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# A NOTE ON THE STABILITY OF $\theta$ -METHODS FOR VOLTERRA INTEGRAL EQUATIONS OF THE SECOND KIND

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#### 1. INTRODUCTION

The majority of stability analyses of numerical methods for Volterra integral equations of the second kind

(1) 
$$y(t) = g(t) + \int_0^t k(t, s, y(s)) ds, \quad t \ge 0,$$

were based on the simple linear test equation

(2) 
$$y(t) = g(t) + \lambda \int_0^t y(s) \, \mathrm{d}s, \quad t \ge 0,$$

where  $\lambda$  is a complex number and Re ( $\lambda$ ) < 0 (see, for example, [1-3]). It is the purpose of this note to present a stability analysis of some methods for the numerical integration of (1) based on the more general test equation

(3) 
$$y(t) = g(t) + \lambda \int_0^t k(s) y(s) ds, \quad t \ge 0,$$

where Re  $(\lambda)$  < 0 and the functions g and k satisfy certain conditions which will be given later.

Denote by h > 0 a fixed step size and define the grid  $\{t_i\}_{i=0}^{\infty}$  by  $t_i = ih, i = 0, 1, ...$ We are interested in the following class of the so called  $\theta$ -methods:

(4) 
$$y_n = g_n + \lambda h [(1 - \theta) \sum_{i=0}^{n-1} k(t_n, t_i, y_i) + \theta \sum_{i=1}^{n} k(t_n, t_i, y_i)],$$

 $i=0,1,\ldots,\theta\in[0,1]$   $(\sum_{i=0}^{-1}=0,\sum_{i=1}^{0}=0)$ . Here,  $g_n=g(t_n)$  and  $y_n$  is the approximation to  $Y(t_n)$ , where Y is the solution of (1). For  $\theta=0$ ,  $\theta=\frac{1}{2}$ , and  $\theta=1$  these are direct quadrature methods based on the left rectangular rule, the trapezoidal rule, and the right rectangular rule, respectively. It is easy to check that the local discretiza-

tion error of (4)

$$\eta_{\theta}(t_n, h) := Y(t_n) - g_n - \lambda h [(1 - \theta) \sum_{i=0}^{n-1} k(t_{n-1}, t_i, Y(t_i)) + \theta \sum_{i=1}^{n} k(t_n, t_i, Y(t_i))]$$

satisfies  $\eta_{\theta}(t_n, h) = O(h)$  for  $\theta = \frac{1}{2}$  and  $\eta_{\theta}(t_n, h) = O(h^2)$  for  $\theta = \frac{1}{2}$  uniformly in  $t_n$  as  $h \to 0$ . Consequently, this method is convergent with order one for  $\theta = \frac{1}{2}$  and with order two for  $\theta = \frac{1}{2}$ , i.e.

$$y_n - Y(t_n) = \begin{cases} O(h), & \theta \neq \frac{1}{2}, \\ O(h^2), & \theta = \frac{1}{2}, \end{cases}$$

as  $n \to \infty$ ,  $nh = t_n$  (see [1, 4]).

In the next section we examine the behaviour of the solution Y of (3) and the approximate solution  $\{y_n\}_{n=0}^{\infty}$  when the method (4) is applied to (3), for a fixed step size h > 0. It turns out that both Y and  $\{y_n\}_{n=0}^{\infty}$  are bounded and the last bound is uniform in h and  $\theta$ .

#### 2. STABILITY ANALYSIS

We have the following bound on the solution Y of the equation (3).

**Theorem 1.** Assume that  $|g(t)| \le G < \infty$  and  $k(t) \ge 0$  for  $t \ge 0$ . Assume also that  $\operatorname{Re}(\lambda) < 0$ . Then the solution Y of (3) satisfies  $|Y(t)| \le G(1 - |\lambda|/\operatorname{Re}(\lambda))$  for  $t \ge 0$ .

Proof. Putting  $z(t) = \int_0^t k(s) y(s) ds$ , the problem (3) can be written as

$$z'(t) = \lambda k(t) z(t) + k(t) g(t), \quad t \ge 0,$$
  
 $z(0) = 0.$ 

The solution Z of this equation is given by

$$Z(t) = \int_0^t k(s) g(s) \exp\left(\lambda \int_s^t k(\tau) d\tau\right) ds, \quad t \ge 0.$$

Let  $\lambda = a + bi$ . It follows that

$$|Z(t)| \le -(G/a) \int_0^t (-a) k(s) \exp\left(a \int_s^t k(\tau) d\tau\right) ds \le$$

$$\le -(G/a) \left[1 - \exp\left(a \int_0^t k(\tau) d\tau\right)\right] \le -G/a.$$

Taking into account that the solution Y of (3) is given by  $Y(t) = \lambda Z(t) + g(t)$ , we obtain  $|Y(t)| \le G(1 - |\lambda|/\text{Re}(\lambda))$ ,  $t \ge 0$ , which is our claim.

Remark. It is impossible to bound the solution Y of (3) by a constant independent

of  $\lambda$ . To see this, let us consider the problems

$$y(t) = \lambda_n \int_0^t y(s) ds + \sin(t), \quad t \ge 0,$$

$$y(t) = i \int_0^t y(s) ds + \sin(t), \quad t \ge 0,$$

where  $\lambda_n \to i$  as  $n \to \infty$ , Re $(\lambda_n) < 0$ , with solutions  $Y_n$  and  $Y_n$ , and observe that  $Y_n$  is unbounded and  $Y_n \to Y$  as  $n \to \infty$  uniformly on any compact interval [0, T], T > 0.

Our next theorem establishes a bound on the solution  $\{y_n\}_{n=0}^{\infty}$  of the equation (4) applied to (3).

**Theorem 2.** In addition to the conditions given in Theorem 1, assume that  $0 < \omega \le \le k(t) \le \Omega < \infty$  for  $t \ge 0$ . Then there exists  $h_{\theta} > 0$  and a constant  $M \ge 0$  independent of  $h, \lambda$  and  $\theta$  such that  $|y_n| \le M(1 - |\lambda|/\text{Re}(\lambda))$ ,  $n = 0, 1, ..., for h \in (0, h_{\theta}]$  and  $\theta \in [0, 1]$ .

Proof. The method (4) applied to (3) yields

(5) 
$$y_n = g_n + \lambda h [(1 - \theta) \sum_{i=0}^{n-1} k_i y_i + \theta \sum_{i=1}^{n} k_i y_i],$$

n = 0, 1, ..., where  $k_i = k(t_i)$ . Subtracting  $y_{n+1}$  and  $y_n$  we obtain

$$y_{n+1} = \frac{1 + (1 - \theta) \lambda h k_n}{1 - \theta \lambda h k_{n+1}} y_n + \frac{g_{n+1} - g_n}{1 - \theta \lambda h k_{n+1}},$$

 $n = 0, 1, \dots$  This is a recurrent equation of the first order, its solution being given by

$$y_{n} = \left(\prod_{i=0}^{n-1} \frac{1 + (1-\theta) \lambda h k_{i}}{1 - \theta \lambda h k_{i+1}}\right) y_{0} + \sum_{i=0}^{n-1} \frac{g_{i+1} - g_{i}}{1 - \theta \lambda h k_{i+1}} \prod_{j=i+1}^{n-1} \frac{1 + (1-\theta) \lambda h k_{j}}{1 - \theta \lambda h k_{j+1}},$$

 $n = 0, 1, \dots$  (see [5]). Hence,

(6) 
$$|y_n| \le \prod_{i=0}^{n-1} \frac{|1 + (1-\theta)\lambda hk_i|}{|1 - \theta\lambda hk_{i+1}|} |y_0| + 2G \sum_{i=0}^{n-1} \prod_{j=i+1}^{n-1} \frac{|1 + (1-\theta)\lambda hk_j|}{|1 - \theta\lambda hk_{j+1}|},$$

 $n = 0, 1, \dots$  On the other hand, the equation (5) can be written as  $y_n = \lambda h z_n + g_n$ , where

$$z_{n} = (1 - \theta) \sum_{i=0}^{n-1} k_{i} y_{i} + \theta \sum_{i=1}^{n} k_{i} y_{i},$$

 $n = 0, 1, \dots$  Subtracting  $z_{n+1}$  and  $z_n$  and eliminating  $y_{n+1}$  and  $y_n$  from the resulting

equation we obtain

$$z_{n+1} = \frac{1 + (1 - \theta) \lambda h k_n}{1 - \theta \lambda k_{n+1}} z_n + \frac{(1 - \theta) k_n g_n + \theta k_{n+1} g_{n+1}}{1 - \theta \lambda h k_{n+1}},$$

 $n = 0, 1, \dots$  Hence, noting that  $z_0 = 0$  we get

$$z_{n} = \sum_{i=0}^{n-1} \frac{(1-\theta) k_{i} g_{i} + \theta k_{i+1} g_{i+1}}{1-\theta \lambda h k_{i+1}} \prod_{j=i+1}^{n-1} \frac{1+(1-\theta) \lambda h k_{j}}{1-\theta \lambda h k_{i+1}},$$

 $n = 0,1, \ldots$  In view of this relation and the relationship between  $y_n$  and  $z_n$  we obtain

(7) 
$$|y_n| \le |\lambda h| \Omega G \sum_{i=0}^{n-1} \prod_{j=i+1}^{n-1} \frac{|1 + (1-\theta) \lambda h k_j|}{|1 - \theta \lambda h k_{j+1}|} + G,$$

 $n=0,1,\ldots$  For any  $\xi\in[\omega,\Omega]$  (and fixed  $\lambda$ , Re  $(\lambda)<0$ ) let us consider the functions

$$\phi_{\varepsilon}(h,\theta) := |1 + (1 - \theta) \lambda h \xi|, \quad \psi_{\varepsilon}(h,\theta) := |1 - \theta \lambda h \xi|.$$

For any fixed  $\theta \in [0, 1)$  the function  $\phi_{\xi}$  attains its minimum value  $|\operatorname{Im}(\lambda)/|\lambda||$  for  $h_{\xi} = -\operatorname{Re}(\lambda)/((1-\theta)|\xi|\lambda|^2)$ . In view of the assumptions on the function k it is clear that there exists  $h_{\theta} > 0$  such that for all  $h \in (0, h_{\theta}]$  the following inequality holds:

$$\phi_{k,i}(h,\theta) \leq \phi_{\omega}(h,\theta) < 1.$$

The largest value of  $h_{\theta}$  for which this inequality is satisfied for any function k satisfying the assumptions of the theorem can be computed from the condition  $\phi_{\omega}(h_{\theta}, \theta) = \phi_{\Omega}(h_{\theta}, \theta)$ , which leads to the formula

$$h_{\theta} = -2 \operatorname{Re}(\lambda) / ((1 - \theta) |\lambda|^{2} (\omega + \Omega)).$$

It is also clear that  $\psi_{k_{j+1}}(h,\theta) \ge \psi_{\omega}(h,\theta) > 1$  for any h > 0 and  $\theta \in (0,1]$ . Hence, putting  $q_{\omega}(h,\theta) = \phi_{\omega}(h,\theta)/\psi_{\omega}(h,\theta)$  and  $Q = \max\{2G,\Omega G\}$ , in view of (6), (7), and the relation  $q_{\omega}(h,\theta) < 1$ , which holds for any  $\theta \in [0,1]$  and  $h \in (0,h_{\theta}]$   $(h_1 = \infty)$ , we obtain

(8) 
$$|y_n| \leq \begin{cases} Q \frac{|\lambda h|}{1 - q_{\omega}(h, \theta)} + G, & h \leq 1/|\lambda|, \\ Q \frac{1}{1 - q_{\omega}(h, \theta)} + G, & h > 1/|\lambda|, \end{cases}$$

 $n=0,1,\ldots$  Let us set  $D:=\{(h,\theta)\colon \theta\in[0,1],\ h\in(0,h_{\theta}]\}$  and define the (continuous) function  $\eta_{\omega}\colon D\to[0,\infty)$  by

$$\eta_\omega(h,\, heta) := \left\{ egin{array}{l} \dfrac{\left|\lambda h
ight|}{1-q_\omega(h,\, heta)}\,, & h \leq 1/\left|\lambda
ight|\,, \ \\ \dfrac{1}{1-q_\omega(h,\, heta)}\,, & h > 1/\left|\lambda
ight|\,. \end{array} 
ight.$$

We will show that  $\eta_{\omega}$  is bounded on D. We have

$$\frac{1}{1-q_{\omega}(h,\theta)} \leq \frac{2|1-\theta\lambda h\omega|^2}{|1-\theta\lambda h\omega|^2-|1+(1-\theta)\lambda h\omega|^2},$$

hence,

$$n_{\omega}(h,\theta) \leq \begin{cases} \frac{2|\lambda| \left(1 - 2\theta a h \omega + \theta^2 |\lambda|^2 h^2 \omega^2\right)}{-2a\omega + |\lambda|^2 h \omega^2(2\theta - 1)}, & h \leq 1/|\lambda|, \\ \frac{2(1 - 2\theta a h \omega + \theta^2 |\lambda|^2 h^2 \omega^2)}{-2ah\omega + |\lambda|^2 h^2 \omega^2(2\theta - 1)}, & h > 1/|\lambda|. \end{cases}$$

Here,  $a = \text{Re}(\lambda)$ . Next we define  $\theta^*$  by  $|\lambda h_{\theta^*}| = 1$ , i.e.

$$\theta^* = 1 + 2 \operatorname{Re}(\lambda)/(|\lambda|(\omega + \Omega)).$$

We may assume without loss of generality that  $\omega + \Omega > 4$ , hence  $\theta^* > \frac{1}{2}$ . We consider the following cases:

1.  $\theta \in [0, \frac{1}{2}]$ . Then there exists a constant  $M_1 \ge 0$  such that

$$\eta_{\omega}(h,\theta) \leq \frac{2|\lambda| \left(1 - 2\theta a h_{\theta} \omega + \theta^2 |\lambda|^2 h^2 \omega^2\right)}{-2a\omega + |\lambda|^2 h_{\theta} \omega^2 (2\theta - 1)} \leq -M_1(|\lambda|/a).$$

2.  $\theta \in (\frac{1}{2}, 1]$  and  $h \in (0, \min\{h_{\theta}, 1/|\lambda|\}]$ . Then there exists  $M_2 \ge 0$  such that

$$\eta_{\omega}(h,\theta) \leq \frac{2|\lambda|(1-2a\omega/|\lambda|+\omega^2)}{-2a\omega+|\lambda|^2 h\omega^2(2\theta-1)} \leq -M_2(|\lambda|/a).$$

3.  $\theta \in [\theta^*, 1]$  and  $h \in (1/|\lambda|, h_{\theta}]$ . Then

$$\begin{split} \eta_{\omega}(h,\theta) & \leq \frac{2}{-2ah\omega + |\lambda|^2 h^2 \omega^2 (2\theta - 1)} + \frac{-4a\omega}{-2a\omega + |\lambda|^2 h\omega^2 (2\theta - 1)} + \\ & + \frac{|\lambda|^2 \omega^2 h}{-2a\omega + |\lambda|^2 h\omega^2 (2\theta - 1)} \leq -(|\lambda|/a\omega) + 2 + (1/(2\theta^* - 1)) \,. \end{split}$$

However, we have  $(1/(2\theta^*-1)) \le (\omega + \Omega)/(\omega + \Omega - 4)$ , hence

$$\eta_{\omega}(h,\theta) \leq -M_3(|\lambda|/a) + M_4$$

for some nonnegative constants  $M_3$  and  $M_4$ .

Combining all these inequalities and taking into account (8) we immediately see that there exists a constant  $M \ge 0$  independent of h,  $\theta$ , and  $\lambda$  such that

$$|y_n| \leq M(1 - |\lambda|/\text{Re}(\lambda)),$$

 $n = 0, 1, \dots$  Thus the theorem is proved.

Remark. It follows from the proof of this theorem that the approximate solution  $\{y_n\}_{n=0}^{\infty}$  given by (5) for  $\theta = 1$  is bounded for any h > 0. This property is similar to the A-stability property of numerical methods for ordinary differential equations.

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