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# ON ALMOST EVERYWHERE DIFFERENTIABILITY OF THE METRIC PROJECTION ON CLOSED SETS IN $l^{p}\left(\mathbb{R}^{n}\right), 2<p<\infty$ 

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Abstract. Let $F$ be a closed subset of $\mathbb{R}^{n}$ and let $P(x)$ denote the metric projection (closest point mapping) of $x \in \mathbb{R}^{n}$ onto $F$ in $l^{p}$-norm. A classical result of Asplund states that $P$ is (Fréchet) differentiable almost everywhere (a.e.) in $\mathbb{R}^{n}$ in the Euclidean case $p=2$. We consider the case $2<p<\infty$ and prove that the $i$ th component $P_{i}(x)$ of $P(x)$ is differentiable a.e. if $P_{i}(x) \neq x_{i}$ and satisfies Hölder condition of order $1 /(p-1)$ if $P_{i}(x)=x_{i}$.

Keywords: normed space; uniform convexity; closed set; metric projection; $l^{p}$-space; Fréchet differential; Lipschitz condition

MSC 2010: 26E25, 46B20, 49J50

## 1. Introduction

Let $\|\cdot\|$ be a norm on $\mathbb{R}^{n}$ and let $F$ be a closed subset of $\mathbb{R}^{n}$. For every $x \in \mathbb{R}^{n}$ we let $P(x)$ denote the metric projection of $x$ onto the set $F$, i.e. $P(x)$ is the set of points $\underline{P}(x)$ in $F$ satisfying

$$
\begin{equation*}
\|\underline{P}(x)-x\|=\inf _{y \in F}\|y-x\|=\operatorname{dist}(x, F) \tag{1}
\end{equation*}
$$

and $\operatorname{dist}(x, F)$ is the distance from $x$ to $F$. It was proved by Asplund [2] that $P(x)$ is Fréchet differentiable almost everywhere (a.e.) in $\mathbb{R}^{n}$ with the Euclidean norm. The key to the proof was Alexandroff's theorem in [10] stating that convex functions have second order differentials a.e. (Abazoglou in [1], Theorem 2, and Zajíček in [12], Theorem 4), extended this result to norms that are close to being Euclidean. In the two-dimensional case, $P$ is known to be Fréchet differentiable a.e. for any strictly convex norm, see [12], Theorem 3, which includes the $l^{p}$-norm, $1<p<\infty$. The present paper treats the $l^{p}$-norm, $2<p<\infty$, in spaces of dimension at least three, which is not covered by the results mentioned above.

The metric projection (closest point mapping) in finite dimensional spaces was studied at some length by Phelps in [8], [9]. The problem of the differentiability of $P(x)$ seems to first have been considered by Kruskal in [7]. He asked if the set of points $x \in \mathbb{R}^{n}$ and directions $v \in S^{n-1}$ such that $P(x)$ has a directional derivative at $x$ in the direction $v$, is dense in $\mathbb{R}^{n} \times S^{n-1}$. See Shapiro [11] and the references contained there for more on directional differentiability of the metric projection. Differentiability of metric projections in general Hilbert spaces is studied in [5]. Asplunds result gives an affirmative answer to Kruskal's question in the Euclidean case. It is the purpose of this paper to give a partial extension of Asplund's result to $2<p<\infty$. We prove that $P_{i}(x)$ is differentiable for a.e. $x$ such that $P_{i}(x)-x_{i} \neq 0$ and that $P_{i}(x)$ satisfies Lipschitz condition if $P_{i}(x)-x_{i}=0$, where $P_{i}(x)$ is the $i$ th coordinate of $P(x)$. We state our result as follows.

Theorem 1. Let $2<p<\infty$, let $F$ be a closed subset of $\mathbb{R}^{n}$ and let $P(x)$ denote the metric projection onto $F$ defined in (1) by the $l^{p}$-norm. Then $P(x)$ is single valued and continuous for a.e. $x$ in $\mathbb{R}^{n}$. Further,
(a) $P_{i}(x)$ is Fréchet differentiable for a.e. $x$ such that $P_{i}(x)-x_{i} \neq 0$,
(b) $P_{i}(x)$ satisfies $P_{i}(x+h)-P_{i}(x)=O\left(\|h\|_{p}^{1 /(p-1)}\right)$, as $h \rightarrow 0$, for a.e. $x$ such that $P_{i}(x)-x_{i}=0$.

Remark. It remains an open question if $P_{i}(x)$ is differentiable a.e. for closed sets $F$ or at least for convex sets, when $P_{i}(x)-x_{i}=0$.

The proof of the theorem uses Asplund's idea to define a convex auxiliary function whose differential is closely connected to $P(x)$. The new idea is the map $D_{p}: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ and its differentiability properties.

The organisation of this paper is as follows. Section 2 gives our notation, definitions and three propositions. The proof of the theorem is given in Section 4 after some lemmas have been proved in Section 3.

## 2. Preliminaries

We consider $\mathbb{R}^{n}$ with points $x=\left(x_{1}, \ldots, x_{n}\right)$ and let $l^{p}=l^{p}\left(\mathbb{R}^{n}\right), 1<p<\infty$, denote $\mathbb{R}^{n}$ with the norm

$$
\|x\|_{p}=\left(\sum_{i=1}^{n}\left|x_{i}\right|^{p}\right)^{1 / p}
$$

Then $l^{p}$ is an $n$-dimensional and uniformly convex Banach space with dual space $l^{q}$, $p^{-1}+q^{-1}=1$, see [3] and [6]. Let $F$ be a closed set in $\mathbb{R}^{n}$ and define the metric projection $P(x)$ onto $F$ by (1). The map $P(x)$ is in general multiple valued and we
denote by $\underline{P}(x)$ any choice of an element in $P(x)$. We say that $P(x)$ is continuous at the point $x$ if $P(x)$ is single valued at $x$ and $\underline{P}(x+h)=P(x)+o(1)$, as $h \rightarrow 0$, for all $\underline{P}(x+h)$ in $P(x+h)$. Similarily, $P(x)$ is Fréchet differentiable at $x$ if $P(x)$ is single valued at $x$ and there is an $n \times n$-matrix $M$ such that

$$
\begin{equation*}
\underline{P}(x+h)=P(x)+M \cdot h+o\left(\|h\|_{p}\right), \text { as } \quad h \rightarrow 0 \tag{2}
\end{equation*}
$$

for all $\underline{P}(x+h)$ in $P(x+h)$. In the following, differentiability always means Fréchet differentiability in this sense. Before we prove Theorem 1 we prepare the way by a series of propositions, which we give in a more general form than is actually needed for the proof. In the following three propositions we assume that $\|\cdot\|$ is any uniformly convex norm on $\mathbb{R}^{n}$ and that $\|x\|$ is differentiable for $x \neq 0$. We denote any such space $\left(\mathbb{R}^{n},\|\cdot\|\right)$ by $B$. Let $P(x)$ be the metric projection defined by (1) onto a closed set $F$ and let $f(x)=\|P(x)-x\|$ be the distance between $x$ and $F$. Then $f$ satisfies Lipschitz condition $|f(x)-f(y)| \leqslant\|x-y\|$ and hence $f$ is differentiable a.e. in $\mathbb{R}^{n}$ by the Rademacher-Stepanoff theorem in [4], p. 216.

Proposition 1. For a.e. $x \in F$ we have $f^{\prime}(x)=0$ and $P^{\prime}(x)=I$, the identity $n \times n$ matrix.

Proof. Let $x \in F$ be a point where $f^{\prime}(x)$ exists, then $0 \leqslant\|P(x+h)-x-h\|=$ $f(x+h)-f(x)=f^{\prime}(x) h+o(\|h\|)$ gives $f^{\prime}(x)=0, P(x+h)-x-h=o(\|h\|)$, as $h \rightarrow 0$, and $P^{\prime}(x)=I$.

Proposition 1 shows that $P(x)$ is differentiable a.e. on $F$. Let $B^{\star}$ be the dual space of $B$ with norm $\|\cdot\|_{\star}$ and denote the pairing between $B$ and $B^{\star}$ by $\langle\cdot, \cdot\rangle$. For any $x \neq 0$ in $B$ there is $x^{\star} \in B^{\star}$ such that $\left\langle x^{\star}, x\right\rangle=\|x\|$ and $\left\|x^{\star}\right\|_{\star}=1$ by the Hahn-Banach theorem. We call $x^{\star}$ the support functional of $x$. It is easy to prove that $x^{\star}$ is unique and is given by the formula

$$
\left\langle x^{\star}, y\right\rangle=\lim _{t \rightarrow 0} \frac{\|x+t y\|-\|x\|}{t}, \quad y \in \mathbb{R}^{n}
$$

An immediate consequence of Proposition 1 and the definition of $x^{\star}$ is the following formula connecting $f^{\prime}(x)$ and $P(x)$, cf. [1], Lemma 4.

Proposition 2. Let $x \in \mathbb{R}^{n} \backslash F$ be a point where $f$ is differentiable. Then $P(x)$ is single valued and continuous at $x$ and $f^{\prime}(x)=(x-P(x))^{\star}$.

Proof. It is proved in [1], Lemma 4 that $P(x)$ is single valued and $f^{\prime}(x)=$ $(x-P(x))^{\star}$. We show that $P(x)$ is continuous at $x$. Choose sequences $\left(x_{i}\right)_{1}^{\infty}$ and
$\left(z_{i}\right)_{1}^{\infty}$ such that $x_{i} \rightarrow x$ and $z_{i} \in P\left(x_{i}\right)$, as $i \rightarrow \infty$. Then $\left(z_{i}\right)_{1}^{\infty}$ is bounded and we may assume that $\left(z_{i}\right)_{1}^{\infty}$ converges to $z \in F$. We get

$$
\begin{aligned}
\|x-P(x)\| & \leqslant\|x-z\| \leqslant\left\|x-x_{i}\right\|+\left\|x_{i}-z_{i}\right\|+\left\|z_{i}-z\right\| \\
& =\left\|x-x_{i}\right\|+f\left(x_{i}\right)+\left\|z_{i}-z\right\| \rightarrow f(x)=\|x-P(x)\|,
\end{aligned}
$$

as $i \rightarrow \infty$. Thus $z=P(x)$, since $P(x)$ is single valued, and $P(x)$ is continuous at $x$.

## 3. Some technical lemmas

This section contains a number of technical lemmas. Lemma 6 and 7 constitute the basis for the proof of Theorem 1 in the next section. We begin with an elementary inequality.

Lemma 1. Let $1<p<\infty$. Then there is $C_{p} \geqslant 1$ such that

$$
2^{p-1} \cdot|t|^{p}+2^{p-1}-|t+1|^{p} \leqslant C_{p} \cdot(t-1)^{2}, \quad-1 \leqslant t \leqslant 1,
$$

where $C_{p}=p / 2,1<p<2$ and $C_{p}=2^{p-2} \cdot\binom{p}{2}, 2 \leqslant p<\infty$. The constant $C_{p}$ for $2 \leqslant p<\infty$ is best possible.

Proof. Define

$$
g_{p}(t)=2^{p-1} \cdot|t|^{p}+2^{p-1}-|t+1|^{p}-C_{p} \cdot(t-1)^{2}, \quad-1 \leqslant t \leqslant 1 .
$$

We first let $2<p<\infty$, noting that $g_{2}(t) \equiv 0$. If $0<t<1$, an easy calculation shows that $g_{p}^{\prime \prime}(t)<0$ and $g_{p}^{\prime}(t) \geqslant g_{p}^{\prime}(1)=0$. Hence, $g_{p}(t) \leqslant g_{p}(1)=0$, for $0 \leqslant t \leqslant 1$. If $-1<t<0$, then $g_{p}^{(3)}(t)<0, g_{p}^{\prime \prime}(t)$ has a unique zero at $t_{0}$ in $(-1,0)$ and $g_{p}^{\prime}(t)$ has its maximum at $t_{0}$. Since both $g_{p}^{\prime}(0)$ and $g_{p}^{\prime}(-1)$ are positive, we have $g_{p}^{\prime}(t)>0$ and hence $g_{p}(t) \leqslant g_{p}(0)<0$ for $-1 \leqslant t \leqslant 0$. The case $1<p<2$ is proved in a similar way. To show that $C_{p}$ is best possible for $2 \leqslant p<\infty$, take $t=1-h$ and let $h \rightarrow 0$.

Lemma 2. Let $2 \leqslant p<\infty$. Then

$$
2^{p-1} \cdot|x|^{p}+2^{p-1} \cdot|y|^{p}-|x+y|^{p} \leqslant C_{p} \cdot R^{p-2} \cdot|x-y|^{2}
$$

for all real numbers $x, y$ such that $|x| \leqslant R$ and $|y| \leqslant R$, where $C_{p}$ is the constant in Lemma 1.

Proof. Assume that $|x| \leqslant|y|$ and take $t=x / y$ in Lemma 1.

For any nonzero vector $x$ in $l^{p}\left(\mathbb{R}^{n}\right), 1<p<\infty$, the dual vector $x^{\star}$ is given by $x^{\star}=\|x\|_{p}^{1-p} \cdot\left(\left|x_{1}\right|^{p-2} \cdot x_{1}, \ldots,\left|x_{n}\right|^{p-2} \cdot x_{n}\right)$. The following closely related map $D_{p}$ will be used in our proof of Theorem 1. Let $1<p<\infty$ and define a one-to-one $\operatorname{map} D_{p}$ of $\mathbb{R}^{n}$ onto $\mathbb{R}^{n}$ by $D_{p}(0)=0$ and

$$
D_{p}(x)=\left(\frac{1}{p} \cdot\|x\|_{p}^{p}\right)^{\prime}=\left(\left|x_{1}\right|^{p-2} \cdot x_{1}, \ldots,\left|x_{n}\right|^{p-2} \cdot x_{n}\right)
$$

for $x \neq 0$, where $\left|x_{i}\right|^{p-2} \cdot x_{i}=0$ if $x_{i}=0$. Note that $D_{2}$ is the identity map.
Lemma 3. Let $1<p<\infty$. Then $D_{p}$ is an injective map of $\mathbb{R}^{n}$ onto $\mathbb{R}^{n}$ with inverse $D_{p}^{-1}(x)=D_{q}(x)$ and $\left\|D_{p}(x)\right\|_{q}^{q}=\|x\|_{p}^{p}$, where $1 / p+1 / q=1$.

Proof. It is clear that $D_{p}(x)=0$ if only if $x=0$. Let $x \neq 0$ and $D_{p}(x)=y$, then

$$
\left|x_{i}\right|^{p-2} \cdot x_{i}=y_{i}, \quad\left|x_{i}\right|=\left|y_{i}\right|^{q-1}
$$

and $x_{i}=\left|y_{i}\right|^{q-2} \cdot y_{i}, 1 \leqslant i \leqslant n$, i.e. $x=D_{q}(y)$. Further, $\|y\|_{q}^{q}=\|x\|_{p}^{p}$, which completes the proof of Lemma 3.

Lemma 4. Let $2 \leqslant p<\infty$. Then $D_{p}(x)$ is Fréchet differentiable for all $x \in \mathbb{R}^{n}$ and $D_{p}^{\prime}(x)$ is given by the diagonal matrix

$$
D_{p}^{\prime}(x)=(p-1) \cdot\left(\left|x_{i}\right|^{p-2} \cdot \delta_{i, j}\right),
$$

where $\delta_{i, j}$ is the Dirac delta function.
Proof. This follows at once from the definition of $D_{p}(x)$.
Remark. Clearly, $D_{2}^{\prime}(x)$ is simply the $n \times n$ identity matrix and $D_{p}^{\prime}(x)$ is invertible at $x$ if and only if $x$ has all its coordinates nonzero. If $x \in \mathbb{R}^{n}$ and $x_{i} \neq 0$, then for the $i$ th coordinate we have

$$
D_{p}(x+h)_{i}=D_{p}(x)_{i}+(p-1) \cdot\left|x_{i}\right|^{p-2} \cdot h_{i}+o\left(\|h\|_{2}\right),
$$

for any $1<p<\infty$.
Our main tool in the proof of Theorem 1 is the auxiliary function $K_{p}(x)$ defined as

$$
\begin{equation*}
K_{p}(x)=-\|x-P(x)\|_{p}^{p}+\lambda \cdot\|x\|_{2}^{2}, \tag{3}
\end{equation*}
$$

where $\lambda>0$ is to be defined below. Note the close relation between $K_{p}(x)$ and $P(x)$. Then $K_{p}(x)$ coincides with the corresponding auxiliary functions in [2] and [1] for
$p=2$. The assumption on the norm in [1] is however not satisfied in the present case, since $\left(\|x\|_{p}^{p}\right)^{\prime \prime}=p \cdot D_{p}^{\prime}(x)$ is not always invertible. The main property of $K_{p}(x)$ is its local convexity for suitable choices of $\lambda$. More exactly, we have the following lemma.

Lemma 5. Let $2<p<\infty$. Then for every $R>0$ there is a number $\lambda=$ $\lambda(F, p, R)>0$ such that $K_{p}(x)$ is convex for $\|x\|_{p}<R$.

Proof. Since $K_{p}(x)$ is continuous, it is sufficient to prove that it is also midpoint convex. It turns out to be sufficient to prove that if $\|x\|_{p}<R$ and $\|y\|_{p}<R$, then

$$
\begin{equation*}
2^{p-1} \cdot\|x+z\|_{p}^{p}+2^{p-1} \cdot\|y+z\|_{p}^{p}-\|x+y+2 z\|_{p}^{p} \leqslant \lambda \cdot\|x-y\|_{2}^{2}, \tag{4}
\end{equation*}
$$

where $z=-\frac{1}{2} P(x+y)$, provided $\lambda$ is large enough, cf. [1] Lemma 6. Then (4) follows from Lemma 2 applied to each coordinate separately with $\lambda=C_{p} \cdot R^{p-2} \cdot n$, since $\|x\|_{p} \leqslant R$ implies $\left|x_{i}\right| \leqslant R, 1 \leqslant i \leqslant n$.

The next two lemmas on the connection between $K_{p}(x)$ and $P(x)$ are the keys to the proof of Theorem 1.

Lemma 6. Let $1<p<\infty$ and let $U$ be an open set where $K_{p}(x)$ is convex and let $\underline{P}(y)$ be any choice for $P(y), y \in U$. Define

$$
\underline{K}_{p}^{\prime}(y)=2 \lambda \cdot y-p \cdot D_{p}(y-\underline{P}(y))
$$

Then $\underline{K}_{p}^{\prime}(y)$ is a subdifferential of $K_{p}(y)$.
Proof. Let $y \in U$ be fixed and choose $\left\{y_{j}\right\}_{1}^{\infty}$ in $U$ such that $y_{j} \rightarrow y$, as $j \rightarrow \infty$, and $f$ is differentiable at $y_{j}, j \geqslant 1$. Then by the convexity of $K_{p}$,

$$
K_{p}\left(y_{j}+h\right) \geqslant K_{p}\left(y_{j}\right)+K_{p}^{\prime}\left(y_{j}\right) \cdot h
$$

for all $j \geqslant 1$ and any sufficiently small $h$. Fix any such $h$, then clearly $K_{p}\left(y_{j}+h\right) \rightarrow$ $K_{p}(y+h)$ and $K_{p}\left(y_{j}\right) \rightarrow K_{p}(y)$, as $j \rightarrow \infty$, by the continuity of $K_{p}$. The lemma follows from the continuity of $D_{p}$ if for every $x \in \underline{P}(y)$ we can choose $\left\{y_{j}\right\}_{1}^{\infty}$ such that also $P\left(y_{j}\right) \rightarrow x$, as $j \rightarrow \infty$. We note that if $z=y+t(x-y), 0<t<1$, then $P(z)=x$ and any $w$ close to $z$ has projection close to $x$, by the uniform convexity of the norm. This completes the proof of Lemma 6.

Lemma 7. Let $1<p<\infty$, let $U$ be an open, convex set, where $K_{p}(y)$ is convex and let $\underline{K}_{p}^{\prime}(y)$ be defined as in Lemma 7. Then if $x$ is any point in $U$, where $f$ is differentiable and $K_{p}^{\prime \prime}(x)$ exists, we have

$$
\underline{K}_{p}^{\prime}(x+h)=K_{p}^{\prime}(x)+K_{p}^{\prime \prime}(x) h+o\left(\|h\|_{2}\right), \quad \text { as } h \rightarrow 0
$$

The following proof is found in [1], p. 495 and is due to Fitzpatrick.
Proof. Let $R>0$ be arbitrary and choose $\lambda$ as in Lemma 6 such that $K_{p}(x)$ is convex for $[[x]]_{p}<R$. Then $K_{p}(x)$ is a.e. twice differentiable for $\|x\|_{p}<R$ by Alexandrov's theorem. Fix any such point $x$, then for every $0<\varepsilon<1$ there is $\delta>0$ such that if $\|y-x\|_{2}<\delta$, then

$$
\begin{equation*}
\left|K_{p}(y)-K_{p}(x)-\left\langle K_{p}^{\prime}(x), y-x\right\rangle-\frac{1}{2}\left\langle K_{p}^{\prime \prime}(x)(y-x), y-x\right\rangle\right| \leqslant \varepsilon\|y-x\|_{2}^{2} . \tag{5}
\end{equation*}
$$

Let $\|z\|_{2}=\|w\|_{2}=1,0<|t|<\delta$ and $\alpha=\sqrt{\varepsilon} \cdot t$. Then by properties of the subdifferential

$$
\left\langle\underline{K}_{p}^{\prime}(x+t w), \alpha z\right\rangle \leqslant K_{p}(x+t w+\alpha z)-K_{p}(x+t w)
$$

and by (5) we get

$$
K_{p}(x+t w+\alpha z) \leqslant 4 \varepsilon|t|^{2}+K_{p}(x)+\left\langle K_{p}^{\prime}(x), t w+\alpha z\right\rangle+\frac{1}{2}\left\langle K_{p}^{\prime \prime}(x)(t w+\alpha z), t w+\alpha z\right\rangle
$$

and

$$
\left.K_{p}(x+t w) \geqslant-\varepsilon|t|^{2}+K_{p}(x)+\left\langle K_{p}^{\prime}(x), t w\right\rangle+\frac{1}{2} K_{p}^{\prime \prime}(t w), t w\right\rangle .
$$

Combining the last three inequalities we obtain

$$
\begin{aligned}
\left\langle\underline{K}_{p}^{\prime}(x+t w), \alpha z\right\rangle \leqslant & 5 \varepsilon|t|^{2}+\left\langle K_{p}(x), \alpha z\right\rangle+\frac{1}{2}\left\langle K_{p}^{\prime \prime}(x)(t w), \alpha z\right\rangle \\
& +\frac{1}{2}\left\langle K_{p}^{\prime \prime}(x)(\alpha z), t w\right\rangle+\frac{1}{2}\left\langle K_{p}^{\prime \prime}(x)(\alpha z), \alpha z\right\rangle+5 \varepsilon|t|^{2} \\
= & \left\langle K_{p}^{\prime}(x), \alpha z\langle+\rangle K_{p}^{\prime \prime}(x)(t w), \alpha z\right\rangle+5 \varepsilon|t|^{2}+\frac{1}{2} \alpha^{2}\left\langle K_{p}^{\prime \prime}(x)(z), z\right\rangle .
\end{aligned}
$$

Since $\alpha=\sqrt{\varepsilon}|t|^{2}$, we have

$$
\left\langle\underline{K}_{p}^{\prime}(x+t w)-K_{p}^{\prime}(x)-K_{p}^{\prime \prime}(x)(t w), z\right\rangle \leqslant 5 \sqrt{\varepsilon}|t|+\frac{1}{2} \sqrt{\varepsilon}|t|\left\langle K_{p}^{\prime \prime}(x)(z), z\right\rangle
$$

and equivalently

$$
\left\|\underline{K}_{p}^{\prime}(x+t w)-K_{p}^{\prime}(x)-K_{p}^{\prime \prime}(x)(t w)\right\|_{2} \leqslant\left(5+\frac{1}{2}\left\|K_{p}^{\prime \prime}(x)\right\|_{2}\right) \sqrt{\varepsilon}|t|=o(|t|),
$$

which proves Lemma 7.

## 4. Proof of Theorem 1

The proof of Theorem 1 is based on the properties of the auxiliary function $K_{p}(x)$ proved above and the map $D_{p}$.

Pro of of Theorem 1. We let $F$ be a closed set in $\mathbb{R}^{n}$ and let $P(x)$ denote the metric projection onto $F$. Since $P^{\prime}(x)=I$ a.e. in $F$ by Proposition 1, we assume that $x \in \mathbb{R}^{n} \backslash F$. Recall the distance function $f(x)=\|P(x)-x\|_{p}$ and the auxiliary function $K_{p}(x)$ defined by (3). Let $R>0$ be arbitrary and choose $\lambda$ as in Lemma 6 such that $K_{p}(x)$ is convex for $\|x\|_{p}<R$. Then $K_{p}(x)$ has a second order differentiable a.e. in $\|x\|_{p}<R$ by Alexandrov's theorem, see [10].

In the following, we let $x$ denote any point in $\mathbb{R}^{n} \backslash F$, where $f$ is differentiable, $K_{p}(x)$ has a second order differential and $\|x\|_{p}<R$. Then by Lemma 3 and Lemma 6 we have

$$
\begin{equation*}
\underline{P}(x+h)=x+h-D_{q}\left(\frac{2 \lambda}{p} \cdot(x+h)-\frac{1}{p} \cdot \underline{K}_{p}^{\prime}(x+h)\right) \tag{6}
\end{equation*}
$$

and further

$$
\begin{align*}
\underline{P}(x+h) & =x+h-D_{q}\left(\frac{2 \lambda}{p} \cdot(x+h)-\frac{1}{p} \cdot K_{p}^{\prime}(x)-\frac{1}{p} \cdot K_{p}^{\prime \prime}(x) h+o\left(\|h\|_{2}\right)\right)  \tag{7}\\
& =x+h-D_{q}\left(\frac{2 \lambda}{p} \cdot x-\frac{1}{p} \cdot K_{p}^{\prime}(x)+\frac{2 \lambda}{p} \cdot h-\frac{1}{p} \cdot K_{p}^{\prime \prime}(x) h+o\left(\|h\|_{2}\right)\right)
\end{align*}
$$

as $h \rightarrow 0$, by Lemma 4 and Lemma 7. Now assume that $P_{i}(x)-x_{i} \neq 0$, then the $i$ th coordinate of $2 \lambda \cdot x-K_{p}^{\prime}(x)$ is nonzero by Lemma 6. Let $z=\left(2 \lambda x-K_{p}^{\prime}(x)\right) / p$, then the $i$ th coordinate of the last term in (7) equals

$$
D_{q}(z)_{i}+(q-1) \cdot\left|z_{i}\right|^{q-1} \cdot\left(\frac{2 \lambda}{p} \cdot h_{i}-\frac{1}{p} \cdot\left(K_{p}^{\prime \prime}(x) h\right)_{i}\right)+o\left(\|h\|_{2}\right)
$$

by the remark following Lemma 4. It follows that there exists a vector $L_{i}$ in $\mathbb{R}^{n}$ such that

$$
\begin{equation*}
\underline{P}_{i}(x+h)=P_{i}(x)+\left\langle L_{i}, h\right\rangle+\varphi_{i}(h), \tag{8}
\end{equation*}
$$

where $\varphi_{i}(h)=o\left(\|h\|_{2}\right)$. More exactly, $L_{i}$ is a linear combination of the $i$ th unit row vector in $\mathbb{R}^{n}$ and the $i$ th row vector in $K_{p}^{\prime \prime}(x)$. Hence, $P_{i}$ is differentiable at $x$, which proves statement (a) in Theorem 1. If $P_{i}(x)=x_{i}$, (7) only gives the weaker result $P_{i}(x+h)-P_{i}(x)=O\left(\|h\|_{p}^{q-1}\right)$, as $h \rightarrow 0$, which proves (b).

Remark. It is tempting to guess that $P_{i}(x+h)-x_{i}-h_{i}=o\left(\|h\|_{p}\right)$, as $h \rightarrow 0$, when $x$ is a density point of the set $E$ where $P_{i}(x)=x_{i}$ for some $1 \leqslant i \leqslant n$. We have only the weaker result that the set $\left\{h:\left|\underline{P}_{i}(x+h)-x_{i}-h_{i}\right| \leqslant \varepsilon \cdot\|h\|_{p}\right\}$ has density one at $h=0$ for every $\varepsilon>0$. This is usually called an approximate derivative of $P_{i}$ at $x$.

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