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. TWO-SIDED SOLUTIONS OF LINEAR INTEGRODIFFERENTIAL EQUATIONS OF VOLTERRA TYPE WITH DELAY

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Summary. For the system $x = A(t) x + \varepsilon \int_{-\infty}^{t} R(t-s) x(s) ds + \varepsilon \int_{t-T}^{t} P(t-s) x(s) ds$, $0 < T < \infty$, where A(t) is either a constant or a periodic matrix, the existence of two-sided solutions with $x(0) = x_0$ is studied in connection with the behaviour of the solutions of the unperturbed system for $\varepsilon = 0$. A Floquet type theorem for the periodic case is also proved.

Keywords: Integrodifferential equation, two-sided solution.

AMS Classification: 45D, 34C.

Consider the integrodifferential equation

(1)
$$\frac{\mathrm{d}x(t)}{\mathrm{d}t} = A x(t) + \varepsilon \int_{-\infty}^{t} R(t-s) x(s) \,\mathrm{d}s + \int_{t-T}^{t} P(t-s) x(s) \,\mathrm{d}s \,,$$

here $x \in \mathbb{R}^n$, $\varepsilon > 0$ is a parameter, A is a constant $n \times n$ matrix, $0 < T < \infty$, and the matrix functions R, P satisfy the conditions

(I) R(t) is continuous and

(2)
$$[[R(t)]] \leq t^{\alpha-1}e^{-\gamma t} \text{ for } t > 0,$$

where α . γ are positive constants, $0 < \alpha < 1$ and ||B|| is the euclidean norm of a matrix B;

(II) P(t) is continuous on the interval [0, T].

Definition. A solution $x_{k}(t)$ of the equation (1) is called two-sided if

- 1. x_{ε} is defined on the interval $(-\infty, \infty)$,
- 2. $\lim_{\varepsilon \to 0} \|x_{\varepsilon} x\|_{L} = 0 \text{ for any } L > 0, \text{ where } \|x_{\varepsilon} x\|_{L} = \max_{-L \le t \le L} \|x_{\varepsilon}(t) x(t)\| \text{ and }$

x is a solution of the equation

(3)
$$\frac{\mathrm{d}x}{\mathrm{d}t} = Ax$$

Remark. The above definition includes also the case of a matrix solution of (1) i.e. either $x_{\varepsilon}(t)$, $x(t) \in \mathbb{R}^n$ or $x_{\varepsilon}(t)$, $x(t) \in M(n)$, where M(n) is the set of all $n \times n$ matrices.

We study the problem of existence of two-sided solutions of the equation (1). We also study the case when the matrix A is nonconstant and periodic. Yu. A. Ryabov [2] proved a sufficient condition for the existence of a two-sided matrix solution of the equation (1) without the second integral term, i.e. when $P \equiv 0$, and has formulated a sufficient condition for the existence and uniqueness of a two-sided solution of this equation.

Theorem 1. Let the conditions (I), (II) be satisfied and let the eigenvalues $\lambda_1, \lambda_2, ...$..., λ_n of the matrix A satisfy the condition

(4) $\min_{j} \operatorname{Re} \lambda_{j} > -\gamma.$

Then there exists an $\varepsilon^* > 0$ such that the following assertions are valid:

(a) For any $\varepsilon \in (0, \varepsilon^*]$ there exists a two-sided matrix solution of the equation (1) of the form

(5)
$$X_{\varepsilon}(t) = e^{Dt},$$

where $D = D(\varepsilon)$ is a matrix independent of t and $\lim_{\varepsilon \to 0} D(\varepsilon) = A$, i.e. $\lim_{\varepsilon \to 0} ||D(\varepsilon) - A|| = 0$.

(b) For any $\varepsilon \in (0, \varepsilon^*]$ and $x_0 \in \mathbb{R}^n$ there exists a unique solution $x_{\varepsilon}(t)$ of the equation (1), satisfying the condition $x_{\varepsilon}(0) = x_0$ and $x_{\varepsilon} \in U_{\delta} = \{z \in C^0((-\infty, \infty), \mathbb{R}^n): z(t) e^{\delta t} < \infty \text{ for all } t \in (-\infty, 0]\}$, where δ is a constant and $0 < \delta < \gamma$.

The assertion (a) of this theorem concerning the case $P \equiv 0$ has been proved by Ryabov in [2], where the existence of the matrix D is proved by the method of matrix series. The proof of the assertion (b) is not given in [2]. We prove both assertions of Theorem 1 using the Banach fixed point theorem.

We need the following lemma.

Lemma 1. Let $0 < \overline{i} < \infty$, $u \in C^0([0, \overline{i}], R)$ be a nonnegative function, $a \ge 0$, $b \ge 0$, $k \ge 0$, $\beta > 0$ constants and

(6)
$$u(t) \leq a + k \int_0^t \int_0^s u(\tau) \, d\tau \, ds + b \int_0^t \int_0^s (s - \tau)^{\beta - 1} u(\tau) \, d\tau \, ds$$
,

 $t \in [0, \bar{t}]$. Then

(7)
$$u(t) \leq a \exp\left\{\frac{k}{2}t^2 + \frac{b}{\beta(\beta+1)}t^{\beta+1}\right\}, t \in [0, \bar{t}].$$

Proof. From the Fubini theorem it follows that the inequality (6) is equivalent to

$$u(t) \leq a + \int_0^t \left[k(t-\tau) + \frac{b}{\beta} (t-\tau)^{\beta} \right] u(\tau) \, \mathrm{d}\tau$$

and applying [1, Theorem 1.4_1] we obtain the inequality (7).

Proof of Theorem 1. Let D be a constant $n \times n$ matrix. The matrix function $X_{\epsilon}(t) = e^{Dt}$ is a matrix solution of the equation (1) if and only if

$$De^{Dt} = Ae^{Dt} + \varepsilon \int_{-\infty}^{t} R(t-s) e^{Ds} ds + \varepsilon \int_{t-T}^{t} P(t-s) e^{Ds} ds$$

Let us look for the matrix solution of this equation in the form D = A + Q, where Q is an unknown matrix. Putting t = 0 in this equation we obtain the following equation for Q:

(8)
$$Q = \varepsilon \int_0^\infty R(\Theta) e^{-(A+Q)\Theta} d\Theta + \varepsilon \int_0^T P(\Theta) e^{-(A+Q)\Theta} d\Theta.$$

Using the substitution $s = t - \Theta$ in the integrals on the right-hand side of (8) one can show that if Q is a matrix solution of (8) and D = A + Q then e^{Dt} is a matrix solution of the equation (1). Therefore it suffices to solve the matrix equation (8).

The condition (4) implies that there exists μ , $-\gamma < \mu < \min_{j} \operatorname{Re} \lambda_{j}$ and a constant k > 1 such that

$$(9)^{\sigma} \qquad ||e^{-A\Theta}|| \leq k e^{-\mu\Theta}, \quad \Theta \geq 0.$$

Let $V_{\varkappa} = \{Q \in M(n): ||Q|| < \varkappa\}$, where M(n) is the set of all $n \times n$ matrices and $0 < \varkappa < \gamma + \mu$. Define the mapping

$$\mathcal{F}_{\varepsilon}: V_{\varkappa} \to M(n), \quad \mathcal{F}_{\varepsilon}(Q) = \varepsilon \int_{0}^{\infty} R(\Theta) e^{-(A+Q)\Theta} d\Theta + \varepsilon \int_{0}^{T} P(\Theta) e^{-(A+Q)\Theta} d\Theta.$$

Lemma 2. There exists an $\varepsilon^* > 0$ such that the mapping $\mathscr{F}_{\varepsilon}$ is contractive for $\varepsilon \in (0, \varepsilon^*]$.

Proof. If $Q_1, Q_2 \in V_x$ then using the inequalities (2), (9) we obtain

(10)
$$\|\mathscr{F}_{\varepsilon}(Q_{1}) - \mathscr{F}_{\varepsilon}(Q_{2})\| \leq \varepsilon \left(k \int_{0}^{\infty} \Theta^{\alpha-1} e^{-(\gamma+\mu)\theta} \|e^{-Q_{1}\theta} - e^{-Q_{2}\theta}\| \,\mathrm{d}\theta + k \int_{0}^{T} e^{-\mu\theta} \|P(\Theta)\| \|e^{-Q_{1}\theta} - e^{-Q_{2}\theta}\| \,\mathrm{d}\Theta \right).$$

The mean value theorem implies that

$$\left\|e^{-Q_1\theta}-e^{-Q_2\theta}\right\|\leq \sup_{Q\in V_{\mathbf{N}}}\left\|e^{Q\theta}\right\|\left\|Q_1\theta-Q_2\theta\right\|\leq \Theta e^{\mathbf{x}\theta}\left\|Q_1-Q_2\right|$$

for any Θ . Using this inequality and (10) we have

$$\begin{aligned} \|\mathscr{F}_{\varepsilon}(Q_{1}) - \mathscr{F}_{\varepsilon}(Q_{2})\| &\leq \varepsilon k \left(\int_{0}^{\infty} e^{-\xi \Theta} \Theta^{\alpha} \, \mathrm{d}\Theta \right. + \\ &+ \int_{0}^{T} \Theta e^{(\alpha - \mu)\Theta} \|P(\Theta)\| \, \mathrm{d}\Theta \right) \|Q_{1} - Q_{2}\| \end{aligned}$$

where $\zeta = \gamma + \mu - \varkappa$. If we put $s = \zeta \Theta$ in the first integral then the above inequality takes the form

$$\left\|\mathscr{F}_{\varepsilon}(Q_{1})-\mathscr{F}_{\varepsilon}(Q_{2})\right\|\leq \varepsilon k[\zeta^{-\alpha-1}\Gamma(\alpha+1)+C],$$

where $C = \int_0^T \Theta e^{(\varkappa - \mu)\Theta} \|P(\Theta)\| d\Theta < \infty$. Since $0 < \alpha + 1 < 2$ we have $0 < < \Gamma(\alpha + 1) < \infty$. Therefore if

(11)
$$0 < \varepsilon < \varepsilon_1 := \nu k^{-1} [\zeta^{\alpha+1} \Gamma(\alpha+1) + C]^{-1},$$

where 0 < v < 1, then

$$\left|\mathscr{F}_{\varepsilon}(Q_{1})-\mathscr{F}_{\varepsilon}(Q_{2})\right|\leq v\left\|Q_{1}-Q_{2}\right\|$$
,

i.e. the mapping $\mathcal{F}_{\varepsilon}$ is contractive.

Lemma 2 implies that if $\varepsilon \in (0, \varepsilon_1)$, where ε_1 is defined by (11), then the mapping $\mathscr{F}_{\varepsilon}$ has a unique fixed point $Q \in V_x$. This matrix is a unique solution of (8) belonging to the set V_x . From (8) we have that $\lim_{\varepsilon \to 0} Q(\varepsilon) = 0$ and so $\lim_{\varepsilon \to 0} D(\varepsilon) = A$, i.e. $\lim_{\varepsilon \to 0} ||D(\varepsilon) - A|| = 0$, where $D(\varepsilon) = A + Q(\varepsilon)$. It remains to prove the assertion (b) of Theorem 1. We shall prove that for any $x_0 \in \mathbb{R}^n$ there exists a unique solution x(t) of the equation (1) satisfying the conditions $x(0) = x_0$ and $\sup_{-\infty < t \le 0} ||x(t)|| e^{\delta t} < \infty$,

where

(12)
$$0 < \delta < \gamma, \quad \mu + \delta > 0$$

and μ is the number from (9). Since $\mu + \gamma > 0$ there exists a number δ satisfying (12). Define the subspace

$$B_{\delta} = \left\{ x \in C^{0}((-\infty, 0], R^{n}) : \sup_{-\infty < t \leq 0} ||x(t)|| e^{\delta t} < \infty \right\}.$$

The set B_{δ} with the norm $||x||_{\delta} = \sup_{-\infty < t \le 0} ||x(t)|| e^{\delta t}$ is a Banach space. Define the mapping

$$G_{\varepsilon}: B_{\delta} \to C^{0}((-\infty, 0], R^{n}),$$

$$(G_{\varepsilon}x)(t) = \varepsilon \left[\int_{0}^{t} e^{A(t-s)} \left(\int_{-\infty}^{s} R(s-\tau) x(\tau) d\tau + \int_{s-\tau}^{s} P(s-\tau) x(\tau) d\tau \right) ds \right], \quad -\infty < t \leq 0.$$

We shall prove that $G_{\varepsilon}(B_{\delta}) \subset B_{\delta}$ and G_{ε} is contractive for $\varepsilon > 0$ sufficiently small. If $x \in B_{\delta}$ and $-\infty < t \leq 0$ then

$$\begin{aligned} \|G_{\varepsilon}(t)\| &\leq \varepsilon k \left[\int_{t}^{0} e^{-\mu(s-\tau)} \left(\int_{-\infty}^{s} e^{-\gamma(s-\tau)} (s-\tau)^{\alpha-1} \|x(\tau)\| \, \mathrm{d}\tau \right. + \\ &+ \int_{s-T}^{s} \|P(s-\tau)\| \, \|x(\tau)\| \, \mathrm{d}\tau \right) \mathrm{d}s \right] &\leq \varepsilon k (I_1(t) + I_2(t)) \, \|x\|_{\delta} \,, \end{aligned}$$

where

$$I_1(t) = \int_t^0 e^{-\mu(s-t)} \left(\int_{-\infty}^s e^{-\gamma(s-\tau)} e^{-\delta\tau} (s-\tau)^{\alpha-1} d\tau \right) ds,$$

$$I_2(t) = \int_t^0 e^{-\mu(s-t)} \left(\int_{s-\tau}^s \|P(s-\tau)\| e^{-\delta\tau} d\tau \right) ds.$$

The function $I_1(t)$ can be written in the form

$$I_1(t) = e^{\mu t} \int_t^0 e^{-(\mu+\delta)s} \left(\int_{-\infty}^s e^{-(\gamma-\delta)(s-\tau)} (s-\tau)^{\alpha-1} d\tau \right) ds,$$

and using the substitution $u = (\gamma - \delta)(s - \tau)$ we obtain

$$I_{1}(t) = e^{\mu t} \int_{t}^{0} e^{-(\mu+\delta)s} \left(\int_{0}^{\infty} (\gamma-\delta)^{-\alpha} e^{-u} u^{\alpha-1} du \right) ds =$$

= $\Gamma(\alpha) (\gamma-\delta)^{-\alpha} e^{\mu t} \int_{t}^{0} e^{-(\mu+\delta)s} ds =$
= $\Gamma(\alpha) (\gamma-\delta)^{-\alpha} (\mu+\delta)^{-1} e^{\mu t} (e^{-(\mu+\delta)t} - 1).$

The function $I_2(t)$ can be written in the form

$$I_{2}(t) = \int_{t}^{0} e^{-\mu(s-t)} \left(\int_{0}^{T} \|P(\Theta)\| e^{\delta\Theta} d\Theta \right) e^{-\delta s} ds =$$

= $e^{\mu t} \left(\int_{0}^{T} \|P(\Theta)\| e^{\delta\Theta} d\Theta \right) (\mu + \delta)^{-1} (e^{-(\mu+\delta)t} - 1)$

Therefore we have the inequality

$$\|G_{\varepsilon} x(t)\| e^{\delta t} \leq \varepsilon k (K_1 + K_2) e^{(\mu+\delta)t} (e^{-(\mu+\delta)t} - 1) \|x\|_{\delta},$$

where $K_1 = \Gamma(\alpha) (\gamma - \delta)^{-\alpha} (\mu + \delta)^{-1} > 0$, $K_2 = (\int_0^T ||P(\Theta)|| e^{\delta \Theta} d\Theta) (\mu + \delta)^{-1} > 0$. Since $\mu + \delta > 0$ we obtain

$$\sup_{t \le \infty < t \le 0} \|G_{\varepsilon} x(t)\| e^{\delta t} \le \varepsilon k (K_1 + K_2) \|x\|_{\delta} < \infty , \quad \text{i.e.} \quad G_{\varepsilon} x \in B_{\delta}$$

and therefore $G_{\varepsilon}B_{\delta} \subset B_{\delta}$. Since G_{ε} is linear we have

$$\|G_{\varepsilon}x_1 - G_{\varepsilon}x_2\|_{\delta} = \|G_{\varepsilon}(x_1 - x_2)\|_{\delta} \leq \varepsilon k(K_1 + K_2) \|x_1 - x_2\|_{\delta}$$

for any $x_1, x_2 \in B_{\delta}$ and thus the map G_{ε} is contractive for any $\varepsilon \in (0, \tilde{\varepsilon})$, where $\tilde{\varepsilon} = k^{-1}(K_1 + K_2)^{-1}$. From now on we assume $\varepsilon \in (0, \tilde{\varepsilon})$. Then the map G_{ε} has a unique fixed point $\varphi_0 \in B_{\delta}$. Since this map is linear and $0 \in B_{\delta}$ we conclude that $\varphi_0 = 0$.

Let φ_1, φ_2 be two solutions of the equation (1) satisfying the condition $\varphi_1(0) = \varphi_2(0) = x_0$, $\sup_{-\infty < t \le 0} ||\varphi_i(t)|| e^{\delta t} < \infty$, i = 1, 2 and let $\varphi(t) = \varphi_1(t) - \varphi_2(t)$. Then

 $\sup_{\substack{-\infty < t \leq 0 \\ < t \leq 0}} \|\varphi(t)\| e^{\delta t} < \infty.$ The mapping $\Phi \in C^0((-\infty, 0], \mathbb{R}^n)$, $\Phi(t) = \varphi(t)$, $-\infty < t \leq 0$, is a fixed point of the map G_e and therefore $\Phi(t) \equiv 0$. Thus if there is a two-sided solution of (1) belonging to B_{δ} then it is uniquely defined on the interval $(-\infty, 0]$. We prove that such a two-sided solution does exist and it is also uniquely defined on the interval $[0, \infty)$.

The function $\Psi(t) = e^{D(\varepsilon)t}x_0$ is a two-sided solution of the equation (1) satisfying the initial condition $\Psi(0) = x_0$. If $\varepsilon > 0$ is sufficiently small then the condition (4) and the equality $\lim_{\varepsilon \to 0} D(\varepsilon) = A$ imply that the eigenvalues $v_1, v_2, ..., v_n$ of the matrix $D(\varepsilon)$ satisfy the condition min Re $v_j > -\gamma$. Therefore there exists a constant $\tilde{\mu}$, $-\gamma < \tilde{\mu} < \min$ Re v_j and a constant $\tilde{k} > 1$ such that

$$\|e^{-D(\varepsilon)\Theta}\| \leq \tilde{k}e^{-\tilde{\mu}\Theta}, \quad \Theta \geq 0 \quad \text{or} \quad \|e^{D(\varepsilon)t}\| \leq \tilde{k}e^{\tilde{\mu}t}, \quad t \leq 0.$$

Since $\mu + \delta > 0$, where μ is the number from (9), we have $\tilde{\mu} + \delta > 0$ for ε sufficiently small. Therefore for such $\varepsilon > 0$ we obtain

$$\sup_{-\infty < t \leq 0} \left\| e^{D(\varepsilon)t} x_0 \right\| e^{\delta t} \leq \sup_{-\infty < t \leq 0} \left(\tilde{k} e^{(\tilde{\mu}+\delta)t} \| x_0 \| \right) = \tilde{k} \| x_0 \| < \infty .$$

This means that the two-sided solution $\Psi(t) = e^{D(\varepsilon)t}x_0$ belongs to the set B_{δ} . It suffices to prove the uniqueness of two-sided solutions of the equation (1) belonging to the set B_{δ} on the interval $[0, \infty)$.

Let $\varphi_1(t)$, $\varphi_2(t)$ be two-sided solutions of the equation (1) belonging to the set B_{δ} and satisfying the condition $\varphi_1(0) = \varphi_2(0) = x_0$. Let $\varphi = \varphi_1 - \varphi_2$. Since we have proved that $\varphi_1(t) = \varphi_2(t)$ for all $t \in (-\infty, 0]$, by (2) we obtain for $t \ge 0$:

$$\begin{aligned} \|\varphi(t)\| &\leq \varepsilon \left\| \int_0^t e^{A(t-s)} \left(\int_0^s R(s-\tau) \varphi(\tau) \, \mathrm{d}\tau \right. + \\ &+ \int_{s-T}^s P(s-\tau) \varphi(\tau) \, \mathrm{d}\tau \right) \, \mathrm{d}s \right\| &\leq \\ &\leq \varepsilon \left[c \int_0^t e^{\nu(t-s)} \left(\int_0^s e^{-\gamma(s-\tau)} (s-\tau)^{\alpha-1} \|\varphi(\tau)\| \, \mathrm{d}\tau + K \int_0^s \|\varphi(\tau)\| \, \mathrm{d}\tau \right) \, \mathrm{d}s \right], \end{aligned}$$

where $v > \max_{j} \operatorname{Re} \lambda_{j}$, c > 0 ($||e^{At}|| \leq ce^{vt}$ for all $t \geq 0$) and $K = \max_{0 \leq t \leq T_{-}} ||P(t)||$.

It suffices to show that for any $0 < \overline{t} < \infty$, $\varphi(t) = 0$ for all $t \in [0, \overline{t}]$. From the above inequality we obtain

$$\|\varphi(t)\| \leq \varepsilon \left[cM \int_0^t \int_0^s (s-\tau)^{\alpha-1} \|\varphi(\tau)\| d\tau ds + cK \int_0^t \int_0^s \|\varphi(\tau)\| d\tau ds \right].$$

Applying Lemma 1 to this inequality we obtain $\varphi(t) = 0$ for all $t \in [0, \bar{t}]$.

We have shown that for $\varepsilon > 0$ sufficiently small and any $x_0 \in \mathbb{R}^n$ there exists a unique solution x_{ε} of the equation (1) satisfying the condition $x_{\varepsilon}(0) = x_0$ and defined on the interval $(-\infty, \infty)$. This solution has the form $x_{\varepsilon}(t) = e^{D(\varepsilon)t}x_0$, where $D(\varepsilon) = A + Q(\varepsilon)$, $\lim_{\varepsilon \to 0} Q(\varepsilon) = 0$. It remains to show that x_{ε} has the second property of a two-sided solution, i.e. $\lim_{\varepsilon \to 0} ||x_{\varepsilon} - x||_{L} = 0$ for any L > 0, where $x(t) = e^{At}x_{0}$. If $X_{\varepsilon}(t) = e^{D(\varepsilon)t}$ and $X(t) = e^{At}$ then

$$\|X_{\varepsilon}(t) - X(t)\| = \|e^{At}[e^{Q(\varepsilon)t} - E]\| \le \|e^{At}\| \|e^{Q(\varepsilon)t} - E\|.$$

The mean value theorem implies that for any L > 0

$$\max_{L \leq t \leq L} \|e^{Q(\varepsilon)t} - E\| \leq \max_{-L \leq t \leq L} (\|Q(\varepsilon) e^{Q(\varepsilon)t}\|) |t| \leq LC(L) \|Q(\varepsilon)\|,$$

where $C(L) = \max_{\substack{-L \leq t \leq L \\ \epsilon \neq 0}} \|e^{Q(\epsilon)t}\|$. Therefore we have $\lim_{\epsilon \neq 0} \|x_{\epsilon} - x\|_{L} = \lim_{\epsilon \neq 0} \max_{\substack{-L \leq t \leq L \\ -L \leq t \leq L}} \|x_{\epsilon}(t) - x(t)\| \leq LC(L) \|x_{0}\| \lim_{\epsilon \neq 0} \|Q(\epsilon)\| = 0$

and the proof of Theorem 1 is complete.

Let us consider the integrodifferential equation

(13)
$$\frac{\mathrm{d}x(t)}{\mathrm{d}t} = A(t) x(t) + \varepsilon \int_{-\infty}^{t} R(t-s) x(s) \,\mathrm{d}s + \varepsilon \int_{t-T}^{t} P(t-s) x(s) \,\mathrm{d}s \,,$$

where R, P, T are as above and A(t) is a continuous τ -periodic matrix function on $(-\infty, \infty)$, $\tau > 0$.

If X(t) is the normed fundamental matrix of the linear system

(14)
$$\frac{\mathrm{d}x}{\mathrm{d}t} = A(t) x$$

then by the Floquet theorem

(15)
$$X(t) = \Phi(t) e^{\Lambda \tau},$$

where Λ is a constant matrix and $\Phi(t)$ is a continuous τ -periodic matrix function. Introducing a new variable $y = \Phi^{-1}(t) x$ the equation (13) becomes

(16)
$$\frac{\mathrm{d}y(t)}{\mathrm{d}t} = \Lambda y(t) + \varepsilon \Phi^{-1}(t) \int_{-\infty}^{t} R(t-s) \Phi(s) y(s) \,\mathrm{d}s + \varepsilon \Phi^{-1}(t) \int_{t-T}^{t} P(t-s) \Phi(s) y(s) \,\mathrm{d}s \,.$$

Let us look for the matrix solution e^{Dt} of the equation (16), where $D = \Lambda + Q$, Q is an unknown matrix. This is a solution of (16) if and only if

(17)
$$De^{Dt} = \Lambda e^{Dt} + \varepsilon \Phi^{-1}(t) \int_{-\infty}^{t} R(t-s) \Phi(s) e^{Ds} ds + \varepsilon \Phi^{-1}(t) \int_{t-T}^{t} P(t-s) \Phi(s) e^{Ds} ds.$$

Putting t = 0 in this equation we obtain the equation for Q:

$$Q = \varepsilon \int_{-\infty}^{0} R(-s) \, \Phi(s) \, e^{(\Lambda+Q)s} \, \mathrm{d}s + \varepsilon \int_{-\tau}^{0} P(-s) \, \Phi(s) \, e^{(\Lambda+Q)s} \, \mathrm{d}s \, .$$

Introducing the substitution $-s = \sigma$ this equation becomes

(18)
$$Q = \varepsilon \int_0^\infty R(\sigma) \Phi(-\sigma) e^{-(\Lambda+Q)\sigma} d\sigma + \varepsilon \int_0^T P(\sigma) \Phi(-\sigma) e^{-(\Lambda+Q)\sigma} d\sigma.$$

Let Q be a solution of (18). Then

$$De^{Dt} = \Lambda e^{Dt} + \varepsilon \int_0^\infty R(\sigma) \, \Phi(-\sigma) \, e^{-D\sigma} \, \mathrm{d}\sigma \, . \, e^{Dt} + \varepsilon \int_0^T P(\sigma) \, \Phi(-\sigma) \, e^{-D\sigma} \, \mathrm{d}\sigma \, . \, e^{Dt} \, ,$$

where D = A + Q. If $\sigma = t - s$ then the above equation becomes

(19)
$$De^{Dt} = \Lambda e^{Dt} + \varepsilon \int_{-\infty}^{t} R(t-s) \Phi(s-t) e^{-D(t-s)} ds \cdot e^{Dt} + \varepsilon \int_{t-T}^{t} P(t-s) \Phi(s-t) e^{-D(t-s)} ds \cdot e^{Dt} \cdot e^{Dt}$$

If the conditions

(20)
$$\Phi(t) R(t-s) \Phi(s-t) = R(t-s) \Phi(s) \text{ for all } t, s \in \mathbb{R},$$

(21)
$$\Phi(t) P(t-s) \Phi(s-t) = P(t-s) \Phi(s) \text{ for all } t, s \in R$$

are satisfied then the equation (19) is equivalent to the equation (17). If A(t) = A is a constant matrix then these conditions are trivially satisfied.

Since the matrix functions $\Phi^{-1}(t)$, $\Phi(t)$ are continuous and periodic they must be bounded. Therefore using the same procedure as in the proof of Theorem 1 we are able to solve the equation (18) and to prove the following theorem.

Theorem 2. Let A(t) be a continuous, τ -periodic matrix function on the interval $(-\infty, \infty)$ and let the matrix functions R, P satisfy the assumptions of Theorem 1. Let $\Phi(t)$, Λ be the matrices defined by (15), let the eigenvalues $\varkappa_1, \varkappa_2, ..., \varkappa_n$ of Λ satisfy the condition

$$\min_{j} \varkappa_{j} > -\gamma$$

and let the conditions (20), (21) be satisfied. Then there exists an $\varepsilon^* > 0$ such that for any $\varepsilon \in (0, \varepsilon^*]$ the following assertions are valid:

(a) There exists a two-sided matrix solution of the equation (16) of the form

$$Y_{\varepsilon}(t) = e^{Dt}$$
,

where $D = D(\varepsilon)$ is a matrix independent of t and $\lim_{\varepsilon \to 0} D(\varepsilon) = \Lambda$.

- (b) For any $y_0 \in \mathbb{R}^n$ there exists a unique two-sided solution $y_{\varepsilon}(t)$ of the equation (16) satisfying the initial condition $y_{\varepsilon}(0) = y_0$ and $y_{\varepsilon} \in U_{\delta} = \{z \in C^0((-\infty, \infty), \mathbb{R}^n): ||z(t)|| e^{\delta t} < \infty$ for all $t \in (-\infty, 0]\}$, where δ is a constant and $0 < \delta < \gamma$.
- (c) There exists a two-sided matrix solution X_{ε} of the equation (13) satisfying the condition $X_{\varepsilon}(0) = E$, where E is the unit matrix. This matrix solution has the form $X_{\varepsilon}(t) = \Phi(t) e^{D(\varepsilon)t}$, where $\Phi(t)$ and $D(\varepsilon)$ are as above.
- (d) For any $x_0 \in \mathbb{R}^n$ there exists a unique two-sided solution x_{ε} of the equation (13) satisfying the initial condition $x_{\varepsilon}(0) = x_0$, $x_{\varepsilon} \in U_{\eta} = \{z \in C^0((-\infty, \infty), \mathbb{R}^n): \|z(t)\| e^{\eta t} < \infty$ for all $t \in (-\infty, 0]\}$, where η is a constant, $0 < \eta < \gamma$ and $x_{\varepsilon}(t) = \Phi(t) e^{D(\varepsilon)t}x_0$, $\Phi(t)$, $D(\varepsilon)$ being as above.

The assertion (c) is a generalization of the Floquet theorem.

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Súhrn

OBOJSTRANNÉ RIEŠENIA LINEÁRNYCH INTEGRODIFERENCIÁLNYCH ROVNÍC VOLTERROVHO TYPU S ONESKORENÍM

Milan Medveď

Pre systém $\dot{x} = A(t) x + \varepsilon \int_{-\infty}^{t} R(t-s) x(s) ds + \varepsilon \int_{t-T}^{t} P(t-s) x(s) ds$, $0 < T < \infty$ kde A(t) je buď konštantná, alebo periodická matica, je študovaná existencia obojstranných riešení pre malé hodnoty parametra $\varepsilon > 0$. V prípade, keď je matica A(t) periodická, je dokázaná veta Floquetovho typu.

Резюме

ДВУСТОРОННИЕ РЕШЕНИЯ ЛИНЕЙНЫХ ИНТЕГРО-ДИФФЕРЕНЦИАЛЬНЫХ УРАВНЕНИЙ ТИПА ВОЛТЕРА С ЗАПАЗДЫВАНИЕМ

Milan Medveď

Исследуется сущэствование двусторонних решений с условием $x(0) = x_0$ для системы $\dot{x}(t) = A(t) x(t) + \varepsilon \int_{-\infty}^{t} R(t-s) x(s) ds \ l + \varepsilon \int_{t-T}^{t} P(t-s) x(s) ds$ в связи с поведением решений невозмущенной системы для $\varepsilon = 0$, где $0 < T < \infty$ и A(t) – постоянная или периодическая матрица. Приведено также доказательство теоремы типа Флоке для периодического случая.

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