

# EQUADIFF 10

---

Josef Diblík; Miroslava Růžičková

Solutions of a singular Cauchy problem for a nonlinear system of differential equations

In: Jaromír Kuben and Jaromír Vosmanský (eds.): Equadiff 10, Czechoslovak International Conference on Differential Equations and Their Applications, Prague, August 27-31, 2001, [Part 2] Papers. Masaryk University, Brno, 2002. CD-ROM; a limited number of printed issues has been issued. pp. 135--137.

Persistent URL: <http://dml.cz/dmlcz/700346>

## Terms of use:

© Institute of Mathematics AS CR, 2002

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://project.dml.cz>

# Solutions of a singular Cauchy problem for a nonlinear system of differential equations

Josef Diblík<sup>1</sup> and Miroslava Růžičková<sup>2</sup>

<sup>1</sup> Department of Mathematics,  
Faculty of Electrical Engineering and Computer Science,  
Brno University of Technology (VUT),  
Technická 8, 616 00 Brno, Czech Republic

Email: [diblik@dmf.fee.vutbr.cz](mailto:diblik@dmf.fee.vutbr.cz)

<sup>2</sup> Department of Appl. Mathematics,  
Faculty of Science,  
University of Žilina,

J. M. Hurbana 15, 010 26 Žilina, Slovak Republic

Email: [ruzickova@fpv.utc.sk](mailto:ruzickova@fpv.utc.sk)

**Abstract.** The solvability of the singular Cauchy problem for the system of nonlinear differential equations

$$\begin{aligned}g(x)y' &= A(x)\alpha(y) - \omega(x), \\ y(0^+) &= 0\end{aligned}$$

is investigated.

**MSC 2000.** 34C10, 34C15, 34B15

**Keywords.** Positive solution, nonlinear system, singular Cauchy problem

Let us consider the system of nonlinear differential equations

$$g(x)y' = A(x)\alpha(y) - \omega(x) \tag{1}$$

and initial Cauchy problem

$$y(0^+) = 0. \tag{2}$$

Here  $y = (y_1, \dots, y_n)^T$  is the vector of unknown functions;  $\alpha(y) = (\alpha_1(y_1), \dots, \alpha_n(y_n))^T$  is a nonlinearity vector with entries  $\alpha_i$ ,  $i = 1, \dots, n$ ;  $A(x)$  is  $n \times n$  matrix with elements  $a_{ij}(x)$ ,  $i, j = 1 \dots, n$ ;  $\omega(x) = (\omega_1(x), \dots, \omega_n(x))^T$  and  $g(x) =$

$\text{diag}(g_1(x), \dots, g_n(x))$  is a diagonal matrix with diagonal entries indicated. The symbol  $I_s$  indicate an interval of the form  $(0, s]$  with a fixed  $s > 0$ . The system (1) is considered under the following main assumptions:

- (C<sub>1</sub>)  $g_i \in C(I_{x_0}, \mathbb{R}^+)$ ,  $i = 1, \dots, n$  with  $\mathbb{R}^+ = (0, \infty)$ ;
- (C<sub>2</sub>)  $\alpha \in C^1(I_{y_0}, \mathbb{R}^n)$ ,  $\alpha(y) \gg 0$  on  $I_{y_0}$ ,  $\alpha'(y) \gg 0$  on  $I_{y_0}$  and  $\alpha(0^+) = 0$ ;
- (C<sub>3</sub>)  $\omega \in C^1(I_{x_0}, \mathbb{R}^n)$ ;
- (C<sub>4</sub>)  $a_{ij} \in C^1(I_{x_0}, \mathbb{R})$ ,  $a_{ii}(x) \neq 0$ ,  $i, j = 1, \dots, n$  and  $\det A(x) \neq 0$  on  $I_{x_0}$ ;
- (C<sub>5</sub>)  $\alpha_i(y) \leq M\alpha'_i(y)$ ,  $i = 1, \dots, n$  on  $I_{y_0}$  with a constant  $M \in \mathbb{R}^+$ ;
- (C<sub>6</sub>)  $\Omega(x) \equiv A^{-1}(x)\omega(x) \gg 0$ ,  $\Omega'(x) \gg 0$  on  $I_{x_0}$  and  $\Omega(0^+) = 0$ .

The problem (1), (2) is a singular problem if assumptions (C<sub>1</sub>)–(C<sub>6</sub>) hold and if, in additional,  $g_i(0^+) = 0$  for at least one  $i \in \{1, \dots, n\}$ . The latter condition is implicitly contained in the assumptions of Theorem 2.

**Definition 1.** A function  $y = y(x) \in C^1(I_{x^*}, \mathbb{R}^n)$  with  $0 < x^* \leq x_0$  is said to be a *solution* of the problem (1), (2) on interval  $I_{x^*}$  if  $y$  satisfies (1) on  $I_{x^*}$  and  $y(0^+) = 0$ .

**Theorem 2.** *Suppose that conditions (C<sub>1</sub>) – (C<sub>6</sub>) are satisfied. Let A) for  $i = 1, \dots, p \leq n$ :*

$$\omega_i(x) < 0, \omega'_i(x) < 0, x \in I_{x_0}, \quad (3)$$

$$a_{ij}(x) \geq 0, j \neq i, j = 1, \dots, n \text{ and } a'_{ij}(x) \geq 0, j = 1, \dots, n, x \in I_{x_0}, \quad (4)$$

and

$$\omega_i(\delta x) > \omega_i(x) + \delta M g_i(x) \frac{\Omega'_i(\delta x)}{\Omega_i(\delta x)}, x \in I_{x_0}$$

for a constant  $\delta \in (0, 1)$ ;

B) for  $i = p + 1, \dots, n$ :

$$\omega_i(x) > 0, \omega'_i(x) > 0, x \in I_{x_0}, \quad (5)$$

$$a_{ij}(x) \leq 0, j \neq i, j = 1, \dots, n \text{ and } a'_{ij}(x) \leq 0, j = 1, \dots, n, x \in I_{x_0}, \quad (6)$$

and

$$\omega_i(Kx) > \omega_i(x) + KM g_i(x) \frac{\Omega'_i(Kx)}{\Omega_i(Kx)}, x \in I_{x_0}$$

for a constant  $K > 1$ . Then there exists  $(n - p)$ -parametric family of solutions of the problem (1), (2), having positive coordinates, on an interval  $I_{x^*} \subseteq I_{x^{**}}$  with  $x^{**} \leq \min\{x_0 K^{-1}, y_0\}$ .

**Consequence.** If Theorem 2 holds then there exist  $(n - p)$ -parametric family of solutions  $y = y^*(x)$  of the problem (1), (2) each of which satisfies on interval  $I_{x^*}$  the inequalities

$$\varphi(\delta x) \ll y^*(x) \ll \varphi(Kx).$$

Consider the linear system

$$g(x)y' = A(x)y - \omega(x). \quad (7)$$

**Theorem 3 (Linear case).** Suppose that conditions  $(C_1), (C_3), (C_4), (C_6), (3) - (6)$  are satisfied. Let, moreover,

$$\omega_i(\delta x) > \omega_i(x) + \delta g_i(x)\Omega'_i(\delta x), \quad x \in I_{x_0}, \quad i = 1, \dots, p \leq n$$

for a constant  $\delta \in (0, 1)$  and

$$\omega_i(Kx) > \omega_i(x) + Kg_i(x)\Omega'_i(Kx), \quad x \in I_{x_0}, \quad i = p + 1, \dots, n$$

for a constant  $K > 1$ . Then there exists  $(n - p)$ -parametric family of solutions  $y = y^*(x)$  of the problem (7), (2), having positive coordinates on an interval  $I_{x^*} \subset I_{x_0}$ , each of which satisfies here the inequalities

$$\Omega(\delta x) \ll y^*(x) \ll \Omega(Kx).$$

*Example 4.* Let us consider a linear singular problem of the type (7), (2):

$$\begin{aligned} x^2 y'_1 &= -5y_1 + y_2 + y_3 + x + x^2, \\ x^2 y'_2 &= y_1 - 5y_2 + y_3 + x + x^2, \\ x^2 y'_3 &= -2y_1 - 3y_2 + 2y_3 - x + 3x^2, \\ y_1(0^+) &= y_2(0^+) = y_3(0^+) = 0. \end{aligned}$$

This problem has (by Theorem 3) one-parametric family of positive solutions. Really, the general solution of system considered is expressed by means of relations

$$\begin{aligned} y_1 &= x + 11C_1 \exp(6/x) + C_2 \exp(3/x) + C_3 \exp(-1/x), \\ y_2 &= x - 10C_1 \exp(6/x) + C_2 \exp(3/x) + C_3 \exp(-1/x), \\ y_3 &= 3x - C_1 \exp(6/x) + C_2 \exp(3/x) + 5C_3 \exp(-1/x) \end{aligned}$$

with arbitrary constants  $C_1, C_2$  and  $C_3$ . By Theorem 2 there exist one-parametric family of positive solutions of nonlinear problem

$$\begin{aligned} x^3 y'_1 &= -5y_1^2 + y_2^5 + y_3^3 + x + x^2, \\ x^4 y'_2 &= y_1^2 - 5y_2^5 + y_3^3 + x + x^2, \\ x^5 y'_3 &= -2y_1^2 - 3y_2^5 + 2y_3^3 - x + 3x^2, \\ y_1(0^+) &= y_2(0^+) = y_3(0^+) = 0. \end{aligned}$$

### Acknowledgment

This work was supported by the grants 201/99/0295 of Czech Grant Agency, 1/5254/01 of Slovak Grant Agency; Slovak-Czech project 022(25)/2000 and by the plan of investigations MSM 262200013 of the Czech Republic.

