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MIXED FINITE ELEMENT IN 3D IN $H(\text{div})$ AND $H(\text{curl})$

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I. INTRODUCTION.

Frayes De Venbeke first introduces the mixed finite element. Then P.A. Raviart and J.M. Thomas does some mathematics on these element in 2D and others do also :

F. Brezzi V. Babuska ...

In 1980 we introduce a family of some mixed finite element in 3D and we use them for solving Navier Stokes equations.

In 1984 F. Brezzi, J. Douglass and L.D. Marini introduce in 2D a new family of mixed finite element conforming in $H(\text{div})$. That paper was the starting point for building new families of finite element in 3D.

II. FINITE ELEMENT IN $H(\text{div})$.

Notations.

K is a tetrahedron

∂K its boundary

n the normal

f a face which area is $\int_f d\gamma$

a is an edge which length is $\int_a ds$

$\text{curl } u = \nabla \wedge u \quad u = (u_1, u_2, u_3)$

$H(\text{curl}) = \{u \in L^2(\Omega)^3 ; \text{curl } u \in (L^2(\Omega))^3 \}$

$\text{div} = \nabla \cdot u$

$H(\text{div}) = \{u \in (L^2(\Omega))^3 ; \text{div } u \in L^2(\Omega) \}$

Spaces of polynomials.

$P_k =$ polynomials of degree less or equal to k

$\tilde{P}_k =$ " homogeneous of degree k

$\mathcal{D}_k = (P_{k-1})^3 + \tilde{P}_{k-1} \quad r$

$$r = \begin{cases} x_1 \\ x_2 \\ x_3 \end{cases}$$

$S_k = \{p \in (P_k) ; (r \cdot p) \equiv 0 \}$

$\mathcal{R}_k = (P_{k-1})^3 \oplus S_k$

$$\dim S_k = k(k+2)$$

$$\dim D_k = \frac{(k+3)(k+1)k}{2}$$

$$\dim R_k = \frac{(k+3)(k+2)k}{2}$$

We are now able to introduce the finite element conforming in $H(\text{div})$.

Definition. We define the finite element by

- 1) K is a tetrahedron
- 2) $P = (P_k)^3$ is a space of polynomials
- 3) The set of degrees of freedom which are

$$(3.1) \quad \int_f (p \cdot n) q \, d\gamma ; \quad \forall q \in P_k(f) ;$$

$$(3.2) \quad \int_K (p \cdot q) \, dx ; \quad \forall q \in R_{k-1} .$$

we have the

Theorem.

The above finite element is unisolvent and conforming in $H(\text{div})$. The associate interpolation operator Π is such that

$$\text{div } \Pi p = \Pi^* \text{div } p ; \quad \forall p \in H(\text{div}) ,$$

where Π^* is the L^2 projection on P_{k-1} .

When $k = 1$, the corresponding element has no interior moments and 12 degrees of freedom. Its divergence is constant.

Proposition. For a tetrahedron "regular enough" which diameter is h , we have

$$\| p - \Pi p \|_{(L^2(K))^3} \leq c h^{k+1} \| p \|_{(H^{k+1}(K))^3} ;$$

$$\| D(p - \Pi p) \|_{(L^2(K))^3} \leq c h^k \| p \|_{(H^{k+1}(K))^3} .$$

We are not going to prove this theorem. But we can recall that a finite element is said to be conforming in a functional space if the interpolate of an element of this space belong to this space.

In our case, the conformity in $H(\text{div})$ is equivalent to the continuity of the normal component at each interface. This property is clearly true for our finite element since the unknowns on the face are

$$\int_f (p \cdot n) q \, d\gamma ; \quad \forall q \in P_k(f)$$

and $p \cdot n$ is also $P_k(f)$.

III. FINITE ELEMENT IN H(curl).

A finite element is conforming in H(curl) if the tangential components are continue at the interface of the mesh.

We introduce the corresponding finite element.

Définition.

- 1) K is a tetrahedron
- 2) $P = (P_k)^3$ is the space of polynomials
- 3) The degrees of freedom are the following moments

$$3.1) \int_a (p \cdot \tau) q \, ds \quad ; \quad \forall q \in P_k(a)$$

$$3.2) \int_f (p \cdot q) \, d\gamma \quad ; \quad \forall q \in \mathcal{D}_{k-1}(f) \text{ and tangent to the face } f$$

$$3.3) \int_K (p \cdot q) \, dx \quad ; \quad \forall q \in \mathcal{D}_{k-2} \quad .$$

We have the

Theorem.

The above finite element is unisolvent and conforming in H(curl). Moreover if Π is the corresponding interpolation operator and Π^* the interpolation operator associate to the H(div) finite element introduce previously for degree k-1 we have

$$\text{curl } \Pi p = \Pi^* \text{curl } p$$

IV. APPLICATION TO THE EQUATION OF STOKES.

The Stokes' equation is usually written in the (u,p) variable in a bounded domain Ω of \mathbb{R}^3 as

$$\left\{ \begin{array}{l} -\nu \Delta u + \text{grad } p = f \quad , \quad \text{in } \Omega \\ \text{div } u = 0 \quad \quad \quad \text{in } \Omega \\ u|_{\Gamma} = 0 \end{array} \right.$$

We introduce the vector potential ϕ as

$$\left\{ \begin{array}{l} -\Delta \phi = \text{curl } u \quad , \quad \text{in } \Omega \\ \text{div } \phi = 0 \quad \quad \quad \text{in } \Omega \\ \phi \wedge n|_{\Gamma} = 0 \end{array} \right.$$

Then the Stokes equation can be written in the (ϕ, ω) variables where

$$\omega = \text{curl } u$$

We introduce

$$H(\text{div}^0) = \{ v \in (L^2(\Omega))^3 \ ; \ \text{div } v \in 0 \ , \ v \cdot n|_{\Gamma} = 0 \}$$

$$H = \{ \psi \in H(\text{curl}) \ ; \ \text{div } \psi = 0 \ ; \ \psi \wedge n|_{\Gamma} = 0 \}$$

Then a variational formulation of the Stokes equation is

$$\left\{ \begin{array}{l} \nu \int_{\Gamma} (\text{curl } \omega \cdot \text{curl } \psi) dx = \int_{\Omega} (f \cdot \text{curl } \psi) dx ; \forall \psi \in H \\ \int_{\Omega} (\omega \cdot \Pi) dx - \int_{\Omega} (\text{curl } \phi \cdot \text{curl } \Pi) dx = 0 ; \forall \Pi \in H(\text{curl}) \end{array} \right.$$

Let C_h be a mesh covering Ω .

We can introduce some finite element spaces

$$W_h = \{ \omega_h \in H(\text{curl}) ; \omega_h|_K \in (P_k)^3 ; \forall K \in C_h \}$$

$$W_h^0 = \{ \omega_h \in W_h ; \omega_h \wedge n|_{\Gamma} = 0 \}$$

$$V_h = \{ v_h \in H(\text{div}) ; v_h|_K \in (P_{k-1})^3 ; \forall K \in C_h \}$$

$$U_h = V_h \cap H(\text{div}^0)$$

The approximate problem become then

$$\left\{ \begin{array}{l} \nu \int_{\Omega} (\text{curl } w_h \cdot v_h) dx = \int_{\Omega} (f \cdot v_h) dx ; \forall v_h \in U_h ; \\ \int_{\Omega} (w_h \cdot \Pi_h) dx - \int_{\Omega} (u_h \cdot \text{curl } \Pi_h) dx = 0 ; \forall \Pi_h \in W_h . \end{array} \right.$$

We can also use a vector potential ϕ_h .

This goes like that

$$\Theta_h = \{ \theta_h \in H^1(\Omega) ; \theta_h|_K \in P_{k+1} ; \forall K \in C_h \}$$

$$\Theta_h^0 = \Theta_h \cap H_0^1(\Omega)$$

We have the

Theorem.

If the transgulation is regular, for every $v_h \in U_h$, there exist a unique $\psi_h \in W_h^0$ such that

$$\left\{ \begin{array}{l} \text{curl } \psi_h = v_h \\ \int_{\Omega} (\psi_h \cdot \text{grad } \theta_h) dx = 0 ; \forall \theta_h \in \Theta_h^0 \end{array} \right.$$

and we have also

$$\|\psi_h\|_{H(\text{curl})} \leq c \|v_h\|_{(L^2(\Omega))^3} .$$

This theorem can be use to transfer the above approximate problem in one in (ψ, ω) and also to find a local basis in the space U_h .

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