (16).

Now we are able to prove the following theorems:

**Theorem 3.** Let all assumptions of Theorem 1 be satisfied. Moreover, assume that for every fixed  $t \ge t_0$ 

(17) 
$$z^{-1}G(t,z)$$
 is nondecreasing for  $z > 0$ ,

and for  $k \in \{1, 2, ..., n-1\}$ ,

(18) 
$$\lim_{v \to \infty} \sup R_{k}(v, u) \int_{m(v)}^{\infty} a_{n}^{-1}(s) c^{-1} G(s, a_{0}^{-1}(\varphi(s)) c) ds > 1$$

for some c > 0. Then the set  $V_k$  is empty.

Proof. Let  $x(t) \in V_k$ ,  $k \in \{1, 2, ..., n-1\}$ . Then  $\lim_{t \to \infty} |L_0 x(t)| = \infty$ . Therefore, for c > 0 there exists  $v_1 > u \ge t_3$  such that  $|L_0 x(v)| > c$  for all  $v > v_1$ . Then from (13) and (17) we obtain

$$1 \ge R_{k}(v,u) \int_{m(v)}^{\infty} a_{n}^{-1}(s)a_{0}^{-1}(\varphi(s)) \frac{G(s,a_{0}^{-1}(\varphi(s))c)}{a_{0}^{-1}(\varphi(s))c} ds,$$

which contradicts (18).

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**Theorem 4.** Let all assumptions of Theorem 1 be satisfied. Moreover, assume that for every fixed  $t \ge t_0$ 

(19) 
$$z^{-1}G(t,z)$$
 is nonincreasing for  $z > 0$ ,

and for  $k \in \{1, 2, ..., n-1\}$ 

(20) 
$$\lim_{v \to \infty} \sup \int_{m(v)}^{\infty} a_n^{-1}(s) c^{-1} G(s, R_k(v, u) a_0^{-1}(\varphi(s)) c) \, \mathrm{d}s > 1$$

for some c > 0. Then the set  $V_k$  is empty.

Proof. Let  $K \in \{1, 2, ..., n-1\}$  and  $x(t) \in V_k$ . Because  $\lim p(v) = 0$  as  $v \to \infty$  and p(v) > 0 for v > u, for c > 0 there exists  $v_2 \ge u \ge t_3$  such that c > p(v) for all  $v > v_2$ . Taking into account (15) and (19) we obtain

$$1 \ge \int_{m(v)}^{\infty} a_n^{-1}(s) a_0^{-1}(\varphi(s)) R_k(v, u) \frac{G(s, a_0^{-1}(\varphi(s)) R_k(v, u)c)}{a_0^{-1}(\varphi(s)) R_k(v, u)c} ds$$

for all  $v > v_2$ . This leads to a contradiction with (20).

**Definition 2.** We will say that the inclusion (E) has property A if, provided n is even, all solutions of (E) are oscillatory and, provided n is odd, each solution x(t) of (E) is either oscillatory or  $\lim L_i x(t) = 0$  as  $t \to \infty$  for i = 0, 1, ..., n - 1.

Definition 3. We will say that the inclusion (E) has property B if for n even each solution x(t) of (E) is either oscillatory or  $\lim L_i x(t) = 0$  as  $t \to \infty$  for  $i = 0, 1, \ldots, n-1$  or it belongs to the class  $V_n$ , i.e.  $\lim |L_i x(t)| = \infty$  as  $t \to \infty$  for  $i = 0, 1, \ldots, n-1$ , and for n odd each solution x(t) of (E) either is oscillatory or belongs to the class  $V_n$ .

Now, from the Theorems 1-4 we obtain the final theorem:

Theorem 5. Let all assumptions of Theorem 1 be satisfied.

a) If the assumptions  $1^{\circ}$ ,  $2^{\circ}$ ,  $3^{\circ}$  are satisfied and if (17) and (18) (or (19) and (20)) hold for k = 1, 2, ..., n - 1, then the inclusion (E) has property A.

b) If the assumptions  $1^{\circ}$ ,  $2^{\circ}$ ,  $4^{\circ}$  are satisfied and if (17) and (18) (or (19) and (20)) hold for k = 1, 2, ..., n - 1, then the inclusion (E) has property B.

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