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Solutions of a singular Cauchy problem for a nonlinear system of differential equations

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Abstract. The solvability of the singular Cauchy problem for the system of nonlinear differential equations

$$\begin{aligned}g(x)y' &= A(x)\alpha(y) - \omega(x), \\ y(0^+) &= 0\end{aligned}$$

is investigated.

MSC 2000. 34C10, 34C15, 34B15

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Let us consider the system of nonlinear differential equations

$$g(x)y' = A(x)\alpha(y) - \omega(x) \tag{1}$$

and initial Cauchy problem

$$y(0^+) = 0. \tag{2}$$

Here $y = (y_1, \dots, y_n)^T$ is the vector of unknown functions; $\alpha(y) = (\alpha_1(y_1), \dots, \alpha_n(y_n))^T$ is a nonlinearity vector with entries α_i , $i = 1, \dots, n$; $A(x)$ is $n \times n$ matrix with elements $a_{ij}(x)$, $i, j = 1 \dots, n$; $\omega(x) = (\omega_1(x), \dots, \omega_n(x))^T$ and $g(x) =$

$\text{diag}(g_1(x), \dots, g_n(x))$ is a diagonal matrix with diagonal entries indicated. The symbol I_s indicate an interval of the form $(0, s]$ with a fixed $s > 0$. The system (1) is considered under the following main assumptions:

- (C₁) $g_i \in C(I_{x_0}, \mathbb{R}^+)$, $i = 1, \dots, n$ with $\mathbb{R}^+ = (0, \infty)$;
- (C₂) $\alpha \in C^1(I_{y_0}, \mathbb{R}^n)$, $\alpha(y) \gg 0$ on I_{y_0} , $\alpha'(y) \gg 0$ on I_{y_0} and $\alpha(0^+) = 0$;
- (C₃) $\omega \in C^1(I_{x_0}, \mathbb{R}^n)$;
- (C₄) $a_{ij} \in C^1(I_{x_0}, \mathbb{R})$, $a_{ii}(x) \neq 0$, $i, j = 1, \dots, n$ and $\det A(x) \neq 0$ on I_{x_0} ;
- (C₅) $\alpha_i(y) \leq M\alpha'_i(y)$, $i = 1, \dots, n$ on I_{y_0} with a constant $M \in \mathbb{R}^+$;
- (C₆) $\Omega(x) \equiv A^{-1}(x)\omega(x) \gg 0$, $\Omega'(x) \gg 0$ on I_{x_0} and $\Omega(0^+) = 0$.

The problem (1), (2) is a singular problem if assumptions (C₁)–(C₆) hold and if, in additional, $g_i(0^+) = 0$ for at least one $i \in \{1, \dots, n\}$. The latter condition is implicitly contained in the assumptions of Theorem 2.

Definition 1. A function $y = y(x) \in C^1(I_{x^*}, \mathbb{R}^n)$ with $0 < x^* \leq x_0$ is said to be a *solution* of the problem (1), (2) on interval I_{x^*} if y satisfies (1) on I_{x^*} and $y(0^+) = 0$.

Theorem 2. *Suppose that conditions (C₁) – (C₆) are satisfied. Let A) for $i = 1, \dots, p \leq n$:*

$$\omega_i(x) < 0, \omega'_i(x) < 0, x \in I_{x_0}, \quad (3)$$

$$a_{ij}(x) \geq 0, j \neq i, j = 1, \dots, n \text{ and } a'_{ij}(x) \geq 0, j = 1, \dots, n, x \in I_{x_0}, \quad (4)$$

and

$$\omega_i(\delta x) > \omega_i(x) + \delta M g_i(x) \frac{\Omega'_i(\delta x)}{\Omega_i(\delta x)}, x \in I_{x_0}$$

for a constant $\delta \in (0, 1)$;

B) for $i = p + 1, \dots, n$:

$$\omega_i(x) > 0, \omega'_i(x) > 0, x \in I_{x_0}, \quad (5)$$

$$a_{ij}(x) \leq 0, j \neq i, j = 1, \dots, n \text{ and } a'_{ij}(x) \leq 0, j = 1, \dots, n, x \in I_{x_0}, \quad (6)$$

and

$$\omega_i(Kx) > \omega_i(x) + KM g_i(x) \frac{\Omega'_i(Kx)}{\Omega_i(Kx)}, x \in I_{x_0}$$

for a constant $K > 1$. Then there exists $(n - p)$ -parametric family of solutions of the problem (1), (2), having positive coordinates, on an interval $I_{x^*} \subseteq I_{x^{**}}$ with $x^{**} \leq \min\{x_0 K^{-1}, y_0\}$.

Consequence. If Theorem 2 holds then there exist $(n - p)$ -parametric family of solutions $y = y^*(x)$ of the problem (1), (2) each of which satisfies on interval I_{x^*} the inequalities

$$\varphi(\delta x) \ll y^*(x) \ll \varphi(Kx).$$

Consider the linear system

$$g(x)y' = A(x)y - \omega(x). \quad (7)$$

Theorem 3 (Linear case). Suppose that conditions $(C_1), (C_3), (C_4), (C_6), (3) - (6)$ are satisfied. Let, moreover,

$$\omega_i(\delta x) > \omega_i(x) + \delta g_i(x)\Omega'_i(\delta x), \quad x \in I_{x_0}, \quad i = 1, \dots, p \leq n$$

for a constant $\delta \in (0, 1)$ and

$$\omega_i(Kx) > \omega_i(x) + Kg_i(x)\Omega'_i(Kx), \quad x \in I_{x_0}, \quad i = p + 1, \dots, n$$

for a constant $K > 1$. Then there exists $(n - p)$ -parametric family of solutions $y = y^*(x)$ of the problem (7), (2), having positive coordinates on an interval $I_{x^*} \subset I_{x_0}$, each of which satisfies here the inequalities

$$\Omega(\delta x) \ll y^*(x) \ll \Omega(Kx).$$

Example 4. Let us consider a linear singular problem of the type (7), (2):

$$\begin{aligned} x^2 y'_1 &= -5y_1 + y_2 + y_3 + x + x^2, \\ x^2 y'_2 &= y_1 - 5y_2 + y_3 + x + x^2, \\ x^2 y'_3 &= -2y_1 - 3y_2 + 2y_3 - x + 3x^2, \\ y_1(0^+) &= y_2(0^+) = y_3(0^+) = 0. \end{aligned}$$

This problem has (by Theorem 3) one-parametric family of positive solutions. Really, the general solution of system considered is expressed by means of relations

$$\begin{aligned} y_1 &= x + 11C_1 \exp(6/x) + C_2 \exp(3/x) + C_3 \exp(-1/x), \\ y_2 &= x - 10C_1 \exp(6/x) + C_2 \exp(3/x) + C_3 \exp(-1/x), \\ y_3 &= 3x - C_1 \exp(6/x) + C_2 \exp(3/x) + 5C_3 \exp(-1/x) \end{aligned}$$

with arbitrary constants C_1, C_2 and C_3 . By Theorem 2 there exist one-parametric family of positive solutions of nonlinear problem

$$\begin{aligned} x^3 y'_1 &= -5y_1^2 + y_2^5 + y_3^3 + x + x^2, \\ x^4 y'_2 &= y_1^2 - 5y_2^5 + y_3^3 + x + x^2, \\ x^5 y'_3 &= -2y_1^2 - 3y_2^5 + 2y_3^3 - x + 3x^2, \\ y_1(0^+) &= y_2(0^+) = y_3(0^+) = 0. \end{aligned}$$

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