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L^p -ESTIMATES FOR SOLUTIONS OF $\bar{\partial}$ -EQUATION ON STRONGLY q -CONVEX DOMAINS

O. ABDELKADER* — SH. KHIDR**

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ABSTRACT. The goal of this article is to construct a solution with L^p -estimates, $1 \leq p \leq \infty$, of the equation $\bar{\partial}g = f$ on strongly q -convex domain D of a Kähler manifold M , $f \in L^p_{r,s}(D, E)$, $s \geq q$, where E is a holomorphic line bundle over M satisfying a certain positivity conditions.

Introduction

The existence of solutions of the equation $\bar{\partial}g = f$ when f is a form of type $(0, s)$, $\bar{\partial}f = 0$, $s \geq 1$, and satisfies L^p -estimates, $1 \leq p \leq \infty$, has been a central theme in complex analysis for many years. On strongly pseudo-convex domains with C^4 -boundary in a Stein manifold, Kerzman [9] has obtained a solution with L^p -estimates, $1 \leq p \leq \infty$, for the equation $\bar{\partial}g = f$ when f is a complex valued form of type $(0, 1)$, $\bar{\partial}f = 0$, and satisfies L^p -estimates. On strongly pseudo-convex domains with C^2 -boundary in \mathbb{C}^n , Øvrelid [11] has generalized this results to $(0, s)$ -forms. Using Kerzman's method, Abdelkader [1] has extended Øvrelid's results to strongly pseudo-convex domains in an n -dimensional complex manifold for forms of type $(0, s)$ with values in a holomorphic positive line bundle and to complex valued forms of type (n, s) when the complex manifold is a Stein manifold. Abdelkader and Khidr [3] have extended Abdelkader's results to forms of type $(0, s)$ with values in a holomorphic vector bundle which is Nakano positive and to complex valued forms of type (r, s) , $0 \leq r \leq n$, when the complex manifold is a Stein manifold.

The local solvability of $\bar{\partial}g = f$ on strongly q -convex set when f is a complex valued form of type $(0, s)$, $\bar{\partial}f = 0$, $s \geq q$, is due to Andreotti and Grauert [5]. On strongly q -convex domains in \mathbb{C}^n , Ma [10] has obtained

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L^p -estimates, $1 \leq p \leq \infty$, for solution of $\bar{\partial}g = f$ when f is a complex valued form of type $(0, s)$, $\bar{\partial}f = 0$, $s \geq q$, and satisfies L^p -estimates.

In this paper, joining the results in [1] and [9] with those in [10], we extend the results of [1] to strongly q -convex domains and to forms of type (r, s) , $s \geq q$, with values in a semi-positive (semi-negative) line bundle. The main aim of this paper is to establish the following existence theorem with L^p -estimates:

THEOREM. *Let M be a Kähler manifold of complex dimension n and E be a holomorphic line bundle over M . Let D be a strongly q -convex domain of M . If E is semi-positive (resp. semi-negative) of type k on \bar{D} , then for any $f \in L^1_{r,s}(D, E)$, $\bar{\partial}f = 0$, $s \geq q$ and $r + s \geq n + k$ (resp. $s \geq q$ and $r + s \leq n - k$), there is a form $g = T^s f \in L^1_{r,s-1}(D, E)$ satisfying $\bar{\partial}g = f$, where T^s is a bounded linear operator. Moreover, if $f \in L^p_{r,s}(D, E)$, $1 \leq p \leq \infty$, there is a constant C_s such that $\|g\|_{L^p_{r,s-1}(D, E)} \leq C_s \|f\|_{L^p_{r,s}(D, E)}$. The constant C_s is independent of f and p . If f is C^∞ , then g is also C^∞ .*

The plan of this paper is as follows: In Section 1, we fix the notation and recall some useful facts. In Section 2, we prove an existence theorem with L^2 -estimates. In Section 3, we give local solution for the $\bar{\partial}$ -equation with L^p -estimates for $1 \leq p \leq \infty$. In Section 4, we prove the existence theorem with L^p -estimates.

1. Notation and preliminaries

From now on, M denotes a Kähler manifold of complex dimension n and let $\pi: E \rightarrow M$ be a holomorphic line bundle over M . Let $\{u_j\}$, $j \in I$, be an open covering of M consisting of coordinates neighborhoods u_j with holomorphic coordinates $z_j = (z_j^1, z_j^2, \dots, z_j^n)$ over which E is trivial, namely $\pi^{-1}(u_j) = u_j \times \mathbb{C}$. A Hermitian metric along the fibers of E is a system of positive C^∞ -functions $h = \{h_j\}$, each defined on u_j , such that $h_j = |e_{ij}|^2 h_i$ on $u_i \cap u_j$, where $\{e_{ij}\}$ is the system of transition functions of E . The curvature form associated to the metric h is defined by $\Theta = \{\Theta_j\}$, $\Theta_j = \sqrt{-1} \bar{\partial} \partial \log h_j = \sqrt{-1} \sum_{\alpha, \beta=1}^n \Theta_{j\alpha\bar{\beta}} dz_j^\alpha \wedge d\bar{z}_j^\beta$, where

$$\Theta_{j\alpha\bar{\beta}} = -\frac{\partial^2 \log h_j}{\partial z_j^\alpha \partial \bar{z}_j^\beta}.$$

Let $T(M)$ (resp. $T^*(M)$) be the holomorphic tangent (resp. cotangent) bundle of M .

DEFINITION 1.1.

i) E is said to be k -positive (resp. k -negative) at $x \in u_j$, if the form

$$\sum_{\alpha, \beta=1}^n \Theta_{j\alpha\bar{\beta}} \tag{1.1}$$

is a Hermitian form on $T_x(M)$ having at least $n - k + 1$ positive (resp. negative) eigenvalues.

- ii) E is said to be *semi-positive* (resp. *semi-negative*) at $x \in u_j$, if the form (1.1) is positive (resp. negative) semi-definite Hermitian form on $T_x(M)$.
- iii) E is said to be *semi-positive* (resp. *semi-negative*) of type k at x , if E is both semi-positive and k -positive (resp. semi-negative and k -negative) at x .

The notation $X \Subset M$ means that X is an open subset of M such that its closure is a compact subset of M .

DEFINITION 1.2. We say that $D \Subset M$ is *strongly q -convex*, $q \geq 1$, if there exist a neighborhood U of the boundary ∂D of D in M and a real-valued C^2 -function ρ with $d\rho(x) \neq 0$ on U such that $U \cap D = \{x \in U : \rho(x) < 0\}$, and its Levi form

$$L(\rho)(x) = \sum \frac{\partial^2 \rho(x)}{\partial z^\alpha \partial \bar{z}^\beta} \zeta^\alpha \bar{\zeta}^\beta, \quad \zeta = (\zeta^1, \zeta^2, \dots, \zeta^n) \in \mathbb{C}^n, \tag{1.2}$$

has at least $n - q + 1$ positive eigenvalues at each point $x \in U$. A function ρ satisfying (1.2) is called *strongly q -convex* at x .

Remark 1.3. By *shrinking* U we can assume that $U \Subset \tilde{U}$, where \tilde{U} is open and the Levi form (1.2) has at least $n - q + 1$ positive eigenvalues at each point $x \in \tilde{U}$. Thus ρ and its derivatives are bounded on U .

From now on, we assume that D is a strongly q -convex domain of M with ρ and U from Definition 1.2. We will use the standard notation of H ö r m a n d e r [6] for differential forms. Let $\Lambda^{r,s}(M, E)$ (resp. $\mathcal{D}^{r,s}(M, E)$) be the space of E -valued differential forms (resp. with compact support) of type (r, s) and of class C^∞ on M . A differential form $\varphi = \{\varphi_j\} \in \Lambda^{r,s}(M, E)$ can be expressed, on u_j , as $\varphi_j(z) = \sum_{A_r, B_s} \varphi_{jA_r B_s}(z) dz_j^{A_r} \wedge d\bar{z}_j^{B_s}$, where A_r and B_s are strictly increasing multi-indices with lengths r and s , respectively. We have the operator $\bar{\partial} : \Lambda^{r,s}(M, E) \rightarrow \Lambda^{r,s+1}(M, E)$, locally defined by:

$$\bar{\partial}\varphi_j(z) = \sum_{A_r, B_s} \sum_{k=1}^n \frac{\partial \varphi_{jA_r B_s}}{\partial \bar{z}_j^k}(z) d\bar{z}_j^k \wedge dz_j^{A_r} \wedge d\bar{z}_j^{B_s}.$$

Let

$$ds^2 = \sum_{\alpha, \beta=1}^n g_{j\alpha\bar{\beta}} dz_j^\alpha d\bar{z}_j^\beta,$$

be the Kähler metric defined on M .

For $\varphi, \psi \in \Lambda^{r,s}(M, E)$ we define a local inner product at $z \in u_j$ by

$$\frac{1}{h_j} \varphi_j(z) \wedge \star \overline{\psi_j(z)} = (\varphi(z), \psi(z)) dv, \tag{1.3}$$

where the Hodge star operator \star and the volume element dv are defined by ds^2 and (φ, ψ) is a C^∞ function on M independent of j . Let $\Lambda^{r,s}(\bar{D}, E)$ be the subspace of $\Lambda^{r,s}(D, E)$ whose elements can be extended smoothly up to ∂D , i.e.,

$$\Lambda^{r,s}(\bar{D}, E) = \{\varphi|_{\bar{D}} : \varphi \in \Lambda^{r,s}(M, E)\}.$$

For $\varphi, \psi \in \Lambda^{r,s}(\bar{D}, E)$, we define the inner product $\langle \varphi, \psi \rangle$ and the norm $\|\varphi\|$ with respect to ds^2 and h by:

$$\langle \varphi, \psi \rangle = \int_D (\varphi, \psi) dv, \quad \|\varphi\|^2 = \langle \varphi, \varphi \rangle. \tag{1.4}$$

Let $|f(z)| = \sqrt{(f(z), f(z))}$ for $f \in \Lambda^{r,s}(D, E)$ and $L^p_{r,s}(D, E)$ be the Banach space of forms f in $\Lambda^{r,s}(D, E)$ for which $\int_D |f(z)|^p dv < \infty$, $1 \leq p < \infty$, and $\text{ess sup}_{z \in D} |f(z)| < \infty$ for $p = \infty$. The norm on $L^p_{r,s}(D, E)$ is defined by

$$\|f\|_{L^p_{r,s}(D, E)} = \left(\int_D |f(z)|^p dv \right)^{1/p} \text{ for } 1 \leq p < \infty \text{ and by } \|f\|_{L^\infty_{r,s}(D, E)} = \text{ess sup}_{z \in D} |f(z)| \text{ for } p = \infty.$$

2. Existence theorems with L^2 -estimates

The L^2 completion of $\Lambda^{r,s}(D, E)$ with respect to the norm defined by (1.4) is denoted by $L^2_{r,s}(D, E)$. Let $\bar{\partial}: L^2_{r,s}(D, E) \rightarrow L^2_{r,s+1}(D, E)$ be the maximal closed extension of the original $\bar{\partial}$. A form $u \in L^2_{r,s}(D, E)$ is in the domain of $\bar{\partial}$ if $\bar{\partial}u$, defined in the sense of distributions, belongs to $L^2_{r,s+1}(D, E)$. Then $\bar{\partial}$ defines a linear closed, densely defined operator. From the general results of functional analysis, $\bar{\partial}$ admits a linear, closed and densely defined adjoint $\bar{\partial}^*: L^2_{r,s+1}(D, E) \rightarrow L^2_{r,s}(D, E)$, called the *Hilbert space adjoint* of $\bar{\partial}$, such that

$$\langle \varphi, \bar{\partial}\psi \rangle = \langle \bar{\partial}^*\varphi, \psi \rangle$$

for any $\psi \in \text{Dom}(\bar{\partial})$ and $\varphi \in \text{Dom}(\bar{\partial}^*)$.

Let

$$\square_{r,s} = \bar{\partial}\bar{\partial}^* + \bar{\partial}^*\bar{\partial}: \text{Dom}(\square_{r,s}) \rightarrow L^2_{r,s}(D, E),$$

be the Complex Laplacian operator of $\bar{\partial}: L^2_{r,s}(D, E) \rightarrow L^2_{r,s+1}(D, E)$, where

$$\begin{aligned} \text{Dom}(\square_{r,s}) = \{ \varphi \in L^2_{r,s}(D, E) : \varphi \in \text{Dom}(\bar{\partial}) \cap \text{Dom}(\bar{\partial}^*), \\ \bar{\partial}\varphi \in \text{Dom}(\bar{\partial}^*) \text{ and } \bar{\partial}^*\varphi \in \text{Dom}(\bar{\partial}) \}. \end{aligned}$$

Let $\mathcal{H}^{r,s}(D, E)$ be the space of harmonic forms of type (r, s) , i.e.,

$$\mathcal{H}^{r,s}(D, E) = \text{Ker}(\square_{r,s}) = \{ \alpha \in L^2_{r,s}(D, E) : \bar{\partial}\alpha = \bar{\partial}^*\alpha = 0 \}.$$

We define a linear operator

$$N_{r,s}: L^2_{r,s}(D, E) \rightarrow L^2_{r,s}(D, E)$$

as follows:

$$N_{r,s}\alpha = \begin{cases} 0 & \text{if } \alpha \in \text{Ker}(\square_{r,s}), \\ \phi & \text{if } \alpha \in \mathcal{R}(\square_{r,s}), \end{cases}$$

where $\mathcal{R}(\square_{r,s})$ is the range of $\square_{r,s}$ and ϕ is the unique solution of $\square_{r,s}\phi = \alpha$ with $\phi \perp \text{Ker}(\square_{r,s})$, and we extend $N_{r,s}$ by linearity. Let $H^{r,s}$ be the orthogonal projection of $L^2_{r,s}(D, E)$ onto $\mathcal{H}^{r,s}(D, E)$. For $s \geq q$, the operator $N_{r,s}$ satisfies the following theorem:

THEOREM 2.1. (cf. [8])

- (1) $N_{r,s}$ is a bounded operator;
- (2) for any $\alpha \in L^2_{r,s}(D, E)$, $\alpha = \bar{\partial}\bar{\partial}^*N_{r,s}\alpha + \bar{\partial}^*\bar{\partial}N_{r,s}\alpha + H^{r,s}\alpha$, and the dimension of $\mathcal{H}^{r,s}(D, E)$ is finite;
- (3) $N_{r,s}H^{r,s} = H^{r,s}N_{r,s} = 0$, $N_{r,s}\square_{r,s} = \square_{r,s}N_{r,s} = I - H^{r,s}$ on $\text{Dom}(\square_{r,s})$, and if $N_{r,s+1}$ is defined on $L^2_{r,s+1}(D, E)$ (resp. $N_{r,s-1}$ is defined on $L^2_{r,s-1}(D, E)$), then $N_{r,s+1}\bar{\partial} = \bar{\partial}N_{r,s}$ on $\text{Dom}(\bar{\partial})$ (resp. $N_{r,s-1}\bar{\partial}^* = \bar{\partial}^*N_{r,s}$ on $\text{Dom}(\bar{\partial}^*)$);
- (4) $N_{r,s}(\Lambda^{r,s}(\bar{D}, E)) \subset \Lambda^{r,s}(\bar{D}, E)$ and $H^{r,s}(\Lambda^{r,s}(\bar{D}, E)) \subset \Lambda^{r,s}(\bar{D}, E)$.

Let $\omega = \frac{1}{2}\sqrt{-1} \sum_{\alpha,\beta=1}^n g_{j\alpha\bar{\beta}} dz_j^\alpha \wedge d\bar{z}_j^\beta$ be the (1, 1) differential form associated

to the Kähler metric ds^2 on M . Let $e(\omega): \Lambda^{r,s}(M, E) \rightarrow \Lambda^{r+1,s+1}(M, E)$ be the linear mapping locally defined by $(e(\omega)\varphi_j) = \omega \wedge \varphi_j$ and $\Gamma: \Lambda^{r,s}(M, E) \rightarrow \Lambda^{r-1,s-1}(M, E)$ be the linear mapping locally defined by $\Gamma = (-1)^{r+s} \star e(\omega) \star$. On $\Lambda^{r,s}(D, E)$, we write \square and $h^{r,s}(D, E)$ for $\square_{r,s}$ and $\mathcal{H}^{r,s}(D, E)$ respectively. For $\varphi \in \Lambda^{r,s}(M, E)$, on Kähler manifolds, at any point, from classical differential geometry, we have the identity

$$((\square - \star^{-1}\square\star)\varphi, \varphi) = ((e(\Theta)\Gamma - \Gamma e(\Theta))\varphi, \varphi). \quad (2.1)$$

THEOREM 2.2. (cf. [4]) *Let M be a Kähler manifold of complex dimension n and E be a holomorphic line bundle over M . Let $D \Subset M$ be a strongly q -convex domain of M . If E is semi-positive (resp. semi-negative) of type k on \bar{D} , then we have $h^{r,s}(D, E) = 0$ for $r + s \geq n + k$ and $s \geq q$ (resp. $r + s \leq n - k$ and $s \geq q$).*

P r o o f. Firstly, we suppose that E is semi-positive of type k on \bar{D} . Then, from Definition 1.1, the matrix $(\Theta_{j\alpha\bar{\beta}})$ is positive semi-definite and of rank $\geq n - k + 1$ at any point of \bar{D} . Let $x_0 \in \bar{D}$ be an arbitrary fixed point and v_i , $i = 1, 2, \dots, n$, be the eigenvalues of $(\Theta_{\alpha\bar{\beta}})$ with respect to $(g_{\alpha\bar{\beta}})$ at x_0 , with $v_1 \geq v_2 \geq \dots \geq v_n \geq 0$. Then $m_1 = \inf_{x \in \bar{D}} v_{n-k+1}(x) > 0$. We define another Kähler metric

$$ds_1^2 = \sum_{\alpha, \beta=1}^n (g_{j\alpha\bar{\beta}} + \mu_1 \Theta_{j\alpha\bar{\beta}}) dz_j^\alpha d\bar{z}_j^\beta,$$

on a neighborhood of \bar{D} , where $\mu_1 > 0$. Let ω_1 be the differential form associated to ds_1^2 and $\Gamma_1: \Lambda^{r,s}(M, E) \rightarrow \Lambda^{r-1, s-1}(M, E)$ be the linear mapping defined by $\Gamma_1 = (-1)^{r+s} \star e(\omega_1) \star$. Let b be the rank of $(\Theta_{\alpha\bar{\beta}})$ at x_0 . Using (2.1), as [2; Lemma 1], we prove that at any point in \bar{D} , for $\varphi \in \Lambda^{r,s}(M, E)$, we have

$$((\Gamma_1 e(\Theta) - e(\Theta)\Gamma_1)\varphi)_{j\alpha_1\alpha_2\dots\alpha_r\bar{\beta}_1\bar{\beta}_2\dots\bar{\beta}_s} = h_j \Omega \varphi_{j\alpha_1\dots\alpha_r\bar{\beta}_1\dots\bar{\beta}_s}, \tag{2.2}$$

where

$$\begin{aligned} \Omega &= \sum_{i=1}^b \frac{v_i}{1 + \mu_1 v_i} - \sum_{i=1}^r \frac{v_{\alpha_i}}{1 + \mu_1 v_{\alpha_i}} - \sum_{i=1}^s \frac{v_{\beta_i}}{1 + \mu_1 v_{\beta_i}} \\ &= \frac{1}{\mu_1} \left(\sum_{i=1}^b \left(1 - \frac{1}{1 + \mu_1 v_i} \right) - \sum_{\alpha_i \leq b} \left(1 - \frac{1}{1 + \mu_1 v_{\alpha_i}} \right) - \sum_{\beta_i \leq b} \left(1 - \frac{1}{1 + \mu_1 v_{\beta_i}} \right) \right). \end{aligned}$$

Let $1 \leq \alpha_1 < \alpha_2 < \dots < \alpha_r \leq n$ (resp. $1 \leq \beta_1 < \beta_2 < \dots < \beta_s \leq n$) be fixed. Suppose that in the set $\{\alpha_1, \dots, \alpha_r\}$ (resp. $\{\beta_1, \dots, \beta_s\}$) there exists s_1 (resp. s_2) among the first b of the set $\{1, 2, 3, \dots, n\}$. Then, we have

$$\Omega \leq \frac{1}{\mu_1} \left(2b - s_1 - s_2 + \sum_{i=1}^{n-k+1} \frac{1}{1 + \mu_1 m_1} - (n - k + 1) \right).$$

But $r + s \geq n + k$ implies that $r - (n - b) + s - (n - b) \geq 2b - n + k$. Hence, there exist at least $2b - n + k$ of α_i and β_i among the first b of the set $\{1, 2, 3, \dots, n\}$. Therefore, $s_1 + s_2 \geq 2b - n + k$, i.e., $2b - s_1 - s_2 - (n - k + 1) \leq -1$. Then, for any fixed $\mu_1 \geq \frac{2n-1}{m_1}$, we have $\Omega \leq -1/2\mu_1$. Then from (2.2), at any point of \bar{D} , for $r + s \geq n + k$ we have

$$((\Gamma_1 e(\Theta) - e(\Theta)\Gamma_1)\varphi, \varphi) \leq -(1/2\mu_1)(\varphi, \varphi),$$

where the inner product (\cdot, \cdot) is defined by the metrics ds_1^2 and h . Therefore, from (2.1), we obtain

$$\begin{aligned} 0 &\leq \langle \star^{-1}\square_1 \star \varphi, \varphi \rangle = \langle (\Gamma_1 e(\Theta) - e(\Theta)\bar{\Gamma}_1)\varphi, \varphi \rangle \\ &\leq -(1/2\mu_1)\langle \varphi, \varphi \rangle \leq 0 \end{aligned}$$

for $\varphi \in h^{r,s}(D, E)$ with $r + s \geq n + k$ where $\square_1 = \bar{\partial}\bar{\partial}_1^* + \bar{\partial}_1^*\bar{\partial}$ and $\bar{\partial}_1^*$ is the formal adjoint of $\bar{\partial}$ when the inner product (\cdot, \cdot) is defined by ds_1^2 and h , i.e., $h^{r,s}(D, E) \cong 0$ for $r + s \geq n + k$.

Secondly, we suppose that E is semi-negative of type k on \bar{D} . Then, from Definition 1.1, the matrix $(\Theta_{j\alpha\bar{\beta}})$ is negative semi-definite and of rank $\geq n - k + 1$ at any point of \bar{D} . We define another Kähler metric

$$ds_2^2 = \sum_{\alpha, \beta=1}^n (g_{j\alpha\bar{\beta}} - \mu_2 \Theta_{j\alpha\bar{\beta}}) dz_j^\alpha d\bar{z}_j^\beta,$$

on a neighborhood of \bar{D} , where $\mu_2 > 0$. Let $x_0 \in D$ be an arbitrary fixed point and $\gamma_i, i = 1, 2, \dots, n$, be the eigenvalues of $(\Theta_{j\alpha\bar{\beta}})$ at x_0 with respect to $(g_{j\alpha\bar{\beta}})$ with $\gamma_1 \leq \gamma_2 \leq \dots \leq \gamma_n \leq 0$. Then $m_2 = \inf_{x \in \bar{D}} \gamma_{n-k+1} < 0$. As in the first case, if \square_2 is defined by ds_2^2 and h , we have

$$0 \leq \langle \star^{-1}\square_2 \star \varphi, \varphi \rangle \leq -(1/2\mu_2)\langle \varphi, \varphi \rangle \leq 0$$

for $\varphi \in h^{r,s}(D, E)$ with $r + s \leq n - k$ and $\mu_2 \geq (1 - 2n)/m_2$, i.e., $h^{r,s}(D, E) \cong 0$ for $r + s \leq n - k$. The proof is complete. \square

The boundedness of the operator $H^{r,s}$, [7; Proposition 1.2.3, Proposition 1.2.4] (as they are applied to [7; Proposition 2.1.1]) and Theorem 2.1 imply that $H^{r,s}(\Lambda^{r,s}(\bar{D}, E))$ is dense in the finite dimensional vector space $\mathcal{H}^{r,s}(D, E)$, $s \geq q$, with respect to the graph norm $(\|\varphi\|^2 + \|\bar{\partial}\varphi\|^2)^{\frac{1}{2}}$. Then $H^{r,s}(\Lambda^{r,s}(\bar{D}, E)) = \mathcal{H}^{r,s}(D, E)$, $s \geq q$. Therefore,

$$h^{r,s}(D, E) \cong \mathcal{H}^{r,s}(D, E) \quad s \geq q.$$

Hence, the image of the orthogonal projection operator $H^{r,s}$ is identically equal to zero, i.e.,

$$H^{r,s}\alpha = 0. \tag{2.3}$$

Form the above results, we prove the following existence theorem with L^2 -estimates:

THEOREM 2.3. *Let D be a strongly q -convex domain of an n -dimensional Kähler manifold M and $E \rightarrow M$ be a holomorphic line bundle over M . If E is semi-positive (resp. semi-negative) of type k on \bar{D} , then for any $\alpha \in L^2_{r,s}(D, E)$, $\bar{\partial}\alpha = 0$, $s \geq q$ and $r + s \geq n + k$ (resp. $s \geq q$ and $r + s \leq n - k$), there is a unique form $\phi \in L^2_{r,s-1}(D, E)$ satisfying $\bar{\partial}\phi = \alpha$ with $\phi \perp \text{Ker}(\bar{\partial})$, and the estimate*

$$\|\phi\|_{L^2_{r,s-1}(E,D)} \leq C\|\alpha\|_{L^2_{r,s}(E,D)}$$

holds. If α is C^∞ , then ϕ is also C^∞ .

Proof. Using (3) of Theorem 2.1 and the condition on α , $\bar{\partial}\alpha = 0$, we have $\bar{\partial}N_{r,s}\alpha = N_{r,s+1}\bar{\partial}\alpha = 0$. Using (2.3) in (2) of Theorem 2.1 we obtain $\alpha = \bar{\partial}\bar{\partial}^*N_{r,s}\alpha$. Therefore we may take $\phi = \bar{\partial}^*N_{r,s}\alpha$, the condition $\phi \perp \text{Ker}(\bar{\partial})$ clearly implies the uniqueness. Moreover, if α is C^∞ , then so is $N_{r,s}\alpha$, hence ϕ is C^∞ . Using (2.3) in (3) of Theorem 2.1 and the fact that $N_{r,s}$ is bounded we have the following L^2 -estimate:

$$\begin{aligned} \|\phi\|_{L^2_{r,s-1}(D,E)}^2 &= \langle \bar{\partial}^*N_{r,s}\alpha, \bar{\partial}^*N_{r,s}\alpha \rangle = \langle \bar{\partial}\bar{\partial}^*N_{r,s}\alpha, N_{r,s}\alpha \rangle \\ &= \langle (\bar{\partial}\bar{\partial}^* + \bar{\partial}^*\bar{\partial})N_{r,s}\alpha, N_{r,s}\alpha \rangle \\ &= \langle \alpha, N_{r,s}\alpha \rangle \leq \|\alpha\|_{L^2_{r,s}(D,E)}\|N_{r,s}\alpha\|_{L^2_{r,s}(D,E)} \\ &\leq C\|\alpha\|_{L^2_{r,s}(D,E)}^2 \end{aligned}$$

This proves the theorem. □

Theorem 2.3 is needed in the course of the proof of Theorem 4.3.

3. Local solution for the $\bar{\partial}$ -equation with L^p -estimates

We consider the following situation: Let D be a strongly q -convex domain of M and $W_\delta = W(\zeta_0, \delta)$ be the open ball in M of an arbitrary fixed center $\zeta_0 \in \partial D$ and radius δ such that $W_\delta \Subset u_j \subset V \Subset U$ for a certain $j \in I$, where δ is a positive constant which depends continuously on the distance $d(\zeta_0, CV)$ from ζ_0 to the complement of V . Then, according to [10] and the fact that every E -valued form is a \mathbb{C} -valued form on W_δ , there exist an open set D_{ζ_0} and a linear operator

$$T^s : L^1_{0,s}(D_{\zeta_0}, E) \rightarrow L^1_{0,s-1}(W_{\delta/2} \cap D, E), \quad s \geq q,$$

with $W_{\delta/2} \cap D \subset D_{\zeta_0} \subset W_\delta \cap D$ and

$$f = T^{s+1}(\bar{\partial}f) + \bar{\partial}T^s f$$

for $f \in L^1_{0,s}(D_{\zeta_0}, E)$ with $\bar{\partial}f \in L^1_{0,s+1}(D_{\zeta_0}, E)$. Moreover, if $f \in L^p_{0,s}(D_{\zeta_0})$, $\bar{\partial}f = 0$, then there is a constant C such that the estimate $\|T^s f\|_{L^p_{0,s-1}(W_{\delta/2} \cap D)} \leq C\|f\|_{L^p_{0,s}(D_{\zeta_0})}$ holds. Then using Kerzman's techniques, [9; Theorem 1.3.1], as [1] and [3] we can prove the following theorem:

THEOREM 3.1 (LOCAL THEOREM). *Let T^s be the operator which is defined above and $f \in L^1_{0,s}(D_{\zeta_0}, E)$, $\bar{\partial}f = 0$, $s \geq q$. Then, there is $g = T^s f \in L^1_{0,s-1}(W_{\delta/2} \cap D, E)$ such that $\bar{\partial}g = f$. If f is C^∞ , then so is g . If $f \in L^p_{0,s}(D_{\zeta_0}, E)$, then $g \in L^p_{0,s-1}(W_{\delta/2} \cap D, E)$ and satisfies*

$$\|g\|_{L^p_{0,s-1}(W_{\delta/2} \cap D, E)} \leq C\|f\|_{L^p_{0,s}(D_{\zeta_0}, E)}, \quad 1 \leq p \leq \infty,$$

where $C = C(s)$ is a constant independent of f and p .

Using Theorem 3.1 (Local theorem), as [1] and [3], we can prove the following lemma:

LEMMA 3.2 (AN EXTENSION LEMMA). *Let $D \Subset M$ be a strongly q -convex domain. Then, there exists (slightly larger) open set $\hat{D} \Subset M$ with the following properties: $\bar{D} \Subset \hat{D}$; for any $f \in L^1_{0,s}(D, E)$ with $\bar{\partial}f = 0$ and $s \geq q$, there exist two bounded linear operators L_1, L_2 , a form $\hat{f} = L_1 f \in L^1_{0,s}(\hat{D}, E)$ and a form $u = L_2 f \in L^1_{0,s-1}(D, E)$ such that:*

- (i) $\bar{\partial}\hat{f} = 0$ in \hat{D} .
- (ii) $\hat{f} = f - \bar{\partial}u$ in D .
- (iii) If $f \in L^p_{0,s}(D, E)$, then $\hat{f} \in L^p_{0,s}(\hat{D}, E)$ and $u \in L^p_{0,s-1}(D, E)$ with the estimates

$$\|\hat{f}\|_{L^p_{0,s}(\hat{D}, E)} \leq C_1\|f\|_{L^p_{0,s}(D, E)}$$

and

$$\|u\|_{L^p_{0,s-1}(D, E)} \leq C_2\|f\|_{L^p_{0,s}(D, E)}, \quad 1 \leq p \leq \infty,$$

where the constants C_1 and C_2 are independent of f and p . If f is C^∞ in D , then \hat{f} is C^∞ in \hat{D} and u is C^∞ in D .

4. Global solution for the $\bar{\partial}$ -equation with L^p -estimates

Recall that ∂D is defined by a function $\rho: U \rightarrow \mathbb{R}$. Cover ∂D by finitely many balls $W_{i,\delta_i} = W(x_i, \delta_i)$, $x_i \in \partial D$, $i = 1, \dots, m$, such that for each $x_i \in \partial D$ we have $W_{i,\delta_i} \Subset u_j \subset V \Subset U$. Put $\delta = \min_{1 \leq i \leq m} \delta_i$. Then as in [9; p. 321, Lemma 2.3.3, Claim] (see also [1; Proposition 3.2]), we can prove the following proposition:

PROPOSITION 4.1. *Let \hat{D} be as in the extension lemma and let $W_{i,\delta}$ be as above such that $W_{i,\delta} \Subset u_j \subset \hat{D}$ for a certain $j \in I$. Then, for any $f \in L^1_{0,s}(W_{i,\delta}, E)$, $\bar{\partial}f = 0$, $s \geq q$, there exists $\alpha = Tf \in L^1_{0,s-1}(W_{i,\delta/2}, E)$ such that $\bar{\partial}\alpha = f$, where T is a bounded linear operator. If $f \in L^p_{0,s}(W_{i,\delta}, E)$, $1 \leq p \leq 2$, then we have $\alpha \in L^{p+1/4n}_{0,s-1}(W_{i,\delta/2}, E)$ and $\|\alpha\|_{L^{p+1/4n}_{0,s-1}(W_{i,\delta/2}, E)} \leq c\|f\|_{L^p_{0,s}(W_{i,\delta}, E)}$ and for any p , $1 \leq p \leq \infty$, we have*

$$\|\alpha\|_{L^p_{0,s-1}(W_{i,\delta/2}, E)} \leq c\|f\|_{L^p_{0,s}(W_{i,\delta}, E)},$$

where $c = c(n, a)$ is a constant independent of f and p .

Using Proposition 4.1 as [1; Proposition 3.2], we prove the following proposition:

PROPOSITION 4.2. *Let \hat{D} be as in the extension lemma. Then, there exists a strongly q -convex domain $D_1 \Subset \hat{D}$ such that for every $\hat{f} \in L^1_{0,s}(\hat{D}, E)$, $\bar{\partial}\hat{f} = 0$, $s \geq q$, there are two bounded linear operators L_1 and L_2 and two forms $f_1 = L_1\hat{f} \in L^1_{0,s}(D_1, E)$ and $\eta_1 = L_2\hat{f} \in L^1_{0,s-1}(D_1, E)$ such that:*

- (i) $\bar{\partial}f_1 = 0$ on D_1 .
- (ii) $\hat{f} = f_1 + \bar{\partial}\eta_1$ on D_1 .
- (iii) $\|f_1\|_{L^{p+1/4n}_{0,s}(D_1, E)} \leq c\|\hat{f}\|_{L^p_{0,s}(\hat{D}, E)}$ for $\hat{f} \in L^p_{0,s}(\hat{D}, E)$, $1 \leq p \leq 2$.
- (iv) For every open set $W \Subset D_1$ and for every p , $1 \leq p \leq \infty$, we have

$$\|f_1\|_{L^p_{0,s}(W, E)} \leq c\|\hat{f}\|_{L^p_{0,s}(\hat{D}, E)},$$

and

$$\|\eta_1\|_{L^p_{0,s-1}(W, E)} \leq c\|\hat{f}\|_{L^p_{0,s}(\hat{D}, E)},$$

where $c = c(\hat{D}, W, n)$ is a constant independent of \hat{f} and p .

The solvability with L^2 -estimates for $\bar{\partial}u = f$ on D_1 follows from Theorem 2.2 and Theorem 2.3.

Using Theorem 2.3, Proposition 4.2 and the interior regularity properties of the $\bar{\partial}$ -operator, as [1; Theorem 3.1], we can prove the following theorem:

THEOREM 4.3. *Let \hat{D} be the strongly q -convex domain of the extension lemma and $W \Subset \hat{D}$. Then, for any form $\hat{f} \in L^1_{0,s}(\hat{D}, E)$ with $\bar{\partial}\hat{f} = 0$, $s \geq q$, there exists a form $\eta \in L^1_{0,s-1}(W, E)$, $\eta = L\hat{f}$, such that $\bar{\partial}\eta = \hat{f}$, where L is a bounded linear operator. If $\hat{f} \in L^p_{0,s}(\hat{D}, E)$ with $1 \leq p \leq \infty$, then*

$$\eta \in L^p_{0,s-1}(W, E) \quad \text{and} \quad \|\eta\|_{L^p_{0,s-1}(W, E)} \leq C\|\hat{f}\|_{L^p_{0,s}(\hat{D}, E)},$$

where $C = C(\hat{D}, W)$ is a constant independent of \hat{f} and p . If \hat{f} is C^∞ , then η is C^∞ .

The idea of the proof of Theorem 4.3 is as follows:

If $p \geq 2$, Theorem 4.3 is an immediate consequence of the fact that $L^p_{0,s}(\hat{D}, E) \subseteq L^2_{0,s}(\hat{D}, E)$, that there exists a solution $u \in L^2_{0,s-1}(\hat{D}, E)$ of $\bar{\partial}u = f$ (if $f \in L^p_{0,s}(\hat{D}, E)$, $\bar{\partial}f = 0$) and the interior regularity properties for solutions of elliptic $\bar{\partial}$ operator. If $1 \leq p < 2$, then the problem of solving $\bar{\partial}u = f$ can be changed into one (in a smaller region) involving a form $f_1 \in L^\tau_{0,s}(D_1, E)$, $\tau > p$; this is the case in which Proposition 4.2 is used. The improvement of the exponent is small, but iterating $4n$ times, we finally obtain a form $f_{4n} \in L^2_{0,s}(D_{4n}, E)$ to which Theorem 2.3 can be applied.

Using Lemma 3.2, Theorem 4.3 and Theorem 2.3 we obtain our results.

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