

Bouzid Mansouri; Abdelouaheb Ardjouni; Ahcene Djoudi

Analysis of periodic solutions for nonlinear coupled integro-differential systems with variable delays

Commentationes Mathematicae Universitatis Carolinae, Vol. 63 (2022), No. 1, 51–68

Persistent URL: <http://dml.cz/dmlcz/150431>

Terms of use:

© Charles University in Prague, Faculty of Mathematics and Physics, 2022

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://dml.cz>

Analysis of periodic solutions for nonlinear coupled integro-differential systems with variable delays

BOUZID MANSOURI, ABDELOUAHEB ARDJOUNI, AHCENE DJOUDI

Abstract. The objective of this work is the application of Krasnosel'skii's fixed point technique to prove the existence of periodic solutions of a system of coupled nonlinear integro-differential equations with variable delays. An example is given to illustrate this work.

Keywords: integro-differential equation; periodic solution; Krasnosel'skii's fixed point theorem

Classification: 34K20, 45J05, 45D05

1. Introduction

There are many papers written on the subject of existence of periodic solutions of nonlinear differential equations and nonlinear integro-differential equations, for such topics we refer the interested reader to [1]–[7], [10], [12] and the references therein. In 2007, in the paper [14] Y. Wang, H. Lian and W. Ge consider the second order nonlinear differential equation

$$x''(t) + p(t)x'(t) + q(t)x(t) = r(t)x'(t - \tau(t)) + f(t, x(t), x(t - \tau(t))),$$

and by using fixed point theorem technique, the authors obtained existence of periodic solutions. H. Deham in [8] considers the second order nonlinear integro-differential equation

$$x''(t) + p(t)x'(t) + q(t)h(x(t)) = \int_{-\infty}^t Q(t, s)f(s, x(s - g(s))) ds,$$

and by Krasnosel'skii–Burton's fixed point theorem shows that the existence of periodic solutions is concluded. In the paper [11] Y. N. Raffoul studies the existence of periodic and asymptotically periodic solutions of the following system of

coupled nonlinear Volterra integro-differential equations with infinite delay

$$\begin{cases} x'(t) = h_1(t)x(t) + h_2(t)y(t) + \int_{-\infty}^t a(t, s)f(x(s), y(s)) ds, \\ y'(t) = p_1(t)y(t) + p_2(t)x(t) + \int_{-\infty}^t b(t, s)g(x(s), y(s)) ds, \end{cases}$$

the author uses Schauder's fixed point theorem to obtain his results.

Motivated by the papers [8], [11], [14] and the references therein and by using Krasnosel'skii's fixed point theorem, in this paper we study the existence of periodic solutions of the following system of coupled nonlinear integro-differential equations with variable delays

$$(1.1) \quad \begin{aligned} x_i''(t) + p_i(t)x_i'(t) + q_i(t)x_i(t) \\ = g_i(t, x_1(t), x_2(t), x_1(t - \tau_1(t)), x_2(t - \tau_2(t))) \\ + c_i(t)x_i'(t - \tau_i(t)) \\ + \int_{-\infty}^t C_i(t, s)f_i(x_1(s), x_2(s)) ds, \quad i = 1, 2, \end{aligned}$$

where $p_i, q_i, i = 1, 2$, are positive continuous real-valued functions and the functions $c_i, C_i, i = 1, 2$, are assumed to be continuous in their arguments throughout the paper. The functions $g_i(t, x, y, z, w), i = 1, 2$, are continuous, periodic in t and Lipschitz continuous in x, y, z and w , $f_i(x, y), i = 1, 2$, are continuous and Lipschitz continuous in x and y , and for some positive constants $\eta_{ji}, j = 1, \dots, 4$, and $i = 1, 2$, we have

$$|g_i(t, y_1, y_2, y_3, y_4) - g_i(t, x_1, x_2, x_3, x_4)| \leq \sum_{j=1}^4 \eta_{ji}|y_j - x_j|,$$

and for some positive constants $\varrho_{ji}, j = 1, 2$, and $i = 1, 2$, we have

$$|f_i(y_1, y_2) - f_i(x_1, x_2)| \leq \sum_{j=1}^2 \varrho_{ji}|y_j - x_j|,$$

we also assume that $g_i(t, 0, 0, 0, 0) = f_i(0, 0) = 0$.

We assume that there exists a positive real number T , such that

$$(1.2) \quad \begin{cases} C_i(t+T, s+T) = C_i(t, s), \\ c_i(t+T) = c_i(t), \quad \tau_i(t+T) = \tau_i(t), \end{cases} \quad i = 1, 2,$$

for all $t \in \mathbb{R}$, with τ_i being scalar functions, continuous and $\tau_i(t) \geq \tau_i^* > 0$, $\tau_i'(t) \neq 1$.

To have a well behaved mapping we must assume that

$$(1.3) \quad \begin{cases} p_i(t+T) = p_i(t), & \int_0^T p_i(s) ds > 0, \\ q_i(t+T) = q_i(t), & \int_0^T q_i(s) ds > 0, \end{cases} \quad i = 1, 2.$$

Define

$$P_T = \{x \in C(\mathbb{R}, \mathbb{R}) : x(t+T) = x(t)\},$$

$$P_T^2 = P_T \times P_T = \{(x_1, x_2) : x_1 \in P_T, x_2 \in P_T\}.$$

Then P_T^2 is a Banach space when endowed with the maximum norm

$$\|(x_1, x_2)\| = \max \left\{ \max_{t \in [0, T]} |x_1(t)|, \max_{t \in [0, T]} |x_2(t)| \right\}.$$

Lemma 1.1 ([9]). *Suppose that (1.2) and (1.4) hold and for $i = 1, 2$,*

$$(1.4) \quad \frac{R_i}{Q_i T} (e^{\int_0^T p_i(u) du} - 1) \geq 1,$$

where

$$R_i = \max_{t \in [0, T]} \left| \int_t^{t+T} \frac{e^{\int_t^s p_i(u) du}}{e^{\int_0^T p_i(u) du} - 1} q_i(s) ds \right|, \quad Q_i = (1 + e^{\int_0^T p_i(u) du})^2 R_i^2.$$

Then there are continuous T -periodic functions a_i and b_i such that

$$b_i(t) > 0, \quad \int_0^T a_i(u) du > 0,$$

and

$$a_i(t) + b_i(t) = p_i(t), \quad b_i'(t) + a_i(t)b_i(t) = q_i(t) \quad \text{for all } t \in \mathbb{R}.$$

Lemma 1.2 ([14]). *Suppose the conditions of Lemma 1.1 hold and $\varphi_i \in P_T$, $i = 1, 2$. Then the equation*

$$x_i''(t) + p_i(t)x_i'(t) + q_i(t)x_i(t) = \varphi_i(t),$$

has a T -periodic solution. Moreover, the periodic solution can be expressed as

$$x_i(t) = \int_t^{t+T} G_i(t, s) \varphi_i(s) ds,$$

where

$$G_i(t, s) = \frac{\int_t^s e^{\int_t^u b_i(v) dv} + \int_u^s a_i(v) dv du + \int_s^{t+T} e^{\int_t^u b_i(v) dv} + \int_u^{s+T} a_i(v) dv du}{(e^{\int_0^T a_i(u) du} - 1)(e^{\int_0^T b_i(u) du} - 1)}.$$

Corollary 1.3 ([14]). *Green's functions G_i , $i = 1, 2$, satisfies the following properties*

$$\begin{aligned} G_i(t, t+T) &= G_i(t, t), & G_i(t+T, s+T) &= G_i(t, s), \\ \frac{\partial}{\partial s} G_i(t, s) &= a_i(s)G_i(t, s) - H_i(t, s), \\ \frac{\partial}{\partial t} G_i(t, s) &= -b_i(t)G_i(t, s) + H_i^*(t, s), \end{aligned}$$

where

$$H_i(t, s) = \frac{e^{\int_t^s b_i(v) dv}}{e^{\int_0^T b_i(v) dv} - 1}, \quad H_i^*(t, s) = \frac{e^{\int_t^s a_i(v) dv}}{e^{\int_0^T a_i(v) dv} - 1}.$$

Lemma 1.4. *Assume (1.2)–(1.4). If $(x_1, x_2) \in P_T^2$, then x_i is a solution of (1.1) if and only if*

$$\begin{aligned} (1.5) \quad x_i(t) &= \int_t^{t+T} G_i(t, u) g_i(u, x_1(u), x_2(u), x_1(u - \tau_1(u)), x_2(u - \tau_2(u))) du \\ &+ \int_t^{t+T} G_i(t, u) \int_{-\infty}^u C_i(u, s) f_i(x_1(s), x_2(s)) ds du \\ &+ \int_t^{t+T} [h_i(u)H_i(t, u) - r_i(u)G_i(t, u)] x_i(u - \tau_i(u)) du, \quad i = 1, 2, \end{aligned}$$

where

$$(1.6) \quad h_i(u) = \frac{c_i(u)}{1 - \tau_i'(u)}, \quad i = 1, 2,$$

$$(1.7) \quad r_i(u) = \frac{(a_i(u)c_i(u) + c_i'(u))(1 - \tau_i'(u)) + \tau_i''(u)c_i(u)}{(1 - \tau_i'(u))^2}, \quad i = 1, 2.$$

PROOF: Let $(x_1, x_2) \in P_T^2$ be a solution of (1.1). From Lemma 1.2 we have

$$\begin{aligned} (1.8) \quad x_i(t) &= \int_t^{t+T} G_i(t, u) g_i(u, x_1(u), x_2(u), x_1(u - \tau_1(u)), x_2(u - \tau_2(u))) du \\ &+ \int_t^{t+T} G_i(t, u) c_i(u) x_i'(u - \tau_i(u)) du \\ &+ \int_t^{t+T} G_i(t, u) \int_{-\infty}^u C_i(u, s) f_i(x_1(s), x_2(s)) ds du, \quad i = 1, 2. \end{aligned}$$

Letting

$$\int_t^{t+T} G_i(t, u) c_i(u) x_i'(u - \tau_i(u)) du = \int_t^{t+T} \frac{G_i(t, u) c_i(u)}{1 - \tau_i'(u)} (1 - \tau_i'(u)) x_i'(u - \tau_i(u)) du,$$

performing an integration by parts, we get

$$\int_t^{t+T} G_i(t, u)c_i(u)x'_i(u - \tau_i(u)) \, du = \left[\frac{G_i(t, u)c_i(u)}{1 - \tau'_i(u)} x_i(u - \tau_i(u)) \right]_t^{t+T} - \int_t^{t+T} [r_i(u)G_i(t, u) - h_i(u)H_i(t, u)]x_i(u - \tau_i(u)) \, du.$$

Since

$$\left[\frac{G_i(t, u)c_i(u)}{1 - \tau'_i(u)} x_i(u - \tau_i(u)) \right]_t^{t+T} = 0,$$

we obtain

$$(1.9) \quad \int_t^{t+T} G_i(t, u)c_i(u)x'_i(u - \tau_i(u)) \, du = \int_t^{t+T} [h_i(u)H_i(t, u) - r_i(u)G_i(t, u)]x_i(u - \tau_i(u)) \, du,$$

where h_i, r_i are given by (1.6) and (1.7). Substituting (1.9) into (1.8), we obtain

$$\begin{aligned} x_i(t) &= \int_t^{t+T} G_i(t, u)g_i(u, x_1(u), x_2(u), x_1(u - \tau_1(u)), x_2(u - \tau_2(u))) \, du \\ &+ \int_t^{t+T} G_i(t, u) \int_{-\infty}^u C_i(u, s)f_i(x_1(s), x_2(s)) \, ds \, du \\ &+ \int_t^{t+T} [h_i(u)H_i(t, u) - r_i(u)G_i(t, u)]x_i(u - \tau_i(u)) \, du, \quad i = 1, 2. \end{aligned}$$

□

Lemma 1.5 ([14]). *Let $\Gamma_i = \int_0^T p_i(u) \, du$, $\Lambda_i = T^2 e^{(1/T) \int_0^T \ln(q_i(u)) \, du}$, $i = 1, 2$. If $\Gamma_i^2 \geq 4\Lambda_i$, then we have*

$$\min \left\{ \int_0^T a_i(u) \, du, \int_0^T b_i(u) \, du \right\} \geq \frac{1}{2} \left(\Gamma_i - \sqrt{\Gamma_i^2 - 4\Lambda_i} \right) := l_i,$$

and

$$\max \left\{ \int_0^T a_i(u) \, du, \int_0^T b_i(u) \, du \right\} \leq \frac{1}{2} \left(\Gamma_i + \sqrt{\Gamma_i^2 - 4\Lambda_i} \right) := m_i.$$

Corollary 1.6 ([14]). *Functions G_i and H_i , $i = 1, 2$, satisfy*

$$\frac{T}{(e^{m_i} - 1)^2} \leq G_i(t, s) \leq \frac{T e^{\int_0^T p_i(v) \, dv}}{(e^{l_i} - 1)^2}, \quad |H_i(t, s)| \leq \frac{e^{m_i}}{e^{l_i} - 1}.$$

To simplify notation, we introduce for $i = 1, 2$, the constants

$$\begin{aligned}\alpha_i &= \frac{T e^{\int_0^T p_i(v) dv}}{(e^{T_i} - 1)^2}, & \gamma_i &= \frac{e^{m_i}}{e^{L_i} - 1}, & \theta_i &= \max_{t \in [0, T]} |h_i(t)|, \\ \beta_i &= \max_{t \in [0, T]} |r_i(t)|, & \lambda_i &= \max_{t \in [0, T]} |a_i(t)|, & \delta_i &= \max_{t \in [0, T]} |b_i(t)|.\end{aligned}$$

2. Periodic solutions

Lemma 2.1 ([13]). *Let \mathbb{M} be a closed convex nonempty subset of a Banach space $(S, \|\cdot\|)$. Suppose that A and B map \mathbb{M} into S such that*

- (i) $x, y \in \mathbb{M}$ implies $Ax + By \in \mathbb{M}$;
- (ii) A is compact and continuous;
- (iii) B is a contraction mapping.

Then there exists $z \in \mathbb{M}$ with $z = Az + Bz$.

We assume the existence of positive constants M_i, K_i and $L_i, i = 1, 2$, such that

$$(2.1) \quad |f_i(x, y)| \leq M_i,$$

$$(2.2) \quad |g_i(t, x, y, z, w)| \leq K_i,$$

and

$$(2.3) \quad \int_t^{t+T} \int_{-\infty}^u |C_i(u, s)| ds du \leq L_i.$$

Set

$$(2.4) \quad M = \max \left\{ \frac{(TK_i + L_i M_i) \alpha_i}{1 - T(\theta_i \gamma_i + \beta_i \alpha_i)} : i = 1, 2 \right\},$$

with $0 < T(\theta_i \gamma_i + \beta_i \alpha_i) < 1, i = 1, 2$.

We define subset Ω_M of P_T^2 as follows

$$\Omega_M = \{(x_1, x_2) \in P_T^2 : \|(x_1, x_2)\| \leq M\}.$$

Then Ω_M is a bounded, closed and convex subset of P_T^2 .

Now for $(x_1, x_2) \in \Omega_M$ we can define an operator $E: \Omega_M \rightarrow P_T^2$ by

$$E(x_1, x_2)(t) = (E_1(x_1, x_2)(t), E_2(x_1, x_2)(t)),$$

where

$$\begin{aligned}
 E_i(x_1, x_2)(t) &= \int_t^{t+T} G_i(t, u) g_i(u, x_1(u), x_2(u), \\
 &\quad x_1(u - \tau_1(u)), x_2(u - \tau_2(u))) \, du \\
 (2.5) \quad &+ \int_t^{t+T} G_i(t, u) \int_{-\infty}^u C_i(u, s) f_i(x_1(s), x_2(s)) \, ds \, du \\
 &+ \int_t^{t+T} [h_i(u) H_i(t, u) - r_i(u) G_i(t, u)] x_i(u - \tau_i(u)) \, du, \\
 &\quad i = 1, 2.
 \end{aligned}$$

To apply Lemma 2.1, we need to construct two mappings, one is a contraction and the other is compact. Therefore, we state (2.5) as

$$E_i(x_1, x_2)(t) = B_i(x_1, x_2)(t) + A_i(x_1, x_2)(t), \quad i = 1, 2,$$

where $B_i, A_i: \Omega_M \rightarrow P_T$ are given by

$$B_i(x_1, x_2)(t) = \int_t^{t+T} G_i(t, u) g_i(u, x_1(u), x_2(u), x_1(u - \tau_1(u)), x_2(u - \tau_2(u))) \, du,$$

and

$$\begin{aligned}
 A_i(x_1, x_2)(t) &= \int_t^{t+T} G_i(t, u) \int_{-\infty}^u C_i(u, s) f_i(x_1(s), x_2(s)) \, ds \, du \\
 &+ \int_t^{t+T} [h_i(u) H_i(t, u) - r_i(u) G_i(t, u)] x_i(u - \tau_i(u)) \, du.
 \end{aligned}$$

Now for $(x_1, x_2) \in \Omega_M$ we can define the operators $B, A: \Omega_M \rightarrow P_T^2$ by

$$\begin{aligned}
 B(x_1, x_2)(t) &= (B_1(x_1, x_2)(t), B_2(x_1, x_2)(t)), \\
 A(x_1, x_2)(t) &= (A_1(x_1, x_2)(t), A_2(x_1, x_2)(t)).
 \end{aligned}$$

Observe that, since the functions $g_i(t, x_1, x_2, x_3, x_4)$, $i = 1, 2$, is Lipschitz continuous in x_1, x_2, x_3, x_4 and $f_i(x_1, x_2)$, $i = 1, 2$, is Lipschitz continuous in x_1, x_2 we have

$$\begin{aligned}
 |g_i(t, x_1, x_2, x_3, x_4)| &= |g_i(t, x_1, x_2, x_3, x_4) - g_i(t, 0, 0, 0, 0) + g_i(t, 0, 0, 0, 0)| \\
 &\leq |g_i(t, x_1, x_2, x_3, x_4) - g_i(t, 0, 0, 0, 0)| + |g_i(t, 0, 0, 0, 0)| \\
 &\leq \sum_{j=1}^4 \eta_{ji} |x_j|,
 \end{aligned}$$

and

$$\begin{aligned}
|f_i(x_1, x_2)| &= |f_i(x_1, x_2) - f_i(0, 0) + f_i(0, 0)| \\
&\leq |f_i(x_1, x_2) - f_i(0, 0)| + |f_i(0, 0)| \leq \sum_{j=1}^2 \varrho_{ji} |x_j|.
\end{aligned}$$

Theorem 2.2. *Suppose (1.2)–(1.4) and (2.1)–(2.3) hold. Suppose that*

$$L_i \alpha_i \sum_{j=1}^2 \varrho_{ji} + T(\theta_i \gamma_i + \beta_i \alpha_i) \leq 1, \quad i = 1, 2,$$

and $2T\alpha_i V_i < 1$, $i = 1, 2$, where $V_i = \max(\eta_{1i} + \eta_{3i}, \eta_{2i} + \eta_{4i})$. Then (1.1) has a T -periodic solution.

PROOF: In order to prove that (1.1) has a T -periodic solution, we shall make sure that A and B satisfy the conditions of Lemma 2.1. For all $(x_1, x_2) \in \Omega_M$, we have $(x_1, x_2)(t + T) = (x_1, x_2)(t)$ and $\|(x_1, x_2)\| \leq M$. Now let us discuss $B(x_1, x_2) + A(x_1, x_2)$. We have

$$\begin{aligned}
&B_i(x_1, x_2)(t + T) \\
&= \int_{t+T}^{t+2T} G_i(t + T, u) g_i(u, x_1(u), x_2(u), x_1(u - \tau_1(u)), x_2(u - \tau_2(u))) \, du \\
&= \int_t^{t+T} G_i(t, u) g_i(u, x_1(u), x_2(u), x_1(u - \tau_1(u)), x_2(u - \tau_2(u))) \, du \\
&= B_i(x_1, x_2)(t), \quad i = 1, 2,
\end{aligned}$$

and

$$\begin{aligned}
&A_i(x_1, x_2)(t + T) \\
&= \int_{t+T}^{t+2T} G_i(t + T, u) \int_{-\infty}^u C_i(u, s) f_i(x_1(s), x_2(s)) \, ds \, du \\
&\quad + \int_{t+T}^{t+2T} [h_i(u) H_i(t + T, u) - r_i(u) G_i(t + T, u)] x_i(u - \tau_i(u)) \, du \\
&= \int_t^{t+T} G_i(t, u) \int_{-\infty}^u C_i(u, s) f_i(x_1(s), x_2(s)) \, ds \, du \\
&\quad + \int_t^{t+T} [h_i(u) H_i(t, u) - r_i(u) G_i(t, u)] x_i(u - \tau_i(u)) \, du \\
&= A_i(x_1, x_2)(t), \quad i = 1, 2.
\end{aligned}$$

Then $E_i(x_1, x_2)(t + T) = E_i(x_1, x_2)(t)$, $i = 1, 2$. Therefore, $E(x_1, x_2)(t + T) = E(x_1, x_2)(t)$.

For any $(x_1, x_2) \in \Omega_M$, we will show that $|E(x_1, x_2)(t)| \leq M$. In view of the above estimates, we have for $i = 1, 2$,

$$\begin{aligned} & |B_i(x_1, x_2)(t)| \\ & \leq \int_t^{t+T} G_i(t, u) |g_i(u, x_1(u), x_2(u), x_1(u - \tau_1(u)), x_2(u - \tau_2(u)))| du \\ & \leq TK_i\alpha_i, \end{aligned}$$

and

$$\begin{aligned} |A_i(x_1, x_2)(t)| & \leq \int_t^{t+T} G_i(t, u) \int_{-\infty}^u |C_i(u, s)| |f_i(x_1(s), x_2(s))| ds du \\ & \quad + \int_t^{t+T} [|h_i(u)| |H_i(t, u)| + |r_i(u)| |G_i(t, u)| |x_i(u - \tau_i(u))|] du \\ & \leq L_i M_i \alpha_i + T(\theta_i \gamma_i + \beta_i \alpha_i) M. \end{aligned}$$

As a consequence of (2.4), we have

$$\frac{(TK_i + L_i M_i) \alpha_i}{1 - T(\theta_i \gamma_i + \beta_i \alpha_i)} \leq M,$$

so,

$$(TK_i + L_i M_i) \alpha_i \leq (1 - T(\theta_i \gamma_i + \beta_i \alpha_i)) M.$$

This implies that

$$\begin{aligned} |E_i(x_1, x_2)(t)| & \leq TK_i \alpha_i + L_i M_i \alpha_i + T(\theta_i \gamma_i + \beta_i \alpha_i) M \\ & \leq (1 - T(\theta_i \gamma_i + \beta_i \alpha_i)) M + T(\theta_i \gamma_i + \beta_i \alpha_i) M = M. \end{aligned}$$

Thus, E maps Ω_M into itself, i.e. $E(\Omega_M) \subseteq \Omega_M$.

We will now show that A is continuous. For $n \in \mathbb{N}$, let $\{(x_{1n}, x_{2n})\}$ be a sequence in Ω_M such that

$$\lim_{n \rightarrow \infty} \|(x_{1n}, x_{2n}) - (x_1, x_2)\| = 0.$$

Since Ω_M is closed, we have $(x_1, x_2) \in \Omega_M$. Then by the definition of A we have

$$\begin{aligned} \|A(x_{1n}, x_{2n}) - A(x_1, x_2)\| & = \max \left\{ \max_{t \in [0, T]} |A_1(x_{1n}, x_{2n})(t) - A_1(x_1, x_2)(t)|, \right. \\ & \quad \left. \max_{t \in [0, T]} |A_2(x_{1n}, x_{2n})(t) - A_2(x_1, x_2)(t)| \right\}, \end{aligned}$$

in which for $i = 1, 2$,

$$\begin{aligned} & |A_i(x_{1n}, x_{2n})(t) - A_i(x_1, x_2)(t)| \\ & \leq \int_t^{t+T} G_i(t, u) \int_{-\infty}^u |C_i(u, s)| |f_i(x_{1n}(s), x_{2n}(s)) - f_i(x_1(s), x_2(s))| ds du \\ & \quad + \int_t^{t+T} [|h_i(u)| |H_i(t, u)| + |r_i(u)| |G_i(t, u)|] |x_{in}(u - \tau_i(u)) - x_i(u - \tau_i(u))| du. \end{aligned}$$

The continuity of f_i along with the Lebesgue dominated convergence theorem implies that

$$\lim_{n \rightarrow \infty} \max_{t \in [0, T]} |A_i(x_{1n}, x_{2n})(t) - A_i(x_1, x_2)(t)| = 0.$$

Thus

$$\lim_{n \rightarrow \infty} \|A(x_{1n}, x_{2n}) - A(x_1, x_2)\| = 0.$$

This result proves that A is continuous.

We now have to show that A is compact. For $n \in \mathbb{N}$, let $\{(x_{1n}, x_{2n})\}$ be a sequence in Ω_M , then we have for $i = 1, 2$,

$$\begin{aligned} |A_i(x_{1n}, x_{2n})(t)| & \leq \int_t^{t+T} G_i(t, u) \int_{-\infty}^u |C_i(u, s)| |f_i(x_{1n}(s), x_{2n}(s))| ds du \\ & \quad + \int_t^{t+T} [|h_i(u)| |H_i(t, u)| + |r_i(u)| |G_i(t, u)|] |x_{in}(u - \tau_i(u))| du \\ & \leq \left(L_i \alpha_i \sum_{j=1}^2 \varrho_{ji} + T(\theta_i \gamma_i + \beta_i \alpha_i) \right) M \leq M. \end{aligned}$$

Thus

$$\|A(x_{1n}, x_{2n})\| \leq M.$$

If we calculate $(A(x_{1n}, x_{2n}))'(t)$, then for $i = 1, 2$,

$$\begin{aligned} & (A_i(x_{1n}, x_{2n}))'(t) \\ & = \int_t^{t+T} [-b_i(t)G_i(t, u) + H_i^*(t, u)] \int_{-\infty}^u C_i(u, s) f_i(x_{1n}(s), x_{2n}(s)) ds du \\ & \quad + h_i(t)x_{in}(t - \tau_i(t)) - \int_t^{t+T} [b_i(t)(h_i(u)H_i(t, u) - r_i(u)G_i(t, u)) \\ & \quad + r_i(u)H_i^*(t, u)] x_{in}(u - \tau_i(u)) du. \end{aligned}$$

Hence, for some positive constant D_i , we obtain

$$\begin{aligned} & |(A_i(x_{1n}, x_{2n}))'(t)| \\ & \leq \int_t^{t+T} (|b_i(t)| |G_i(t, u)| + |H_i^*(t, u)|) \int_{-\infty}^u |C_i(u, s)| |f_i(x_{1n}(s), x_{2n}(s))| ds du \end{aligned}$$

$$\begin{aligned}
 & + |h_i(t)||x_{in}(t - \tau_i(t))| + \int_t^{t+T} [|b_i(t)|(|h_i(u)||H_i(t, u)| + |r_i(u)||G_i(t, u)| \\
 & + |r_i(u)||H_i^*(t, u)|)] |x_{in}(u - \tau_i(u))| du \\
 & \leq (\delta_i\alpha_i + \gamma_i)L_iM \sum_{j=1}^2 \varrho_{ji} + \theta_iM + T[\delta_i(\theta_i\gamma_i + \beta_i\alpha_i) + \beta_i\gamma_i]M \leq D_i.
 \end{aligned}$$

Thus

$$\|(A(x_{1n}, x_{2n}))'\| \leq D,$$

where $D = \max(D_1, D_2)$. Thus, the sequence $(A(x_{1n}, x_{2n}))$ is uniformly bounded and equi-continuous. The Arzelà–Ascoli theorem implies that there exists a subsequence $(A(x_{1n_k}, x_{2n_k}))$ of $(A(x_{1n}, x_{2n}))$ converging uniformly to a continuous T -periodic function. Thus, A is compact.

For all $(x_{11}, x_{21}), (x_{12}, x_{22}) \in \Omega_M$, and for $i = 1, 2$,

$$\begin{aligned}
 & |B_i(x_{11}, x_{21})(t) - B_i(x_{12}, x_{22})(t)| \\
 & \leq \int_t^{t+T} G_i(t, u) |g_i(u, x_{11}(u), x_{21}(u), x_{11}(u - \tau_1(u)), x_{21}(u - \tau_2(u))) \\
 & \quad - g_i(u, x_{21}(u), x_{22}(u), x_{21}(u - \tau_1(u)), x_{22}(u - \tau_2(u)))| du \\
 & \leq T\alpha_i(\eta_{1i}|x_{11}(t) - x_{21}(t)| + \eta_{3i}|x_{11}(t - \tau_1(t)) - x_{21}(t - \tau_1(t))| \\
 & \quad + \eta_{2i}|x_{21}(t) - x_{22}(t)| + \eta_{4i}|x_{21}(t - \tau_2(t)) - x_{22}(t - \tau_2(t))|) \\
 & \leq T\alpha_i \left(\eta_{1i} \max_{t \in [0, T]} |x_{11}(t) - x_{21}(t)| + \eta_{3i} \max_{t \in [0, T]} |x_{11}(t - \tau_1(t)) - x_{21}(t - \tau_1(t))| \right. \\
 & \quad \left. + \eta_{2i} \max_{t \in [0, T]} |x_{21}(t) - x_{22}(t)| + \eta_{4i} \max_{t \in [0, T]} |x_{21}(t - \tau_2(t)) - x_{22}(t - \tau_2(t))| \right) \\
 & \leq T\alpha_i \left((\eta_{1i} + \eta_{3i}) \max_{t \in [0, T]} |x_{11}(t) - x_{21}(t)| + (\eta_{2i} + \eta_{4i}) \max_{t \in [0, T]} |x_{21}(t) - x_{22}(t)| \right) \\
 & \leq 2T\alpha_i V_i \max \left(\max_{t \in [0, T]} |x_{11}(t) - x_{21}(t)|, \max_{t \in [0, T]} |x_{21}(t) - x_{22}(t)| \right),
 \end{aligned}$$

hence B_i is a contraction because $2T\alpha_i V_i < 1$. Then

$$\begin{aligned}
 & |B(x_{11}, x_{21})(t) - B(x_{12}, x_{22})(t)| \\
 & = \max\{|B_1(x_{11}, x_{21})(t) - B_1(x_{12}, x_{22})(t)|, \\
 & \quad |B_2(x_{11}, x_{21})(t) - B_2(x_{12}, x_{22})(t)|\},
 \end{aligned}$$

this implies that

$$\begin{aligned}
 & \|B(x_{11}, x_{21}) - B(x_{12}, x_{22})\| \\
 & \leq 2T\alpha V \max \left(\max_{t \in [0, T]} |x_{11}(t) - x_{21}(t)|, \max_{t \in [0, T]} |x_{21}(t) - x_{22}(t)| \right),
 \end{aligned}$$

where $\alpha V = \max(\alpha_1 V_1, \alpha_2 V_2)$. Hence B is a contraction.

Thus, the conditions of Lemma 2.1 are satisfied and there is a $(x_1, x_2) \in \Omega_M$, such that $(x_1, x_2) = A(x_1, x_2) + B(x_1, x_2)$. \square

In the next theorem for $i = 2$ we relax condition (2.1).

Theorem 2.3. *Suppose (1.2)–(1.4), (2.1) for $i = 1$, (2.2) and (2.3) hold. Suppose that*

$$L_i \alpha_i \sum_{j=1}^2 \rho_{ji} + T(\theta_i \gamma_i + \beta_i \alpha_i) \leq 1, \quad i = 1, 2,$$

and $2T\alpha_i V_i < 1$, $i = 1, 2$, where $V_i = \max(\eta_{1i} + \eta_{3i}, \eta_{2i} + \eta_{4i})$. In addition, we assume the existence of continuous nondecreasing function W_2 such that

$$|f_2(x_1, x_2)| \leq f_2(|x_1|, x_2) \leq N_2 W_2(|x_1|)$$

for some positive constant N_2 , and for $u > 0$ we ask that

$$(2.6) \quad \frac{W_2(u)}{u} + \frac{TK_2}{L_2 N_2 u} \leq \frac{1 - T(\theta_2 \gamma_2 + \beta_2 \alpha_2)}{L_2 N_2 \alpha_2}.$$

Then (1.1) has a T -periodic solution.

PROOF: Set

$$(2.7) \quad \sigma = \frac{(TK_1 + L_1 M_1) \alpha_1}{1 - T(\theta_1 \gamma_1 + \beta_1 \alpha_1)}.$$

For any $(x_1, x_2) \in \Omega_\sigma$, we have by the proof of Theorem 2.2 that

$$|E_1(x_1, x_2)(t)| \leq \sigma.$$

Thus

$$\begin{aligned} & |B_2(x_1, x_2)(t)| \\ & \leq \int_t^{t+T} G_2(t, u) |g_2(u, x_1(u), x_2(u), x_1(u - \tau_1(u)), x_2(u - \tau_2(u)))| du \\ & \leq TK_2 \alpha_2, \end{aligned}$$

and

$$\begin{aligned} |A_2(x_1, x_2)(t)| & \leq \int_t^{t+T} G_2(t, u) \int_{-\infty}^u |C_2(u, s)| f_2(|x_1(s)|, x_2(s)) ds du \\ & \quad + \int_t^{t+T} [|h_2(u)| |H_2(t, u)| + |r_2(u)| G_2(t, u)] |x_2(u - \tau_2(u))| du \end{aligned}$$

$$\begin{aligned} &\leq N_2 W_2(\sigma) \int_t^{t+T} G_2(t, u) \int_{-\infty}^u |C_2(u, s)| ds du \\ &\quad + \sigma \int_t^{t+T} [|h_2(u)| |H_2(t, u)| + |r_2(u)| G_2(t, u)] du \\ &\leq L_2 N_2 \alpha_2 W_2(\sigma) + T(\theta_2 \gamma_2 + \beta_2 \alpha_2) \sigma. \end{aligned}$$

As a consequence of (2.6), we get

$$\frac{(TK_2 + L_2 N_2 W_2(\sigma)) \alpha_2}{1 - T(\theta_2 \gamma_2 + \beta_2 \alpha_2)} \leq \sigma,$$

so, we have

$$(TK_2 + L_2 N_2 W_2(\sigma)) \alpha_2 \leq (1 - T(\theta_2 \gamma_2 + \beta_2 \alpha_2)) \sigma.$$

This implies that

$$\begin{aligned} |E_2(x_1, x_2)(t)| &\leq TK_2 \alpha_2 + L_2 \alpha_2 N_2 W_2(\sigma) + T(\theta_2 \gamma_2 + \beta_2 \alpha_2) \sigma \\ &\leq (1 - T(\theta_2 \gamma_2 + \beta_2 \alpha_2)) \sigma + T(\theta_2 \gamma_2 + \beta_2 \alpha_2) \sigma = \sigma. \end{aligned}$$

The rest of the proof follows along the lines of the proof of Theorem 2.2. □

In the next theorem for $i = 1$ we relax condition (2.1).

Theorem 2.4. *Suppose (1.2)–(1.4), (2.1) for $i = 2$, (2.2) and (2.3) hold. Suppose that*

$$L_i \alpha_i \sum_{j=1}^2 \rho_{ji} + T(\theta_i \gamma_i + \beta_i \alpha_i) \leq 1, \quad i = 1, 2,$$

and $2T\alpha_i V_i < 1$, $i = 1, 2$, where $V_i = \max(\eta_{1i} + \eta_{3i}, \eta_{2i} + \eta_{4i})$. In addition, we assume the existence of continuous nondecreasing function W_1 such that

$$|f_1(x_1, x_2)| \leq f_1(x_1, |x_2|) \leq N_1 W_1(|x_2|)$$

for some positive constant N_1 , and for $u > 0$ we ask that

$$(2.8) \quad \frac{W_1(u)}{u} + \frac{TK_1}{L_1 N_1 u} \leq \frac{1 - T(\theta_1 \gamma_1 + \beta_1 \alpha_1)}{L_1 N_1 \alpha_1}.$$

Then (1.1) has a T -periodic solution.

The proof follows along the lines of the proof of Theorem 2.3, and hence we omit it here.

3. An example

Example 3.1. Consider the following coupled integro-differential system

$$\begin{aligned}
 (3.1) \quad & x_1''(t) + \frac{1}{\pi}x_1'(t) + \frac{1}{10^3}x_1(t) = \frac{1}{10^9}\sin(x_1(t)) + \frac{2}{10^9}\sin(x_2(t)) \\
 & + \frac{1}{10^8}\sin(x_1(t-2\pi)) + \frac{3}{10^8}\sin(x_2(t-4\pi)) \\
 & + \frac{2}{10^8}\sin(t)x_1'(t-2\pi) \\
 & + \int_{-\infty}^t \frac{1-e^{-2\pi}}{\pi 10^8}e^{-2t+2s} \left(\frac{1}{10}\sin(x_1(s)) + \frac{1}{10^3}\sin(x_2(s)) \right) ds, \\
 & x_2''(t) + \frac{1}{\pi}x_2'(t) + \frac{1}{10^3}x_2(t) = \frac{2}{10^8}\sin(x_1(t)) + \frac{1}{10^8}\sin(x_2(t)) \\
 & + \frac{3}{10^9}\sin(x_1(t-2\pi)) + \frac{1}{10^9}\sin(x_2(t-4\pi)) \\
 & + \frac{3}{10^8}\sin(t)x_2'(t-4\pi) \\
 & + \int_{-\infty}^t \frac{1}{10^9}e^{-t+s} \left(\frac{1}{10^2}\sin(x_1(s)) + \frac{1}{10^4}\sin(x_2(s)) \right) ds.
 \end{aligned}$$

Then

$$\begin{aligned}
 p_1(t) = p_2(t) &= \frac{1}{\pi}, & q_1(t) = q_2(t) &= \frac{1}{10^3}, & T &= 2\pi, \\
 \tau_1(t) &= 2\pi, & \tau_2(t) &= 4\pi, & c_1(t) &= \frac{2}{10^8}\sin(t), \\
 c_2(t) &= \frac{3}{10^8}\sin(t), & C_1(t, s) &= \frac{1-e^{-2\pi}}{\pi 10^8}e^{-2t+2s}, & C_2(t, s) &= \frac{1}{10^9}e^{-t+s}, \\
 g_1(t, x_1(t), x_2(t), x_1(t-2\pi), x_2(t-4\pi)) \\
 &= \frac{1}{10^9}\sin(x_1(t)) + \frac{2}{10^9}\sin(x_2(t)) + \frac{1}{10^8}\sin(x_1(t-2\pi)) + \frac{3}{10^8}\sin(x_2(t-4\pi)), \\
 g_2(t, x_1(t), x_2(t), x_1(t-2\pi), x_2(t-4\pi)) \\
 &= \frac{2}{10^8}\sin(x_1(t)) + \frac{1}{10^8}\sin(x_2(t)) + \frac{3}{10^9}\sin(x_1(t-2\pi)) + \frac{1}{10^9}\sin(x_2(t-4\pi)),
 \end{aligned}$$

and

$$\begin{aligned}
 f_1(x_1(t), x_2(t)) &= \frac{1}{10}\sin(x_1(t)) + \frac{1}{10^3}\sin(x_2(t)), \\
 f_2(x_1(t), x_2(t)) &= \frac{1}{10^2}\sin(x_1(t)) + \frac{1}{10^4}\sin(x_2(t)).
 \end{aligned}$$

Hence

$$\begin{aligned}
 & |g_1(t, x_1(t), x_2(t), x_1(t - 2\pi), x_2(t - 4\pi))| \\
 & \leq \frac{1}{10^9} |x_1(t)| + \frac{2}{10^9} |x_2(t)| + \frac{1}{10^8} |x_1(t - 2\pi)| + \frac{3}{10^8} |x_2(t - 4\pi)|, \\
 & |g_2(t, x_1(t), x_2(t), x_1(t - 2\pi), x_2(t - 4\pi))| \\
 & \leq \frac{2}{10^8} |x_1(t)| + \frac{1}{10^8} |x_2(t)| + \frac{3}{10^9} |x_1(t - 2\pi)| + \frac{1}{10^9} |x_2(t - 4\pi)|,
 \end{aligned}$$

$$|f_1(x_1, x_2)| \leq \frac{1}{10} |x_1(t)| + \frac{1}{10^3} |x_2(t)|,$$

and

$$|f_2(x_1, x_2)| \leq \frac{1}{10^2} |x_1(t)| + \frac{1}{10^4} |x_2(t)|.$$

So,

$$\begin{array}{cccc}
 \eta_{11} = \frac{1}{10^9}, & \eta_{21} = \frac{2}{10^9}, & \eta_{31} = \frac{1}{10^8}, & \eta_{41} = \frac{3}{10^8}, \\
 \eta_{12} = \frac{2}{10^8}, & \eta_{22} = \frac{1}{10^8}, & \eta_{32} = \frac{3}{10^9}, & \eta_{42} = \frac{1}{10^9}, \\
 \varrho_{11} = \frac{1}{10}, & \varrho_{21} = \frac{1}{10^3}, & \varrho_{12} = \frac{1}{10^2}, & \varrho_{22} = \frac{1}{10^4}.
 \end{array}$$

We check the conditions of Lemma 1.1 for $i = 1, 2$,

$$\begin{aligned}
 R_i &= \max_{t \in [0, 2/\pi]} \left| \int_t^{t+2\pi} \frac{e^{\int_t^s (1/\pi) du}}{e^{\int_0^{2\pi} (1/\pi) du} - 1} \frac{1}{10^3} ds \right| \simeq 0.003, \\
 Q_i &= \left(1 + e^{\int_0^{2\pi} (1/\pi) du} \right)^2 R_i^2 \simeq 0.0006,
 \end{aligned}$$

and

$$\frac{R_i}{2\pi Q_i} \left(e^{\int_0^{2\pi} (1/\pi) du} - 1 \right) \simeq 5.0842 \geq 1,$$

this implies

$$a_i(t) = 0.0032, \quad b_i(t) = 0.3152, \quad i = 1, 2.$$

We check the conditions of Lemma 1.5

$$\Gamma_i = \int_0^{2\pi} \frac{1}{\pi} du = 2, \quad \Lambda_i = (2\pi)^2 e^{(1/2\pi) \int_0^{2\pi} \ln(1/10^3) du} \simeq 0.0395,$$

and

$$2^2 \geq 4 \cdot 0.0395 \Rightarrow \Gamma_i^2 \geq 4\Lambda_i, \quad i = 1, 2,$$

then we have for $i = 1, 2$,

$$\begin{aligned} \min \left\{ \int_0^{2\pi} 0.0032 \, du, \int_0^{2\pi} 0.3152 \, du \right\} &\geq \frac{1}{2} \left(\Gamma_i - \sqrt{\Gamma_i^2 - 4\Lambda_i} \right) \\ &\simeq \frac{1}{2} \left(2 - \sqrt{2^2 - 4 \cdot 0.0395} \right) = l_i \simeq 0.0199, \\ \max \left\{ \int_0^{2\pi} 0.0032 \, du, \int_0^{2\pi} 0.3152 \, du \right\} &\leq \frac{1}{2} \left(\Gamma_i + \sqrt{\Gamma_i^2 - 4\Lambda_i} \right) \\ &\simeq \frac{1}{2} \left(2 + \sqrt{2^2 - 4 \times 0.0395} \right) = m_i \simeq 1.9801. \end{aligned}$$

By Corollary 1.6, we get

$$\begin{aligned} \frac{2\pi}{(e^{1.9801} - 1)^2} \simeq 0.1611 \leq G_i(t, s) &\leq \frac{2\pi e^{\int_0^{2\pi} (1/\pi) \, dv}}{(e^{0.0199} - 1)^2} \simeq 1.15 \cdot 10^5, \quad i = 1, 2, \\ |H_i(t, s)| &\leq \frac{e^{1.9801}}{e^{0.0199} - 1} \simeq 3.61 \cdot 10^2, \quad i = 1, 2. \end{aligned}$$

We obtain

$$\alpha_i = 1.15 \cdot 10^5, \quad \gamma_i = 3.61 \cdot 10^2, \quad \lambda_i = 0.0032, \quad \delta_i = 0.3152, \quad i = 1, 2,$$

$$\theta_1 = \max_{t \in [0, 2\pi]} |h_1(t)| = \max_{t \in [0, 2\pi]} |c_1(t)| = \max_{t \in [0, 2\pi]} \left| \frac{2}{10^8} \sin(t) \right| = \frac{2}{10^8},$$

$$\theta_2 = \max_{t \in [0, 2\pi]} |h_2(t)| = \max_{t \in [0, 2\pi]} |c_2(t)| = \max_{t \in [0, 2\pi]} \left| \frac{3}{10^8} \sin(t) \right| = \frac{3}{10^8},$$

$$\begin{aligned} \beta_1 &= \max_{t \in [0, 2\pi]} |r_1(t)| = \max_{t \in [0, 2\pi]} |a_1(t)c_1(t) + c'_1(t)| \\ &= \max_{t \in [0, 2\pi]} \left| 0.0032 \cdot \frac{2}{10^8} \sin(t) + \frac{2}{10^8} \cos(t) \right| = \frac{2.0064}{10^8}, \end{aligned}$$

$$\begin{aligned} \beta_2 &= \max_{t \in [0, 2\pi]} |r_2(t)| = \max_{t \in [0, 2\pi]} |a_2(t)c_2(t) + c'_2(t)| \\ &= \max_{t \in [0, 2\pi]} \left| 0.0032 \cdot \frac{3}{10^8} \sin(t) + \frac{3}{10^8} \cos(t) \right| = \frac{3.0096}{10^8}, \end{aligned}$$

$$|f_1(x_1(t), x_2(t))| \leq M_1 = \frac{101}{10^3}, \quad |f_2(x_1(t), x_2(t))| \leq M_2 = \frac{101}{10^4},$$

$$|g_1(t, x_1(t), x_2(t), x_1(t - 2\pi), x_2(t - 4\pi))| \leq K_1 = \frac{43}{10^9},$$

$$|g_2(t, x_1(t), x_2(t), x_1(t - 2\pi), x_2(t - 4\pi))| \leq K_2 = \frac{34}{10^9},$$

$$\int_t^{t+2\pi} \int_{-\infty}^u \left| \frac{1 - e^{-2\pi}}{\pi 10^8} e^{-2u+2s} \right| ds du \leq L_1 = \frac{0.9982}{10^8},$$

$$\int_t^{t+2\pi} \int_{-\infty}^u \left| \frac{1}{10^9} e^{-u+s} \right| ds du \leq L_2 = \frac{2\pi}{10^9}.$$

Therefore,

$$L_1 \alpha_1 \sum_{j=1}^2 \varrho_{j1} + T(\theta_1 \gamma_1 + \beta_1 \alpha_1) = 0.0145 \leq 1,$$

$$L_2 \alpha_2 \sum_{j=1}^2 \varrho_{j2} + T(\theta_2 \gamma_2 + \beta_2 \alpha_2) = 0.0218 \leq 1,$$

and

$$V_1 = \max(\eta_{11} + \eta_{31}, \eta_{21} + \eta_{41}) = \max\left(\frac{1}{10^9} + \frac{1}{10^8}, \frac{2}{10^9} + \frac{3}{10^8}\right) = \frac{32}{10^9},$$

$$V_2 = \max(\eta_{12} + \eta_{32}, \eta_{22} + \eta_{42}) = \max\left(\frac{2}{10^8} + \frac{3}{10^9}, \frac{1}{10^8} + \frac{1}{10^9}\right) = \frac{23}{10^9},$$

so,

$$2T\alpha_1 V_1 = 4\pi \cdot 1.15 \cdot 10^5 \cdot \frac{32}{10^9} = 0.0462 < 1,$$

$$2T\alpha_2 V_2 = 4\pi \cdot 1.15 \cdot 10^5 \cdot \frac{23}{10^9} = 0.0332 < 1.$$

The conditions of Theorem 2.2 are satisfied, then (3.1) has a 2π -periodic solution.

Acknowledgment. The authors would like to thank the anonymous referee for the valuable comments.

REFERENCES

- [1] Adivar M., Raffoul Y. N., *Existence of periodic solutions in totally nonlinear delay dynamic equations*, Electron. J. Qual. Theory Differ. Equ. **2009** (2009), Special Edition I, no. 1., 20 pages.
- [2] Ardjouni A., Djoudi A., *Periodic solutions for a second-order nonlinear neutral differential equation with variable delay*, Electron. J. Differential Equations **2011** (2011), no. 128, 7 pages.
- [3] Ardjouni A., Djoudi A., *Existence of periodic solutions for a second order nonlinear neutral differential equation with functional delay*, Electron. J. Qual. Theory Differ. Equ. **2012** (2012), no. 31, 9 pages.
- [4] Ardjouni A., Djoudi A., *Existence of periodic solutions for a second order nonlinear neutral differential equation with variable delay*, Palest J. Math. **3** (2014), no. 2, 191–197.
- [5] Ardjouni A., Djoudi A., *Periodic solutions for a second order nonlinear neutral functional differential equation with variable delay*, Matematiche (Catania) **69** (2014), no. 2, 103–115.

- [6] Biçer E., Tunç C., *On the existence of periodic solutions to non-linear neutral differential equations of first order with multiple delays*, Proc. of the Pakistan Academy of Sciences **52** (2015), no. 1, 89–94.
- [7] Gabsi H., Ardjouni A., Djoudi A., *Existence of periodic solutions for two types of second-order nonlinear neutral integro-differential equations with infinite distributed mixed-delay*, Advances in the Theory of Nonlinear Analysis and Its Applications **2** (2018), no. 4, 184–194.
- [8] Hafsia D., *Existence of periodic solutions for a second order nonlinear integro-differential equations with variable delay*, Canad. J. Appl. Math. **2** (2020), no. 1, 36–44.
- [9] Liu Y., Ge W., *Positive periodic solutions of nonlinear Duffing equations with delay and variable coefficients*, Tamsui Oxf. J. Math. Sci. **20** (2004), no. 2, 235–255.
- [10] Mansouri B., Ardjouni A., Djoudi A., *Existence of positive periodic solutions for two types of third-order nonlinear neutral differential equations with variable coefficients*, Differ. Uravn. Protsessy Upr. **3** (2018), no. 3, 46–63.
- [11] Raffoul Y., *Analysis of periodic and asymptotically periodic solutions in nonlinear coupled Volterra integro-differential systems*, Turkish. J. Math. **42** (2018), no. 1, 108–120.
- [12] Raffoul Y. N., *Periodic solutions for neutral nonlinear differential equations with functional delay*, Electron. J. Differential Equations **2003** (2003), no. 102, 7 pages.
- [13] Smart D. R., *Fixed Point Theorems*, Cambridge Tracts in Mathematics, 66, Cambridge University Press, London, 1974.
- [14] Wang Y., Lian H., Ge W., *Periodic solutions for a second order nonlinear functional differential equation*, Appl. Math. Lett. **20** (2007), no. 1, 110–115.

B. Mansouri:

FACULTY OF SCIENCES, DEPARTMENT OF MATHEMATICS,
BADJI-MOKHTAR-ANNABA UNIVERSITY, P. O. BOX 12, 17 HASSEN CHAOUCHE,
ANNABA, 23000, ALGERIA

E-mail: mansouri.math@yahoo.fr

A. Ardjouni:

FACULTY OF SCIENCES AND TECHNOLOGY,
DEPARTMENT OF MATHEMATICS AND INFORMATICS,
UNIVERSITÉ MED-CHERIF MESSAADIA DE SOUK AHRAS,
P. O. BOX 1553, SOUK AHRAS, 41000, ALGERIA

E-mail: abd_ardjouni@yahoo.fr

A. Djoudi:

APPLIED MATHEMATICS LAB., FACULTY OF SCIENCES, DEPARTMENT OF MATHEMATICS,
BADJI-MOKHTAR-ANNABA UNIVERSITY, P. O. BOX 12, 17 HASSEN CHAOUCHE,
ANNABA, 23000, ALGERIA

E-mail: adjoudi@yahoo.com

(Received November 16, 2020, revised May 5, 2021)