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# Full regularity of weak solutions to a class of nonlinear fluids in two dimensions - stationary, periodic problem 

Petr Kaplický, Josef Málek, Jana Stará


#### Abstract

We prove the existence of regular solution to a system of nonlinear equations describing the steady motions of a certain class of non-Newtonian fluids in two dimensions. The equations are completed by requirement that all functions are periodic.


Keywords: non-Newtonian fluids, shear dependent viscosity, regularity, Hölder continuity of gradients
Classification: 76F10, 35Q35, 35J65

## 0. Introduction

Let $\Omega$ be a two-dimensional square $(0, L) \times(0, L), L \in(0, \infty)$. We consider the following problem in $\mathbb{R}^{2}$ : to find $v=\left(v_{1}, v_{2}\right)$ and $\pi$ which are periodic with the period $L$ at each variable $x_{i}, i=1,2$, and solve the equations

$$
\operatorname{div} v=0
$$

$$
\begin{equation*}
v_{k} \frac{\partial v}{\partial x_{k}}-\operatorname{div}(T(D(v)))+\nabla \pi=f \tag{0.1}
\end{equation*}
$$

where $f=\left(f_{1}, f_{2}\right)$ is a given periodic vector field in $\mathbb{R}^{2}$ with zero mean value. Throughout the whole paper we use the summation convention; thus

$$
v_{k} \frac{\partial v}{\partial x_{k}}=\sum_{k=1}^{2} v_{k} \frac{\partial v}{\partial x_{k}}
$$

etc.
Let $\mathbb{S}$ be the set of symmetric matrices of the type $2 \times 2$. Then $D(v)$ belonging to $\mathbb{S}$ denotes the symmetrized $\nabla v$ and has components $D_{i j}(v)=\frac{1}{2}\left(\frac{\partial v_{i}}{\partial x_{j}}+\frac{\partial v_{j}}{\partial x_{i}}\right)$, $i, j=1,2$. Further we put the following assumptions on nonlinear tensor function $T: \mathbb{S} \rightarrow \mathbb{S}:$
(i) there exists $F: \mathbb{R}_{0}^{+} \rightarrow \mathbb{R}_{0}^{+}$such that $F \in C^{2}\left(\mathbb{R}_{0}^{+}\right)$and for all $i, j=1,2$

$$
\begin{equation*}
T_{i j}(\eta)=\frac{\partial F\left(|\eta|^{2}\right)}{\partial p_{i j}}=2 F^{\prime}\left(|\eta|^{2}\right) \eta_{i j}, \quad \forall \eta \in \mathbb{S}, \quad F(0)=\frac{\partial F(0)}{\partial p_{i j}}=0 \tag{0.2}
\end{equation*}
$$

[^0](ii) for a certain $p \in(1, \infty)$ there exist $C_{1}, C_{2}>0$ such that
\[

$$
\begin{equation*}
\frac{\partial^{2} F\left(|\eta|^{2}\right)}{\partial p_{i j} \partial p_{k l}} \xi_{i j} \xi_{k l} \geq C_{1}\left(1+|\eta|^{2}\right)^{\frac{p-2}{2}}|\xi|^{2}, \quad \forall \eta, \xi \in \mathbb{S} ; \tag{0.3}
\end{equation*}
$$

\]

and (for all $i, j, k, l=1,2$ )

$$
\begin{equation*}
\left|\frac{\partial^{2} F\left(|\eta|^{2}\right)}{\partial p_{i j} \partial p_{k l}}\right| \leq C_{2}\left(1+|\eta|^{2}\right)^{\frac{p-2}{2}}, \quad \forall \eta \in \mathbb{S} \tag{0.4}
\end{equation*}
$$

The purpose of this paper is to show that no matter whatever $p \in(1, \infty)$ is given, a weak solution to (0.1) exists and in fact it is as regular as data (smoothness of $f$ and $F$ ) allow starting from the assumption

$$
f \in L^{p^{\prime}}(\Omega) \text { if } p \in(1,2) \text { or } f \in L^{r}(\Omega), r>2, \text { if } p \geq 2
$$

We start with the notion of weak solution to (0.1). Let us denote ${ }^{1}$

$$
V_{p}=\left\{\varphi \in W_{\mathrm{loc}}^{1, p}\left(\mathbb{R}^{2}, \mathbb{R}^{2}\right) ; \varphi \text { periodic, } \operatorname{div} \varphi=0, \int_{\Omega} \varphi \mathrm{d} x=0\right\}
$$

We say that $v \in V_{p}$ is a weak solution to (0.1) if

$$
\begin{equation*}
\int_{\Omega} v_{k} \frac{\partial v_{i}}{\partial x_{k}} \varphi_{i} \mathrm{~d} x+\int_{\Omega} T_{i j}(D(v)) D_{i j}(\varphi) \mathrm{d} x=\int_{\Omega} f_{i} \varphi_{i} \mathrm{~d} x \tag{0.5}
\end{equation*}
$$

for all $\varphi$ smooth, periodic and divergence-free. Let us remark that without any additional information on $v$, the first integral is well-defined only for $p \geq \frac{4}{3}$. The method of the proof, however, provides directly better regularity of $v$. More precisely, we obtain below $v \in W_{\mathrm{loc}}^{2, p}\left(\mathbb{R}^{2}\right) \cap V_{p}$.

It is worth noticing that the nonlinearity $T$ has some useful properties that follows from (0.2)-(0.4). Namely: there exist $C_{i}, i=3,4,5$, such that

$$
\begin{gather*}
T(\eta) \cdot \eta \geq C_{4}\left(|\eta|^{p}-1\right), \quad \forall \eta \in \mathbb{S}  \tag{0.6}\\
|T(\eta)| \leq C_{5}\left(1+|\eta|^{2}\right)^{\frac{p-1}{2}}, \quad \forall \eta \in \mathbb{S}  \tag{0.7}\\
(T(\eta)-T(\xi)) \cdot(\eta-\xi) \geq C_{5}|\eta-\xi|^{2}, \quad \forall \eta, \xi \in \mathbb{S} \\
\text { with } C_{5}=C_{5}(\eta, \xi) \equiv C_{1} \int_{0}^{1}\left(1+|\xi-s(\eta-\xi)|^{2}\right)^{\frac{p-2}{2}} \mathrm{~d} s \tag{0.8}
\end{gather*}
$$

(If $A, B \in \mathbb{S}$, then $A \cdot B \equiv A_{i j} B_{i j}$.)

[^1]In particular, the last condition means that the corresponding elliptic operator is strictly monotone. If the Leray-Lions theory of monotone operators is applied directly to (0.1), the existence of weak solutions is obtained for $p \geq \frac{3}{2}$ (in dimension $d$, the corresponding bound reads $p \geq \frac{3 d}{d+2}$, which is the case when testing by $\varphi \in V_{p}$ is allowed in (0.5))(see [4] for details).

Finer techniques, using strict monotonicity of $T$ and a construction of a special $L^{\infty}$-test function, provide the existence of weak solution to ( 0.1 ) for $p \geq \frac{4}{3}$ (generally for $p \geq \frac{2 d}{d+1}$, cf. [3]). The bound corresponds to the situation when $v_{k} \frac{\partial v}{\partial x_{k}} \in L^{1}(\Omega)$ for $v \in V_{p}$.

In two dimensions, these results can be improved because of an additional ${ }^{2}$ cancellation in the convective term. More precisely, using the fact that $\frac{\partial u_{1}}{\partial x_{1}}=$ $-\frac{\partial u_{2}}{\partial x_{2}}$, we can easily check that

$$
\begin{equation*}
\frac{\partial u_{i}}{\partial x_{j}} \frac{\partial u_{j}}{\partial x_{s}} \frac{\partial u_{i}}{\partial x_{s}}=0 \tag{0.9}
\end{equation*}
$$

(see [12] for the proof of it).
This cancellation brings in the periodic case higher regularity for $v$ for all $p>1$, namely

$$
v \in \begin{cases}W_{\text {loc }}^{2,2}\left(\mathbb{R}^{2}\right) \cap V_{p} & \text { for } p \geq 2  \tag{0.10}\\ W_{\text {loc }}^{2, p}\left(\mathbb{R}^{2}\right) \cap V_{p} & \text { for } p \in(1,2)\end{cases}
$$

which gives the compactness for $\nabla v$, and consequently the existence of weak solutions.

To obtain higher regularity, we will show that there is a $p_{0}>2$ such that

$$
\begin{equation*}
\nabla v \in W_{\mathrm{loc}}^{1, p_{0}}\left(\mathbb{R}^{2}\right) \tag{0.11}
\end{equation*}
$$

Once having (0.11), we see that $\nabla v$, and thus $D(v)$, is hölderian. In particular, the 'coefficients' $\frac{\partial^{2} F\left(|D(v)|^{2}\right)}{\partial p_{i j} \partial p_{k l}}$ are bounded and Hölder continuous for all $p \in(1, \infty)$. Then the standard approach used in the regularity theory of linear elliptic systems gives as much regularity as needed (or as data allow).

The key role in getting (0.11) plays Lemma A formulated below, concerning linear elliptic systems with bounded measurable coefficients and extendable to linear systems of the Stokes type (cf. [10] or [11] for the proofs based on the $L^{p}$-estimates for linear systems proved by Bojarski in [2] and Meyers in [7]).

Let $\kappa \in \mathbb{N}, \kappa \geq 1$. For $u: \Omega \rightarrow \mathbb{R}^{2}$, let us denote

$$
N_{i} u=\sum_{r=1}^{2} \sum_{|\alpha|=\kappa} a_{i r \alpha} D^{\alpha} u_{r}, \quad i=1, \ldots, h .
$$

[^2]Similarly, denoting $\xi^{\alpha}=\xi_{1}^{\alpha_{1}} \xi_{2}^{\alpha_{2}}$, we put

$$
N_{i r} \xi=\sum_{|\alpha|=\kappa} a_{i r \alpha} \xi^{\alpha}
$$

and we assume

$$
\operatorname{rang} N \xi=\operatorname{rang}\left(N_{i r} \xi\right)_{i=1, \ldots, h}^{r=1,2}=2 \quad \forall \xi \in \mathbb{R}^{m} i
$$

Now consider the equation

$$
\begin{equation*}
\int_{\Omega} A_{i j}(x) N_{i} u(x) N_{j} \varphi(x) \mathrm{d} x=\int_{\Omega} g_{j} N_{j} \varphi \mathrm{~d} x, \quad \forall \varphi \in W^{\kappa, 2} \tag{0.12}
\end{equation*}
$$

Assume that
(0.13)

$$
\begin{gathered}
A_{i j} \in L^{\infty}(\Omega), A_{i j}=A_{j i} \quad \text { for } i, j=1,2 \\
\exists \lambda_{1}, \lambda_{2}>0 \quad \forall \eta \in \mathbb{R}^{h} \text { and for a.e. } x \in \Omega: \lambda_{1}|\eta|^{2} \leq A_{i j}(x) \eta_{i} \eta_{j} \leq \lambda_{2}|\eta|^{2}
\end{gathered}
$$

and

$$
\begin{equation*}
g \in L^{r}(\Omega), \quad r>2 \tag{0.14}
\end{equation*}
$$

Then it holds:
Lemma A. Let $u \in W^{\kappa, 2}(\Omega)$ be a solution of (0.12) with $A_{i j}$ satisfying (0.13). Let $2 \leq p \leq 2+\rho$. Then there exist $\gamma_{1}=\gamma_{1}(\rho)>1$ and $\gamma_{2}=\gamma_{2}(\rho)>1$ such that

$$
\begin{equation*}
\|u\|_{\kappa, p} \leq \frac{C}{\lambda_{1}} \gamma_{2}^{1-\frac{2}{p}}\|g\|_{p} \tag{0.15}
\end{equation*}
$$

for $p$ satisfying

$$
\begin{equation*}
p \leq 2\left(1-\lg \left[\frac{1-\frac{\lambda_{1}}{2 \lambda_{2}}}{1-\frac{\lambda_{1}}{\lambda_{2}}}\right] / \lg \gamma_{1}\right)^{-1} \tag{0.16}
\end{equation*}
$$

The same result is valid for the generalized Stokes system

$$
\begin{equation*}
\int_{\Omega} A_{i j}(x) N_{i} u(x) N_{j} \varphi(x) \mathrm{d} x+\int_{\Omega} \pi \operatorname{div} \varphi=\int_{\Omega} g_{j} N_{j} \varphi \mathrm{~d} x \quad \forall \varphi \in W^{\kappa, 2} \tag{0.17}
\end{equation*}
$$

where the solution $u \in W^{\kappa, 2}(\Omega) \cap V_{p}$. One way how to see that Lemma A is applicable to $(0.17)$ is to introduce the stream function to $u$ and $\varphi$, which leads to an elliptic equation of higher order for the stream function to $u$. An alternative way is to proceed as in the proof of Lemma A (cf. [10] or [11]) using as the
starting point $L^{2+\rho}$-estimates $(\rho>0)$ for solutions of the Stokes system instead of $L^{2+\rho}$-estimates for the Laplace equation, see for example [1] for the proof of these estimates.

The scheme of the paper is following: Section 1 is devoted to the question of $W^{2, p_{0}}$-regularity, $p_{0}>2$, of solution to $(0.1)-(0.4)$ for $p=2$, where we can apply Lemma A directly as the coefficients are bounded (cf. (0.3)-(0.4)) from above and below. Section 2 deals with the most interesting case $p \in(1,2)$. We construct $\lambda$-approximations to ( 0.1 ) which are again 'quadratic', so that the corresponding solutions $u^{\lambda}$ 's are smooth by the results in Section 1. The main task of Section 2 is to obtain this smoothness uniformly for all $\lambda>0$. Letting $\lambda \rightarrow 0$ we finally obtain the $W^{2, p_{0}}$-regularity of the solution to the original problem (0.1). Moreover, we show the full regularity result. Section 3 is devoted to the results for $p>2$. Here we only present theorems and omit the proofs, that are similar to those in Section 2. The detailed proofs for $p>2$ will be given in a forthcoming paper, where we will analyze the Dirichlet boundary problem. By our preliminary calculations it seems that we will be able to gain the continuity for $\nabla v$ 'only' for $p \geq \frac{6}{5}$, in contrary to the periodic problem, where the Hölder continuity of $\nabla v$ holds for all $p>1$, as presented below.

We finish this introductory part by a few words on the physical background of (0.1). The system (0.1) occurs in non-linear fluid mechanics. It describes the steady motion of a class of homogeneous incompressible fluids (having constant density normalized to one). Then $v$ represents the velocity field and $\pi$ is the pressure. This class of fluids is characterized by the nonlinear dependence of the extra stress tensor on the velocity gradient. The principle of the material frame indifference and the representation of the isotropic tensors of second order in two dimensions lead then to the form

$$
\begin{equation*}
T(D(v))=2 \mu\left(|D(v)|^{2}\right) D(v) \tag{0.18}
\end{equation*}
$$

Note that $F$ defined by $F\left(|D(v)|^{2}\right)=\int_{0}^{|D(v)|^{2}} \mu(s) \mathrm{d} s$ satisfies (0.2). Setting in addition

$$
\begin{equation*}
\mu(s)=2 \mu_{0}(1+s)^{\frac{p-2}{2}}, \quad \mu_{0}>0 \tag{0.19}
\end{equation*}
$$

we obtain the classical example of $T$ undergoing (0.2)-(0.4). If $p \neq 2$ then the apparent viscosity $\mu$ is a function of $|D(v)|^{2}$ and the model (0.5)-(0.6) can capture such non-Newtonian phenomena as shear thinning (if $p \in(1,2)$ ) or shear thickening $(p>2)$, and these models are used in modelling of processes in many branches of science (see [6] for further references).

1. The case $p=2$

In this section we consider the system (0.1) with assumptions (0.2)-(0.4) for $p=2$. We have

Theorem 1.1. Let $f \in V_{2}^{*}$ (dual to $V_{2}$ ) and $p=2$. Then there exists a weak solution $v \in V_{2}$ and $\pi \in L^{2}(\Omega), \int_{\Omega} \pi \mathrm{d} x=0$, such that

$$
\begin{equation*}
\|\nabla u\|_{2}+\|\pi\|_{2} \leq C\|f\|_{V_{2}^{*}} \tag{1.2}
\end{equation*}
$$

If in addition $f \in L^{p_{0}}(\Omega), p_{0}>2$, then

$$
\begin{equation*}
\|v\|_{2, p_{0}} \leq C\left(\|f\|_{V_{2}^{*}}+\|f\|_{p_{0}}\right) \tag{1.3}
\end{equation*}
$$

Proof: By the classical Leray-Lions theory ( $p \geq \frac{3}{2}$ ) we obtain the existence of a $v \in V_{2}$ satisfying (0.5) and

$$
\|D(v)\|_{2} \leq C\|f\|_{V_{2}^{*}}
$$

It is easy to verify that

$$
\begin{equation*}
\|\nabla v\|_{2}=\sqrt{2}\|D(v)\|_{2} \quad \text { for } v \in V_{2} \tag{1.4}
\end{equation*}
$$

which implies

$$
\begin{equation*}
\|\nabla v\|_{2} \leq C\|f\|_{V_{2}^{*}} \tag{1.5}
\end{equation*}
$$

Defining

$$
\langle E, \varphi\rangle \equiv \int_{\Omega} T_{i j}(D(v)) D_{i j}(\varphi) \mathrm{d} x+\int_{\Omega} v_{k} \frac{\partial v_{i}}{\partial x_{k}} \varphi_{i} \mathrm{~d} x-\int_{\Omega} f_{i} \varphi_{i} \mathrm{~d} x
$$

for all $\varphi \in W_{\text {loc }}^{1,2}\left(\mathbb{R}^{2}\right)$ periodic we see from (0.5) and (1.5)

$$
\begin{equation*}
\langle E, \varphi\rangle=0, \quad \forall \varphi \in V_{2} \quad \text { and }\|E\|_{\left(W^{1,2}(\Omega)\right)^{*}} \leq C<\infty \tag{1.6}
\end{equation*}
$$

By de Rham's theorem and Nečas theorem on negative norms (see [8]), we obtain the existence of $\pi \in L^{2}(\Omega)$ such that

$$
\begin{gather*}
\int_{\Omega} \pi \mathrm{d} x=0, \quad\|\pi\|_{2} \leq C\|f\|_{V_{2}^{*}}^{2}  \tag{1.7}\\
\langle E, \varphi\rangle=\int_{\Omega} \pi \operatorname{div} \varphi \mathrm{d} x \quad \forall \varphi \in W_{\mathrm{loc}}^{1,2}\left(\mathbb{R}^{2}\right) \text { periodic. }
\end{gather*}
$$

Due to the periodicity and 'Hilbert's' structure we can now easily apply the standard difference technique to obtain $W^{2,2}$-regularity for $v$. Indeed, denoting

$$
d_{h}^{r} v(x) \equiv \frac{v\left(x+h e^{r}\right)-v(x)}{h}, \quad r=1,2,
$$

( $e^{r}$ denotes unit vector at $r$-axes direction), we get from (0.5) a similar system for $d_{h}^{r} v, r=1,2$,

$$
\begin{gather*}
\operatorname{div}\left(d_{h}^{r} v\right)=0 \\
\int_{\Omega}\left(d_{h}^{r} v_{k}(x) \frac{\partial v_{i}}{\partial x_{k}}\left(x+h e^{r}\right)+v_{k}(x) \frac{\partial d_{h}^{r} v_{i}(x)}{\partial x_{k}}\right) \varphi_{i}(x) \mathrm{d} x  \tag{1.8}\\
+\int_{\Omega} A_{i j}^{k l}(x) D_{k l}\left(d_{h}^{r} v\right) D_{i j}(\varphi) \mathrm{d} x=\int_{\Omega} d_{h}^{r} f_{i} \varphi_{i} \mathrm{~d} x
\end{gather*}
$$

for all $\varphi \in V_{2}$. In (1.8)

$$
A_{i j}^{k l}(x) \equiv \int_{0}^{1} \frac{\partial^{2} F\left(D v(x)+s\left(D v\left(x+h e^{r}\right)-D v(x)\right)\right)}{\partial p_{i j} \partial p_{k l}} \mathrm{~d} s
$$

Testing in (1.8) by $d_{h}^{r} v \in V_{2}$ and using (0.3) together with (1.4), we obtain

$$
\begin{equation*}
C_{1}\left\|\nabla d_{h}^{r} v\right\|_{2}^{2} \leq C\left(\|f\|_{2}^{2}+\left\|d_{h}^{r} v\right\|_{4}^{2}\right) \tag{1.9}
\end{equation*}
$$

where we used the fact that $\int_{\Omega} v_{k} \frac{\partial}{\partial x_{k}}\left(d_{h}^{r} v_{i}\right) d_{h}^{r} v_{i} \mathrm{~d} x=0$ and the term

$$
\int_{\Omega} d_{h}^{r} v_{k} \frac{\partial v_{i}}{\partial x_{k}} d_{h}^{r} v_{i} \mathrm{~d} x
$$

was estimated by Hölder's inequality and (1.5). Since in two dimensions

$$
\begin{equation*}
\|u\|_{4} \leq\|u\|_{2}^{1 / 2}\|\nabla u\|_{2}^{1 / 2} \tag{1.10}
\end{equation*}
$$

we see immediately from (1.9)

$$
\begin{equation*}
\left\|\nabla d_{h}^{r} v\right\|_{2}^{2} \leq C\left(\|f\|_{2}^{2}+1\right) \tag{1.11}
\end{equation*}
$$

This implies

$$
\begin{gather*}
\|\nabla \pi\|_{2} \leq C \\
\left\|\nabla^{2} v\right\|_{2} \leq C\left(\|f\|_{2}+1\right) \tag{1.12}
\end{gather*}
$$

and the equations $(0.1)_{2}$ hold a.e. (for $p=2!!$ ). Moreover, for $r=1,2$, the functions $w^{r} \equiv \frac{\partial v}{\partial x^{r}} \in V_{2}$ and $\sigma^{r} \equiv \frac{\partial \pi}{\partial x_{r}} \in L^{2}(\Omega)$ solve in the weak sense the system

$$
\begin{gather*}
\operatorname{div} w^{r}=0 \\
\frac{\partial}{\partial x_{r}}\left(v_{k} \frac{\partial v_{i}}{\partial x_{k}}\right)-\frac{\partial}{\partial x_{j}}\left(\frac{\partial^{2} F\left(|D v|^{2}\right)}{\partial p_{i j} \partial p_{k l}} D_{k l}\left(w^{r}\right)\right)+\frac{\partial \sigma^{r}}{\partial x_{i}}=\frac{\partial f_{i}}{\partial x_{r}}, \quad i=1,2 \tag{1.13}
\end{gather*}
$$

As the coefficients $A_{i j}^{k l} \equiv \frac{\partial^{2} F\left(|D(v)|^{2}\right)}{\partial p_{i j} \partial p_{k l}}$ satisfy assumption (0.13), $f \in L_{p_{0}}(\Omega)$ and

$$
\left\|v_{k} \frac{\partial v}{\partial x_{k}}\right\|_{p_{0}} \leq C\|\nabla v\|_{p_{0}}\|v\|_{\infty} \leq C\|v\|_{2,2}^{2} \leq C\left(\|f\|_{2}^{2}+1\right)
$$

we can apply Lemma A that guaranties

$$
\begin{equation*}
v \in W_{\operatorname{loc}}^{2, p_{0}}\left(\mathbb{R}^{2}\right), \quad \nabla v \in C^{0, \alpha}(\bar{\Omega}), \quad \alpha=1-\frac{2}{p_{0}} \tag{1.14}
\end{equation*}
$$

The proof of Theorem 1.1 is complete.
Remark 1.15. Let us remark that for the case $p=2$ we proved that every weak solution has Hölder-continuous first derivatives. Higher regularity is then reduced to a more or less standard application of the technique of the regularity theory for linear elliptic systems. The only term that requires circumspection is the term of the type

$$
J \equiv \int_{\Omega} \frac{\partial^{3} F\left(|D(v)|^{2}\right)}{\partial p_{i j} \partial p_{k l} \partial p_{r s}} D_{r s}(\nabla v) D_{k l}(\nabla v) D_{i j}\left(\nabla^{(2)} v\right) d x
$$

which appears while deriving $W^{3,2}$-regularity. In such a case, we have $L^{2}$-norm of the third derivatives of $v$ on the left hand side and we know (see (1.14)) that $v \in W_{\text {loc }}^{2, p_{0}}\left(\mathbb{R}^{2}\right)$ for $p_{0}>2$. Write $p_{0}=2+\rho$. Then the interpolation inequality analogous to (1.10)

$$
\|u\|_{4} \leq\|u\|_{2+\rho}^{\frac{2+\rho}{4}}\|\nabla u\|_{2}^{\frac{2-\rho}{4}}
$$

leads to the following estimate of $J$ (using also (1.14), the Hölder and Young inequalities):

$$
\begin{aligned}
|J| \leq C \int_{\Omega}\left|\nabla^{(2)} v\right|^{2}\left|\nabla^{(3)} v\right| & \leq C\left\|\nabla^{(2)} v\right\|_{4}^{2}\left\|\nabla^{(3)} v\right\|_{2} \\
& \leq\left\|\nabla^{(2)} v\right\|_{p_{0}^{2}}^{\frac{2+\rho}{2}}\left\|\nabla^{(3)} v\right\|_{2}^{2-\frac{\rho}{2}} \leq \frac{\varepsilon}{2}\left\|\nabla^{(3)} v\right\|_{2}^{2}+C .
\end{aligned}
$$

Choosing $\varepsilon<2 C_{1}$, we move $\frac{\varepsilon}{2}\left\|\nabla^{(3)} v\right\|_{2}^{2}$ to the left hand side, and we conclude $W^{3,2}$-regularity for $v$. The higher regularity is then straightforward.

## 2. The case $p \in(1,2), \lambda$-approximations

In order to prove the $W^{2, p_{0}}$-regularity $\left(p_{0}>2\right)$ for $(0.1)-(0.3)$ for $p \in(1,2)$, we study the following quadratic $\lambda$-approximations to $(0.1)$ : for $\lambda \in(0,1)$ we consider $(v, \pi)=\left(v^{\lambda}, \pi^{\lambda}\right)$ as a solution of the system (in $\left.\mathbb{R}^{2}\right)$

$$
\begin{equation*}
v_{k} \frac{\partial v}{\partial x_{k}}-\operatorname{div}\left(\left(1+\lambda|D(v)|^{2}\right)^{\frac{2-p}{2}} T(D(v))\right)=-\nabla \pi+f \tag{2.1}
\end{equation*}
$$

where all functions are again periodic, etc. Denoting

$$
\begin{aligned}
& \tau_{i j}^{\lambda} \stackrel{\text { def. }}{\equiv}\left(1+\lambda|D(v)|^{2}\right)^{\frac{2-p}{2}} \\
& T_{i j}(D(v)) \\
&=2\left(1+\lambda|D(v)|^{2}\right)^{\frac{2-p}{2}} F^{\prime}\left(|D(v)|^{2}\right) D_{i j}(v)
\end{aligned}
$$

we first verify that $\tau^{\lambda}$ satisfy (0.2)-(0.4) with the quadratic potential

$$
\begin{equation*}
F^{\lambda}\left(|D(v)|^{2}\right) \equiv \int_{0}^{|D(v)|^{2}}(1+\lambda s)^{\frac{2-p}{2}} F^{\prime}(s) \mathrm{d} s \tag{2.2}
\end{equation*}
$$

Indeed, recalling that $\frac{\partial F\left(|\eta|^{2}\right)}{\partial \eta_{i j}}=2 F^{\prime}\left(|\eta|^{2}\right) \eta_{i j}$ we have
$\frac{\partial^{2} F^{\lambda}\left(|\eta|^{2}\right)}{\partial \eta_{i j} \partial \eta_{k l}}=\left(1+\lambda|\eta|^{2}\right)^{\frac{2-p}{2}} \frac{\partial^{2} F\left(|\eta|^{2}\right)}{\partial \eta_{i j} \partial \eta_{k l}}+\lambda(2-p)\left(1+\lambda|\eta|^{2}\right)^{-\frac{p}{2}} \frac{\partial F\left(|\eta|^{2}\right)}{\partial \eta_{i j}} \eta_{k l}$
and
(2.3) $\frac{\partial^{2} F^{\lambda}\left(|\eta|^{2}\right)}{\partial \eta_{i j} \partial \eta_{k l}} \xi_{i j} \xi_{k l}=\left(1+\lambda|\eta|^{2}\right)^{\frac{2-p}{2}} \frac{\partial^{2} F\left(|\eta|^{2}\right)}{\partial \eta_{i j} \partial \eta_{k l}} \xi_{i j} \xi_{k l}$

$$
+2(2-p) \lambda\left(1+\lambda|\eta|^{2}\right)^{-\frac{p}{2}} F^{\prime}\left(|\eta|^{2}\right) \eta_{k l} \xi_{k l} \eta_{i j} \xi_{i j}
$$

Note that the last term is nonnegative for $p \in(1,2)$. Consequently by (0.3), (0.4) and (0.7)

$$
\begin{align*}
\frac{\partial^{2} F^{\lambda}\left(|\eta|^{2}\right)}{\partial \eta_{i j} \partial \eta_{k l}} \xi_{i j} \xi_{k l} & \geq C_{1} \lambda^{\frac{2-p}{2}}|\xi|^{2} \stackrel{\text { def. }}{\equiv} \tilde{C}_{1}(\lambda)|\xi|^{2} \\
\left|\frac{\partial^{2} F^{\lambda}\left(|\eta|^{2}\right)}{\partial \eta_{i j} \partial \eta_{k l}}\right| & \leq C_{2}+C_{5} . \tag{2.4}
\end{align*}
$$

Thus we can apply Theorem 1.1 and we obtain for each $\lambda>0$ the existence of $p^{\lambda}>2$ and $v^{\lambda}$ such that

$$
v^{\lambda} \in W_{\mathrm{loc}}^{2, p^{\lambda}}\left(\mathbb{R}^{2}\right) \cap C^{1}(\bar{\Omega})
$$

In the rest of this section we will show that (for certain $p_{0}>2$ ) we have

$$
\begin{equation*}
\left\|v^{\lambda}\right\|_{2, p_{0}} \leq K \text { uniformly with respect to } \lambda>0 \tag{2.5}
\end{equation*}
$$

Assume for a while that (2.5) holds. Then letting $\lambda \rightarrow 0$ we can find a sequence $\lambda_{n} \rightarrow 0$ such that $v^{n} \equiv v^{\lambda_{n}}$ satisfy

$$
\begin{array}{cc}
v^{n} \rightharpoonup v & \text { weakly in } W^{2, p_{0}}(\Omega) \\
v^{n} \rightarrow v & \text { strongly in } W^{1,2}(\Omega)
\end{array}
$$

Then it is trivial to see that $v$ satisfies (0.5) and $v \in W^{2, p_{0}}(\Omega)$ (cf. (2.5)). Then $\nabla v \in C^{0, \alpha}(\bar{\Omega})$, and we have
Theorem 2.6. Let $p \in(1,2)$ and $f \in L^{p^{\prime}}(\Omega)$. Then there exists a solution $v, \pi$ to (0.1)-(0.4) such that

$$
\begin{gathered}
v \in W_{\mathrm{loc}}^{2, p^{\prime}}\left(\mathbb{R}^{2}\right) \cap C^{1, \alpha}(\bar{\Omega}), \\
\pi \in W_{\operatorname{loc}}^{1, p^{\prime}}\left(\mathbb{R}^{2}\right), \quad \int_{\Omega} \pi \mathrm{d} x=0
\end{gathered}
$$

The direct consequence of Theorem 2.6 (see also Remark 1.15) is the following Theorem 2.7. Let $p \in(1,2), k \in \mathbb{N}, k \geq 1$. Assume $F \in C^{k+2}\left(\mathbb{R}_{0}^{+}\right)$and $f \in W^{k, 2}(\Omega)$. Then

$$
v \in W_{\mathrm{loc}}^{k+2,2}\left(\mathbb{R}^{2}\right)
$$

In particular, if $F \in C^{\infty}\left(\mathbb{R}_{0}^{+}\right)$and $f \in C^{\infty}(\bar{\Omega})$, then $v \in C^{\infty}(\bar{\Omega})$.
Proof of Theorem 2.6: As described above, it remains to show (2.5) for $v^{\lambda}$ being the solution of (2.1). Let us first note that by testing $(2.1)_{2}$ by $v=v^{\lambda}$ we obtain, with help of (0.6), the uniform estimate

$$
\begin{equation*}
\left\|D\left(v^{\lambda}\right)\right\|_{p} \leq C<\infty \tag{2.8}
\end{equation*}
$$

This helps us to show another uniform estimate, namely

$$
\begin{equation*}
\int_{\Omega}\left(1+\left|D\left(v^{\lambda}\right)\right|^{2}\right)^{\frac{p-2}{2}}\left|D\left(\nabla v^{\lambda}\right)\right|^{2} \mathrm{~d} x \leq C<\infty \tag{2.9}
\end{equation*}
$$

Indeed, multiplying $(2.1)_{2}$ scalarly by $-\Delta v^{\lambda}$ (recall that for $\lambda$ fixed we have enough regularity and $-\Delta v^{\lambda}$ is divergence-free and periodic), integrating over $\Omega$, performing integration by parts and using the notation (2.2), we obtain

$$
\begin{align*}
\int_{\Omega} \frac{\partial^{2} F^{\lambda}\left(\left|D\left(v^{\lambda}\right)\right|^{2}\right)}{\partial p_{i j} \partial p_{k l}} D_{i j}\left(\frac{\partial v^{\lambda}}{\partial x_{s}}\right) & D_{k l}\left(\frac{\partial v^{\lambda}}{\partial x_{s}}\right) \mathrm{d} x  \tag{2.10}\\
& =\int_{\Omega} f \Delta v^{\lambda} \mathrm{d} x-\int_{\Omega} \frac{\partial v_{k}^{\lambda}}{\partial x_{s}} \frac{\partial v_{i}^{\lambda}}{\partial x_{k}} \frac{\partial v_{i}^{\lambda}}{\partial x_{s}} \mathrm{~d} x
\end{align*}
$$

Using the fact $\frac{\partial v_{1}^{\lambda}}{\partial x_{1}}=-\frac{\partial v_{2}^{\lambda}}{\partial x_{2}}$ one can check that the last term vanishes. Using (0.3) and $\left(1+\lambda|\eta|^{2}\right)^{\frac{2-p}{2}} \geq 1$ in (2.4) leads to

$$
\begin{equation*}
\frac{\partial^{2} F^{\lambda}\left(|\eta|^{2}\right)}{\partial \eta_{i j} \partial \eta_{k l}} \xi_{i j} \xi_{k l} \geq C_{1}\left(1+|\eta|^{2}\right)^{\frac{p-2}{2}}|\xi|^{2} \tag{2.11}
\end{equation*}
$$

Then from (2.10)

$$
\begin{equation*}
C_{1} \int_{\Omega}\left(1+\left|D\left(v^{\lambda}\right)\right|^{2}\right)^{\frac{p-2}{2}}\left|D\left(\nabla v^{\lambda}\right)\right|^{2} \mathrm{~d} x \leq\left\|\nabla^{2} v^{\lambda}\right\|_{p}\|f\|_{p^{\prime}} \tag{2.12}
\end{equation*}
$$

Now we will show that $\left\|\nabla^{2} v^{\lambda}\right\|_{p}$ is controlled by the integral on the left-hand side of (2.12). With help of Hölder's inequality we have

$$
\begin{align*}
& \left\|D\left(\nabla v^{\lambda}\right)\right\|_{p}^{2}  \tag{2.13}\\
& \quad \leq\left(1+\left\|D\left(v^{\lambda}\right)\right\|_{p}\right)^{2-p} \int_{\Omega}\left(1+\left|D\left(v^{\lambda}\right)\right|^{2}\right)^{\frac{p-2}{2}}\left|D\left(\nabla v^{\lambda}\right)\right|^{2} \mathrm{~d} x
\end{align*}
$$

The algebraic identity

$$
\begin{equation*}
\frac{\partial^{2} v_{i}}{\partial x_{j} \partial x_{k}}=\frac{\partial D_{i k}(v)}{\partial x_{j}}+\frac{\partial D_{i j}(v)}{\partial x_{k}}-\frac{\partial D_{j k}(v)}{\partial x_{i}} \tag{2.14}
\end{equation*}
$$

together with (2.13) and (2.8) give

$$
\begin{equation*}
\left\|\nabla^{2} v^{\lambda}\right\|_{p}^{2} \leq C \int_{\Omega}\left(1+\left|D\left(v^{\lambda}\right)\right|^{2}\right)^{\frac{p-2}{2}}\left|D\left(\nabla v^{\lambda}\right)\right|^{2} \mathrm{~d} x \tag{2.15}
\end{equation*}
$$

Hence, from (2.12) and (2.15) we have (2.9) and

$$
\begin{equation*}
\left\|\nabla^{2} v^{\lambda}\right\|_{p}^{2} \leq C<\infty \tag{2.16}
\end{equation*}
$$

Now we are ready to prove (2.5). Similarly to the analysis in Section 1, we have for $w_{r}=\frac{\partial v^{\lambda}}{\partial x_{r}}, r=1,2$, the equation

$$
\begin{equation*}
\int_{\Omega} \frac{\partial^{2} F^{\lambda}\left(\left|D\left(v^{\lambda}\right)\right|^{2}\right)}{\partial p_{i j} \partial p_{k l}} D_{k l}\left(w_{r}\right) D_{i j}(\phi) \mathrm{d} x=\int_{\Omega} G_{\alpha}^{\lambda} \frac{\partial \phi_{\alpha}}{\partial x_{r}} \mathrm{~d} x \tag{2.17}
\end{equation*}
$$

valid for all $\phi$ smooth, $\operatorname{div} \phi=0$. Here

$$
G^{\lambda} \equiv v_{k}^{\lambda} \frac{\partial v^{\lambda}}{\partial x_{k}}-f
$$

It follows from (2.16) and the assumption on $f$ the existence of $q>2$ such that

$$
\left\|G^{\lambda}\right\|_{q} \leq C<\infty
$$

For fixed $\lambda>0$ all assumption of Lemma A are verified. Denote $V=V(\lambda) \equiv$ $\sup _{x \in \bar{\Omega}}\left(1+\left|D\left(v^{\lambda}(x)\right)\right|^{2}\right)^{\frac{1}{2}}$. Then $(2.4)_{2}$ and (2.11) imply

$$
\begin{equation*}
C_{1} V^{p-2}|\xi|^{2} \leq \frac{\partial^{2} F^{\lambda}\left(\left|D\left(v^{\lambda}\right)\right|^{2}\right)}{\partial \eta_{i j} \partial \eta_{k l}} \xi_{i j} \xi_{k l} \leq\left(C_{2}+C_{5}\right)|\xi|^{2} \tag{2.18}
\end{equation*}
$$

valid for all $\lambda>0$. By Lemma $A$

$$
\begin{equation*}
\left\|w_{r}\right\|_{1, q} \leq K V^{2-p}, \quad r=1,2 \tag{2.19}
\end{equation*}
$$

with

$$
\begin{equation*}
q \leq 2\left(1-\lg \left[\frac{1-\frac{1}{2} \frac{C_{1}}{C_{2}} V^{p-2}}{1-\frac{C_{1}}{C_{2}} V^{p-2}}\right] / \lg \gamma_{3}\right)^{-1}, \quad \gamma_{3}>1 \tag{2.20}
\end{equation*}
$$

which gives

$$
q=2\left(1-\delta \lg \left[\frac{1-\frac{1}{2} \frac{C_{1}}{C_{2}} V^{p-2}}{1-\frac{C_{1}}{C_{2}} V^{p-2}}\right] / \lg \gamma_{3}\right)^{-1} \quad \text { for a certain } \delta \in(0,1]
$$

This implies

$$
\begin{aligned}
1-\frac{2}{q}=\frac{\delta}{\lg \gamma_{3}} \lg \left(\frac{1-\frac{1}{2} \frac{C_{1}}{C_{2}} V^{p-2}}{1-\frac{C_{1}}{C_{2}} V^{p-2}}\right)= & \frac{\delta}{\lg \gamma_{3}} \lg \left(1+\frac{\frac{1}{2} \frac{C_{1}}{C_{2}} V^{p-2}}{1-\frac{C_{1}}{C_{2}} V^{p-2}}\right) \geq \\
& \begin{cases}\delta \frac{\lg 2}{\lg \gamma_{3}} & \text { if } \frac{3}{2} \frac{C_{1}}{C_{2}} V^{p-2} \geq 1 \\
\delta \frac{1}{4 \lg \gamma_{3}} \frac{C_{1}}{C_{2}} V^{p-2} & \text { if } \frac{3}{2} \frac{C_{1}}{C_{2}} V^{p-2}<1\end{cases}
\end{aligned}
$$

as $\lg (1+x) \geq \frac{x}{2}$ on $[0,1]$. Thus setting $L \equiv \min \left(\frac{\lg 2}{\lg \gamma_{3}}, \frac{C_{1}}{4 C_{2} \lg \gamma_{3}}\right)$ yields $\left(1 \geq V^{p-2}\right)$

$$
\begin{equation*}
1-\frac{2}{q} \geq L V^{p-2} \delta \equiv M \delta \tag{2.21}
\end{equation*}
$$

Then $q>\frac{2}{1-M \delta}>2$. (Of course, we restrict only on such $q$ 's that $W^{2, p}(\Omega) \hookrightarrow$ $W^{1, q}(\Omega)$.) Let us finally denote $\theta \equiv\left(1+\left|D\left(v^{\lambda}\right)\right|^{2}\right)^{\frac{1}{2}}$. By (2.8) and (2.9)

$$
\begin{equation*}
\left\|\theta^{\frac{p}{2}}\right\|_{1,2}<K \tag{2.22}
\end{equation*}
$$

and by (2.19)

$$
\begin{equation*}
\left\|\theta^{\frac{p}{2}}\right\|_{1, q}<K V^{2-p} \tag{2.23}
\end{equation*}
$$

For $p_{0} \in(2, q)$, the interpolation inequality implies

$$
\left\|\theta^{\frac{p}{2}}\right\|_{1, p_{0}} \leq\left\|\theta^{\frac{p}{2}}\right\|_{1,2}^{1-a}\left\|\theta^{\frac{p}{2}}\right\|_{1, q}^{a} \leq K V^{a(2-p)}
$$

where $a$ is given by $\frac{1}{p_{0}}=\frac{1-a}{2}+\frac{a}{q}$. Then it holds due to (2.21)

$$
1-\frac{2}{p_{0}}=1-2\left(\frac{a}{q}+\frac{1-a}{2}\right)=a\left(1-\frac{2}{q}\right) \geq M \delta a=L V^{p-2} \delta a
$$

and from the Morrey imbedding inequality (cf. [13, p. 58])

$$
\begin{aligned}
V^{\frac{p}{2}}=\left\|\theta^{\frac{p}{2}}\right\|_{C(\bar{\Omega})} \leq K & \left(\frac{p_{0}-1}{p_{0}-2}\right)^{1-\frac{1}{p_{0}}} V^{a(2-p)} \\
& \leq K\left(\frac{1}{1-\frac{2}{p_{0}}}\right)^{1-\frac{1}{q}} V^{a(2-p)} \leq \tilde{K} V^{(2-p)\left(a+1-\frac{1}{q}\right)} \delta^{1-\frac{1}{q}}
\end{aligned}
$$

We need $(2-p)\left(a+1-\frac{1}{q}\right)<\frac{p}{2}$, which can be rewritten as

$$
p>\frac{2\left(a+1-\frac{1}{q}\right)}{a+\frac{3}{2}-\frac{1}{q}} \stackrel{a \rightarrow 0}{\rightarrow}+\frac{2(q-1)}{\frac{3}{2} q-1} \stackrel{q \rightarrow 2}{\rightarrow} 1 .
$$

Therefore, for given $p \in(1,2)$ we find $q_{0}$ so that $\frac{2\left(q_{0}-1\right)}{\frac{3}{2} q_{0}-1} \leq \frac{1+p}{2}$. Taking $q<q_{0}$ in such a way that (2.20) holds, then we can fix $a$ so that

$$
p>\frac{2\left(a+1-\frac{1}{q}\right)}{a+\frac{3}{2}-\frac{1}{q}} .
$$

Under these circumstances, $\left\|\theta^{\frac{p}{2}}\right\|_{C(\bar{\Omega})}=\left\|\left(1+\left|D\left(v^{\lambda}\right)\right|^{2}\right)^{\frac{p}{4}}\right\|_{C(\bar{\Omega})} \leq K$ which implies (2.3) from (2.23). The proof of Theorem 2.5 is complete.

## 3. The case $p>2$

Using the analogous regularization we can repeat the procedures of Section 2 for $p \in(2,3)$ under some restriction on the constants $C_{1}, C_{2}, C_{5}$, compare also with [9]. By a slightly different regularization based on changing the values of $F$ outside the ball with a radius $R$ of a suitable functional $F_{R}$ with quadratic growth (see [5]) and using the bootstrap arguments for higher $p$ we obtain the following
Theorem 3.1. Let $r, p \in(2, \infty)$ and $f \in L^{r}(\Omega)$. Then there exists a solution $v, \pi$ to (0.1)-(0.4) such that

$$
\begin{gathered}
v \in W_{\mathrm{loc}}^{2, r}\left(\mathbb{R}^{2}\right) \cap C^{1, \alpha}(\bar{\Omega}), \\
\pi \in W_{\mathrm{loc}}^{1, r}\left(\mathbb{R}^{2}\right), \quad \int_{\Omega} \pi \mathrm{d} x=0
\end{gathered}
$$

The direct consequence of Theorem 2.6 is the following
Theorem 2.7. Let $p \in(2, \infty), k \in \mathbb{N}, k \geq 1$. Assume $F \in C^{k+2}\left(\mathbb{R}_{0}^{+}\right)$and $f \in W^{k, 2}(\Omega)$. Then

$$
v \in W_{\mathrm{loc}}^{k+2,2}\left(\mathbb{R}^{2}\right)
$$

In particular, if $F \in C^{\infty}\left(\mathbb{R}_{0}^{+}\right)$and $f \in C^{\infty}(\bar{\Omega})$, then $v \in C^{\infty}(\bar{\Omega})$.

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[^1]:    ${ }^{1}$ We use the standard notation for Lebesgue spaces $L^{p}(\Omega)$ and Sobolev spaces $W^{k, p}(\Omega)$, and their norms $\|\cdot\|_{p}$ and $\|\cdot\|_{k, p}$ respectively.

[^2]:    ${ }^{2}$ By the standard cancellation we mean the fact that $\int_{\Omega} w_{k} \frac{\partial v_{i}}{\partial x_{k}} v_{i} \mathrm{~d} x=0$ for any $w$ which is divergence-free.

