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ON THE INTEGRAL GEOMETRY OF THE LINEAR SUBSPACES IN A BIPLANAR SPACE

ADRIJAN V. BORISOV (Received February 2, 1982)

Let J_p and K_q be fixed skew linear subspaces of the *n*-dimensional real projective space P_n , such that dim $J_p = p$, dim $K_q = q$, $p \le q$ and p + q = n - 1. The biplanar Kleinian space $B_n^{p,q}$ has P_n as the underlying space and its fundamental group G_L consists of all collineations of P_n preserving J_p and K_q . The subspaces J_p and K_q together form the absolute of $B_n^{p,q}$. The dimension of G_L is equal to $L = p^2 + q^2 + 2(p+q) + 1$.

We use a family of biplanar frames $R_L = (A_1 A_2 \dots A_{p+1} B_1 B_2 \dots B_{q+1})$ having the following property: the vertices A_1, A_2, \dots, A_{p+1} lie in J_p and B_1, B_2, \dots, B_{q+1} lie in K_q . An arbitrary element of G_L has the form

$$x'_{i} = \sum_{j=1}^{p+1} a_{ij} x_{j}, \qquad i = 1, ..., p+1,$$

$$y'_{u} = \sum_{v=1}^{q+1} b_{uv} y_{v}, \qquad u = 1, ..., q+1,$$

where $A = \det(a_{ij}) \neq 0$ and $B = \det(b_{uv}) \neq 0$. Without loss of generality we can suppose that

$$A.B=1.$$

Let

$$dA_{i} = \sum_{j=1}^{p+1} \omega_{i}^{j} A_{j}, \qquad i = 1, ..., p+1,$$

$$dB_{u} = \sum_{p=1}^{q+1} \psi_{u}^{p} B_{v}, \qquad u = 1, ..., q+1$$

be the infinitesimal transformations of R_L , where the 1-forms

(2)
$$\omega_i^j = \frac{1}{A} | A_1 \dots A_{j-1} dA_i A_{j+1} \dots A_{p+1} |,$$

$$\psi_u^p = \frac{1}{B} | B_1 \dots B_{p-1} dB_u B_{p+1} \dots B_{q+1} |$$

satisfy the structure equations

$$D\omega_i^j = \sum_{k=1}^{p+1} \omega_i^k \wedge \omega_k^j, \qquad i, j = 1, \dots, p+1,$$

$$D\psi_u^v = \sum_{w=1}^{q+1} \psi_u^w \wedge \psi_w^v, \qquad u, v = 1, \dots, q+1$$

and the unique non-differential condition

(3)
$$\sum_{i=1}^{p+1} \omega_i^i + \sum_{u=1}^{q+1} \psi_u^u = 0,$$

which is a consequence of (1). If we consider the homogeneous coordinates

(4)
$$A_{i}(a_{1i}, a_{2i}, ..., a_{p+1.i}, 0, 0, ..., 0), \qquad i = 1, ..., p+1, \\ (B_{u}(0, 0, ..., 0, b_{1u}, b_{2u}, ..., b_{q+1.u}), \qquad u = 1, ..., q+1$$

of the vertices of R_L , then from (2) we get

(5)
$$\omega_{i}^{j} = \frac{1}{A} \sum_{k=1}^{p+1} A_{kj} \, \mathrm{d}a_{ki} = -\frac{1}{A} \sum_{k=1}^{p+1} a_{ki} \, \mathrm{d}A_{kj},$$

$$\psi_{u}^{v} = \frac{1}{B} \sum_{w=1}^{q+1} B_{wv} \, \mathrm{d}b_{wu} = -\frac{1}{B} \sum_{w=1}^{q+1} b_{wu} \, \mathrm{d}B_{wv},$$

where A_{kj} and B_{wv} are the cofactors of the elements a_{kj} and b_{wv} , respectively.

2. Let L_t $(0 \le t \le p)$ be an arbitrary linear subspace of $B_n^{p,q}$, without common points with the absolute. Using the method of L. A. Santalo in [6], we find conditions for the density of L_t to be invariant with respect to G_L . Assume that L_t is determined by the linearly independent points $M_1 = A_1 + B_1, M_2 = A_2 + B_2, ..., M_{t+1} = A_{t+1} + B_{t+1}$. The isotropy group of L_t is given by the following completely integrable Pfaffian system

$$\omega_{\perp}^{\mu}-\psi_{\perp}^{\mu}=0, \qquad \omega_{\perp}^{\alpha}=0, \qquad \psi_{\perp}^{\beta}=0,$$

where

$$\lambda, \mu = 1, ..., t + 1;$$
 $\alpha = t + 2, ..., p + 1;$ $\beta = t + 2, ..., q + 1.$

We now consider the (t + 1)(n - t)-form

(6)
$$dL_t = \bigwedge_{\lambda=1}^{t+1} \left[\bigwedge_{\alpha=t+2}^{p+1} \omega_{\lambda}^{\alpha} \wedge \bigwedge_{\beta=t+2}^{q+1} \psi_{\lambda}^{\beta} \wedge \bigwedge_{\mu=1}^{t+1} (\omega_{\lambda}^{\mu} - \psi_{\lambda}^{\mu}) \right].$$

By the well-known criterion of S. S. Chern [4], there exists a unique biplanar density (6) of L_t iff $D(dL_t) = 0$. But

$$D(\mathrm{d}L_t) = \sum_{\lambda=1}^{t+1} \left[(p+1) \,\omega_{\lambda}^{\lambda} + (q+1) \,\psi_{\lambda}^{\lambda} \right] \wedge \mathrm{d}L_t$$

and $D(dL_t) = 0$ iff

(7)
$$\sum_{\lambda=1}^{r+1} \left[(p+1) \omega_{\lambda}^{\lambda} + (q+1) \psi_{\lambda}^{\lambda} \right] = 0.$$

From (3) we see that (7) holds iff p = q and t = p. Thus obtain the following theorem:

Theorem 1. The subspaces L_t have the density (6) invariant with respect to G_L iff p = q and t = p.

The theorem shows that the only case in which the linear subspaces L_t without common points with the absolute have a biplanar density is one of maximal dimension t = p and $B_n^{p,q} = B_{2p+1}^{pp}$. The latter means that the biplanar space is the generalized biaxial space. Thus we obtain a new characterization of the generalized biaxial space.

Remark. One can analogously show that the linear subspaces which have common points with J_p and K_q have no density invariant under G_L .

Let us now consider the set of *m*-tuples of skew linear subspaces $\Sigma_1 = (L_{t_1}, L_{t_2}, ..., L_{t_m})$ without common points with J_p and K_q and whose dimensions t_i satisfy the condition

$$t_1 + t_2 + \dots + t_m + m \le p + 1$$
.

Assume that L_{t_1} is determined by the linearly independent points $M_1, M_2, ..., M_{t_1+1}$ and L_{t_2} by the linearly independent points $M_{t_1+2}, M_{t_1+3}, ..., M_{t_1+t_2+2}$ and so on, where $M_i = A_i + B_i$, $i = 1, ..., t_1 + t_2 + ... + t_m + m$. In the exterior product

(8)
$$d\Sigma_1 = dL_{t_1} \wedge dL_{t_2} \wedge \dots \wedge dL_{t_m}$$

the factor (for $1 \le s \le m$)

$$dL_{t_s} = \bigwedge_{\lambda_s} \left[\bigwedge_{\alpha'_s} (\omega_{\lambda_s}^{\alpha'_s} \wedge \psi_{\lambda_s}^{\alpha'_s}) \wedge \bigwedge_{\alpha''_s} \omega_{\lambda_s}^{\alpha''_s} \wedge \bigwedge_{\mu_s} \psi_{\lambda_s}^{\beta''_s} \wedge \bigwedge_{\mu_s} (\omega_{\lambda_s}^{\mu_s} - \psi_{\lambda_s}^{\mu_s}) \right],$$

$$t_1 + \ldots + t_{s-1} + s \leq \lambda_s, \ \mu_s \leq t_1 + \ldots + t_s + s,$$

$$1 \leq \alpha'_a \leq t_1 + \ldots + t_{s-1} + s - 1, \qquad t_1 + \ldots + t_s + s + 1 \leq \alpha''_s \leq p + 1,$$

$$t_1 + \ldots + t_s + s + 1 \leq \beta''_s \leq q + 1$$

is the exterior product of all left sides of the equations of the completely integrable Pfaffian system, which determines the isotropy group of the element L_{t_s} . It follows from

$$D(\mathrm{d}\Sigma_1) = \sum_{\lambda=1}^{t_1+t_2+\ldots+t_m+m} [(p+1)\,\omega_\lambda^\lambda + (q+1)\,\psi_\lambda^\lambda] \wedge \mathrm{d}\Sigma_1$$

and the criterion of S. S. Chern that a necessary and sufficient condition for

existence of the biplanar density (8) of the m-tuples Σ_1 is

$$\sum_{\lambda=1}^{t_1+t_2+\ldots+t_m+m} [(p+1)\,\omega_{\lambda}^{\lambda}+(q+1)\,\psi_{\lambda}^{\lambda}]=0.$$

From (3) we conclude that the above equality has place iff p = q and $t_1 + t_2 + ... + t_m + m = p + 1$.

Hence we have

Theorem 2. The m-tuples Σ_1 have the invariant density (8) under G_L iff p = q and $t_1 + t_2 + ... + t_m + m = p + 1$.

The Theorem 1 is the special case m=1 of the Theorem 2. Remark that the existence of invariant density for Σ_1 in $B_{2p+1}^{p,p}$ is established by G. Stanilov [3].

Let Σ_2 be an arbitrary system of h+s+m skew linear subspaces $L_{p_1}, L_{p_2}, \ldots, L_{p_h}, L_{q_1}, L_{q_2}, \ldots, L_{q_e}, L_{r_1}, L_{r_2}, \ldots, L_{r_m}$ which satisfy the conditions

$$\bigcup_{k=1}^{h} L_{p_{k}} \subset J_{p}, \quad \bigcup_{\sigma=1}^{s} L_{q_{\sigma}} \subset K_{q}, \quad (\bigcup_{a=1}^{m} L_{r_{a}}) \cap (J_{p} \cup K_{q}) = \emptyset,$$

$$P + R + h + m \leq p + 1, \quad Q + R + s + m \leq q + 1,$$

where

$$P = \sum_{\lambda=1}^{h} p_{\lambda}, \qquad Q = \sum_{\sigma=1}^{s} q_{\sigma}, \qquad R = \sum_{\alpha=1}^{m} r_{\alpha}$$

and

$$p_{\lambda} = \dim L_{p_{\lambda}}, \qquad \lambda = 1, ..., h,$$

$$q_{\sigma} = \dim L_{q_{\sigma}}, \qquad \sigma = 1, ..., s,$$

$$r_{a} = \dim L_{r_{a}}, \qquad a = 1, ..., m.$$

Suppose that the linear subspaces $L_{p_{\lambda}}$ ($\lambda = 1, ..., h$), $L_{q_{\sigma}}$ ($\sigma = 1, ..., s$), $L_{r_{\alpha}}$ ($\sigma = 1, ..., m$) are determined by the linearly independent points

$$\begin{split} L_{p_{\lambda}} &= (A_{P-p_{\lambda}+\lambda}, A_{P-p_{\lambda}+\lambda+1}, ..., A_{P+\lambda}), \\ L_{q_{\sigma}} &= (B_{Q-q_{\sigma}+\sigma}, B_{Q-q_{\sigma}+\sigma+1}, ..., B_{Q+\sigma}), \\ L_{r_{\alpha}} &= (M_{R-r_{\alpha}+\alpha}, M_{R-r_{\alpha}+\alpha+1}, ..., M_{R+\alpha}), \end{split}$$

where $M_{R-r_a+e+e} = A_{E+e+e} + B_{F+e+e}$, $E = P + R + h - r_a$ and $F = Q + R + s - r_a$ for $\varepsilon = 0, 1, ..., r_a$. The completely integrable Pfaffian system, which determines the isotropy group of Σ_2 has the form

(9)
$$\omega_{i_{A}}^{J_{A}} = 0, \ \psi_{a_{\sigma}}^{v_{\sigma}} = 0, \ \omega_{\xi_{a}}^{q_{a}} = 0, \ \psi_{\theta_{a}}^{r_{a}} = 0, \\ \omega_{E+a+\delta}^{E+a+\delta} - \psi_{F+a+\delta}^{F+a+\delta} = 0,$$

where

$$P - p_{\lambda} + \lambda \leq i_{\lambda} \leq P + \lambda, \qquad 1 \leq \lambda \leq h,$$

$$1 \leq j_{\lambda} \leq P - p_{\lambda} + \lambda - 1, \qquad P + \lambda + 1 \leq j_{\lambda} \leq p + 1,$$

$$Q - q_{\sigma} + \sigma \leq u_{\sigma} \leq Q + \sigma, \qquad 1 \leq \sigma \leq s,$$

(10)
$$1 \leq v_{\sigma} \leq Q - q_{\sigma} + \sigma - 1, \qquad Q + \sigma + 1 \leq v_{\sigma} \leq q + 1,$$

$$E + a \leq \xi_{a} \leq E + r_{a} + a, \qquad 1 \leq a \leq m,$$

$$1 \leq \eta_{a} \leq E + a - 1, \qquad E + r_{a} + a + 1 \leq \eta_{a} \leq p + 1,$$

$$F + a \leq \varrho_{a} \leq F + r_{a} + a, \qquad 0 \leq \varepsilon, \ \delta \leq r_{a},$$

$$1 \leq \tau_{a} \leq F + a - 1, \qquad F + r_{a} + a + 1 \leq \tau_{a} \leq q + 1.$$

After exterior differentiation of the form

(11)
$$d\Sigma_2 = \Lambda \omega_{i_1}^{j_{\lambda}} \wedge \psi_{u_{\alpha}}^{v_{\alpha}} \wedge \omega_{\xi_{\alpha}}^{\eta_a} \wedge \psi_{\alpha_{\alpha}}^{\tau_a} \wedge (\omega_{E+a+s}^{E+a+\delta} - \psi_{E+a+s}^{F+a+\delta})$$

which contains as factors all left sides of (9) (the indices have the ranges (10), we get

$$D(d\Sigma_{2}) = [(p+1) \sum_{i=1}^{P+R+h+m} \omega_{i}^{i} + (Q+s) \sum_{j=1}^{p+1} \omega_{j}^{j} + (q+1) \sum_{u=1}^{Q+R+s+m} \psi_{u}^{u} + (P+h) \sum_{v=1}^{q+1} \psi_{v}^{v}] \wedge d\Sigma_{2}.$$

It follows from (3) that the form $d\Sigma_2$ is closed iff

$$(p+1)\sum_{i=1}^{P+R+h+m}\omega_i^i+(Q+s)\sum_{j=1}^{p+1}\omega_j^j+(q+1)\sum_{u=1}^{Q+R+s+m}\psi_u^u+(P+h)\sum_{v=1}^{q+1}\psi_v^v=0.$$

It is not hard to see that the above equality is possible exactly in one of the following three cases:

(i)
$$P + R + h + m = p + 1$$
, $Q + R + s + m = q + 1$;

(12) (ii)
$$P + h = p + 1$$
, $s = 0$, $m = 0$;

(iii)
$$Q + s = q + 1$$
, $h = 0$, $m = 0$.

Therefore we get the following theorem:

Theorem 3. The systems Σ_2 have the biplanar density (11) only in the cases (12). Theorem 3 allows us to determine in a simple manner the systems Σ_2 with invariant biplanar density. As an example, we consider the four-dimensional biplanar space $B_4^{1,2}$ with absolute of a line J_1 and a plane K_2 . From Theorem 3 the possible cases are:

I.
$$h = 2$$
, $s = 3$, $m = 0$, $P = 0$, $Q = 0$, $R = 0$;
II. $h = 2$, $s = 2$, $m = 0$, $P = 0$, $Q = 1$, $R = 0$;
III. $h = 1$, $s = 2$, $m = 1$, $P = 0$, $Q = 0$, $R = 0$;
IV. $h = 1$, $s = 1$, $m = 1$, $P = 0$, $Q = 1$, $R = 0$;
V. $h = 0$, $s = 1$, $m = 2$, $P = 0$, $Q = 0$, $R = 0$;
VI. $h = 0$, $s = 1$, $m = 1$, $P = 0$, $Q = 0$, $R = 1$;
VII. $h = 2$, $s = 0$, $m = 0$, $P = 0$, $Q = 0$, $R = 0$;
IX. $h = 0$, $s = 3$, $m = 0$, $P = 0$, $Q = 0$, $R = 0$;
IX. $h = 0$, $s = 2$, $m = 0$, $P = 0$, $Q = 1$, $R = 0$.

If $p_1 = p_2 = ... = p_h = 0$, $q_1 = q_2 = ... = q_s = 0$ and $r_1 = r_2 = ... = r_m = 0$, then the systems Σ_2 consist of h + s + m linearly independent points: h points in τ_p , s points in K_q and m points outside $J_p \cup K_q$. This special case is considered in [1]. An analogue of Theorem 3 for $B_{2p+1}^{p,p}$ is proved in [2].

3. Here we give a geometric interpretation of the biplanar density of some systems of special linear subspaces.

Example 1. Let h=2, s=2, m=0 and choose $p_1=0$, $p_2=p-1$, $q_1=0$, $q_2=q-1$. The conditions (i) in (12) are satisfied and, from Theorem 3, the systems $\Sigma_2'=\{(\text{a point in }J_p)+(\text{a }(p-1)\text{-dimensional plane in }J_p)+(\text{a point in }K_q)+(\text{a }(q-1)\text{-dimensional plane in }K_q)\}$ have an invariant biplanar density. The subspaces are chosen to be skew. Let

$$\Sigma_2' = \{L_{p_1} = (A_1), L_{p_2} = (A_2, ..., A_{p+1}), L_{q_1} = (B_1), L_{q_2} = (B_2, ..., B_{q+1})\}.$$

Then the density of the systems Σ'_2 is given by the following 2(p+q)-form

(13)
$$d\Sigma_2' = \bigwedge_{i=2}^{p+1} (\omega_1^i \wedge \omega_i^1) \wedge \bigwedge_{u=2}^{q+1} (\psi_1^u \wedge \psi_u^1).$$

In view of [5], we get an other expression for (13). At least one of the coordinates $(a_{11}, a_{21}, ..., a_{p+1,1}, 0, 0, ..., 0)$ of the point L_{p_1} and at least one of the coordinates $(0, 0, ..., 0, b_{11}, b_{21}, ..., b_{q+1,1})$ of the point L_{q_1} are non-zero. Let $a_{p+1,1} \neq 0$, $b_{q+1,1} \neq 0$. Setting

$$X_i = a_{i1}/a_{p+1,1},$$
 $Y_u = b_{u1}/b_{q+1,1},$ $i = 1, ..., p+1; u = 1, ..., q+1,$ from (5) we obtain

(14)
$$\omega_{1}^{i} = \frac{1}{A} a_{p+1,1} \sum_{k=1}^{p} A_{ki} dX_{k} + \frac{da_{p+1,1}}{a_{p+1,1}} \delta_{1i},$$

$$\psi_{1}^{u} = \frac{1}{B} b_{q+1,1} \sum_{v=1}^{q} B_{vu} dY_{v} + \frac{db_{q+1,1}}{b_{q+1,1}} \delta_{1u},$$

where δ_{**} is the well-known symbol of Kronecker.

It follows from (4) that the (p-1)-plane L_{p_2} and the (q-1)-plane L_{q_2} have the have the equations

$$L_{p_2}: A_{11}x_1 + A_{21}x_2 + \dots + A_{p_1}x_p + A_{p+1,1}x_{p+1} = 0,$$

$$y_1 = 0, y_2 = 0, \dots, y_{q+1} = 0,$$

$$L_{q_2}: x_1 = 0, x_2 = 0, \dots, x_{p+1} = 0,$$

$$B_{11}y_1 + B_{21}y_2 + \dots + B_{q_1}y_q + B_{q+1,1}y_{q+1} = 0.$$

At least one of the coefficients $A_{11}, A_{21}, ..., A_{p+1,1}$ in the first equation of L_{p_2} and at least one of the coefficients $B_{11}, B_{21}, ..., B_{q+1,1}$ in the latter equation of

 L_{q_2} are non-zero. Suppose that $A_{p+1,1} \neq 0$, $B_{q+1,1} \neq 0$. Then, setting

$$\alpha_i = A_{i1}/A_{p+1,1},$$
 $i = 1, ..., p + 1,$
 $\beta_u = B_{u1}/B_{q+1,1},$ $u = 1, ..., q + 1,$

from (5) we get

(15)
$$\omega_{i}^{1} = -\frac{1}{A} A_{p+1,1} \sum_{k=1}^{p} a_{ki} d\alpha_{k} - \frac{dA_{p+1,1}}{A_{p+1,1}} \delta_{1i},$$

$$\psi_{u}^{1} = -\frac{1}{B} B_{q+1,1} \sum_{v=1}^{q} b_{vu} d\beta_{v} - \frac{dB_{q+1,1}}{B_{q+1,1}} \delta_{1u}.$$

Putting (14) and (15) in (13) we have

$$\mathrm{d}\Sigma_2' = \left(\frac{a_{p+1,1}A_{p+1,1}}{A}\right)^{p+1} \left(\frac{b_{q+1,1}B_{q+1,1}}{B}\right)^{q+1} \bigwedge_{i=1}^{p} (\mathrm{d}X_i \wedge \mathrm{d}\alpha_i) \wedge \bigwedge_{u=1}^{q} (\mathrm{d}Y_u \wedge \mathrm{d}\beta_u).$$

But

$$a_{p+1,1}A_{p+1,1} = A(\alpha_1X_1 + \dots + \alpha_pX_p + 1)^{-1},$$

$$b_{q+1,1}B_{q+1,1} = B(\beta_1Y_1 + \dots + \beta_qY_q + 1)^{-1}$$

and therefore

$$\mathrm{d}\Sigma_2' = \frac{\bigwedge\limits_{i=1}^p (\mathrm{d}X_i \wedge \mathrm{d}\alpha_i) \wedge \bigwedge\limits_{u=1}^q (\mathrm{d}Y_u \wedge \mathrm{d}\beta_u)}{\mid \alpha_1 X_1 + \ldots + \alpha_p X_p + 1\mid^{p+1} \mid \beta_1 Y_1 + \ldots + \beta_q Y_q + 1\mid^{q+1}}.$$

Example 2. Let h=2, s=0, m=0 and choose $p_1=0$, $p_2=p-1$. Then the conditions (ii) in Theorem 3 are satisfied. The systems Σ_2'' , which consist of skew (point in J_p) + ((p-1)-dimensional plan in J_p) have the biplanar density

$$\mathrm{d}\Sigma_2'' = \bigwedge_{i=2}^{p+1} (\omega_1^i \wedge \omega_i^1).$$

As in Example 1, using the same notations, we obtain

$$\mathrm{d}\Sigma_2'' = \frac{\bigwedge_{i=1}^{p} (\mathrm{d}X_i \wedge \mathrm{d}\alpha_i)}{|\alpha_1 X_1 + \ldots + \alpha_p X_p + 1|^{p+1}}.$$

Example 3. Let h=0, s=2, m=0 and choose $q_1=0$, $q_2=q-1$. Clearly, these values satisfy the conditions (iii) in (12) and hence the systems Σ_2''' of skew (point in K_q) + ((q-1)-dimensional plane in K_q) have the invariant biplanar density

$$\mathrm{d}\Sigma_2^{\prime\prime\prime} = \bigwedge_{u=2}^{q+1} (\psi_1^u \wedge \psi_u^1).$$

Using the notations of the Example 1, we have

$$\mathrm{d}\Sigma_1''' = \frac{\bigwedge\limits_{u=1}^q (\mathrm{d}Y_u \wedge \mathrm{d}\beta_u)}{\mid \beta_1 Y_1 + \ldots + \beta_q Y_q + 1\mid^{q+1}} \,.$$

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A. V. Borisov
Faculty of Mathematics and Mechanics
University of Sofia
Boul. A. Ivanov 5
BG-1126 Sofia
Bulgaria.