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A NOTE ON APPLICATIONS OF THE ALGEBRAIC DERIVATIVE TO SOLVING OF SOME DIFFERENTIAL EQUATIONS

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Abstract

In this note by means of Mikusinski operational calculus the differential equations with linear coefficients are investigated.

Key words: operational calculus, power series, solutions of linear differential equations

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1 Introduction

K. Yosida in [4] solved the Laplace differential equation

$$a_2 t x''(t) + (a_1 t + b_1) x'(t) + (a_0 t + b_0) x(t) = 0 \quad (1)$$

where $a_i, b_i \in \mathbb{C}$, $i = 0, 1, 2$ and $t \in [0, \infty)$ by means of Mikusinski operational calculus assuming that the algebraic equations

$$a_2 z^2 + a_1 z + a_0 = 0$$

has two distinct roots z_1 and z_2 .

The purpose of this note is to show that Yosida method presented in [4] may be used to determining particular solutions of the differential equations with linear coefficients.

$$a_n t x^{(n)}(t) + (a_{n-1} t + b_{n-1}) x^{(n-1)}(t) + \dots + (a_0 t + b_0) x(t) = 0 \quad (2)$$

$a_i, b_i \in \mathbb{C}$, $i = 0, 1, 2, \dots, n$, $t \in [0, \infty)$ and without the restriction that the polynomial

$$a_n z^n + a_{n-1} z^{n-1} + \dots + a_0$$

has distinct roots.

We shall use in this note notations introduced by J. Mikusinski ([2],[3]).

Let \mathcal{C} be the ring of continuous complex-valued functions in $[0, \infty)$ with ordinary addition and convolution as multiplication. The formal quotients p/q , p and q are in \mathcal{C} will be called Mikusinski operators. By \mathcal{M} , we shall denote the field of Mikusinski operators. The basic idea of our considerations is connected with the concept of an algebraic derivative D ([1],[2] p.294). The algebraic derivative D is defined as follows

$$\begin{aligned} Df &= D\{f(t)\} = \{-tf(t)\} \quad \text{for } f \in \mathcal{C}, \\ D(p/q) &= (Dpq - pDq)/q^2 \quad \text{for } p, q \in \mathcal{C}, \quad q \neq 0. \end{aligned}$$

For the positive integers n we have

$$Ds^n = ns^{n-1}, \tag{3}$$

s denotes the differential operator.

This equation suggests that the operation D may be considered as derivation with respect to the differential operator s .

2 Operational differential equations

K. Yosida in his paper has shown the more general formula

$$D(s - \alpha)^\gamma = \gamma(s - \alpha)^{\gamma-1}, \quad \alpha, \gamma \in \mathbb{C}. \tag{4}$$

Moreover, we shall need a formula of differentiation of the exponential operational functions

$$\exp[\gamma(s - \alpha)^{-k}], \quad \alpha, \gamma \in \mathbb{C}, \quad k \in \mathbb{N}. \tag{[2], p.202}.$$

Obviously, the operator $(s - \alpha)^{-k}$, $k \in \mathbb{N}$ is in \mathcal{C} . The above exponential operational function can be defined by means of the power series

$$\exp[\gamma(s - \alpha)^{-k}] = 1 + \frac{\gamma(s - \alpha)^{-k}}{1!} + \frac{\gamma(s - \alpha)^{-2k}}{2!} + \dots \tag{[2], p.206}$$

Now, differentiating this power series term by term with respect to s we obtain

$$D \exp[\gamma(s - \alpha)^{-k}] = \exp[\gamma(s - \alpha)^{-k}] \gamma(-k)(s - \alpha)^{-k-1}. \tag{5}$$

The formulas (4) and (5) allow to solve the operational differential equation

$$\frac{Dx}{x} = \frac{Q(s)}{P(s)}, \tag{6}$$

where P and Q are polynomials with complex coefficients and $\deg. Q < \deg. P$.

The equation (6) can be written as follows

$$\frac{Dx}{x} = \sum_{i=1}^r \sum_{j=1}^{k_i} \frac{\gamma_{ij}}{(s - \alpha_i)^j}, \quad \alpha_i, \gamma_{ij} \in \mathbb{C} \quad (7)$$

The complex numbers α_i are the roots of the polynomial

$$a_n z^n + a_{n-1} z^{n-1} + \dots + a_0, \quad k_i \in \mathbb{N}, \quad k_1 + \dots + k_r = \deg. P.$$

Let $v_1, \dots, v_n, v_i \neq 0$ for $i = 1, \dots, n$ be arbitrary elements of \mathcal{M} . It can easily be observed that

$$\frac{D(v_1 v_2 \dots v_n)}{v_1 v_2 \dots v_n} = \frac{Dv_1}{v_1} + \frac{Dv_2}{v_2} + \dots + \frac{Dv_n}{v_n}$$

This indicates that each equation

$$\frac{Dx}{x} = \frac{\gamma_{ij}}{(s - \alpha_i)^j} \quad (8)$$

may be solved separately.

Let v_{ij} be solution of the differential equation (8). Then the element

$$v = \prod_{i=1}^r \prod_{j=1}^{k_i} v_{ij}$$

is a solution of the differential equation (7).

From (4) it follows that the operator

$$c(s - \alpha_i)^{\gamma_{i1}}, \quad c \in \mathbb{C}$$

is a solution of the operational equation

$$\frac{Dx}{x} = \frac{\gamma_{i1}}{(s - \alpha_i)^1}$$

According to (5) the operator

$$c \exp\left[\frac{\gamma_{ij}}{-j+1}(s - \alpha_i)^{-j+1}\right], \quad c \in \mathbb{C}$$

is a solution of the operational equation

$$\frac{Dx}{x} = \frac{\gamma_{ij}}{(s - \alpha_i)^j} \quad j = 2, \dots, k_i.$$

Finally, we conclude that the element

$$v = c \prod_{i=1}^r (s - \alpha_i)^{\gamma_{i1}} \prod_{j=2}^{k_i} \exp\left[\frac{\gamma_{ij}}{-j+1} (s - \alpha_i)^{-j+1}\right] \quad (9)$$

satisfies the equation (7).

Naturally, if

1° there exists an operator v such that $Dv = w$ and

2° there exists the exponential function $e^{v(\cdot)}$ ([2] p.203),

then according to ([1]) e^v is a solution of the operator equation

$$\frac{Dx}{x} = w.$$

It is known, if $w = P(s)/Q(s)$, where P and Q are polynomials, then there exists an operator v such that $Dv = w$. If $\deg. P > \deg. Q$, then the exponential function $e^{v(\cdot)}$ does not exist ([3] p.217). If $\deg. P < \deg. Q$ and $\gamma_{11} = \gamma_{21} = \dots = \gamma_{r1} = 0$ in the equation (7), then the exponential function $e^{v(\cdot)}$ exists. Generally, the existence of an exponential function is an open problem. For example, there exists the exponential function $e^{-s(\cdot)}$ for real arguments but the exponential function $e^{i s(\cdot)}$, $i = \sqrt{-1}$ does not exist. In the both cases the series

$$1 + \frac{-s}{1!} + \frac{(-s)^2}{2!} + \dots$$

$$1 + \frac{is}{1!} + \frac{(is)^2}{2!} + \dots$$

are divergent ([3] p.160,168).

The operator

$$v = \{-te^{\alpha t} \ln t\} / \{te^{\alpha t}\}$$

is a solution of the operator equation $Dx = (s - \alpha)^{-1}$. Now, the existence of the exponential function $e^{v(\cdot)}$ is an open problem. Finally, the formula (9) can be expanded in a power series.

3 Applications

We know that if a function $x \in \mathcal{C}$ has a n -th derivative $\{x^n(t)\}$, which is continuous in the interval $[0, \infty)$, then

$$x^n = s^n x - s^{n-1} x(0) - \dots - s x^{n-2}(0) - x^{n-1}(0). \quad ([2] \text{ p.51})$$

Assuming that $x \neq 0$ and it is n -time continuously differentiable we can rewrite the equation (2) as follows

$$\begin{aligned} & -a_n D[s^n x - s^{n-1}x(0) - \dots - sx^{n-2}(0) - x^{n-1}(0)] + (a_{n-1}D + b_{n-1}) \\ & [s^{n-1}x - s^{n-2}x(0) - \dots - sx^{n-3}(0) - x^{n-2}(0)] + \dots + (-a_0D + b_0)x = 0 \end{aligned}$$

This equation can be written in the compact form

$$-P(s)Dx + Q(s)x = R(s), \quad (10)$$

where $P(s) = a_n s^n + a_{n-1} s^{n-1} + \dots + a_0$ and $\deg. Q$ and $\deg. R$ are less n . For some initials dates the right hand side of the equation (10) vanishes. We shall consider in this note only such situation. Finally, we conclude that if the element

$$x = c \prod_{i=1}^r (s - \alpha_i)^{\gamma_{i1}} \prod_{j=2}^{k_i} \exp\left[\frac{\gamma_{ij}}{-j+1}(s - \alpha_i)^{-j+1}\right] \quad (11)$$

is in \mathcal{C} , then it is a solution of the differential equation (2).

4 Example

Let us consider the differential equation

$$tx^{(2)}(t) + (-2\alpha t + 1)x^{(1)}(t) + (\alpha^2 t + \beta)x(t) = 0$$

Further we have

$$\frac{Dx}{x} = \frac{-1}{s - \alpha} + \frac{\alpha + \beta}{(s - \alpha)^2}.$$

From (9) it follows that

$$x = (s - \alpha)^{-1} \exp[-(\alpha + \beta)(s - \alpha)^{-1}].$$

The solution x can be represented by the power series

$$x = \frac{1}{s - \alpha} + \frac{-(\alpha + \beta)}{1!(s - \alpha)^2} + \frac{(\alpha + \beta)^2}{2!(s - \alpha)^3} t + \dots$$

Finally we obtain

$$x(t) = e^{\alpha t} \left(1 + \frac{-(\alpha + \beta)}{[1!]^2} t + \frac{(\alpha + \beta)^2}{[2!]^2} t^2 + \dots \right).$$

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