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# HARDY SPACE METHODS FOR NONLINEAR PARTIAL DIFFERENTIAL EQUATIONS

STEFAN MÜLLER

**ABSTRACT.** Hardy space methods have lead to remarkable progress on nonlinear partial differential equations with critical growth. The results obtained by a variety of authors include the regularity theory for weakly harmonic maps, existence results for the two-dimensional instationary Euler equations with vortex sheet initial data and the Lipschitz parametrization of  $W^{2,2}$  surfaces. This paper gives a quick review of the basic tools needed and discusses their application.

## 1. Introduction

In recent years research by a variety of authors lead to remarkable progress in the study of nonlinear partial differential equations with critical growth through the use of Hardy space methods. The idea is simple. A typical difficulty when dealing with such equations is that the nonlinear term is a priori only known to be in  $L^1$  while there is no good elliptic theory in  $L^1$ . There is, however, a well-established regularity theory in the slightly smaller Hardy space  $\mathcal{H}^1$  and Coifman, Meyer, Lions and Semmes [CLMS] recently discovered that certain nonlinear quantities which at first glance only seem to be in  $L^1$  are in fact in  $\mathcal{H}^1$ . In the following I will briefly discuss applications of this idea to the (longstanding) regularity problem for harmonic maps, good parametrizations of surfaces and the two-dimensional Euler equations. Further applications can be found in [CLMS]. First, it is time to recall the definition of  $\mathcal{H}^1$  and some of its properties.

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## 2. The Hardy space $\mathcal{H}^1$

The *Hardy spaces*  $\mathcal{H}^p$  (with  $0 < p < \infty$ ) have been an object of interest in complex analysis for a long time. A breakthrough came in the early 70's when it was discovered that they possess a simple real variable characterization and that various seemingly unrelated definitions are equivalent. A classic reference is the article by Fefferman and Stein [FS] (see also [Se] for a short introduction to Hardy spaces). In the following we only consider  $\mathcal{H}^1(\mathbb{R}^n)$  which can be defined as follows.

Let  $\phi$  be a smooth function with compact support in the unit ball and suppose that  $\int \phi = 1$ . For a function  $f \in L^1(\mathbb{R}^n)$  define the regularized maximal function by

$$f^*(x) = \sup_{\varepsilon > 0} \left| \int_{\mathbb{R}^n} \varepsilon^{-n} \phi\left(\frac{x-y}{\varepsilon}\right) f(y) dy \right|. \quad (1)$$

**DEFINITION 1.** The function  $f$  is in  $\mathcal{H}^1(\mathbb{R}^n)$  if and only if  $f^* \in L^1(\mathbb{R}^n)$ .

The expression  $\|f^*\|_{L^1}$  defines a norm on  $\mathcal{H}^1$  and different choices of  $\phi$  lead to equivalent norms. Note that  $f^*$  is closely related to the Hardy–Littlewood maximal function but that it takes into account possible cancellations since the absolute value is taken outside the integral. By the Lebesgue point theorem  $\mathcal{H}^1$  is a subspace of  $L^1$ . Note also that  $f$  can only be in  $\mathcal{H}^1$  if  $\int f = 0$  since otherwise  $f^*$  only decays like  $|x|^{-n}$  at  $\infty$ .

A crucial property of  $\mathcal{H}^1$  is that elliptic operators (or more generally singular integral operators) behave well on that space while the same is not true in  $L^1$ . We will only need the following result.

**THEOREM 2.** ([FS]). Let  $f \in \mathcal{H}^1$  and let  $u$  be a solution of

$$-\Delta u = f \quad \text{in } \mathbb{R}^n.$$

Then  $u$  can be written in the form  $u = u_0 + H$  where  $H$  is harmonic and  $u_0$  satisfies

$$\|\nabla^2 u_0\|_{\mathcal{H}^1} \leq C \|f\|_{\mathcal{H}^1}. \quad (2)$$

If  $n = 2$  then one can use the embeddings (see [Ad], Lemma 5.8)  $W^{2,1} \hookrightarrow C^0$  and  $W^{2,1} \hookrightarrow W^{1,2}$  to show that  $u_0 \in W^{1,2} \cap C^0$  and

$$\|\nabla u_0\|_{L^2} + \|u_0\|_{L^\infty} \leq \|f\|_{\mathcal{H}^1}. \quad (3)$$

The space  $\mathcal{H}^1$  has various other interesting properties. In particular its dual is the John–Nirenberg space BMO of functions of bounded mean oscillation, see [FS], [Se], [Tor] ... for many further details.

In the last section we will also need local versions of the Hardy space. To this end let

$$f^{**}(x) = \sup_{1 > \varepsilon > 0} \left| \int_{\mathbb{R}^n} \varepsilon^{-n} \phi\left(\frac{x-y}{\varepsilon}\right) f(y) dy \right|.$$

The local Hardy space  $h^1$  introduced by G o l d b e r g [Go] consists of all functions  $f$  for which  $\|f^{**}\|_{L^1}$  is finite and this quantity gives a norm on  $h^1$ . Finally  $\mathcal{H}_{\text{loc}}^1$  consists of all functions  $f$  for which  $f^{**} \in L_{\text{loc}}^1$  (see also [Zhe] and [EM], Section 5).

### 3. Some nonlinearities are special

It has been known for some time now that certain nonlinear expressions such as the Jacobien  $\det \nabla u$  of a map  $u : \mathbb{R}^n \rightarrow \mathbb{R}^n$  behave particular well under weak convergence and this observation has been crucial in such diverse fields as nonlinear elasticity and quasiregular maps (see [Mo], [Re], [Ba]).

More recently it emerged that the Jacobien also enjoys special integrability properties. The following result was shown in [Mu1], [Mu2] (inspired by results of Zhang [Zh]): if  $u \in W^{1,n}(\mathbb{R}^n, \mathbb{R}^n)$  and if  $\det \nabla u \geq 0$  a.e. then  $\det \nabla u \log(2 + \det \nabla u)$  is locally integrable (see [IS], [BFS], [IL], [Mi] for further developments). The space  $L \log L$  is well known in harmonic analysis and Coifman, Lions, Meyer and Semmes, partially motivated by the above results, established the crucial connection to  $\mathcal{H}^1$ .

**THEOREM 3.** ([CLMS]) *If  $u \in W^{1,n}(\mathbb{R}^n, \mathbb{R}^n)$  then  $\det \nabla u \in \mathcal{H}^1$  and*

$$\|\det \nabla u\|_{\mathcal{H}^1} \leq C \|\nabla u\|_{L^n}^n. \tag{4}$$

The connection between weakly continuous quantities and quantities that enjoy higher integrability does not seem to be coincidental. See [CLMS] for results similar to the one above for the quantities that appear in the theory of compensated compactness which was developed by Murat and Tartar (see [Ta1]). Combining Theorems 2 and 3 one can recover the remarkable earlier results of Wente [We] (see also Brezis and Coron [BC] and Tartar [Ta2], [Ta3], [Ta4]) on the equation  $-\Delta u = \det \nabla v$  (Wente considered a slightly more special case but the same ideas apply).

A very short proof of the theorem which starts from the definition of  $\mathcal{H}^1$  given in Section 2 and uses only the fact that the Jacobien can be written as a divergence (see [Mo], [Re], [Ba]), the Sobolev–Poincare inequality and  $L^p$  ( $p > 1$ ) estimates for the Hardy–Littlewood maximal function (see [St]) appears in [Li] (see also [Ev]).

### 4. Weakly harmonic maps

Let  $B$  be the unit ball in  $\mathbb{R}^2$  and let  $u \in W^{1,2}(B, \mathbb{R}^{n+1})$ . Suppose that

$$u(x) \in S^n \quad \text{a.e.}$$

We say that  $u$  is weakly harmonic if

$$-\Delta u = u|\nabla u|^2 \tag{5}$$

in the weak sense, i.e. if  $u$  is a stationary point of the Dirichlet integral subject to the constraint  $u \in S^n$ . It had been open for a long time whether all such maps are smooth although that was known under additional assumptions (see, e.g., the references in [He1], [He2], [Ri]).

**THEOREM 4.** ([He1]) *Weakly harmonic maps are smooth.*

Helein also showed that the regularity theorem still holds if the target  $S^n$  is replaced by an arbitrary Riemannian manifold ([He2]). His results were generalized by Evans [Ev] and Bethuel [Be] who proved partial regularity of weakly harmonic maps from higher dimensional domains provided that a monotonicity formula holds. Riviere [Ri] gave counterexamples to regularity if that condition is not imposed.

*A sketch of the proof.* The first observation is that equation (5) can be written in divergence form. This is essentially a consequence of the symmetries of  $S^n$  and Noether's theorem and to the author's knowledge was first observed in the derivation of the Eriksen–Leslie theory of liquid crystals (see [Le]), see also Shah ([Sh]). Specifically a map  $u: B \rightarrow S^n$  (in  $W^{1,2}$ ) is a weak solution of (5) if and only if

$$\operatorname{div} b^{ij} = 0, \quad \text{for all } i, j = 1, \dots, n + 1,$$

where

$$b^{ij} = u^i \nabla u^j - u^j \nabla u^i.$$

In particular there exist functions  $w^{ij}$  such that  $b^{ij} = \nabla^\perp w^{ij}$ , where  $\nabla^\perp = (-\partial/\partial x^2, \partial/\partial x^1)$ . A short calculation using  $|u| = 1$  shows that

$$u^i |\nabla u|^2 = \sum_j \det(\nabla w^{ij}, \nabla u^j)$$

and (after a suitable localization argument) it follows from Theorems 2 and 3 that  $u$  is continuous. Standard results for harmonic maps then imply that  $u$  is smooth. □

It should be noted Helein's original proof does not use  $\mathcal{H}^1$ , in fact the result in the appendix of [BC] gives slightly more precise results. The proof for general targets, as well as the partial regularity results do, however, make use of  $\mathcal{H}^1$  (see also the references in [Ev] and [Be]).

### 5. Lipschitz parametrization of $W^{2,2}$ graphs

Let  $w \in W^{2,2}(\mathbb{R}^2)$  and let  $\Gamma \subset \mathbb{R}^3$  be the graph of  $w$ . Although  $W^{2,2}$  functions need not to be Lipschitz, Toro established the striking fact that  $\Gamma$  has a bilipschitz parametrization.

**THEOREM 5.** ([To]) *There exists a parametrization  $f : \mathbb{R}^2 \rightarrow \Gamma$  and a constant  $C$  (depending only on  $\|\nabla^2 w\|_{L^2}$ ) such that for all  $x, y \in \mathbb{R}^2$*

$$C^{-1}|x - y| \leq |f(x) - f(y)| \leq C|x - y|.$$

Toro's proof proceeds by an explicit iterative construction. Here I would like to sketch the alternative proof of [MS].

**S k e t c h o f p r o o f.** For convenience we assume that  $w$  is smooth with compact support and show that the Lipschitz constant  $C$  only depends on  $\|\nabla^2 w\|_{L^2}$ . Let  $f$  be a conformal parametrization of  $\Gamma$ , i.e.,  $f_{x_1} \cdot f_{x_2} = 0$  and  $|f_{x_1}| = |f_{x_2}| = e^u$ . Since  $w$  has compact support  $u$  is harmonic outside a large ball and hence has a limit at  $\infty$ . Replacing  $f(x)$  by  $f(\lambda x)$  if necessary we may assume that this limit is zero.

The Gauss curvature  $K$  of  $\Gamma$  satisfies

$$-\Delta u = e^{2u}(K \circ f).$$

Let  $N : \Gamma \rightarrow S^2$  be the Gauss map that associates to each point  $p \in \Gamma$  its normal  $N(p)$  (given by  $f_{x_1} \wedge f_{x_2} / |f_{x_1} \wedge f_{x_2}|$ ) and let  $\phi = N \circ f$ . Since  $K$  is the Jacobien of the Gauss map we have

$$e^{2u}(K \circ f) = \det \nabla \phi.$$

By the conformal invariance of the Dirichlet integral and a short calculation

$$\int_{\mathbb{R}^2} |\nabla \phi|^2 dx = \int_{\Gamma} |\nabla N|^2 \leq \int_{\mathbb{R}^2} |\nabla^2 w|^2 dx.$$

It now follows from Theorems 2 and 3 (and (4)) that

$$\sup |u| \leq C \int_{\mathbb{R}^2} |\nabla^2 w|^2 dx. \tag{6}$$

Here we used the fact that bounded harmonic functions are constant and that  $u$  approaches zero at infinity. In applying Theorem 3 we glossed over the fact

that  $\phi$  takes its values in  $S^2$  rather than  $\mathbb{R}^2$ . This causes no problem since  $\Gamma$  is a graph and therefore  $\phi$  only takes its values in the upper half-sphere which can be mapped to a ball in  $\mathbb{R}^2$  by a volume-preserving diffeomorphism.

From (6) we obtain the upper bound in the theorem. For the lower bound a short argument is needed to compare the extrinsic and the intrinsic distance on  $\Gamma$  (see [MS], Section 5).  $\square$

Similar techniques can be applied to (smooth) immersed surfaces  $M \hookrightarrow \mathbb{R}^n$  which need not be graphs. The fundamental assumption in this case is that the second fundamental form  $A$  satisfies

$$\int_M |A|^2 < \infty. \tag{7}$$

By a result of H u b e r [Hu] such surfaces admit a conformal parametrization  $f : S \setminus \{a_1, \dots, a_q\} \rightarrow M \hookrightarrow \mathbb{R}^n$  where  $S$  is a compact Riemann surface.

**THEOREM 6.** ([MS]) *Let  $M$  be as above and suppose that  $M$  is complete, connected and non-compact. Then the immersion  $f$  is proper, i.e.  $f(x) \rightarrow \infty$  if  $x \rightarrow a_i$ . If, in addition,  $\int_M |A|^2 < 4\pi$ , then the conformal type of  $M$  is  $C$  and  $f : C \rightarrow M \hookrightarrow \mathbb{R}^n$  is an embedding.*

## 6. Instationary Euler equations

We are interested in solutions of the two-dimensional instationary Euler equations

$$u_t + \operatorname{div} u \otimes u = -\nabla p, \tag{8}$$

$$\operatorname{div} u = 0, \tag{9}$$

with “rough” initial data. More precisely we suppose that  $u_0(x) := u(0, x)$  satisfies

$$\omega_0 := \operatorname{curl} u_0 \in \mathcal{M},$$

where  $\mathcal{M}$  denotes the space of Radon measures on  $\mathbb{R}^2$ . The condition  $\operatorname{div} u_0 = 0$  and  $\omega_0$  determine  $u_0$  up to a gradient of a harmonic function. Choose a normalization by requiring that  $u_0$  can be written as  $u_0(x) = \lambda(|x|)x^\perp + u_1(x)$  where  $\lambda$  is smooth and where  $u_1 \in L^2(\mathbb{R}^2; \mathbb{R}^2)$ .

The case where  $\omega_0$  is a one-dimensional measure concentrated on a curve corresponds to so-called vortex-sheet initial data which are believed to be of

great practical importance and have been studied extensively numerically (see, e.g., [Ma1] and the references therein).

A standard procedure to obtain solutions for such rough initial data  $u_0$  is to approximate them by smooth data  $u_{0\epsilon}$  and to pass to the limit  $\epsilon \rightarrow 0$  in the corresponding solutions  $u_\epsilon$ . By the usual estimates (see [Yu], [Ka], [DM], [De]) one obtains bounds (independent of  $\epsilon$ ) for  $u_\epsilon(t, \cdot) \in L^2_{loc}$ ,  $\omega_\epsilon(t, \cdot) \in L^1_{loc}$ , uniformly for  $t \in [0, T]$  and there exists a sequence  $\epsilon_j \rightarrow 0$  such that

$$\begin{aligned} u_{\epsilon_j} &\rightharpoonup \bar{u} \quad \text{weakly in } L^2_{loc}([0, T] \times \mathbb{R}^2) \\ u_{\epsilon_j} &\rightarrow \bar{u} \quad \text{a.e. in } [0, T] \times \mathbb{R}^2. \end{aligned}$$

If instead of weak convergence in  $L^2_{loc}$  one had strong convergence then one could easily show that  $\bar{u}$  is a solution of (8) and (9). Such strong convergence may, however not hold in general (cf. [Ma1]). Di Perna and Majda (see [DM], where further references can be found) begun a detailed investigation into the question whether a limit of (exact or approximate) solutions of Euler’s equation is again a solution if no strong convergence holds. In particular they showed that this is the case for the stationary Euler equation (in two dimensions) by a careful analysis of the “concentration set” where strong convergence fails. It has so far not been possible to extend that approach to the time-dependent case, mainly due to poor control in time (but see [Lo], [Bi]).

Delort [De] took a different approach. First note that  $u$  is a weak solution of (8), (9) if and only if

$$\omega_t = ((u^2)^2 - (u^1)^2)_{x_1x_2} + (u^1u^2)_{x_2x_2} - (u^1u^2)_{x_1x_1}, \tag{10}$$

where  $\omega = \text{curl } u$  or

$$u = K * \omega, \quad K(z) = \frac{1}{2\pi} \frac{z^\perp}{|z|^2}. \tag{11}$$

Delort then showed the following, using the representation (11) of  $u$ .

**THEOREM 7.** *If  $\omega_{0\epsilon} \geq 0$  then one has with the above notation*

$$u^1_{\epsilon_j} u^2_{\epsilon_j} \rightharpoonup \bar{u}^1 \bar{u}^2, \quad (u^1_{\epsilon_j})^2 - (u^2_{\epsilon_j})^2 \rightharpoonup (\bar{u}^1)^2 - (\bar{u}^2)^2$$

*in the sense of distributions. In particular  $\bar{u}$  is a solution of (8), (9).*

For variants and generalizations of Delort’s argument see [Ge] and [Ma2].

In [EM] (see also [Se]) an attempt was made to understand Delort’s result in the context of Hardy spaces. The main observation is the following.



**THEOREM 8.** *Let  $\psi \in W_{\text{loc}}^{1,2}(\mathbb{R}^2)$  and suppose that  $\Delta\psi \geq 0$ . Then  $\psi_{x_1}\psi_{x_2}$  and  $(\psi_{x_1})^2 - (\psi_{x_2})^2$  are in  $\mathcal{H}_{\text{loc}}^1$  and for each  $\phi \in C_0^\infty(\mathbb{R}^2)$  one has*

$$\|\phi\psi_{x_1}\psi_{x_2}\|_{h^1} + \|\phi((\psi_{x_1})^2 - (\psi_{x_2})^2)\|_{h^1} \leq C \int_{B(0,R)} |D\psi|^2 dx,$$

where  $C$  and  $R$  only depend on  $\phi$  (but not on  $\psi$ ).

The proof is similar in spirit to Delort's and relies on the definition of  $\mathcal{H}_{\text{loc}}^1$  given above and the representation (11) of  $u$ .

For the application to the Euler equation note that due to the equation  $\text{div } u = 0$ ,  $u$  can be expressed as  $u = \nabla^\perp \psi$  so that  $\omega = \text{curl } u = \Delta\psi$ .

Delort's result can then be recovered from the following fact (see [EM] for details of the argument).

**THEOREM 9.** ([JJ], [EM]). *Suppose that  $f_j \rightarrow f$  a.e. and that  $\|f_j\|_{h^1}$  is bounded. Then  $f_j \rightarrow f$  in the sense of distributions.*

Note that the result fails if  $h^1$  is replaced by  $L^1$ . Using the Hardy space approach one also obtains a new estimate for the streamfunction  $\psi$ , namely  $\psi_t \in L^\infty([0, T], L_{\text{loc}}^1)$  or more precisely

$$\|\phi\psi_t(t, \cdot)\|_{h^1} \leq C(\phi, T), \quad \text{for all } \phi \in C_0^\infty(\mathbb{R}^2), \quad t \in [0, T].$$

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