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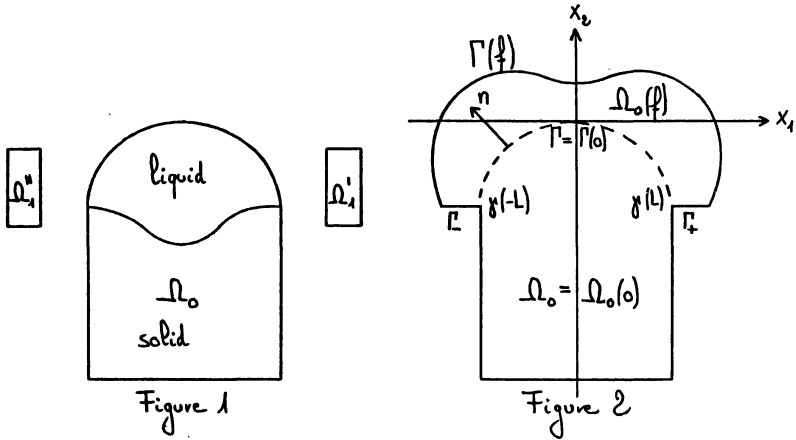
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# AN ELECTROMAGNETIC FREE-BOUNDARY PROBLEM

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A section of the electromagnetic casting (EMC) device is schematically represented in Figure 1.  $\Omega_0$  represents the ingot (aluminium) with a solid part and a liquid part. An alternating current runs along the inductors  $\Omega_1', \Omega_1''$ ; it induces an electromagnetic field which, in its turn, produces Laplace forces in the ingot; these forces compensate the action of the gravity and maintain the liquid metal in equilibrium. The interface liquid-air is the main unknown of the problem. The ingot is supposed to be infinitely long so that the free boundary problem is two dimensional.

In Figure 2,  $\Omega_0$  is a given approximation of the section of this ingot at equilibrium;  $\partial\Omega_0$  is smooth except at the two corners at the bottom.  $\Gamma \subset \partial\Omega_0$  (dotted line) is the interface and we suppose that  $0 \in \Gamma$ .  $\Omega = \Omega_0 \cup \Omega_1$ , where  $\Omega_1 = \Omega_1' \cup \Omega_1''$ , is symmetric with respect to the  $x_2$ -axis.  $\Gamma$  admits the parametrization  $x = (x_1, x_2) = \gamma(\xi)$ ,  $-L \leq \xi \leq L$ , where  $\xi$  is the arc length parameter. The unit exterior normal is denoted by  $n(\xi) = (n_1(\xi), n_2(\xi))$ . We introduce, in the neighbourhood of  $\Gamma$ , the orthogonal curvilinear system of coordinates  $(\xi, \eta)$  defined by the relation  $x = \gamma(\xi) + \eta n(\xi)$ . Let  $W = \{f \in C^0[-L, L] \mid \|f\| < \varepsilon\}$  where  $\|\cdot\|$  is the uniform norm and  $\varepsilon > 0$  is chosen small enough in accordance to the geometry. For  $f \in W$ , let  $\Gamma(f)$  be defined by the parametrization  $x = \gamma(\xi) + f(\xi) n(\xi)$ ,  $-L \leq \xi \leq L$ .  $\Omega_0(f)$  is then defined as the domain with boundary  $(\partial\Omega_0 - \Gamma) \cup \Gamma(f) \cup \Gamma_{\pm} \cup \Gamma$ , where  $\Gamma_{\pm}$  are the two horizontal segments described in Figure 2. Finally we set  $\Omega(f) = \Omega_0(f) \cup \Omega_1$ .

We rely on [1], [2], [3] for a justification of the mathematical model. Let  $W_0^1(\mathbb{R}^2)$  be the completion of  $C^\infty(\mathbb{R}^2)$  (complex functions) for the norm  $\|v\|_{W_0^1(\mathbb{R}^2)} = \int_{\mathbb{R}^2} |\nabla v|^2 + \int_{\Omega_0} |v|^2$  (see [1] for details). For  $f \in W$ , we define  $a(f) : W_0^1(\mathbb{R}^2) \times W_0^1(\mathbb{R}^2) \rightarrow \mathbb{C}$ ,  $b(f) : W_0^1(\mathbb{R}^2) \rightarrow \mathbb{C}$ :

$$a(f)(u,v) = \int_{\mathbb{R}^2} \nabla u \cdot \nabla \bar{v} - 2i \alpha^2 \int_{\Omega} u \bar{v}, \quad b(f)(v) = 2i \alpha^2 \int_{\Omega_1} d \bar{v}. \quad (1)$$

Here  $\alpha$  is a (large) real constant depending on the conductivity of the metal and on the frequency of the currents.  $i$  is the complex unit,  $\bar{v}$  is the complex conjugate of  $v$ .  $d : \Omega_1 \rightarrow \mathbb{R}$  is a real odd function with respect to  $x_1$ , the restrictions of which on  $\Omega_1'$  and  $\Omega_1''$  are constant;  $d$  is related to the intensity of the current running in the inductors.

The proofs of the results stated in this paper can be found in [2].

Proposition 1 . For  $f \in W$ , there exists a unique  $\varphi(f) \in W_0^1(\mathbb{R}^2)$  such that

$$a(f)(\varphi(f),v) = b(f)(v), \quad \forall v \in W_0^1(\mathbb{R}^2). \quad (2)$$

$\varphi(f)$  is a potential the bidimensional curl of which is the magnetic field. In the neighbourhood of  $\Gamma$ ,  $\varphi(f)$  will be considered as a function of the curvilinear coordinates  $(\xi,\eta)$ . For  $f \in W$ ,  $H(f)$  is the function defined on  $\Gamma(f)$  by

$$H(f)(\xi) = \frac{1}{2} C_m | \varphi(f)(\xi, f(\xi)) |^2 + C_g x_2(\xi, f(\xi)). \quad (3)$$

The first term in (2) represents an approximation of the "magnetic pressure" on  $\Gamma(f)$ ; the second term gives the pressure due to the gravity;  $C_m$  and  $C_g$  are positive constants. The equilibrium is obtained when the total pressure  $H(f)$  is constant along  $\Gamma(f)$ . Due to an industrial constraint explained in [2], this constant vanishes in our case. Consequently, our problem is to find  $f \in W$  such that  $H(f) = 0$ . Because of the complexity of the geometry, it seems to us not realistic to prove a mathematical existence theorem. We however have the following results.

We consider  $a$ ,  $\varphi$  and  $H$  as function defined on  $W$  with values in the sesquilinear forms on  $(W_0^1(\mathbb{R}^2))^2$  forms, in  $W_0^1(\mathbb{R}^2)$  and in  $C^0[-L,L]$ , respectively. Let  $D$  and  $\partial_\eta$  denote the Fréchet derivative with respect to  $f$  and the partial derivative with respect to  $\eta$  in the coordinate system  $(\xi,\eta)$ .  $J(\xi,\eta)$  will denote the jacobian of the transformation  $(\xi,\eta) \rightarrow (x_1,x_2)$ .

Proposition 2

a) For any bounded domain  $\Lambda \subset \mathbb{R}^2$  and any  $2 \leq p \leq \infty$ , one has

$$\varphi \in C^1(W, W_0^1(\mathbb{R}^2)) \cap C^1(W, W^{1,p}(\Lambda)) \cap C^0(W, W^{2,p}(\Lambda)).$$

b) For  $h \in C^0[-L, L]$ ,  $D\phi[h]$  is characterized by the variational equality

$$a(f) (D\phi(f)[h], v) = - Da(f)[h](\phi(f), v), \quad \forall v \in W_0^1(\mathbb{R}^2), \quad (4)$$

where  $Da(f)[h](u, v) = -2i \alpha^2 \int_{-L}^L J(\xi, f(\xi)) \cdot h(\xi) \cdot u(\xi, f(\xi)) \cdot \bar{v}(\xi, f(\xi)) d\xi$ .

### Proposition 3

a) There exists  $0 < \mu < 1$  such that  $H \in C^{1,\mu}(W, C^0[-L, L])$ .

b)  $DH(f)[h](\xi) = C_m \operatorname{Re} \{ \bar{\phi}(f)(\xi, f(\xi)) \cdot (D\phi(f)[h](\xi, f(\xi)) + \partial_{\eta} \phi(f)(\xi, f(\xi)) \cdot h(\xi)) \} + C_g h(\xi) \eta_2(\xi)$ .

It can be shown that  $DH(f)$  can be expressed as the sum of a compact operator and a multiplication operator of the form  $r(\xi)h(\xi)$ , where  $r \in C^0[-L, L]$ . A physical analysis shows that it is realistic to suppose that  $r(\xi) \neq 0, \forall \xi \in [-L, L]$ . Under this hypothesis  $DH(f)$  is a Fredholm operator.

Proposition 3 suggests the use Newton's method for solving the equation  $H(f) = 0$ . Numerically, this implies the discretization of (2) and (4); this has been realized efficiently in [2] with boundary elements; 90 % of the time necessary to compute one iteration is used for determining  $\phi$  in (2). Numerical experiments for concrete situations show a very fast convergence; three Newton iterations are generally sufficient.

For more details and other approaches to the EMC problem, see [2], [3].

### References

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