

Irena Hinterleitner; Josef Mikeš

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*Archivum Mathematicum*, Vol. 49 (2013), No. 5, 295--302

Persistent URL: <http://dml.cz/dmlcz/143553>

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# ON HOLOMORPHICALLY PROJECTIVE MAPPINGS FROM MANIFOLDS WITH EQUIAFFINE CONNECTION ONTO KÄHLER MANIFOLDS

IRENA HINTERLEITNER AND JOSEF MIKEŠ

**ABSTRACT.** In this paper we study fundamental equations of holomorphically projective mappings from manifolds with equiaffine connection onto (pseudo-) Kähler manifolds with respect to the smoothness class of connection and metrics. We show that holomorphically projective mappings preserve the smoothness class of connections and metrics.

## 1. INTRODUCTION

T. Otsuki and Y. Tashiro [23] introduced the concept of holomorphically projective mappings of Kähler manifolds which preserve the complex structure, and which are generalizations of geodesic mappings. These mappings are studied in many directions, see [2]–[29]. On the other hand, issues related to the mappings and almost complex structures are found in [3, 4, 6, 15, 22, 23, 24, 26, 29].

Fundamental equations for holomorphically projective mappings of (pseudo-) Kähler manifolds in a linear form were found by Domashev and Mikeš [5, 16, 18], see [26, pp. 210–220], [22, pp. 245–248]. In [7] I. Hinterleitner studied holomorphically projective mappings between  $e$ -Kähler manifolds in detail. It was shown that they preserve the smoothness class  $C^r$  ( $r \geq 2$ ) of the metric.

In the papers [1, 19] research on holomorphically projective mappings from manifolds with affine connections onto (pseudo-) Kähler manifolds was initiated.

In our paper, we present some new results obtained for holomorphically projective mappings from  $n$ -dimensional manifolds  $A_n$  with equiaffine connection  $\nabla$  and with covariantly almost constant structure  $F$  onto (pseudo-) Kähler manifolds  $\bar{K}_n$  with metric  $\bar{g}$  and with structure  $\bar{F}$  from the point of view of differentiability of affine connections and metrics. Here we refine the results of [7, 1, 19]:

*If  $A_n \in C^{r-1}$  ( $r \geq 2$ ) admits holomorphically projective mappings onto  $\bar{K}_n \in C^2$ , then  $\bar{K}_n \in C^r$ .*

Here  $A_n \in C^{r-1}$  and  $\bar{K}_n \in C^r$  denotes that  $\nabla \in C^{r-1}$  and  $\bar{g} \in C^r$ , which means that in a common coordinate system  $x = \{x^1, x^2, \dots, x^n\}$  their components

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2010 *Mathematics Subject Classification*: primary 53B20; secondary 53B21, 53B30, 53B35, 53C26.

*Key words and phrases*: holomorphically projective mapping, smoothness class, Kähler manifold, manifold with affine connection, fundamental equation.

DOI: 10.5817/AM2013-5-295

$\Gamma_{ij}^h(x) \in C^{r-1}$  and  $\bar{g}_{ij}(x) \in C^r$ , respectively. We suppose that the differentiability degree  $r$  is equal to  $0, 1, 2, \dots, \infty, \omega$ , where  $0, \infty$  and  $\omega$  denotes continuous, infinitely differentiable, and real analytic functions, respectively.

The connection  $\nabla$  of  $A_n$ , as it is known, need not be the Levi-Civita connection of any metric and  $A_n$  need not be a (pseudo-) Riemannian manifold, i.e. there need not be a metric, see [6].

## 2. DEFINITIONS AND BASIC RESULTS OF $F$ -PLANAR MAPPINGS

In [1, 19] were studied holomorphically projective mappings from manifolds  $A_n$  with affine connection onto Kähler manifolds  $\bar{K}_n$ , which are special cases of  $F$ -planar mappings (Mikeš and Sinyukov [21], see [8, 17], [22, p. 213–238]).

We consider an  $n$ -dimensional manifold  $A_n$  with a torsion-free affine connection  $\nabla$ , and an affiner structure  $F$ , i.e. a tensor field of type  $(1, 1)$ .

**Definition 1** (Mikeš, Sinyukov [21], see [22, p. 213]). A curve  $\ell$ , which is given by the equations  $\ell = \ell(t)$ ,  $\lambda(t) = d\ell(t)/dt$  ( $\neq 0$ ),  $t \in I$ , where  $t$  is a parameter, is called  $F$ -planar, if its tangent vector  $\lambda(t_0)$ , for any initial value  $t_0$  of the parameter  $t$ , remains, under parallel translation along the curve  $\ell$ , in the distribution generated by the vector functions  $\lambda$  and  $F\lambda$  along  $\ell$ .

In accordance with this definition,  $\ell$  is  $F$ -planar, if and only if the following condition holds ([21], see [22, p. 213]):  $\nabla_{\lambda(t)}\lambda(t) = \varrho_1(t)\lambda(t) + \varrho_2(t)F\lambda(t)$ , where  $\varrho_1$  and  $\varrho_2$  are some functions of the parameter  $t$ .

We suppose two spaces  $A_n$  and  $\bar{A}_n$  with torsion-free affine connection  $\nabla$  and  $\bar{\nabla}$ , respectively. Affine structures  $F$  and  $\bar{F}$  are defined on  $A_n$ , resp.  $\bar{A}_n$ .

**Definition 2** (Mikeš, Sinyukov [21], see [22, p. 213]). A diffeomorphism  $f$  between manifolds with affine connection  $A_n$  and  $\bar{A}_n$  is called an  $F$ -planar mapping if any  $F$ -planar curve in  $A_n$  is mapped onto an  $\bar{F}$ -planar curve in  $\bar{A}_n$ .

Due to the diffeomorphism  $f$  we always suppose that  $\nabla$ ,  $\bar{\nabla}$ , and the affiners  $F$ ,  $\bar{F}$  are defined on  $M$  where  $A_n = (M, \nabla, F)$  and  $\bar{A}_n = (M, \bar{\nabla}, \bar{F})$ . The following holds.

**Theorem 1.** *An  $F$ -planar mapping  $f$  from  $A_n$  onto  $\bar{A}_n$  preserves  $F$ -structures (i.e.  $\bar{F} = aF + b \text{Id}$ ,  $a, b$  are some functions), and is characterized by the following condition*

$$(1) \quad P(X, Y) = \psi(X) \cdot Y + \psi(Y) \cdot X + \varphi(X) \cdot FY + \varphi(Y) \cdot FX$$

for any vector fields  $X, Y$ , where  $P = \bar{\nabla} - \nabla$  is the deformation tensor field of  $f$ ,  $\psi$  and  $\varphi$  are some linear forms.

This theorem was proved by Mikeš and Sinyukov [21] for finite dimension  $n > 3$ , a more concise proof of this theorem for  $n > 3$  and also a proof for  $n = 3$  was given by I. Hinterleitner and Mikeš [8], see [22, p. 214].

We introduce the following classes of  $F$ -planar mappings from manifolds  $A_n$  with affine connection  $\nabla$  onto (pseudo-) Riemannian manifolds  $\bar{V}_n$  with metric  $\bar{g}$ :

**Definition 3** (Mikeš [17], see [22, p. 225]).

1. An  $F$ -planar mapping of a manifold  $A_n$  with affine connection onto a (pseudo-) Riemannian manifold  $\bar{V}_n$  is called an  $F_1$ -planar mapping if the metric tensor satisfies the condition

$$(2) \quad \bar{g}(X, FX) = 0, \quad \text{for all } X.$$

2. An  $F_1$ -planar mapping  $A_n \rightarrow \bar{V}_n$  is called an  $F_2$ -planar mapping if the one-form  $\psi$  is gradient-like, i.e.

$$(3) \quad \psi(X) = \nabla_X \Psi,$$

where  $\Psi$  is a function on  $A_n$ .

3. An  $F_1$ -planar mapping  $A_n \rightarrow \bar{V}_n$  is called an  $F_3$ -planar mapping if the one-forms  $\psi$  and  $\varphi$  are related by

$$(4) \quad \psi(X) = \varphi(FX).$$

**Remark.**  $F$ -planar curves and  $F_1$ -planar mappings are a generalization of quasi-geodesic curves, resp. mappings by A. Z. Petrov [24], which he used for space-times.

### 3. DEFINITIONS AND BASIC RESULTS OF HOLOMORPHICALLY PROJECTIVE MAPPINGS ONTO KÄHLER MANIFOLDS

(Pseudo-) Kähler manifolds were first considered by P.A. Shirokov and independently these manifolds were studied by E. Kähler, see [22, p. 68].

**Definition 4.** A (pseudo-) Riemannian manifold  $\bar{K}_n = (M, \bar{g}, \bar{F})$  is called a (pseudo-) Kähler manifold if beside the tensor  $\bar{g}$ , a tensor field  $\bar{F}$  of type (1,1) is given on  $M$ , such that the following conditions hold:

$$(5) \quad (a) \quad \bar{F}^2 = -\text{Id}, \quad (b) \quad \bar{g}(X, \bar{F}X) = 0 \text{ for all } X, \quad (c) \quad \bar{\nabla} \bar{F} = 0.$$

We remark that the formulas (1) – (4) hold for holomorphically projective mappings between (pseudo-) Kähler manifolds, see [4, 5, 16, 18, 22, 26]. For this reason we give the following definition

**Definition 5.** An  $F$ -planar mapping  $A_n$  onto a Kähler manifold  $\bar{K}_n$  is called a holomorphically projective mapping, if it is  $F_3$ -planar.

By analysis of formulas (4) and (5c) we find that  $\nabla \bar{F} = 0$ . After differentiation of (5a), using (5c), and  $\bar{F} = aF + b\text{Id}$  (see Theorem 1), we find that  $\bar{F} = \pm F$ . Thus the following theorem holds.

**Theorem 2.** If  $A_n = (M, \nabla, F)$  admits holomorphically projective mappings onto a (pseudo-) Kähler manifold  $\bar{K}_n = (M, \bar{g}, \bar{F})$ , then  $\bar{F} = \pm F$  and the structure  $F$  is a covariantly constant almost complex structure, i.e.  $F^2 = -\text{Id}$  and  $\nabla F = 0$ .

From formulas (4) and (5a) follows that for holomorphically projective mappings  $f: A_n \rightarrow \bar{K}_n$ :

$$\varphi(X) = -\psi(FX) \quad \text{for all } X.$$

From Theorem 2 and formulas (1), (5b) follows the following theorem.

**Theorem 3.** *Let  $A_n = (M, \nabla, F)$  be a manifold  $M$  with affine connection  $\nabla$  and with a covariantly constant complex structure  $F$ . A diffeomorphism  $f$  from  $A_n$  onto a Kähler manifold  $\bar{K}_n = (M, \bar{g}, F)$  is a holomorphically projective mapping if and only if*

$$(6) \quad \begin{aligned} & \text{a) } P(X, Y) = \psi(X) \cdot Y + \psi(Y) \cdot X - \psi(FX) \cdot FY - \psi(FY) \cdot FX; \\ & \text{b) } \bar{g}(FX, FX) = g(X, X), \end{aligned}$$

holds for any  $X, Y$ , where  $P = \bar{\nabla} - \nabla$  is the deformation tensor field of  $f$ ,  $\psi$  is a linear form.

In local notation formulas (6) have the following form:

$$(7) \quad \begin{aligned} & \text{a) } \bar{\Gamma}_{ij}^h(x) = \Gamma_{ij}^h(x) + \delta_i^h \psi_j + \delta_j^h \psi_i - \delta_i^h \psi_{\bar{j}} - \delta_j^h \psi_{\bar{i}}, \quad \text{b) } \bar{g}_{\bar{i}\bar{j}} = g_{ij}, \end{aligned}$$

where  $\Gamma_{ij}^h, \bar{\Gamma}_{ij}^h, \bar{g}_{ij}, \psi_i$  and  $F_i^h$  are the components of  $\nabla, \bar{\nabla}, \bar{g}, \psi$  and  $F$ , respectively. Here and in the following we will use the conjugation operation of indices in the way

$$A_{\dots \bar{i} \dots} = A_{\dots \alpha \dots} F_i^\alpha \quad \text{and} \quad A_{\dots \bar{i} \dots} = A_{\dots \alpha \dots} F_\alpha^i.$$

Equations (7) are equivalent to the equations

$$(8) \quad \begin{aligned} & \text{a) } \nabla_k \bar{g}_{ij} = 2\psi_k \bar{g}_{ij} + \psi_i \bar{g}_{jk} + \psi_j \bar{g}_{ik} + \psi_{\bar{i}} \bar{g}_{\bar{j}k} + \psi_{\bar{j}} \bar{g}_{\bar{i}k}, \quad \text{b) } \bar{g}_{\bar{i}\bar{j}} = g_{ij}. \end{aligned}$$

After contraction of (7) we obtain  $\psi_i = \frac{1}{n+2} (\partial_i \sqrt{|\det \bar{g}|} - \Gamma_{\alpha i}^\alpha)$ , where  $\partial_i = \frac{\partial}{\partial x^i}$ .

Moreover, if  $\nabla$  is an equiaffine connection ([6], [22, p. 35]) then a function  $G$  exists for which  $\Gamma_{\alpha i}^\alpha = \partial_i G$ . In this case

$$(9) \quad \psi_i = \partial_i \Psi, \quad \Psi = \frac{1}{n+2} (\sqrt{|\det \bar{g}|} - G).$$

Because the holomorphically projective mapping is  $F_3$ -planar, after elementary modifications we have the following theorem ([17], [22]):

**Theorem 4.** *Let  $A_n$  be a manifold with an equiaffine connection which satisfies the assumption of Theorem 3. A manifold  $A_n$  admits holomorphically projective mappings onto  $\bar{K}_n$  if and only if a regular symmetric tensor  $a^{ij}$  and a vector  $\lambda^i$  satisfy the following equations:*

$$(10) \quad \begin{aligned} & \text{a) } \nabla_k a^{ij} = \lambda^i \delta_k^j + \lambda^j \delta_k^i + \lambda^{\bar{i}} \delta_k^{\bar{j}} + \lambda^{\bar{j}} \delta_k^{\bar{i}}, \quad \text{b) } a^{\bar{i}\bar{j}} = a^{ij}. \end{aligned}$$

From equations (8) we obtain (10) by the relations

$$a^{ij} = e^{-2\Psi} \bar{g}^{ij}, \quad \lambda^i = -e^{-2\Psi} \bar{g}^{i\alpha} \psi_\alpha,$$

where  $\|\bar{g}^{ij}\| = \|\bar{g}_{ij}\|^{-1}$ . On the other hand from equations (10) we obtain (8) by the relations

$$\bar{g}^{ij} = e^{2\Psi} a^{ij}, \quad \Psi = \ln \sqrt{|\det \bar{g}|} - G, \quad \|\bar{g}_{ij}\| = \|a^{ij}\|^{-1}.$$

Evidently, the results of Section 3 hold if

$$A_n = (M, \nabla, F) \in C^0 \quad (\Gamma_{ij}^h(x) \in C^0, F_i^h(x) \in C^1)$$

and

$$\bar{K}_n = (M, \bar{g}, F) \in C^1 \quad (\bar{g}_{ij}(x) \in C^1).$$

4. HOLOMORPHICALLY PROJECTIVE MAPPINGS FROM  $A_n \in C^1$   
 ONTO  $\bar{K}_n \in C^2$

Let  $A_n = (M, \nabla, F)$  be a manifold  $M$  with an equiaffine connection  $\nabla$  and with a covariantly constant complex structure  $F$  and let  $A_n$  admit a holomorphically projective mapping onto the Kähler manifold  $\bar{K}_n = (M, \bar{g}, F)$ . We suppose that

$$A_n \in C^1 \quad (\Gamma_{ij}^h(x) \in C^1, F_i^h(x) \in C^1) \quad \text{and} \quad \bar{K}_n \in C^2 \quad (\bar{g}_{ij}(x) \in C^2).$$

From  $\nabla_j F_i^h = 0$  it follows that  $F_i^h \in C^2$  and its integrability condition has the form  $R_{ijk}^{\bar{h}} = R_{ij\bar{k}}^h$ , where  $R_{ijk}^h$  is the curvature tensor on  $A_n$ .

We shall investigate the integrability condition of equation (10). Let us differentiate it covariantly by  $x^l$  and then alternate it w.r. to the indices  $k$  and  $l$ . From the Ricci identity we find the following:

$$(11) \quad \nabla_l \lambda^i \delta_k^j + \nabla_l \lambda^j \delta_k^i - \nabla_k \lambda^i \delta_l^j - \nabla_k \lambda^j \delta_l^i + \nabla_l \lambda^{\bar{i}} \delta_k^{\bar{j}} + \nabla_l \lambda^{\bar{j}} \delta_k^{\bar{i}} - \nabla_k \lambda^{\bar{i}} \delta_l^{\bar{j}} - \nabla_k \lambda^{\bar{j}} \delta_l^{\bar{i}} = -a^{\alpha i} R_{\alpha k l}^j - a^{\alpha j} R_{\alpha k l}^i.$$

Contracting (11) by the indices  $j$  and  $k$ , we obtain

$$(12) \quad (n - 1) \nabla_l \lambda^i - \nabla_{\bar{l}} \lambda^{\bar{i}} = \mu \cdot \delta_l^i + \nabla_{\alpha} \lambda^{\bar{\alpha}} \cdot \delta_l^{\bar{i}} - a^{\alpha i} R_{\alpha l} - a^{\alpha \beta} R_{\alpha \beta l}^i,$$

where  $\mu \stackrel{\text{def}}{=} \nabla_{\alpha} \lambda^{\alpha}$ ,  $R_{ij} \stackrel{\text{def}}{=} R_{i\alpha j}^{\alpha}$  is the Ricci tensor, which is symmetric for the equiaffine connection  $\nabla$ .

When we contract (12) with  $F_i^l$  and then use properties of the Riemann and the Ricci tensors, we can see  $\nabla_{\alpha} \lambda^{\bar{\alpha}} = 0$ . We apply the conjugation operation bar on the indices  $i$  and  $l$ , and subtract (12) from the result. After some calculations we have

$$n \cdot (\nabla_{\bar{l}} \lambda^{\bar{i}} - \nabla_l \lambda^i) = (a^{\alpha i} R_{\alpha l} + a^{\alpha \beta} R_{\alpha \beta l}^i) - (a^{\alpha \bar{i}} R_{\alpha \bar{l}} + a^{\alpha \beta} R_{\alpha \beta \bar{l}}^{\bar{i}}),$$

and from (12) we find

$$(13) \quad n \nabla_l \lambda^i = \mu \delta_l^i - a^{\alpha \beta} T_{l\alpha\beta}^i,$$

where

$$T_{l\alpha\beta}^i \stackrel{\text{def}}{=} \frac{n - 1}{n} (\delta_{\beta}^i R_{\alpha l} + R_{\alpha \beta l}^i) + \frac{1}{n} (\delta_{\beta}^{\bar{i}} R_{\alpha \bar{l}} + R_{\alpha \beta \bar{l}}^{\bar{i}}).$$

5. HOLOMORPHICALLY PROJECTIVE MAPPINGS FROM  $A_n \in C^r$  ( $r \geq 2$ )  
 ONTO  $\bar{K}_n \in C^2$

Let  $A_n = (M, \nabla, F)$  be a manifold  $M$  with an equiaffine connection  $\nabla$  and with a covariantly constant complex structure  $F$  (i.e.  $F^2 = -\text{Id}$  and  $\nabla F = 0$ ), which admits holomorphically projective mappings onto the Kähler manifold  $\bar{K}_n = (M, \bar{g}, F)$ . We suppose that

$$A_n \in C^{r-1} \quad (\Gamma_{ij}^h(x) \in C^{r-1}, r \geq 2, F_i^h(x) \in C^1) \quad \text{and} \quad \bar{K}_n \in C^2 \quad (\bar{g}_{ij}(x) \in C^2).$$

From  $\nabla_j F_i^h = 0$  it follows that  $F_i^h \in C^r$ . We proof the following theorem

**Theorem 5.** *If  $A_n \in C^{r-1}$  ( $r \geq 2$ ) admits holomorphically projective mappings onto  $\bar{K}_n \in C^2$ , then  $\bar{K}_n \in C^r$ .*

The proof of this theorem follows from the following lemmas.

**Lemma 1** (see [11]). *Let  $\lambda^h \in C^1$  be a vector field and  $\varrho$  a function. If  $\partial_i \lambda^h - \varrho \delta_i^h \in C^1$ , then  $\lambda^h \in C^2$  and  $\varrho \in C^1$ .*

**Lemma 2.** *If  $A_n \in C^2$  admits a holomorphically projective mapping onto  $\bar{K}_n \in C^2$ , then  $\bar{K}_n \in C^3$ .*

**Proof.** In this case equations (10) and (13) hold. According to our assumptions,  $\Gamma_{ij}^h \in C^2$  and  $\bar{g}_{ij} \in C^2$ . By a simple check-up we find  $\Psi \in C^2$ ,  $\psi_i \in C^1$ ,  $a^{ij} \in C^2$ ,  $\lambda^i \in C^1$  and  $R_{ijk}^h, R_{ij} \in C^1$ .

From the above-mentioned conditions we easily convince ourselves that from equation (13) follows  $\partial_l \lambda^i - \mu/n \in C^1$ . From Lemma 1 follows that  $\lambda^i \in C^2$ ,  $\mu \in C^1$ . Differentiating (10) twice we convince ourselves that  $a_{ij} \in C^3$ , and, evidently, also  $\Psi \in C^3$  and  $\bar{g}_{ij} \in C^3$ . □

Further we covariantly differentiate (13) by  $x^m$ , and after alternation of the indices  $l$  and  $m$  and application of the Ricci identities and (10) we obtain:

$$(14) \quad -n\lambda^\alpha R_{\alpha lm}^i = \delta_l^i \nabla_m \mu - \delta_m^i \nabla_l \mu - a^{\alpha\beta} (\nabla_m T_{l\alpha\beta}^i - \nabla_l T_{m\alpha\beta}^i) - \lambda^\alpha \Theta_{\alpha lm}^i,$$

where

$$\Theta_{\alpha lm}^i \stackrel{\text{def}}{=} T_{lam}^i + T_{lma}^i + T_{l\bar{a}m}^i + T_{lm\bar{a}}^i - T_{m\alpha l}^i - T_{ml\alpha}^i - T_{m\bar{a}l}^i - T_{m\bar{l}\alpha}^i.$$

We contract formula (14) w.r. to the indices  $i$  and  $m$ , and we get

$$(15) \quad (n-1) \nabla_l \mu = n \lambda^\alpha R_{\alpha l} - a^{\alpha\beta} (\nabla_\gamma T_{l\alpha\beta}^\gamma - \nabla_l T_{\gamma\alpha\beta}^\gamma) - \lambda^\alpha \Theta_{\alpha l\gamma}^\gamma.$$

The following theorem is the result of previous computations and Theorem 1.

**Theorem 6.** *Let  $A_n (\in C^r, r \geq 2)$  be an equiaffine space with affine connection and let be defined a covariantly constant affinor  $F_i^h$  such that  $F_\alpha^h F_i^\alpha = -\delta_i^h$ . Then  $A_n$  admits a holomorphically projective mapping onto a Kählerian space  $\bar{K}_n (\in C^2)$  if and only if the following system of linear differential equations of Cauchy type is solvable with respect to the unknown functions  $a^{ij}$ ,  $\lambda^i$  and  $\mu$ :*

$$(16) \quad \begin{aligned} \nabla_k a^{ij} &= \lambda^i \delta_k^j + \lambda^j \delta_k^i + \lambda^{\bar{i}} \delta_k^{\bar{j}} + \lambda^{\bar{j}} \delta_k^{\bar{i}}; \\ n \nabla_l \lambda^i &= \mu \delta_l^i - a^{\alpha\beta} T_{l\alpha\beta}^i; \\ (n-1) \nabla_l \mu &= n \lambda^\alpha R_{\alpha l} - a^{\alpha\beta} (\nabla_\gamma T_{l\alpha\beta}^\gamma - \nabla_l T_{\gamma\alpha\beta}^\gamma) - \lambda^\alpha \Theta_{\alpha l\gamma}^\gamma, \end{aligned}$$

where the matrix  $(a^{ij})$  should further satisfy  $\det \|a^{ij}\| \neq 0$  and the algebraic conditions

$$(17) \quad a^{ij} = a^{j\bar{i}}; \quad a^{\bar{i}\bar{j}} = a^{ij}.$$

Here  $T$  and  $\Theta$  are tensors which are explicitly expressed in terms of objects defined on  $A_n$ , i.e. the affine connection  $A_n$  and the affinor  $F_i^h$ .

This theorem is a generalization of results in [5, 7, 1, 16, 19], see [18, 22, 26].

The system (16) does not have more than one solution for the initial Cauchy conditions  $a^{ij}(x_o) = a_o^{ij}$ ,  $\lambda^i(x_o) = \lambda_o^i$ ,  $\mu(x_o) = \mu_o$  under the conditions (17). Therefore the general solution of (14) does not depend on more than  $N_o = 1/4(n+1)^2$  parameters. The question of existence of a solution of (14) leads to the consideration of integrability conditions, which are linear equations w.r. to the unknowns  $a^{ij}$ ,  $\lambda^i$  and  $\mu$  with coefficient functions defined on the manifold  $A_n$ .

**Acknowledgement.** The paper was supported by the grant P201/11/0356 of The Czech Science Foundation and by the project FAST-S-13-2088 of the Brno University of Technology.

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I. HINTERLEITNER,  
BRNO UNIVERSITY OF TECHNOLOGY, FACULTY OF CIVIL ENGINEERING,  
DEPARTMENT OF MATHEMATICS,  
ŽIŽKOVA 17, 602 00 BRNO, CZECH REPUBLIC  
*E-mail*: hinterleitner.irena@seznam.cz

J. MIKEŠ  
PALACKY UNIVERSITY, DEPARTMENT OF ALGEBRA AND GEOMETRY,  
17. LISTOPADU 12, 771 46 OLOMOUC, CZECH REPUBLIC  
*E-mail*: josef.mikes@upol.cz