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COMMENTATIONES MATHEMATICAE UNIVERSITATIS CAROLINAE

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A NOTE ON THE EXISTENCE OF MORE THAN ONE SOLUTION FOR ASYMPTOTICALLY LINEAR EQUATIONS

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Abstract: Consider the nonlinear operator equation Lu + $\overline{N(u)} = f$ with nonlinearity satisfying $P_0N(x_0) \rightarrow 0$ as $\|x_0\| \rightarrow \infty$ for x_0 in Ker L, P_0 being the projection onto Coker L. Under additional hypotheses we show that this equation has the property that for $\|P_0f\|$ sufficiently small, it has at least two solutions.

Key words: Fredholm, semilinear alternative problems, degree, Leray-Schauder degree, homotopy.

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Introduction. Consider the nonlinear operator equation

(A) Lu + N(u) = f

where L is a linear Fredholm map of index zero between Banach spaces X and Y and N is a compact uniformly bounded map of X into Y. Using the notation $X_0 = \text{Ker L}$, $P_0 = \text{projection onte}$ Coker L, we decompose each x in X into $x_0 + x_1$ where $X \neq X_0 \oplus$ $\oplus X_1$ and X_1 is some complement of X_0 in X. We assume

(H.1) Given $\varepsilon > 0$ and $k \ge 0$ there exists $\rho > 0$ such that if $||x_1|| \le k$ and $||x_0|| \ge \rho$, $||P_0N(x_0 + x_1)|| < \varepsilon$. In addition, suppose Ker L is one-dimensional and

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(H.2) For any M, there exists a number R_0 such that if $||x_1|| \leq M$ and $||x_0|| \geq R_0 P_0 N(x_0 + x_1)$ and $P_0 N(-x_0 + x_1)$ are of opposite signs.

Then the followin result is known:

<u>Theorem</u>. Assuming (H.1) and (H.2), the equation (A) has a solution for each f in the range of L. Furthermore there is a number c depending on P_1f , where $P_1 = I - P_0$ is the projection onto the range of L, such that for $||P_0f|| < c(P_1f)$ (A) has a solution.

Examples of boundary-value problems where essentially this abstract result is used can be found in references [1], [2], and [3].

The generalization of this theorem to the case where dim Ker L>1 is easily seen. Let $\{x_{oi}\}_{i=1,...,n}$ be a fixed basis of unit vectors spanning Ker L and let an arbitrary element of Ker L be denoted by $a \cdot x_o$ where $a = (a_1,...,a_n)$ $x_o = (x_{o1},...,x_{on})$ and $a \cdot x_o = a_1x_{o1} + ... + a_nx_{on}$. Instead of (H.2) assume

(H.3) For any M there exists a number R_0 such that $||x_1|| \leq M$ and $|a| \geq R_0$ imply $P_0N(a \cdot x_0 + x_1) \neq 0$ and letting $\varphi(a) = P_0N(a \cdot x_0)$ be regarded as a map of \mathbb{R}^n into \mathbb{R}^n , assume for $\mathbb{R} \geq \mathbb{R}_0$

(H.4) deg $(\phi, 0, D_R^n) \neq 0$ where D_R^n is the ball of radius R in \mathbb{R}^n and deg is the standard Brouwer degree.

Clearly for the case of a one-dimensional kernel, (H.3) and (H.4) are equivalent to (H.2). The result now reads as follows:

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<u>Theorem</u>. Let L and N be as above with N satisfying (H.1), (H.3), and (H.4). Then for each f, there is a number $c(P_1f)$ such that for $||P_0f|| < c(P_1f)$, (A) has a solution.

A variant of this result has been proved and used by Mawhin in the study of periodic solutions of ordinary vector differential equations. (See [4] and [5]).

In this note we extend the results mentioned above by 'showing that for $\|P_0f\|$ sufficiently small and $\neq 0$, (A) has in fact at least two solutions.

<u>Section 1.</u> Here we formally state and prove our main result.

<u>Theorem 1</u>. Suppose N satisfies (H.1),(H.3),and (H.4). Then for each f, there exists a number $c(P_1f)$ such that for $0 < ||P_0f|| < c(P_1f)$, equation (A) has at least two solutions. Here $c(P_1f)$ is the same constant needed in the previously mentioned work.

To prove Theorem 1, using the standard method for semilinear alternative problems, we rewrite (A) as

(1) $F(x_1, a) = 0$

where F: $X_1 \times \mathbb{R}^n \longrightarrow X_1 \times \mathbb{R}^n$ is given by

(2) $F(x_1,a) = (x_1 + L^{-1}P_1 [N(a \cdot x_0 + x_1) - f],$ $P_0N(a \cdot x_0 + x_1) - P_0f)$

Here P_1 is the projection onto $L(X_1)$ and L: $X_1 \rightarrow L(X_1)$ has an inverse which we have denoted as L^{-1} . Let $D_k = \{(x_1, a): ||x_1|| + |a| \le k\}$ and let S_k be its boundary. Then we have

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.<u>Lemma 1</u>. There exist constants c and k such that if $\|P_0f\| < c$, $\deg_{IS}(F,(0,0),D_k) \neq 0$, where \deg_{IS} is the Leray-Schauder degree. Furthermore these constants depend on P_1f .

Proof. Let
(3)
$$H(x_1,a,t) = (x_1 + tL^{-1}P_1[N(a \cdot x_0 + x_1) - f],$$

 $P_0N(a \cdot x_0 + tx_1) - P_0f)$

We claim that there exist constants, c, k such that if $\|P_0f\| < c, H(x_1,a,t) \neq 0$ on S_k . This is easily seen since if the first component of H is zero, by (3),

$$(4) || \mathbf{x}_{1} || \leq || \mathbf{L}^{-1} \mathbf{P}_{1} || [\sup_{\mathbf{x} \in \mathbf{X}} || \mathbf{N}(\mathbf{x}) || + || \mathbf{P}_{1} \mathbf{f} ||] \equiv \mathbf{M}$$

and thus by hypothesis, there exists R_0 such that $P_0N(\mathbf{a} \cdot \mathbf{x}_0 + \mathbf{x}_1) \neq 0$ for $||\mathbf{x}_1|| \neq M$ and $|\mathbf{a}| \geq R_0$ so that on the bounded set $\{(\mathbf{x}_1, \mathbf{a}): ||\mathbf{x}_1|| \neq M, R_0 \neq |\mathbf{a}| \neq R_0 + M\}$ there is some constant $\alpha > 0$ such that $||P_0N(\mathbf{a} \cdot \mathbf{x}_0 + \mathbf{x}_1)|| > \alpha$. Thus picking $\mathbf{c} = \alpha$, if $||P_0f|| < \mathbf{c}$ and $\mathbf{k} = M + R_0$ we have $H(\mathbf{x}_1, \mathbf{a}, \mathbf{t}) \neq 0$. This gives us that $H(\mathbf{x}_1, \mathbf{a}, 0)$ is homotopic to $H(\mathbf{x}_1, \mathbf{a}, 1)$ on S_k . But $H(\mathbf{x}_1, \mathbf{a}, 1) =$ $= F(\mathbf{x}_1, \mathbf{a})$ and

(5)
$$H(x_1,a,0) = (x_1,P_0N(a \cdot x_0) - P_0f)$$

so that

 $\deg_{IS}(F,(0,0),D_k) = \deg (P_0N(a \cdot x_0) - P_0f,0,D_k^n)$ $= \deg (\phi,0,D_k^n) \neq 0 \text{ by hypothesis (H.4).}$

It is easily seen from (4) and the subsequent inequalities that c and k depend on P_1f .

Lemma 2. If $P_0 f \neq 0$, there is a k_1 depending on $P_0 f$

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such that $\deg_{LS}(F, (0,0), D_{k_1}) = 0$.

<u>Proof</u>. Let $k_1 = M + \rho$ where M is given by equation (4) and ρ is given by hypothesis (H.1) with $\epsilon = \|P_0f\|$.

Thus on Sk,

 $G(x_{1},a,t) = (x_{1} + tL^{-1}P_{1}[N(a \cdot x_{0} + x_{1}) - f],$ $tP_{0}(a \cdot x_{0} + x_{1}) - P_{0}f)$

is a non-vanishing homotopy between $F(x_1,a)$ and $G(x_1,a,0) = (x_1, -P_of)$. But clearly

 $\deg_{IS}(G,(0,0),D_{k_1}) = 0$

since G is not surjective. Thus deg_{LS}(F,(0,0),D_{k1}) = 0.

Finally we have

<u>Proof of Theorem 1</u>. Given f, suppose $||P_0f|| < c$, where c is given in Lemma 1. Then there exists k such that $\deg_{IS}(F,(0,0),D_k) \neq 0$. But by Lemma 2, there is a k_1 such that $\deg_{IS}(F,(0,0),D_k) \neq 0$. Therefore there must be a zero of F between S_k and S_{k_1} . Thus we conclude that for $||P_0f|| < < c$, F must have at least two zeros.

<u>Remark.</u> Note that if $P_0 f = 0$, the proof of Lemma 2 breaks down, and in fact Prof. Fučík has pointed out to me that the boundary-value problem with f = 0

$$-u'' - u + u(1 + u^2)^{-1} = 0$$
$$u(0) = u(w) = 0$$

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satisfying (H.1) and (H.2), is uniquely solvable.

I would like to express my thanks to Prof. Fučík for the current formulation of hypothesis (H.1).

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