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MIXED FORMULATION OF ELLIPTIC VARIATIONAL INEQUALITIES AND ITS APPROXIMATION

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INTRODUCTION

A dualization technique is frequently employed to obtain an approximation of variational inequalities (see [4]). A properly chosen Lagrangian \mathcal{L} enables us to transform the original minimization problem into a problem of finding its saddle-point on a certain convex set $K \times \Lambda$. This approach has some advantages:

- it avoides the complex construction of convex sets of admissible functions;

- it offers algorithms for numerical computations.

Last but not least, it makes it possible to approximate the Lagrange multipliers associated with the problem. Since these multipliers have usually a good physical meaning (for example outward fluxes, normal or friction forces), their knowledge is welcome.

In the present paper, conditions sufficient for the convergence of saddle-points $\{u_h, \lambda_H\}$ of \mathscr{L} on $K_h \times \Lambda_H$ (approximation of $K \times \Lambda$) to the saddle-point $\{u, \lambda\}$ of \mathscr{L} on $K \times \Lambda$ are studied. Applications to the unilateral problem and to problems with friction are presented.

1. MIXED FORMULATION OF VARIATIONAL INEQUALITIES

Let V, L be two real Hilbert spaces, with the norms $\|\|\|$, $\|\|$, respectively, and let V', L' be their dual spaces. On V, a quadratic functional \mathcal{J} will be given

$$\mathscr{J}(v) = \frac{1}{2} a(v, v) - \langle f, v \rangle,$$

where a is a continuous, symmetric and V-elliptic bilinear form, $f \in V'$ and \langle , \rangle denotes the duality pairing between V' and V.

Let $\mathscr{L}: V \times L \to R_1$ be a functional of the form

(1)
$$\mathscr{L}(v,\mu) = \mathscr{J}(v) + b(v,\mu) - [g,\mu],$$

where $b: V \times L \to R_1$ is a continuous bilinear form, $g \in L'$ and $[g, \mu]$ denotes the value of g at μ . Finally, let $K \subseteq V$, $\Lambda \subseteq L$ be non-empty, closed convex subsets. We make the following assumptions, concerning K and Λ :

 Λ is either

(CC) a convex cone with its vertex at Θ (zero element of L) and K = V

or

(BC) a bounded convex subset of L.

We shall consider the following problem:

$$(\mathscr{P}) \qquad \begin{cases} \text{to find an element } \{u, \lambda\} \in K \times \Lambda \text{ such that} \\ \mathscr{L}(u, \mu) \leq \mathscr{L}(u, \lambda) \leq \mathscr{L}(v, \lambda) \ \forall v \in K, \ \forall \mu \in \Lambda . \end{cases}$$

 $\{u, \lambda\}$ will be called a saddle-point of \mathscr{L} on $K \times A$.

Remark 1 $\{u, \lambda\} \in K \times \Lambda$ is a saddle-point of \mathscr{L} on $K \times \Lambda$ if and only if

(2)
$$\mathscr{L}(u,\lambda) = \min_{K} \sup_{\Lambda} \mathscr{L}(v,\mu) = \max_{\Lambda} \inf_{K} \mathscr{L}(v,\mu)$$

(see [2], [3]). Let us denote $j(v) = \sup_{A} \{b(v, \mu) - [g, \mu]\}$. It is easy to see that j is a lower semicontinuous convex function. With regard to (2) and (\mathscr{P}) we see that $u \in K$ solves the following problem:

(3)
$$\mathscr{J}(u) + j(u) = \min_{K} \left\{ \mathscr{J}(v) + j(v) \right\}.$$

An equivalent formulation of (\mathcal{P}) is the following ([3]):

$$(\mathcal{P})' \qquad \begin{cases} \text{to find } \{u, \lambda\} \in K \times \Lambda \text{ such that} \\ a(u, v - u) + b(v - u, \lambda) \ge \langle f, v - u \rangle \ \forall v \in K \\ b(u, \mu - \lambda) \le [g, \mu - \lambda] \ \forall \mu \in \Lambda. \end{cases}$$

We present two typical examples, leading to the problem (\mathcal{P}) .

Example 1 (Dualization of constraints). Let $u \in K$ be such that

$$(\mathscr{P}_1) \qquad \qquad \mathscr{J}(u) \leq \mathscr{J}(v) \quad \forall v \in K \; .$$

We shall suppose that the following characterization of K holds:

$$K = \{ v \in V \mid b(v, \mu) \leq [g, \mu] \; \forall \mu \in \Lambda \},\$$

where b, g have the above mentioned properties and Λ is a convex cone with the vertex at Θ . Then (\mathcal{P}_1) leads to the search of a saddle-point $\{u, \lambda\}$ of \mathcal{L} on $V \times \Lambda$ (see [2]) and j is the indicator function of K. In this case (CC) is satisfied.

Example 2. Let K be a closed, convex subset of the Sobolev space $H^1(\Omega)$ and

 $\Omega \subset R_2$ a bounded domain with a continuous boundary $\partial \Omega$. We look for $u \in K$, satisfying

$$(\mathscr{P}_2) \qquad \qquad \mathscr{S}(u) \leq \mathscr{S}(v) \quad \forall v \in K ,$$

where $\mathscr{S}(v) = \mathscr{J}(v) + \int_{\partial\Omega} |v| \, ds$ is a non-differentiable functional. Then (\mathscr{P}_2) leads to the search of a saddle-point $\{u, \lambda\}$ of $\mathscr{L}(v, \mu) = \mathscr{J}(v) + \int_{\partial\Omega} \mu v \, ds$ on $K \times \Lambda$, where

$$\Lambda = \left\{ \lambda \in L^2(\partial \Omega) \middle| \ \left| \lambda \right| \le 1 \text{ a.e. on } \partial \Omega \right\}.$$

In this case, $j(v) = \int_{\partial\Omega} |v| ds$ and (BC) is satisfied. We see, that introducing the new variable $\mu \in \Lambda$, we obtain a differentiable functional $\mathscr{L}(v, \mu)$, which is more suitable for numerical calculations in many cases.

The formulation (\mathcal{P}) (or $(\mathcal{P})'$) will be called a *mixed formulation of* (3).

Remark 2 (\mathscr{P})' is meaningful for a general continuous, V-elliptic bilinear form a (not necessarily symmetric). In such a case, (\mathscr{P})' is a mixed formulation of the following problem:

(4)
$$\begin{cases} \text{to find } u \in K \text{ such that} \\ a(u, v - u) + j(v) - j(u) \ge \langle f, v - u \rangle \quad \forall v \in K . \end{cases}$$

Let us mention briefly some well-known results on the existence and uniqueness of solutions of (\mathcal{P}) .

Let $b: V \times L \rightarrow R_1$ satisfy Babuška-Brezzi's condition

(5)
$$\exists \beta = \text{const.} > 0 : \sup_{V} \frac{b(v, \mu)}{\|v\|} \ge \beta |\mu| \quad \forall \mu \in L.$$

Theorem 1. Let (5) and (CC) be satisfied. Then there exists a unique solution of (\mathcal{P}) .

For the proof, see [1].

If (BC) is satisfied, the situation is much simpler.

Theorem 2. Let (BC) be satisfied. Then (\mathcal{P}) has a solution, the first component of which is uniquely determined.

Proof. The existence of a solution follows from the V-elipticity of a and the boundedness of Λ , the uniqueness of the first component from the V-elipticity of a (see [3]).

Approximation of (\mathcal{P})

Let $h, H \in (0, 1)$ be two parameters, tending to 0+. To every couple h, H we associate finite dimensional subspaces $V_h \subset V$ and $L_H \subset L$, respectively. Let K_h and Λ_H be closed, convex subsets of V_h and L_H , respectively.

Similarly as in the continuous case we make the following assumptions:

 A_{II} is either

 $(CC_H)a$ convex cone with vertex at Θ and $K_h = V_h$

or

 (BC_{H}) a convex subset of L_{H} , bounded uniformly in L, i.e. there exists a positive number c > 0 such that

$$|\mu_H| \leq c \quad \forall \mu_H \in \Lambda_H \quad \forall H \in (0, 1) .$$

By the approximation of (\mathscr{P}) we mean the problem of finding a saddle-point $\{u_h, \lambda_H\} \in K_h \times \Lambda_H$ of \mathscr{L} on $K_h \times \Lambda_H$:

$$(\mathscr{P}_{hH}) \qquad \qquad \mathscr{L}(u_h, \mu_H) \leq \mathscr{L}(u_h, \lambda_H) \leq \mathscr{L}(v_h, \lambda_H) \quad \forall v_h \in K_h , \quad \forall \mu_H \in \Lambda_H ,$$

or equivalently

$$(\mathcal{P}_{hH})' \qquad \begin{cases} \text{to find } \{u_h, \lambda_H\} \in K_h \times \Lambda_H \text{ such that} \\ a(u_h, v_h - u_h) + b(v_h - u_h, \lambda_H) \geq \langle f, v_h - u_h \rangle \ \forall v_h \in K_h \\ b(u_h, \mu_H - \lambda_H) \leq [g, \mu_H - \lambda_H] \ \forall \mu_H \in \Lambda_H. \end{cases}$$

Let us not that $K_h \notin K$ and $\Lambda_H \notin \Lambda$, in general.

Interpretation of (\mathcal{P}_{hH})

If we set $j_H(v_h) = \sup_{A_H} \{b(v_h, \mu_H) - [g, \mu_H]\}$, the first component $u_h \in K_h$ minimizes the functional $\mathscr{J}(v_h) + j_H(v_h)$ over K_h .

As far as the existence and uniqueness of (\mathcal{P}_{hH}) is concerned, results similar to those from Theorems 1, 2 hold. To this end let us suppose that there exists a positive number $\hat{\beta}$, independent of h, H and such that

(6)
$$\sup_{V_h} \frac{b(v_h, \mu_H)}{\|v_h\|} \ge \hat{\beta} |\mu_H| \quad \forall \mu_H \in L_H$$

Theorem 3. Let (CC_{II}) and (6) be satisfied. Then there exists a unique solution of (\mathcal{P}_{hH}) .

Theorem 4. Let (BC_H) be satisfied. Then there exists a solution of (\mathcal{P}_{hH}) , the first component of which is uniquely determined.

The most difficult task is the verification of (6) in particular examples.

Example 3. Let us consider the problem (\mathcal{P}_1) with

$$\mathscr{J}(v) = \frac{1}{2} \|v\|_{H^1(\Omega)}^2 - (f, v)_0, \quad f \in L^2(\Omega),$$

and

$$K = \{ v \in H^1(\Omega) | v \ge 0 \text{ on } \partial\Omega \},\$$

where $(,)_0$ denotes the $L^2(\Omega)$ -scalar product. The corresponding mixed formulation is

$$\begin{cases} \text{to find } \{u, \lambda\} \in H^1(\Omega) \times H^{-1/2}(\partial\Omega) \text{ such that} \\ (\text{grad } u, \text{grad } v)_0 + (u, v)_0 + \langle v, \lambda \rangle = (f, v)_0 \ \forall v \in H^1(\Omega) \\ \langle u, \mu - \lambda \rangle \leq 0 \ \forall \mu \in H^{-1/2}(\partial\Omega), \end{cases}$$

where $H_{-}^{-1/2}(\partial\Omega)$ denotes the convex cone of non-positive linear functionals over the space $H^{1/2}(\partial\Omega)$ and \langle , \rangle is the corresponding duality pairing. It is easy to see ([2]) that $\lambda = -\partial u/\partial n$. One can prove ([6]) that Babuška-Brezzi's condition (5) holds with $\beta = 1$.

Let $\{\mathcal{T}_h\}$ be a regular family of triangulations of $\overline{\Omega}$, whose nodes lying on $\partial\Omega$, form an equidistant partition of $\partial\Omega$. Let us denote them by $a_1, ..., a_m, a_{m+1} = a_1$. Now we set

$$V_{h} = \left\{ v_{h} \in C(\overline{\Omega}) \middle| v \middle|_{T_{i}} \in P_{1}(T_{i}) \ \forall T_{i} \in \mathscr{T}_{h} \right\}$$
$$L_{H} \equiv L_{h} = \left\{ \mu_{h} \in L^{2}(\partial \Omega) \middle| \mu_{h} \middle|_{a_{i}a_{i+1}} \in P_{0}(a_{i}a_{i+1}), \ i = 1, \dots, m \right\}$$
$$A_{H} \equiv A_{h} = \left\{ \mu_{h} \in L_{h} \middle| \mu_{h} \leq 0 \text{ on } \partial \Omega \right\},$$

where $P_1(T_i)$ and $P_0(a_i a_{i+1})$ are the spaces of *linear polynomials* on T_i and of *constant functions* on $a_i a_{i+1}$, respectively. Then the problem $(\mathcal{P}_{hH}) = (\mathcal{P}_h)$ has a solution $\{u_h, \lambda_h\}$ with a uniquely determined u_h (see [2]). Next we analyze the condition (6). Let $\mu_h \in L_h$ be such that

(6)'
$$\int_{\partial\Omega} v_h \mu_h \, \mathrm{d}s = 0 \quad \forall v_h \in V_h \Leftrightarrow \int_{\partial\Omega} \varphi_j \mu_h \, \mathrm{d}s = 0 \quad j = 1, \dots, m ,$$

where $\varphi_j \in V_h$, $\varphi_j(a_i) = \delta_{ij}$ and $\varphi_j = 0$ at the internal nodes of \mathcal{T}_h . (6)' is equivalent to the following system of linear algebraic equations:

$$\mu_{1} + \mu_{2} = 0$$

$$\mu_{2} + \mu_{3} = 0$$

$$\vdots \qquad \vdots$$

$$\mu_{1} + \mu_{m} = 0 \quad \mu_{i} = \mu|_{a_{i}a_{i+1}}.$$

If the number *m* of $a_i a_{i+1}$ is even, the system has also a non-trivial solution. Consequently, the condition (6) cannot be satisfied and the second component λ_h is not uniquely determined, in general. In order to obtain (6), we use *two systems* of partitions $\{\mathcal{F}_h\}, \{\mathcal{F}_H\}$ of $\overline{\Omega}$ and $\partial \Omega$, respectively. Let $h = \max \operatorname{diam} T_i$, $H = \max \operatorname{length} a_i a_{i+1}$, a_i nodes of \mathcal{F}_H . We define V_h in the same way as above and

$$L_{H} = \{ \mu_{H} \in L^{2}(\partial \Omega) | \mu_{H|a_{i}a_{i+1}} \in P_{0}(a_{i}a_{i+1}), i = 1, ..., m \}$$
$$\Lambda_{H} = \{ \mu_{H} \in L_{H} | \mu_{H} \leq 0 \text{ on } \partial \Omega \}.$$

If the ratio h/H is sufficiently small, then

$$\sup_{V_h} \frac{\langle v_h, \mu_H \rangle}{\|v_h\|_{H^1(\Omega)}} \ge \hat{\beta} |\mu_H|_{H^{-1/2}(\partial\Omega)} ,$$

with $\hat{\beta}$ independent of *h*, *H* (see [6]).

2. ERROR ESTIMATES

Our aim is to establish relations between u_h , u and λ_H , λ . To this end we give another, equivalent form of $(\mathcal{P})'$.

Let $\mathscr{H} = V \times L$ be a Hilbert space, equipped with the norm:

$$\|V\|_{\mathscr{H}} = \{\|v\|^2 + |\mu|^2\}^{1/2}, \quad V = (v, \mu) \in \mathscr{H},$$

 $\mathscr{A}:\mathscr{H}\times\mathscr{H}\to R_1$ a bilinear form

$$\mathscr{A}(U, V) = a(u, v) + b(v, \lambda) - b(u, \mu), \quad U = (u, \lambda) \in \mathscr{H}$$
$$V = (v, \mu) \in \mathscr{H}$$

and $\mathscr{F}:\mathscr{H}\to R_1$ a linear functional

$$\langle \mathscr{F}, \mathsf{V} \rangle = \langle f, v \rangle - [g, \mu], \quad \mathsf{V} = (v, \mu) \in \mathscr{H}.$$

The definition of A immediately implies

(7)
$$\mathscr{A}(\boldsymbol{V},\boldsymbol{V}) = a(v,v) \quad \forall \boldsymbol{V} = (v,\mu) \in \mathscr{H} ;$$

(8)
$$\exists M = \text{const.} > 0 : |\mathscr{A}(U, V)| \leq M ||U||_{\mathscr{H}} ||V||_{\mathscr{H}} \quad \forall U, V \in \mathscr{H}.$$

It is readily seen that $(\mathcal{P})'$ is equivalent to

Next, let $\mathscr{K}_{hH} = K_h \times \Lambda_H$ be a closed, convex subset of \mathscr{H} ; $\mathscr{K}_{hH} \notin \mathscr{K}$, in general. The problem

represents an approximation of (**P**), equivalent to $(\mathcal{P}_{hH})'$ (or (\mathcal{P}_{hH})).

First we prove an auxiliary lemma.

Lemma 1. Let $\{u, \lambda\}$ and $\{u_h, \lambda_H\}$ be solutions of $(\mathcal{P})'$ and $(\mathcal{P}_{hH})'$, respectively. Then

(9)
$$c \|u - u_{h}\|^{2} \leq c_{1} \{ \|u - v_{h}\|^{2} + |\lambda - \mu_{H}|^{2} \} + A_{1}(v_{h}) + A_{2}(v) + \{ b(u, \lambda_{H} - \mu) - [g, \lambda_{H} - \mu] \} + \{ b(u, \lambda - \mu_{H}) - [g, \lambda - \mu_{H}] \} + c_{2} |\lambda - \lambda_{H}|^{2}$$

holds for every $v_h \in K_h$, $v \in K$, $\mu_H \in \Lambda_H$, $\mu \in \Lambda$, where

$$A_1(v_h) = a(u, v_h - u) + b(v_h - u, \lambda) + \langle f, u - v_h \rangle$$

$$A_2(v) = a(u, v - u_h) + b(v - u_h, \lambda) + \langle f, u_h - v \rangle$$

and c, c_1, c_2 are positive constants independent of h, H.

Proof. By virtue of (7) and the definitions of (**P**) and (**P**_{*hH*}), we get – using the definitions of \mathscr{A} and \mathscr{F}

(10)
$$\begin{aligned} \alpha \| u - u_h \|^2 &\leq \mathscr{A}(U - \mathfrak{U}, \ U - \mathfrak{U}) = \mathscr{A}(U, \ U) - \mathscr{A}(\mathfrak{U}, \ U) - \\ &- \mathscr{A}(U, \ \mathfrak{U}) + \mathscr{A}(\mathfrak{U}, \ \mathfrak{U}) \leq \langle \mathscr{F}, \ U - V \rangle + \mathscr{A}(U, \ V) + \\ &+ \langle \mathscr{F}, \ \mathfrak{U} - \mathfrak{V} \rangle + \mathscr{A}(\mathfrak{U}, \ \mathfrak{V}) - \mathscr{A}(U, \ U) - \mathscr{A}(U, \ U) = \\ &= \langle \mathscr{F}, \ U - \mathfrak{V} \rangle + \langle \mathscr{F}, \ \mathfrak{U} - V \rangle + \mathscr{A}(U, \ V - \mathfrak{U}) + \\ &+ \mathscr{A}(\mathfrak{U} - U, \ \mathfrak{V} - U) + \mathscr{A}(U, \ \mathfrak{V} - U) = A_1(v_h) + A_2(v) + \\ &+ \{b(u, \ \lambda_H - \mu) - [g, \ \lambda_H - \mu]\} + \{b(u, \ \lambda - \mu_H) - \\ &- [g, \ \lambda - \mu_H]\} + a(u_h - u, \ v_h - u) + b(v_h - u, \ \lambda_H - \lambda) - \\ &- b(u_h - u, \ \mu_H - \lambda) \,. \end{aligned}$$

The boundedness of a, b together with the inequality $2hf \leq 1/\epsilon h^2 + \epsilon f^2$ yields

(11)
$$\alpha \| u - u_h \|^2 \leq A_1(v_h) + A_2(v) + \{ b(u, \lambda_H - \mu) - [g, \lambda_H - \mu] \} + + \{ b(u, \lambda - \mu_H) - [g, \lambda - \mu_H] \} + M_1 \varepsilon \| u - u_h \|^2 + + M_1/\varepsilon \| u - v_h \|^2 + M_2/\varepsilon \| v_h - u \|^2 + M_2 \varepsilon |\lambda_H - \lambda|^2 + + M_2 \varepsilon \| u - u_h \|^2 + M_2/\varepsilon |\lambda - \mu_H|^2 .$$

For $\varepsilon > 0$ sufficiently small, we arrive at (9).

As a direct consequence of Lemma 1, we obtain

Theorem 5. Let (CC), (CC_H) and (6) be satisfied. Let there exist a solution $\{u, \lambda\}$ of $(\mathcal{P})'$. Then

(12)
$$c \|u - u_{h}\|^{2} \leq c_{1}\{\|u - v_{h}\|^{2} + |\lambda - \mu_{H}|^{2}\} + \{b(u, \lambda_{H} - \mu) - [g, \lambda_{H} - \mu]\} + \{b(u, \lambda - \mu_{H}) - [g, \lambda - \mu_{H}]\},$$
(12)

(13)
$$|\lambda - \lambda_H| \leq c\{||u - u_h|| + |\lambda - \mu_H|\}$$

hold for any $v_h \in V_h$, $\mu \in \Lambda$, $\mu_H \in \Lambda_H$ with positive constants c, c_1 .

Proof. Since (CC) and (CC_H) are satisfied, K = V, $K_h = V_h$, i.e. K and K_h are linear sets. Therefore, in $(\mathcal{P})'_2$ and $(\mathcal{P}_{hH})'_2$ the sign of equality can be written, so that

(14)
$$A_1(v_h) = 0 \quad \forall v_h \in V_h$$

As K = V and $V_h \subset V \forall h \in (0, 1)$, we can choose $v = u_h$ in (9). Hence

(15) $A_2(v) = 0$.

Let $\mu_H \in \Lambda_H$ be arbitrary. From (6) we obtain

(16)
$$\hat{\beta}|\lambda_H - \mu_H| \leq \sup_{Vh} \frac{b(v_h, \mu_H - \lambda_H)}{\|v_h\|}$$

Using $(\mathcal{P}_{hH})_2'$ and $(\mathcal{P})_2'$, we may write

$$b(v_h, \mu_H - \lambda_H) = b(v_h, \mu_H) - b(v_h, \lambda_H) = b(v_h, \mu_H) + a(u_h, v_h) - \langle f, v_h \rangle = b(v_h, \mu_H) + a(u_h, v_h) - a(u, v_h) - b(v_h, \lambda) = b(v_h, \mu_H - \lambda) + a(u_h - u, v_h) \leq c\{|\mu_H - \lambda| + ||u_h - u||\} ||v_h|$$

This identity together with (16) implies

$$|\mu_H - \lambda_H| \leq c\{||u - u_h|| + |\lambda - \mu_H|\} \quad \forall \mu_H \in \Lambda_H.$$

Using the triangle inequality

$$|\lambda - \lambda_H| \leq |\lambda - \mu_H| + |\mu_H - \lambda_H| \quad \forall \mu_H \in \Lambda_H$$

we obtain (13). Finally, replacing the term $M_2 \varepsilon |\lambda_H - \lambda|$ on the right hand side of (11) by (13) and making use of (14) and (15), we obtain (12) for $\varepsilon > 0$ sufficiently small.

Remark 3. If $\Lambda_H \subset \Lambda$ for $\forall H \in (0, 1)$, we can insert $\mu = \lambda_H$ into (12). Therefore, (12) takes the following simpler form:

(12')
$$c \|u - u_{h}\|^{2} \leq c_{1}\{\|u - v_{h}\|^{2} + |\lambda - \mu_{H}|^{2}\} + \{b(u, \lambda - \mu_{H}) - [g, \lambda - \mu_{H}]\} \quad \forall v_{h} \in V_{h}, \quad \mu_{H} \in \Lambda_{H}.$$

Theorem 6. Let (BC) and (BC_H) be satisfied. Then

(17)
$$c \|u - u_{h}\|^{2} \leq A_{1}(v_{h}) + A_{2}(v) + c_{1}\{\|u - v_{h}\|^{2} + |\lambda - \mu_{H}|^{2}\} + c_{2}\|u - v_{h}\| + \{b(u, \lambda_{H} - \mu) - [g, \lambda_{H} - \mu]\} + \{b(u, \lambda - \mu_{H}) - [g, \lambda - \mu_{H}]\}$$

$$holds for any v_{h} \in K_{h}, v \in K, \ \mu \in A, \ \mu_{H} \in A_{H}.$$

(18) Moreover if K = V, $K_h = V_h$ and (6) is satisfied, then (12) and (13) hold.

Proof. We have to prove (17) only. As Λ , Λ_H are bounded in L,

$$|b(v_h - u, \lambda_H - \lambda)| \leq c ||v_h - u|| \quad \forall v_h \in K_h$$

Hence (17) follows by virtue of (10).

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Remark 4. If $K_h \subset K$, $\Lambda_H \subset \Lambda \forall h, H \in (0, 1)$ then setting $v = u_h$, $\mu = \lambda_H$, we obtain $A_2(v) = 0$, $b(u, \lambda_H - \mu) - [g, \lambda_H - \mu] = 0$.

Next, let us suppose that the pair of real parameters h, H satisfies

$$h \rightarrow 0+ \Leftrightarrow H \rightarrow 0+$$

Relations (12), (13) and (17) can be used to estimate the rate of convergence of u_h to u and λ_H to λ , provided the exact solution is smooth enough. Other application are given by the following convergence theorems.

Theorem 7. Let (BC), (BC_H) be satisfied and, moreover let

(19)
$$\forall v \in K \quad \exists v_h \in K_h : v_h \to v \text{ in } V;$$

- (20) $\forall \mu \in \Lambda \quad \exists \mu_H \in \Lambda_H : \mu_H \to \mu \text{ in } L;$
- (21) $v_h \in K_h$, $v_h \rightarrow v$ (weakly) in V implies $v \in K$;

(22)
$$\mu_H \in \Lambda_H, \quad \mu_H \to \mu \quad in \ Limplies \quad \mu \in \Lambda;$$

(23)
$$\exists r > 0 \quad \exists \{v_h\}, \quad v_h \in K_h \quad such \ that \quad ||v_h|| \leq r \quad \forall h \in (0, 1).$$

Let the solution $\{u, \lambda\} \in Kx \land of (\mathcal{P})'$ be unique. Then

$$u_h \to u$$
 in V , $\lambda_H \to \lambda$ in L .

Proof. First, $\{u_h\}$, $\{\lambda_H\}$ are bounded. For $\{\lambda_H\}$ this follows from (BC_H) , for $\{u_h\}$ from (23) and $(\mathscr{P}_{hH})_2'$. Hence, there exists a subsequence $\{u_{h'}, \lambda_{H'}\} \subset \{u_h, \lambda_H\}$ and $\{u^*, \lambda^*\} \in V \times L$ such that

(24)
$$u_{h'} \rightarrow u^* \text{ in } V, \quad \lambda_{H'} \rightarrow \lambda^* \text{ in } L.$$

By virtue of (21), (22), $u^* \in K$, $\lambda^* \in \Lambda$. Let us show that $\{u^*, \lambda^*\}$ is a solution of $(\mathscr{P})'$. Let $\{v, \mu\} \in K \times \Lambda$ be an arbitrarily chosen element. From (19), (20) we conclude that there exist $v_h \in K_h$, $\mu_H \in \Lambda_H$ such that

(25)
$$v_{\rm h} \rightarrow v \text{ in } V, \quad \mu_H \rightarrow \mu \text{ in } L.$$

Since $\{u_{h'}, \lambda_{H'}\}$ is a solution of $(\mathcal{P}_{h'H'})'$, it satisfies

(26)
$$a(u_{h'}, u_{h'} - v_{h'}) + b(u_{h'} - v_{h'}, \lambda_{H'}) \leq \langle f, u_{h'} - v_{h'} \rangle \quad \forall v_{h'} \in K_h$$

(27)
$$b(u_{h'}, \mu_{H'} - \lambda_{H'}) \leq [g, \mu_{H'} - \lambda_{H'}] \quad \forall \mu_{H'} \in \Lambda_{H'}.$$

Passing to the limit for $h', H' \rightarrow 0+$ in (26), together with (24), (25) implies that

(28)
$$a(u^*, u^* - v) + \liminf_{h', H'} b(u_{h'}, \lambda_{H'}) - b(v, \lambda^*) \leq \langle f, u^* - v \rangle \quad \forall v \in K.$$

The same procedure is applicable to (27):

(29)
$$b(u^*,\mu) - [g,\mu-\lambda^*] \leq \liminf_{\mathbf{h}',\mathbf{H}'} b(u_{\mathbf{h}'},\lambda_{\mathbf{H}'}) \quad \forall \mu \in \Lambda.$$

Setting $\mu = \lambda^*$ in (29), we obtain

(30)
$$b(u^*, \lambda^*) \leq \liminf_{h', H'} b(u_{h'}, \lambda_{H'}).$$

Substitution of (30) into (28) yields:

$$a(u^*, u^* - v) + b(u^* - v, \lambda^*) \leq \langle f, u^* - v \rangle \quad \forall v \in K.$$

The choice $v = u^*$ in (28) implies:

$$\liminf_{h',H'} b(u_{h'}, \lambda_{H'}) \leq b(u^*, \lambda^*)$$

From this and (29), we have

$$b(u^*, \mu - \lambda^*) \leq [g, \mu - \lambda^*] \quad \forall \mu \in \Lambda$$

Thus $\{u^*, \lambda^*\}$ is a solution of $(\mathscr{P})'$. By virtue of its uniqueness, the whole sequences $\{u_h\}, \{\lambda_H\}$ tend weakly to u, λ . Let us show that $u_h \to u$ strongly in V. Let $\{\bar{v}_h\}, \bar{v}_h \in K_h, \{\bar{\mu}_H\}, \bar{\mu}_H \in \Lambda_H$ be such that

$$\bar{v}_h \to u \;, \quad \bar{\mu}_H \to \lambda \;.$$

Applying (17) with v = u, $\mu = \lambda$, $v_h = \bar{v}_h$, $\mu_H = \bar{\mu}_H$ and using the weak convergence $u_h \rightarrow u$, $\lambda_H \rightarrow \lambda$, we obtain $u_h \rightarrow u$ in V.

Remark 5. If $K_h \subset K$ and $\Lambda_H \subset \Lambda$, the conditions (21) and (22) respectively, are satisfied.

Theorem 8. Let (CC), (CC_{II}) and (6) be satisfied. Let $\{u, \lambda\}$ be the unique solution of $(\mathcal{P})'$. Moreover, let us suppose that

(31)
$$\forall v \in V \quad \exists v_h \in V_h : v_h \to v \text{ in } V;$$

(32)
$$\forall \mu \in \Lambda \quad \exists \mu_H \in \Lambda_H : \mu_H \to \mu \text{ in } L;$$

(33)
$$\mu_H \in \Lambda_H, \quad \mu_H \to \mu \quad in \ Limplies \quad \mu \in \Lambda;$$

(34) there exist a real number d, a positive number c and a bounded sequence $\{\bar{v}_h\}, \bar{v}_h \in V_h$ such that $j_H(v_h) \ge d \ \forall v_h \in V_h, \ \forall h, \ H \in (0, 1), \ j_H(\bar{v}_h) \le c \ \forall h, \ H \in (0, 1).$

Then $u_h \rightarrow u, \ \lambda_H \rightarrow \lambda$.

Proof. We shall prove the boundedness of $\{u_h\}$ and $\{\lambda_H\}$ only. The rest of the proof is analogous to that of Theorem 7. The convergence of λ_H to λ follows from (13).

According to the interpretation of $(\mathcal{P}_{hH})'$, $u_h \in V_h$ satisfies

$$a(u_h, v_h - u_h) + j_H(v_h) - j_H(u_h) \ge \langle f, v_h - u_h \rangle \quad \forall v_h \in V_h$$

Hence

$$a(u_h, u_h) + j_H(u_h) \leq a(u_h, \bar{v}_h) + j_H(\bar{v}_h) - \langle f, \bar{v}_h - u_h \rangle.$$

This and (34) implies the boundedness of $\{u_h\}$ and by virtue of (13) we deduce the boundedness of $\{\lambda_H\}$.

Remark 6. If $A_H \subset A \ \forall H \in (0, 1)$, (33) is automatically satisfied.

Condition (6), guaranteeing the convergence of λ_H to λ is very restrictive. That is why we shall be interested in the convergence u_h to u only if (CC) and (CC_H) hold. To this end let us suppose that the functions

$$j(v) = \sup_{A} \{b(v, \mu) - [g, \mu]\}$$
$$j_{H}(v_{h}) = \sup_{A_{H}} \{b(v_{h}, \mu_{H}) - [g, \mu_{H}]\}$$

take their values from the set $\{0, +\infty\}$. We shall denote by

$$\mathscr{K} = \left\{ v \in V \middle| j(v) = 0 \right\}$$
$$\mathscr{K}_{hH} = \left\{ v_h \in V_h \middle| j_H(v_h) = 0 \right\},$$

i.e. *j* and j_H are the *indicator functions* of the closed convex sets \mathscr{H} and \mathscr{H}_{hH} , respectively. Let $\{u, \lambda\} \in V \times A$ and $\{u_h, \lambda_H\} \in V_h \times A_H$ be solutions of (\mathscr{P}) and (\mathscr{P}_{hH}) , respectively. From the interpretation of these problems we see that $u \in \mathscr{H}$ and $u_h \in \mathscr{H}_{hH}$ are solutions of the minimizing problems:

$$\mathcal{J}(u) \leq \mathcal{J}(v) \quad \forall v \in \mathcal{K}$$

and

$$\mathscr{J}(u_h) \leq \mathscr{J}(v_h) \quad \forall v_h \in \mathscr{K}_{hH} ,$$

respectively.

As far as the convergence of u_h to u is concerned, we have

Theorem 9. Let (CC), (CC_H) be satisfied and there exist solutions $\{u, \lambda\}$ and $\{u_h, \lambda_H\}$ of (\mathcal{P}) and (\mathcal{P}_{hH}) , respectively, the first components of which are uniquely determined. Let

(35)
$$\forall v \in \mathscr{K} \quad \exists v_h \in \mathscr{H}_{hH} : v_h \to v \text{ in } V;$$

(36)
$$v_h \in \mathscr{H}_{hH}, \quad v_h \to v \text{ in } V \text{ implies } v \in \mathscr{H}$$

Then $u_h \rightarrow u$ in V.

Proof is a direct consequence of Th. 0.6 from [2].

3. APPLICATIONS

Example A. Let us consider the unilateral boundary value problem introduced in Example 3, with the same definitions of V_h , L_H and Λ_H . First, we consider the case,

when h = H, i.e. the partition of $\partial \Omega$ is generated by the triangulation \mathcal{T}_h of $\overline{\Omega}$. In that case

$$\mathscr{K}_{hH} \equiv \mathscr{K}_h = \left\{ v_h \in V_h \middle| v_h(a_{i+1/2}) \ge 0, \ i = 1, ..., m \right\},$$

where $a_{i+1/2}$ is the midpoint of $a_i a_{i+1}$. It means that \mathscr{K}_h contains all piecewise linear functions, the mean values of which are non-negative on $a_i a_{i+1}$. The function $j_h(v_h) = \sup \langle v_h, \mu_h \rangle$ is the indicator function of \mathscr{K}_h .

Now, let us suppose that h/H is sufficiently small. Then the condition (6) holds and one can use Theorem 5 for estimating the rate of convergence of u_h to u and λ_H to λ under some additional assumptions. We can prove the following result:

Theorem 10. Let

(i) $u \in K \cap H^2(\Omega)$; (ii) $u \in H^{1,\infty}(a_i a_{i+1}), i = 1, ..., m$; (iii) the set of points where u changes from u > 0 to u = 0 is finite. Then

$$\begin{aligned} \|u - u_h\|_{H^1(\Omega)} &\leq c(u) (h + H) \\ \|\lambda - \lambda_H\|_{H^{-1/2}(\partial\Omega)} &\leq c(u, \lambda) (h + H) \\ \|\lambda - \lambda_H\|_{L^2(\partial\Omega)} &\leq c(u, \lambda) h^{-1/2} (h + H) . \end{aligned}$$

For the proof see [6].

Example B. Let us define the following problem:

$$\begin{cases} to find \ u \in H^1(\Omega) \ such that \\ \mathscr{S}(u) \leq \mathscr{S}(v) \quad \forall v \in H^1(\Omega), \end{cases}$$

where $\mathscr{S}(v) = \frac{1}{2} \|v\|_{H^1(\Omega)}^2 + g \int_{\partial\Omega} |v| \, ds - (f, v)_0$ with $g \in R_1, g > 0, f \in L^2(\Omega)$. The corresponding Lagrangian of this problem is

$$\mathscr{L}(v,\mu) = \frac{1}{2} \|v\|_{H^{1}(\Omega)}^{2} + g \int_{\partial\Omega} \mu v \, \mathrm{d}s - (f,v)_{0} \, ,$$

 $(v, \mu) \in H^1(\Omega) \times \Lambda$ and

$$\Lambda = \left\{ \mu \in L^2(\partial \Omega) \middle| \ \left| \mu \right| \le 1 \text{ a.e. on } \partial \Omega \right\}$$

It is easy to see that there exists a unique saddle-point $\{u, \lambda\}$ of \mathscr{L} on $H^1(\Omega) \times \Lambda$ and $\partial u/\partial n = -\lambda g$.

We define V_h as in the example A, $K_h = V_h$ and

$$\Lambda_H \equiv \Lambda_h = \left\{ \mu_h \in L^2(\partial \Omega) \middle| \ \mu_{h|a_i a_{i+1}} \in P_0(a_i a_{i+1}), \ \left| \mu_h \right| \le 1 \text{ on } \partial \Omega \right\}.$$

It is easy to verify that the conditions (19)–(23) are satisfied. Hence $u_h \to u$ in $H^1(\Omega)$, $\lambda_h \to \lambda$ in $L^2(\partial \Omega)$.

If the ratio h/H is sufficiently small, then Babuška-Brezzi's condition (6) is fulfilled and a result, similar to Theorem 10 can be obtained. Example C. (Signorini problem with friction.) Let $\Omega \subset R_2$ be a bounded, polygonal domain, the boundary of which is decomposed as follows: $\partial \Omega = \overline{\Gamma}_u \cup \overline{\Gamma}_K$, where Γ_u , Γ_K are non-empty and open subsets of $\partial \Omega$. Let

$$V = \left\{ v \in (H^1(\Omega))^2 \middle| v = 0 \text{ on } \Gamma_u \right\},$$
$$K = \left\{ v \in V \middle| v_n \le 0 \text{ on } \Gamma_K \right\},$$

where $v_n = v \cdot n$ is the normal component of v. We shall consider the problem

$$\begin{cases} \text{to find } \mathbf{u} \in \mathbf{K} \text{ such that} \\ \mathscr{S}(\mathbf{u}) \leq \mathscr{S}(\mathbf{v}) \quad \forall \mathbf{v} \in \mathbf{K}, \end{cases}$$

where $\mathscr{S}(\mathbf{v}) = \frac{1}{2} \int_{\partial\Omega} \tau_{ij}(\mathbf{v}) \varepsilon_{ij}(\mathbf{v}) d\mathbf{x} + g \int_{\partial\Omega} |v_t| d\mathbf{s} - \int_{\Omega} f_i v_i d\mathbf{x}, \varepsilon_{ij}(\mathbf{v}) = \frac{1}{2} (\partial v_i / \partial x_j + \partial v_j / \partial x_i)$ and $\tau_{ij}(\mathbf{v})$ are components of the strain and stress tensor, respectively, corresponding to the displacement \mathbf{v} and mutually coupled by the linear Hooke's law. Finally, let $f = (f_1, f_2) \in (L^2(\Omega))^2$, $g \in R_1$, g > 0 and $v_t = \mathbf{v} \cdot \mathbf{t}$ be the tangential component of \mathbf{v} . The corresponding Lagrangian is defined on $\mathbf{K} \times \Lambda$, where

$$\Lambda = \left\{ \mu \in L^2(\Gamma_K) \middle| \ \left| \mu \right| \le 1 \text{ a.e. on } \Gamma_K \right\}$$

as follows

$$\mathscr{L}(\boldsymbol{v},\mu) = \frac{1}{2} \int_{\Omega} \tau_{ij}(\boldsymbol{v}) \,\varepsilon_{ij}(\boldsymbol{v}) \,\mathrm{d}x \,+\, g \int_{\Gamma_{k}} \mu v_{i} \,\mathrm{d}s \,-\, \int_{\Omega} f_{i} v_{i} \,\mathrm{d}x \,.$$

It is readily seen that there exists a unique saddle-point $\{u, \lambda\}$ of \mathscr{L} on $K \times \Lambda$ and $T_t(u) = -g\lambda$, where $T_t(u)$ denotes the tangential traction component on Γ_K . Application of this formulation will be discussed in [7].

Example D. (Signorini problem with friction.) We shall consider the problem from Example C. Let $\Lambda = \Lambda_1 \times \Lambda_2$ be a closed convex subset of $(H^{-1/2}(\Gamma_K))^2$ (dual space to $(H^{1/2}(\Gamma_K))^2$), where

$$\Lambda_1 = \left\{ \mu_1 \in H^{-1/2}(\Gamma_K), \ \mu_1 \ge 0 \right\}$$
$$\Lambda_2 = \left\{ \mu_2 \in L^2(\Gamma_K), \ |\mu_2| \le g \text{ a.e. on } \Gamma_K \right\}$$

Moreover, we suppose that Γ_K is a straight segment. Let

$$\mathscr{L}(\boldsymbol{v},\mu_1,\mu_2) = \frac{1}{2} \int_{\Omega} \tau_{ij}(\boldsymbol{v}) \,\varepsilon_{ij}(\boldsymbol{v}) \,\mathrm{d}x + \langle \mu_1, v_n \rangle + \langle \mu_2, v_i \rangle - \int_{\Omega} f_i v_i \,\mathrm{d}x$$

be the Lagrangian, defined on $Vx \Lambda_1 \times \Lambda_2$. It can be proved that \mathscr{L} has a unique saddle-point $\{u, \lambda_1, \lambda_2\}$ on $Vx \Lambda_1 \times \Lambda_2$ and $\lambda_1 = -T_n(u)$, $\lambda_2 = -T_t(u)$, where $T_n(u)$ denotes the normal traction component on Γ_K . Analysis of this above formulation will be discussed in [5]. Let us mention, that although the theory, presented here is not directly, applicable to this formulation, a slight modification will do.

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Souhrn

SMÍŠENÁ FORMULACE ELIPTICKÝCH VARIAČNÍCH NEROVNOSTÍ A JEJÍ APROXIMACE

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V této práci se studuje aproximace smíšené formulace eliptických variačních nerovnic. Smíšená formulace je definována jako problém nalezení sedlového bodu Lagrangeovy funkce \mathcal{L} na kartézském součinu konvexních množin $K \times \Lambda$. Její aproximace je pak definována jako úloha nalezení sedlového bodu \mathcal{L} na $K_h \times \Lambda_H$, kde K_h , Λ_H jsou konečně-dimensionální aproximace K, Λ . Jsou vysloveny postačující podmínky k tomu, aby takto nalezené aproximace na $K_h \times \Lambda_H$ konvergovaly k sedlovému bodu \mathcal{L} na $K \times \Lambda$. Obecné výsledky jsou pak aplikovány na konkrétní příklady.

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