Richard Delanghe Decomposable systems of differential operators and generalized inverses

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DECOMPOSABLE SYSTEMS OF DIFFERENTIAL OPERATORS AND GENERALIZED INVERSES

by R. Delanghe

0. Introduction

In his paper [4], M.R. Hestenes showed that each closed linear operator $L:H \rightarrow H'$, H and H' being Hilbert spaces, admits a generalized inverse $L^{-1}:H' \rightarrow H$ and he developed a "spectral theory" for such operators. As an example he considered the gradient operator which satisfies the relation $-\Delta = (-\operatorname{div})$ grad. In [3] H.G. Garnir built up a framework for studying abstract Dirichlet-Neumann problems for decomposable systems of differential operators with constant coefficients i.e. operators $L(\partial/\partial x)$ of the form $L(\partial/\partial x) =$ $L^+(-\partial/\partial x)L(\partial/\partial x)$ where $L(\partial/\partial x)$ is a matrix differential operator. In this paper we combine the results of the cited authors in the case where the (D-N)-problem for the operators under consideration is well-posed. In particular, a spectral decomposition is obtained for the operator L which factorizes L and for its generalized inverse L^{-1} .

1. Generalized inverses

Let H,H' be Hilbert spaces and let $L:H \rightarrow H'$ be a closed densely defined linear operator with domain dom(L), kernel $\eta(L)$ and range R(L). Then the generalized inverse L^{-1} of L is defined as follows. Call $C(L) = dom(L) \cap \eta(L)$; then $dom(L) = C(L) \oplus \eta(L)$ whence for each $v \in domL$, $v = \hat{v} + v_0$ with $\hat{v} \in C(L)$, $v_0 \in \eta(L)$. As $L \mid C(L)$ is injective and $R(L \mid C(L)) = R(L)$, the inverse \tilde{L} of L with $dom(\tilde{L}) = R(L)$ and $R(\tilde{L}) = C(L)$, may be extended to the linear operator $L^{-1}: H' \rightarrow H$ defined by

(i) dom $(L^{-1}) = R(L) \oplus R(L)^{\perp}$

(ii) If $w \in dom(L^{-1})$ with $w = \hat{w} + w_0$, $\hat{w} \in R(L)$, $w_0 \in R(L)^{\perp}$, then $L^{-1}w = \hat{w} = \hat{v}$ if and only if $(L | C(L)) \hat{v} = \hat{w}$.

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From (i) and (ii) it follows that $R(L^{-1})=C(L)$. L^{-1} is called the <u>generalized inverse</u> of L (also called <u>pseudo-inverse</u> or <u>generalized reciprocal</u> of L).

Among other properties we mention (see [4], [5] and [6])
(i) L⁻¹:H'→H is a closed densely defined linear operator

- (ii) $(L^{-1})^{-1} = L$
- (iii) $(L^{-1})^* = (L^*)^{-1}$

2. Decomposable differential operators

In this section we first recall the abstract setting for studying the Dirichlet-Neumann problem posed for a decomposable system of differential operators $L(\partial/\partial x = L^+(-\partial/\partial x)L(\partial/\partial x)$ as it was worked out in [3]. As an example we give the case of the negative Laplacian which is decomposed by its "square root" the Dirac operator.

In the second subsection we derive spectral decompositions of the operators L and L^{-1} in the case where the (D-N)-problem is well-posed for L.

2.1. The (D-N)-problem for decomposable operators Let Ω be an open subset of \mathbb{R}^m , let $N \in \mathbb{N}$ (N>1) and let $L_{2,N}(\Omega)$ be the Hilbert space of $\mathbb{C}^{N\times 1}$ -valued L_2 -functions in Ω , i.e. $\vec{u} \in L_{2,N}(\Omega)$ if

 $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_N \end{bmatrix} \quad \text{with } u_j \in L_2(\Omega), j = 1, \dots, N.$

The inner product and norm on $L_{2,N}(\Omega)$ are defined by

$$\langle \vec{u}, \vec{v} \rangle_{N} = \int_{\Omega} \vec{u} x \vec{v} dx = \sum_{j=1}^{N} \int_{\Omega} u_{j}(x) \vec{v}_{j}(x) dx,$$
$$\| \vec{u} \|_{N}^{2} = \sum_{j=1}^{N} \int_{\Omega} |u_{j}(x)|^{2} dx.$$

Furthermore, let $L=L(\partial/\partial x)$ be an MxN matrix such that its elements L_{ij} are linear partial differential operators with constant coefficients and put

 $L=L(3/3x)=L^{+}(-3/3x)L(3/3x)$

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where $L^{+}=L^{+}(-\partial/\partial x)$ is obtained by taking the adjoint of $L(\partial/\partial x)$ and replacing $\partial/\partial x_i$ by $-\partial/\partial x_i$, $j=1,\ldots,m$.

In general, if $L_{1,N}^{1oc}(\Omega)$ and $\mathcal{P}(\Omega; c^{N\times 1})$ denote respectively the space of $c^{N\times 1}$ -valued locally integrable functions in Ω and the space of $c^{N\times 1}$ -valued testfunctions in Ω , then the action of an MxN matrix differential operator $P(\partial/\partial x)$ having constant coefficients on $\vec{u} \in L_{1,N}^{1oc}(\Omega)$ is defined to be element $P\vec{u} \in L_{1,M}^{1oc}(\Omega)$, provided that it exists, such that for all $\vec{\varphi} \in \mathcal{P}(\Omega; c^{M\times 1})$

 $\int_{\Omega} P(\partial/\partial x) \vec{u} x \vec{\varphi} dx = \int_{\Omega} \vec{u} x P^{+}(-\partial \partial x) \vec{\varphi} dx.$

Returning to the decomposable differential operator $L=L^+L$, put

 $Z_1, L^{=\{\vec{u} \in L_2, N(\Omega) : L\vec{u} \in L_2, M(\Omega)\}}$

and equip this space with the inner product

 $\langle \vec{u}, \vec{v} \rangle = \langle \vec{u}, \vec{v} \rangle_{N} + \langle L\vec{u}, L\vec{v} \rangle_{M}$

Then $Z_{1,L}$ is a Hilbert space containing $\mathcal{D}(\alpha; c^{N\times 1})$. Furthermore let $\dot{\alpha}$ be the boundary of α and let $\dot{\alpha}_D$ and $\dot{\alpha}_N$ be two subsets of $\dot{\alpha}$ such that $\dot{\alpha} = \dot{\alpha}_D \cup \dot{\alpha}_N$ and $\dot{\alpha}_D \cap \dot{\alpha}_N = \phi$. Then $V_{\dot{\alpha}_D}$

stands for the closure in $Z_{1,L}$ of the set of functions $\vec{u} \in Z_{1,L}$ such that \vec{u} is identically zero in a neighbourhood of $\hat{\Omega}_D$, this neighbourhood defending upon \vec{u} .

Finally define the subspace N of V as follows : $\vec{u} \in N$ if and only if (N_1) $\vec{u} \in L_{2,N}(\Omega)$, $L\vec{u} \in L_{2,N}(\Omega)$

(N₂) (Dirichlet condition on $\dot{\Omega}_{\rm D}$) $\vec{u} \in V$

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 (N_3) (Neumann condition on $\dot{\Omega}_N$)

Taking N=dom(L), then clearly $\mathcal{P}(\Omega; c^{N\times 1})$ is contained in N. Moreover L is a non-negative self-adjoint operator and its domain N is dense in V for the $Z_{1,L}$ -norm (see [3]). $\hat{\Omega}_{D}$ Taking V =dom(L) we have R. DELANGHE

2.1.1. Theorem (i) L is a closed densely defined linear operator (ii) $L=L^*L$ (iii) L^* is a closed extension of L^+ . <u>Proof</u>. (i) As $\mathcal{P}(\Omega; c^{N \times 1}) \subset V$, *L* is densely defined. Now let $(\vec{u}_k)_{k \in N}$ be a sequence in V such that $\vec{u}_k \rightarrow \vec{u}$ in $L_{2,N}(\Omega)$ and $L\vec{u}_k \rightarrow \vec{w}$ in $L_{2,M}(\Omega)$. Then $(\vec{u}_k)_{k \in \mathbb{N}}^{*D}$ is a Cauchy-sequence in $Z_{1,L}$ and as V is closed in $Z_{1,L}$, $\vec{u} \in V$ and $L\vec{u} = \vec{w}$, whence L is closed. (ii) Put $T=L^*L$. Then T is a self-adjoint linear operator in $L_{2,N}(\Omega)$ with $N \subset dom(T)$. Moreover T | N = L. Indeed, take $\vec{n} \in N$ and $\vec{\varphi} \in \mathcal{D}(\Omega; c^{N \times 1})$. Then by virtue of condition (N_3) $< L\vec{n}, \vec{\varphi} >_{N} = < L\vec{n}, L\vec{\varphi} >_{M}$ while from $\mathcal{D}(\Omega; c^{N \times 1}) \subset N \subset \operatorname{dom}(L^*L)$ it follows that $< T\vec{n}, \vec{\varphi} >_{N} = < L^{*}L\vec{n}, \vec{\varphi} >_{M} = < L\vec{n}, L\vec{\varphi} >$ whence, by the density of $\mathcal{D}(\Omega; c^{N \times 1})$ in L_N(Ω), Ln=Tn and so T|N=L. Consequently T is a self-adjoint extension of L so that, L being itself self-adjoint, T=L. (iii) Obvious. For examples of decomposable differential operators occurring in mathematical physics, we refer to [3]. Note that since $L=L^*L$ is a non negative self-adjoint operator, L coincides with its Friedrichs extension. Moreover V is the energy space of L and hence its square root \sqrt{L} has V as its $\Omega_{\rm D}$ domain (see [7] Satz 20.5). 2.1.2. The generalized Cauchy-Riemann operator D As a further example of such operators L and L we consider the case of the negative Laplacian and the generalized Cauchy-Riemann operator (also called Dirac operator) acting on $L_2(\Omega; A_m(C))$. Let A be the Clifford algebra constructed over an orthonormal basis $\{e_1, \ldots, e_m\}$ of R^m with multiplication rules

 $e_i e_j + e_j e_i = -2\delta_{ij}$, i, j=1,...,m.

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Consider its basis elements $e_A = e_{h_1} e_{h_2} \dots e_{h_r}$ where $A = \{h_1, \dots, h_r\} \in \{1, \dots, n\}$ is ordered in such a way that $1 \le h_1 < h_2 < \dots < h_r \le m$, $e_{\phi} = e_{\phi}$ being the identity of A. Furthermore put for each $A \in PN$,

$$\overline{e}_{A}^{=(-1)^{n(A)(n(A)+1)/2}}e_{A}^{+},$$

n(A) being the cardinality of A, call

 $A_m(C) = A \otimes_R C$.

and define for each $\lambda = \sum_{A} \lambda_{A} e_{A} \in A_{m}(C)$,

$$\overline{\lambda} = \sum_{A} \overline{\lambda}_{A} \overline{e}_{A}$$
.

Order the basis elements $\boldsymbol{e}_{\boldsymbol{A}}$ in a certain way, say $B = \{e_{(K)} : K = 1, 2, \dots, 2^{m}\}$ whereby $e_{(1)}$ is taken to be e_0 , associate to each $\lambda \in A_m(C)$ the linear operator $\sqcap_{\lambda} : A_m(C) \to A_m(C)$ given by $\sqcap_{\lambda}(u) = \lambda u$ for all $u \in A_m(C)$ and call $\theta(\lambda)$ the matrix representation of \square_{λ} with respect to B, i.e. $\theta(\lambda)_{K,L} = [\lambda e_{(K)}]_{(L)}, K, L = 1, \dots, 2^{m}$. Then a faithful matrix representation is obtained of $A_m(C)$ into $c^{2^m x 2^m}$ and it may be easily checked that for each $\lambda \in A_m(C)$ $\theta(\overline{\lambda}) = (\theta(\lambda))^+$ (see also [1]). Moreover if for each $u \in A_m(C)$, we put $\vec{u}=[u]_{R}$, the coordinate vector of u with respect to B, then $\Box_{\lambda}(u) = \lambda u = \theta(\lambda) u.$ Now consider the generalized Cauchy-Riemann operator $D = \sum_{j=1}^{m} e_j \frac{\partial}{\partial x_j}$. Then $D^2 = DD = -\Delta_m e_0$, Δ_m being the Laplacian in \mathbb{R}^m . Call $L(\partial/\partial x) = \theta(D)$ and $L(\partial/\partial x) = \theta(-\Delta_m e_0)$. Then we have that $L(\partial/\partial x) = L^{+}(-\partial/\partial x)L(\partial/\partial x)$. Indeed, $\theta(\overline{D}) = \theta(-D)$ and $\theta(\overline{D}) = \theta(D)^{T}$ so that $\theta(D) = \theta(-D)^T$. But, as $\theta(D)$ is a homogeneous first order differential operator with real coefficients , $L^+(-\partial/\partial x)=\theta(-D)^T$. whence $L(\partial/\partial x) = L^{+}(-\partial/\partial x)$ and $L(\partial/\partial x) = \theta(-\Delta_m e_0) = \theta(D^2) = \theta(D)\theta(D) = L^+(-\partial/\partial x)L(\partial/\partial x).$. We may thus define for $u \in L_2(\Omega; A_m(C))$, $w = Du \in L_2(\Omega; A_m(C))$ as being the unique element in $L_2(\Omega; A_m(C))$, provided that it exists, such

that for all $\varphi \in \mathcal{D}(\Omega; A_m(C))$,

$$< L(D)\vec{u}, \vec{\varphi} > = <\vec{u}, L^{\dagger}(-D)\vec{\varphi} >$$
$$= <\vec{u}, L(D)\vec{\varphi} >.$$

Call Z ={ $u\in L_2(\Omega; A_m(C): Du\in L_2(\Omega; A_m(C))$ and equip this space with the inner product

$$[u,v] = \langle \vec{u}, \vec{v} \rangle + \langle L\vec{u}, L\vec{v} \rangle$$

Then $Z_{1,L}$ is a Hilbert space and as $L^+(-\partial/\partial x) = L(\partial/\partial x)$, $Z_{1,L} = Z_{1,L}^+$.

Now consider the pure Dirichlet problem for the operator $-\Delta_m e_0$ acting on $L_2(\Omega; A_m(\mathcal{C}))$, i.e. take $\dot{\Omega}_D = \dot{\Omega}$. Then, as the set of functions $u \in V$, having bounded support is dense in V, $u \in V$, Ω , $\dot{\Omega}$, $\dot{\Omega}$ if and only if $u \in Z_1$, L and

 $\langle Du, v \rangle = \langle u, Dv \rangle$ for all $v \in \mathbb{Z}_{1, 1} = \mathbb{Z}_{1, 1} +$

(see [3], pp.70-71).

Hence D is symmetric in V $_{\Omega}$ and as D is closed (see also Theorem 2.11(i)), we have

<u>Theorem</u>. D is a self-adjoint linear operator in $L_2(\Omega; A_m(C))$. Corollary. D⁻¹ is self-adjoint.

2.2. Well-posed (D-N)-problems for decomposable operators In this subsection we again consider differential operators of the form $L(\partial/\partial x) = L^+(-\partial/\partial x)L(\partial/\partial x)$ and the associated spaces V and N. Ω_D

The (D-N)-problem for L in N is said to be <u>well posed</u> if for each $\vec{f} \in L_{2,N}(\Omega)$ there exists a unique $\vec{n} \in N$ such that

> (i) $L\vec{n} = \vec{f}$ (ii) $\vec{f}_k \rightarrow \vec{f}$ in $L_{2,N}(\Omega)$ implies that $\vec{n}_k \rightarrow \vec{n}$ in $L_{2,N}(\Omega)$.

As has been shown in [3], a necessary and sufficient condition for the (D-N)-problem to be well-posed in N for L is that there exists C>0 such that for all $\vec{u} \in V_{\perp}$,

$$\|\vec{u}\|_{N}^{2} < \frac{1}{C} \|\vec{L}\vec{u}\|_{M}^{2}$$
(2.2)

Assume hence forth that the (D-N)-problem is well-posed for L in N.

DECOMPOSABLE SYSTEMS OF DIFFERENTIAL OPERATORS AND GENERALIZED 89 INVERSES Condition (2.2) implies that $n(L) = \{0\}$ whence C(L) = dom(L) = V. Ω_D

Moreover it means that *L* is reciprocally bounded in V or Ω_{D}^{n} R(*L*) is closed in L_{2,M}(Ω) (see [4], Theorem 3.3) and so dom(L^{-1})=L_{2.M}(Ω).

Condition (2.2) together with the self-adjointness of L in N also implies the existence of a spectral measure M in C carried by $[C,+\infty[$ and of a bounded self-adjoint operator G(Z) in $L_{2,N}(\Omega)$ such that

$$L = \int_{0}^{+\infty} \lambda \, dM \text{ and } G(z) = \int_{0}^{+\infty} \frac{dM}{\lambda - z}$$

for all $z \in \rho(L)$, $\rho(L) \subset c$ being the resolvent set of L and G(z) being the Green's operator corresponding to L-z (see [3]). As $0 \in \rho(L)$, we thus have for the operator

$$G_0 = G(0) = \int_0^{+\infty} \frac{dM}{\lambda} \text{ that } LG_0 = 1_{L_2,N}(\Omega) \text{ and } G_0 L = 1_N \text{ whence clearly}$$

$$G_0 = L^{-1}.$$

Moreover, as both L and G_0 are positive-definite, their square roots are represented by

$$\sqrt{L} = \int_{0}^{+\infty} \sqrt{\lambda} dM \text{ and } \sqrt{G_0} = \int_{0}^{+\infty} \frac{1}{\sqrt{\lambda}} dM.$$
 (2.3)

We so obtain

2.2.1 <u>Theorem</u>. Suppose that the (D-N)-problem is well-posed for the operator $L(\partial/\partial x) = L^+(-\partial/\partial x)L(\partial/\partial x)$ in N. Then there exists a partial isometry R : $L_{2,N}(\Omega) \rightarrow L_{2,M}(\Omega)$ such that

(i)
$$G_0 = L^{-1}$$
 and $\sqrt{G_0} = (\sqrt{L})^{-1}$
(ii) $L_0 = R\sqrt{L}$, $L^{-1} = \sqrt{G_0}R^*$ and $L^* = \sqrt{LR}^*$
(iii) (Spectral decomposition of L and L^*
 $L = \int_0^{+\infty} \sqrt{\lambda} d(R^M)$, $L^* = \int_0^{+\infty} \sqrt{\lambda} d(MR^*)$ (2.4)

(iv) (Spectral decomposition of L^{-1}) :

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$$L^{-1} = \int_{0}^{+\infty} \frac{1}{\sqrt{\lambda}} d(MR^{*})$$
 (2.5)

Proof. (i) As we have already remarked, $G_0=L^{-1}$ and as L is a non-negative self-adjoint operator , $\sqrt{L^{-1}} = (\sqrt{L})^{-1}$ (see [4], Theorem 5.2) whence $\sqrt{G_0} = (\sqrt{L})^{-1}$. (ii) The polar decomposition of L yields that $L=R\sqrt{L^*L}$ or. taking account of Theorem 2.1.1.(ii), that $L=R\sqrt{L}$. Hereby $R:L_{2,N}(\Omega) \rightarrow L_{2,M}(\Omega)$ is a partial isometry with dom(R)= $\overline{R(L)} = L_{2,N}(\Omega)$, $im(R) = \overline{R(L)} = R(L)$ and satisfying $R^{-1} = R^*$ (see [8] Satz 7.20 and [4], Theorem 6.2). Call $D = \sqrt{G_0} R^* = (\sqrt{L})^{-1} R^{-1}$. Then $D = L^{-1}$. Indeed, R^{*} and R^{*-1}=R are bounded while $n(R^{**})=n(R)=n(L)=n(\sqrt{G_0})$. Hence, using the Corollary to [4] Theorem 3.5, the desired result is obtained. As $L=R\sqrt{L}$ with R bounded, we have that $L^*=(\sqrt{L})^*R^*$ $=\sqrt{LR^*}$ (see also [8] Satz 4.19). (iii) and (iv). As $\sqrt{\lambda}$ and $\frac{1}{\sqrt{\lambda}}$ are *M*-integrable and R,R^{*} are partial isometries, $\sqrt{\lambda}$ and $\frac{1}{\sqrt{\lambda}}$ are respectively RM- and MR*integrable so that, using (2.3) and the results from [2], p. 43, the relations (2.4) and (2.5) are obtained. 2.2.2. <u>Remark</u>. By means of (2.4) we have that for all $\vec{v} \in V$, $L\vec{\mathbf{v}} = \int_{0}^{+\infty} \sqrt{\lambda} d(RM\vec{\mathbf{v}}).$

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Rijksuniversiteit Gent Seminarie voor Algebra en Functionaalanalyse Galglaan 2 B-9000 Gent Belgium