## Czechoslovak Mathematical Journal

## Ladislav Nebeský <br> A new proof of a characterization of the set of all geodesics in a connected graph

Czechoslovak Mathematical Journal, Vol. 48 (1998), No. 4, 809-813

Persistent URL: http: //dml.cz/dmlcz/127456

## Terms of use:

(C) Institute of Mathematics AS CR, 1998

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.


This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project DML-CZ: The Czech Digital Mathematics Library http://dml.cz

# A NEW PROOF OF A CHARACTERIZATION OF THE SET OF ALL GEODESICS IN A CONNECTED GRAPH 

Ladislav Nebeský, Praha

(Received September 13, 1996)

In [2], the present author gave a characterization of the set of all geodesics (or shortest paths) in a connected graph $G$. More precisely, he gave a necessary and sufficient condition for a set of paths in $G$ to be the set of all geodesics in $G$. The proof of necessity is easy and was omitted in [2]. But the proof of sufficiency given there was rather long.

This characterization was partially modified in [3]; the proof given there was also long (in fact, the characterization was derived form a more general theorem proved there). In the present paper we present its new and shorter proof. The proof utilizes a new lemma, which yields a deeper insight into the idea of the characterization.

Let $G$ be a (finite undirected) connected graph (without loops and multiple edges), and let $V, E$ and $D$ denote its vertex set, its edge set and its diameter, respectively. If $u, v \in V$, then $d(u, v)$ denotes the distance between $u$ and $v$ in $G$. (The letters $g, h, \ldots, n$ will be used to denote integers).

We denote by $\Sigma_{N}$ the set of all sequences

$$
\begin{equation*}
u_{0}, \ldots, u_{g} \tag{0}
\end{equation*}
$$

where $u_{0}, \ldots, u_{g} \in V$ and $g \geqslant 0$. Similarly as in [2] and [3], instead of (0) we will write $u_{0} \ldots u_{g}$. Let $\alpha=v_{0} \ldots v_{h}$, where $v_{0}, \ldots, v_{h} \in V$ and $h \geqslant 0$. We write $A \alpha=v_{0}$, $Z \alpha=v_{h},\|\alpha\|=h$ and

$$
\bar{\alpha}=v_{h} \ldots v_{0} .
$$

Let $\beta=x_{0} \ldots x_{i}$ and $\gamma=y_{0} \ldots y_{j}$, where $x_{0}, \ldots, x_{i}, y_{0}, \ldots, y_{j} \in V, i \geqslant 0$ and $j \geqslant 0$; we write

$$
\beta \gamma=x_{0} \ldots x_{i} y_{0} \ldots y_{j}
$$

We denote by $*$ the empty sequence in the sense that $* \delta=\delta=\delta *$ for each $\delta \in \Sigma_{N}$. Put $* *=*$ and $*=*$. Define $\Sigma=\Sigma_{N} \cup\{*\}$.

Let $\pi \in \Sigma_{N}$. We say that $\pi$ is a path in $G$ if there exist $k \geqslant 0$ and mutually distinct $w_{0}, \ldots, w_{k} \in V$ such that $\pi=w_{0} \ldots w_{k}$ and if $k \geqslant 1$, then

$$
\left\{w_{0}, w_{1}\right\}, \ldots,\left\{w_{k-1}, w_{k}\right\} \in E .
$$

The set al all paths in $G$ will be denoted by $\mathcal{P}$. If $\mathcal{Q} \subseteq \mathcal{P}$ and $m \geqslant 0$, then we define

$$
\mathcal{Q}(m)=\{\omega \in \mathcal{Q} ; d(A \omega, Z \omega)=m\} .
$$

Obviously, if $\pi \in \mathcal{P}$, then $d(A \pi, Z \pi) \leqslant\|\pi\|$.
Let $\tau \in \Sigma_{N}$. We say that $\tau$ is a geodesic (or a shortest path) in $G$ if $\tau \in \mathcal{P}$ and $d(A \tau, Z \tau)=\|\tau\|$.

The following theorem gives a characterization of the set of all geodesics in $G$.

Theorem ([3]). Let $\mathcal{R} \subseteq \mathcal{P}$, and let $\Gamma$ denote the set of all geodesics in $G$. Then the statements (1) and (2) are equivalent:
(1) $\mathcal{R}=\Gamma$.
(2) $\mathcal{R}$ satisfies the following properties $\mathbf{A}(\mathcal{R})-\mathbf{G}(\mathcal{R})$ (for all $u, v, x, y \in V$ and all $\varphi, \psi \in \Sigma):$
$\mathbf{A}(\mathcal{R})$ if $u v \varphi x \in \mathcal{R}$, then $\{u, x\} \notin E$;
$\mathbf{B}(\mathcal{R})$ if $u v \varphi x \in \mathcal{R}$, then $x \bar{\varphi} v u \in \mathcal{R}$;
$\mathbf{C}(\mathcal{R})$ if $u v \varphi x \in \mathcal{R}$, then $v \varphi x \in \mathcal{R}$;
$\mathbf{D}(\mathcal{R})$ if $u v \varphi x, v \psi x \in \mathcal{R}$, then $u v \psi x \in \mathcal{R}$;
$\mathbf{E}(\mathcal{R})$ if $u v \varphi x$, vu $\psi y \in \mathcal{R}$ and $\{x, y\} \in E$, then $v \varphi x y \in \mathcal{R}$;
$\mathbf{F}(\mathcal{R})$ if $u v \varphi x \in \mathcal{R},\{x, y\} \in E$, uv@y $\notin \mathcal{R}$ for all $\varrho \in \Sigma$ and $u \sigma y x \notin \mathcal{R}$ for all $\sigma \in \Sigma$, then $v \varphi x y \in \mathcal{R}$;
$\mathbf{G}(\mathcal{R})$ there exists $\xi \in \mathcal{R}$ such that $A \xi=u$ and $Z \xi=x$.
We will present a new proof of the theorem. The proof that (1) implies (2) is not complicated and will be omitted here. We only prove that (2) implies (1).

The next lemma yields a deeper insight into the theorem and suggest a new method for proving it.

Lemma. Let $u_{0}, u_{1}, \ldots, u_{g+h-1} \in V$, where $\min (g, h) \geqslant 2$. Denote $j=\min (g, h)$ and $u_{g+h}=u_{0}, u_{g+h+1}=u_{1}, \ldots, u_{g+h+j}=u_{j}$. Moreover, denote

$$
\alpha_{i}=u_{i} u_{i+1} \ldots u_{i+g} \text { and } \beta_{i}=u_{i+g} u_{i+g+1} \ldots u_{i+g+h}
$$

for each $i, 0 \leqslant i \leqslant j$.

Let $\mathcal{Q}, \mathcal{T} \subseteq \mathcal{P}$. Assume that $\mathcal{Q}$ satisfies $\mathbf{B}(\mathcal{Q})-\mathbf{F}(\mathcal{Q})$ and $\mathcal{T}$ satisfies $\mathbf{B}(\mathcal{T})-\mathbf{E}(\mathcal{T})$. Next, assume that the following conditions I-IV hold for all $i, 0 \leqslant i \leqslant j$, and all $\varphi$, $\psi \in \Sigma:$

I if $\alpha_{i} \in \mathcal{Q}$ and $\beta_{i} \notin \mathcal{T}$, then $\alpha_{i} \in \mathcal{T}$;
II if $u_{i} u_{i+1} \varphi u_{i+g+1} \in \mathcal{Q}, \beta_{i} \in \mathcal{T}$ and $\alpha_{i+1} \notin \mathcal{Q}$, then $u_{i} u_{i+1} \varphi u_{i+g+1} \in \mathcal{T}$;
III if $u_{i} u_{i+1} \varphi u_{i+g} \in \mathcal{T}$ and $u_{i} u_{i+1} \psi u_{i+g} \in \mathcal{Q}$, then $u_{i+1} \varphi u_{i+g} \in \mathcal{Q}$;
IV if $u_{i+g} u_{i+g+1} \varphi u_{i+g+h} \in \mathcal{T}$ and $u_{i+g} u_{i+g+1} \psi u_{i+g+h} \in \mathcal{Q}$, then $u_{i+g+1} \varphi u_{i+g+h}$ $\in \mathcal{Q}$.
Finally, assume that $\alpha_{0} \in \mathcal{Q}$ and $\beta_{0} \in \mathcal{T}$. Then $\beta_{0} \in \mathcal{Q}$.
Proof. Suppose, to the contrary, that $\beta_{0} \notin \mathcal{Q}$. Then $\beta_{0} \in \mathcal{T}-\mathcal{Q}$. First, we will show that
either $\alpha_{j} \notin \mathcal{Q}$ or $\beta_{j} \notin \mathcal{T}$.

If $g=h$, then (3) immediately follows from the fact that $\beta_{0} \notin \mathcal{Q}$. Next, let $g>h$. Then $j=h$. Suppose that $\alpha_{j} \in \mathcal{Q}$. Applying $\mathbf{B}(\mathcal{Q})$ to $\alpha_{0}$ and $\mathbf{C}(\mathcal{Q})$ to $\alpha_{j}$, we get

$$
u_{g} u_{g-1} \ldots u_{0}, u_{g-1} u_{g} \ldots u_{g+h} \in \mathcal{Q}
$$

Recall that $u_{g+h}=u_{0}$. By $\mathbf{D}(\mathcal{Q})$,

$$
u_{g} u_{g-1} u_{g} \ldots u_{g+h} \in \mathcal{Q}
$$

Thus $\mathcal{Q}-\mathcal{P} \notin \emptyset$, a contradiction. We get $\alpha_{j} \notin \mathcal{Q}$ and therefore (3) holds. Finally, let $h>g$. Then $j=g$. In a similar way, we get $\beta_{j} \notin \mathcal{T}$. Thus (3) holds again.

Recall that $\alpha_{0} \in \mathcal{Q}$ and $\beta_{0} \in \mathcal{T}-\mathcal{Q}$. Combining this fact with (3), we see that there exists $k, 0 \leqslant k<j$ such that

$$
\begin{equation*}
\alpha_{k} \in \mathcal{Q} \text { and } \beta_{k} \in \mathcal{T}-\mathcal{Q} \tag{4}
\end{equation*}
$$

and

$$
\begin{equation*}
\alpha_{k+1} \notin \mathcal{Q} \text { or } \beta_{k+1} \notin \mathcal{T}-\mathcal{Q} \tag{5}
\end{equation*}
$$

Denote $\alpha=\alpha_{k}, \alpha^{\prime}=\alpha_{k+1}, \beta=\beta_{k}, \beta^{\prime}=\beta_{k+1}$. Clearly, $\alpha, \beta \in \mathcal{P}$. We distinguish two cases:

1. Let $\alpha^{\prime} \in \mathcal{Q}$. If $\alpha^{\prime} \notin \mathcal{T}$, then I implies that $\beta^{\prime} \in \mathcal{T}$. If $\alpha^{\prime} \in \mathcal{T}$, then combining $\mathbf{B}(\mathcal{T})$ and $\mathbf{E}(\mathcal{T})$, we get $\beta^{\prime} \in \mathcal{T}$ again. By (5), $\beta^{\prime} \notin \mathcal{T}-\mathcal{Q}$. Hence $\beta^{\prime} \in \mathcal{Q}$. By (4), $\alpha \in \mathcal{Q}$. Combining $\mathbf{B}(\mathcal{Q})$ with $\mathbf{E}(\mathcal{Q})$, we get $\beta \in \mathcal{Q}$, which contradicts (4).
2. Let $\alpha^{\prime} \notin \mathcal{Q}$. Denote $u=u_{k}, v=u_{k+1}, x=u_{k+g}$ and $y=u_{k+g+1}$. Clearly, there exist $\varphi, \tau \in \Sigma$ such that $\alpha=u v \varphi x$ and $\beta=x y \tau u$. Hence $\alpha^{\prime}=v \varphi x y$. We distinguish two subcases:
2.1. Let $u \sigma y x \notin \mathcal{Q}$ for all $\sigma \in \Sigma$. By virtue of $\mathbf{F}(\mathcal{Q})$, there exists $\varrho \in \Sigma$ such that uv@y $\in \mathcal{Q}$. Since $\beta \in \mathcal{T}$ and $\alpha^{\prime} \notin \mathcal{Q}$, II implies that uv@y $\in \mathcal{T}$. By $\mathbf{B}(\mathcal{T})$, $y \bar{\varrho} v u \in \mathcal{T}$. Recall that $x y \tau u \in \mathcal{T}$. By $\mathbf{D}(\mathcal{T})$, $x y \bar{\varrho} v u \in \mathcal{T}$ and by $\mathbf{B}(\mathcal{T})$, uv@yx $\in \mathcal{T}$. Since $u v \varphi x \in \mathcal{Q}$, III implies that v@yx $\in \mathcal{Q}$. By $\mathbf{D}(\mathcal{Q})$, uv@yx $\in \mathcal{Q}$ and by $\mathbf{B}(\mathcal{Q})$, $x y \bar{\varrho} v u \in \mathcal{Q}$. Since $x y \tau u \in \mathcal{T}$, IV implies that $y \tau u \in \mathcal{Q}$. By $\mathbf{D}(\mathcal{Q}), \beta=x y \tau u \in \mathcal{Q}$, which contradicts (4).
2.2. Let there exist $\sigma \in \Sigma$ such that $u \sigma y x \in \mathcal{Q}$. $\operatorname{By} \mathbf{B}(\mathcal{Q}), x y \bar{\sigma} u \in \mathcal{Q}$. Since $\beta \in \mathcal{T}$, IV implies that $y \tau u \in \mathcal{Q}$. By $\mathbf{D}(\mathcal{Q}), \beta \in \mathcal{Q}$, which contradicts (4) again.

Thus $\beta_{0} \in \mathcal{Q}$, which completes the proof of the lemma.
Proof of the theorem. We will only prove that (2) implies (1). Now, let (2) hold. We will prove that $\Gamma(n) \subseteq \mathcal{R}(n)$ and $\mathcal{R}(n) \subseteq \Gamma(n)$ for every $n \geqslant 0$. We proceed by induction on $n$. The fact that $\Gamma(0)=\mathcal{R}(0)$ follows from $\mathbf{G}(\mathcal{R})$. The fact that $\Gamma(1)=\mathcal{R}(1)$ follows from $\mathbf{G}(\mathcal{R})$ and $\mathbf{A}(\mathcal{R})$. Let $n \geqslant 2$. Assume that

$$
\begin{equation*}
\Gamma(m)=\mathcal{R}(m) \text { for each } m, 0 \leqslant m<n . \tag{6}
\end{equation*}
$$

The case when $D<n$ is trivial. Suppose that $D \geqslant n$.
Consider an arbitrary $\omega \in \Gamma(n)$. Put $\mathcal{Q}=\mathcal{R}, \mathcal{T}=\Gamma$ and $h=n$. Obviously, $\mathbf{G}(\mathcal{Q})$ holds. There exist $u_{0}, \ldots, u_{g+h-1} \in V$, where $g \geqslant h$, such that

$$
\begin{equation*}
u_{0} u_{1} \ldots u_{g} \in \mathcal{Q} \text { and } \omega=u_{g} u_{g+1} \ldots u_{g+h}, \text { where } u_{g+h}=u_{0} \tag{7}
\end{equation*}
$$

By virtue of (6), I-IV hold. According to the lemma, $\omega \in \mathcal{R}$. We have proved that $\Gamma(n) \subseteq \mathcal{R}(n)$.

Consider an arbitrary $\omega \in \mathcal{R}(n)$. Put $\mathcal{Q}=\Gamma, \mathcal{T}=\mathcal{R}$ and $g=n$. There exist $u_{0}, \ldots, u_{g+h-1} \in V$, where $h \geqslant g$, such that (7) holds. Combining (6) with the fact that $\Gamma(n) \subseteq \mathcal{R}(n)$, we see that I-IV hold. According to the lemma, $\omega \in \Gamma$. We have proved that $\mathcal{R}(n) \subseteq \Gamma(n)$, which completes the proof of the theorem.

Remark 1. The fact that $V$ is finite was not utilized in any point of our proof.
Remark 2. A different way of characterizing the set of all geodesics in a connected graph can be found in [4].

Remark 3. Some types of graphs can be characterized by counting geodesics. For this topis, see [1].

## References

[1] P. V. Ceccherini: Studying structures by counting geodesics. In: Combinatorial Designs and Applications (W.D. Wallis et al., eds.). Marcel Dekker, New York and Basel, 1990, pp. 15-32.
[2] L. Nebeský: A characterization of the set of all shortest paths in a connected graph. Math. Bohemica 119 (1994), 15-20.
[3] L. Nebeský: On the set of all shortest paths of a given length in a connected graph. Czechoslovak Math. Journal 46 (121) (1996), 155-160.
[4] L. Nebeský: Geodesics and steps in a connected graph. Czechoslovak Math. Journal 47 (122) (1997), 149-161.

Author's address: Nám. J. Palacha 2, 11638 Praha 1, Czech Republic (Filozofická fakulta Univerzity Karlovy).

