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SPINOR FIELDS ON RIEMANNIAN MANIFOLDS

OLGA POKORNÁ¹

1. Introduction

Let (M, g) be a connected Riemannian manifold of dimension n with a spin structure (\tilde{P}, η) , let S be a spinor bundle on M and $\Gamma(S)$ the space of all smooth sections of S .

A spin field $\psi \in \Gamma(S)$ is called Killing spinor with a Killing number $\lambda \in \mathbb{C}$ if the differential equation

$$\nabla_X^S \psi = \lambda X.\psi \quad (1)$$

is satisfied for all vector fields X on M .

A spinor field $\psi \in \Gamma(S)$ is called a twistor spinor if for all vector fields X on M

$$\mathcal{D}\psi = \nabla_X^S \psi + \frac{1}{n} X.D\psi = 0 \quad (2)$$

and such a field ψ is called E -spinor (or so-called Lichnerowicz spinor) if for all vectors fields X on the manifold M

$$E\psi = \nabla_X^S(D\psi) + \frac{R}{4(n-1)} X.\psi = 0, \quad (3)$$

where D denotes the Dirac operator.

The equation (3) was introduced by A. Lichnerowicz in 1988 in connection with a study of spinor fields. At the same time he proved the following important theorems (see [4]).

Theorem 1.1. (Lichnerowicz)

If (M, g) is a connected Riemannian spin manifold of dimension $n \geq 3$ with a nontrivial E -spinor, then the scalar curvature R is constant on M .

Theorem 1.2 (Lichnerowicz)

If (M, g) is a compact Riemannian spin manifold with a nontrivial E -spinor, then

$$\text{Ker}(\mathcal{D}) = \text{Ker}(E) = \mathbf{K},$$

where we denoted by \mathbf{K} the space of all Killing spinors on M (see [1], e.g.).

¹This paper is in final form and no version of it will be submitted for publication elsewhere.

I have succeeded in finding E -spinors on $S^2 \times R^1$ and $H^2 \times R^1$. It is a natural way to construct E -spinors which are not Killing ones. Noncompact Riemannian manifolds $S^2 \times R^1$ and $H^2 \times R^1$ are not the Einstein spaces and that is why Killing spinors do not exist there.

Proposition 1.3

Every solution of the equation (3) on $H^2 \times R^1$ is of the form

$$\begin{aligned} \psi(x, t) = & \{A_0 \cos(\frac{1}{2}t) + A_1 \sin(\frac{1}{2}t)\}\psi^+(x) + \{A_0 \sin(\frac{1}{2}t) - A_1 \cos(\frac{1}{2}t)\}\psi^-(x) + \\ & + \{B_0 \cos(\frac{1}{2}t) + B_1 \sin(\frac{1}{2}t)\}\varphi^+(x) + \{-B_0 \sin(\frac{1}{2}t) + B_1 \cos(\frac{1}{2}t)\}\varphi^-(x), \end{aligned}$$

where A_0, A_1, B_0, B_1 are arbitrary constants and $\psi = \psi^+ + \psi^-$ resp. $\varphi = \varphi^+ + \varphi^-$ are Killing spinors on H^2 corresponding to $\lambda = \frac{i}{2}$ (resp. $\lambda = -\frac{i}{2}$). Proof.(see [5])

Proposition 1.4

Every solution of the equation (3) on $S^2 \times R^1$ is of the form

$$\begin{aligned} \psi(x, t) = & \{A_0 \cosh(\frac{1}{2}t) + A_1 \sinh(\frac{1}{2}t)\}\psi^+(x) - i\{A_0 \sinh(\frac{1}{2}t) + A_1 \cosh(\frac{1}{2}t)\}\psi^-(x) + \\ & + \{B_0 \cosh(\frac{1}{2}t) + B_1 \sinh(\frac{1}{2}t)\}\varphi^+(x) + i\{B_0 \sinh(\frac{1}{2}t) + B_1 \cosh(\frac{1}{2}t)\}\varphi^-(x), \end{aligned}$$

where A_0, A_1, B_0, B_1 are arbitrary constants and $\psi = \psi^+ + \psi^-$ resp. $\varphi = \varphi^+ + \varphi^-$ are Killing spinors on S^2 corresponding to $\lambda = \frac{1}{2}$ (resp. $\lambda = \frac{i}{2}$). Proof.(see [5])

2. The other relations between $Ker(E)$ and $Ker(D)$.

Theorem 2.1

Let (M, g) be a connected Riemannian manifold of dimension n with a spin structure. If $\psi \in Ker(E) \neq \{0\}$, then

$$R^S(X, Y).D\psi + \frac{R}{4(n-1)}(Y.\nabla_X^S\psi - X.\nabla_Y^S\psi) = 0, \quad (4)$$

where $R^S(X, Y)$ is the curvature tensor of the connection ∇^S on S and X, Y are vector fields on M .

Proof: If $\psi \in Ker(E) \neq \{0\}$, then the Theorem 1.1 implies that the scalar curvature R is constant on M (see [4]).

By differentiation of the equation (3) with respect to Y , we get

$$\nabla_Y^S \nabla_X^S (D\psi) + \frac{R}{4(n-1)}(\nabla_Y^S X).\psi + \frac{R}{4(n-1)}X.\nabla_Y^S \psi = 0. \quad (5)$$

Exchanging X and Y , we get

$$\nabla_X^S \nabla_Y^S (D\psi) + \frac{R}{4(n-1)} (\nabla_X^S Y) \cdot \psi + \frac{R}{4(n-1)} Y \cdot \nabla_X^S \psi = 0. \tag{6}$$

The equation (3) is also valid for vector fields $[X, Y]$ on M :

$$\nabla_{[X, Y]}^S (D\psi) + \frac{R}{4(n-1)} [X, Y] \cdot \psi = 0. \tag{7}$$

By subtracting the equations (5) and (7) from (6), we get

$$\begin{aligned} &\nabla_X^S \nabla_Y^S (D\psi) - \nabla_Y^S \nabla_X^S (D\psi) - \nabla_{[X, Y]}^S (D\psi) + \\ &+ \frac{R}{4(n-1)} (\nabla_X^S Y - \nabla_Y^S X - [X, Y]) \psi + \\ &+ \frac{R}{4(n-1)} (Y \cdot \nabla_X^S \psi - X \cdot \nabla_Y^S \psi) = 0. \quad \blacksquare \end{aligned}$$

For a given $\psi \in \Gamma(S)$, let us define functions

$$C\psi = \text{Re}(D\psi, \psi)$$

$$Q\psi = |\psi|^2 |D\psi|^2 - C^2\psi - \sum_{i=1}^n (\text{Re}(D\psi, e_i\psi))^2$$

Then we have

Theorem 2.2

Let (M, g) be a connected Riemannian spin manifold of dimension $n \geq 3$ such that $\text{Ker}(E) \neq 0$ and the scalar curvature is nonzero. Then the quadratic forms C and Q are constant on $\text{Ker}(E)$.

Proof: Theorem 1.1 implies that the scalar curvature R is constant. Moreover R is nonzero. Then Corollary of Theorem 1 (see[2]) implies that,

$$\dim_C \text{Ker}(E) = \dim_C \text{Ker}(D) \leq 2^{\lfloor n/2 \rfloor + 1}.$$

On this vector space, there exist quadratic forms C and Q .

For all $X \in T_x M$, $x \in M$ we get

$$X(C\psi) = \text{Re}((\nabla_X^S D\psi, \psi) + (D\psi, \nabla_X^S \psi)). \tag{8}$$

Proposition 2 (see [2]) implies, that

$$\nabla_X^S \psi = \frac{2(n-1)}{R(n-2)} \left(\frac{R}{2(n-1)} X - \text{Ric}(X) \right) \cdot D\psi.$$

We obtain

$$\begin{aligned} X(C\psi) &= \text{Re} \left(-\frac{R}{4(n-1)} X \cdot \psi, \psi \right) + \text{Re} \left(D\psi, \frac{2(n-1)}{R(n-2)} \left(\frac{R}{2(n-1)} X - \text{Ric}(X) \right) \cdot D\psi \right) = \\ &= -\frac{R}{4(n-1)} \text{Re}(X \cdot \psi, \psi) + \frac{2(n-1)}{R(n-2)} \cdot \text{Re} \left(D\psi, \left(\frac{R}{2(n-1)} X - \text{Ric}(X) \right) \cdot D\psi \right). \end{aligned}$$

Clifford multiplication has the following property with respect to the Hermetian scalar product (,)

$$\text{Re}(X\psi, \psi) = 0 \quad \text{for all } X \in T_x M, x \in M$$

hence $C\psi = \text{konst.}$

Moreover, if $\psi \in \text{Ker}(E)$, then Theorem 1 (see [2]) implies that

$$\varphi = D\psi \in \text{Ker}(\mathcal{D})$$

hence $Q\varphi = \text{konst}$ (see [3]).

But

$$\begin{aligned} Q\varphi &= |\varphi|^2 |D\varphi|^2 - C^2 \varphi - \sum_{i=1}^n (\text{Re}(D\varphi, e_i \cdot \varphi))^2 = \\ &= |D\psi|^2 |D^2\psi|^2 - (\text{Re}(D^2\psi, D\psi))^2 - \sum_{i=1}^n (\text{Re}(D^2\psi, e_i \cdot D\psi))^2 = \\ &= \frac{n^2 R^2}{16(n-1)^2} (|D\psi|^2 |\psi|^2 - (\text{Re}(\psi, D\psi))^2) - \sum_{i=1}^n (\text{Re}(\psi, e_i \cdot D\psi))^2 = \\ &= \left(\frac{nR}{4(n-1)} \right)^2 Q\psi. \end{aligned}$$

Moreover we have

$$\text{Re}(\psi, e_i \cdot D\psi) = -\text{Re}(D\psi, e_i \cdot \psi).$$

Hence $Q\psi$ is constant. ■

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