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Existence of solutions for Navier problems with degenerate nonlinear elliptic equations

Albo Carlos Cavalleiro

Abstract. In this paper we are interested in the existence and uniqueness of solutions for the Navier problem associated to the degenerate nonlinear elliptic equations

$$\Delta(v(x) |\Delta u|^{q-2} \Delta u) - \sum_{j=1}^n D_j [\omega(x) \mathcal{A}_j(x, u, \nabla u)] = f_0(x) - \sum_{j=1}^n D_j f_j(x), \text{ in } \Omega$$

in the setting of the weighted Sobolev spaces.

1 Introduction

In this paper we prove the existence and uniqueness of (weak) solutions in the weighted Sobolev space $X = W^{2,q}(\Omega, v) \cap W_0^{1,p}(\Omega, \omega)$ (see Definition 4) for the Navier problem

$$\begin{cases} Lu(x) = f_0(x) - \sum_{j=1}^n D_j f_j(x), & \text{in } \Omega \\ u(x) = 0, & \text{on } \partial\Omega \\ \Delta u(x) = 0, & \text{on } \partial\Omega \end{cases} \quad (1)$$

where L is the partial differential operator

$$Lu(x) = \Delta(v(x) |\Delta u|^{q-2} \Delta u) - \sum_{j=1}^n D_j [\omega(x) \mathcal{A}_j(x, u(x), \nabla u(x))]$$

where $D_j = \partial/\partial x_j$, Ω is a bounded open set in \mathbb{R}^n , ω and v are two weight functions, Δ is the usual Laplacian operator, $1 < p, q < \infty$ and the functions $\mathcal{A}_j: \Omega \times \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}$ ($j = 1, \dots, n$) satisfy the following conditions:

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- (H1) $x \mapsto \mathcal{A}_j(x, \eta, \xi)$ is measurable on Ω for all $(\eta, \xi) \in \mathbb{R} \times \mathbb{R}^n$
 $(\eta, \xi) \mapsto \mathcal{A}_j(x, \eta, \xi)$ is continuous on $\mathbb{R} \times \mathbb{R}^n$ for almost all $x \in \Omega$.

- (H2) There exists a constant $\theta_1 > 0$ such that

$$[\mathcal{A}(x, \eta, \xi) - \mathcal{A}(x, \eta', \xi')] \cdot (\xi - \xi') \geq \theta_1 |\xi - \xi'|^p$$

whenever $\xi, \xi' \in \mathbb{R}^n$, $\xi \neq \xi'$, where $\mathcal{A}(x, \eta, \xi) = (\mathcal{A}_1(x, \eta, \xi), \dots, \mathcal{A}_n(x, \eta, \xi))$
 (where a dot denote here the Euclidean scalar product in \mathbb{R}^n).

- (H3) $\mathcal{A}(x, \eta, \xi) \cdot \xi \geq \lambda_1 |\xi|^p$, where λ_1 is a positive constant.

- (H4) $|\mathcal{A}(x, \eta, \xi)| \leq K_1(x) + h_1(x)|\eta|^{p/p'} + h_2(x)|\xi|^{p/p'}$, where K_1, h_1 and h_2 are non-negative functions, with h_1 and $h_2 \in L^\infty(\Omega)$, and $K_1 \in L^p(\Omega, \omega)$ (with $1/p + 1/p' = 1$).

By a *weight*, we shall mean a locally integrable function ω on \mathbb{R}^n such that $\omega(x) > 0$ for a.e. $x \in \mathbb{R}^n$. Every weight ω gives rise to a measure on the measurable subsets on \mathbb{R}^n through integration. This measure will be denoted by μ . Thus, $\mu(E) = \int_E \omega(x) dx$ for measurable sets $E \subset \mathbb{R}^n$.

In general, the Sobolev spaces $W^{k,p}(\Omega)$ without weights occur as spaces of solutions for elliptic and parabolic partial differential equations. For degenerate partial differential equations, i.e., equations with various types of singularities in the coefficients, it is natural to look for solutions in weighted Sobolev spaces (see [1], [2] and [4]).

In various applications, we can meet boundary value problems for elliptic equations whose ellipticity is disturbed in the sense that some degeneration or singularity appears. This bad behaviour can be caused by the coefficients of the corresponding differential operator as well as by the solution itself. The so-called p -Laplacian is a prototype of such an operator and its character can be interpreted as a degeneration or as a singularity of the classical (linear) Laplace operator (with $p = 2$). There are several very concrete problems from practice which lead to such differential equations, e.g. from glaciology, non-Newtonian fluid mechanics, flows through porous media, differential geometry, celestial mechanics, climatology, petroleum extraction, reaction-diffusion problems, etc.

A class of weights, which is particularly well understood, is the class of A_p -weights (or Muckenhoupt class) that was introduced by B. Muckenhoupt (see [11]). These classes have found many useful applications in harmonic analysis (see [13]). Another reason for studying A_p -weights is the fact that powers of distance to submanifolds of \mathbb{R}^n often belong to A_p (see [10]). There are, in fact, many interesting examples of weights (see [9] for p -admissible weights).

In the non-degenerate case (i.e. with $v(x) \equiv 1$), for all $f \in L^p(\Omega)$, the Poisson equation associated with the Dirichlet problem

$$\begin{cases} -\Delta u = f(x), & \text{in } \Omega \\ u(x) = 0, & \text{on } \partial\Omega \end{cases}$$

is uniquely solvable in $W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$ (see [8]), and the nonlinear Dirichlet problem

$$\begin{cases} -\Delta_p u = f(x), & \text{in } \Omega \\ u(x) = 0, & \text{on } \partial\Omega \end{cases}$$

is uniquely solvable in $W_0^{1,p}(\Omega)$ (see [3]), where $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2} \nabla u)$ is the p -Laplacian operator. In the degenerate case, the weighted p -Biharmonic operator has been studied by many authors (see [12] and the references therein), and the degenerated p -Laplacian was studied in [4].

The following theorem will be proved in section 3.

Theorem 1. *Assume (H1) – (H4). If*

- (i) $v \in A_q$, $\omega \in A_p$ (with $1 < p, q < \infty$),
- (ii) $f_j/\omega \in L^{p'}(\Omega, \omega)$ ($j = 0, 1, \dots, n$),

then the problem (1) has a unique solution $u \in X = W^{2,q}(\Omega, v) \cap W_0^{1,p}(\Omega, \omega)$.

2 Definitions and basic results

Let ω be a locally integrable nonnegative function in \mathbb{R}^n and assume that $0 < \omega(x) < \infty$ almost everywhere. We say that ω belongs to the Muckenhoupt class A_p , $1 < p < \infty$, or that ω is an A_p -weight, if there is a positive constant $C = C_{p,\omega}$ such that

$$\left(\frac{1}{|B|} \int_B \omega(x) \, dx \right) \left(\frac{1}{|B|} \int_B \omega^{1/(1-p)}(x) \, dx \right)^{p-1} \leq C$$

for all balls $B \subset \mathbb{R}^n$, where $|\cdot|$ denotes the n -dimensional Lebesgue measure in \mathbb{R}^n . If $1 < q \leq p$, then $A_q \subset A_p$ (see [7], [9] or [13] for more information about A_p -weights). The weight ω satisfies the doubling condition if there exists a positive constant C such that $\mu(B(x; 2r)) \leq C\mu(B(x; r))$, for every ball $B = B(x; r) \subset \mathbb{R}^n$, where $\mu(B) = \int_B \omega(x) \, dx$. If $\omega \in A_p$, then μ is doubling (see Corollary 15.7 in [9]).

As an example of A_p -weight, the function $\omega(x) = |x|^\alpha$, $x \in \mathbb{R}^n$, is in A_p if and only if $-n < \alpha < n(p-1)$ (see Corollary 4.4, Chapter IX in [13]).

If $\omega \in A_p$, then

$$\left(\frac{|E|}{|B|} \right)^p \leq C \frac{\mu(E)}{\mu(B)}$$

whenever B is a ball in \mathbb{R}^n and E is a measurable subset of B (see 15.5 *strong doubling property* in [9]). Therefore, if $\mu(E) = 0$ then $|E| = 0$.

Definition 1. Let ω be a weight, and let $\Omega \subset \mathbb{R}^n$ be open. For $0 < p < \infty$ we define $L^p(\Omega, \omega)$ as the set of measurable functions f on Ω such that

$$\|f\|_{L^p(\Omega, \omega)} = \left(\int_\Omega |f(x)|^p \omega(x) \, dx \right)^{1/p} < \infty.$$

If $\omega \in A_p$, $1 < p < \infty$, then $\omega^{-1/(p-1)}$ is locally integrable and we have $L^p(\Omega, \omega) \subset L^1_{\text{loc}}(\Omega)$ for every open set Ω (see Remark 1.2.4 in [14]). It thus makes sense to talk about weak derivatives of functions in $L^p(\Omega, \omega)$.

Definition 2. Let $\Omega \subset \mathbb{R}^n$ be open, $1 < p < \infty$ and $\omega \in A_p$. We define the weighted Sobolev space $W^{k,p}(\Omega, \omega)$ as the set of functions $u \in L^p(\Omega, \omega)$ with weak derivatives $D^\alpha u \in L^p(\Omega, \omega)$, $1 \leq |\alpha| \leq k$. The norm of u in $W^{k,p}(\Omega, \omega)$ is defined by

$$\|u\|_{W^{k,p}(\Omega, \omega)} = \left(\int_{\Omega} |u(x)|^p \omega(x) dx + \sum_{1 \leq |\alpha| \leq k} \int_{\Omega} |D^\alpha u(x)|^p \omega(x) dx \right)^{1/p}. \quad (2)$$

We also define $W_0^{k,p}(\Omega, \omega)$ as the closure of $C_0^\infty(\Omega)$ with respect to the norm $\|\cdot\|_{W^{k,p}(\Omega, \omega)}$.

If $\omega \in A_p$, then $W^{k,p}(\Omega, \omega)$ is the closure of $C^\infty(\Omega)$ with respect to the norm (2.1) (see Theorem 2.1.4 in [14]). The spaces $W^{k,p}(\Omega, \omega)$ and $W_0^{k,p}(\Omega, \omega)$ are Banach spaces and the spaces $W^{k,2}(\Omega, \omega)$ and $W_0^{k,2}(\Omega, \omega)$ are Hilbert spaces.

It is evident that a weight function ω which satisfies $0 < c_1 \leq \omega(x) \leq c_2$ for $x \in \Omega$ (where c_1 and c_2 are constants), gives nothing new (the space $W_0^{k,p}(\Omega, \omega)$ is then identical with the classical Sobolev space $W_0^{k,p}(\Omega)$). Consequently, we shall be interested above in all such weight functions ω which either vanish somewhere in $\Omega \cup \partial\Omega$ or increase to infinity (or both).

In this paper we use the following results.

Theorem 2. Let $\omega \in A_p$, $1 < p < \infty$, and let Ω be a bounded open set in \mathbb{R}^n . If $u_m \rightarrow u$ in $L^p(\Omega, \omega)$ then there exist a subsequence $\{u_{m_k}\}$ and a function $\Phi \in L^p(\Omega, \omega)$ such that

- (i) $u_{m_k}(x) \rightarrow u(x)$, $m_k \rightarrow \infty$, μ -a.e. on Ω ;
- (ii) $|u_{m_k}(x)| \leq \Phi(x)$, μ -a.e. on Ω ; (where $\mu(E) = \int_E \omega(x) dx$).

Proof. The proof of this theorem follows the lines of Theorem 2.8.1 in [6]. □

Theorem 3. (The weighted Sobolev inequality) Let Ω be an open bounded set in \mathbb{R}^n and $\omega \in A_p$ ($1 < p < \infty$). There exist constants C_Ω and δ positive such that for all $u \in C_0^\infty(\Omega)$ and all k satisfying $1 \leq k \leq n/(n-1) + \delta$,

$$\|u\|_{L^{kp}(\Omega, \omega)} \leq C_\Omega \|\nabla u\|_{L^p(\Omega, \omega)}.$$

Proof. See Theorem 1.3 in [5]. □

Lemma 1. Let $1 < p < \infty$.

- (a) There exists a constant α_p such that

$$\left| |x|^{p-2}x - |y|^{p-2}y \right| \leq \alpha_p |x - y| (|x| + |y|)^{p-2} y,$$

for all $x, y \in \mathbb{R}^n$;

(b) There exist two positive constants β_p, γ_p such that for every $x, y \in \mathbb{R}^n$

$$\beta_p(|x|+|y|)^{p-2}|x-y|^2 \leq (|x|^{p-2}x-|y|^{p-2}y) \cdot (x-y) \leq \gamma_p(|x|+|y|)^{p-2}|x-y|^2.$$

Proof. See [3], Proposition 17.2 and Proposition 17.3. \square

Definition 3. Let $\Omega \subset \mathbb{R}^n$ be a bounded open set and $v \in A_q, \omega \in A_p, 1 < p, q < \infty$. We denote by $X = W^{2,q}(\Omega, v) \cap W_0^{1,p}(\Omega, \omega)$ with the norm

$$\|u\|_X = \|\nabla u\|_{L^p(\Omega, \omega)} + \|\Delta u\|_{L^q(\Omega, v)}.$$

Definition 4. We say that an element $u \in X = W^{2,q}(\Omega, v) \cap W_0^{1,p}(\Omega, \omega)$ is a (weak) solution of problem (1) if for all $\varphi \in X$ we have

$$\begin{aligned} \int_{\Omega} |\Delta u|^{q-2} \Delta u \Delta \varphi v \, dx + \sum_{j=1}^n \int_{\Omega} \omega \mathcal{A}_j(x, u(x), \nabla u(x)) D_j \varphi \, dx \\ = \int_{\Omega} f_0 \varphi \, dx + \sum_{j=1}^n \int_{\Omega} f_j D_j \varphi \, dx. \end{aligned}$$

3 Proof of Theorem 1

The basic idea is to reduce the problem (1) to an operator equation $Au = T$ and apply the theorem below.

Theorem 4. Let $A : X \rightarrow X^*$ be a monotone, coercive and hemicontinuous operator on the real, separable, reflexive Banach space X . Then for each $T \in X^*$ the equation $Au = T$ has a solution $u \in X$.

Proof. See Theorem 26.A in [16]. \square

To prove the existence of solutions, we define $B, B_1, B_2 : X \times X \rightarrow \mathbb{R}$ and $T : X \rightarrow \mathbb{R}$ by

$$\begin{aligned} B(u, \varphi) &= B_1(u, \varphi) + B_2(u, \varphi), \\ B_1(u, \varphi) &= \sum_{j=1}^n \int_{\Omega} \omega \mathcal{A}_j(x, u, \nabla u) D_j \varphi \, dx = \int_{\Omega} \omega \mathcal{A}(x, u, \nabla u) \cdot \nabla \varphi \, dx, \\ B_2(u, \varphi) &= \int_{\Omega} |\Delta u|^{q-2} \Delta u \Delta \varphi v \, dx, \\ T(\varphi) &= \int_{\Omega} f_0 \varphi \, dx + \sum_{j=1}^n \int_{\Omega} f_j D_j \varphi \, dx. \end{aligned}$$

Then $u \in X$ is a (weak) solution to problem (1) if

$$B(u, \varphi) = B_1(u, \varphi) + B_2(u, \varphi) = T(\varphi), \quad \text{for all } \varphi \in X.$$

Step 1. For $j = 1, \dots, n$ we define the operator $F_j : X \rightarrow L^{p'}(\Omega, \omega)$ by

$$(F_j u)(x) = \mathcal{A}_j(x, u(x), \nabla u(x)).$$

We now show that operator F_j is bounded and continuous.

(i) Using (H4) we obtain

$$\begin{aligned}
\|F_j u\|_{L^{p'}(\Omega, \omega)}^{p'} &= \int_{\Omega} |F_j u(x)|^{p'} \omega \, dx = \int_{\Omega} |\mathcal{A}_j(x, u, \nabla u)|^{p'} \omega \, dx \\
&\leq \int_{\Omega} \left(K_1 + h_1 |u|^{p/p'} + h_2 |\nabla u|^{p/p'} \right)^{p'} \omega \, dx \\
&\leq C_p \int_{\Omega} \left[(K_1^{p'} + h_1^{p'} |u|^p + h_2^{p'} |\nabla u|^p) \omega \right] dx \\
&= C_p \left[\int_{\Omega} K_1^{p'} \omega \, dx + \int_{\Omega} h_1^{p'} |u|^p \omega \, dx + \int_{\Omega} h_2^{p'} |\nabla u|^p \omega \, dx \right], \quad (3)
\end{aligned}$$

where the constant C_p depends only on p . We have, by Theorem 3,

$$\begin{aligned}
\int_{\Omega} h_1^{p'} |u|^p \omega \, dx &\leq \|h_1\|_{L^\infty(\Omega)}^{p'} \int_{\Omega} |u|^p \omega \, dx \\
&\leq C_\Omega^p \|h_1\|_{L^\infty(\Omega)}^{p'} \int_{\Omega} |\nabla u|^p \omega \, dx \\
&\leq C_\Omega^p \|h_1\|_{L^\infty(\Omega)}^{p'} \|u\|_X^p,
\end{aligned}$$

and

$$\int_{\Omega} h_2^{p'} |\nabla u|^p \omega \, dx \leq \|h_2\|_{L^\infty(\Omega)}^{p'} \int_{\Omega} |\nabla u|^p \omega \, dx \leq \|h_2\|_{L^\infty(\Omega)}^{p'} \|u\|_X^p.$$

Therefore, in (3) we obtain

$$\|F_j u\|_{L^{p'}(\Omega, \omega)} \leq C_p \left(\|K\|_{L^{p'}(\Omega, \omega)} + (C_\Omega^{p/p'} \|h_1\|_{L^\infty(\Omega)} + \|h_2\|_{L^\infty(\Omega)}) \|u\|_X^{p/p'} \right),$$

and hence the boundedness.

(ii) Let $u_m \rightarrow u$ in X as $m \rightarrow \infty$. We need to show that $F_j u_m \rightarrow F_j u$ in $L^{p'}(\Omega, \omega)$. We will apply the Lebesgue Dominated Convergence Theorem. If $u_m \rightarrow u$ in X , then $u_m \rightarrow u$ in $L^p(\Omega, \omega)$ and $|\nabla u_m| \rightarrow |\nabla u|$ in $L^p(\Omega, \omega)$. Using Theorem 2, there exist a subsequence $\{u_{m_k}\}$ and functions Φ_1 and Φ_2 in $L^p(\Omega, \omega)$ such that

$$\begin{aligned}
u_{m_k}(x) &\rightarrow u(x), \quad \mu_1\text{- a.e. in } \Omega, \\
|u_{m_k}(x)| &\leq \Phi_1(x), \quad \mu_1\text{- a.e. in } \Omega, \\
|\nabla u_{m_k}(x)| &\rightarrow |\nabla u(x)|, \quad \mu_1\text{- a.e. in } \Omega, \\
|\nabla u_{m_k}(x)| &\leq \Phi_2(x), \quad \mu_1\text{- a.e. in } \Omega.
\end{aligned}$$

where $\mu_1(E) = \int_E \omega(x) \, dx$. Hence, using (H4), we obtain

$$\begin{aligned}
\|F_j u_{m_k} - F_j u\|_{L^{p'}(\Omega, \omega)}^{p'} &= \int_{\Omega} |F_j u_{m_k}(x) - F_j u(x)|^{p'} \omega \, dx \\
&= \int_{\Omega} |\mathcal{A}_j(x, u_{m_k}, \nabla u_{m_k}) - \mathcal{A}_j(x, u, \nabla u)|^{p'} \omega \, dx \\
&\leq C_p \int_{\Omega} \left(|\mathcal{A}_j(x, u_{m_k}, \nabla u_{m_k})|^{p'} + |\mathcal{A}_j(x, u, \nabla u)|^{p'} \right) \omega \, dx \\
&\leq C_p \left[\int_{\Omega} \left(K_1 + h_1 |u_{m_k}|^{p/p'} + h_2 |\nabla u_{m_k}|^{p/p'} \right)^{p'} \omega \, dx \right. \\
&\quad \left. + \int_{\Omega} \left(K_1 + h_1 |u|^{p/p'} + h_2 |\nabla u|^{p/p'} \right)^{p'} \omega \, dx \right] \\
&\leq 2C_p \int_{\Omega} \left(K_1 + h_1 \Phi_1^{p/p'} + h_2 \Phi_2^{p/p'} \right)^{p'} \omega \, dx \\
&\leq 2C_p \left[\int_{\Omega} K_1^{p'} \omega \, dx + \int_{\Omega} h_1^{p'} \Phi_1^p \omega \, dx + \int_{\Omega} h_2^{p'} \Phi_2^p \omega \, dx \right] \\
&\leq 2C_p \left[\|K_1\|_{L^{p'}(\Omega, \omega)}^{p'} + \|h_1\|_{L^\infty(\Omega)}^{p'} \int_{\Omega} \Phi_1^p \omega \, dx \right. \\
&\quad \left. + \|h_2\|_{L^\infty(\Omega)}^{p'} \int_{\Omega} \Phi_2^p \omega \, dx \right] \\
&\leq 2C_p \left[\|K_1\|_{L^{p'}(\Omega, \omega)}^{p'} + \|h_1\|_{L^\infty(\Omega)}^{p'} \|\Phi_1\|_{L^p(\Omega, \omega)}^p \right. \\
&\quad \left. + \|h_2\|_{L^\infty(\Omega)}^{p'} \|\Phi_2\|_{L^p(\Omega, \omega)}^p \right].
\end{aligned}$$

By condition (H1), we have

$$F_j u_m(x) = \mathcal{A}_j(x, u_m(x), \nabla u_m(x)) \rightarrow \mathcal{A}_j(x, u(x), \nabla u(x)) = F_j u(x),$$

as $m \rightarrow +\infty$. Therefore, by the Dominated Convergence Theorem, we obtain $\|F_j u_{m_k} - F_j u\|_{L^{p'}(\Omega, \omega)} \rightarrow 0$, that is, $F_j u_{m_k} \rightarrow F_j u$ in $L^{p'}(\Omega, \omega)$. By the Convergence principle in Banach spaces (see Proposition 10.13 in [15]) we have

$$F_j u_m \rightarrow F_j u \text{ in } L^{p'}(\Omega, \omega). \quad (4)$$

Step 2. We define the operator $G: X \rightarrow L^{q'}(\Omega, v)$ by

$$(Gu)(x) = |\Delta u(x)|^{q-2} \Delta u(x).$$

We also have that the operator G is continuous and bounded. In fact,

(i) We have

$$\begin{aligned} \|Gu\|_{L^{q'}(\Omega, v)}^{q'} &= \int_{\Omega} |\Delta u|^{q-2} \Delta u |v|^{q'} dx \\ &= \int_{\Omega} |\Delta u|^{(q-2)q'} |\Delta u|^{q'} v dx \\ &= \int_{\Omega} |\Delta u|^q v dx \leq \|u\|_X^q. \end{aligned}$$

Hence, $\|Gu\|_{L^{q'}(\Omega, v)} \leq \|u\|_X^{q/q'}$.

(ii) If $u_m \rightarrow u$ in X then $\Delta u_m \rightarrow \Delta u$ in $L^q(\Omega, v)$. By Theorem 2, there exist a subsequence $\{u_{m_k}\}$ and a function $\Phi_3 \in L^q(\Omega, v)$ such that

$$\begin{aligned} \Delta u_{m_k}(x) &\rightarrow \Delta u(x), \quad \mu_2 - \text{a.e. in } \Omega \\ |\Delta u_{m_k}(x)| &\leq \Phi_3(x), \quad \mu_2 - \text{a.e. in } \Omega. \end{aligned}$$

where $\mu_2(E) = \int_E v(x) dx$. Hence, using Lemma 1(a), we obtain, if $q \neq 2$

$$\begin{aligned} \|Gu_{m_k} - Gu\|_{L^{q'}(\Omega, v)}^{q'} &= \int_{\Omega} |Gu_{m_k} - Gu|^{q'} v dx \\ &= \int_{\Omega} \left| |\Delta u_{m_k}|^{q-2} \Delta u_{m_k} - |\Delta u|^{q-2} \Delta u \right|^{q'} v dx \\ &\leq \int_{\Omega} \left[\alpha_q |\Delta u_{m_k} - \Delta u| (|\Delta u_{m_k}| + |\Delta u|)^{(q-2)} \right]^{q'} v dx \\ &\leq \alpha_q^{q'} \int_{\Omega} |\Delta u_{m_k} - \Delta u|^{q'} (2\Phi_3)^{(q-2)q'} v dx \\ &\leq \alpha_q^{q'} 2^{(q-2)q'} \left(\int_{\Omega} |\Delta u_{m_k} - \Delta u|^q v dx \right)^{q'/q} \\ &\quad \times \left(\int_{\Omega} \Phi_3^{(q-2)qq'/(q-q')} v dx \right)^{(q-q')/q} \\ &\leq \alpha_q^{q'} 2^{(q-2)q'} \|u_{m_k} - u\|_X^{q'} \|\Phi\|_{L^q(\Omega, v)}^{q-q'}, \end{aligned}$$

since $(q-2)qq'/(q-q') = q$ if $q \neq 2$. If $q = 2$, we have

$$\|Gu_{m_k} - Gu\|_{L^2(\Omega, v)}^2 = \int_{\Omega} |\Delta u_{m_k} - \Delta u|^2 v dx \leq \|u_{m_k} - u\|_X^2.$$

Therefore (for $1 < q < \infty$), by the Dominated Convergence Theorem, we obtain

$$\|Gu_{m_k} - Gu\|_{L^{q'}(\Omega, v)} \rightarrow 0,$$

that is, $Gu_{m_k} \rightarrow Gu$ in $L^{q'}(\Omega, v)$. By the Convergence principle in Banach spaces (see Proposition 10.13 in [15]), we have

$$Gu_m \rightarrow Gu \quad \text{in } L^{q'}(\Omega, v). \quad (5)$$

Step 3. We have, by Theorem 3,

$$\begin{aligned}
|T(\varphi)| &\leq \int_{\Omega} |f_0| |\varphi| \, dx + \sum_{j=1}^n \int_{\Omega} |f_j| |D_j \varphi| \, dx \\
&= \int_{\Omega} \frac{|f_0|}{\omega} |\varphi| \omega \, dx + \sum_{j=1}^n \int_{\Omega} \frac{|f_j|}{\omega} |D_j \varphi| \omega \, dx \\
&\leq \|f_0/\omega\|_{L^{p'}(\Omega, \omega)} \|\varphi\|_{L^p(\Omega, \omega)} + \sum_{j=1}^n \|f_j/\omega\|_{L^{p'}(\Omega, \omega)} \|D_j \varphi\|_{L^p(\Omega, \omega)} \\
&\leq \left(C_{\Omega} \|f_0/\omega\|_{L^{p'}(\Omega, \omega)} + \sum_{j=1}^n \|f_j/\omega\|_{L^{p'}(\Omega, \omega)} \right) \|\varphi\|_X.
\end{aligned}$$

Moreover, using (H4) and the Hölder inequality, we also have

$$\begin{aligned}
|B(u, \varphi)| &\leq |B_1(u, \varphi)| + |B_2(u, \varphi)| \\
&\leq \sum_{j=1}^n \int_{\Omega} |\mathcal{A}_j(x, u, \nabla u)| |D_j \varphi| \omega \, dx + \int_{\Omega} |\Delta u|^{q-2} |\Delta u| |\Delta \varphi| v \, dx. \quad (6)
\end{aligned}$$

In (6) we have

$$\begin{aligned}
\int_{\Omega} |\mathcal{A}(x, u, \nabla u)| |\nabla \varphi| \omega \, dx &\leq \int_{\Omega} \left(K_1 + h_1 |u|^{p/p'} + h_2 |\nabla u|^{p/p'} \right) |\nabla \varphi| \omega \, dx \\
&\leq \|K_1\|_{L^{p'}(\Omega, \omega)} \|\nabla \varphi\|_{L^p(\Omega, \omega)} + \|h_1\|_{L^\infty(\Omega)} \|u\|_{L^{p/p'}(\Omega, \omega)}^{p/p'} \|\nabla \varphi\|_{L^p(\Omega, \omega)} \\
&\quad + \|h_2\|_{L^\infty(\Omega)} \|\nabla u\|_{L^{p/p'}(\Omega, \omega)}^{p/p'} \|\nabla \varphi\|_{L^p(\Omega, \omega)} \\
&\leq \left(\|K_1\|_{L^{p'}(\Omega, \omega)} + (C_{\Omega}^{p/p'} \|h_1\|_{L^\infty(\Omega)} + \|h_2\|_{L^\infty(\Omega)}) \|u\|_X^{p/p'} \right) \|\varphi\|_X,
\end{aligned}$$

and

$$\begin{aligned}
\int_{\Omega} |\Delta u|^{q-2} |\Delta u| |\Delta \varphi| v \, dx &= \int_{\Omega} |\Delta u|^{q-1} |\Delta \varphi| v \, dx \\
&\leq \left(\int_{\Omega} |\Delta u|^q v \, dx \right)^{1/q'} \left(\int_{\Omega} |\Delta \varphi|^q v \, dx \right)^{1/q} \\
&\leq \|u\|_X^{q/q'} \|\varphi\|_X.
\end{aligned}$$

Hence, in (6) we obtain, for all $u, \varphi \in X$

$$\begin{aligned}
|B(u, \varphi)| &\leq \left[\|K_1\|_{L^{p'}(\Omega, \omega)} + C_{\Omega}^{p/p'} \|h_1\|_{L^\infty(\Omega)} \|u\|_X^{p/p'} \right. \\
&\quad \left. + \|h_2\|_{L^\infty(\Omega, \omega)} \|u\|_X^{p/p'} + \|u\|_X^{q/q'} \right] \|\varphi\|_X.
\end{aligned}$$

Since $B(u, \cdot)$ is linear, for each $u \in X$, there exists a linear and continuous operator $A: X \rightarrow X^*$ such that $\langle Au, \varphi \rangle = B(u, \varphi)$, for all $u, \varphi \in X$ (where $\langle f, x \rangle$

denotes the value of the linear functional f at the point x) and

$$\begin{aligned} \|Au\|_* &\leq \|K_1\|_{L^{p'}(\Omega,\omega)} + C_\Omega^{p/p'} \|h_1\|_{L^\infty(\Omega)} \|u\|_X^{p/p'} \\ &\quad + \|h_2\|_{L^\infty(\Omega,\omega)} \|u\|_X^{p/p'} + \|u\|_X^{q/q'}. \end{aligned}$$

Consequently, problem (1) is equivalent to the operator equation

$$Au = T, \quad u \in X.$$

Step 4. Using condition (H2) and Lemma 1(b), we have

$$\begin{aligned} \langle Au_1 - Au_2, u_1 - u_2 \rangle &= B(u_1, u_1 - u_2) - B(u_2, u_1 - u_2) \\ &= \int_\Omega \omega \mathcal{A}(x, u_1, \nabla u_1) \cdot \nabla(u_1 - u_2) \, dx + \int_\Omega |\Delta u_1|^{q-2} \Delta u_1 \Delta(u_1 - u_2) v \, dx \\ &\quad - \int_\Omega \omega \mathcal{A}(x, u_2, \nabla u_2) \cdot \nabla(u_1 - u_2) \, dx - \int_\Omega |\Delta u_2|^{q-2} \Delta u_2 \Delta(u_1 - u_2) v \, dx \\ &= \int_\Omega \omega \left(\mathcal{A}(x, u_1, \nabla u_1) - \mathcal{A}(x, u_2, \nabla u_2) \right) \cdot \nabla(u_1 - u_2) \, dx \\ &\quad + \int_\Omega (|\Delta u_1|^{q-2} \Delta u_1 - |\Delta u_2|^{q-2} \Delta u_2) \Delta(u_1 - u_2) v \, dx \\ &\geq \theta_1 \int_\Omega \omega |\nabla(u_1 - u_2)|^p \, dx + \beta_q \int_\Omega (|\Delta u_1| + |\Delta u_2|)^{q-2} |\Delta u_1 - \Delta u_2|^2 v \, dx \\ &\geq \theta_1 \int_\Omega \omega |\nabla(u_1 - u_2)|^p \, dx + \beta_q \int_\Omega (|\Delta u_1 - \Delta u_2|)^{q-2} |\Delta u_1 - \Delta u_2|^2 v \, dx \\ &= \theta_1 \int_\Omega \omega |\nabla(u_1 - u_2)|^p \, dx + \beta_q \int_\Omega |\Delta u_1 - \Delta u_2|^q v \, dx \\ &\geq 0. \end{aligned}$$

Therefore, the operator A is monotone. Moreover, using (H3), we obtain

$$\begin{aligned} \langle Au, u \rangle &= B(u, u) = B_1(u, u) + B_2(u, u) \\ &= \int_\Omega \omega \mathcal{A}(x, u, \nabla u) \cdot \nabla u \, dx + \int_\Omega |\Delta u|^{q-2} \Delta u \Delta u v \, dx \\ &\geq \int_\Omega \lambda_1 |\nabla u|^p \omega \, dx + \int_\Omega |\Delta u|^q v \, dx \\ &= \lambda_1 \|\nabla u\|_{L^p(\Omega,\omega)}^p + \|\Delta u\|_{L^q(\Omega,v)}^q. \end{aligned}$$

Hence, since $1 < p, q < \infty$, we have

$$\frac{\langle Au, u \rangle}{\|u\|_X} \rightarrow +\infty, \quad \text{as } \|u\|_X \rightarrow +\infty,$$

(using $\lim_{t+s \rightarrow \infty} \frac{t^p + s^q}{t+s} = \infty$) that is, A is coercive.

Step 5. We need to show that the operator A is continuous.

Let $u_m \rightarrow u$ in X as $m \rightarrow \infty$. We have,

$$\begin{aligned}
 |B_1(u_m, \varphi) - B_1(u, \varphi)| &\leq \sum_{j=1}^n \int_{\Omega} |\mathcal{A}_j(x, u_m, \nabla u_m) - \mathcal{A}_j(x, u, \nabla u)| |D_j \varphi| \omega \, dx \\
 &= \sum_{j=1}^n \int_{\Omega} |F_j u_m - F_j u| |D_j \varphi| \omega \, dx \\
 &\leq \sum_{j=1}^n \|F_j u_m - F_j u\|_{L^{p'}(\Omega, \omega)} \|D_j \varphi\|_{L^p(\Omega, \omega)} \\
 &\leq \sum_{j=1}^n \|F_j u_m - F_j u\|_{L^{p'}(\Omega, \omega)} \|\varphi\|_X,
 \end{aligned}$$

and

$$\begin{aligned}
 |B_2(u_m, \varphi) - B_2(u, \varphi)| &= \left| \int_{\Omega} |\Delta u_m|^{q-2} \Delta u_m \Delta \varphi v \, dx - \int_{\Omega} |\Delta u|^{q-2} \Delta u \Delta \varphi v \, dx \right| \\
 &\leq \int_{\Omega} \left| |\Delta u_m|^{q-2} \Delta u_m - |\Delta u|^{q-2} \Delta u \right| |\Delta \varphi| v \, dx \\
 &= \int_{\Omega} |G u_m - G u| |\Delta \varphi| v \, dx \\
 &\leq \|G u_m - G u\|_{L^{q'}(\Omega, v)} \|\Delta \varphi\|_{L^q(\Omega, v)} \\
 &\leq \|G u_m - G u\|_{L^{q'}(\Omega, v)} \|\varphi\|_X,
 \end{aligned}$$

for all $\varphi \in X$. Hence,

$$\begin{aligned}
 |B(u_m, \varphi) - B(u, \varphi)| &\leq |B_1(u_m, \varphi) - B_1(u, \varphi)| + |B_2(u_m, \varphi) - B_2(u, \varphi)| \\
 &\leq \left[\sum_{j=1}^n \|F_j u_m - F_j u\|_{L^{p'}(\Omega, \omega)} + \|G u_m - G u\|_{L^{q'}(\Omega, v)} \right] \|\varphi\|_X.
 \end{aligned}$$

Then we obtain

$$\|A u_m - A u\|_* \leq \sum_{j=1}^n \|F_j u_m - F_j u\|_{L^{p'}(\Omega, \omega)} + \|G u_m - G u\|_{L^{q'}(\Omega, v)}.$$

Therefore, using (4) and (5) we have $\|A u_m - A u\|_* \rightarrow 0$ as $m \rightarrow +\infty$, that is, A is continuous (and this implies that A is hemicontinuous).

Therefore, by Theorem 4, the operator equation $Au = T$ has a solution $u \in X$ and it is a solution for problem (1).

Step 6. Let us now prove the uniqueness of the solution. Suppose that $u_1, u_2 \in X$ are two solutions of problem (1). Then,

$$\begin{aligned}
 \int_{\Omega} |\Delta u_i|^{q-2} \Delta u_i \Delta \varphi v \, dx + \sum_{j=1}^n \int_{\Omega} \omega \mathcal{A}_j(x, u_i(x), \nabla u_i(x)) D_j \varphi \, dx \\
 = \int_{\Omega} f_0 \varphi \, dx + \sum_{j=1}^n \int_{\Omega} f_j D_j \varphi \, dx,
 \end{aligned}$$

for all $\varphi \in X$, and $i = 1, 2$. Hence, we obtain

$$\begin{aligned} & \int_{\Omega} \left(|\Delta u_1|^{q-2} \Delta u_1 - |\Delta u_2|^{q-2} \Delta u_2 \right) \Delta \varphi v \, dx \\ & + \int_{\Omega} \omega \left(\mathcal{A}(x, u_1(x), \nabla u_1(x)) - \mathcal{A}(x, u_2(x), \nabla u_2(x)) \right) \cdot \nabla \varphi \, dx = 0. \end{aligned}$$

In particular, for $\varphi = u_1 - u_2 \in X$ we have, by (H2) and Lemma 1(b) (analogous to Step 4),

$$\begin{aligned} 0 &= \int_{\Omega} \omega \left(\mathcal{A}(x, u_1, \nabla u_1) - \mathcal{A}(x, u_2, \nabla u_2) \right) \cdot \nabla (u_1 - u_2) \, dx \\ &+ \int_{\Omega} \left(|\Delta u_1|^{q-2} \Delta u_1 - |\Delta u_2|^{q-2} \Delta u_2 \right) \Delta (u_1 - u_2) v \, dx \\ &\geq \theta_1 \int_{\Omega} |\nabla (u_1 - u_2)|^p \omega \, dx + \beta_q \int_{\Omega} |\Delta (u_1 - u_2)|^q v \, dx. \end{aligned}$$

Hence, $\|\nabla(u_1 - u_2)\|_{L^p(\Omega, \omega)} = 0$ and $\|\Delta(u_1 - u_2)\|_{L^q(\Omega, v)} = 0$. Since $u_1, u_2 \in X$, then $u_1 = u_2$ μ_1 -a.e. Therefore, since $\omega \in A_p$, we obtain that $u_1 = u_2$ a.e.

Example 1. Consider $\Omega = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 < 1\}$, the weight functions $\omega(x, y) = (x^2 + y^2)^{-1/2}$ and $v(x, y) = (x^2 + y^2)^{-2/3}$ ($\omega \in A_3$ and $v \in A_2$, $p = 3$, $q = 2$), and the function

$$\begin{aligned} \mathcal{A}: \Omega \times \mathbb{R}^2 &\rightarrow \mathbb{R}^2 \\ \mathcal{A}((x, y), \eta, \xi) &= h_2(x, y) |\xi| \xi, \end{aligned}$$

where $h(x, y) = 2e^{(x^2+y^2)}$. Let us consider the partial differential operator

$$Lu(x, y) = \Delta((x^2 + y^2)^{-2/3} |\Delta u| \Delta u) - \operatorname{div}((x^2 + y^2)^{-1/2} \mathcal{A}((x, y), u, \nabla u)).$$

Therefore, by Theorem 1, the problem (1)

$$\begin{cases} Lu(x) = \frac{\cos(xy)}{(x^2 + y^2)} - \frac{\partial}{\partial x} \left(\frac{\sin(xy)}{(x^2 + y^2)} \right) - \frac{\partial}{\partial y} \left(\frac{\sin(xy)}{(x^2 + y^2)} \right), & \text{in } \Omega \\ u(x) = 0, & \text{on } \partial\Omega \\ \Delta u(x) = 0, & \text{on } \partial\Omega \end{cases}$$

has a unique solution $u \in X = W^{2,2}(\Omega, v) \cap W_0^{1,3}(\Omega, \omega)$.

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