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In: Jarolím Bureš and Vladimír Souček (eds.): Proceedings of the Winter School "Geometry and Physics". Circolo Matematico di Palermo, Palermo, 1990. Rendiconti del Circolo Matematico di Palermo, Serie II, Supplemento No. 22. pp. [201]--203.

Persistent URL: <http://dml.cz/dmlcz/701472>

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DERIVATIONS ON THE NIJENHUIS-SCHOUTEN BRACKET ALGEBRA

Jiří Vanžura

This is an announcement of results. The proofs will appear elsewhere.

All structures appearing in this paper are of class C^∞ . Let M be a connected and paracompact orientable manifold, $\dim M = m$. As usual we denote by TM the tangent bundle of M , and by $\Lambda^i TM$ its i -th exterior power. We set

$$L_i = \Gamma \Lambda^{i+1} TM \quad \text{for } -1 \leq i \leq m-1,$$

where Γ denotes the functor of sections over M . In order to avoid technical complications we set

$$L_i = 0 \quad \text{for } i < -1 \text{ or } i > m-1.$$

Obviously for any $i \in \mathbf{Z}$ L_i is a real vector space. To complete our notation we set

$$L = \sum_{i=-\infty}^{\infty} L_i.$$

If $\alpha \in L_i$ we call α homogenous element and write $|\alpha| = i$. Let us notice that L_{-1} is the vector space of functions on M , and L_0 is the vector space of vector fields on M .

Using a result of Schouten [2], Nijenhuis [1] defined a bilinear mapping

$$[\ , \]: L \times L \rightarrow L$$

which is now called Nijenhuis-Schouten bracket. This bracket is characterized by the following properties (All elements are homogenous.):

- (a) $[L_i, L_j] \subset L_{i+j}$
- (b) $[\alpha, \beta] = -(-1)^{|\alpha| \cdot |\beta|} [\beta, \alpha]$
- (c) $(-1)^{|\gamma| \cdot |\alpha|} [\alpha, [\beta, \gamma]] + (-1)^{|\alpha| \cdot |\beta|} [\beta, [\gamma, \alpha]] + (-1)^{|\beta| \cdot |\gamma|} [\gamma, [\alpha, \beta]] = 0$
- (d) $[\alpha, f] = \iota_{df} \alpha$, where $f \in L_{-1}$ and ι denotes the inner product operator.
- (e) $[\alpha, \beta \wedge \gamma] = [\alpha, \beta] \wedge \gamma + (-1)^{|\alpha| \cdot |\beta|} \beta \wedge [\alpha, \gamma]$

The properties (b) and (c) show that L is a graded Lie algebra. Further using (b)-(e) we find easily that for $X \in L_0$, $\alpha \in L$ there is $[X, \alpha] = \mathcal{L}_X \alpha$, where \mathcal{L}_X denotes the Lie derivative. Consequently for $X, Y \in L_0$ $[X, Y]$ is the ordinary Lie bracket.

Let us recall that a derivation of degree $k \in \mathbf{Z}$ on L is a linear mapping $D: L \rightarrow L$ such that

- (1) $DL_i \subset L_{i+k}$
- (2) $D[\alpha, \beta] = [D\alpha, \beta] + (-1)^{k \cdot |\alpha|} [\alpha, D\beta]$.

A derivation D is called local if it has the following property: If $\alpha \in L_i$, $U \subset M$ is an open subset and $\alpha|U = 0$, then $D\alpha|U = 0$. We shall denote by Der_k the vector space of all local derivations of degree k on L . The goal of this paper is to describe Der_k for $k \in \mathbf{Z}$.

PROPOSITION 1. $\text{Der}_k = 0$ for $k < -1$.

For the sake of formulation of the next propositions we shall recall some facts about the forms of higher order. By a k -form on M we shall mean a local skew-symmetric k -linear (over the reals) mapping

$$\omega: \underbrace{L_0 \times \dots \times L_0}_{k\text{-times}} \rightarrow L_{-1}.$$

(ω is called local if it has the following property: If $X_1, \dots, X_k \in L_0$, $U \subset M$ is an open subset, and $X_1|U = 0$, then $\omega(X_1, \dots, X_k)|U = 0$.) The usual formula

$$\begin{aligned} d\omega(X_1, \dots, X_{k+1}) &= \sum_{i=1}^{k+1} (-1)^{i+1} X_i \omega(X_1, \dots, \hat{X}_i, \dots, X_{k+1}) \\ &\quad + \sum_{i < j} (-1)^{i+j} \omega([X_i, X_j], X_1, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_{k+1}) \end{aligned}$$

defines the exterior derivative $d\omega$ of ω , which is a $(k+1)$ -form (i.e. it is again local). Ordinary k -forms on M we shall call k -forms of order 0.

We shall fix a volume element μ on M (i.e. an everywhere nonzero m -form of order 0). For any $X \in L_0$ there exists a unique function, which we shall denote by $\text{div} X$ such that

$$\mathcal{L}_X \mu = \text{div} X \cdot \mu,$$

where \mathcal{L}_X denotes the Lie derivative with respect to X . The linear mapping $\text{div}: X \mapsto \text{div} X$ is a closed 1-form. (We remark that this is not a 1-form of order 0. In fact the order of div is 1.)

Obviously any derivation $D \in \text{Der}_{-1}$ determines a 1-form ω_D on M defined by the formula

$$\omega_D(X) = DX.$$

PROPOSITION 2. *If $\dim M = 1$, then the mapping $D \mapsto \omega_D$ defines an isomorphism between Der_{-1} and the vector space of closed 1-forms on M .*

PROPOSITION 3. *If $\dim M > 1$, then the mapping $D \mapsto \omega_D$ defines an isomorphism between Der_{-1} and the vector space consisting of all 1-forms*

$$\omega = c \cdot \text{div} + \omega'$$

on M , where $c \in \mathbf{R}$, and ω' is a closed 1-form of order 0.

PROPOSITION 4. *Let $D \in Der_0$. Then there exist unique $X_D \in L_0$ and $c \in \mathbf{R}$ such that*

$$D\alpha = \mathcal{L}_{X_D}\alpha + ic\alpha, \quad \alpha \in L_i, \quad -1 \leq i \leq m-1,$$

where \mathcal{L}_{X_D} denotes the Lie derivative with respect to X_D .

Conversely for any $X \in L_0$ and $c \in \mathbf{R}$ the formula

$$D\alpha = \mathcal{L}_X\alpha + ic\alpha, \quad \alpha \in L_i, \quad -1 \leq i \leq m-1$$

defines a derivation of degree 0 on L .

PROPOSITION 5. *Every derivation $D \in Der_k, k > 0$ is inner.*

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