

Frank Sommen

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## SPINGROUPS AND SPHERICAL MEANS II

F. Sommen (\*)

Abstract. In this paper we study generalized mean values of functions in  $R^m$  over spheres of any codimension, by making use of representations of  $\text{Spin}(m)$  on spaces of functions in the Clifford algebra over  $R^m$ . This leads to several versions, refinements and generalizations of the classical Euler-Poisson-Darboux equation. Furthermore for spheres of codimension 2 we interpret these equations in terms of complex Clifford analysis.

Introduction. The notion of spherical means of a function is known to be useful in partial differential equations as is shown by F. John (see [6]). Especially for operators, which may be expressed in terms of Laplacians (and powers of it), it is applicable, because of the Darboux equation

$$\Delta_{\vec{x}} f(\vec{x}, r) = \left( \frac{\partial^2}{\partial r^2} + \frac{m-1}{r} \frac{\partial}{\partial r} \right) f(\vec{x}, r),$$

since it transforms the Laplacian into a one-dimensional operator. In our previous paper [10] we extended spherical means by using the representations of  $\text{Spin}(m)$  instead of  $\text{SO}(m)$  and so-called spherical monogenics instead of spherical harmonics. Spherical monogenics are, roughly speaking, hypercomplex generalizations of the classical complex powers  $z \rightarrow z^k$ ,  $k \in \mathbb{Z}$ , i.e. they are homogeneous solutions of a Dirac type operator  $D$ , with values in a Clifford algebra. These ideas fit completely into the general setting of group representations and integral geometry as is being studied by S. Helgason in [3]. Our previous paper [10] was restricted to spheres of codimension one and so the spherical means have only one extra dimension, the radius of the sphere. Hence the Darboux equations link this radial dimension  $r$  to the space variable  $\vec{x} \in R^m$ .

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In this paper we study mean values of functions over spheres of any dimension. Such spheres are parametrised by their center  $\vec{x}$ , the radius  $r$  and an  $s$ -vector  $\omega$ , which represents the axis so that spherical means depend on coordinates  $(\vec{x}, r, \omega)$  where  $r$  and  $\omega$  are extra dimensions. Hence there exist Darboux equations which link the radius  $r$  with the space variable  $\vec{x}$ , called radial Darboux equations, and equations which express the " $\omega$ -derivatives" in terms of the space derivatives, called angular Darboux equations.

In the first section we recall the main definitions and properties of [10].

The second section is devoted to spherical means of codimension 2. In this section we link the radial and angular Darboux equations together in such a way that we obtain solutions of the complex monogenic system  $(D_x + iD_y)f = 0$ ,

$$D_x + iD_y = \sum_{j=1}^m e_j \left( \frac{\partial}{\partial x_j} + i \frac{\partial}{\partial y_j} \right)$$

being a complex Dirac type operator in  $C^m$  (see [8], [11], [12]).

The study of spherical means of any codimension is more involved. To that end we make use of functions defined in the entire Clifford algebra  $C_m$  or in its real part

$R_m$  or in the spaces of  $s$ -vectors  $R_{m,s}$  (see also [4]). The study of  $\text{Spin}(m)$ -representations is done in section 3.

In section 4 we study the Darboux equations for spheres of any codimension.

Preliminaries. Let  $\{e_1, \dots, e_m\}$  be an orthonormal basis of  $R^m$ . Then by  $C_m$  we denote the complex Clifford algebra constructed by means of this basis. Hence a general element  $a \in C_m$  is of the form

$$a = \sum_{A \subseteq N} e_A a_A, \quad a_A \in C, \quad N = \{1, \dots, m\}, \quad \text{where for } A = \{\alpha_1, \dots, \alpha_h\}, \quad \alpha_1 < \dots < \alpha_h,$$

$$e_A = e_{\alpha_1} \dots e_{\alpha_h}.$$

The product in  $C_m$  is determined by the relations

$$e_i e_j + e_j e_i = -2\delta_{ij}; \quad i, j = 1, \dots, m, \quad e_\emptyset = 1.$$

By  $R_m$  we denote the real Clifford algebra over  $R^m$ .

Every  $a \in C_m$  may uniquely be written into the form  $a = [a]_0 + [a]_1 + \dots + [a]_m$ , where  $[a]_s \in C_{m,s}$ ;  $s = 0, \dots, m$  and where  $C_{m,s}$  is the space of complex  $s$ -vectors  $C_{m,s} = \left\{ \sum_{|A|=s} a_A e_A : a_A \in C \right\}$ . The space of real  $s$ -vectors will be

denoted by  $R_{m,s}$ .

An involution on  $C_m$  is given by  $\bar{a} = \sum_{A \subset \mathbb{N}} \bar{a}_A \bar{e}_A$ , where  $\bar{a}_A$  denotes complex conjugation and  $\bar{e}_A = \bar{e}_{\alpha_1} \dots \bar{e}_{\alpha_1}$ ,  $\bar{e}_j = -e_j$ ;  $j=1, \dots, m$ . Notice that on  $R_m$

$$\bar{a} = [a]_0 - [a]_1 - [a]_2 + [a]_3 + \dots$$

An inner product on  $R_m$  is given by  $\langle a, b \rangle = [\bar{a}b]_c$ . This inner product coincides with the one induced from  $R^{2n}$ . The norm of  $a \in C_m$  is given by  $|a|^2 = \sum_A |a_A|^2$  and satisfies  $|ab| \leq 2^m |a| |b|$ .

By the identifications  $R^{m+1} = R_{m,0} + R_{m,1}$  and  $R^m = R_{m,1}$ ,  $R^{m+1}$  and  $R^m$  are naturally imbedded in  $R_m$ . Hence  $(x_0, x_1, \dots, x_m) \in R^{m+1}$  will be identified with  $x_0 + \vec{x}$ ,  $\vec{x} = \sum_{j=1}^m x_j e_j$ . The inner product in  $R^m$  will be denoted by  $\langle \vec{x}, \vec{y} \rangle$ .

Let  $\Omega \subset R^m$  be open; then  $f \in C_1(\Omega, C_m)$  will be called left monogenic

in  $\Omega$  if  $Df=0$ , where  $D = \sum_{j=1}^m e_j \frac{\partial}{\partial x_j}$  is a generalized Cauchy-Riemann operator,

called Dirac operator or vector derivative.

A function  $P_k(\vec{\omega})(O_k(\vec{\omega}))$ ,  $\vec{\omega} \in S^{m-1}$  is called inner (outer) spherical monogenic of degree  $k$  if  $r^k P_k(\vec{\omega})(r^{-(k+m-1)} O_k(\vec{\omega}))$  is left monogenic in  $R^m$  (in  $R^m \setminus \{0\}$ ).

Every spherical harmonic admits a unique decomposition  $S_k = P_k + O_{k-1}$  into spherical monogenics.

By  $\omega_m$  we denote the area of  $S^{m-1}$ .

### 1. Basic representations of Spin(m)

Let  $s \in \text{Spin}(m)$  and  $f \in L_2(S^{m-1}; C_m)$ . Then we consider the basic representations  $H_0$  and  $L$  of  $\text{Spin}(m)$ , given by  $H_0(s)f(\vec{x}) = f(\vec{s}x)$ ,  $L(s)f(\vec{x}) = sf(\vec{s}x)$ .  $H_0$  corresponds to the usual representation of  $SO(m)$ , while  $L$  corresponds to spin 1/2-representation.

The Lie algebra of  $\text{Spin}(m)$  is the space  $R_{m,2}$  of real bivectors, the elements of which are of the form  $\sum_{i < j} x_{ij} e_{ij}$ ,  $x_{ij} \in R$ . Hence the

infinitesimal representations of  $H_0$  and  $L$  are given by

$$dH_0(e_{ij}) = -2L_{ij}, \quad dL(e_{ij}) = -2L_{ij} + e_{ij},$$

where  $L_{ij} = x_i \frac{\partial}{\partial x_j} - x_j \frac{\partial}{\partial x_i}$ .

The Casimir operators  $C(H_0)$  and  $C(L)$  of  $H_0$  and  $L$  are hence given by

$$C(H_0) = \Delta_S, \quad C(L) = \Delta_S + \Gamma - \frac{1}{4} \binom{m}{2},$$

where  $\Delta_S$  is the Laplace-Beltrami operator and  $\Gamma = - \sum_{i < j} e_{ij} L_{ij}$ ,

the spherical Dirac operator (see [ 7 ], [ 9 ], [ 13 ]).

The eigenspaces of  $\Delta_S$  are the classical spaces  $H_k$  of spherical harmonics of degree  $k$  (eigenvalue  $-k(k+m-2)$ ); the eigenspaces of  $C(L)$  are denoted by  $M_k$ .

$M_k$  is called the space of spherical monogenics of degree  $k$ . As  $\Delta_S = \Gamma(m-2-\Gamma)$ ,  $H_k$  and  $M_k$  are of the form

$$H_k = M_{+,k} + M_{-,k}, \quad M_k = M_{+,k} + M_{-,k},$$

where  $M_{\pm,k}$  are the eigenspaces of  $\Gamma$  with eigenvalues  $-k$  and  $k+m-1$  (see [ 7 ], [ 9 ], [ 13 ]).

The elements of  $M_{\pm,k}$  are called inner and outer spherical monogenics of degree  $k$  and are denoted by  $P_k(\omega)$  and  $Q_k(\omega)$ ,  $\omega \in S^{m-1}$ .

The projections on  $H_k$ ,  $M_k$ ,  $M_{+,k}$ ,  $M_{-,k}$  are respectively denoted by  $S_k$ ,  $\Pi_k$ ,  $P_k$ ,  $Q_k$ .

We have that  $Q_k(f) = -\vec{\omega} P_k(\vec{\omega} f)$  and

$$P_k(f)(\vec{\omega}) = \frac{(-1)^{k+1}}{\omega_m k!} \int_{S^{m-1}} \langle \vec{\omega}, \nabla \rangle^k \left( \frac{\vec{u}}{|\vec{u}|^m} \right) \vec{u} f(\vec{u}) dS_u.$$

Let  $D = \sum_{j=1}^m e_j \frac{\partial}{\partial x_j}$ ; then  $D = \vec{\omega} \left( \frac{\partial}{\partial r} + \frac{1}{r} \Gamma \right) \omega$ . Hence if  $P_k, Q_k$  are spherical

monogenic,  $r^k P_k(\vec{\omega})$  and  $r^{-(k+m-1)} Q_k(\vec{\omega})$  are left monogenic in  $R^m \setminus \{0\}$ . As  $D$  is invariant under the representation  $L$ ,  $D$  commutes with  $\Pi_k = P_k + Q_k$ . This leads to a refinement of the classical theory of spherical means (see [ 6 ], [ 10 ]) of which we recall the main definitions and properties.

Let  $f$  be a function in a domain of  $R^m$ . Then we consider the refined spherical means

$$P(f)(\vec{x}, r) = \frac{1}{\omega_m} \int_{S^{m-1}} f(\vec{x} + r\vec{\omega}) dS_\omega,$$

$$Q(f)(\vec{x}, r) = \frac{1}{\omega_m} \int_{S^{m-1}} \vec{\omega} \cdot f(\vec{x} + r\vec{\omega}) dS_\omega.$$

These refined spherical means satisfy a first order Darboux system

of the form

$$D_x P(f)(\vec{x}, r) = \left(\frac{\partial}{\partial r} + \frac{m-1}{r}\right) Q(f)(\vec{x}, r)$$

$$D_x Q(f)(\vec{x}, r) = -\frac{\partial}{\partial r} P(f)(\vec{x}, r),$$

which follows straight from  $\Pi_0(D_x f(\vec{x}+\vec{y})) = D_y \Pi_0 f(\vec{x}+\vec{y})$ , where  $\Pi_0(f)(\vec{x}+\vec{y}) = P(f)(\vec{x}, |\vec{y}|) - \vec{y}/|\vec{y}| \cdot Q(f)(\vec{x}, |\vec{y}|)$ .

Hence we may generalize these spherical means to

$$\Pi_k(f(\vec{x}+\vec{u}))(\vec{y}) = P_k(f(\vec{x}+\vec{u}))(\vec{y}) - \frac{\vec{y}}{|\vec{y}|} P_k\left(\frac{\vec{u}}{|\vec{u}|} f(\vec{x}+\vec{u})\right)(\vec{y}),$$

leading up to the generalized Darboux system

$$P_{+,k}(Df) = \left(\frac{\partial}{\partial r} + \frac{k+m-1}{r}\right) P_{-,k}(f),$$

$$P_{-,k}(Df) = \left(-\frac{\partial}{\partial r} + \frac{k}{r}\right) P_{+,k}(f),$$

where for  $r = |\vec{y}|$ ,

$$P_{+,k}(f)(\vec{x}, r) = P_k(f(\vec{x}+\vec{u}))(\vec{y}),$$

$$P_{-,k}(f)(\vec{x}, r) = P_k\left(\frac{\vec{u}}{|\vec{u}|} f(\vec{x}+\vec{u})\right)(\vec{y}),$$

and where for fixed  $(\vec{x}, r)$ ,  $P_{\pm,k}(f)(\vec{x}, r)$  have values in  $M_{+,k}$ .

In terms of the Gegenbauer polynomials  $C_\nu^\lambda(\theta)$  (see [5]), we have the following explicit formulae

$$P_{+,k}(f)(\vec{x}, r) = \frac{1}{\omega_m} \int_{S^{m-1}} (C_k^{\frac{m}{2}}(\theta) + \vec{\omega}\vec{u} C_{k-1}^{\frac{m}{2}}(\theta)) f(r\vec{u}+\vec{x}) dS_u,$$

$$P_{-,k}(f)(\vec{x}, r) = \frac{1}{\omega_m} \int_{S^{m-1}} (\vec{u} C_k^{\frac{m}{2}}(\theta) - \vec{\omega} C_{k-1}^{\frac{m}{2}}(\theta)) f(r\vec{u}+\vec{x}) dS_u,$$

where  $\vec{y} = r\vec{\omega}$ ,  $\vec{\omega} \in S^{m-1}$  and  $\theta = \langle \vec{\omega}, \vec{u} \rangle$ ,  $\vec{u} \in S^{m-1}$ .

## 2. Spherical means of codimension 2

In view of its importance in complex analysis we treat spherical means of codimension 2 separately.

Let  $\Omega \subseteq R^m$  be open and put

$$\hat{\Omega} = \{(\vec{x}, \vec{y}) : \vec{x} \in \Omega, \vec{x} + S_y \subseteq \Omega\}, \quad S_y = \{\vec{u} : |\vec{u}| = |\vec{y}|, \langle \vec{u}, \vec{y} \rangle = 0\}.$$

The component of  $\hat{\Omega}$  containing  $\Omega$  is called the complex harmonic hull of  $\Omega$  (see e.g. [1]).

First we introduce the 0-th order spherical means by

$$P^1(f)(\vec{x}, \vec{y}) = \frac{1}{\omega_{m-1}} \int_{S^{m-1}} \delta(\langle \vec{u}, \vec{\omega} \rangle) f(\vec{x} + r\vec{u}) dS_u$$

$$Q^1(f)(\vec{x}, \vec{y}) = \frac{1}{\omega_{m-1}} \int_{S^{m-1}} \vec{u} \delta(\langle \vec{u}, \vec{\omega} \rangle) f(\vec{x} + r\vec{u}) dS_u,$$

where  $\vec{y} = r\vec{\omega}$ ,  $r = |\vec{y}|$  and  $(\vec{x}, \vec{y}) \in \hat{\Omega}$ .

From the codimension 1 case we immediately obtain the radial Darboux equations

$$(D_x - \vec{\omega} \langle \vec{\omega}, D_x \rangle) P^1(f) = \left( \frac{\partial}{\partial r} + \frac{m-2}{r} \right) Q^1(f),$$

$$(D_x - \vec{\omega} \langle \vec{\omega}, D_x \rangle) Q^1(f) = -\frac{\partial}{\partial r} P^1(f).$$

However, this only expresses the radial part of the  $\vec{y}$ -derivatives in terms of  $\vec{x}$ -derivatives. Of course there will also be an angular version of the Darboux equations. This is obtained in

Theorem 1.  $P^1(f)$  and  $Q^1(f)$  satisfy the angular Darboux equations

$$r\vec{\omega} \langle \vec{\omega}, D_x \rangle P^1(f) = (1 - \Gamma_y) Q^1(f)$$

$$r\vec{\omega} \langle \vec{\omega}, D_x \rangle Q^1(f) = \Gamma_y P^1(f),$$

where  $r\vec{\omega} = \vec{y}$  and  $\Gamma_y = \sum_{i < j} e_{ij} (y_j \frac{\partial}{\partial y_i} - y_i \frac{\partial}{\partial y_j})$ .

Proof. As  $\delta(\langle \vec{u}, \vec{\omega} \rangle) = |\vec{y}| \delta(\langle \vec{u}, \vec{y} \rangle)$ , we have that

$$\Gamma_y P^1(f)(\vec{x}, \vec{y})$$

$$= \frac{|\vec{y}|}{\omega_{m-1}} \int_{S^{m-1}} \Gamma_y \delta(\langle \vec{u}, \vec{y} \rangle) f(\vec{x} + |\vec{y}| \vec{u}) dS_u$$

$$= \frac{1}{\omega_{m-1}} \int_{S^{m-1}} \delta'(\langle \vec{u}, \vec{\omega} \rangle) (\vec{u} \wedge \vec{\omega}) f(\vec{x} + r\vec{u}) dS_u$$

$$= -\frac{1}{\omega_{m-1}} \int_{S^{m-1}} \delta(\langle \vec{u}, \vec{\omega} \rangle) \langle \vec{\omega}, D_u \rangle (\vec{u} \wedge \vec{\omega} f(\vec{x} + r\vec{u})) dS_u$$

$$= r\vec{\omega} \langle \vec{\omega}, D_x \rangle Q^1(f).$$

Similarly we obtain that

$$\begin{aligned}
 \Gamma_y Q(f) &= -\frac{1}{\omega_{m-1}} \int_{S^{m-1}} \delta(\langle \vec{u}, \vec{\omega} \rangle) \langle \vec{\omega}, D_u \rangle [ \vec{u} \wedge \vec{\omega} \cdot \vec{u} f(\vec{x} + r\vec{u}) ] dS_u \\
 &= -\frac{1}{\omega_{m-1}} \int_{S^{m-1}} \delta(\langle \vec{u}, \vec{\omega} \rangle) \vec{u} \wedge \vec{\omega} [ \vec{\omega} f(\vec{x} + r\vec{u}) + \vec{u} r \langle \vec{\omega}, D_x \rangle f(\vec{x} + r\vec{u}) ] dS_u \\
 &= Q^1(f) - r \vec{\omega} \langle \vec{\omega}, D_x \rangle P^1(f). \quad \blacksquare
 \end{aligned}$$

Notice that the radial Darboux equations follow from the L-invariance of D, together with the commutation relations

$$[D_x \vec{\omega} \langle \vec{\omega}, D_x \rangle, P^1] = [D_x \vec{\omega} \langle \vec{\omega}, D_x \rangle, Q^1] = 0,$$

$$[\vec{\omega} \langle \vec{\omega}, D_x \rangle, P^1] = 0, \quad \vec{\omega} \langle \vec{\omega}, D_x \rangle Q^1 = -Q^1 \bullet \vec{\omega} \langle \vec{\omega}, D_x \rangle.$$

The angular equations were shown independently from this. There is however a nice way to link the radial and angular equations together, which has a meaning in complex analysis.

Indeed, we have that

$$\begin{aligned}
 P^1(D_x f) &= \left( \frac{\partial}{\partial r} - \frac{1}{r} \Gamma_y \right) Q^1(f) + \frac{m-1}{r} Q^1(f) \\
 &= \vec{\omega} \left( \frac{\partial}{\partial r} + \frac{1}{r} \Gamma_y \right) (-\vec{\omega} Q^1(f)) = D_y(-\vec{\omega} Q^1(f)).
 \end{aligned}$$

and

$$-\vec{\omega} Q^1(D_x f) = D_y P^1(f).$$

Furthermore, by the above commutation relations,  $\vec{\omega} Q^1(D_x f) = -D_x \vec{\omega} Q^1(f)$ , so that we arrive at the system

$$(D_x + iD_y) [P^1(f) - i\vec{\omega} Q^1(f)] = 0.$$

Hence spherical means of codimension 2 provide global solutions of the complex monogenic system  $(D_x + iD_y)g = 0$ , which we already studied partially in [11] (see also [8], [12]). It is natural to introduce one single spherical mean of codimension 2 by means of

$$M(f)(\vec{x}, \vec{y}) = \frac{1}{\omega_{m-1}} \int_{S^{m-1}} (1 + i\vec{u} \wedge \vec{\omega}) \delta(\langle \vec{u}, \vec{\omega} \rangle) f(\vec{x} + r\vec{u}) dS_u.$$

Then  $M(f)$  is a solution of  $(D_x + iD_y)g = 0$  such that  $\lim_{y \rightarrow 0} M(f)(x, y) = f(x)$ .

Example. Let us take the Dirac measure  $\delta(\vec{x} + r\vec{u})$ . Then in spherical

coordinates, putting  $\vec{x} = |\vec{x}| \vec{\xi}$ , we have that

$$\delta(\vec{x} + r\vec{u}) = \frac{1}{r^{m-1}} \delta(r - |\vec{x}|) \otimes \delta(\vec{u} + \vec{\xi}), \quad \vec{u}, \vec{\xi} \in S^{m-1}.$$

Hence the spherical mean of the Dirac measure is given by

$$M(\delta)(\vec{x}, \vec{y}) = \frac{1}{\omega_{m-1}} \frac{1 - i \vec{\xi} \wedge \vec{\omega}}{|y|^{m-1}} \delta(|\vec{y}| - |\vec{x}|) \times \delta(\langle \vec{\xi}, \vec{\omega} \rangle), \quad \vec{x} = |\vec{x}| \vec{\xi}, \quad \vec{y} = |\vec{y}| \vec{\omega}.$$

Notice that  $M(\delta)(\vec{x}, \vec{y})$  is concentrated on the isotropic sphere in  $C^m$ . One can easily show that  $M(\delta)(\vec{x}, \vec{y})$  is a global distributional solution of  $(D_x + iD_y)g = 0$ .

Next we introduce the  $k$ -th spherical means of codimension 2, denoted by  $P_{\pm k}(f)(\vec{x}, \vec{y}), (\vec{x}, \vec{y}) \in \hat{\Omega}$ .

To that end, we first introduce vector bundles over  $S^{m-1}$  as follows. For  $\vec{\omega} \in S^{m-1}$ ,  $M_{\pm, k}(\vec{\omega})$  are the right  $C_m$ -modules of inner and outer spherical monogenics of degree  $k$  on  $S_{\vec{\omega}} = \{\vec{u} \in S^{m-1} : \vec{u} \perp \vec{\omega}\}$  and  $P_{k, \vec{\omega}}$  is the projection onto  $M_{+, k}(\vec{\omega})$ . Furthermore, we put  $M_k(\vec{\omega}) = M_{+, k}(\vec{\omega}) + M_{-, k}(\vec{\omega})$  and  $H_k(\vec{\omega}) = M_{+, k}(\vec{\omega}) + M_{-, k-1}(\vec{\omega})$  and denote by  $\Pi_{k, \vec{\omega}}$  and  $S_{k, \vec{\omega}}$  the corresponding projection operators. Notice that  $\Pi_{k, \vec{\omega}} = P_{k, \vec{\omega}} - \vec{v} P_{k, \vec{\omega}} \vec{v}$ , where  $\vec{v}$  is the unit normal vectorfield on  $S_{\vec{\omega}}$ .

Definition 1. The  $k$ -th inner and outer spherical means of codim 2 are given by

$$P_{+, k}^1 f(\vec{x}, r\vec{\omega}) = P_{k, \vec{\omega}}(f(\vec{x} + r\vec{u})),$$

$$P_{-, k}^1 f(\vec{x}, r\vec{\omega}) = P_{k, \vec{\omega}}(\vec{u} f(\vec{x} + r\vec{u})),$$

and are considered as sections of  $M_{+, k}(\vec{\omega})$  (for fixed  $\vec{x}$ ).

Putting  $\theta = \langle \vec{u}, \vec{v} \rangle$ , we have that in terms of the Gegenbauer polynomials,

$$P_{+, k}(f)(\vec{x}, r\vec{\omega})(\vec{v}) = \frac{1}{\omega_{m-1}} \int_{S^{m-1}} \delta(\langle \vec{\omega}, \vec{u} \rangle) (C_k^{\frac{m-1}{2}}(\theta) + \vec{v} u C_{k-1}^{\frac{m-1}{2}}(\theta)) f(r\vec{u} + \vec{x}) dS_u$$

and

$$P_{-,k}^1(f)(x, r\vec{\omega})(\vec{v}) = \frac{1}{\omega_{m-1}} \int_{S^{m-1}} \delta(\langle \vec{\omega}, \vec{u} \rangle) [ \vec{u} C_k^{\frac{m-1}{2}}(\theta) - \vec{v} C_{k-1}^{\frac{m-1}{2}}(\theta) ] f(r\vec{u} + \vec{x}) dS_x.$$

Of course  $P_{\pm,k}^1(f)(\vec{x}, r\vec{\omega}) \in M_{+,k}(\vec{\omega})$  only for  $\vec{v} \perp \vec{\omega}$ .

The radical Darboux equations are now of the form

$$P_{+,k}^1((D_x \vec{\omega} \langle \vec{\omega}, D_x \rangle) f) = \left( \frac{\partial}{\partial r} + \frac{k+m-2}{r} \right) P_{-,k}^1(f)$$

$$P_{-,k}^1((D_x \vec{\omega} \langle \vec{\omega}, D_x \rangle) f) = \left( -\frac{\partial}{\partial r} + \frac{k}{r} \right) P_{+,k}^1(f).$$

The angular Darboux equations are not expressed nicely in terms of  $P_{\pm,k}^1$ . In order to obtain them, we first write  $P_{\pm,k}^1$  into the form

$$P_{+,k}^1(f) = A_{+,k}(f) + \vec{v} A_{-,k-1}(f)$$

$$P_{-,k}^1(f) = A_{-,k}(f) - \vec{v} A_{+,k-1}(f),$$

where

$$A_{+,k}(f) = \frac{1}{\omega_{m-1}} \int_{S^{m-1}} \delta(\langle \vec{\omega}, \vec{u} \rangle) C_k^{\frac{m-1}{2}}(\theta) f(r\vec{u} + \vec{x}) dS_n$$

and  $A_{-,k}(f) = A_{+,k}(\vec{u}f)$ . Similar to Theorem 1, we obtain that for

$$\langle \vec{\omega}, \vec{v} \rangle = 0,$$

$$r\vec{\omega} \langle \vec{\omega}, D_x \rangle A_{+,k}(f) = (1 - \Gamma_\omega) A_{-,k}(f),$$

$$r\vec{\omega} \langle \vec{\omega}, D_x \rangle A_{-,k}(f) = \Gamma_\omega A_{+,k}(f).$$

Next we introduce

Definition 2. The  $k$ -th spherical harmonic means of  $f$  are given by

$$S_{+,k}^1(f(\vec{x} + r\vec{u})) = A_{+,k}(f) - A_{+,k-2}(f),$$

$$S_{-,k}^1(f(\vec{x} + r\vec{u})) = A_{-,k}(f) - A_{-,k-2}(f).$$

Notice that formally  $S_{+,k}^1 = P_{+,k}^1 - \vec{v} P_{-,k}^1$  and

$$S_{-,k}^1(f) = S_{+,k}^1(\vec{u}f) = P_{-,k}^1(f) + \vec{v} P_{+,k}^1(f).$$

Next we prove the generalized Darboux system for the k-th spherical harmonic means.

Theorem 2. Let  $\vec{y}=r\vec{\omega}$ ,  $\vec{v}\in S^{m-1}$  such that  $\langle \vec{v}, \vec{\omega} \rangle = 0$  and let  $\Gamma_{\vec{v}}$  be the spherical Dirac operator on  $S_{\omega}$ . Then  $S_{+,k}^1(f)$  and  $S_{-,k}^1(f)$  satisfy the system

$$(D_x + iD_y - \frac{i\vec{\omega}\Gamma_{\vec{v}}}{r})(S_{+,k}^1(f) - i\vec{\omega}S_{-,k}^1(f)) = 0.$$

Proof. First notice that  $S_{\pm,k}^1(f)$  satisfy the same angular Darboux system from Theorem 1. Next, the radial Darboux system for  $P_{\pm,k}$  leads to

$$S_{+,k}^1((D_x - \vec{\omega}\langle \vec{\omega}, D_x \rangle)f) = (\frac{\partial}{\partial r} + \frac{m-2-\Gamma_{\vec{v}}}{r})S_{-,k}^1(f),$$

$$S_{-,k}^1((D_x - \vec{\omega}\langle \vec{\omega}, D_x \rangle)f) = -(\frac{\partial}{\partial r} + \frac{\Gamma_{\vec{v}}}{r})S_{+,k}^1(f).$$

Hence, by combining both systems, we obtain that for

$$\langle \vec{v}, \vec{\omega} \rangle = 0, \vec{y} = r\vec{\omega},$$

$$S_{+,k}^1(D_x f) = D_y(-\vec{\omega}S_{-,k}^1(f)) - \frac{\Gamma_{\vec{v}}}{r}S_{-,k}^1(f),$$

$$-\vec{\omega}S_{-,k}^1(D_x f) = D_y S_{+,k}^1(f) + \frac{\Gamma_{\vec{v}}\vec{\omega}}{r}S_{+,k}^1(f).$$

It is now clear that  $S_{+,k}^1(D_x f) = D_x S_{+,k}^1(f)$  while straightforward computation leads to

$$\begin{aligned} & S_{-,k}^1((D_x - \vec{\omega}\langle \vec{\omega}, D_x \rangle)f) \\ &= -2\frac{\Gamma_{\vec{v}}}{r}S_{+,k}^1(f) + (D_x - \vec{\omega}\langle \vec{\omega}, D_x \rangle)S_{-,k}^1(f). \end{aligned}$$

Hence, as  $S_{-,k}^1(\vec{\omega}\langle \vec{\omega}, D_x \rangle f) = -\vec{\omega}\langle \vec{\omega}, D_x \rangle S_{-,k}^1(f)$ , we obtain that for  $\langle \vec{v}, \vec{\omega} \rangle = 0$ ,

$$D_x S_{+,k}^1(f) = D_y(-\vec{\omega}S_{-,k}^1(f)) - \frac{\Gamma_{\vec{v}}}{r}S_{-,k}^1(f),$$

$$D_x(\vec{\omega}S_{-,k}^1(f)) = D_y(S_{+,k}^1(f)) - \frac{\Gamma_{\vec{v}}\vec{\omega}}{r}S_{+,k}^1(f),$$

which may be simplified to the stated system. ■

Notice that the above equation should be considered as an equation for sections of the bundle  $S_k(\omega)$ , on which  $\Gamma_{\vec{v}}$  acts as a finite dimensional linear operator.

3. Extended representations of Spin(m)

Let  $R_{m,s}$  be the space of real s-vectors and let  $\tilde{R}_{m,s}$  be the cone of elements of the form  $\vec{y} = \vec{y}_1 \cdot \vec{y}_2 \dots \vec{y}_s$  with  $\vec{y}_1 \perp \dots \perp \vec{y}_s$ . Notice that

$\tilde{R}_{m,s} \setminus \{0\} = \tilde{G}_{m,s}(R) \times R_+$ ,  $\tilde{G}_{m,s}(R)$  being the Grassmann manifold of oriented s-dimensional subspaces of  $R^m$ .

First of all we introduce extended representations H and L of Spin(m) as follows. Let  $\Omega \subseteq R_m$ , f a function in  $\Omega$  and  $t \in \text{Spin}(m)$ . Then we put  $H(t)f(y) = f(\bar{t}yt)$ ,  $L(t)f(y) = tf(\bar{t}yt)$ ,  $y \in \Omega$ .

Furthermore,  $y \in R_m$  may be written as

$$y = [y]_0 + [y]_1 + \dots + [y]_m, \quad [y]_s \in R_{m,s}, \quad s = 0, \dots, m,$$

and  $\bar{t}[y]_s t = [\bar{t}yt]_s$ ,  $t \in \text{Spin}(m)$ . Hence the representations H and L are well defined for functions in  $\Omega \subseteq R_{m,s}$ .

Furthermore, if y is of the form  $y = \vec{y}_1 \dots \vec{y}_s \in \tilde{R}_{m,s}$  then  $\bar{t}y = \bar{t}\vec{y}_1 \bar{t}\vec{y}_2 \dots \bar{t}\vec{y}_s$ ,  $t \in \tilde{R}_{m,s}$ . Hence H and L may even act on functions defined on  $\tilde{R}_{m,s}$ .

The Casimir operator of H is of the form

$$C(H) = \frac{1}{4} \sum_{i < j} (dH(e_{ij}))^2,$$

where  $dH(e_{ij})$  are the infinitesimal representations of  $e_{ij}$ . Let  $\Delta_{\tilde{G}_{m,s}}$  be the Laplace-Beltrami operator on  $\tilde{G}_{m,s}(R)$ , then  $\Delta_{\tilde{G}_{m,s}}$  equals

the restriction of  $G(H)$  to  $\tilde{R}_{m,s}$ .

The infinitesimal representations of  $e_{ij}$  corresponding to L are given by  $dL(e_{ij}) = dH(e_j) + e_{ij}$ . Hence the Casimir operator of L is given by

$$C(L) = C(H) + \Gamma - \frac{1}{4} \binom{m}{2},$$

where  $\Gamma = \frac{1}{2} \sum_{i < j} e_{ij} dH(e_{ij})$ .

Notice that  $\Gamma^2 = [\Gamma^2]_0 + [\Gamma^2]_2 + [\Gamma^2]_4$ , where

$$[\Gamma^2]_0 = C(H), \quad [\Gamma^2]_2 = (m-2)\Gamma$$

and

$$[\Gamma^2]_4 = \frac{1}{4} \sum_{i < j < k < l} e_{ijkl} (dH(e_{ij})dH(e_{kl}) - dH(e_{ik})dH(e_{jl}))$$

$$+dH(e_{i1})dH(e_{jk})).$$

Next, consider the Clifford derivative on  $R_m$ , introduced by D. Hestenes and G. Sobczyk in [4] and given by  $D = \sum_A e_A \frac{\partial}{\partial y_A}$ . Then

on  $R_m$  we have that

$$\begin{aligned} dH(e_{ij})f(y) &= \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} (f((1-\epsilon e_{ij})y(1+\epsilon e_{ij})) - f(y)) \\ &= \langle [y, e_{ij}], D \rangle f = \langle e_{ij}, \bar{y}D + y\bar{D} \rangle f, \end{aligned}$$

where  $\langle y, u \rangle = [\bar{y}u]_0 = [y\bar{u}]_0$ ,  $u, y \in R_m$ .

Hence on  $R_m$  we obtain that

$$\Gamma = \frac{1}{2} [\bar{y}D + y\bar{D}]_2.$$

Furthermore, let  $D_{m,s}$  be the  $s$ -vector derivative, given by  $\sum_{|A|=s} e_A \frac{\partial}{\partial y_A}$ ,

then the restrictions of  $\Gamma$  to  $R_{m,s}$  and  $\tilde{R}_{m,s}$  are both of the form

$$\Gamma|_{R_{m,s}} = \frac{1}{2} [\bar{y}D_{m,s} + y\bar{D}_{m,s}]_2,$$

and will be denoted by  $\Gamma_{y,s}$ .

Examples. (i) For  $s=1$  we have that  $[\Gamma_{y,s}^2]_4 = 0$  so that  $\Delta_S = \Gamma(m-2-\Gamma)$ .

(ii) For  $s=2$  we put  $y = \sum_{k<1} y_{k1} e_{k1}$  and  $y_{k1} = -y_{1k}$  and we have that

$$dH(e_{ij}) = 2 \sum_{k \neq i, j} (y_{kj} \frac{\partial}{\partial y_{ki}} - y_{ki} \frac{\partial}{\partial y_{kj}}).$$

Hence  $\Gamma_{y,2}$  is given by

$$\Gamma_{y,2} = \sum_{i < j} \sum_{k \neq i, j} e_{ij} (y_{kj} \frac{\partial}{\partial y_{ki}} - y_{ki} \frac{\partial}{\partial y_{kj}}).$$

Notice that in this case  $[\Gamma_{y,2}^2]_4 \neq 0$ , which makes  $\Gamma_{y,2}$  quite independent

from  $\Delta_{G_{m,2}}^{\sim}$ .  $\Gamma_{y,2}$  is even not an elliptic operator.

#### 4. Spherical means of higher codimension

Let  $s < m-1$  and  $\Omega \subset R^m$  open. Then by  $\hat{\Omega}_s$  we denote the set of all spheres

of codimension  $s+1$  inside  $\Omega$ . We parametrise  $\hat{\Omega}_s$  as follows.

Let  $\vec{\omega}_1, \dots, \vec{\omega}_s$  be an orthonormal  $s$ -frame; then  $\omega = \vec{\omega}_1 \dots \vec{\omega}_s$  represents the oriented  $s$ -space spanned by  $\vec{\omega}_1, \dots, \vec{\omega}_s$ . Hence  $\omega \in \tilde{G}_{m,s}(R) = \tilde{R}_{m,s} \cap S^{2m-1}$ .

A sphere of codimension  $s+1$  is determined by its center  $\vec{x}$ , its radius  $r$  and the  $s$ -vector  $\omega$  which represents the axis.

Hence  $\hat{\Omega}_s = \{(\vec{x}, r\omega) : \vec{x} + \vec{y} \in \Omega, |\vec{y}| = r, \vec{y} \perp \omega\}$ .

The normal vectors to  $\text{span}\{\vec{\omega}_1, \dots, \vec{\omega}_s\}$  are given by the equations  $\langle \vec{\omega}_j, \vec{u} \rangle = 0, j=1, \dots, s$ , and the Dirac measure on the space  $N(\omega)$  of normal vectors is given by

$$\delta(\langle \vec{u}, \vec{\omega}_1 \rangle) \dots \delta(\langle \vec{u}, \vec{\omega}_s \rangle) = \delta(\langle \vec{u}, \omega \rangle).$$

Definition 3. The 0-th spherical means of  $f \in C_0(\Omega)$  of codimension  $s+1$  are given by

$$P^S(f)(\vec{x}, r\omega) = \frac{1}{\omega_{m-s}} \int_{S^{m-1}} \prod_{j=1}^s \delta(\langle \vec{u}, \vec{\omega}_j \rangle) f(\vec{x} + r\vec{u}) dS_{\vec{u}},$$

$$Q^S(f)(\vec{x}, r\omega) = \frac{1}{\omega_{m-s}} \int_{S^{m-1}} \prod_{j=1}^s \delta(\langle \vec{u}, \vec{\omega}_j \rangle) \vec{u} f(\vec{x} + r\vec{u}) dS_{\vec{u}},$$

where  $(\vec{x}, r\omega) \in \hat{\Omega}_s$ .

Notice that, when  $s$  is odd,

$$\vec{u}\omega + \omega\vec{u} = 2 \sum_{j=1}^s (-1)^j \langle \vec{u}, \vec{\omega}_j \rangle \hat{\omega}_j,$$

whereas for  $s$  even,

$$\vec{u}\omega - \omega\vec{u} = 2 \sum_{j=1}^s (-1)^j \langle \vec{u}, \vec{\omega}_j \rangle \hat{\omega}_j,$$

where  $\hat{\omega}_j = \vec{\omega}_1 \dots \hat{\vec{\omega}}_j \dots \vec{\omega}_s$ .

For  $s$  odd we put  $-\langle \vec{u}, \omega \rangle = \frac{1}{2}(\vec{u}\omega + \omega\vec{u})$ , whereas for  $s$  even,  $-\langle \vec{u}, \omega \rangle = \frac{1}{2}(\vec{u}\omega - \omega\vec{u})$ . Hence  $\langle \vec{u}, \omega \rangle$  is an  $(s-1)$ -vector in the Clifford algebra spanned by  $\vec{\omega}_1, \dots, \vec{\omega}_s$ , which we denote by  $A(\omega)$ .

Hence  $\langle \vec{u}, \omega \rangle$  behaves like an  $s$ -dimensional vector in  $A(\omega)$ . This justifies the notation  $\delta(\langle \vec{u}, \omega \rangle)$  for the Dirac measure on  $N(\omega)$ . We now have

Lemma 1. The Dirac operator may be decomposed as  $D = D_+(\omega) + D_-(\omega)$  where

$$D_+(\omega) = \frac{1}{2} \sum_{j=1}^m \bar{\omega}\{\omega, e_j\} \frac{\partial}{\partial x_j}, \quad D_-(\omega) = \frac{1}{2} \sum_{j=1}^m \bar{\omega}\{\omega, e_j\} \frac{\partial}{\partial x_j}.$$

Furthermore for s even (resp. s odd),

$$D_{\pm}(\omega) = \sum_{j=1}^s \vec{\omega}_j \langle \vec{\omega}_j, D \rangle$$

Hence we obtain the radial Darboux equations

Theorem 3. For s even (resp. s odd), we have that

$$D_{\pm}(\omega) P^S(f) = \left( \frac{\partial}{\partial r} + \frac{m-s+1}{r} \right) Q^S(f)$$

$$D_{\pm}(\omega) Q^S(f) = -\frac{\partial}{\partial r} P^S(f).$$

In order to establish the angular Darboux equations, we first study the action of the operator  $\Gamma_{y,s}$ , introduced in the previous section, on  $\delta(\langle u, \omega \rangle)$ .

Lemma 2. For s odd (resp. s even), we have that

$$\Gamma_{y,s} \delta(\langle \vec{u}, \omega \rangle) = \vec{u} \wedge D_{\pm}(\omega) \delta(\langle \vec{u}, \omega \rangle).$$

Proof. First consider any smooth function  $f(\vec{y}_1, \dots, \vec{y}_s)$ , defined in a neighbourhood of the cone

$$K = \{ (\vec{y}_1, \dots, \vec{y}_s) \in (\mathbb{R}^m \setminus \{0\}) : \vec{y}_1 \perp \dots \perp \vec{y}_s \},$$

such that  $f|_K$  depends only on the s-vector  $\vec{y}_1 \dots \vec{y}_s$ . Then  $f|_K$  determines a function on  $\tilde{R}_{m,s}$ , which we denote by  $f|_{\tilde{R}_{m,s}}$ . Of course this is no restriction in the classical sense, since K is a bundle over  $\tilde{R}_{m,s}$  in which  $\tilde{R}_{m,s}$  is not inbedded as a classical surface.

In any case, we may define a representation  $H'$  of  $\text{Spin}(m)$  on  $f$  by  $H'(t)f(\vec{y}_1, \dots, \vec{y}_s) = f(\vec{t}\vec{y}_1 t, \dots, \vec{t}\vec{y}_s t)$  and  $H'(t)f(\vec{y}_1, \dots, \vec{y}_s)$  may still be "restricted" to  $\tilde{R}_{m,s}$ .

Furthermore  $(H'(t)f)|_{\tilde{R}_{m,s}} = f|_{\tilde{R}_{m,s}}(\vec{t}\vec{y}_1 \dots \vec{y}_s \vec{t}) = H(t)(f|_{\tilde{R}_{m,s}}),$

so that also

$$dH(e_{ij})(f|_{\tilde{R}_{m,s}}) = (dH'(e_{ij})f)|_{\tilde{R}_{m,s}}$$

$$= -2 \sum_{k=1}^s (L_{ij}^k f) | \tilde{R}_{m,s},$$

where  $L_{ij}^k = y_{ki} \frac{\partial}{\partial y_{kj}} - y_{kj} \frac{\partial}{\partial y_{ki}}$ . Hence we arrive at

$$\Gamma_{y,s}(f | \tilde{R}_{m,s}) = - \left( \sum_{i < j} e_{ij} \sum_{k=1}^s L_{ij}^k f \right) | \tilde{R}_{m,s}.$$

We now apply this to the function

$$f(\vec{y}_1, \dots, \vec{y}_s) = |\vec{y}_1| \dots |\vec{y}_s| \delta(\langle \vec{u}, \vec{y}_1 \rangle) \dots \delta(\langle \vec{u}, \vec{y}_s \rangle),$$

which, after action on a testfunction  $\varphi(u)$  behaves like a  $C_\infty$ -function.

Notice that  $f | \tilde{R}_{m,s} = \delta(\langle \vec{u}, \omega \rangle)$ . Hence, putting  $\vec{y}_j = |\vec{y}_j| \vec{\omega}_j$  and

$\Gamma_{yk} = - \sum_{i < j} e_{ij} L_{ij}^k$ , we arrive at

$$\begin{aligned} \Gamma_{y,s} \delta(\langle \vec{u}, \omega \rangle) &= |\vec{y}_1| \dots |\vec{y}_s| \Gamma_{y,s} (\delta(\langle \vec{u}, \vec{y}_1 \rangle) \dots \delta(\langle \vec{u}, \vec{y}_s \rangle)) \\ &= (\vec{u} \wedge \sum_{k=1}^s \vec{\omega}_k \delta'(\langle \vec{u}, \vec{\omega}_k \rangle) \prod_{j \neq k} \delta(\langle \vec{u}, \vec{\omega}_j \rangle)) | \tilde{R}_{m,s}. \end{aligned}$$

On the other hand, for  $\langle \vec{\omega}_h, \vec{\omega}_j \rangle = \delta_{kj}$ , i.e. on  $K$ ,

$$\sum_{k=1}^s \vec{\omega}_k \langle \vec{\omega}_k, D_u \rangle \delta(\langle \vec{u}, \omega \rangle) = \sum_{k=1}^s \vec{\omega}_k \delta'(\langle \vec{u}, \vec{\omega}_k \rangle) \prod_{j \neq k} \delta(\langle \vec{u}, \vec{\omega}_j \rangle),$$

which, in view of Lemma 1, leads to the stated identity. ■

This leads to the angular Darboux equations.

Theorem 4. For  $s$  odd (resp.  $s$  even), we have that

$$D_{\pm}(\omega) P^S(f) = \frac{1}{r} (s - \Gamma_{y,s}) Q^S(f),$$

$$D_{\pm}(\omega) Q^S(f) = \frac{1}{r} \Gamma_{y,s} P^S(f).$$

Proof. We have that  $\vec{u} \wedge D_{\pm}(\omega) = \sum_{k=1}^s \langle \vec{\omega}_k, D_u \rangle \vec{u} \wedge \vec{\omega}_k = 0$ , so that, in view of Lemma 2,

$$\begin{aligned} &\Gamma_{y,s} P^S(f)(\vec{x}, r\omega) \\ &= \frac{1}{\omega_{m-s}} \int_{S^{m-1}} \vec{u} \wedge (D_{\pm}(\omega) \delta(\langle \vec{u}, \omega \rangle)) f(\vec{x} + r\vec{u}) dS_u \\ &= -\frac{1}{\omega_{m-s}} \int_{S^{m-1}} \delta(\langle \vec{u}, \omega \rangle) \vec{u} \wedge \left( r \sum_{k=1}^s \vec{\omega}_k \langle \vec{\omega}_k, D_x \rangle \right) f(\vec{x} + r\vec{u}) dS_u \\ &= r D_{\pm}(\omega) Q^S(f)(\vec{x}, r\omega), \end{aligned}$$

since for  $\vec{u} \perp \vec{\omega}_k$ ,  $\vec{u} \wedge \vec{\omega}_k = -\vec{\omega}_k \wedge \vec{u} = -\vec{\omega}_k \vec{u}$ .

Similarly, as  $D_{\pm}(\omega) \vec{u} = \sum_{k=1}^s \vec{\omega}_k \langle \vec{\omega}_k, P_u' \rangle \vec{u} = -s$ ,

$$\begin{aligned} \Gamma_{y,s} Q^S(f)(\vec{x}, r\omega) &= -\frac{1}{\omega_{m-s}} \int_{S^{m-1}} \delta(\langle \vec{u}, \omega \rangle) \vec{u} \wedge D_{\pm}(\omega)(\vec{u}f(x+r\vec{u})) dS_u \\ &= sQ^S(f) - rD_{\pm}(\omega)P^S(f). \quad \blacksquare \end{aligned}$$

Notice that for  $s$  odd (resp.  $s$  even),  $D_{\pm}(\omega)$  commutes with both  $P^S$  and  $Q^S$ , while  $D_{\pm}(\omega)$  commutes with  $P^S$  and anticommutes with  $Q^S$ . Hence Theorems 3 and 4 lead to the system

$$P^S(D_X f) = \left(\frac{\partial}{\partial r} - \frac{1}{r} \Gamma_{y,s}\right) Q^S(f) + \frac{m-1}{r} Q^S(f),$$

$$Q^S(D_X f) = -\left(\frac{\partial}{\partial r} + \frac{1}{r} \Gamma_{y,s}\right) P^S(f) \dots$$

Furthermore, for  $s$  even  $D_+(\omega)$  anticommutes with  $\omega$ , while for  $s$  odd  $D_-(\omega)$  commutes with  $\omega$ . This means that for  $s$  even (resp.  $s$  odd)  $D_X$  commutes (resp. anticommutes) with  $Q^S$ . Hence the second Darboux equations may be written as

$$D_X \omega Q^S(f) = (-1)^{s+1} \omega \left(\frac{\partial}{\partial r} + \frac{1}{r} \Gamma_{y,s}\right) P^S(f).$$

Next, put  $y=r\omega$ . Then we shall establish an expression for  $\Gamma_{y,s}(yf(y))$  in terms of  $y\Gamma_{y,s}(f(y))$  and  $yf(y)$ . This corresponds to the hypercomplex refinement of the Kelvin inversion, given by  $\Gamma(\vec{y}f(\vec{y})) = -\vec{y}\Gamma_{y,s}f(\vec{y}) + m\vec{y}f(\vec{y})$ , so that the map  $f(\vec{y}) \rightarrow \frac{\vec{y}}{|\vec{y}|^m} f\left(\frac{\vec{y}}{|\vec{y}|^2}\right)$  pre-

serves monogenicity and changes inner spherical monogenics into outer spherical monogenics and vice versa (see [7], [9], [13]). First we prove

Lemma 3. Let  $\omega = \vec{\omega}_1 \dots \vec{\omega}_s \in \tilde{G}_{m,s}(R)$  and let  $(\vec{u}_1, \dots, \vec{u}_{m-s})$  be a local orthonormal frame, orthogonal to  $\omega$ . Then  $\Gamma_{y,s}$  is locally given by

$$\Gamma_{y,s} = r \sum_{j,k} (-1)^k \vec{\omega}_k \vec{u}_j \langle \vec{u}_j \hat{\omega}_k, D_{m,s} \rangle,$$

where  $r\omega = y$  and  $\hat{\omega}_k = \vec{\omega}_1 \dots \vec{\omega}_{k-1} \vec{\omega}_{k+1} \dots \vec{\omega}_s$ .

Proof. Let us recall that  $\Gamma_{y,s}$  is given by  $\Gamma_{y,s} = \frac{1}{2} [ \bar{y} D_{m,s} + y \bar{D}_{m,s} ]_2$ .

Next, consider local orthonormal frames  $(\vec{\omega}_1, \dots, \vec{\omega}_s)$  and  $(\vec{u}_1, \dots, \vec{u}_{m-s})$  such that  $\vec{\omega} = \vec{\omega}_1 \dots \vec{\omega}_s$  and  $(\vec{u}_1, \dots, \vec{u}_{m-s})$  is orthogonal to  $\omega$ . Then it is easy to see that

$$D_{m,s} = \omega \langle \omega, D_{m,s} \rangle + \sum_{j,k} \vec{u}_j \hat{\omega}_k \langle \vec{u}_j \hat{\omega}_k, D_{m,s} \rangle + L_{m,s},$$

where  $L_{m,s}$  is normal to  $\tilde{R}_{m,s}$ . Hence, as  $y=r\omega$  and  $\bar{y}=r\bar{\omega}$ , we obtain that

$$[\bar{y}D_{m,s}]_2 = r \sum_{j,k} [\bar{\omega} \vec{u}_j \hat{\omega}_k]_2 \langle \vec{u}_j \hat{\omega}_k, D_{m,s} \rangle,$$

$$[y\bar{D}_{m,s}]_2 = r \sum_{j,k} [\overline{\omega \vec{u}_j \hat{\omega}_k}]_2 \langle \vec{u}_j \hat{\omega}_k, D_{m,s} \rangle,$$

since  $[\bar{\omega}L_{m,s}]_2 = [\omega\bar{L}_{m,s}]_2 = 0$ .

Now  $\vec{u}_j \hat{\omega}_k = (-1)^{s-1} \hat{\omega}_k \vec{u}_j$  and  $\bar{\omega} = (-1)^{s-k} \bar{\omega}_k \bar{\omega}_k$ , so that  $\overline{\omega \vec{u}_j \hat{\omega}_k} = (-1)^k \bar{\omega}_k \vec{u}_j$ .

On the other hand,  $\omega = (-1)^{k-1} \hat{\omega}_k \hat{\omega}_k$  so that  $\overline{\omega \vec{u}_j \hat{\omega}_k} = (-1)^{k-1} \bar{\omega}_k \vec{u}_j = (-1)^k \bar{\omega}_k \vec{u}_j$ . This leads to the stated lemma. ■

Theorem 5. Let  $f(y)$  be a function on  $\tilde{R}_{m,s}$ . Then we have that

$$\Gamma_{y,s} y f(y) = -y \Gamma_{y,s} f(y) + s(m-s) y f(y).$$

Proof. Putting  $y = \sum_A y_A e_A$ , we have that

$$\Gamma_{y,s} y f(y) = \sum_{|A|=s} y_A \Gamma_{y,s} e_A f(y) + \Gamma_{y,s}(y) f(y).$$

For  $s$  odd,  $\omega$  commutes with  $\vec{\omega}_k$  and anticommutes with  $\vec{u}_j$ , whereas for  $s$  even,  $\omega$  commutes with  $\vec{u}_j$  and anticommutes with  $\vec{\omega}_k$ . Hence we obtain that

$$\sum_{|A|=s} y_A \Gamma_{y,s} e_A f(y) = r \sum_{j,k} (-1)^k \bar{\omega}_k \vec{u}_j (r\omega) \langle \vec{u}_j \hat{\omega}_k, D_{m,s} \rangle f(y)$$

$$= -y \Gamma_{y,s} f(y).$$

Furthermore we have that

$$\Gamma_{y,s} y = r \sum_{j,k} (-1)^k \bar{\omega}_k \vec{u}_j \sum_{|A|=s} \langle \vec{u}_j \hat{\omega}_k, e_A \rangle e_A$$

$$= r \sum_{j,k} \omega = s(m-s) y. \quad \blacksquare$$

In order to establish the complete system of Darboux equations, we

introduce a new differential operator.

Definition 4. The operator  $D_y$  on  $\tilde{R}_{m,s}$  is given by  $D_y = \omega(\frac{\partial}{\partial r} + \frac{1}{r}\Gamma_{y,s})$ .

Proposition 1. Let  $\vec{\omega}_1 \dots \vec{\omega}_s = \omega$  and let  $(\vec{u}_1, \dots, \vec{u}_{m-s})$  be an orthonormal basis, orthogonal to  $\omega$ . Then we have that

$$D_y = \omega \langle \omega, D_{m,s} \rangle + \sum_{j,k} \vec{u}_j \hat{\omega}_k \langle \vec{u}_j \hat{\omega}_k, D_{m,s} \rangle,$$

or, in other words,  $D_y$  is the projection of  $D_{m,s}$ , tangent to  $\tilde{R}_{m,s}$ .

Proof. This follows easily from the fact that

$$\frac{\partial}{\partial r} = \langle \omega, D_{m,s} \rangle \text{ and } (-1)^k \omega \vec{\omega}_k \vec{u}_j = (-1)^k \vec{u}_j \vec{\omega}_k \omega = \vec{u}_j \hat{\omega}_k$$

and the fact that an orthonormal basis for the tangent space of  $\tilde{R}_{m,s}$  in  $R_{m,s}$  is given by  $\{\omega, \vec{u}_j \hat{\omega}_k : j, k\}$ . ■

Notice that if  $f$  is a  $C_1$ -function in a neighbourhood  $\Omega$  of a point of  $\tilde{R}_{m,s}$  such that in  $\Omega \cap \tilde{R}_{m,s}$  all normal derivations to  $\tilde{R}_{m,s}$  of  $f$  vanish, then  $D_y(f|_{\tilde{R}_{m,s}}) = (D_{m,k}f)|_{\tilde{R}_{m,s}}$ . We now have the Darboux system.

Theorem 5. The spherical means of codim  $s+1$  satisfy the system

$$D_x P^s(f) = (-1)^{\frac{s(s+1)}{2}} (D_y + \frac{(s-1)(s+1-m)\omega}{r}) \omega Q^s(f),$$

$$D_x \omega Q^s(f) = (-1)^{s+1} D_y P^s(f).$$

Proof. As  $\omega^2 = (-1)^{\frac{s(s+1)}{2}}$ , we have that

$$\begin{aligned} & (\frac{\partial}{\partial r} - \frac{1}{r}\Gamma_{y,s}) Q^s(f) \\ &= (-1)^{\frac{s(s+1)}{2}} (\frac{\partial}{\partial r} - \frac{1}{r}\Gamma_{y,s}) \omega \cdot \omega Q^s(f) \\ &= (-1)^{\frac{s(s+1)}{2}} [D_y \omega Q^s(f) - \frac{s(m-s)}{r} \omega^2 Q^s(f)], \end{aligned}$$

while clearly

$$D_x \omega Q^s(f) = (-1)^{s+1} D_y P^s(f). \quad \blacksquare$$

General spherical means of codimension  $s+1$  are introduced as follows. First, denote for  $\omega \in \tilde{G}_{m,s}(R), M_{\pm,k}(\omega)$  the right-module of inner (outer)

spherical monogenics of degree  $k$  on  $S_\omega = \{\vec{u} \in S^{m-1}; \langle \vec{u}, \omega \rangle = 0\}$ .  
Let  $P_{k,\omega}$  be the projection on  $M'_{+,k}(\omega)$  and put

$$M_k(\omega) = M_{+,k}(\omega) + M_{-,k}(\omega), H_k(\omega) = M_{+,k}(\omega) + M_{-,k-1}(\omega);$$

then the projections on  $M_k(\omega)$  and  $S_k(\omega)$  are denoted by  $\Pi_{k,\omega}$  and  $S_{k,\omega}$ .

**Definition 5.** Let  $f$  be a continuous function in  $\Omega \subset \mathbb{R}^m$ . Then the  $k$ -th inner and outer spherical means of codim  $s+1$  of  $f$  are defined by

$$P_{+,k}^S f(\vec{x}, r\omega) = P_{k,\omega}(f(\vec{x} + r\vec{u})),$$

$$P_{-,k}^S f(\vec{x}, r\omega) = P_{k,\omega}(\vec{u}f(\vec{x} + r\vec{u})),$$

and are considered as sections of  $M_{+,k}(\omega)$  such that  $(\vec{x}, r\omega) \in \hat{\Omega}_S$ .

Notice that, if  $\vec{v}$  is the unit normal on  $S_\omega$ ,  $\theta = \langle \vec{u}, \vec{v} \rangle$ , then  $P_{+,k}^S$  is given by

$$\begin{aligned} & P_{+,k}^S(f)(\vec{x}, r\omega)(\vec{v}) \\ &= \frac{1}{\omega_{m-s}} \int_{S^{m-1}} \int_1^s \delta(\langle \vec{u}, \vec{\omega}_j \rangle) (C_k^{\frac{m-s}{2}}(\theta) + \vec{v}\vec{u}C_{k-1}^{\frac{m-s}{2}}(\theta)) f(r\vec{u} + \vec{x}) dS_{\mathbb{U}}. \end{aligned}$$

Furthermore, the radial Darboux equations are given by ( $s$  being even and odd respectively)

$$P_{+,k}^S(D_{\pm}(\omega)f) = \left(\frac{\partial}{\partial r} + \frac{k+m-s-1}{r}\right) P_{-,k}^S(f),$$

$$P_{-,k}^S(D_{\pm}(\omega)f) = \left(-\frac{\partial}{\partial r} + \frac{k}{r}\right) P_{+,k}^S(f).$$

The construction of angular Darboux equations is similar to the one in section 2 and uses the operator  $\Gamma_{y,s}$ . To that end, let

$$S_{+,k}^S(f) = P_{+,k}^S(f) - \vec{v}P_{-,k-1}^S(f), S_{-,k}^S(f) = P_{-,k}^S(f) + \vec{v}P_{+,k-1}^S(f).$$

We then obtain

**Proposition 2.** For  $s$  even (resp.  $s$  odd),  $S_{+,k}^S$  and  $S_{-,k}^S$  satisfy the angular Darboux system

$$D_{\mp}(\omega)S_{+,k}^S(f) = \frac{1}{r}(s - \Gamma_{y,s})S_{-,k}^S(f),$$

$$D_{\pm}(\omega)S_{-,k}^S(f) = \frac{1}{r}\Gamma_{y,s}S_{+,k}^S(f).$$

This finally leads to the complete Darboux system.

Theorem 7. The  $k$ -th spherical harmonic means of codimension  $s+1$  satisfy the system

$$D_x S_{+,k}^S(f) = (-1)^{\frac{s(s+1)}{2}} \left( D_y + \frac{(s-1)(s+1-m)\omega - \omega\Gamma_y}{r} \right) \omega S_{-,k}^S(f),$$

$$D_x \omega S_{-,k}^S(f) = (-1)^{s+1} \left( D_y - \frac{\omega\Gamma_y}{r} \right) S_{+,k}^S(f).$$

Proof. The radial and angular Darboux equations already lead to the system

$$S_{+,k}^S(D_x f) = \left( \frac{\partial}{\partial r} - \frac{1}{r}\Gamma_{y,s} + \frac{m-1}{r} - \frac{\Gamma_y}{r} \right) S_{-,k}^S(f),$$

$$S_{-,k}^S(D_x f) = - \left( \frac{\partial}{\partial r} + \frac{1}{r}\Gamma_{y,s} + \frac{1}{r}\Gamma_y \right) S_{+,k}^S(f).$$

The rest follows easily from the fact that  $D_x$  commutes with  $S_{+,k}^S$  while

$$S_{-,k}^S(D_{\mp}(\omega)f) = -D_{\mp}(\omega)S_{-,k}^S(f),$$

$$S_{-,k}^S(D_{\pm}(\omega)f) = D_{\pm}(\omega)S_{-,k}^S(f) - \frac{2\Gamma_y}{r}S_{+,k}^S(f),$$

so that

$$\omega S_{+,k}^S(D_x f) = (-1)^s D_x \omega S_{-,k}^S(f) - 2\frac{\omega\Gamma_y}{r}S_{+,k}^S(f). \blacksquare$$

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State University of Ghent  
Seminar of Algebra and Functional analysis  
Galglaan 2  
B-9000 Gent, Belgium.