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# ON THE RELATION BETWEEN YOUNG'S AND KURZWEIL'S CONCEPT OF STIELTJES INTEGRAL 

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The considerations in this paper are limited to the closed interval $[a, b],-\infty<$ $<a<b<+\infty$ and to finite real functions defined on this interval. For a real function $g:[a, b] \rightarrow R$ we denote by var $_{a}^{b} g$ the obvious (total) variation of $g$ on $[a, b]$. The set of all real functions $g:[a, b] \rightarrow R$ with $\operatorname{var}_{a}^{b} g<+\infty$ is denoted by $B V(a, b)$.

## 1. THE RIEMANN AND YOUNG INTEGRALS.

Let $\mathscr{D}$ be the set of all sequences $D=\left\{\alpha_{0}, \alpha_{1}, \ldots, \alpha_{k}\right\}$ of points in the interval $[a, b]$ such that

$$
\begin{equation*}
a=\alpha_{0}<\alpha_{1}<\ldots<\alpha_{k}=b . \tag{1,1}
\end{equation*}
$$

We consider finite sequences (subdivisions of $[a, b]$ ) $B=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\}$. For a given $D=\left\{\alpha_{0}, \alpha_{1}, \ldots, \alpha_{k}\right\} \in \mathscr{D}$ we denote by $\mathscr{B}^{*}(D), \mathscr{B}(D)$ the sets of all subdivisions $B=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\}$ such that, respectively,
a) $\alpha_{j-1} \leqq \tau_{j} \leqq \alpha_{j}$,
b) $\alpha_{j-1}<\tau_{j}<\alpha_{j}$
for all $j=1,2, \ldots, k$.
On $\mathscr{D}$ we define the binary relation $\succ$ in the following manner: for $D, D^{\prime} \in \mathscr{D}$ we have $D^{\prime} \succ D$ if $D^{\prime}$ is a refinement of $D$, i.e. if any point $\alpha_{j}$ from $D$ appears also in $D^{\prime}$.

If we define $|D|=\max _{j=1, \ldots, k}\left|\alpha_{j}-\alpha_{j-1}\right|$ for $D \in \mathscr{D}$ then another binary relation $\gg$ may be defined on $\mathscr{D}$ by $D^{\prime} \gtrdot D$ if $\left|D^{\prime}\right| \leqq|D|$.

It can be easily shown that $(\mathscr{D}, \succ)$ and $(\mathscr{D}, \gg)$ are directed sets.
Let now be given finite functions $f, g:[a, b] \rightarrow R$; for every $B=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots\right.$ $\left.\ldots, \tau_{k}, \alpha_{k}\right\}$ satisfying $(1,1)$ and $(1,2)$ a) we put

$$
\begin{equation*}
R(B)=\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right) \tag{1,3}
\end{equation*}
$$

Definition 1,1. The function $f:[a, b] \rightarrow R$ is Riemann-Stieltjes integrable (Riemann-Stieltjes norm integrable) on the interval $[a, b]$ with respect to $g:[a, b] \rightarrow$ $\rightarrow R$ if there is a real number $I$ such that to every $\varepsilon>0$ there exists $\bar{D} \in \mathscr{D}$ so that

$$
|R(B)-I|<\varepsilon
$$

for all $B \in \mathscr{B}^{*}(D)$ if $D \succ \bar{D}(D \gg \bar{D})$. The number $I$ will be denoted by $R \int_{a}^{b} f \mathrm{~d} g$ ( $N R \int_{a}^{b} f \mathrm{~d} g$ ) and is called the Riemann-Stieltjes (Riemann-Stieltjes norm) integral of $f$ with respect to $g$ on $[a, b]$.

Supposing that for the function $g:[a, b] \rightarrow R$ the limits $\lim _{s \rightarrow t+} g(s)=g(t+)$, $\lim _{s \rightarrow t_{-}} g(s)=g(t-)$ exist for all $t \in[a, b]$ (for the endpoints of $[a, b]$ the corresponding onesided limits) then we put for $f:[a, b] \rightarrow R$ and $B=\left\{\alpha_{0}, \tau_{1}, \ldots, \tau_{k}, \alpha_{k}\right\}$ satisfying $(1,1),(1,2)$ b)

$$
\begin{gather*}
Y(B)=\sum_{j=1}^{k}\left[f ( \alpha _ { j - 1 } ) \left(g\left(\alpha_{j-1}+\right)-g\left(\alpha_{j-1}\right)+f\left(\tau_{j}\right)\left(g\left(\alpha_{j}-\right)-g\left(\alpha_{j-1}+\right)\right)+\right.\right.  \tag{1,4}\\
\left.+f\left(\alpha_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j}-\right)\right)\right]= \\
=\sum_{j=1}^{k}\left[f\left(\alpha_{j-1}\right) \Delta^{+} g\left(\alpha_{j-1}\right)+f\left(\tau_{j}\right)\left(g\left(\alpha_{j}-\right)-g\left(\alpha_{j-1}+\right)\right)+f\left(\alpha_{j}\right) \Delta^{-} g\left(\alpha_{j}\right)\right]= \\
\left.=\sum_{j=0}^{k} f\left(\alpha_{j}\right) \Delta g\left(\alpha_{j}\right)+\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}-\right)-g \alpha_{j-1}+\right)\right)
\end{gather*}
$$

where $\Delta^{+} g\left(\alpha_{j}\right)=g\left(\alpha_{j}+\right)-g\left(\alpha_{j}\right), \Delta^{-} g\left(\alpha_{j}\right)=g\left(\alpha_{j}\right)-g\left(\alpha_{j}-\right), j=1,2, \ldots, k-1$, $\Delta^{+} g(b)=\Delta^{-} g(a)=0$ and $\Delta g\left(\alpha_{j}\right)=\Delta^{+} g\left(\alpha_{j}\right)+\Delta^{-} g\left(\alpha_{j}\right), j=0,1,2, \ldots, k$.

Definition 1,2. If for $g:[a, b] \rightarrow R$ the limits $g(t+), g(t-)$ exist for all $t \in[a, b]$ then the function $f:[a, b] \rightarrow R$ is said to be Young (Young norm) integrable on the interval $[a, b]$ with respect to $g$ if there is a number $I$ such that to every $\varepsilon>0$ there exists $\tilde{D} \in \mathscr{D}$ so that

$$
|Y(B)-I|<\varepsilon
$$

for all $B \in \mathscr{B}(D)$ if $D \succ \tilde{D}\left(D \gg \Sigma()\right.$. The number $I$ will be denoted by $Y \int_{a}^{b} f \mathrm{~d} g$ ( $N Y \int_{a}^{b} f \mathrm{dg}$ ) and is called the Young integral (Young norm integral) of $f$ with respect to $g$ on $[a, b]$.

Remark 1,1. From Def. 1,1 and Def. 1,2 it is clear that if $N R \int_{a}^{b} f \mathrm{~d} g, N Y \int_{a}^{b} f \mathrm{~d} g$ exist then also $R \int_{a}^{b} f \mathrm{~d} g, Y \int_{a}^{b} f \mathrm{~d} g$ exist respectively, because evidently $D \succ D^{\prime}$ implies $D \gg D^{\prime}$. The concept of the Stieltjes type integral from Def. 1,2 is in detail described and studied in the book [2] (cf. II.19.3 in [2]).

In the sequel we suppose that $g \in B V(a, b)$. Hence $Y(B)$ from $(1,4)$ is defined, because $g(t-), g(t+)$ exist for any $t \in[a, b]$.

For the Riemann-Stieltjes integral the following result is known (cf. II.10.10 in [2] or [1])

Theorem 1,1. If $f:[a, b] \rightarrow R, g \in B V(a, b)$ and $R \int_{a}^{b} f \mathrm{~d} g$ exists, then $f$ is bounded on a finite number of 'closed intervals which are complementary to a finite number of open intervals on which the function $g$ is constant.

In [2] (Theorem 19.3.1 in [2]) the same statement is asserted, $R \int_{a}^{b} f \mathrm{~d} g$ being replaced by $Y \int_{a}^{b} f \mathrm{~d} g$. Unfortunately, this statement does not hold in general. This fact can be demonstrated in the following way: Let $g \in B V(a, b), g(a)=g(b)=$ $=g(t+)=g(t-)$ for all $t \in(a, b)$ (i.e. $g$ is different from a constant on a countable set of points in $(a, b))$. Further let $f:[a, b] \rightarrow R$ be an arbitrary finite function. For any $D \in \mathscr{D}$ and $B=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\} \in \mathscr{B}(D)$ we have

$$
Y(B)=\sum_{j=0}^{k} f\left(\alpha_{j}\right) \Delta g\left(\alpha_{j}\right)+\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}-\right)-g\left(\alpha_{j-1}+\right)\right)=0
$$

because $g\left(\alpha_{j}+\right)=g\left(\alpha_{j}-\right)$ and $\Delta g\left(\alpha_{j}\right)=0$. This yields the following.
Proposition 1,1. Let $g \in B V(a, b), g(a)=g(b)=g(t+)=g(t-)$ for all $t \in(a, b)$. Then $Y \int_{a}^{b} f \mathrm{~d} g$ exists and equals zero for every finite function $f:[a, b] \rightarrow R$.

Example 1,1. Let us define $g(1 /(k+1))=2^{-k}, k=1,2, \ldots, g(t)=0$ for $t[0,1]-$ $-\{1 /(k+1)\}_{k=1}^{\infty}$. We put $f(1 /(k+1))=2^{k}, f(0)=f(1)=0$ and we suppose that $f$ is linear in $\left[\frac{1}{2}, 1\right],[1 /(k+2), 1 /(k+1)], k=1,2, \ldots$ The Young integral $Y \int_{0}^{1} f \mathrm{~d} g$ exists by Proposition 1,1 and equals zero by the same Proposition. Any finite number of closed intervals which are complementary to a finite number of open intervals on which $g$ is constant contains necessarily an interval of the form $[0, \alpha], \alpha>0$ on which $g$ is not constant and the function $f$ defined above is not bounded. Hence we obtain that Theorem 19.3.1 from Chapter II. in [2] is false.

For the Young integral the following Theorem (an analogue to Theorem 1,1) holds:

Theorem 1,2. If $f:[a, b] \rightarrow R, g \in B V(a, b)$ and $Y \int_{a}^{b} f \mathrm{~d} g$ exists, then $f$ is bounded on a finite number of closed intervals which are complementary to a finite number of open intervals $J_{i}=\left(a_{i}, b_{i}\right), a_{i}<b_{i}, i=1,2, \ldots, l$ such that $g\left(a_{i}+\right)=g\left(b_{i}-\right)=$ $=g(t+)=g(t-)$ for all $t \in J_{i}, i=1,2, \ldots, l$.

Proof. By definition for every $\varepsilon>0$ there exists a $\tilde{D} \in \mathscr{D}$ such that $\mid Y(B)-$ $-Y \int_{a}^{b} f \mathrm{~d} g \mid<\varepsilon$ for all $B \in \mathscr{B}(D)$ if $D \succ \tilde{D}$. We choose a fixed $D=\left\{\alpha_{0}, \alpha_{1} \ldots\right.$ $\left.\ldots, \alpha_{k}\right\} \in \mathscr{D}, D \succ \tilde{D}$. We have evidently

$$
\left.|Y(B)|=\mid \sum_{j=0}^{k} f\left(\alpha_{j}\right) \Delta g\left(\alpha_{j}\right)+\sum_{j=1}^{k} f\left(\tau_{j}\right) g\left(\alpha_{j}-\right)-g\left(\alpha_{j-1}+\right)\right)\left|<\left|Y \int_{a}^{b} f \mathrm{~d} g\right|+\varepsilon\right.
$$

for all $B \in \mathscr{B}(D)$, i.e. for all $\tau_{j} \in\left(\alpha_{j-1}, \alpha_{j}\right), j=1,2, \ldots, k$. Hence there is a constant $K>0\left(K=\left|\sum_{j=0}^{k} f\left(\alpha_{j}\right) \Delta g\left(\alpha_{j}\right)+\left|Y \int_{a}^{b} f \mathrm{~d} g\right|+\varepsilon\right)\right.$ such that

$$
\begin{equation*}
\left|\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}-\right)-g\left(\alpha_{j-1}+\right)\right)\right| \leqq K \tag{1,5}
\end{equation*}
$$

for all $\tau_{j} \in\left(\alpha_{j-1}, \alpha_{j}\right), j=1,2, \ldots, k$.
Let us suppose that $f$ is unbounded in some $\left(\alpha_{j-1}, \alpha_{j}\right)$. If $g\left(\alpha_{j}-\right)-g\left(\alpha_{k-1}+\right) \neq 0$ then $f\left(\tau_{j}\right)\left(g\left(\alpha_{j}-\right)-g\left(\alpha_{j-1}+\right)\right)$ would be arbitrarily large for a suitable choice of $\tau_{j} \in\left(\alpha_{j-1}, \alpha_{j}\right)$, but this contradicts $(1,5)$. Therefore we have necessarily $g\left(\alpha_{j}-\right)=$ $=g\left(\alpha_{j-1}+\right)=c$, where $c$ is a constant. Let now $a \in\left(\alpha_{j-1}, \alpha_{j}\right)$ be given; by the assumption $f$ is not bounded either in $\left(\alpha_{j-1}, a\right)$ or in $\left(a, \alpha_{j}\right)$. If we add the point $a$ to $D$ then we obtain $D^{\prime}=\left\{\alpha_{0}, \alpha_{1}, \ldots, \alpha_{j-1}, a, \alpha_{j}, \alpha_{j+1}, \ldots, \alpha_{k}\right\} \in \mathscr{D}$ where evidently $D^{\prime}>D \succ \tilde{D}$ and the same argument as above gives either $g(a-)=c$ or $g(a+)=c$. In this way we obtain that if $f$ is not bounded in some $\left(\alpha_{j-1}, \alpha_{j}\right)$ then $g\left(\alpha_{j}-\right)=$ $=g\left(\alpha_{j-1}+\right)=c$ and for any $a \in\left(\alpha_{j-1}, \alpha_{j}\right)$ we have either $g(a+)=c$ or $g(a-)=c$. Since we suppose $g \in B V(a, b)$, the limits $g(t+)$ and $g(t-)$ exist for any $t \in\left(\alpha_{j-1}, \alpha_{j}\right)$ and it is a matter of routine to show that $g(a+)=g(a-)=c$ for all $a \in\left(\alpha_{j-1}, \alpha_{j}\right)$. This proves the Theorem, since the number of intervals $\left(\alpha_{j-1}, \alpha_{j}\right)$ is finite.

Remark 1,2. Evidently in Theorem 1,2 the assumption $g \in B V(a, b)$ can be replaced by the requirement that the limits $g(t+)$ and $g(t-)$ exist for all $t \in[a, b]$ (with the corresponding onesided limits at the endpoints of $[a, b])$.

Corollary 1,1. Let $g \in B V(a, b)$ be given and let $J_{i}=\left(a_{i}, b_{i}\right), i=1,2, \ldots, l$ be a finite system of open intervals in $[a, b]$ such that $g\left(a_{i}+\right)=g\left(b_{i}\right)-=g(t+)=$ $=g(t-)$ holds for all $t \in J_{i}$. If for $f:[a, b] \rightarrow R$ the integral $Y \int_{a}^{b} f \mathrm{~d} g$ exists and if $\tilde{f}:[a, b] \rightarrow R$ is such a function that $f(t)=\tilde{f}(t)$ for all $t \in[a, b]-\bigcup_{i-1}^{l} J_{i}$ then $Y \int_{a}^{b} f\left(\mathrm{~d} g\right.$ exists and $Y \int_{a}^{b} f \mathrm{~d} g=Y \int_{a}^{b} f \mathrm{~d} g$. The same statement holds also for the Young norm integral.

The proof follows easily from the definition of the Young integral and from the fact that the term from $Y(B)($ cf. $(1,4))$ which corresponds to some $\left[\alpha_{j-1}, \alpha_{j}\right] \subset J_{i}$ equals zero for any function $f$.

The Young integral is an extension of the Riemann-Stieltjes integral; the following theorem holds:

Theorem 1,3. (cf. II.19.3.3 in [2]). If $f:[a, b] \rightarrow R, g \in B V(a, b)$ and $R \int_{a}^{b} f \mathrm{~d} g$ exists then $Y \int_{a}^{b} f \mathrm{~d} g$ exists and the two integrals are equal. (The same holds for the norm integrals.)

In the opposite direction we have the following

Theorem 1,4. (cf. II.19.3.4 in [2]). If $f:[a, b] \rightarrow R, g \in B V(a, b) g$ is continuous in $[a, b]$ and $Y \int_{a}^{b} f \mathrm{~d} g$ exists then $R \int_{a}^{b} f \mathrm{~d} g$ exists and both integrals are equal. The same statement is valid for the norm integrals.

For continuous $g \in B V(a, b)$ we can state the following Theorem which is a reversion of the statement given in Remark 1,1.

Theorem 1,5. Let $f:[a, b] \rightarrow R, g \in B V(a, b), g$ continuous and let $Y \int_{a}^{b} f \mathrm{~d} g$ exist. Then $N Y \int_{a}^{b} f \mathrm{~d} g$ exists and $Y \int_{a}^{b} f \mathrm{~d} g=N Y \int_{a}^{b} f \mathrm{~d} g$.

Proof. Let $\varepsilon>0$ be given. By definition there is a $\tilde{D}=\left\{a_{0}, a_{1}, \ldots, a_{k}\right\} \in \mathscr{D}$ such that $\left|Y\left(B^{\prime}\right)-Y \int_{a}^{b} f \mathrm{~d} g\right|<\varepsilon$ for all $B^{\prime} \in \mathscr{B}\left(D^{\prime}\right), D^{\prime} \succ D$. Regarding Theorem 1,2 and Corollary 1,1 we can suppose without any loss of generality that the function $f$ is bounded, i.e. $|f(t)| \leqq M$ for all $t \in[a, b]$. If this is not satisfied, then we define the function $f$ by Corollary 1,1 so that $f$ is bounded and we work with the integral $Y \int_{a}^{b} f \mathrm{~d} g$ instead of $Y \int_{a}^{b} f \mathrm{~d} g$.

From the continuity of $g$ at all points $a_{i}, i=1, \ldots, k$ we obtain the existence of a $\delta>0$ such that $\left|g(t)-g\left(a_{i}\right)\right|<\varepsilon / 2 M k$ provided $\left|t-a_{i}\right|<\delta, i=1, \ldots, k$.

Let $D=\left\{\alpha_{0}, \alpha_{1}, \ldots, \alpha_{l}\right\} \in \mathscr{D}$ be an arbitrary subdivision such that $|D|<\delta$ and let us construct a subdivision $D^{\prime}$ which is a common refinement of $D$ and $\tilde{D}$; evidently $D^{\prime} \succ \widetilde{D}$. For a given $B \in \mathscr{B}(D)$ and $B^{\prime} \in \mathscr{B}\left(D^{\prime}\right)$ we give an estimate of $\left|Y(B)-Y\left(B^{\prime}\right)\right|$.

If it occurs that $\alpha_{j-1}<a_{h+1}<\ldots<a_{h+m_{j}}<\alpha_{j}$ then

$$
\begin{gathered}
s_{j}=f\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right)= \\
=f\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(a_{h+m_{j}}\right)\right)+\left(g\left(a_{h+m_{j}}\right)-g\left(a_{h+m_{j}-1}\right)\right)+\ldots+\left(g\left(a_{h+1}\right)-g\left(\alpha_{j-1}\right)\right)
\end{gathered}
$$

is the term of $Y(B)$ corresponding to $\alpha_{j-1}<\tau_{j}<\alpha_{j}$ and the terms of $Y\left(B^{\prime}\right)$ are of the form

$$
\begin{gathered}
s_{j}^{\prime}=f\left(\tau_{q+m_{j}}^{\prime}\right)\left(g\left(\alpha_{j}\right)-g\left(a_{h+m_{j}}\right)\right)+f\left(\tau_{q+m_{j}-1}^{\prime}\right)\left(g\left(a_{h+m_{j}}\right)-g\left(a_{h+m_{j}-1}\right)\right)+\ldots \\
\ldots+f\left(\tau_{q}^{\prime}\right)\left(g\left(a_{h+1}\right)-g\left(\alpha_{j-1}\right)\right)
\end{gathered}
$$

The difference $s_{j}-s_{j}^{\prime}$ consists of $m+1$ terms of the form

$$
\left(f\left(\tau_{j}\right)-f\left(\tau_{q+x}^{\prime}\right)\right)(g(u)-g(v))
$$

where $|u-v|<\delta($ since $|D|<\delta)$ and either $u$ or $v$ equals to some $a_{i}$. Hence

$$
\left.\mid f\left(\tau_{j}\right)-f\left(\tau_{q+x}^{\prime}\right)\right)(g(u)-g(v)) \mid<2 M \cdot(\varepsilon / 2 M k)=\varepsilon / k
$$

and

$$
\left|s_{j}-s_{j}^{\prime}\right|<\varepsilon\left(m_{j}+1\right) / k=\varepsilon m_{j} / k+\varepsilon / k .
$$

If the interval $\left(\alpha_{j-1}, \alpha_{j}\right)$ does not contain points from $\tilde{D}$ then the corresponding terms
from $Y(B)$ and $Y\left(B^{\prime}\right)$ are equal. Hence we have

$$
\left|Y(B)-Y\left(B^{\prime}\right)\right|<\varepsilon \sum\left(m_{j}+1\right) / k
$$

where the sum on the right hand side is taken over all $j$ for which $\left(\alpha_{j-1}, \alpha_{j}\right)$ contains points from $\tilde{D}$. The number of such intervals is at most $k-1$ and $\sum m_{j} \leqq k$; this yields

$$
\left|Y(B)-Y\left(B^{\prime}\right)\right|<\varepsilon(1+((k-1) / k)<2 \varepsilon .
$$

In this way we obtain

$$
\left|Y(B)-Y \int_{a}^{b} f \mathrm{~d} g\right| \leqq\left|Y(B)-Y\left(B^{\prime}\right)\right|+\left|Y\left(B^{\prime}\right)-Y \int_{a}^{b} f \mathrm{~d} g\right|<3 \varepsilon
$$

for all $\dot{B} \in \mathscr{B}(D),|D|<\varepsilon$, i.e. $N Y \int_{a}^{b} f \mathrm{~d} g$ exists and is equal to $Y \int_{a}^{b} f \mathrm{~d} g$.
If $g, h \in B V(a, b), f:[a, b] \rightarrow R,|f(t)| \leqq M$ for all $t \in[a, b]$ and if $B=\left\{\alpha_{0}, \tau_{1}\right.$, $\left.\alpha_{1}, \ldots, \tau, \alpha_{k}\right\} \in \mathscr{B}(D)$ for some $D=\left\{\alpha_{0}, \ldots, \alpha_{k}\right\} \in \mathscr{D}$ then we denote

$$
Y_{h}(B)=\sum_{j=0}^{k} f\left(\alpha_{j}\right) \Delta h\left(\alpha_{j}\right)+\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(h\left(\alpha_{j}-\right)-h\left(\alpha_{j-1}+\right)\right)
$$

and similarly $Y_{g}(B)$ denotes the Young sum for $g$ (cf. $(1,4)$ ).
Evidently the inequality

$$
\begin{equation*}
\left|Y_{g}(B)-Y_{h}(B)\right| \leqq M \operatorname{var}_{a}^{b}(g-h) \tag{1,6}
\end{equation*}
$$

holds.
Similarly for $f, f:[a, b] \rightarrow R$ and $g \in B V(a, b)$ we have

$$
\begin{equation*}
\left|Y^{f}(B)-Y^{f}(B)\right| \leqq \sup _{t \in[a, b]}|f(t)-\tilde{f}(t)| \operatorname{var}_{a}^{b} g \tag{1,7}
\end{equation*}
$$

for any $B \in \mathscr{B}(D), \quad D \in \mathscr{D}$, where $\quad Y^{\mathcal{f}}(B)=\sum_{j=0}^{k} f\left(\alpha_{j}\right) \Delta g\left(\alpha_{j}\right)+\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}-\right)-\right.$
$\left.-g\left(\alpha_{j-1}+\right)\right)$ and similarly for $Y^{f}(B)($ cf. $(1,4))$.
The inequality $(1,6)$ immediately leads to the following
Proposition 1,2. (cf. II. 19.3 .9 in [2]). If $g_{n}, g \in B V(a, b), n=1,2, \ldots \lim _{n \rightarrow \infty} \operatorname{var}_{a}^{b}\left(g_{n}-\right.$ $-g)=0, f:[a, b] \rightarrow R,|f(t)| \leqq M$ for all $t \in[a, b]$ and $Y \int_{a}^{b} f \mathrm{~d} g_{n}$ exists for all $n=1,2, \ldots$ then both $Y \int_{a}^{b} f \mathrm{~d} g$ and $\lim _{n \rightarrow \infty} Y \int_{a}^{b} f \mathrm{~d} g_{n}$ exist and are equal.

Corollary 1,2. If $g_{b} \in B V(a, b)$ is a pure break function and $f:[a, b] \rightarrow R$ is bounded $(|f(t)| \leqq M$ for $t \in[a, b])$ then $Y \int_{a}^{b} f \mathrm{~d} g_{b}$ exists and we have $Y \int_{a}^{b} f \mathrm{~d} g_{b}=$ $=\sum_{t \in[a, b]} f(t) \Delta g_{b}(t)$.
Proof. To every pure break function $g_{b} \in \operatorname{BV}(a, b)$ there exists a sequence $g_{n} \in$ $\in \operatorname{BV}(a, b), n=1,2, \ldots$ of break functions with a finite number of discontinuities
such that $\lim \operatorname{var}_{a}^{b}\left(g_{n}-g\right)=0$. Therefore by Proposition 1,2 it is sufficient to prove $n \rightarrow \infty$ that $Y \int_{a}^{b} \stackrel{n \rightarrow \infty}{f \mathrm{~d}} g$ exists for any pure break function $g \in B V(a, b)$ with a finite number of discontinuities at the points $\left\{t_{1}, \ldots, t_{v}\right\} \subset[a, b]$; let us now prove it: we choose an arbitrary $\tilde{D}=\left\{\alpha_{0}, \alpha_{1}, \ldots, \alpha_{k}\right\} \in \mathscr{D}$ such that $\left\{t_{1}, \ldots, t_{v}\right\} \subset \tilde{D}$. For every $B=$ $=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\} \in \mathscr{B}(D), D \succ \tilde{D}$ we have

$$
Y(B)=\sum_{j=1}^{k} f\left(\alpha_{j}\right) \Delta g\left(\alpha_{j}\right)+\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}-\right)-g\left(\alpha_{j-1}+\right)\right)=\sum_{i=1}^{v} f\left(t_{i}\right) \Delta g\left(t_{i}\right)
$$

because $g\left(\alpha_{j}-\right)-g\left(\alpha_{j-1}+\right)=0$ for all $j=1,2, \ldots, k$ and $\Delta g\left(\alpha_{j}\right)=0$ if $\alpha_{j} \notin$ $\notin\left\{t_{1}, \ldots, t_{v}\right\}$. This implies the existence of $Y \int_{a}^{b} f \mathrm{~d} g$ and moreover we have obtained the equality

$$
Y \int_{a}^{b} f \mathrm{~d} g=\sum_{i=1}^{\nu} f\left(t_{i}\right) \Delta g\left(t_{i}\right)
$$

From the inequality $(1,7)$ we obtain
Proposition 1,3. (cf. II. 19.3 .8 in [2]). If $f_{n}:[a, b] \rightarrow R, \lim f_{n}=f$ uniformly in $[a, b], g \in B V(a, b)$ and if $Y \int_{a}^{b} f_{n} \mathrm{~d} g$ exists for all $n=1,2, \ldots$ then $Y \int_{a}^{b} f \mathrm{~d} g$ as well as $\lim _{n \rightarrow \infty} Y \int_{a}^{b} f_{n} \mathrm{~d} g$ exist and are equal.

Corollary 1,3. If $f, g \in B V(a, b)$ then $Y \int_{a}^{b} f \mathrm{~d} g$ exists.
Proof. It is known that every $f \in B V(a, b)$ is representable as the uniform limit of a sequence $f_{n}$ of step-functions on $[a, b]$ (see for example 7.3.2.1 in [1]), i.e. every $f_{n}$ is a pure break function with a finite number of points of discontinuity $\left\{t_{1}, t_{2}, \ldots, t_{v_{n}}\right\} \subset[a, b]$. We prove that $Y \int_{a}^{b} f_{n} \mathrm{~d} g$ exists for all $n=1,2, \ldots$ Let $\widetilde{D} \in \mathscr{D}$ be an arbitrary subdivision of $[a, b]$ with $\left\{t_{1}, t_{2}, \ldots, t_{v_{n}}\right\} \subset D$; let be $D>\tilde{D}$, $B=\left\{\alpha_{0}, \tau_{1}, \ldots, \tau_{k}, \alpha_{k}\right\} \in \mathscr{B}(D)$ and let us suppose that $a<t_{1}<\ldots<t_{v_{n}}<b$.

Hence using the fact that the function $f_{n}$ is constant with values $f(a), f\left(t_{i}+\right)$, $i=1, \ldots, v_{n}-1, f(b)$ in the intervals $\left[a, t_{1}\right),\left(t_{i}, t_{i+1}\right) i=1, \ldots, v_{n}-1,\left(t_{v_{n}}, b\right]$ respectively, we obtain

$$
\begin{gathered}
Y(B)=\sum_{j=0}^{k} f_{n}\left(\alpha_{j}\right) \Delta g\left(\alpha_{j}\right)+\sum_{j=1}^{k} f_{n}\left(\tau_{j}\right)\left(g\left(\alpha_{j}-\right)-g\left(\alpha_{j-1}+\right)\right)= \\
=f(a) \Delta^{+} g(a)+\sum_{i=1}^{v_{n}} f\left(t_{i}\right) \Delta g\left(t_{i}\right)+f(b) \Delta^{-} g(b)+ \\
+f(a+)\left(g\left(t_{1}-\right)-g(a+)\right)+\sum_{i=1}^{v_{n}} f\left(t_{i}+\right)\left(g\left(t_{i+1}-\right)-g\left(t_{i}+\right)\right)+ \\
+f(b-)\left(g(b-)-g\left(t_{v_{n}}+\right)\right)=\sum_{i=1}^{v_{n}} f\left(t_{i}\right) \Delta g\left(t_{i}\right)+\sum_{i=1}^{v_{n}-1} f\left(t_{i}+\right)\left(g\left(t_{i+1}-\right)-g\left(t_{i}+\right)\right)+ \\
+f(a)\left(g\left(t_{1}-\right)-g(a)\right)+f(b)\left(g(b)-g\left(t_{v_{n}}+\right)\right),
\end{gathered}
$$

i.e. the Young sum depends only on $t_{1}, \ldots, t_{v_{n}}$ and is independent of the choice of $D \succ \tilde{D}$ and $B \in \mathscr{B}(D)$. This implies that the integral $Y \int_{a}^{b} f_{n} \mathrm{~d} g$ exist and has the value $Y(B)$ evaluated above.

The analogous argument gives the same result if $a=t_{1}$ or $b=t_{v_{n}}$. The existence of $Y \int_{a}^{b} f \mathrm{~d} g$ follows now from Proposition 1,3.

## 2. THE KURZWEIL INTEGRAL

Let for any $\tau \in[a, b]$ a $\delta=\delta(\tau)>0$ be given (i.e. $\delta:[a, b] \rightarrow(0,+\infty)$ ).
Put

$$
\begin{equation*}
S=\left\{(\tau, t) \in R^{2} ; a \leqq \tau \leqq b, \tau-\delta(\tau) \leqq t \leqq \tau+\delta(\tau)\right\} \tag{2,1}
\end{equation*}
$$

and denote by $\mathscr{S}=\mathscr{S}(a, b)$ the system of all such sets $S \in R^{2}$. Any set $S \in \mathscr{S}$ can be evidently characterized by a function $\delta:[a, b] \rightarrow(0,+\infty)$.

We consider finite sequences of numbers $A=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\}$ such that

$$
\begin{gather*}
a=\alpha_{0}<\alpha_{1}<\ldots<\alpha_{k}=b  \tag{2,2}\\
\alpha_{j-1} \leqq \tau_{j} \leqq \alpha_{j}, \quad j=1, \ldots, k \tag{2,3}
\end{gather*}
$$

For a given set $S \in \mathscr{P}, A$ is called a subdivision of $[a, b]$ subordinate to $S$ if

$$
\begin{equation*}
\left(\tau_{j}, t\right) \in S \text { for } t \in\left[\alpha_{j-1}, \alpha_{j}\right], j=1,2, \ldots, k \tag{2,4}
\end{equation*}
$$

The set of all subdivisions $A$ of $[a, b]$ subordinate to $S \in \mathscr{S}$ let be denoted by $A(S)$ (cf. Definition $1,1,3$ in [3]). In [3], Lemma $1,1,1$ it is proved that $A(S) \neq \emptyset$ for any $S \in \mathscr{S}$.

Let $f:[a, b] \rightarrow R, g:[a, b] \rightarrow R$ be given. For every $A=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\}$ satisfying $(2,2)$ and $(2,3)$ we put

$$
\begin{equation*}
K(A)=\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right) \tag{2,5}
\end{equation*}
$$

Definition 2,1. The function $f:[a, b] \rightarrow R$ is Stieltjes integrable on the interval $[a, b]$ with respect to $g:[a, b] \rightarrow R$ in the sense of Kurzweil if there is a number $I$ such that to every $\varepsilon>0$ there exists such a set $S \in \mathscr{S}$ that

$$
\begin{equation*}
|K(A)-I|<\varepsilon \tag{2,6}
\end{equation*}
$$

if $A \in A(S)$. The number $I$ will be denoted by $K \int_{a}^{b} f \mathrm{~d} g$ and called the Kurzweil integral of $f$ with respect to $g$ on $[a, b]$.

The following proposition is an obvious consequence of the completeness of $R$ and of Def. 2,1:

Proposition 2,1. Let $f, g:[a, b] \rightarrow R$. The integral $K \int_{a}^{b} f \mathrm{~d} g$ exists if and only if for any $\varepsilon>0$ there is a set $S \in \mathscr{S}$ such that

$$
\begin{equation*}
\left|K\left(A_{1}\right)-K\left(A_{2}\right)\right|<\varepsilon \tag{2,7}
\end{equation*}
$$

for all $A_{1}, A_{2} \in A(S)$.
Remark 2,1. The above Def. 1. follows the definition given in [3] (see 1.2 in [3]). In [3] the notation $\int_{a}^{b} \mathrm{D} U(\tau, t)$ with $U(\tau, t)=f(\tau) g(t)$ is used instead of our symbol $K \int_{a}^{b} f \mathrm{~d} g$. Some fundamental theorems (additivity etc). about the Kurzweil integral can be found in [3] (cf. 1,3 in [3]).

Remark 2,2. It is almost evident that if the Riemann-Stieltjes norm integral $N R \int_{a}^{b} f \mathrm{~d} g$ exists then also the Kurzweil integral $K \int_{a}^{b} f \mathrm{~d} g$ exists and both integrals are equal. To prove this fact it is sufficient to set $\delta(\tau)=|\bar{D}|$ for any $\varepsilon>0$ where $\bar{D}$ is the subdivision from Def. 1,1.

Though it is not immediately apparent, the Kurzweil integral from Def. 2,1 is equivalent to the Perron-Stieltjes integral if we suppose $g \in B V(a, b)$.

Remark 2,3. For given finite $f:[a, b] \rightarrow R, g \in B V(a, b)$ we denote by $P \int_{a}^{b} f \mathrm{~d} g$ the Perron-Stieltjes integral of the point function $f$ with respect to the additive function $G$ of a interval in $[a, b]$ which is defined by the relation $G(I)=g(d)-g(c)$ for $I=[c, d] \subset[a, b]$.(cf. [4]).

The following theorem states the result promised above.
Theorem 2,1. Let $f:[a, b] \rightarrow R$ be finite, $g \in B V(a, b)$. Then the integral $K \int_{a}^{b} f \mathrm{~d} g$ exists if and only if the integral $P \int_{a}^{b} f \mathrm{~d} g$ exists and both integrals have the same value.

Proof. 1. Let $P \int_{a}^{b} f \mathrm{~d} g$ exist. From the definition (cf. [4]) we have: For any $\varepsilon>0$ there is a major function $U$ and a minor function $\left.V^{*}\right)(U$ and $V$ are additive functions of interval in $[a, b]$ ) of $f$ with respect to $G$ such that

$$
\begin{equation*}
U([a, b])-V([a, b])<\varepsilon \tag{2,8}
\end{equation*}
$$

Let $\delta_{1}:[a, b] \rightarrow(0,+\infty), \delta_{2}:[a, b] \rightarrow(0,+\infty)$ be the function occuring in the definition of the minor function $V$ and the major function $U$, respectively. Let us put $\delta(\tau)=\min \left(\delta_{1}(\tau), \delta_{2}(\tau)\right)$ for any $\tau \in[a, b]$ and let $S \in \mathscr{S}$ be the set which corresponds to $\delta:[a, b] \rightarrow(0,+\infty)$ by $(2,1)$. We suppose that an arbitrary $A=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots\right.$
*) An additive function of an interval $V$ is said to be a minor function of $f$ with respect to $G$ on $[a, b]$ if to each point $\tau \in[a, b]$ there corresponds a number $\delta_{1}=\delta_{1}(\tau)>0$ such that $V([c, d]) \leqq f(\tau) G([c, d])=f(\tau)(g(d)-g(c))$ for every interval $[c, d]$ such that $\tau \in[c, d]$ and $|d-c|<\delta_{1}(\tau)$. The major function $U$ is defined analogously.
$\left.\ldots, \tau_{k}, \alpha_{k}\right\} \in A(S)$ is given. The properties of a subdivision from $A(S)$ as well as those of a major and minor function guarantee the inequality

$$
\left.V\left[\alpha_{j-1}, \alpha_{j}\right]\right) \leqq f\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right) \leqq U\left(\left[\alpha_{j-1}, \alpha_{j}\right]\right)
$$

for any $j=1,2, \ldots, k$. Hence the additivity of $U$ and $V$ implies

$$
V([a, b]) \leqq \sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right)=K(A) \leqq U([a, b])
$$

From $(2,8)$ we obtain in this way the inequality $\left|K\left(A_{1}\right)-K\left(A_{2}\right)\right|<\varepsilon$ for all $A_{1}, A_{2} \in$ $\in A(S)$ which means that by Prop. 2,1 the integral $K \int_{a}^{b} f \mathrm{~d} g$ exists. Considering that $P \int_{a}^{b} f \mathrm{~d} g=\inf _{U} U([a, b])=\sup _{\boldsymbol{V}} V([a, b])$ we have evidently also $K \int_{a}^{b} f \mathrm{~d} g=$ $=P \int_{a}^{b} f . \mathrm{d} g .{ }^{U}$
2. Now we suppose that $K \int_{a}^{b} f \mathrm{~d} g$ exists. Let an arbitrary $\varepsilon>0$ be given. According to Prop. 2,1 we choose a set $S \in \mathscr{S}$ (characterized by $\delta:[a, b] \rightarrow(0,+\infty)$ ) such that

$$
\begin{equation*}
\left|K\left(A_{1}\right)-K\left(A_{2}\right)\right|<\varepsilon \tag{2,9}
\end{equation*}
$$

for all $A_{1}, A_{2} \in A(S)$.
For a given $\tau, a<\tau \leqq b$ let $A_{\tau}$ be a subdivision of $[a, \tau]$ subordinate to $S\left(A_{\tau} \in\right.$ $\in A(S, \tau), A(S, \tau)$ is the set of all subdivisions of $[a, \tau]$ subordinated to $S)$. Let us define

$$
M(\tau)=\sup K\left(A_{\tau}\right), \quad m(\tau)=\inf K\left(A_{\tau}\right)
$$

$M(a)=m(a)=0$. We put $U([c, d])=M(d)-M(c), V([c, d])=m(d)-m(c)$ for $[c, d] \subset[a, b]$. Hence by definition and by $(2,9)$ we have

$$
\begin{equation*}
0 \leqq U([a, b])-V([a, b])=M(b)-m(b) \leqq \varepsilon . \tag{2,10}
\end{equation*}
$$

$U$ is a major function of $f$ with respect to $G$ : Let $\delta:[a, b] \rightarrow(0,+\infty)$ be the function which characterizes the set $S$. For fixed $\tau \in[a, b]$ let $[c, d] \subset[a, b], \tau \in[c, d]$, $|d-c|<\delta(\tau)$. Then by definition

$$
f(\tau) G([c, d])+M(c)=f(\tau)(g(d)-g(c))+M(c) \leqq M(d),
$$

i.e.

$$
f(\tau) G([c, d]) \leqq M(d)-M(c)=U([c, d])
$$

In a similar way it can be proved that $V$ is a minor function of $f$ with respect to $G$ in $[a, b]$.

The existence of the Perron-Stieltjes integral $P \int_{a}^{b} f \mathrm{~d} g$ follows immediately from $(2,10)$.

Definition 2,2. Let $g:[a, b] \rightarrow R$ be given. A point $t \in[a, b]$ is called a point of variability of the function $g$ if to every $\varepsilon>0$ there is $a t^{\prime} \in[a, b],\left|t-t^{\prime}\right|<\varepsilon$
such that $g(t) \neq g\left(t^{\prime}\right)$. The set of all points of variability of $g$ in $[a, b]$ is denoted by $V_{g}$ while $C_{g}=[a, b]-V_{g}$.

It is easy to prove that the set $V_{g}$ is closed in $[a, b]$.
Proposition 2,2. Let $f_{1}, f_{2}, g:[a, b] \rightarrow R, f_{1}(t)=f_{2}(t)$ for $t \in V_{g}$ and let $K \int_{a}^{b} f_{1} \mathrm{~d} g$ exist. Then $K \int_{a}^{b} f_{2} \mathrm{~d} g$ exists and equals $K \int_{a}^{b} f_{1} \mathrm{~d} g$.

Proof. For every $\tau \in C_{g}=[a, b]-V_{g}$ there is by definition a $\tilde{\delta}(\tau)>0$ such that for all $\tau^{\prime} \in[a, b],\left|\tau-\tau^{\prime}\right|<\tilde{\delta}(\tau)$ we have $g(\tau)=g\left(\tau^{\prime}\right)$. Since $K \int_{a}^{b} f_{1} \mathrm{~d} g$ exists, we can choose to every $\varepsilon>0$ a set $S \in \mathscr{S}$ (characterized by a function $\delta:[a, b] \rightarrow$ $\rightarrow(0,+\infty))$ such that

$$
\begin{equation*}
\left|\sum_{j=1}^{k} f_{1}\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right)-K \int_{a}^{b} f_{1} \mathrm{~d} g\right|<\varepsilon \tag{2,11}
\end{equation*}
$$

for any $A=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\} \subset A(S)$. We define $\delta^{*}(\tau)=\delta(\tau)$ for $\tau \in V_{g}$ and $\delta^{*}(\tau)=\min (\delta(\tau), \delta(\tau) / 2)$ for $\tau \in C_{g}$; evidently $\delta^{*}(\tau) \leqq \delta(\tau)$ for all $\tau \in[a, b]$ and $S^{*} \subset S$ if $S^{*} \in \mathscr{S}$ is the set in $R^{2}$ characterized by the function $\delta^{*}:[a, b] \rightarrow(0,+\infty)$. Let further $A \in A\left(S^{*}\right)$, then also $A \in A(S)$ and $(2,11)$ holds for any $A=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots\right.$ $\left.\ldots, \tau_{k}, \alpha_{k}\right\} \in A\left(S^{*}\right)$. If $\tau_{j} \in C_{g}$ then we have from (2,3) that $\left|t-\tau_{j}\right| \leqq \delta^{*}\left(\tau_{j}\right) \leqq$ $\leqq \tilde{\delta}\left(\tau_{j}\right) / 2<\tilde{\delta}\left(\tau_{j}\right)$ for all $t \in\left[\alpha_{j-1}, \alpha_{j}\right]$ and therefore $g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)=0$. Hence for all $A=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\} \in A(S)$ we have by assumption

$$
\sum_{j=1}^{k} f_{1}\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right)=\sum_{j=1}^{k} f_{2}\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right)
$$

and by $(2,11)$ also

$$
\left\|\sum_{j=1}^{k} f_{2}\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right)-K \int_{a}^{b} f_{1} \mathrm{~d} g\right\|<\varepsilon
$$

for any $A \in A\left(S^{*}\right)$. This completes the proof.
Proposition 2,3. Let $g_{l}, g \in B V(a, b), l=1,2, \ldots$ and $\lim _{l \rightarrow \infty} \operatorname{var}_{a}^{b}\left(g_{l}-g\right)=0$. Further we assume that for $f:[a, b] \rightarrow R$ it is $|f(t)| \leqq M$ for all $t \in[a, b]$ and that $K \int_{a}^{b} f \mathrm{~d} g_{l}$ exists for all $l=1,2, \ldots$. Then also $K \int_{a}^{b} f \mathrm{~d} g$ and the limit $\lim _{l \rightarrow \infty} K \int_{a}^{b} f \mathrm{~d} g_{l}$ exist and the equality

$$
\lim _{l \rightarrow \infty} K \int_{a}^{b} f \mathrm{~d} g_{l}=K \int_{a}^{b} f \mathrm{~d} g
$$

holds.
Proof. For every subdivision $A=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\}$ we have evidently

$$
\begin{equation*}
\text { - }\left|K(A)-K_{l}(A)\right| \leqq M \cdot \operatorname{var}_{a}^{b}\left(g-g_{l}\right) \tag{2,12}
\end{equation*}
$$

where $K_{l}(A)$ is the Kurzweil sum for $f$ and $g_{l}$.

Let $\varepsilon>0$ be given. We choose $l_{0}$ such that $\operatorname{var}_{a}^{b}\left(g_{l}-g\right)<\varepsilon / 4 M$ for $l>l_{0_{b}}$. (If $M=0$ then the proposition is evidently valid.) Since $K \int_{a}^{b} f \mathrm{~d} g_{l}$ exists for all $l$ we can find for a given $l>l_{0}$ a set $S \in \mathscr{S}$ such that for any $A_{1}, A_{2} \in A(S)$ we have $\left|K_{l}\left(A_{1}\right)-K_{l}\left(A_{2}\right)\right|<\varepsilon / 2$ (cf. Prop. 3,1). Hence

$$
\begin{gathered}
\left|K\left(A_{1}\right)-K\left(A_{2}\right)\right| \leqq\left|K\left(A_{1}\right)-K_{l}\left(A_{1}\right)\right|+\left|K_{l}\left(A_{1}\right)-K_{l}\left(A_{2}\right)\right|+\left|K_{l}\left(A_{2}\right)-K\left(A_{2}\right)\right| \leqq \\
\leqq 2 M \operatorname{var}_{a}^{b}\left(g_{l}-g\right)+\varepsilon / 2<\varepsilon
\end{gathered}
$$

for any $A_{1}, A_{2} \in A(S)$ and $K \int_{a}^{b} f \mathrm{~d} g$ exists by Prop. 2,1. The other part of the proposition is a consequence of the inequality $(2,12)$.

Corollary 2,1. If $g_{b} \in B V(a, b)$ is a pure break function and $f:[a, b] \rightarrow R$ is bounded then $K \int_{a}^{b} f \mathrm{~d} g_{b}$ exists and we have $K \int_{a}^{b} f \mathrm{~d} g_{b}=\sum_{t \in[a, b]} f(t) \Delta g_{b}(t)$.

Proof. Similarly as in the proof of Corollary 1,2 it is sufficient to prove that $K \int_{a}^{b} f \mathrm{~d} g$ exists for any pure break function $g \in B V(a, b)$ which is discontinuous at the points of a finite set $\left\{t_{1}, t_{2}, \ldots, t_{v}\right\} \subset[a, b]$ and that $K \int_{a}^{b} f \mathrm{~d} g=\sum_{i=1}^{v} f\left(t_{i}\right) \Delta g\left(t_{i}\right)$. Let us suppose that $a \leqq t_{1}<t_{2}<\ldots t_{v}<b$ and let us define

$$
\delta(\tau)=\frac{4}{4} \varrho\left(\tau,\left\{a, t_{1}, \ldots, t_{v}, b\right\}\right)
$$

for $\tau \in(a, b), \tau \neq t_{i}, i=1, \ldots, v$, where $\varrho$ is the Euclidean distance; further we define

$$
\Delta_{j}=\max _{\tau \in\left(t_{,}, t_{j+1}\right)} \delta(\tau), \quad j=1, \ldots, v-1
$$

and $\Delta_{0}=\max \delta(\tau), \Delta_{v}=\max _{\tau \in\left(t_{v}, b\right)} \delta(\tau)$ if $a<t_{1}, t_{v}<b$, respectively and we set $\delta(a)=$ $=\delta\left(t_{j}\right)=\delta(b)=\Delta, j=1, \ldots, v$, where $\Delta=\min _{j}\left(\Delta_{j}\right)$. In this way we have defined a function $\delta:[a, b] \rightarrow(0,+\infty)$ which provides a set $S$ defined by $(2,1)$.

Let now $A=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\} \in A(S)$. By definition we have $\left[\alpha_{j-1}, \alpha_{j}\right] \subset$ $\subset\left[\tau_{j}-\delta\left(\tau_{j}\right), \tau_{j}+\delta\left(\tau_{j}\right)\right]$ for any $j=1, \ldots, k$ and the following assertions are valid:

1) if $\tau_{j} \in\left\{a, t_{1}, \ldots, t_{v}, b\right\}$ then $\left|\alpha_{j}-\alpha_{j-1}\right| \leqq 2 \delta\left(\tau_{j}\right)=2 \Delta$ and $\left[\alpha_{j-1}, \alpha_{j}\right] \cap$ $\cap\left\{a, t_{1}, \ldots, t_{v}, b\right\}=\tau_{j}$,
2) if $\tau_{j} \notin\left\{a, t_{1}, \ldots, t_{v}, b\right\}$ then $\left|\alpha_{j}-\alpha_{j-1}\right| \leqq 2 \delta\left(\tau_{j}\right)=\frac{1}{2} \varrho\left(\tau_{j},\left\{a, t_{1}, \ldots, t_{v}, b\right\}\right)$ and therefore $\left[\alpha_{j-1}, \alpha_{j}\right] \cap\left\{a, t_{1}, \ldots, t_{v}, b\right\}=\emptyset$.

Hence $\left\{a, t_{1}, \ldots, t_{v}, b\right\} \subset\left\{\tau_{1}, \ldots, \tau_{k}\right\}$ and

$$
\begin{gathered}
K(A)=\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)\right)=\dot{f}(a)(g(a+)-g(a))+ \\
+\sum_{i=1}^{v} f\left(t_{i}\right)\left(g\left(t_{i}+\right)-g\left(t_{i}-\right)\right)+f(b)(g(b)-g(b-))=\sum_{i=1}^{v} f\left(t_{i}\right) \Delta g\left(t_{i}\right)
\end{gathered}
$$

for any $A \in A(S)$, i.e. $K \int_{a}^{b} f \mathrm{~d} g$ exists and equals $\sum_{i=1}^{v} f\left(t_{i}\right) \Delta g\left(t_{i}\right)$. This proves the corol-
lary.

Proposition 2,4. Let $T \subset(a, b)$ be given such that $[a, b]-T$ is dense in $[a, b]$ (i.e. $[a, b]-T=[a, b])$ and let $g(t)=0$ for $t \in[a, b]-T$. If $K \int_{a}^{b} f \mathrm{~d} g$ exists then necessarily $K \int_{a}^{b} f \mathrm{~d} g=0$.

Proof. For any $\delta:[a, b] \rightarrow(0,+\infty)$ we choose from the system of intervals $(\tau-\delta(\tau), \tau+\delta(\tau)), \tau \in[a, b]$ a finite system $\left(\tau_{j}-\delta\left(\tau_{j}\right), \tau_{j}+\delta\left(\tau_{j}\right)\right)=J_{j}, j=1, \ldots$ $\ldots, k$ such that $\tau_{j}<\tau_{j+1},[a, b] \subset \bigcup_{j=1} J_{j}$ and $[a, b]-\bigcup_{\substack{j=1 \\ j \neq r}} J_{j} \neq \emptyset$ for any $r=$ $=1, \ldots, k$. Hence $J_{j} \cap J_{j+1} \neq \emptyset$ is an interval for all $j=1, \ldots, k-1$ and the density of $[a, b]-T$ implies that there is an $\alpha_{j} \in\left(J_{j} \cap J_{j+1}\right) \cap([a, b]-T)$ for $j=1, \ldots, k-1$. If we set $\alpha_{0}=a, \alpha_{k}=b$, then we evidently obtain a subdivision $A=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\} \in A(S)$, where $S$ is determined by $\delta$ (cf. (2,1)) and $g\left(\alpha_{i}\right)=0$ for $i=0,1, \ldots, k$. Hence we have $K(A)=0$ for this subdivision $A$ and our proposition follows immediately from Def. 2,1.

Example 2,1 (due to I. Vrkoč). Let $g(1 /(l+1))=2^{-l}, l=1,2, \ldots, g(t)=0$ for $t \in[0,1]-\{1 /(l+1)\}_{l=1}^{\infty}$. Evidently $g \in \operatorname{BV}(a, b)$. Let us put $f(1 /(l+1))=2^{l}$, $f(t)=0$ for $t \in[0,1]-\{1 /(l+1)\}_{l=1}^{\infty}$. We show that the integral $K \int_{0}^{1} f \mathrm{~d} g$ does not exist. For an arbitrary $\delta:[0,1] \rightarrow(0,+\infty)$ we set $\alpha_{0}=\tau_{0}=0$. Since $1 /(l+1) \rightarrow$ $\rightarrow 0$ for $l \rightarrow \infty$, in ( $0, \delta(0)$ ) there exists a point of the form $1 /\left(l_{0}+1\right)$. We set further $\alpha_{1}=\tau_{1}=1 /\left(l_{0}+1\right)$ and choose points $\alpha_{2}, \ldots, \alpha_{k}$ and $\tau_{2} \ldots, \tau_{k}$ such that $A=$ $=\left\{\alpha_{0}, \tau_{1}, \alpha_{1}, \ldots, \tau_{k}, \alpha_{k}\right\} \in A(S)$ where $S$ is the set given by $\delta($ cf. $(2,1))$ and $g\left(\alpha_{j}\right)=0$ for $j=2, \ldots, k$.

This choice of $A \in A(S)$ yields

$$
\begin{gathered}
K(A)=\sum_{j=1}^{k} f\left(\tau_{j}\right)\left(g\left(\alpha_{j}\right)-g\left(\alpha_{j-1}\right)=f\left(\tau_{1}\right) g\left(\alpha_{1}\right)=\right. \\
=f\left(1 /\left(l_{0}+1\right)\right) g\left(1 /\left(l_{0}+1\right)=f\left(1 /\left(l_{0}+1\right)\right) g\left(1 /\left(l_{0}+1\right)\right)=1\right.
\end{gathered}
$$

for any $\delta:[0,1] \rightarrow(0,+\infty)$. Hence the integral $K \int_{a}^{b} f \mathrm{~d} g$ cannot exist. Indeed, if it existed, its value would be zero by Prop. 2,4 the set $T=\{1 /(l+1)\}_{l=1}^{\infty}$ having all properties required in Prop. 2,4. However, for any $S$ we have constructed an $A \in A(S)$ such that $K(A)=1$ and Definition 2,1 yields a contradiction with the existence of $K \int_{a}^{b} f \mathrm{~d} g$.

The set $T=\{1 /(l+1)\}_{l=1}^{\infty}=V_{g}$ is the set of all points of variability of $g$. The function $g$ is evidently of bounded variation in $[0,1](g \in B V(0,1))$. By Prop. 2,2 the integral $K \int_{a}^{b} f \mathrm{~d} g$ does not exist for $g$ given above and for any arbitrary function $f$ satisfying $f(1 /(l+1))=2^{-1}, f:[0,1] \in R($ e.g. for the function from Example 1,1).

In this way functions $g \in B V(0,1)$ are constructed such that the Young integral $Y \int_{0}^{1} f \mathrm{~d} g$ exists but the Kurzweil integral $K \int_{0}^{1} f \mathrm{~d} g$ does not.

$$
\text { 3. COMPARISON OF } Y \int_{a}^{b} f \mathrm{~d} g \text { AND } K \int_{a}^{b} f \mathrm{~d} g \text { FOR } g \in B V(a, b)
$$

In this section we assume that $g \in B V(a, b), f:[a, b] \rightarrow R$ and $Y \int_{a}^{b} f \mathrm{~d} g$ exists The aim of our study is to find additional properties of $f$ and $g$ guaranteeing the existence of the integral $K \int_{a}^{b} f \mathrm{~d} g$.

For the function $g \in B V(a, b)$ let us denote by $N_{S} \subset(a, b)$ the set of all points $t \in(a, b)$ of discontinuity of the function $g$ for which $g(t-)=g(t+)$, i.e.

$$
N_{S}=\{t \in(a, b) ; g(t-)=g(t+), g(t) \neq g(t-)\}
$$

and let us define $g_{S}(t)=g(t)-g(t-)$ for $t \in N_{S}, g_{S}(t)=0$ for $t \in[a, b]-N_{S}$; we have evidently $g_{S} \in B V(a, b)$ because $\operatorname{var}_{a}^{b} g_{S}=2 \sum_{t \in N_{S}}(g(t)-g(t-))<\operatorname{var}_{a}^{b} g$. In Prop. 1,1 we have proved that $Y \int_{a}^{b} f \mathrm{~d} g_{s}$ exists for any function $f:[a, b] \rightarrow R$ and $Y \int_{a}^{b} f \mathrm{~d} g_{s}=0$.

We denote further $g_{R}=g-g_{S}$; evidently $g_{R} \in B V(a, b)$ and if $g_{R}(t+)=g_{R}(t-)$ then $g_{R}(t)=g_{R}(t-)$, i.e. $g_{R}$ is continuous at all points of continuity of $g$ as well as for all $t \in N_{S}$.

Since $Y \int_{a}^{b} f \mathrm{~d} g_{s}$ exists by the assumption, the integral $Y \int_{a}^{b} f \mathrm{~d} g_{R}$ exists as well and equals $Y \int_{a}^{b} f \mathrm{~d} g-Y \int_{a}^{b} f \mathrm{~d} g_{S}=Y \int_{a}^{b} f \mathrm{~d} g$. Using the existence of $Y \int_{a}^{b} f \mathrm{~d} g_{R}$ we obtain from Theorem 1,2 that $f$ is bounded on a finite number of closed intervals which are complementary to a finite number of open intervals on which the function $g_{R}$ is constant. It is possible to assume that $|f(t)| \leqq M$ for all $t \in[a, b]$; in the opposite case we set $f=f$ on the set on which $f$ is bounded and $\tilde{f}=0$ otherwise. By Corollary 1,1 the existence of $Y \int_{a}^{b} f \mathrm{~d} g_{R}$ is equivalent to the existence of $Y \int_{a}^{b} f \mathrm{~d} g_{R}$ and we have $Y \int_{a}^{b} f \mathrm{~d} g_{R}=Y \int_{a}^{b} f \mathrm{~d} g_{R}$.

Now we uset the usual decomposition $g_{R}=g_{c}+g_{R b}$ of $g_{R} \in B V(a, b)$ into the continuous part $g_{c}$ and a pure break function $g_{R b}$. Corollary 1,2 guarantees the existence of $Y \int_{a}^{b} f \mathrm{~d} g_{R b}$ and so we obtain also the existence of $Y \int_{a}^{b} f \mathrm{~d} g_{c}$. Moreover, we have

$$
Y \int_{a}^{b} f \mathrm{~d} g_{R b}=\sum_{t \in[a, b]} f(t) \Delta g_{R b}(t)=\sum_{t \in[a, b]} f(t) \Delta g(t)
$$

Since $g_{c} \in B V(a, b)$ is continuous the norm integral $N Y \int_{a}^{b} f \mathrm{~d} g_{c}$ exists by Theorem 1,5 and by Theorem 1,4 also the Riemann-Stieltjes norm integral $N R \int_{a}^{b} f \mathrm{~d} g_{c}$ exists. From Remark 2,2 the existence of $K \int_{a}^{b} f \mathrm{~d} g_{c}$ and the equality $K \int_{a}^{b} f \mathrm{~d} g_{c}=Y \int_{a}^{b} f \mathrm{~d} g_{c}$ immediately follows. Further, Corollary 2,1 implies the existence of $K \int_{a}^{b} f \mathrm{~d} g_{R b}$ since the function $f$ is bounded, and also the equality $K \int_{a}^{b} f \mathrm{~d} g_{R b}=Y \int_{a}^{b} f \mathrm{~d} g_{R b}$.

Hence the integral $K \int_{a}^{b} f \mathrm{~d} g_{R}=K \int_{a}^{b} f \mathrm{~d} g_{c}+K \int_{a}^{b} f \mathrm{~d} g_{R b}$ exists; this statement is an easy consequence of Prop. 2,2.

We can summarize the above results for the case $N_{S}=\emptyset$ in the following
Theorem 3,1. If $f:[a, b] \rightarrow R, g \rightarrow B V(a, b$ is such that $g(t+)=g(t-)$ for some $t \in(a, b)$ implies $g(t)=g(t-)$ and if $Y \int_{a}^{b} f \mathrm{~d} g$ exists, then also $K \int_{a}^{b} f \mathrm{~d} g$ exists and both integrals are equal.

In the general case, i.e. if $N_{S} \neq \emptyset$ the existence of $Y \int_{a}^{b} f \mathrm{~d} g$ implies not necessarily the existence of $K \int_{a}^{b} f \mathrm{~d} g$. This fact is shown in Example 2,1.

If we suppose that $f$ is bounded on $N_{S}\left(|f(t)| \leqq M\right.$ for $\left.t \in N_{S}\right)$ then we define $f(t)=$ $=f(t)$ for $t \in N_{S}, f(t)=0$ for $t \in[a, b]-N_{S}$. Hence $f$ is bounded and from Corollary 2,1 we obtain the existence of $K \int_{a}^{b} f f \mathrm{~d} g_{s}$ while Prop. 2,2 guarantees the existence of $K \int_{a}^{b} f \mathrm{~d} g_{S}$. Corollary 2,1 gives moreover $K \int_{a}^{b} f \mathrm{~d} g_{S}=0$ because $g_{S}(t)=g_{S}(t+)-$ $-g_{S}(t-)=0$ for all $t \in[a, b]$. This yields the following

Theorem 3,2. If $f:[a, b] \rightarrow R,|f(t)| \leqq M$ for $t \in N_{S}, g \in B V(a, b)$ and $Y \int_{a}^{b} f \mathrm{~d} g$ exists then $K \int_{a}^{b} f \mathrm{~d} g$ exists and both integrals are equal.

Remark 3,1. Evidently, if the set $N_{S}$ is finite, then the boundedness of $f$ on $N_{S}$ can be omitted.

Corollary 3,1. If $f, g \in B V(a, b)$ then $K \int_{a}^{b} f \mathrm{~d} g$ exists and equals $Y \int_{a}^{b} f \mathrm{~d} g$.
Proof. This statement follows from Corollary 1,3 which states the same result for the Young integral, from the boundedness of $f$ and from Theorem 3,2.

Finally, we mention the known fact (see [1]), that if we set $[a, b]=[0,1], g(t)=$ $=t, f(t)=\sin (1 / t)-(1 / t) \cos (1 / t)$, for $t \in(0,1], f(0)=0$ then the Perron integral $P \int_{0}^{1} f \mathrm{~d} g$ exists and by Theorem 2,1 also the integral $K \int_{0}^{1} f \mathrm{~d} g$ exists. It is also known that for this choice of $f$ and $g$ the Riemann integral does not exist. Since $g(t)=t$ is continuous in $[0,1]$ we obtain that $Y \int_{0}^{1} f \mathrm{~d} g$ cannot exist (cf. Theorems 1,3, 1,4) and so we have an example of functions $g \in B V(a, b), f:[a, b] \rightarrow R$ such that $K \int_{a}^{b} f \mathrm{dg}$ exists but $Y \int_{a}^{b} f \mathrm{~d} g$ does not.

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