## Aplikace matematiky

Jaroslav Hrouda<br>On a classification of stationary points in nonlinear programming

Aplikace matematiky, Vol. 14 (1969), No. 1, 23-28

Persistent URL: http://dml.cz/dmlcz/103205

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# ON A CLASSIFICATION OF STATIONARY POINTS IN NONLINEAR PROGRAMMING 

Jaroslav Hrouda

(Received April 20, 1967)

## § 1

We will deal with a constrained extremum problem (that of nonlinear programming)

$$
\begin{equation*}
\max _{\boldsymbol{x}}\left\{F(x) \mid f_{i}(x) \leqq a_{i}, i=1, \ldots, m ; \varphi_{k}(x) \leqq b_{k}, k=1, \ldots, n\right\} . \tag{1}
\end{equation*}
$$

Here $x$ is a point of Banach space $E ; F$ and $f_{i}$ are nonlinear functionals continuously differentiable in the sense of Fréchet; ${ }^{1}$ ) $F^{\prime}(x), f_{i}^{\prime}(x)$ are their derivatives at the point $x$; $\varphi_{k}$ are linear functionals; $a_{i}, b_{k}$ real numbers. Let $R$ stand for the set of $E$ (called the feasible domain of the problem) defined by the inequalities in (1); $R$ is a closed set.

Let us now briefly mention the terms introduced by Altman in [1]. ${ }^{2}$ )
Definition 1. $s \in E, s \neq 0$ is called a feasible direction of the point $x \in R$ if there exists a number $\bar{t}>0$ such that

$$
\begin{equation*}
x+t s \in R \quad \text { for all } \quad 0<t \leqq t \tag{2}
\end{equation*}
$$

We denote by $A(x)$ the set of all feasible directions of the point $x$.
Definition 2. $x \in R$ is called an $R$-stationary point of the functional $F$ if $A(x) \neq \emptyset$ and

$$
\begin{equation*}
\sup _{s}\left\{F^{\prime}(x) s \mid s \in A(x)\right\}=0 . \tag{3}
\end{equation*}
$$

Let us denote by $M_{x}, N_{x}$ the sets of indices

$$
\begin{align*}
& M_{x}=\left\{i \mid f_{i}(x)=a_{i}, 1 \leqq i \leqq m\right\}  \tag{4}\\
& N_{x}=\left\{k \mid \varphi_{k}(x)=b_{k}, 1 \leqq k \leqq n\right\} \tag{5}
\end{align*}
$$

[^0]and by $S(x)$ the set of vectors
\[

$$
\begin{equation*}
\left.S(x)=\left\{s \in E \mid f_{i}^{\prime}(x) s \leqq 0, i \in M_{x} ; \varphi_{k}(s) \leqq 0, k \in N_{x}\right\} .^{3}\right) \tag{6}
\end{equation*}
$$

\]

Definition 3. $s \in E$ is called a regular direction of the point $x$ if $s \in S(x)$ and

$$
\begin{equation*}
f_{i}^{\prime}(x) s<0, \quad i \in M_{x} . \tag{7}
\end{equation*}
$$

For the set of all regular directions of the point $x$ the symbol $S_{R}(x)$ will be used. Obviously, $0 \notin S_{R}(x)$ if $M_{x} \neq \emptyset$. If $M_{x}=\emptyset$, then $S_{R}(x)=S(x)$.

Definition 4. $x \in R$ is called a regular stationary point of the functional $F$ if $S_{R}(x) \neq \emptyset$ and

$$
\begin{equation*}
\sup _{s}\left\{F^{\prime}(x) s \mid s \in S_{R}(x)\right\}=0 . \tag{8}
\end{equation*}
$$

| The condition $S_{R}(x) \neq \emptyset$ can be formulated equivalently as follows: For any numbers $u_{i}, v_{k}$ the relations

$$
\sum_{t \in M_{x}} u_{i} f_{i}^{\prime}(x)+\sum_{k \in N_{x}} v_{k} \varphi_{k}=0, \quad u_{i} \geqq 0, \quad v_{k} \geqq 0
$$

imply $u_{i}=0\left(i \in M_{x}\right)$. Usually, this condition is required to be fulfilled for all the points of the domain $R$ as the so-called regularity condition. ${ }^{4}$ )

## § 2

In this paragraph we will derive some properties of the concepts given by Definitions 1 through 4 . It will be shown that the regular stationary point is an $R$-stationary point; under the regularity condition the concepts given by Definitions 2 and 4 are equivalent.

Lemma 1. For each $x \in R$ the inclusions

$$
\begin{equation*}
S_{R}(x) \subset A(x) \subset S(x) \tag{9}
\end{equation*}
$$

hold.
Proof. Let $s \in S_{R}(x)$. According to the generalized Lagrange's formula we can write

$$
\begin{equation*}
\left.f_{i}(x+t s)=f_{i}(x)+t f_{i}^{\prime}\left(x+\Theta_{i} t s\right) s, \quad i=1, \ldots, m .^{5}\right) \tag{10}
\end{equation*}
$$

[^1]Assuming $f_{i}^{\prime}$ to be continuous, it follows from (4) and (7) that there exist sufficiently small numbers $t_{i}>0$ such that

$$
f_{i}(x+t s) \leqq a_{i} \quad \text { for all } \quad 0<t \leqq t_{i}, \quad i=1, \ldots, m .
$$

Further, for the linear functionals according to (5) and (6) there exist sufficiently small $t_{k}>0$ such that

$$
\varphi_{k}(x+t s)=\varphi_{k}(x)+t \varphi_{k}(s) \leqq b_{k}, \quad 0<t \leqq t_{k}, \quad k=1, \ldots, n .
$$

Then the demand (2) can be fulfilled by putting $\bar{t}=\min _{i, k}\left\{t_{i}, t_{k}\right\}$, hence $s \in A(x)$, and
the first inclusion in (9) is proved.
Let now $s \notin S(x)$. This means that $f_{i}^{\prime}(x) s>0$ for some $i \in M_{x}$ or $\varphi_{k}(s)>0$ for some $k \in N_{x}$. (Following footnote $3, M_{x}=\emptyset, N_{x}=\emptyset$ cannot hold simultaneously.) In the former case the continuity of $f_{i}^{\prime},(10)$, and (4) imply

$$
f_{i}(x+t s)>a_{i} \text { for all sufficiently small } t>0
$$

i.e. $s \notin A(x)$. The same conclusion can be reached also in the latter case. Thus $A(x) \subset$ $\subset S(x)$ holds.

Lemma 2. If $S_{R}(x) \neq \emptyset$, then $S_{R}(x)$ is dense in $S(x)$ for each $x$.
Proof. Let $\bar{s} \in S_{R}(x)$. To each $s \in S(x)$ there exists an arbitrarily close regular direction

$$
\begin{equation*}
s^{t}=s+t \bar{s}, \quad t>0 \quad \text { arbitrary } \tag{11}
\end{equation*}
$$

Indeed,

$$
\begin{aligned}
f_{i}^{\prime}(x) s^{t} & =f_{i}^{\prime}(x) s+t f_{i}^{\prime}(x) \bar{s}<0, \\
\varphi_{k}\left(s^{t}\right) & =\varphi_{k}(s)+t \varphi_{k}, \\
(\bar{s}) \leqq 0, & k \in N_{x} .
\end{aligned}
$$

Lemma 3. If $x \in R, S_{R}(x) \neq \emptyset$, the conditions (3) and (8) are equivalent to

$$
\begin{equation*}
\sup _{s}\left\{F^{\prime}(x) s \mid s \in S(x)\right\}=0 . \tag{12}
\end{equation*}
$$

Proof. Let us denote by $m_{A}, m_{R}$, and $m_{S}$ the left-hand sides of (3), (8), and (12), respectively. ${ }^{6}$ ) With regard to (9) it holds

$$
\begin{equation*}
m_{R} \leqq m_{A} \leqq m_{S} \tag{13}
\end{equation*}
$$

According to Lemma 2 there exist regular directions arbitrarily close to element $0 \in S(x)$, thus

$$
\begin{equation*}
m_{R} \geqq 0 . \tag{14}
\end{equation*}
$$

${ }^{6}$ ) Clearly, either $m_{\boldsymbol{A}} \leqq 0$ or $m_{\boldsymbol{A}}=+\infty$; the same is true for other two symbols.

Now,

$$
\begin{equation*}
m_{R}=0 \Rightarrow m_{S}=0 \tag{15}
\end{equation*}
$$

for if there were an $s \in S(x)$ such that $F^{\prime}(x) \cdot s>0$, a regular direction $s^{t}$ formed like that in (11) with a sufficiently small $t>0$ would satisfy the (impossible) inequality

$$
F^{\prime}(x) s^{t}=F^{\prime}(x) s+t F^{\prime}(x) \bar{s}>0
$$

Then it follows from (13), (14), and (15)

$$
m_{A}=0 \Leftrightarrow m_{R}=0 \Leftrightarrow m_{S}=0 .
$$

## § 3

In this paragraph we will propose a generalization of the concept of the $R$-stationary point.

Definition 5. $x \in R$ is called an $R$-quasistationary point of the functional $F$ if either

$$
\begin{equation*}
S_{R}(x)=\emptyset \tag{16}
\end{equation*}
$$

or

$$
\begin{equation*}
\sup _{s}\left\{F^{\prime}(x) s \mid s \in S_{R}(x)\right\}=0 . \tag{17}
\end{equation*}
$$



Fig. 1.

The extent of the new concept is schematically illustrated in Figure 1. The logical circle represents the set $R$ and its dashed part the $R$-quasistationary points.

The quasi-stationarity of a point in the sense of Definition 5 can be proved by means of a criterion identical with that of Altman [2, Theorem 1]:

Theorem 1. $x \in R$ is an $R$-quasistationary point of the functional $F$ if and only if

$$
\begin{equation*}
\max _{(s, \sigma)}\left\{\sigma \mid F^{\prime}(x) s \geqq \sigma ; f_{i}^{\prime}(x) s \leqq-\sigma, i \in M_{x} ; \varphi_{k}(s) \leqq 0, k \in N_{x}\right\}=0 . \tag{18}
\end{equation*}
$$

Proof. Let $\bar{\sigma}$ denote the left-hand side of (18). Let $\bar{\sigma}=0$. Let us admit that the point $x$ is not $R$-quasistationary, i.e. there exists a vector $\tilde{s} \in S_{R}(x)$ for which $F^{\prime}(x) \tilde{s}>$ $>0$. If we put down

$$
\tilde{\sigma}=\min \left\{F^{\prime}(x) \tilde{s} ;-f_{i}^{\prime}(x) \tilde{s}, i \in M_{x}\right\},
$$

the vector $\tilde{s}$ and the number $\tilde{\sigma}$ will fulfil the inequalities in (18) and at the same time $\tilde{\sigma}>0$; but this contradicts our assumption. Conversely, let us suppose that the point $x$ is $R$-quasistationary. If there were some vector $\tilde{s}$ satisfying the inequalities in (18) with $\tilde{\sigma}>0$, then $\tilde{s}$ would be a regular direction of the point $x$ and $F^{\prime}(x) \tilde{s}>0$. This is impossible, however, and therefore $\bar{\sigma}=0$ must hold (this value of $\bar{\sigma}$ is realized, e.g., by $s=0$ ).

A constructive way of getting $R$-quasistationary points is provided by the wellknown method of feasible directions. Altman's theorem [2, Theorem 2] on convergence of this method remains valid even if the regularity condition is omitted; ${ }^{7}$ ) then the limit point of the method will be an $R$-quasistationary point. The usefulness of the new concept is now apparent: The regularity condition is a strong requirement when applied to general (non-convex) regions and is difficult to verify in practice. The method of the feasible directions can be used without it, however.

Remark. The terms from Definitions 2, 4, and 5 are essentially related to the maximization-type problem (1), although this is not explicitly worded in them. Evidently, the corresponding terms for the minimization-type problem could be obtained by means of infimum.

The author wishes to express his thanks to Mr. Josef Nedoma for help in correcting some mistakes.

## References

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${ }^{7}$ ) The regularity condition enters the proof of the theorem only through Theorem 1.

## Souhrn

## K JEDNÉ KLASIFIKACI STACIONÁRNÍCH BODU゚ V NELINEÁRNÍM PROGRAMOVÁNÍ

## Jaroslav Hrouda

M. Altman v práci „Stationary points in non-linear programming" popsal trídy $R$-stacionárních a regulárních stacionárních bodů ( $R$ je přípustná oblast úlohy nelineárního programování v Banachově prostoru - obecně nekonvexní). V našem článku ukazujeme, že na množinách $R$ splňujících tzv. podmínku regularity jsou obě tyto třídy totožné. Definujeme širší třídu stacionarit zahrnující všechny body, k nimž může (slabě) konvergovat Zoutendijkova metoda přípustných směrů, je-li použita bez ohledu na podmínku regularity.

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[^0]:    ${ }^{1}$ ) $F$ is not assumed to be concave nor $f_{i}$ convex.
    ${ }^{2}$ ) Keeping his original notation.

[^1]:    ${ }^{3}$ ) If $M_{x}=\emptyset, N_{x}=\emptyset$, then $S(x)=E$.
    ${ }^{4}$ ) In [1] it is denoted by $\mathrm{R}_{3}$, in [3, sect. 7.7] by Cl .
    ${ }^{5}$ ) $0<\Theta_{i}<1$.

