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## ADDITION TO MY PAPER "GENERALIZED ORDINARY DIFFERENTIAL EQUATIONS AND CONTINUOUS DEPENDENCE ON A PARAMETER"

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### (Received December 8, 1958)

This paper contains an improved treatment of section 3 of [1]. It follows that the results of section 4 of [1] are valid in a more general form. Further the results of section 5,1 [1] are formulated and proved in a correct way.

We shall use definitions and notations introduced in [1].

1. We shall give new proofs of Theorems 3.1 and 3.2 [1]. In these proofs weaker assumptions concerning the monotonity properties of  $\psi(\eta)$  are needed.

Let  $\psi(\eta)$  be defined for  $0 \leq \eta \leq \sigma$ ,  $(\sigma > 0)$ ,  $\psi(0) = 0$ ,  $\psi(\eta) \geq 0$ . Let

$$\sum_{j=1}^{\infty} 2^{j} \psi\left(\frac{\eta}{2^{j}}\right) \tag{1}$$

converge uniformly. (This assumption is specially fulfilled if  $\psi(\eta)$  is nondecreasing and  $\sum_{i=1}^{\infty} 2^{j} \psi\left(\frac{\sigma}{2^{j}}\right) < \infty$ .) Let us put  $arPsi_{n}(\eta) = \sum_{i=1}^{\infty} rac{2^{j}}{\eta} \, \psi\left(rac{\eta}{2^{j}}
ight) \, \, ext{ for } \, \, 0 < \eta \leqq \sigma \, , \ \ arPsi_{n}(0) = 0 \, .$  $\text{If } \frac{\sigma}{2^{k+1}} \leq \eta \leq \frac{\sigma}{2^k} \left( k = 0, \, 1, \, 2, \, \ldots \right), \quad \zeta = 2^k \eta, \quad \text{then} \quad \varPsi(\eta) = \sum_{j=1}^\infty \frac{2^j}{\zeta} \, \psi\left(\frac{\zeta}{2^j}\right).$ 

As (1) convergences uniformly, it follows, that  $\Psi(\eta) \to 0$  for  $\eta \to 0 +$ .

Let  $\tau_* < \tau^* \leq \tau_* + \sigma$ . Let Q be the square  $\tau_* \leq t \leq \tau^*, \tau_* \leq \tau \leq \tau^*$ . Let  $V(\tau, t)$  be defined on  $Q, \tau_* \leq \lambda_1 < \lambda_2 \leq \tau^*$ . Let us denote

$$S_{i}(V; \lambda_{1}, \lambda_{2}) = S_{i} = \sum_{j=0}^{2i-1} [V(\zeta_{j}, \zeta_{j+1}) - V(\zeta_{j}, \zeta_{j})], \qquad (1a)$$

$$Z_{i}(V; \lambda_{1}, \lambda_{2}) = Z_{i} = \sum_{j=0}^{2i-1} [V(\zeta_{j+1}, \zeta_{j+1}) - V(\zeta_{j+1}, \zeta_{j})]$$
(1b)

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where

$$\zeta_{j} = \lambda_{1} + rac{j}{2^{i}} (\lambda_{2} - \lambda_{1}) \,, \;\; j = 0, \, 1, \, 2, \, ..., \, 2^{i} \,.$$

**Lemma 1.** If  $\frac{\partial V}{\partial t} = v(\tau, t)$  is continuous and if  $|v(\tau, t) - v(\tau', t)| \leq C|\tau - \tau'|$ for  $\tau, \tau', t \in \langle \tau_*, \tau^* \rangle$ , then  $\int_{\lambda_1}^{\lambda_2} DV$  exists and

$$\int_{\lambda_1}^{\lambda_2} \mathrm{D}V = \int_{\lambda_1}^{\lambda_2} v(\tau, \tau) \,\mathrm{d}\tau \,, \tag{2}$$

$$\int_{i_1}^{\lambda_2} \mathrm{D}V = \lim_{i \to \infty} S_i = \lim_{i \to \infty} Z_i \,. \tag{3}$$

Proof. Let  $h(t) = \int_{\lambda_1}^t v(\tau, \tau) \, \mathrm{d}\tau$ . As

$$egin{aligned} |h(t)-h( au)-V( au,t)+V( au, au)|&=\left|\int\limits_{ au}^{t}v(\xi,\,\xi)\,\mathrm{d}\xi-\int\limits_{ au}^{ au}v( au,\,\xi)\,\mathrm{d}\xi
ight|&\leq&\ &\leq&rac{C}{2}\,|t- au|^2\,, \end{aligned}$$

it follows, that  $h(t) + \epsilon t$  (resp.  $h(t) - \epsilon t$ ),  $\epsilon > 0$  is an upper (lower) function of V, the integral  $\int_{\lambda_1}^{\lambda_2} DV$  exists and (2) holds (cf. [1], section 1,1). Further

$$\left|\int_{\lambda_1}^{\lambda_2} \mathrm{D}V - S_i\right| = \left|\sum_{j=0}^{2i-1} \left[\int_{\zeta_j}^{\zeta_{j+1}} v(\tau,\tau) \,\mathrm{d}\tau - \int_{\zeta_j}^{\zeta_{j+1}} v(\zeta_j,\tau) \,\mathrm{d}\tau\right]\right| \leq \sum_{j=0}^{2i-1} \int_{\zeta_j}^{\zeta_{j+1}} C(\tau-\zeta_j) \,\mathrm{d}\tau =$$
$$= \frac{C}{2} \frac{(\lambda_2 - \lambda_1)^2}{2^i}.$$

Similarly

$$\left|\int_{\lambda_{1}}^{\lambda_{2}} \mathrm{D}V - Z_{i}\right| \leq \frac{C}{2} \frac{(\lambda_{2} - \lambda_{1})^{2}}{2^{i}}$$

and (3) holds.

**Theorem 1.** Let  $U(\tau, t)$  be defined and continuous on Q and let

$$|U( au+\eta,t+\eta)-U( au+\eta,t)-U( au,t+\eta)+U( au,t)|\leq arphi(\eta)$$

 $\text{ if } 0 < \eta \leq \sigma \text{ and if } (\tau + \eta, t + \eta), \ (\tau + \eta, \tau), \ (\tau, t + \eta), \ (\tau, t) \in Q. \ Then \int_{\tau_*}^{\tau^*} DU \\$ 

exists and

$$\left|\int_{\lambda_1}^{\lambda_2} DU - U(\lambda_1, \lambda_2) + U(\lambda_1, \lambda_1)\right| \leq \frac{1}{2}(\lambda_2 - \lambda_1) \Psi(\lambda_2 - \lambda_1) , \qquad (4)$$

$$\left|\int_{\lambda_1}^{\lambda_2} DU - U(\lambda_2, \lambda_2) + U(\lambda_2, \lambda_1)\right| \leq \frac{1}{2}(\lambda_2 - \lambda_1) \Psi(\lambda_2 - \lambda_1)$$
(5)

for  $\tau^* \leq \lambda_1 < \lambda_2 \leq \tau^*$ .

**Proof.** By a usual approximating process we find such a sequence of functions  $U_k(\tau, t)$  on Q that

- i)  $U_k(\tau, t)$  has continuous derivatives of the second order,
- ii)  $U_k(\tau, t) \rightarrow U(\tau, t)$  uniformly,

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iii) for every  $\vartheta > 0$  there is such a  $K(\vartheta)$ , that

$$|U_k( au+\eta,t+\eta)-U_k( au+\eta,t)-U_k( au,t+\eta)+U_k( au,t)|\leq \psi(\eta)$$

 $\mathbf{i}\mathbf{f}$ 

$$k > K(\vartheta), \ au_* + \vartheta \leq au < au + \eta \leq au^* - artheta, \ au_* + artheta \leq t < t + \eta \leq au^* - artheta.$$

Let

$$artheta > 0 \ , \ \ au_{m{*}} + artheta \leqq \lambda_1 < \lambda_2 \leqq au^{m{*}} - artheta \ .$$

According to Lemma 1  $\int_{\lambda_1}^{\lambda_2} DU_k$  exists and  $\int_{\lambda_1}^{\lambda_2} DU_k = \lim_{i \to \infty} S_i(U_k, \lambda_1, \lambda_2).$ 

$$S_{i+1}(U_k; \lambda_1, \lambda_2) - S_i(U_k; \lambda_1, \lambda_2) =$$

$$= \sum_{j=0}^{2^{i-1}} \left[ U_k(\xi_j, \xi_j + \eta) - U_k(\xi_j, \xi_j) - U_k(\xi_j - \eta, \xi_j + \eta) + U_k(\xi_j - \eta, \xi_j) \right],$$

$$\xi_j = \lambda_1 + \frac{j}{2^i} \left( \lambda_2 - \lambda_1 \right) + \frac{\lambda_2 - \lambda_1}{2^{i+1}}, \quad \eta = \frac{\lambda_2 - \lambda_1}{2^{i+1}}.$$

If  $k > K(\vartheta)$ , then

$$|S_{i+1}(U_k;\lambda_1,\lambda_2)-S_i(U_k;\lambda_1,\lambda_2)|\leq 2^i\psi\left(rac{\lambda_2-\lambda_1}{2^{i+1}}
ight)$$

and

$$\left| \int_{\lambda_{1}}^{\lambda_{2}} \mathrm{D}U_{k} - U_{k}(\lambda_{1}, \lambda_{2}) + U_{k}(\lambda_{1}, \lambda_{1}) \right| = \lim_{i \to \infty} S_{i} - S_{0} \leq \sum_{i=0}^{\infty} |S_{i+1} - S_{i}| \leq \sum_{i=0}^{\infty} 2^{i} \psi \left( \frac{\lambda_{2} - \lambda_{1}}{2^{i+1}} \right) = \frac{1}{2} \left( \lambda_{2} - \lambda_{1} \right) \Psi(\lambda_{2} - \lambda_{1}) .$$
 (6)

Similarly

$$\left| \int_{\lambda_1}^{\lambda_2} DU_k - U_k(\lambda_2, \lambda_2) + U_k(\lambda_2, \lambda_1) \right| \leq \frac{1}{2} (\lambda_2 - \lambda_1) \, \Psi(\lambda_2 - \lambda_1) \,. \tag{7}$$

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Let  $0 < \delta \leq \sigma$  and let  $A = \{\alpha_0, \tau_1, \alpha_1, ..., \tau_s, \alpha_s\}$  be such a subdivision of  $\langle \lambda_1, \lambda_2 \rangle$  (i. e.  $\lambda_1 = \alpha_0 < \alpha_1 < \cdots < \alpha_s = \lambda_2$ ,  $\alpha_0 \leq \tau_1 \leq \alpha_1 \leq \cdots \leq \alpha_{s-1} \leq \tau_s \leq \alpha_s$ ) that

$$\tau_j - \alpha_{j-1} \leq \delta$$
,  $\alpha_j - \tau_j < \delta$ . (8)

Let us put

$$R(V, A) = \sum_{j=1}^{s} \left[ V(\tau_j, \alpha_j) - V(\tau_j, \alpha_{j-1}) \right].$$

Then

$$\left|\int_{\lambda_1}^{\lambda_2} \mathrm{D} U_k - R(U_k, A)\right| =$$

$$= \left|\sum_{j=1}^{s} \left[\int_{\alpha_{j-1}}^{\tau_{j}} \mathrm{D}U_{k} - U_{k}(\tau_{j}, \tau_{j}) + U_{k}(\tau_{j}, \alpha_{j-1}) + \int_{\tau_{j}}^{\alpha_{j}} \mathrm{D}U_{k} - U_{k}(\tau_{j}, \alpha_{j}) + U_{k}(\tau_{j}, \tau_{j})\right]\right| \leq \sum_{j=1}^{s} \frac{1}{2} \left[(\tau_{j} - \alpha_{j-1}) \Psi(\tau_{j} - \alpha_{j-1}) + (\alpha_{j} - \tau_{j}) \Psi(\alpha_{j} - \tau_{j})\right] \leq \\ \leq \frac{\lambda_{2} - \lambda_{1}}{2} \sup_{0 < t \leq \delta} \Psi(t) \ .$$

If  $A_1$ ,  $A_2$  are subdivisions of  $\langle \lambda_1, \lambda_2 \rangle$  which fulfil (8), then

$$|R(U_k, A_2) - R(U_k, A_1)| \leq (\lambda_2 - \lambda_1) \sup_{0 < t \leq \delta} \Psi(t) .$$
(9)

As  $U_k \to U$  it follows that  $R(U_k, A_1) \to R(U, A_1), R(U_k, A_2) \to R(U, A_2)$  and

$$|R(U, A_2) - R(U, A_1)| \leq (\lambda_2 - \lambda_1) \sup_{0 < t \leq \delta} \Psi(t) .$$
<sup>(10)</sup>

Consequently  $\int_{1}^{\lambda_2} DU$  exists as  $\Psi(\delta) \to 0$  with  $\delta \to 0.1$ )

<sup>1</sup>) Summarizing the results of [1], section 1 we obtain, that  $\int DV$  exists if and only if for every  $\varepsilon > 0$  there exists such a positive function  $\delta(\tau)$  that  $\lambda_1$ 

$$|R(V, A_2) - R(V, A_1)| < \varepsilon \tag{(*)}$$

if the subdivisions  $A_1 = \{\alpha_0, \tau_1, \alpha_1, ..., \tau_s, \alpha_s\}, A_2 = \{\alpha_0', \tau_1', \alpha_1', ..., \tau_{r'}, \alpha_{r'}'\}$  of  $\langle \lambda_1, \lambda_2 \rangle$  fulfil the conditions

$$\begin{aligned} &\tau_{j} - \alpha_{j-1} < \delta(\tau_{j}) , \quad \alpha_{j} - \tau_{j} < \delta(\tau_{j}) , \quad j = 1, 2, ..., s , \\ &\tau_{i}' - \alpha_{j-1} < \delta(\tau_{j}') , \quad \alpha_{j}' - \tau_{j}' < \delta(\tau_{j}') , \quad j = 1, 2, ..., r . \end{aligned}$$

In this case  $|\int_{\lambda_1}^{\lambda_2} DV - R(V, A_1)| \leq \varepsilon$ . Let  $\delta_1$  be such a positive constant, that  $(\lambda_2 - \lambda_1) \Psi(\delta) < \varepsilon$  for  $0 < \delta < \delta_1$ . We proved that (\*) is fulfilled for V = U (cf. (10)) if  $\delta(\tau) = \delta_1$ . As in this case ( $\delta(\tau) = \delta_1 = \text{const}$ ) (\*\*) is equivalent to the usual conditions (that the respective subdivisions  $A_1, A_2$  are fine  $\lambda_2$ enough) of the Riemann theory of integration, we may say, that  $\int_{\lambda}^{\lambda_1} DU$  exists in the sense of Riemann. of Riemann.

It follows from (9) and (10) that

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As  $\delta$  is arbitrary and  $R(U_k, A_1) \to R(U, A_1), \int_{\lambda_1}^{\lambda_2} \mathrm{D}U_k \to \int_{\lambda_1}^{\lambda_2} \mathrm{D}U.$ 

Passing to the limit for  $k \to \infty$  in (6) and (7) we obtain (4) and (5) with the additional assumption  $\tau_* < \lambda_1 < \lambda_2 < \tau^*$ .

Let  $\zeta \in (\tau_*, \tau^*)$ . As  $\int_{\zeta}^{\lambda} DU$  is uniformly continuous in  $\lambda$  on  $(\tau_*, \tau^*)$  and  $U(\tau, t)$  is continuous on Q,  $\int_{\lambda_1}^{\lambda} DU$  exists if  $\tau_* \leq \lambda_1 < \lambda_2 \leq \tau^*$  (cf. Theorem 1,3,5, [1]) and (4) and (5) hold for  $\tau_* \leq \lambda_1 < \lambda_2 \leq \tau^*$ . Theorem 1 is proved.

Let S be the set of such  $(\tau, t)$  that  $\tau_* \leq \tau \leq \tau^*$ ,  $\tau_* \leq t \leq \tau^*$ ,  $|\tau - t| \leq \sigma$ . **Theorem 2.** Let the functions  $U_k(\tau, t)$ ,  $k = 0, 1, 2, \ldots$  be defined and continuous on S and let

$$|U_k(\tau+\eta,t+\eta)-U_k(\tau+\eta,t)-U_k(\tau,t+\eta)+U_k(\tau,t)|\leq \varphi(\eta)$$

if

$$0 < \eta \leq \sigma, \quad (\tau + \eta, t + \eta), \quad (\tau + \eta, t), \quad (\tau, t + \eta), \quad (\tau, t) \in S.$$
Let  $U_k(\tau, t) \to U(\tau, t)$  uniformly on  $S$  with  $k \to \infty$ . (11)
Then

$$\int_{\lambda_1}^{\lambda_2} DU_k \to \int_{\lambda_1}^{\lambda_2} DU \text{ with } k \to \infty \text{ uniformly for } \tau_* \leq \lambda_1 \leq \lambda_2 \leq \tau^* \text{ .}$$
(12)

Proof. From (2) and (3) we obtain in a similar manner as in the proof of the preceding theorem that

$$|\int\limits_{\lambda_1}^{\lambda_2} \mathrm{D} U_k - B(U_k,A)| \leq (\lambda_2 - \lambda_1) \sup_{\mathbf{0} < t \leq \delta} arPsi(t)$$

in the subdivision A of  $\langle \lambda_1, \lambda_2 \rangle$  fulfils (8),  $0 < \delta \leq \sigma$  and (12) follows from (11), as  $B(U_k, A) \to B(U, A)$  with  $k \to \infty$  (cf. Theorem 1,3,4, [1]).

Note 1. The results of section 4, [1] (specially Theorems 4,1,1, 4,1,2, 4,2,1, Lemma 4,1,1) are valid, if we omit the assumption that  $\eta^{-1}\psi(\eta)$  is nondecreasing (we assume of course, that  $\sum_{j=1}^{\infty} 2^{j}\psi\left(\frac{\sigma}{2^{j}}\right) < \infty$ ;  $\psi(\eta) = \omega_{1}(\eta) \omega_{2}(\eta)$  is nondecreasing, as  $\omega_{1}(\eta)$  and  $\omega_{2}(\eta)$  are nondecreasing).

Note 2. Suppose that the values of the function  $U(\tau, t)$   $(\tau, t \in \langle \tau_*, \tau^* \rangle)$  belong to a Banach space *B*. For  $X \in B$  let |X| be the norm of *X*. Let  $\langle \lambda_1, \lambda_2 \rangle \subset$ 

 $\subset \langle au_*, au^* 
angle.$  If  $A = \{lpha_0, au_1, lpha_1, \ldots, au_s, lpha_s\}$  is a subdivision of  $\langle \lambda_1, \lambda_2 \rangle$ , put $R(U, A) = \sum_{i=1}^s [U( au_i, lpha_i) - U( au_i, lpha_{i-1})].$ 

Suppose that for every  $\varepsilon > 0$  there exists such a function  $\delta(\tau) > 0$  that

$$|R(U,A) - R(U,A')| < \varepsilon$$

if the subdivisions  $A = \{\alpha_0, \tau_1, \alpha_1, ..., \tau_s, \alpha_s\}, A' = \{\alpha'_0, \tau'_1 \alpha'_1, ..., \tau'_r, \alpha'_r\}$  of  $\langle \lambda_1, \lambda_2 \rangle$  fulfil the conditions

$$\begin{aligned} &\tau_i - \alpha_{i-1} < \delta(\tau_i) \,, \quad \alpha_i - \tau_i < \delta(\tau_i) \,, \quad i = 1, \, 2, \, \dots, s \,, \\ &\tau_i' - \alpha_{i-1}' < \delta(\tau_i') \,, \quad \alpha_i' - \tau_i' < \delta(\tau_i') \,, \quad i = 1, \, 2, \, \dots, r \,. \end{aligned}$$

Then there exists such a  $W \in B$  that

$$|W - R(U, A)| \leq \varepsilon$$

if the subdivision A of  $\langle \lambda_1, \lambda_2 \rangle$  fulfils (1\*). In this case we define

$$\int_{\lambda_1}^{\lambda_2} \mathrm{D}U(\tau, t) = W$$

We shall show that Theorem 1 remains valid if the values of U belong to B. Let us put

$$\overline{S}(U; \lambda_1, \lambda_2) = \lim_{i \to \infty} S_i(U; \lambda_1, \lambda_2) , \qquad (2^*)$$

$$\overline{Z}(U; \lambda_1, \lambda_2) = \lim_{i \to \infty} Z_i(U; \lambda_1, \lambda_2) ,$$
 (3\*)

where  $S_i$ ,  $Z_i$  are defined by the formulas (1a), (1b). In the same manner as we deduced (6) we obtain that the limits in (2<sup>\*</sup>) and (3<sup>\*</sup>) exist and that

$$|S(U; \lambda_1, \lambda_2) - U(\lambda_1, \lambda_2) + U(\lambda_1, \lambda_1)| \leq \frac{1}{2}(\lambda_2 - \lambda_1) \Psi(\lambda_2 - \lambda_1), \quad (4^*)$$

$$|\overline{Z}(U;\lambda_1,\lambda_2) - U(\lambda_2,\lambda_2) + U(\lambda_2,\lambda_1)| \leq \frac{1}{2}(\lambda_2 - \lambda_1) \Psi(\lambda_2 - \lambda_1) .$$
 (5\*)

Obviously

$$\varphi S_i(U; \lambda_1, \lambda_2) = S_i(\varphi U; \lambda_1, \lambda_2), \quad \varphi Z_i(U; \lambda_1, \lambda_2) = Z_i(\varphi U; \lambda_1, \lambda_2)$$

where  $\varphi$  is a linear functional on B. It follows that

$$p\overline{S}(U; \lambda_1, \lambda_2) = \int_{\lambda_1}^{\lambda_2} \mathrm{D} \varphi U(\tau, t) = \varphi \overline{Z}(U; \lambda_1, \lambda_2) \ .$$

Hence

$$\overline{S}(U; \lambda_1, \lambda_2) = \overline{Z}(U; \lambda_1, \lambda_2) \tag{6*}$$

and

$$\overline{S}(U; \lambda_1, \lambda_2) + \overline{S}(U; \lambda_2, \lambda_3) = \overline{S}(U; \lambda_1, \lambda_3).$$
(7\*)

Let  $\delta > 0$  and let A be a subdivision of  $\langle \lambda_1, \lambda_2 \rangle$ ,  $\alpha_i - \tau_i < \delta$ ,  $\tau_i - \alpha_{i-1} < \delta$ , i = 1, 2, ..., s.

It follows from  $(4^*)-(7^*)$  that

$$|\overline{S}(U;\,\lambda_1,\,\lambda_2)-R(U,A)|\leq (\lambda_2-\lambda_1)\sup_{0< t\leq oldsymbol{\delta}} arPsi(t)\,.$$

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Consequently  $\int_{1}^{\lambda_2} DU(\tau, t)$  exists and

$$\int\limits_{\lambda_1}^{\lambda_2} \mathrm{D} U( au,t) = \overline{S}(U;\,\lambda_1,\,\lambda_2) \;.$$

From  $(4^*)$ ,  $(5^*)$  and  $(6^*)$  we obtain (4) and (5). Theorem 1 holds.

Theorem 2 follows from Theorem 1 in the same manner as in the scalar case.

2. Some considerations in section 5,1, [1] are not correct (especially p. 444, formulas in the 3<sup>rd</sup> and 5<sup>th</sup> line from below and p. 445 formula in the 6<sup>th</sup> line from above). The aim of section 5,1, [1] was to prove that the solutions of generalized linear differential equations are unique and to establish the variation-of-constants formula. Here we shall give the correct proofs. The author intends to use the variation-of-constants formula for an investigation of linear differential equations. Therefore we shall work with general moduli of continuity  $\omega_3$ ,  $\omega_4$  while in section 5,1 [1] it was assumed that the respective moduli of continuity are powers of  $\eta$ .

Let  $\omega_3(\eta) \ \omega_4(\eta)$  be nondecreasing on  $\langle 0, \sigma \rangle$ ,  $\omega_3(\eta) \ge c\eta$ ,  $\omega_4(\eta) \ge c\eta$  (c > 0),  $\omega_5(\eta) = \max(\omega_3(\eta), \omega_4(\eta)), \ \psi_4(\eta) = \omega_4^2(\eta), \ \psi_5(\eta) = \omega_5(\eta) \ \omega_4(\eta).$ 

$$\text{Suppose that } \sum_{j=1}^\infty 2^j \psi_5\left(\frac{\sigma}{2^j}\right) < \infty \text{ and put } \varPsi_i(\eta) = \sum_{j=1}^\infty \frac{2^j}{\eta} \, \psi_i\left(\frac{\eta}{2^j}\right)\!\!, \, i=4,5.$$

Let A(t),  $t \in (-\infty, \infty)$  be an  $n \times n$ -matrix and let B(t) be an *n*-vector and suppose that

$$|A(t_2) - A(t_1)|| \le \omega_4(|t_2 - t_1)|$$
 for  $|t_2 - t_1| \le \sigma$ , (13)

$$|B(t_2) - B(t_1)|| \le \omega_3(|t_2 - t_1|) \text{ for } |t_2 - t_1| \le \sigma.$$
 (14)

**Lemma 2.** Let  $c \in E_n$ . There exists at most one regular<sup>2</sup>) solution  $x(\tau)$  of

<sup>2</sup>) Let  $F(x, t) \in F(G, \omega_1, \omega_2, \sigma)$  (cf. [1], section 4,1). Let  $x(\tau), \tau \in \langle \tau_1, \tau_2 \rangle$  be a solution of

$$\frac{\mathrm{d}x}{\mathrm{d}\tau} = \mathrm{D}F(x,t) \; .$$

 $x(\tau)$  is a regular solution, if there is such a  $\sigma' > 0$ , that  $||x(\tau_3) - x(\tau_4)|| \le 2\omega_1(|\tau_3 - \tau_4|)$  for  $\tau_3, \tau_4 \in \langle \tau_1, \tau_2 \rangle$ ,  $|\tau_3 - \tau_4| \le \sigma'$ . This definition is equivalent to Definition 4.2.1 [1], as the interval  $\langle \tau_1, \tau_2 \rangle$  is compact.

Let  $y(\tau)$  be a solution of

$$\frac{\mathrm{d}y}{\mathrm{d}\tau} = \mathrm{D}[A(t) \ y + B(t)] \tag{16}$$

on an interval I [I may be closed, open or  $I = (-\infty, \infty)$ ]. Let  $\langle \tau_1, \tau_2 \rangle$  be a compact subinterval of  $I \cdot y(\tau)$  is continuous on I (cf. Theorem 1,3,6 and Definition 2,1,1 [1] and therefore there exists such a bounded open subset G of  $E_{n+1}[(n + 1)$ -dimensional Euclidean space], that contains all the points  $(y(\tau), \tau)$  for  $\tau \in \langle \tau_1, \tau_2 \rangle$ . Obviously  $A(t) y + B(t) \in F(G, K_3\omega_5(\eta), K_3\omega_4(\eta), \sigma)$  if  $K_3$  is great enough.  $y(\tau), \tau \in \langle \tau_1, \tau_2 \rangle$  is regular [with respect to  $F(G, K_3\omega_5(\eta), K_3\omega_4(\eta), (\sigma)]$ , if there is such a  $\sigma > 0$ , that  $||y(\tau_4) - y(\tau_3)|| \leq 2K_3\omega_5(|\tau_4 - \tau_3|)$  for  $\tau_3, \tau_4 \in \langle \tau_1, \tau_2 \rangle, |\tau_4 - \tau_3| \leq \sigma'$ . We shall say that  $y(\tau)$  is a regular solution of (16), if for every compact subinterval  $\langle \tau_1, \tau_2 \rangle$  of I there exist such positives  $K_4$  and  $\sigma'$  that  $||y(\tau_4) - (\tau_3)|| \leq K_4\omega_5(|\tau_4 - \tau_3|)$  for  $\tau_3, \tau_4 \in \langle \tau_1, \tau_2 \rangle, |\tau_4 - \tau_3| \leq \sigma'$ .

$$\frac{\mathrm{d}x}{\mathrm{d}\tau} = \mathrm{D}A(t) x , \qquad (15)$$

which fulfils  $x(t_0) = c$ .

In order to prove Lemma 2 we may use the proof of Lemma 5,1 [1]. At the same time Lemma 2 is a consequence of Theorem 1 [2].

**Lemma 3.** The regular solutions of (15) are defined for  $\tau \in (-\infty, \infty)$ .

Lemma 3 is a consequence of Lemma 2 and Theorem 4,2,1 [1], where we put  $F_1(x, t) = F_0(x, t) = A(t) x$ ,  $x_0(\tau) = 0$ ,  $\varepsilon = 1$ , G = E(x, t; ||x|| < 1). It follows that for every T > 0 there is such a  $\delta > 0$  that the regular solutions of (15) which fulfil  $||x(0)|| < \delta$  are defined on  $\langle 0, T \rangle$  and fulfil  $||x(\tau)|| < 1$  on  $\langle 0, T \rangle$ . By the substitution t' = -t we obtain that the solutions of (15) which fulfil  $||x(0)|| < \delta'$  are defined on  $\langle -T, 0 \rangle$  and fulfil  $||x(\tau)|| < 1$  on  $\langle -T, 0 \rangle$ .

The fundamental matrix of (15) is a  $n \times n$ -matrix  $\Phi(\tau)$ ,  $\Phi(0) = E^3$ ) every column of which is a regular solution of (15). It follows from Lemmas 2 and 3 that  $\Phi(\tau)$  is defined uniquely for  $\tau \in (-\infty, \infty)$ .

Our aim is to establish the variation-of-constants formula for the solutions of

$$\frac{\mathrm{d}x}{\mathrm{d}\tau} = \mathrm{D}[A(t) \, x + B(t)] \,. \tag{16}$$

Let  $A_k(t)$ ,  $B_k(t)$  be such matrices and vectors, that  $A_k(t) \to A(t)$ ,  $B_k(t) \to B(t)$ uniformly on every bounded interval,  $\frac{d}{dt}A_k(t) = a_k(t)$ ,  $\frac{d}{dt}B_k(t) = b_k(t)$  are continuous,  $A_k(t)$  fulfil (13),  $B_k(t)$  fulfil (14).

As the generalized equation

$$rac{\mathrm{d}x}{\mathrm{d} au} = \mathrm{D}[A_k(t) \ x + B_k(t)]$$

is equivalent to the classical equation

$$rac{\mathrm{d}x}{\mathrm{d}t} = a_k(t) \, x + b_k(t)$$
 ,

we have the variation-of-constants formula

$$\begin{aligned} x_k(s) &= \Phi_k(s)[z + \int_0^s \Xi_k(t) \ b_k(t) \ dt] = \\ &= \Phi_k(s)[z + \int_0^s D\Xi_k(\tau) \ B_k(t)], \quad x_k(0) = z, \end{aligned}$$
(17)

where  $\Phi_k(\tau)$  is the fundamental matrix of

$$\frac{\mathrm{d}x}{\mathrm{d}\tau} = \mathrm{D}[A_k(t)\,x] \tag{18}$$

and  $\Xi_k(\tau) = \Phi_k^{-1}(\tau)$ .

<sup>3</sup>) E is the unit matrix.

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According to Lemma 2 and Theorem 4,2,1, [1]  $\Phi_k(\tau) \to \Phi(\tau)$  uniformly on every bounded interval. As  $\Xi_k^*(\tau)^4$  is the fundamental matrix of

$$\frac{\mathrm{d}x}{\mathrm{d}\tau} = -\mathrm{D}A_k^*(t) x \,, \tag{19}$$

it follows similarly, that  $\Xi_k^*(\tau) \to \Xi^*(\tau)$  uniformly on every bounded interval, where  $\Xi^*(\tau)$  is the fundamental matrix of

$$\frac{\mathrm{d}x}{\mathrm{d}\tau} = -\mathrm{D}A^*(t)\,x\,.$$

Passing to the limit for  $k \to \infty$  in  $\Phi_k(\tau) \Xi_k(\tau) = E$  we obtain that  $\Phi(\tau) \Xi(\tau) =$  $= E \left( \Xi = \Xi^{**} \right).$ 

Let T > 0. As the columns of  $\mathcal{Z}_k^*(\tau)$  are regular solutions of (19), there exist such  $K_{5k}$  and  $\sigma'_k$  that

$$\begin{split} \|\Xi_k(t_2) - \Xi_k(t_1)\| &\leq K_{5k} \omega_4(|t_2 - t_1|) \quad \text{for} \quad t_1, t_2 \in \langle -T, T \rangle \ , \\ |t_2 - t_1| &\leq \sigma'_k \ . \end{split}$$

It follows that there exist such constants  $K_{6k}$ , that

$$egin{aligned} \|arepsilon_k(t_2)-arepsilon_k(t_1)\|&\leq K_{6k}\omega_4(|t_2-t_1|) \quad ext{for} \quad t_1,t_2\ \epsilon \left<-T,\ T
ight>,\ |t_2-t_1|&\leq \sigma \ . \end{aligned}$$

According to Lemma 4,1,1 [1] there exist such  $\sigma^* > 0$  ( $\sigma^* \leq \sigma$ ) and L > 0(independent on k) that

$$\begin{aligned} \|\Xi_k(t_2) - \Xi_k(t_1)\| &\leq L\omega_4(|t_2 - t_1|) \quad \text{for} \quad t_1, t_2 \in \langle -T, T \rangle , \\ |t_2 - t_1| &\leq \sigma^* .^5 ) \end{aligned}$$
(20)

Similarly

$$\begin{aligned} \|\Phi_k(t_2) - \Phi_k(t_1)\| &\leq L'\omega_4(|t_2 - t_1|) \quad \text{for} \quad t_1, t_2 \in \langle -T, T \rangle , \\ |t_2 - t_1| &\leq \sigma^* . \end{aligned}$$
(21)

Theorem 2 together with (14) and (17) implies that

$$\int_{0}^{\bullet} \mathrm{D}\Xi_{k}(\tau) \ B_{k}(t) \to \int_{0}^{\bullet} \mathrm{D}\Xi(\tau) \ B(t) \quad \text{uniformly with} \quad k \to \infty \quad \text{for} \\ s \ \epsilon \ \langle -T, \ T \rangle \ . \tag{22}$$

Consequently the uniform limit  $\lim x_k(t) = x(t)$  exists. From (13), (14), (17),  $k \rightarrow \infty$ (20), (21) and Theorem 1 we obtain that

$$\begin{split} \|\int\limits_{t_1}^{t_2} \mathrm{D}\mathcal{Z}_k(\tau) \; B_k(t)\| &\leq K_7 \omega_3(|t_2 - t_1|) \quad \text{for} \quad t_1, t_2 \; \epsilon \left< -T, \; T \right>, \quad |t_2 - t_1| \leq \sigma^* \;, \\ \|x_k(t_2) - x_k(t_1)\| &\leq K_8 \omega_5(|t_2 - t_1|) \quad \text{for} \quad t_1, t_2 \; \epsilon \left< -T, \; T \right>, \quad |t_2 - t_1| \leq \sigma^* \;. \end{split}$$

<sup>&</sup>lt;sup>4)</sup>  $\Xi_k^*$  is the conjugate transpose to  $\Xi_k$ . <sup>5)</sup> The number  $\sigma^*$  which occurs in Lemma 4,1,1 [1] depends only on K,  $G_{i_1} \omega_1, \omega_2$ , not on the right-hand side of equation (4,1,04). Let us denote by  $\xi_{kj}^*(\tau)$  ( $\xi_j^*(\tau)$ ) the *j*-th co-lumn of the matrix  $\Xi_k^*(\tau)$  ( $\Xi^*(\tau)$ ). In the present case we choose such an open and bounded set  $G_1$  that contains all the points ( $\xi_{k,j}^*(\tau), \tau$ ), ( $\xi_j^*(\tau), \tau$ ),  $k = 1, 2, 3, \ldots, j =$   $= 1, 2, \ldots, n, \tau \in \langle -T, T \rangle$ .

According to Theorem 4,1,1 [1]  $x(\tau)$  is a solution of (16).<sup>6</sup>) Passing to the limit for  $k \to \infty$  in (17) we obtain the required variation-of-constants formula

$$x(s) = \Phi(s)[z + \int_{0}^{s} DE(\tau) B(t)], \quad x(0) = z.$$
(23)

As the difference of two regular solutions of (16) is a regular') solution of (15), Lemma 2 implies that  $x(\tau)$  is the only regular solution of (16), which fulfils x(0) = z.

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### Резюме

## ДОБАВЛЕНИЕ К МОЕЙ СТАТЬЕ "ОБОБЩЕННЫЕ ОБЫКНОВЕННЫЕ ДИФФЕРЕНЦИАЛЬНЫЕ УРАВНЕНИЯ И НЕПРЕРЫВНАЯ ЗАВИСИМОСТЬ ОТ ПАРАМЕТРА"

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Дается улучшенное изложение третьего параграфа статьи [1]. В новых доказательствах теорем этого параграфа употребляются более слабые предположения, касающиеся монотонности функции  $\psi(\eta)$ . Следовательно, в этих более общих предположениях верны и основные результаты статьи [1], содержащиеся в четвертом параграде. Далее, для обобщенных линейных уравнений выводится формула вариации постоянных (что представляет корректное изложение параграфа 5,1 статьи [1]).

<sup>&</sup>lt;sup>6</sup>)  $A_k(t) x + B_k(t) \epsilon F(G, K_g \omega_5(\eta), \omega_4(\eta), \sigma)$  where G is a suitable bounded set and  $K_g$  is great enough.

<sup>&</sup>lt;sup>7</sup>) Cf. footnote <sup>2</sup>).