## Mathematica Bohemica

## Andriy Bandura; Tetyana Salo; Oleh Skaskiv

Non-homogeneous directional equations: Slice solutions belonging to functions of bounded $L$-index in the unit ball

Mathematica Bohemica, Vol. 149 (2024), No. 2, 247-260

Persistent URL: http://dml.cz/dmlcz/152471

## Terms of use:

© Institute of Mathematics AS CR, 2024

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.


This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project DML-CZ: The Czech Digital Mathematics Library http://dml.cz

# NON-HOMOGENEOUS DIRECTIONAL EQUATIONS: SLICE SOLUTIONS BELONGING TO FUNCTIONS OF BOUNDED $L$-INDEX IN THE UNIT BALL 

Andriy Bandura, Ivano-Frankivsk, Tetyana Salo, Oleh Skaskiv, Lviv

Received September 8, 2022. Published online April 12, 2023.
Communicated by Grigore Sălăgean


#### Abstract

For a given direction $\mathbf{b} \in \mathbb{C}^{n} \backslash\{\mathbf{0}\}$ we study non-homogeneous directional linear higher-order equations whose all coefficients belong to a class of joint continuous functions which are holomorphic on intersection of all directional slices with a unit ball. Conditions are established providing boundedness of $L$-index in the direction with a positive continuous function $L$ satisfying some behavior conditions in the unit ball. The provided conditions concern every solution belonging to the same class of functions as the coefficients of the equation. Our considerations use some estimates involving a directional logarithmic derivative and distribution of zeros on all directional slices in the unit ball.


Keywords: bounded index; bounded $L$-index in direction; slice function; holomorphic function; directional differential equation; bounded $l$-index; directional derivative; unit ball

MSC 2020: 32A10, 32A17, 32A37

## 1. Introduction

American mathematician Lepson in [20] and his scholar MacDonnell in [21] were the first to introduce the notion of bounded index for entire functions of one variable. An entire function $f: \mathbb{C} \rightarrow \mathbb{C}$ is called a function of bounded index if there exists $m \in \mathbb{Z}_{+}$such that for every $p \in \mathbb{Z}_{+}$and all $z \in \mathbb{C}$ one has

$$
\begin{equation*}
\frac{\left|f^{(p)}(z)\right|}{p!} \leqslant \max _{0 \leqslant s \leqslant m} \frac{\left|f^{(s)}(z)\right|}{s!} . \tag{1.1}
\end{equation*}
$$

The research of the first author was funded by the National Research Foundation of Ukraine, 2020.02/0025, 0120U103996.

The least such integer $m$ satisfying (1.1) is called the index of the function $f$. These functions have fascinating properties: some local regular behavior (see [14]), a uniform distribution of zeros and a bounded logarithmic derivative outside an exceptional set (see [15]), their antiderivative has bounded value distribution (see [16]), etc. Moreover, every entire solution of a linear higher-order homogeneous differential equation with constant coefficients possesses property (1.1), i.e., it is of bounded index (see [24]). Later a similar fact was established when the coefficients $a_{j}=a_{j}(z)$ of the equation $f^{(n)}(t)+\sum_{j=0}^{n-1} a_{j} f^{(j)}(t)=0$ are polynomials (see [25]). It is obviuos that every polynomial has bounded index. However, Shah in [26] and Hayman in [16] proved that each entire function having bounded index is a function of exponential type.

Therefore, Kuzyk and Sheremeta proposed an extension of this notion introducing a function of bounded $l$-index (see [18]). They replaced $p!$ and $s!$ by $p!l^{p}(z)$ and $s!l^{s}(z)$ in the previous definition, respectively, where $l: \mathbb{C} \rightarrow \mathbb{R}_{+}$belongs to continuous functions. Such a class of functions having bounded $l$-index is very wide. If the multiplicities of zeros of an entire function are uniformly bounded, then there exists a positive continuous function $l$ providing boundedness of the $l$ index for the entire function (see [12], [28]). This notion was also generalized for functions of several complex variables by two approaches. The first approach uses all possible partial derivatives in the definition (bounded index in joint variables, see $[6],[22],[23])$ and the second approach uses directional derivatives in the definition (bounded index in a direction, see [5], [7], [17]). Although the first approach seems more natural, the second approach allows to deduce more multi-dimensional analogs of known one-dimensional propositions describing properties of functions having bounded index. In particular, the bounded index in direction helps to obtain an analog of logarithmic criterion even for bounded index in joint variables (see [1]). This criterion is a central tool in applications of the theory of a bounded index to differential equations.

Recently, we started to study a sufficiently general class of holomorphic functions. Our researches were inspired by the following Favorov's problem (see [8]):

Question 1.1 ([8]). Are deducible known propositions on properties of analytic functions having bounded $L$-index in the direction $\mathbf{b} \in \mathbb{C}^{n} \backslash\{0\}$ for joint continuous and holomorphic on the slices $\left\{z^{0}+t \mathbf{b}: t \in \mathbb{C}\right\}$ functions?

Here we continue our investigations initialized in [2], [3], [4]. A concept of $L$-index boundedness in direction for slice analytic functions of several complex variables was introduced and many criteria of $L$-index boundedness in direction were obtained. We present some applications of these criteria to consider slice analytic solutions
of directional differential equations. Since functions of bounded index have many applications in analytic theory of differential equations (see [6], [10], [23]), we study the local behavior of slice holomorphic functions of bounded $L$-index in direction which satisfies some linear higher-order directional differential equations.

In [11], a question was considered on the additional conditions, providing index boundedness of every slice entire solution for linear higher-order directional differential equation with slice entire coefficients. Here we consider the question for slice holomorphic functions in the unit ball.

Let us introduce some notations from [2]. Let $\mathbb{R}_{+}=(0, \infty), \mathbb{R}_{+}^{*}=[0, \infty), \mathbf{0}=$ $(0, \ldots, 0), \mathbf{1}=(1, \ldots, 1), \mathbf{b}=\left(b_{1}, \ldots, b_{n}\right) \in \mathbb{C}^{n} \backslash\{\mathbf{0}\}$ be a given direction, $\mathbb{B}^{n}=$ $\left\{z \in \mathbb{C}^{n}:|z|<1\right\}$ be a unit ball, $\mathbb{D}=\{z \in \mathbb{C}:|z|<1\}$ be a unit disc, $L: \mathbb{B}^{n} \rightarrow \mathbb{R}_{+}$ be a continuous function. For a given $z \in \mathbb{B}^{n}$, we denote $S_{z}=\left\{t \in \mathbb{C}: z+t \mathbf{b} \in \mathbb{B}^{n}\right\}$. Clearly, $\mathbb{D}=\mathbb{B}^{1}$. The slice functions on $S_{z}$ for fixed $z^{*} \in \mathbb{B}^{n}$ will be denoted as $g_{z^{*}}(t)=F\left(z^{*}+t \mathbf{b}\right)$ and $l_{z^{*}}(t)=L\left(z^{*}+t \mathbf{b}\right)$ for $t \in S_{z}$.

Let $\widetilde{\mathcal{H}}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ be a class of functions which are holomorphic on every slice $\left\{z^{*}+t \mathbf{b}\right.$ : $\left.t \in S_{z^{*}}\right\}$ for each $z^{*} \in \mathbb{B}^{n}$ and let $\mathcal{H}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ be a class of functions from $\widetilde{\mathcal{H}}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ which are joint continuous. The notation $\partial_{\mathbf{b}} F(z)$ stands for the derivative of the function $g_{z}(t)$ at the point 0 , i.e., for every $p \in \mathbb{N}, \partial_{\mathbf{b}}^{p} F(z)=g_{z}^{(p)}(0)$, where $g_{z}(t)=$ $F(z+t \mathbf{b})$ is an analytic function of complex variable $t \in S_{z}$ for given $z \in \mathbb{B}^{n}$. Besides, we denote by $\langle a, c\rangle=\sum_{j=1}^{n} a_{j} \overline{c_{j}}$ the Hermitian inner product in $\mathbb{C}^{n}$, where $a, c \in \mathbb{C}^{n}$.

The hypothesis on joint continuity together with the hypothesis on holomorphy in one direction do not imply holomorphy in whole $n$-dimensional unit ball. Some examples to demonstrate it were presented in [2].

A function $F \in \widetilde{\mathcal{H}}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ is said to be of bounded L-index in the direction $\mathbf{b} \in$ $\mathbb{C}^{n} \backslash\{\mathbf{0}\}$ (we denote this class by $B_{\mathbf{b}}\left(L, \mathbb{B}^{n}\right)$ ) (see [2]) if there exists $m_{0} \in \mathbb{Z}_{+}$such that for all $m \in \mathbb{Z}_{+}$and each $z \in \mathbb{B}^{n}$, inequality

$$
\begin{equation*}
\frac{\left|\partial_{\mathbf{b}}^{m} F(z)\right|}{m!L^{m}(z)} \leqslant \max _{0 \leqslant k \leqslant m_{0}} \frac{\left|\partial_{\mathbf{b}}^{k} F(z)\right|}{k!L^{k}(z)} \tag{1.2}
\end{equation*}
$$

holds. The least such integer number $m_{0}$, obeying (1.2), is called the $L$-index in the direction $\mathbf{b}$ of the function $F$ and is denoted by $N_{\mathbf{b}}\left(F, L, \mathbb{B}^{n}\right)$. For $n=1, \mathbf{b}=1$, $L(z)=l(z)$, and $z \in \mathbb{C}$ instead $z \in \mathbb{B}$, inequality (1.2) defines a function of bounded $l$-index with the $l$-index $N(F, l) \equiv N_{1}(F, l, \mathbb{C})$ (see [19], [28], [29]), and if in addition $l(z) \equiv 1$, then we obtain a definition of index boundedness with index $N(F) \equiv$ $N_{1}(F, 1, \mathbb{C})$ (see [20], [21]). It is also worth mentioning paper [31], which introduces the concept of generalized index. It is quite close to the bounded $l$-index.

To obtain constructive and sufficiently general results, one must impose additional restrictions on the function $L$, since continuity alone is not enough for this.

For $z \in \mathbb{B}^{n}$ we denote

$$
\lambda_{\mathbf{b}}(\eta)=\sup \left\{\sup _{t, \tau \in S_{z}}\left\{\frac{L(z+t \mathbf{b})}{L(z+\tau \mathbf{b})}:|t-\tau| \leqslant \frac{\eta}{\min \{L(z+t \mathbf{b}), L(z+\tau \mathbf{b})\}}\right\}: z \in \mathbb{B}^{n}\right\} .
$$

Let $Q_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ be the class of positive continuous functions $L: \mathbb{B}^{n} \rightarrow \mathbb{R}_{+}$satisfying for given $\beta>1$ and for every $\eta \in[0, \beta]$ the condition

$$
\lambda_{\mathbf{b}}(\eta)<\infty
$$

and for all $z \in \mathbb{B}^{n}$ the inequality

$$
\begin{equation*}
L(z)>\frac{\beta|\mathbf{b}|}{1-|z|} . \tag{1.3}
\end{equation*}
$$

The last condition (1.3) is, in a sense, final.

## 2. Auxiliary propositions

Throughout this section, we will assume that $L \in Q_{\mathbf{b}}\left(\mathbb{B}^{n}\right), F \in \widetilde{\mathcal{H}}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$, where $\mathbf{b} \in \mathbb{C} \backslash\{0\}, n \geqslant 2$. Let us formulate several theorems proved in articles [3], [4], which we will use in what follows. The following theorem from [4] describes sufficient conditions for the boundedness of $L$-index in direction in terms of the local behavior of the maximum of the modulus of the function.

Theorem 2.1 ([4]). If there exist $r_{1}, r_{2} \in(0, \beta], r_{1}<r_{2}$, and exists $P_{1} \geqslant 1$ for all $z \in \mathbb{B}^{n}$ such that

$$
\max \left\{|F(z+t \mathbf{b})|:|t|=r_{2} / L(z)\right\} \leqslant P_{1} \max \left\{|F(z+t \mathbf{b})|:|t|=r_{1} / L(z)\right\}
$$

then $F \in B_{\mathbf{b}}\left(L, \mathbb{B}^{n}\right)$.
We also need the following analogue of the theorem obtained by Fricke (see [15]) for entire functions of bounded index of one complex variable.

Theorem 2.2 ([4]). If $F \in B_{\mathbf{b}}\left(L, \mathbb{B}^{n}\right)$, then for all $R \in(0, \beta)$ there exists $P_{2}(R) \geqslant 1$, exists $\eta(R) \in(0, R)$ and for all $z \in \mathbb{B}^{n}$ there exists $r=r(z) \in[\eta(R), R]$ such that

$$
\begin{equation*}
\max \{|F(z+t \mathbf{b})|:|t|=r / L(z)\} \leqslant P_{2}(R) \min \{|F(z+t \mathbf{b})|:|t|=r / L(z)\} \tag{2.1}
\end{equation*}
$$

Also, we use an analogue of logarithmic criterion for function from the class $\widetilde{\mathcal{H}}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$. The one-dimensional analogue of the criterion is efficient to investigate boundedness of $l$-index of infinite products (see [13], [27], [30]). As a necessary conditions the criterion was obtained by Fricke (see [14], [15]) for entire functions of one complex variable having bounded index. We put

$$
G_{r}(F):=G_{r}^{\mathbf{b}}(F):=\bigcup_{a \in \mathbb{B}^{n}: F(a)=0}\{a+t \mathbf{b}: t \in \mathbb{C},|t|<r / L(a)\} .
$$

For given $z \in \mathbb{B}^{n}$ and $r>0$ we denote by

$$
n_{z}(r)=n_{\mathbf{b}}(r, z, 1 / F):=\sum_{\left|a_{k}^{0}\right| \leqslant r} 1
$$

the counting function of zeros $a_{k}^{0}$ of the slice function $g_{z}(t)=F(z+t \mathbf{b})$ in the disc $\{t \in \mathbb{C}:|t| \leqslant r\}$. If for given $z \in \mathbb{B}^{n}$ and for all $t \in S_{z}: g_{z}(t)=F(z+t \mathbf{b}) \equiv 0$, then we put $n_{z}(r)=-1$. Denote also $n(r)=\sup _{z \in \mathbb{B}^{n}} n_{z}(r / L(z))$.

Theorem 2.3 ([4]). If $F \in B_{\mathbf{b}}\left(L, \mathbb{B}^{n}\right)$, then
(1) for all $r \in(0, \beta]$ there exists $P=P(r)>0$ and for all $z \in \mathbb{B}^{n} \backslash G_{r}^{\mathbf{b}}(F)$ :

$$
\left|\partial_{\mathbf{b}} F(z)\right| \leqslant P L(z)|F(z)| ;
$$

(2) for all $r \in(0, \beta]$ there exists $\widetilde{n}(r) \in \mathbb{Z}_{+}$and for all $z^{0} \in \mathbb{B}^{n}, F\left(z^{0}+t \mathbf{b}\right) \not \equiv 0$ :

$$
n_{\mathbf{b}}\left(r / L\left(z^{0}\right), z^{0}, 1 / F\right) \leqslant \widetilde{n}(r)
$$

The following statement is actually obtained in the proof of Theorem 2.3 in [4]:
Lemma 2.1. If $F \in B_{\mathbf{b}}\left(L, \mathbb{B}^{n}\right)$, then for all $z^{0} \in \mathbb{B}^{n} \backslash G_{r}^{\mathbf{b}}(F), r \in(0, \beta)$, and for all $\widetilde{a}^{k}=z^{0}+a_{k}^{0} \mathbf{b} \in \mathbb{B}^{n}, F\left(\widetilde{a}^{k}\right)=0$, we have

$$
\begin{equation*}
\left|z^{0}-\widetilde{a}_{k}\right|>\frac{r|\mathbf{b}|}{2 L\left(z^{0}\right) \lambda_{\mathbf{b}}(r)} \tag{2.2}
\end{equation*}
$$

The following (Theorem 2.4) is an analogue of Hayman's theorem (see [16]) proved for entire functions of single variable.

Theorem 2.4 ([3]). A function $F \in \widetilde{\mathcal{H}}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ is of bounded L-index in the direction $\mathbf{b}$ if and only if there exists $p \in \mathbb{Z}_{+}$, exists $C>0$ and for all $z \in \mathbb{B}^{n}$ :

$$
\frac{\left|\partial_{\mathbf{b}}^{p+1} F(z)\right|}{L^{(p+1)}(z)} \leqslant C \max \left\{\frac{\left|\partial_{\mathbf{b}}^{k} F(z)\right|}{L^{-k}(z)}: 0 \leqslant k \leqslant p\right\} .
$$

In the proof of Lemma 2.2 we will use methods from a proof of its counterparts in [7] for another class of functions which are analytic in some domain from $n$-dimensional complex space.

Lemma 2.2. Let $F \in B_{\mathbf{b}}\left(L, \mathbb{B}^{n}\right)$. Then for all $r>0$ and for all $m \in \mathbb{N}$ there exists $P=P(r, m)>1$ such that for all $z \in \mathbb{B}^{n} \backslash G_{r}^{\mathbf{b}}(F):\left|\partial_{\mathbf{b}}^{m} F(z)\right| \leqslant P L^{m}(z)|F(z)|$.

Proof. By Theorem 2.2 with $R=r /\left(2 \lambda_{\mathbf{b}}(r)\right)$, there exist $P_{2}=P_{2}(R) \geqslant 1$, $\eta=\eta(R) \in(0, R)$ such that for every $z \in \mathbb{B}^{n}$ and some $r^{*}=r^{*}(z) \in[\eta(R), R]$, inequality (2.1) is true with $r=r^{*}$. Applying the Cauchy inequality, for $r=r^{*}$ we have

$$
\frac{1}{m!}\left|\partial_{\mathbf{b}}^{m} F(z)\right| \leqslant\left(\frac{L(z)}{r}\right)^{m} \max \left\{|F(z+t \mathbf{b})|:|t|=\frac{r}{L(z)}\right\}
$$

Hence, by inequalities (2.1) and $\eta \leqslant r=r^{*}$ we get

$$
\frac{1}{m!}\left|\partial_{\mathbf{b}}^{m} F(z)\right| \leqslant P_{2}\left(\frac{L(z)}{\eta}\right)^{m} \min \left\{|F(z+t \mathbf{b})|:|t|=\frac{r^{*}}{L(z)}\right\}
$$

Inequality (2.2) from Lemma 2.1 implies that $F(z+t \mathbf{b}) \neq 0$ on the set $\{t:|t| \leqslant$ $\left.r /\left(2 \lambda_{2}^{\mathbf{b}}(r) L(z)\right)\right\}$ for every $z \in \mathbb{B}^{n} \backslash G_{r}^{\mathbf{b}}(F)$. By the maximum modulus principle in variable $t \in \mathbb{C}$ for the function $1 / F(z+t \mathbf{b})$ one has

$$
\frac{1}{|F(z)|} \leqslant \frac{1}{\min \left\{|F(z+t \mathbf{b})|:|t|=r^{*} / L(z)\right\}}
$$

i.e., $|F(z)| \geqslant \min \left\{|F(z+t \mathbf{b})|:|t|=r^{*} / L(z)\right\}$. Thus,

$$
\left|\partial_{\mathbf{b}}^{m} F(z)\right| \leqslant m!P_{2} \eta^{-m} L^{m}(z)|F(z)|
$$

Since $z$ is arbitrary, we finally obtain the required inequality with $P=P_{2} m!\eta^{-m}$.

## 3. The main result

Let us consider the directional differential equation

$$
\begin{equation*}
h_{0}(z) \partial_{\mathbf{b}}^{p} w+h_{1}(z) \partial_{\mathbf{b}}^{p-1} w+\ldots+h_{p}(z) w=h(z) \tag{3.1}
\end{equation*}
$$

where $h_{j}, h$ are functions from the class $\mathcal{H}_{\mathbf{b}}^{n}, j \in\{0,1, \ldots, p\}$. For entire functions of bounded $L$-index in direction $p=2$ and entire functions $h_{0}, h_{1}, h_{2}, h$, the equation was investigated in [5], [10], and in the case of holomorphic in the unit ball coefficients $h_{j}$, $h$, equation (3.1) was studied in [7].

Here we consider the equation under a much weaker assumption that the coefficients of (3.1) are slice holomorphic functions in the unit ball. Let us remind that a case of entire on directional slices functions was examined in [11]. Denote

$$
\begin{gathered}
H(z)=h(z) \prod_{j=0}^{p} h_{j}(z), \quad n(r, H)=\sup _{z \in \mathbb{B}^{n}} n_{\mathbf{b}}(r / L(z), z, 1 / H), \\
r^{*}=\sup _{s \geqslant 1} \frac{s-1}{8(n(s, H)+1) \lambda_{\mathbf{b}}(s)}, \quad E(F)=\bigcup_{\substack{z \in Z_{F}: \\
\forall t \in \mathbb{C}, F(z+t \mathbf{b}) \equiv 0}}\{z+t \mathbf{b}: t \in \mathbb{C}\},
\end{gathered}
$$

where $Z_{F}$ is a zero set of the function $F$. We also denote $G_{r}=\left(G_{r}(h) \backslash E(h)\right) \cup$ $G_{r}\left(g_{0}\right) \cup \bigcup_{j=1}^{p}\left(G_{r}\left(h_{j}\right) \backslash E\left(h_{j}\right)\right)$.

We prove the following theorem.
Theorem 3.1. Let $L \in Q_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ with $\beta>3$ in condition (1.3) and $\left\{h_{0}(z), \ldots\right.$, $\left.h_{p}(z), h(z)\right\} \subset \mathcal{H}_{\mathbf{b}}\left(\mathbb{B}^{n}\right) \cap B_{\mathbf{b}}\left(L, \mathbb{B}^{n}\right)$. If there exist $r \in\left(0 ; \min \left\{\frac{1}{3} \beta, r^{*}\right\}\right)$ and $T>0$ such that $\mathbb{B}^{n} \backslash G_{r} \neq \emptyset$ and for all $z \in \mathbb{B}^{n} \backslash G_{r}\left(h_{0}\right)$ and for all $j \in\{1, \ldots, p\}$ it is

$$
\begin{equation*}
\left|h_{j}(z)\right| \leqslant T L^{j}(z)\left|h_{0}(z)\right|, \tag{3.2}
\end{equation*}
$$

then every solution $F \in \mathcal{H}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ of equation (3.1) has bounded $L$-index in the direction $\mathbf{b}$.

Proof. Our proof is based on some ideas from [11]. It is easy to see that the condition $F \in \mathcal{H}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ implies $\partial_{\mathbf{b}}^{m} F \in \mathcal{H}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$ for all $m \in \mathbb{N}$. It should also be noted that Theorem 2.3 and the restrictions of Theorem 3.1 provide the validity of the inequalities $n(r, H)<\infty$ and $r^{*}>0$.

Since by condition $\mathbb{B}^{n} \backslash G_{r} \neq \emptyset$, from conditions of Theorem 3.1 and Lemma 2.2 by inequality (3.2) it follows that exists $r \in\left(0, \min \left\{\beta ; r^{*}\right\}\right)$, exists $T^{*}=\max \{P, T$, $P \cdot T\}>0$ for all $z \in \mathbb{B}^{n} \backslash G_{r}$ :

$$
\begin{align*}
\left|\partial_{\mathbf{b}} h(z)\right| & \leqslant P|h(z)| L(z) \leqslant T^{*}|h(z)| L(z)  \tag{3.3}\\
\left|h_{j}(z)\right| & \leqslant T^{*}\left|h_{0}(z)\right| L^{j}(z), \quad j \in\{1,2, \ldots, p,\} \\
\left|\partial_{\mathbf{b}} h_{j}(z)\right| & \leqslant P L(z)\left|h_{j}(z)\right| \leqslant P \cdot T\left|h_{0}(z)\right| L^{j+1}(z) \\
& \leqslant T^{*}\left|h_{0}(z)\right| L^{j+1}(z), \quad j \in\{0,1,2, \ldots, p,\} . \tag{3.4}
\end{align*}
$$

Let us now apply the derivative $\partial_{\mathbf{b}}$ to both sides of equation (3.1):

$$
h_{0}(z) \partial_{\mathbf{b}}^{p+1} F(z)+\sum_{j=1}^{p} h_{j}(z) \partial_{\mathbf{b}}^{p+1-j} F(z)+\sum_{j=0}^{p} \partial_{\mathbf{b}} h_{j}(z) \partial_{\mathbf{b}}^{p-j} F(z)=\partial_{\mathbf{b}} h(z) .
$$

Then using inequalities (3.3), (3.4) and $|h(z)| \leqslant \sum_{j=0}^{p}\left|h_{j}(z) \| \partial_{\mathbf{b}}^{p-j} F(z)\right|$ for all $z \in$ $\mathbb{B}^{n} \backslash G_{r}$, we successively obtain

$$
\left|\partial_{\mathbf{b}} h(z)\right| \leqslant T^{*}|h(z)| L(z) \leqslant T^{*} L(z) \sum_{j=0}^{p}\left|h_{j}(z)\right|\left|\partial_{\mathbf{b}}^{p-j} F(z)\right|
$$

and

$$
\begin{aligned}
\mid h_{0}(z) & \left|\left|\partial_{\mathbf{b}}^{p+1} F(z)\right|\right. \\
\leqslant & \left|\partial_{\mathbf{b}} h(z)\right|+\sum_{j=1}^{p}\left|h_{j}(z)\right|\left|\partial_{\mathbf{b}}^{p+1-j} F(z)\right|+\sum_{j=0}^{p}\left|\partial_{\mathbf{b}} h_{j}(z)\right|\left|\partial_{\mathbf{b}}^{p-j} F(z)\right| \\
\leqslant & T^{*} L(z) \sum_{j=0}^{p}\left|h_{j}(z)\right| \partial_{\mathbf{b}}^{p-j} F(z)\left|+\sum_{j=1}^{p}\right| h_{j}(z)| | \partial_{\mathbf{b}}^{p+1-j} F(z) \mid \\
& +\sum_{j=0}^{p}\left|\partial_{\mathbf{b}} h_{j}(z)\right|\left|\partial_{\mathbf{b}}^{p-j} F(z)\right| \\
\leqslant & T^{*}\left|h_{0}(z)\right|\left|L^{p+1}(z)\right|\left(\left(T^{*}+1\right) \sum_{j=0}^{p} \frac{\left|\partial_{\mathbf{b}}^{p-j} F(z)\right|}{L^{p-j}(z)}+\sum_{j=1}^{p} \frac{\left|\partial_{\mathbf{b}}^{p+1-j} F(z)\right|}{L^{p+1-j}(z)}\right) \\
\leqslant & P_{3}\left|h_{0}(z)\right| L^{p+1}(z) \max _{0 \leqslant j \leqslant p} \frac{\left|\partial_{\mathbf{b}}^{j} F(z)\right|}{L^{j}(z)},
\end{aligned}
$$

where $P_{3}=T^{*}\left(\left(T^{*}+1\right)(p+1)+p\right)>0$. Thus, for all $z \in \mathbb{B}^{n} \backslash G_{r}$,

$$
\begin{equation*}
L^{-(p+1)}(z)\left|\partial_{\mathbf{b}}^{p+1} F(z)\right| \leqslant P_{3} \max \left\{L^{-j}(z)\left|\partial_{\mathbf{b}}^{j} F(z)\right|: 0 \leqslant j \leqslant p\right\} \tag{3.5}
\end{equation*}
$$

For any point $z^{\prime} \in A:=H\left(h_{0}\right) \backslash \bigcup_{j=1}^{p}\left(G_{r}\left(h_{j}\right) \backslash E\left(h_{j}\right)\right)$ there exists a sequence of the points $z^{m} \in \mathbb{B}^{n} \backslash G_{r}$ satisfying (3.5) with $z=z^{m}$ and such that $z^{m} \rightarrow z^{\prime}$ as $m \rightarrow \infty$. Substituting $z=z^{m}$ in (3.5) and passing to the limit as $m \rightarrow \infty$, by the joint continuity of the function $F$, we obtain that inequality is valid for all $z \in A \cup\left(\mathbb{B}^{n} \backslash G_{r}\right)$.

If all zeros of the function $H$ belong to $E(H)$, i.e., $\mathbb{B}^{n}=A \cup\left(\mathbb{B}^{n} \backslash G_{r}\right)$, then by Theorem 2.4 the function $F$, asa function from the class $\mathcal{H}_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$, has bounded $L$-index in the direction $\mathbf{b}$. Otherwise, $n(s, H) \geqslant 1$.

It is easy to see that for $r \in\left(0, \min \left\{\frac{1}{3} \beta, r^{*}\right\}\right)$ and $r^{*}=\sup _{s \geqslant 1}(s-1) /(8(n(s, H)+1) \times$ $\left.\lambda_{\mathbf{b}}(s)\right)$, there exists $r^{\prime} \in\left[1, \frac{1}{3} \beta\right)$ such that $r \leqslant\left(r^{\prime}-1\right) /\left(8\left(n\left(r^{\prime}, H\right)+1\right) \lambda_{\mathbf{b}}\left(r^{\prime}\right)\right)$.

Let $z^{*} \in \mathbb{B}^{n}$ be an arbitrary point and $K^{*}=\left\{z^{*}+t \mathbf{b}:|t| \leqslant r^{\prime} / L\left(z^{*}\right)\right\}$. The slice holomorphic functions $h_{0}, h_{1}, \ldots, h_{p}, h$ have bounded $L$-index in the direction $\mathbf{b}$, therefore by Theorem 2.3, the set $K^{*}$ contains at most $n\left(r^{\prime}, H\right)$ zeros of these functions or $K^{*} \subset Z_{H}$.

Let $c_{m}^{*}$ be the points such that $H\left(z^{*}+c_{m}^{*} \mathbf{b}\right)=0$ (i.e., $c_{m}^{*}$ are the zeros of the slice function $H$ ) and $z^{*}+c_{m}^{*} \mathbf{b} \in K^{*} \cap\left(Z_{h} \backslash E(h)\right) \cup \bigcup_{j=0}^{p}\left(Z_{h_{j}} \backslash E\left(h_{j}\right)\right)$, where $m \in \mathbb{N}$, $m \leqslant n\left(r^{\prime}, H\right)$. Remark, that $L\left(z^{*}+c_{m}^{*} \mathbf{b}\right) \geqslant L\left(z^{*}\right) / \lambda_{\mathbf{b}}\left(r^{\prime}\right)$, because $L \in Q_{\mathbf{b}}\left(\mathbb{B}^{n}\right)$. Then, obviously,

$$
\begin{aligned}
\widetilde{K}_{m}^{*} & :=\left\{z^{*}+t \mathbf{b}:\left|t-c_{m}^{*}\right| \leqslant \frac{r}{L\left(z^{*}+c_{m}^{*} \mathbf{b}\right)}\right\} \\
& \subset\left\{z^{*}+t \mathbf{b}:\left|t-c_{m}^{*}\right| \leqslant \frac{r^{\prime}-1}{8\left(n\left(r^{\prime}, H\right)+1\right) \lambda_{\mathbf{b}}\left(r^{\prime}\right) L\left(z^{*}+c_{m}^{*} \mathbf{b}\right)}\right\} \\
& \subset K_{m}^{*}:=\left\{z^{*}+t \mathbf{b}:\left|t-c_{m}^{*}\right| \leqslant \frac{r^{\prime}-1}{8\left(n\left(r^{\prime}, H\right)+1\right) L\left(z^{*}\right)}\right\} .
\end{aligned}
$$

Therefore, for each point $z^{*}+t \mathbf{b} \in K^{*} \backslash \underset{z^{*}+c_{m}^{*} \mathbf{b} \in K^{*}}{ } K_{m}^{*}$, inequality (3.5) is true and thus, for these points $z^{*}+t \mathbf{b}$ from inequalities $L\left(z^{*}\right) \geqslant L\left(z^{*}+t \mathbf{b}\right) / \lambda_{\mathbf{b}}\left(r^{\prime}\right)$ and (3.5) it follows

$$
\begin{align*}
\frac{\left|\partial_{\mathbf{b}}^{p+1} F\left(z^{*}+t \mathbf{b}\right)\right|}{L^{p+1}\left(z^{*}\right)} & \leqslant\left(\lambda_{\mathbf{b}}\left(r^{\prime}\right)\right)^{p+1} \frac{\left|\partial_{\mathbf{b}}^{p+1} F\left(z^{*}+t \mathbf{b}\right)\right|}{L^{p+1}\left(z^{*}+t \mathbf{b}\right)}  \tag{3.6}\\
& \leqslant P_{3}\left(\lambda_{\mathbf{b}}\left(r^{\prime}\right)\right)^{p+1} \max _{0 \leqslant j \leqslant p}\left\{\frac{\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t \mathbf{b}\right)\right|}{L^{j}\left(z^{*}+t \mathbf{b}\right)}\right\} \\
& \leqslant P_{3}\left(\lambda_{\mathbf{b}}\left(r^{\prime}\right)\right)^{p+1} \max _{0 \leqslant j \leqslant p}\left\{\frac{\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t \mathbf{b}\right)\right|}{L^{j}\left(z^{*}\right)}\left(\lambda_{\mathbf{b}}\left(r^{\prime}\right)\right)^{j}\right\} \\
& \leqslant P_{3}\left(\lambda_{\mathbf{b}}\left(r^{\prime}\right)\right)^{2 p+1} \max _{0 \leqslant j \leqslant p}\left\{\frac{\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t \mathbf{b}\right)\right|}{L^{j}\left(z^{*}\right)}\right\}=P_{4} w_{z^{*}}(t)
\end{align*}
$$

where $w_{z^{*}}(t)=\max \left\{\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t \mathbf{b}\right)\right| / L^{j}\left(z^{*}\right): 0 \leqslant j \leqslant p\right\}$ and $P_{4}=P_{3}\left(\lambda_{\mathbf{b}}\left(r^{\prime}\right)\right)^{2 p+1}$.
Let $D$ be a sum of diameters $K_{m}^{*}$. Then $D \leqslant 2\left(r^{\prime}-1\right) n\left(r^{\prime}, H\right) /\left(8\left(n\left(r^{\prime}, H\right)+1\right) \times\right.$ $\left.L\left(z^{*}\right)\right)<r^{\prime}-1 /\left(4 L\left(z^{*}\right)\right)$. Therefore there exist numbers $r_{1} \in\left[\frac{1}{4} r^{\prime}, \frac{1}{2} r^{\prime}\right]$ and $r_{2} \in$ $\left[\frac{1}{4}\left(3 r^{\prime}+1\right) ; r^{\prime}\right]$ such that for $z^{*}+t \mathbf{b} \in C_{j}=\left\{z^{*}+t \mathbf{b}:|t|=r_{j} / L\left(z^{*}\right)\right\}, j \in\{1,2\}$, one has $z^{*}+t \mathbf{b} \in K^{*} \backslash \bigcup_{c_{m}^{*} \in K^{*}} K_{m}^{*}$. Let $z^{*}+t_{1} \mathbf{b} \in C_{1}$ and $z^{*}+t_{2} \mathbf{b} \in C_{2}$ be arbitrary points. We connect these points $z^{*}+t_{1} \mathbf{b}, z^{*}+t_{2} \mathbf{b}$ by a smooth curve $\gamma=\left\{z^{*}+t(s) \mathbf{b}: 0 \leqslant s \leqslant 1\right\}$ (i.e., $\left.z^{*}+t(0) \mathbf{b}=z^{*}+t_{1} \mathbf{b}, z^{*}+t(1) \mathbf{b}=z^{*}+t_{2} \mathbf{b}\right)$ such that $w_{z^{*}}(t) \neq 0$ and $\gamma \subset K^{*} \backslash \bigcup_{c_{m}^{*} \in K^{*}} K_{m}^{*}$.

Let us describe in detail the construction of this curve $\gamma$, using the ideas from the proof in [9] with adapting them for the unit ball. First, let $\ell: t(s)=\left(t_{2}-t_{1}\right) s+t_{1}$, $s \in[0,1]$ be the line segment connecting the points $t_{1}$ and $t_{2}$. Let $t_{k}^{*}=\left(t_{2}-t_{1}\right) s_{k}+t_{1}$, $s_{k} \in(0,1)$ be points such that $w_{z^{*}}\left(t_{k}^{*}\right)=0$. The number $m_{0}=m_{0}\left(z^{*}+t_{1} \mathbf{b}, z^{*}+t_{2} \mathbf{b}\right)$
of such points $t_{k}^{*}$ is finite. Without loss generality of our reasoning, we can assume that $\left(t_{k}^{*}\right)$ is the sequence of these points in ascending order of values $\left|t_{1}-t_{k}^{*}\right|, k \in$ $\{1,2, \ldots, p\}$. We choose

$$
r_{0} \in\left(0, \min \left\{\left|t_{k}^{*}-t_{k+1}^{*}\right|,\left|t_{1}^{*}-t_{1}\right|,\left|t_{m_{0}}^{*}-t_{2}\right|, \frac{r^{\prime}}{4 \pi L\left(z^{*}\right)}: 1 \leqslant k \leqslant m_{0}-1\right\}\right) .
$$

We now choose circles $\gamma_{k}$ centered at the points $t_{k}^{*}$ and with radii $r_{k}^{\prime}<r_{0} / 2^{k}$ such that $w_{z^{*}}(t) \neq 0$ for all $t$ on these circles. It is possible because $F \not \equiv 0$.

Every such circle $\gamma_{k}$ is divided into two semicircles by the line $\ell$. The required piecewise-analytic curve $\ell^{*}$ consists of segments of line $\ell$, which connect the circles in series between themselves or with the points $t_{1}, t_{2}$, and of arcs of semicircles of the constructed circles. If the curve $\ell^{*}$ intersects a set $K_{m}^{*}$, then we replace part of the curve $\ell^{*} \cap K_{m}^{*}$ with a semicircle centered at the point $c_{m}^{*}$ and radius $r^{\prime} /\left(8\left(n\left(r^{\prime}, H\right)+1\right) L\left(z^{*}\right)\right)$. For the resulting curve, we keep the notation $\gamma=\ell^{*}$.

From the construction of the curve $\gamma$ described above, it can be seen that the following estimate is valid for the length of the curve

$$
\begin{align*}
|\gamma| & \leqslant|\mathbf{b}|\left(\frac{\pi r_{1}}{L\left(z^{*}\right)}+\frac{r_{2}-r_{1}}{L\left(z^{*}\right)}+\frac{\pi r_{0}}{L\left(z^{*}\right)}+\frac{\pi n\left(r^{\prime}, H\right) r^{\prime}}{8\left(n\left(r^{\prime}, H\right)+1\right) L\left(z^{*}\right)}\right)  \tag{3.7}\\
& <\frac{|\mathbf{b}|}{L\left(z^{*}\right)}\left(\frac{\pi r^{\prime}}{2}+r^{\prime}+\frac{\pi r^{\prime}}{8}\right)<\frac{3|\mathbf{b}| r^{\prime}}{L\left(z^{*}\right)} .
\end{align*}
$$

Then on $\gamma$, inequality (3.6) is valid, that is,

$$
\frac{\left|\partial_{\mathbf{b}}^{p+1} F\left(z^{*}+t(s) \mathbf{b}\right)\right|}{L^{p+1}\left(z^{*}\right)} \leqslant P_{4} w_{z^{*}}(t(s)) \quad \text { for } 0 \leqslant s \leqslant 1 .
$$

From the construction of the curve $\gamma$ described above, it is also clear that the function $z=z^{*}+t(s) \mathbf{b}:[0,1] \rightarrow \mathbb{C}$ is piecewise analytic. Hence, for arbitrary $k \in \mathbb{Z}_{+}, j \in \mathbb{Z}_{+}$, $k \leqslant p$, either

$$
\begin{equation*}
(\forall s \in[0,1]): \frac{\left|\partial_{\mathbf{b}}^{k} F\left(z^{*}+t(s) \mathbf{b}\right)\right|}{L^{k}\left(z^{*}\right)} \equiv \frac{\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right|}{L^{j}\left(z^{*}\right)}, \tag{3.8}
\end{equation*}
$$

or there exists a finite set of points $s_{m} \in[0 ; 1]$ such that

$$
\begin{equation*}
\left.\frac{\left|\partial_{\mathbf{b}}^{k} F\left(z^{*}+t(s) \mathbf{b}\right)\right|}{L^{k}\left(z^{*}\right)}\right|_{s=s_{m}}=\left.\frac{\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right|}{L^{j}\left(z^{*}\right)}\right|_{s=s_{m}} . \tag{3.9}
\end{equation*}
$$

Hence, for the function $w_{z^{*}}(t(s))=\max \left\{\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right| / L^{j}\left(z^{*}\right): 0 \leqslant j \leqslant p\right\}$, two cases are possible:
(1) In an interval of analyticity of the curve $\gamma$ the function $w_{z^{*}}(t(s))$ identically equals simultaneously to some derivatives, that is, (3.8) holds. It means that $w_{z^{*}}(t(s)) \equiv\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right| / L^{j}\left(z^{*}\right)$ for some $j \leqslant p$. Clearly, the function $\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)$ is analytic. Then $\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right|$ is a continuously differentiable function on the interval of analyticity except the points where this derivative equals zero: $\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right|=0$. However, there are not the points, because in the opposite case $w_{z^{*}}(t(s))=0$. But it contradicts the construction of the curve $\gamma$.
(2) In an interval of analyticity of the curve $\gamma$, the function $w_{z^{*}}(t(s))$ equals simultaneously to some derivatives at a finite number of points $s_{k}$, that is, (3.9) holds. Then the points $s_{k}$ divide the interval of analyticity into a finite number of segments, in which of them $w_{z^{*}}(t(s))$ equals to one from the partial derivatives, i.e., $w_{z^{*}}(t(s)) \equiv\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right| / L^{j}\left(z^{*}\right)$ for some $j \leqslant p$. As above, in each of these segments the functions $\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right|$, and $w_{z^{*}}(t(s))$ are continuously differentiable except the points $s_{k}$.

Therefore, the function $\left|g_{z^{*}}(t(s))\right|$ is continuous on $[0,1]$ and continuously differentiable except, possibly, a finite set of points. Moreover, for a complex-valued function of real variable the inequality

$$
\frac{\mathrm{d}}{\mathrm{~d} s}|\varphi(s)| \leqslant\left|\frac{\mathrm{d}}{\mathrm{~d} s} \varphi(s)\right|
$$

holds except the points $s$ where $\varphi(s)=0$. Therefore in view of (3.6) we obtain

$$
\begin{aligned}
\frac{\mathrm{d}}{\mathrm{~d} s}\left|g_{z^{*}}(t(s))\right| & \leqslant \max _{0 \leqslant j \leqslant p}\left\{\frac{\mathrm{~d}}{\mathrm{~d} s} \frac{\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right|}{L^{j}\left(z^{*}\right)}\right\} \\
& \leqslant \max _{0 \leqslant j \leqslant p}\left\{\frac{\left|\partial_{\mathbf{b}}^{j+1} F\left(z^{*}+t(s) \mathbf{b}\right)\right|}{L^{j+1}\left(z^{*}\right)}\left|t^{\prime}(s)\right| L\left(z^{*}\right)\right\} \\
& \leqslant \max _{0 \leqslant j \leqslant p+1}\left\{\frac{\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t(s) \mathbf{b}\right)\right|}{L^{j}\left(z^{*}\right)}\right\}\left|t^{\prime}(s)\right| L\left(z^{*}\right) \\
& \leqslant P_{5}\left|g_{z^{*}}(t(s))\right|\left|t^{\prime}(s)\right| L\left(z^{*}\right),
\end{aligned}
$$

where $P_{5}=\max \left\{1, P_{4}\right\}$. Hence, using (3.7), we have

$$
\begin{aligned}
\left|\ln \frac{\left|g_{z^{*}}\left(t_{2}\right)\right|}{\left|g_{z^{*}}\left(t_{1}\right)\right|}\right| & =\left|\int_{0}^{1} \frac{1}{\left|g_{z^{*}}(t(s))\right|} \frac{\mathrm{d}}{\mathrm{~d} s}\right| g_{z^{*}}(t(s))|\mathrm{d} s| \leqslant P_{5} L\left(z^{*}\right) \int_{0}^{1}\left|t^{\prime}(s)\right| \mathrm{d} s \\
& \leqslant P_{5} L\left(z^{*}\right)|\gamma| \leqslant 3|\mathbf{b}| r^{\prime} P_{5},
\end{aligned}
$$

that is,

$$
\begin{equation*}
\left|g_{z^{*}}\left(t_{2}\right)\right| \leqslant\left|g_{z^{*}}\left(t_{1}\right)\right| \exp \left\{3|\mathbf{b}| r^{\prime} P_{5}\right\} \tag{3.10}
\end{equation*}
$$

It is possible to choose $t_{2}$ such that $\left|g_{z^{*}}\left(t_{2}\right)\right|=\left|F\left(z^{*}+t_{2} \mathbf{b}\right)\right|=\max \left\{\left|F\left(z^{*}+t \mathbf{b}\right)\right|\right.$ : $\left.z^{*}+t \mathbf{b} \in C_{2}\right\}$. Hence and from inequality (3.10) we get

$$
\begin{align*}
\max \left\{\left|F\left(z^{*}+t \mathbf{b}\right)\right|:|t|=\frac{3 r^{\prime}+1}{4 L\left(z^{*}\right)}\right\} & \leqslant \max \left\{\left|F\left(z^{*}+t \mathbf{b}\right)\right|: z^{*}+t \mathbf{b} \in C_{2}\right\}  \tag{3.11}\\
& =\left|F\left(z^{*}+t_{2} \mathbf{b}\right)\right|=\left|g_{z^{*}}\left(t_{2}\right)\right| \\
& \leqslant\left|g_{z^{*}}\left(t_{1}\right)\right| \exp \left\{3|\mathbf{b}| r^{\prime} P_{5}\right\} .
\end{align*}
$$

Recalling that $z^{*}+t_{1} \mathbf{b} \in C_{1}=\left\{z^{*}+t \mathbf{b}:|t|=r_{1} / L\left(z^{*}\right)\right\}$ and $r_{1} \in\left[\frac{1}{4} r^{\prime}, \frac{1}{2} r^{\prime}\right]$, for all $j \in\{1,2, \ldots, p\}$, by Cauchy's inequality in variable $t$ on the circle $\left\{t \in \mathbb{C}:\left|t-t_{1}\right|=\right.$ $\left.r^{\prime} /\left(4 L\left(z^{*}\right)\right)\right\}$ we obtain

$$
\begin{aligned}
\frac{r^{\prime j}}{\left(4 L\left(z^{*}\right)\right)^{j}}\left|\partial_{\mathbf{b}}^{j} F\left(z^{*}+t_{1} \mathbf{b}\right)\right| & \leqslant j!\max \left\{\left|F\left(z^{*}+t \mathbf{b}\right)\right|:\left|t-t_{1}\right|=\frac{r^{\prime}}{4 L\left(z^{*}\right)}\right\} \\
& \leqslant p!\max \left\{\left|F\left(z^{*}+t \mathbf{b}\right)\right|:|t|=\frac{3 r^{\prime}}{4 L\left(z^{*}\right)}\right\}
\end{aligned}
$$

Thus,

$$
\begin{equation*}
\left|g_{z^{*}}\left(t_{1}\right)\right| \leqslant p!\max \left\{1,\left(4 / r^{\prime}\right)^{p}\right\} \max \left\{\left|F\left(z^{*}+t \mathbf{b}\right)\right|:|t|=\frac{3 r^{\prime}}{4 L\left(z^{*}\right)}\right\} \tag{3.12}
\end{equation*}
$$

We put $P_{6}=p!\max \left\{1,\left(4 / r^{\prime}\right)^{p}\right\} \exp \left\{3|\mathbf{b}| r^{\prime} P_{5}\right\}$. Then inequalities (3.11) and (3.12) imply that

$$
\max \left\{\left|F\left(z^{*}+t \mathbf{b}\right)\right|:|t|=\frac{3 r^{\prime}+1}{4 L\left(z^{*}\right)}\right\} \leqslant P_{6} \max \left\{\left|F\left(z^{*}+t \mathbf{b}\right)\right|:|t|=\frac{3 r^{\prime}}{4 L\left(z^{*}\right)}\right\}
$$

Finally, by Theorem 2.1, the function $F \in B_{\mathbf{b}}\left(L, \mathbb{B}^{n}\right)$.

## References

[1] V.Baksa, A. Bandura, O. Skaskiv: Analogs of Hayman's theorem and of logarithmic criterion for analytic vector-valued functions in the unit ball having bounded $L$-index in joint variables. Math. Slovaca 70 (2020), 1141-1152.
[2] A. Bandura, M. Martsinkiv, O. Skaskiv: Slice holomorphic functions in the unit ball having a bounded $L$-index in direction. Axioms 10 (2021), Article ID 4, 15 pages.
3] A.I. Bandura, T. M. Salo, O. B. Skaskiv: Slice holomorphic functions in the unit ball: Boundedness of $L$-index in a direction and related properties. Mat. Stud. 57 (2022), 68-78.
[4] A. Bandura, L. Shegda, O. Skaskiv, L. Smolovyk: Some criteria of boundedness of $L$-index in a direction for slice holomorphic functions in the unit ball. Int. J. Appl. Math. 34 (2021), 775-793.
[5] A. Bandura, O. Skaskiv: Boundedness of the $L$-index in a direction of entire solutions of second order partial differential equation. Acta Comment. Univ. Tartu. Math. 22 (2018), 223-234.
zbl MR doi
[6] A. Bandura, O. Skaskiv: Analog of Hayman's theorem and its application to some system of linear partial differential equations. J. Math. Phys. Anal. Geom. 15 (2019), 170-191.
zbl MR doi
[7] A. Bandura, O. Skaskiv: Linear directional differential equations in the unit ball: Solutions of bounded $L$-index. Math. Slovaca 69 (2019), 1089-1098.
[8] A. Bandura, O. Skaskiv: Slice holomorphic functions in several variables with bounded
$L$-index in direction. Axioms 8 (2019), Article ID 88, 12 pages.
[9] A. Bandura, O. Skaskiv: Some criteria of boundedness of the $L$-index in direction for
zbl MR doi
[9] A. Bandura, O. Skaskiv: Some criteria of boundedness of the $L$-index in direction for
slice holomorphic functions of several complex variables. J. Math. Sci., New York 244 (2020), 1-21.
zbl MR doi
[10] A. Bandura, O. Skaskiv, P. Filevych: Properties of entire solutions of some linear PDE's. J. Appl. Math. Comput. Mech. 16 (2017), 17-28.

MR doi
[11] A. Bandura, O.Skaskiv, L. Smolovyk: Slice holomorphic solutions of some directional differential equations with bounded $L$-index in the same direction. Demonstr. Math. 52 (2019), 482-489.
zbl MR doi
[12] M. T. Bordulyak: A proof of Sheremeta's conjecture concerning entire function of bounded $l$-index. Mat. Stud. 12 (1999), 108-110.
zbl
[13] M. T. Bordulyak, M. M. Sheremeta: On the existence of entire functions of bounded $l$-index and $l$-regular growth. Ukr. Math. J. 48 (1996), 1322-1340.
zbl MR doi
[14] G. H. Fricke: Functions of bounded index and their logarithmic derivatives. Math. Ann. 206 (1973), 215-223.
[15] G. H. Fricke: Entire functions of locally slow growth. J. Anal. Math. 28 (1975), 101-122. zbl doi
[16] W. K. Hayman: Differential inequalities and local valency. Pac. J. Math. 44 (1973), 117-137.
[17] I. M. Hural: About some problem for entire functions of unbounded index in any direction. Mat. Stud. 51 (2019), 107-110.
zbl MR doi
[18] A. D. Kuzyk, M. N. Sheremeta: Entire functions of bounded l-distribution of values. Math. Notes 39 (1986), 3-8.
zbl MR doi
[19] A. D. Kuzyk, M. N. Sheremeta: Entire functions satisfying linear differential equations. Differ. Equations 26 (1990), 1268-1273.
zbl MR doi
B. Lepson: Differential equations of infinite order, hyperdirichlet series and entire functions of bounded index. Entire Functions and Related Parts of Analysis. Proceedings of Symposia in Pure Mathematics 11. AMS, Providence, 1968, pp. 298-307.
zbl MR
[21] J. J. MacDonnell: Some Convergence Theorems for Dirichlet-type Series Whose Coefficients Are Entire Functions of Bounded Index: Doctoral Dissertation. Catholic University of America, Washington, 1957.

MR
[22] F. Nuray, R. F. Patterson: Multivalence of bivariate functions of bounded index. Matematiche 70 (2015), 225-233.
zbl MR doi
[23] F. Nuray, R.F. Patterson: Vector-valued bivariate entire functions of bounded index satisfying a system of differential equations. Mat. Stud. 49 (2018), 67-74.
zbl MR doi
[24] S. M. Shah: Entire functions of bounded index. Proc. Am. Math. Soc. 19 (1968), 1017-1022.
zbl MR doi
[25] S. M. Shah: Entire functions satisfying a linear differential equation. J. Math. Mech. 18 (1969), 131-136.
zbl MR doi
[26] S. M. Shah: Entire function of bounded index. Complex Analysis. Lecture Notes in Mathematics 599. Springer, Berlin, 1977, pp. 117-145.
zbl MR doi
[27] M. M. Sheremeta: Generalization of the fricke theorem on entire functions of finite index. Ukr. Math. J. 48 (1996), 460-466.
[28] M. Sheremeta: Analytic Functions of Bounded Index. Mathematical Studies Monograph Series 6. VNTL Publishers, Lviv, 1999.
zbl MR
[29] M. M. Sheremeta: On the $l$-index boundedness of some composition of functions. Mat. Stud. 47 (2017), 207-210.
zbl MR doi
[30] M. M. Sheremeta, M. T. Bordulyak: Boundedness of the $l$-index of Laguerre-Pólya entire functions. Ukr. Math. J. 55 (2003), 112-125.
zbl MR doi
[31] S. Strelitz: Asymptotic properties of entire transcendental solutions of algebraic differential equations. Value Distribution Theory and Its Applications. Contemporary Mathematics 25. AMS, Providence, 1983, pp. 171-214.

Authors' addresses: Andriy Bandura (corresponding author), Ivano-Frankivsk National Technical University of Oil and Gas, Karpatska 15, 76019 Ivano-Frankivsk, Ukraine, e-mail: andriykopanytsia@gmail.com; Tetyana Salo, Lviv Polytechnic National University, Stepana Bandery St. 12, 79000 Lviv, Ukraine, e-mail: tetyan.salo@gmail.com; Oleh Skaskiv, Ivan Franko National University of Lviv, Universytetska St. 1, 79000 Lviv, Ukraine, e-mail: olskask@gmail.com.

