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# CONTRACTIONS SIMILAR TO ISOMETRIES 

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In the present paper we investigate properties of contractions on a Hilbert space which are similar to isometries. A contraction is considered to be a compression of an isometry $V$ to a $V^{*}$-invariant subspace $\mathcal{H}$. A criterion for similarity of this compression to an isometry is given in terms of the space $\mathcal{H}$. As a consequence, we obtain some known criteria for a contraction to be similar to an isometry as well as some new results.

## Preliminary

Let $\mathcal{H}$ be a Hilbert space and $\mathcal{A}$ a closed subspace of $\mathcal{H}$. As usual, we denote by $\mathcal{A}^{\perp}$ the orthocomplement of $\mathcal{A}$ in $\mathcal{H}$ and by $P(\mathcal{A})$ the orthogonal projection of $\mathcal{H}$ onto $\mathcal{A}$. The algebra of all bounded linear operators on $\mathcal{H}$ is denoted by $B(\mathcal{H})$.

An operator $T \in B(\mathcal{H})$ is said to be similar to an isometry if there exists a boundedly invertible operator $C \in B(\mathcal{H})$ and an isometry $Z \in B(\mathcal{H})$ such that

$$
T=C^{-1} Z C
$$

It is easy to see that the fact that the isometry $Z$ acts on the same space $\mathcal{H}$ as $T$ is not important.

Indeed, if $T=D^{-1} Z^{\prime} D$ with $D: \mathcal{H}^{\prime} \rightarrow \mathcal{H}^{\prime}$ invertible, $Z^{\prime}$ an isometry on $\mathcal{H}^{\prime}$, then the operator $\Phi=\left(D^{*} D\right)^{1 / 2} D^{-1} \in B\left(\mathcal{H}^{\prime}\right)$ is a unitary operator, and consequently, $T$ is similar to the isometry $\Phi Z^{\prime} \Phi^{-1} \in B(\mathcal{H})$.

Let $T \in B(\mathcal{H})$ be a contraction (i.e. $|T| \leqslant 1$ ). Since the sequence of operators $\left\{T^{* n} T^{n}\right\}$ is nonincreasing, the limit $\lim _{n \rightarrow \infty} T^{* n} T^{n}$ in the strong operator topology exists and we can define a nonnegative operator

$$
A(T)=\left(s-\lim _{n \rightarrow \infty} T^{* n} T^{n}\right)^{1 / 2}
$$

Since

$$
|A(T) x|=\lim _{n \rightarrow \infty}\left|T^{n} x\right|
$$

we have

$$
|A(T) T x|=|A(T) x|
$$

It follows that there exists an isometry $W(T)$ on $\overline{\operatorname{Ran} A(T)}$ such that

$$
A(T) T=W(T) A(T)
$$

The just introduced concept allows us to give a simple generally known characterization of a contraction which is similar to an isometry.

Lemma 1. A contraction $T \in B(\mathcal{H})$ is similar to an isometry if and only if $A(T)$ is invertible.

Proof. If $T$ is similar to an isometry, i.e. if $C T C^{-1}=Z$ is an isometry for some invertible operator $C$ we have

$$
\left|T^{n} x\right|=\left|C^{-1} Z^{n} C x\right| \geqslant|C|^{-1} \cdot\left|Z^{n} C x\right|=|C|^{-1} \cdot|C x| \geqslant|C|^{-1} \cdot\left|C^{-1}\right|^{-1} \cdot|x| .
$$

## Hence

$$
|A(T) x| \geqslant|C|^{-1} \cdot\left|C^{-1}\right|^{-1} \cdot|x| .
$$

Since the operator $A(T)$ is nonnegative and bounded from below, we deduce that $A(T)$ is invertible.

On the other hand, if $A(T)$ is invertible then the isometry $W(T)$ acts on the whole of $\mathcal{H}$ and $T$ is similar to $W(T)$.

## Contractions similar to isometries

Let us consider a contraction $T \in B(\mathcal{H})$ which is similar to an isometry $Z \in$ $B(\mathcal{H}) ; Z=C T C^{-1}$. Let $\mathcal{H}=\mathcal{R}_{Z} \oplus \mathcal{S}_{Z}$ be the Wold decomposition of the isometry $Z$, i.e. both spaces $\mathcal{R}_{Z}, \mathcal{S}_{Z}$ are $Z$-reducing, $Z \mid \mathcal{R}_{Z}$ is a unitary operator, $Z \mid \mathcal{S}_{Z}$ is a unilateral shift. The spaces $\mathcal{R}_{Z}, \mathcal{S}_{Z}$ can be expressed as $\mathcal{R}_{Z}=\bigcap_{n=1}^{\infty} Z^{n} \mathcal{H}, \mathcal{S}_{Z}=$ $\left\{x ; \lim _{n \rightarrow \infty} Z^{* n} x=0\right\}$.

Since the isometry $Z$ is the direct sum of $Z \mid \mathcal{R}_{Z}$ and $Z \mid \mathcal{S}_{Z}$, we will be interested in the structure of the two parts $Z\left|\mathcal{R}_{Z}, Z\right| \mathcal{S}_{Z}$.

A unilateral shift is up to unitary equivalence determined by its multiplicity which is equal to the dimension of the kernel of its adjoint. The multiplicity of the unilateral shift $Z \mid \mathcal{S}_{Z}$ is equal to

$$
\operatorname{dim} \operatorname{ker}\left(Z \mid \mathcal{S}_{Z}\right)^{*}=\operatorname{dim} \operatorname{ker} Z^{*} \mid \mathcal{S}_{Z}=\operatorname{dim} \operatorname{ker} Z^{*}=\operatorname{dim} \operatorname{ker} T^{*}
$$

That is why we will be interested above all in the structure of the operator $Z \mid \mathcal{R}_{Z}$. Using the fact that $C$ is invertible we can express the operator $Z \mid \mathcal{R}_{Z}$ as

$$
\begin{gathered}
Z\left|\mathcal{R}_{Z}=C T C^{-1}\right| \bigcap_{n=1}^{\infty} Z^{n} \mathcal{H}=C T C^{-1}\left|\bigcap_{n=1}^{\infty} Z^{n} C \mathcal{H}=C T C^{-1}\right| C \bigcap_{n=1}^{\infty} T^{n} \mathcal{H}= \\
=\left(C \mid \bigcap_{n=1}^{\infty} T^{n} \mathcal{H}\right)\left(T \mid \bigcap_{n=1}^{\infty} T^{n} \mathcal{H}\right)\left(C \mid \bigcap_{n=1}^{\infty} T^{n} \mathcal{H}\right)^{-1}
\end{gathered}
$$

As a consequence we obtain

Lemma 2. Let a contraction $T$ be similar to an isometry $Z$. Then $Z \mid \mathcal{R}_{Z}$ is similar to $T \mid \bigcap_{n=1}^{\infty} T^{n} \mathcal{H}$.

We will use the notation

$$
\begin{gathered}
\mathcal{A}=\bigcap_{n=1}^{\infty} T^{n} \mathcal{H}, \\
\mathcal{B}=\left\{x ; \lim _{n \rightarrow \infty} T^{* n} x=0\right\}
\end{gathered}
$$

Lemma 3. Let $T$ be a contraction similar to an isometry $Z=C T C^{-1}$, then

$$
\mathcal{H}=\mathcal{A} \oplus \mathcal{B}
$$

Proof. Take an $a \in \mathcal{A}$. Let $c_{n}$ be such that $a=T^{n} c_{n}(n \in \mathbf{N})$. For $b \in \mathcal{B}$ we have

$$
\begin{aligned}
& |(a, b)|=\left|\left(T^{n} c_{n}, b\right)\right|=\left|\left(c_{n}, T^{* n} b\right)\right| \leqslant\left|c_{n}\right| \cdot\left|T^{* n} b\right| \leqslant\left|C^{-1}\right| \cdot\left|C c_{n}\right| \cdot\left|T^{* n} b\right|= \\
= & \left|C^{-1}\right| \cdot\left|Z^{n} C c_{n}\right| \cdot\left|T^{* n} b\right| \leqslant\left|C^{-1}\right| \cdot|C| \cdot\left|C^{-1} Z^{n} C c_{n}\right| \cdot\left|T^{* n} b\right|= \\
= & \left|C^{-1}\right| \cdot|C| \cdot|a| \cdot\left|T^{* n} b\right| .
\end{aligned}
$$

Since $T^{* n} \rightarrow 0$ as $n$ tends to infinity we obtain $(a, b)=0$ and, consequently, the spaces $\mathcal{A}$ and $\mathcal{B}$ are orthogonal.

On the other hand, the orthocomplement $\mathcal{A}^{\perp}$ can be expressed as

$$
\mathcal{A}^{\perp}=\bigvee_{n=1}^{\infty} \operatorname{ker} T^{* n} \subset \mathcal{B}
$$

thus

$$
\mathcal{A} \oplus B=\mathcal{H}
$$

In order to obtain a criterion for a contraction to be similar to an isometry we will apply some facts from the dilation theory (cf. [1]).

Let $T \in \mathcal{B}(\mathcal{H})$ be a contraction. Then there exists a Hilbert space $\mathcal{K} \supset \mathcal{H}$ and an isometry $V \in \mathcal{B}(\mathcal{K})$ such that

$$
\begin{aligned}
T^{n} & =P(\mathcal{H}) V^{n} \mid \mathcal{H} \quad(n \geqslant 0) \\
\mathcal{K} & =\bigvee_{n=0}^{\infty} V^{n} \mathcal{H}
\end{aligned}
$$

The isometry $V$ is uniquely determined up to unitary equivalence and is called the minimal isometric dilation of $T$. The above conditions imply

$$
V^{*} \mathcal{H} \subset \mathcal{H}
$$

or equivalently,

$$
T P(\mathcal{H})=P(\mathcal{H}) V
$$

Our aim now is to obtain some relation between $T \mid \mathcal{A}$ and $V$. Let $\mathcal{K}=\mathcal{R} \oplus \mathcal{S}$ be the Wold decomposition of the minimal isometric dilation $V$ of $T$.

Lemma 4. Let $T$ be a contraction similar to an isometry. Then $T \mid \bigcap_{n=1}^{\infty} T^{n} \mathcal{H}$ is similar to the unitary operator $V \mid \mathcal{R}$.

Proof. Let $T$ be a contraction similar to an isometry $Z=C T C^{-1}$. Since $T P(\mathcal{H})=P(\mathcal{H}) V$ we have $T^{*}=V^{*} \mid \mathcal{H}$ and

$$
T^{*} P(\mathcal{A})=V^{*} P(\mathcal{A})
$$

According to Lemma 3 we have

$$
P(\mathcal{B}) T^{*} P(\mathcal{A})=V^{*} P(\mathcal{A})-I^{\prime}(\mathcal{A}) T^{*} P(\mathcal{A})
$$

Applying $P\left(\mathcal{B}^{\perp}\right)$ we obtain

$$
P\left(B^{\perp}\right)\left(V^{*} P(\mathcal{A})-(T \mid \mathcal{A})^{*} P(\mathcal{A})\right)=0
$$

Since $\mathcal{S}=\left\{x \in \mathcal{K} ; V^{* n} x \rightarrow 0\right\}$ we have $\mathcal{B}=\mathcal{S} \bigcap \mathcal{H}$ and $\mathcal{R} \subset \mathcal{B}^{\perp}$. In particular,

$$
P(\mathcal{R})\left(V^{*} P(\mathcal{A})-(T \mid \mathcal{A})^{*} P(\mathcal{A})\right)=0
$$

Using the fact that the space $\mathcal{R}$ is $V$-reducing we obtain

$$
\left(V^{*} \mid \mathcal{R}\right)(P(\mathcal{R}) \mid \mathcal{A})=(P(\mathcal{R}) \mid \mathcal{A})(T \mid \mathcal{A})^{*}
$$

or equivalently,

$$
(P(\mathcal{R}) \mid \mathcal{A})^{*}(V \mid \mathcal{R})=(T \mid \mathcal{A})(P(\mathcal{R}) \mid \mathcal{A})^{*}
$$

It remains to prove that the operator $Q=P(\mathcal{R}) \mid \mathcal{A}$ is invertible.
Since $V^{n}$ is an isometry the projection onto the space $V^{n} \mathcal{K}$ is equal to $V^{n} V^{* n}$. Since $\mathcal{R}=\bigcap_{n=1}^{\infty} V^{n} \mathcal{K}$ we have, for $h \in \mathcal{H}$,

$$
P(\mathcal{R}) h=\lim _{n \rightarrow \infty} V^{n} V^{* n} h=\lim _{n \rightarrow \infty} V^{n} T^{* n} h
$$

and

$$
|Q a|^{2}=\lim _{n \rightarrow \infty}\left|V^{n} T^{* n} a\right|=\lim _{n \rightarrow \infty}\left|T^{* n} a\right|^{2}
$$

for $a \in \mathcal{A}$. Further, let $c_{n}$ be such that $a=T^{n} c_{n}(n \in \mathbf{N})$. Using the fact that $\left|\left(T^{* n} T^{n}\right)^{1 / 2} x\right|^{2}=\left|T^{n} x\right|^{2}$ and Lemma 1 we have

$$
\begin{aligned}
& \left|T^{* n} a\right|=\left|T^{* n} T^{n} c_{n}\right|=\left|\left[\left(T^{* n} T^{n}\right)^{1 / 2}\right]^{2} c_{n}\right|=\left|T^{n}\left(T^{* n} T^{n}\right)^{1 / 2} c_{n}\right| \geqslant \\
\geqslant & |C|^{-1} \cdot\left|C^{-1}\right|^{-1} \cdot\left|\left(T^{* n} T^{n}\right)^{1 / 2} c_{n}\right|= \\
= & |C|^{-1} \cdot\left|C^{-1}\right|^{-1} \cdot\left|T^{n} c_{n}\right|=|C|^{-1} \cdot\left|C^{-1}\right|^{-1} \cdot|a| .
\end{aligned}
$$

Thus

$$
|Q a| \geqslant|C|^{-1} \cdot\left|C^{-1}\right|^{-1} \cdot|a|
$$

in other words, $Q$ is bounded from below. It suffices to prove that

$$
\mathcal{R} \ominus \operatorname{Ran} Q=\operatorname{ker} Q^{*}=\operatorname{ker} P(\mathcal{A}) \mid \mathcal{R}=\{0\}
$$

Let us consider $r \in R$ such that $P(\mathcal{A}) r=0$. Since $\mathcal{R} \subset \mathcal{B}^{\perp}$ we have also

$$
P(\mathcal{H}) r=P(\mathcal{A}) r+P(\mathcal{B}) r=0,
$$

or equivalently, $r \in \mathcal{H}^{\perp}$.
Using the fact that $V \mid \mathcal{R}$ is a unitary operator and $V \mathcal{H}^{\perp} \subset \mathcal{H}^{\perp}$ we obtain, for $n \in \mathbf{N}$,

$$
\begin{aligned}
0 & =P(\mathcal{H}) r=P(\mathcal{H}) V^{n} V^{* n} r=P(\mathcal{H}) V^{n}\left(P(\mathcal{H})+P\left(\mathcal{H}^{\perp}\right)\right) V^{* n} r= \\
& =P(\mathcal{H}) V^{n} P(\mathcal{H}) V^{* n} r=T^{n} P(\mathcal{H}) V^{* n} r .
\end{aligned}
$$

Since $T^{n}$ is injective we have $P(\mathcal{H}) V^{* n} r=0$ so that

$$
|r|=\left|V^{* n} r\right|=\left|P\left(\mathcal{H}^{\perp}\right) V^{* n} r\right|=\left|\left(V \mid \mathcal{H}^{\perp}\right)^{* n} r\right| .
$$

The fact that $V \mid \mathcal{H}^{\perp}$ is a shift operator (i.e. $\left.\left(V \mid \mathcal{H}^{\perp}\right)^{* n} \rightarrow 0\right)$ completes the proof.

Putting together Lemma 2 and Lemma 4 we conclude that operators $Z \mid \mathcal{R}_{Z}$ and $V \mid \mathcal{R}$ are similar. Since both operators are unitary they are even unitarily equivalent. In particular, in view of Lemma 4 we obtain that two isometries are similar if and only if they are unitarily equivalent. Further, since $\operatorname{dim} \operatorname{ker} T^{*} \leqslant \operatorname{dim} \operatorname{ker} V^{*}$ there exists a $V$-invariant subspace $\mathcal{M}$ of $\mathcal{K}$ such that $V \mid \mathcal{M}$ is unitarily equivalent to $Z$ and hence $V \mid \mathcal{M}$ is similar to $T$. Let $\mathcal{N}$ be a $V$-invariant subspace of $\mathcal{K}$. It follows from $P(\mathcal{H}) V P(\mathcal{H})=P(\mathcal{H}) V$ that

$$
T(P(\mathcal{H}) \mid \mathcal{N})=(P(\mathcal{H}) \mid \mathcal{N})(V \mid \mathcal{N})
$$

We know that there exists a $V$-invariant subspace $\mathcal{M}$ of $\mathcal{K}$ such that $T$ is similar to $V \mid \mathcal{M}$. We will show now that there exists a $V$-invariant subspace $\mathcal{N}$ of $\mathcal{K}$ such that $P(\mathcal{H}) \mid \mathcal{N}$ is invertible. First, we will prove the following simple lemma.

Lemma 5. Let $\mathcal{E}, \mathcal{F}$ be closed subspaces of a Hilbert space $\mathcal{K}$. Then $\mathcal{E} \dot{\mathcal{F}}=\mathcal{K}$ (i.e. $\mathcal{K}$ is the direct sum of $\mathcal{E}$ and $\mathcal{F}$ ) if and only if $P\left(\mathcal{E}^{\perp}\right) \mid \mathcal{F}$ is an invertible operator from $\mathcal{F}$ onto $\mathcal{E}^{\perp}$.

Proof. It is sufficient to observe that

$$
\begin{aligned}
& \mathcal{E} \cap \mathcal{F}=\{0\} \Leftrightarrow P\left(\mathcal{E}^{\perp}\right) \mid \mathcal{F} \text { is injective, } \\
& \mathcal{E}+\mathcal{F}=\mathcal{K} \Leftrightarrow P\left(\mathcal{E}^{\perp}\right) \mid \mathcal{F} \text { is surjective. }
\end{aligned}
$$

Proposition 6. Let $T$ be a contraction, let $V$ be its minimal isometric dilation. Then $T$ is similar to an isometry if and only if there exists a $V$-invariant subspace $\mathcal{N}$ of $\mathcal{K}$ such that

$$
\mathcal{N} \dot{+} \mathcal{H}^{\perp}=\mathcal{K}
$$

or equivalently, the operator $P(\mathcal{H}) \mid \mathcal{N}$ is invertible.
Proof. If there exists a subspace $\mathcal{N}$ such that $V \mathcal{N} \subset \mathcal{N}$ and $P(\mathcal{H}) \mid \mathcal{N}$ is invertible then $T$ is similar to an isometry as a consequence of the relation

$$
T(P(\mathcal{H}) \mid \mathcal{N})=(P(\mathcal{H}) \mid \mathcal{N})(V \mid \mathcal{N})
$$

Conversely, let a contraction $T \in B(\mathcal{H})$ be similar to an isometry $U \in B(\mathcal{H}), T=$ $C^{-1} U C$. Suppose that $\mathcal{L}$ is a subspace of $\mathcal{K}$ such that $V \mathcal{L} \subset \mathcal{L}$ and $\mathcal{H}^{\perp} \dot{+} \mathcal{L}=\mathcal{K}$. According to Lemma 5 the operator $X=P(\mathcal{H}) \mid \mathcal{L}: \mathcal{L} \rightarrow \mathcal{H}$ is invertible and so

$$
X^{-1} T=V X^{-1}
$$

Using the fact that

$$
C^{-1} U=T C^{-1}
$$

we obtain

$$
\left(X^{-1} C^{-1}\right) U=V\left(X^{-1} C^{-1}\right)
$$

so the operator $X^{-1} C^{-1}$ intertwines $U$ and the minimal isometric dilation $V$ of $T$. Let us observe that $P(\mathcal{H}) X^{-1} C^{-1}=C^{-1}$ and $\mathcal{L}=\operatorname{Ran} X^{-1}$.

On the other hand, by virtue of the Lifting Theorem the relation $C^{-1} U=T C^{-1}$ implies that there exists an operator $Y: \mathcal{H} \rightarrow \mathcal{K}$ such that

$$
\begin{aligned}
Y U & =V Y \\
P(\mathcal{H}) Y & =C^{-1}
\end{aligned}
$$

That is why we set

$$
\mathcal{N}=\operatorname{Ran} Y C
$$

First, $V Y C=Y U C=Y C T$, hence $V \mathcal{N} \subset \mathcal{N}$. Since

$$
Y C P(\mathcal{H}) Y C P(\mathcal{H})=Y C C^{-1} C P(\mathcal{H})=Y C P(\mathcal{H})
$$

the operator $Y C P(\mathcal{H})$ is an idempotent and $\mathcal{N}=\operatorname{Ran} Y C P(\mathcal{H})$. It remains to show that

$$
\text { ker } Y C P(\mathcal{H})=\mathcal{H}^{\perp}
$$

Indeed,

$$
\mathcal{H}^{\perp} \subset \operatorname{ker} Y C P(\mathcal{H}) \subset \operatorname{ker} P(\mathcal{H}) Y C P(\mathcal{H})=\operatorname{ker} P(\mathcal{H})=\mathcal{H}^{\perp}
$$

The proof is complete.

The just proved condition for a contraction to be similar to an isometry has the following equivalent form.

Lemma 7. The following conditions are equivalent.
$1^{0}$ There exists a subspace $\mathcal{N}$ of $\mathcal{K}$ such that

$$
\begin{aligned}
V \mathcal{N} & \subset \mathcal{N}, \\
\mathcal{H}^{\perp}+\mathcal{N} & =\mathcal{K} .
\end{aligned}
$$

$2^{0}$ There exists an operator $L: \mathcal{S} \rightarrow \mathcal{H}^{\perp}$ such that

$$
\begin{aligned}
L P(\mathcal{S}) \mid \mathcal{H}^{\perp} & =I_{\mathcal{H}^{\perp}} \\
L(V \mid \mathcal{S}) & =\left(V \mid \mathcal{H}^{\perp}\right) L
\end{aligned}
$$

Moreover, condition $1^{0}$ implies $\mathcal{R} \subset \mathcal{N}$.
Proof. Assume that $1^{0}$ holds. We set

$$
\begin{aligned}
X & =P(\mathcal{H}) \mid \mathcal{N}, \\
\tilde{L} & =\left(1-X^{-1} P(\mathcal{H})\right)
\end{aligned}
$$

and

$$
L=\tilde{L} \mid \mathcal{S}: \mathcal{S} \rightarrow \mathcal{H}^{\perp} .
$$

The operator $\widetilde{L}$ is idempotent, equals the identity on $\mathcal{H}^{\perp}$ and vanishes just on $\mathcal{N}$, hence $\operatorname{Ran} \widetilde{L}=\mathcal{H}^{\perp}$. Take a $k \in \mathcal{K}$ and its decomposition with respect to $\mathcal{K}=\mathcal{H}^{\perp}+\mathcal{N}$,

$$
k=h^{\perp}+n, \quad\left(h^{\perp} \in \mathcal{H}^{\perp}, n \in \mathcal{N}\right) .
$$

It follows that

$$
\tilde{L} V k=\tilde{L} V h^{\perp}+\widetilde{L} V n=V h^{\perp}=V \tilde{L} h^{\perp}+V \tilde{L} n=V \tilde{L} k .
$$

In particular, we have also

$$
L(V \mid \mathcal{S})=\left(V \mid \mathcal{H}^{\perp}\right) L
$$

Since $V \mid \mathcal{H}^{\perp}$ is a shift operator we obtain

$$
\tilde{L} \mathcal{R}=\widetilde{L} \bigcap_{n=1}^{\infty} V^{n} \mathcal{K} \subset \bigcap_{n=1}^{\infty} V^{n} \tilde{L} \mathcal{K} \subset \bigcap_{n=1}^{\infty} V^{n} \mathcal{H}^{\perp}=\{0\}
$$

Thus we obtain $\mathcal{R} \subset \mathcal{N}$. Consequently, for $h^{\perp} \in \mathcal{H}^{\perp}$ we have

$$
L P(\mathcal{S}) h^{\perp}=\widetilde{L}(P(\mathcal{S})+P(\mathcal{R})) h^{\perp}=h^{\perp}
$$

On the other hand, assume $2^{0}$ and set

$$
\mathcal{N}=\operatorname{ker} L P(\mathcal{S}) .
$$

It is obvious that

$$
V \mathcal{N} \subset N
$$

Since $L P(\mathcal{S}) L P(\mathcal{S})=L P(\mathcal{S})$ the operator $L P(\mathcal{S})$ is an idempotent and its range is equal to $\mathcal{H}^{\perp}$. Thus

$$
\mathcal{H}^{\perp} \dot{+} \mathcal{N}=\mathcal{K}
$$

Condition $2^{0}$ as a criterion for similarity of a contraction to an isometry was proved by Sz.-Nagy and Foiass [2]. From this criterion another criterion for similarity of a contraction to an isometry in terms of the characteristic function was derived in [2]. We also derive this criterion from Proposition 6 and Lemma 7 but in a different way.

First, let us recall one of the definitions of the Hardy space $H^{2}(\mathcal{E})$ (cf. [1]).
Let $\mathcal{E}$ be a separable Hilbert space. We denote by $H^{2}(\mathcal{E})$ the space of all functions with values in $\mathcal{E}$ which are analytic in the unit disc and their Taylor coefficients are square summable. The norm on $H^{2}(\mathcal{E})$ is defined as

$$
\left|\sum_{k=0}^{\infty} \lambda^{k} a_{k}\right|^{2}=\sum_{k=0}^{\infty}\left|a_{k}\right|^{2} \quad\left(a_{k} \in \mathcal{E}\right)
$$

Let $T \in B(\mathcal{H})$ be a contraction, let $V$ be its minimal isometric dilation. As usual, we use the notation

$$
\begin{gathered}
D=\left(1-T^{*} T\right)^{1 / 2}, \quad \mathcal{D}=\overline{\operatorname{RanD}}, \\
D_{*}=\left(1-T T^{*}\right)^{1 / 2}, \quad \mathcal{D}=\overline{\operatorname{Ran} D_{*}}, \\
\mathcal{L}=\overline{(V-T) \mathcal{H}} \\
\mathcal{L}_{*}=\overline{\left(I-V T^{*}\right) \mathcal{H}}
\end{gathered}
$$

Let $\varphi: \mathcal{L} \rightarrow \mathcal{D}$ be an isometry defined on the space $(V-T) \mathcal{H}$ by the formula

$$
\varphi(V-T) h=D h \quad(h \in \mathcal{H})
$$

Clearly, $\varphi$ is a unitary mapping of $\mathcal{L}$ onto $\mathcal{D}$. Since

$$
\mathcal{H}^{\perp}=\mathcal{L} \oplus V \mathcal{L} \oplus V^{2} \mathcal{L} \oplus \ldots
$$

there exists a unitary operator $\Phi: \mathcal{H}^{\perp} \rightarrow H^{2}(\mathcal{D})$ such that

$$
\Phi\left(\sum_{0}^{n} V^{k} \ell_{k}\right)=\sum_{0}^{n} \varphi\left(\ell_{k}\right) \lambda^{k} \quad\left(\ell_{k} \in \mathcal{L}\right) .
$$

Similarly, there exist a unitary mapping $\varphi_{*}: \mathcal{L}_{*} \rightarrow \mathcal{D}_{*}$ such that

$$
\varphi_{*}\left(I-V T^{*}\right) h=D_{*} h \quad(h \in \mathcal{H})
$$

and a unitary operator $\Phi_{*}: \mathcal{S} \rightarrow H^{2}\left(\mathcal{D}_{*}\right)$ such that

$$
\Phi_{*}\left(\sum_{0}^{n} V^{k} \ell_{* k}\right)=\sum_{0}^{n} \varphi_{*}\left(\ell_{* k}\right) \lambda^{k} .
$$

Let us consider the operator $P(\mathcal{S}) \mid \mathcal{H}^{\perp}$ which is one of the forms of the characteristic function. The operator $\Theta_{+}: H^{2}(\mathcal{D}) \rightarrow H^{2}\left(\mathcal{D}_{*}\right)$ defined as

$$
\Theta_{+}=\Phi_{*}\left(P(\mathcal{S}) \mid \mathcal{H}^{\perp}\right) \Phi^{-1}
$$

is another form of the characteristic function. The bounded analytic function $\Theta\left(\Theta(\lambda): \mathcal{D} \rightarrow \mathcal{D}_{*}\right)$ which is defined for $|\lambda|<1$ as

$$
\Theta(\lambda)=-T+D_{*}\left(\lambda^{-1}-T^{*}\right)^{-1} D,
$$

is the third form of the characteristic function. The operator $\Theta_{+}$can be expressed as

$$
\left(\Theta_{+} u\right)(\lambda)=\Theta(\lambda) u(\lambda) \quad u \in H^{2}(\mathcal{D})
$$

Let $T_{1} \in B\left(\mathcal{H}_{1}\right), T_{2} \in B\left(\mathcal{H}_{2}\right)$ be contractions. We use the notation

$$
\mathcal{I}\left(T_{1}, T_{2}\right)=\left\{X: \mathcal{H}_{1} \rightarrow \mathcal{H}_{2} \text { a bounded linear operator; } T_{2} X=X T_{1}\right\}
$$

Proposition 8. Let $T$ be a contraction, let $V$ be its minimal isometric dilation, let $\Theta$ be its characteristic function. Then $T$ is similar to an isometry if and only if there exists a bounded analytic function $\Delta(\lambda)(|\lambda|<1)$ such that

$$
\Delta(\lambda) \Theta(\lambda)=I_{\mathcal{D}}
$$

for all $|\lambda|<1$.
Proof. Since $\Phi \in \mathcal{I}\left(V \mid \mathcal{H}^{\perp}, S\right), \Phi_{*} \in \mathcal{I}\left(V \mid \mathcal{S}, S_{*}\right)$ the operator $P(\mathcal{S}) \mid \mathcal{H}^{\perp}$ has a left inverse operator $L \in \mathcal{I}\left(V|\mathcal{S}, V| \mathcal{H}^{\perp}\right)$ if and only if $\Theta_{+}$has a left inverse operator intertwining the shifts $S$ and $S_{*}$ on $H^{2}(\mathcal{D})$ and $H^{2}\left(\mathcal{D}_{*}\right)$, respectively. If the operator $\Theta_{+}$has a left inverse operator $\Delta_{+} \in \mathcal{I}\left(S_{*}, S\right)$ then, according to Proposition V.3.2 [1], there exists a bounded analytic function $\Delta$ such that

$$
\left(\Delta_{+} u\right)(\lambda)=\Delta(\lambda) u(\lambda) \quad\left(u \in H^{2}(\mathcal{D})\right) .
$$

It follows that

$$
\Delta(\lambda) \Theta(\lambda)=I_{\mathcal{D}} \quad(|\lambda|<1)
$$

On the other hand, if there exists a bounded analytic function $\Delta(\lambda)(|\lambda|<1)$ such that

$$
\Delta(\lambda) \Theta(\lambda)=I_{\mathcal{D}}
$$

then the operator $\Delta_{+}$defined as

$$
\left(\Delta_{+} u\right)(\lambda)=\Delta(\lambda) u(\lambda) \quad\left(u \in H^{2}(\mathcal{D})\right)
$$

is a left inverse operator to the operator $\Theta_{+}$and $\Delta_{+} \in \mathcal{I}\left(S_{*}, S\right)$. It suffices now to apply Proposition 6 and Lemma 7.

## Similarity of compressions

Let $V \in B(\mathcal{K})$ be an isometry. The compression $P(\mathcal{H}) V \mid \mathcal{H}$ on a $V^{*}$-invariant subspace $\mathcal{H}$ is a contraction. On the other hand, it follows from the existence of the minimal isometric dilation of a contraction that any contraction can be obtained in this way.

It is natural to ask when such a compression is similar to an isometry (i.e. what condition must the space $\mathcal{H}$ satisfy). In Proposition 6 and Lemma 7 two equivalent conditions concerning the space $\mathcal{H}$ are given. We will reformulate condition $1^{0}$ from Lemma 7 in terms of an invertible operator commuting with $V^{*}$ and $V$-reducing subspaces of $\mathcal{K}$ :

Let us consider condition $1^{0}$, i.e. there exists a closed $V$-invariant subspace $\mathcal{N}$ of $\mathcal{K}$ such that

$$
\mathcal{H}^{\perp} \dot{+} \mathcal{N}=\mathcal{K}
$$

We will construct a Hilbert space

$$
\tilde{\mathcal{K}}=\mathcal{H}^{\perp} \oplus \mathcal{N}
$$

an isometry $\tilde{V}$ on $\widetilde{\mathcal{K}}$ and use the relation between $V$ and $\widetilde{V}$. We obtain an interesting representation of the space $\mathcal{H}$ with the required properties.

Theorem 9. Let $T \in B(\mathcal{H})$ be a contraction, $V \in B(\mathcal{K})$ its minimal isometric dilation with the Wold decomposition $\mathcal{K}=\mathcal{R} \oplus \mathcal{S}$. Then the contraction $T$ is similar to an isometry if and only if there exists a closed subspace $\mathcal{A}(\mathcal{R} \subset \mathcal{A} \subset \mathcal{K})$ which is $V$-reducing, and an invertible operator $\Theta \in B(\mathcal{K})$ commuting with $V^{*}$ such that

$$
\mathcal{H}=\Theta \mathcal{A}
$$

Proof. Assume that the contraction $T$ is similar to an isometry. According to Proposition 6 there exists a $V$-invariant subspace $\mathcal{N}$ of $\mathcal{K}$ such that

$$
\mathcal{N} \dot{+} \mathcal{H}^{\perp}=\mathcal{K} .
$$

Both spaces $\mathcal{H}^{\perp}$ and $\mathcal{N}$ are $V$-invariant. We now define the space

$$
\widetilde{\mathcal{K}}=\left\{x \oplus y ; x \in \mathcal{N}, y \in \mathcal{H}^{\perp}\right\}
$$

and the operator $\tilde{V}: \tilde{\mathcal{K}} \rightarrow \tilde{\mathcal{K}}$,

$$
\tilde{V}(x \oplus y)=V x \oplus V y
$$

We set $\tilde{\mathcal{N}}=\{x \oplus 0 ; x \in \mathcal{N}\}$. The subspace $\tilde{\mathcal{N}}$ of $\tilde{\mathcal{K}}$ is $V$-reducing and $\tilde{\mathcal{N}}^{\perp}=$ $\left\{0 \oplus \boldsymbol{y} ; \boldsymbol{y} \in \mathcal{H}^{\perp}\right\}$. Further, we define an operator $\Delta: \tilde{\mathcal{K}} \rightarrow \mathcal{K}$ as

$$
\Delta(x \oplus y)=x+y
$$

If follows from the relation $\mathcal{N} \dot{+} \mathcal{H}^{\perp}=\mathcal{K}$ that $\Delta$ is invertible. The spaces $\mathcal{H}^{\perp}, \mathcal{N}$ can be expressed as

$$
\begin{aligned}
\mathcal{H}^{\perp} & =\Delta \tilde{\mathcal{N}}^{\perp} \\
\mathcal{N} & =\Delta \tilde{\mathcal{N}}
\end{aligned}
$$

Since

$$
x \in \mathcal{H} \Leftrightarrow\left(x, \Delta \tilde{\mathcal{N}}^{\perp}\right)=0 \Leftrightarrow \Delta^{*} x \in \tilde{\mathcal{N}} \Leftrightarrow x \in \Delta^{*-1} \tilde{\mathcal{N}}
$$

we have

$$
\mathcal{H}=\Delta^{*-1} \tilde{\mathcal{N}}
$$

Since the operator $\Delta$ is invertible and $\Delta \tilde{V}=V \Delta$ the isometries $V$ and $\tilde{V}$ are similar. Consequently, the unitary parts $V|\mathcal{R}, \tilde{V}| \tilde{\mathcal{R}}$ as well as the shift parts $V|\mathcal{S}, \tilde{V}| \widetilde{\mathcal{S}}$ are
unitarily equivalent. In other words, there exists a unitary operator $\Phi: \mathcal{K} \rightarrow \tilde{\mathcal{K}}$ such that

$$
\begin{aligned}
& \Phi \mathcal{R}=\tilde{\mathcal{R}} \\
& \Phi \mathcal{S}=\widetilde{\mathcal{S}} \\
& \tilde{V} \Phi=\Phi V
\end{aligned}
$$

Consequently, we have also

$$
\boldsymbol{\Phi}^{*} \tilde{V}=V \boldsymbol{\Phi}^{*}
$$

Since $\mathcal{R}=\bigcap_{n=1}^{\infty} V^{n} \mathcal{K}, \tilde{\mathcal{R}}=\bigcap_{n=1}^{\infty} \tilde{V}^{n} \tilde{\mathcal{K}}$ the space $\tilde{\mathcal{R}}$ can be expressed as $\tilde{\mathcal{R}}=$ $\Delta^{-1} \Delta \tilde{\mathcal{R}}=\Delta^{-1} \bigcap_{n=1}^{\infty} \Delta \tilde{V}^{n} \tilde{\mathcal{K}}=\Delta^{-1} \bigcap_{n=1}^{\infty} V^{n} \mathcal{K}=\Delta^{-1} \mathcal{R}$. If we define

$$
\begin{aligned}
& \mathcal{A}=\Phi^{*} \tilde{\mathcal{N}} \\
& \Theta=\Delta^{*-1} \Phi
\end{aligned}
$$

we obtain the required properties: $\mathcal{A}$ is a $V$-reducing subspace of $\mathcal{K}, \mathcal{R}=\Phi^{*} \widetilde{\mathcal{R}}=$ $\Phi^{*} \Delta^{-1} \mathcal{R} \subset \Phi^{*} \Delta^{-1} \mathcal{N}=\Phi^{*} \tilde{\mathcal{N}}=\mathcal{A}$ and $\Theta$ is an invertible operator on $\mathcal{K}$ commuting with $V^{*}$. According to the definition of $\mathcal{A}$ and $\Theta$ we obtain

$$
\mathcal{H}=\Delta^{*-1} \tilde{\mathcal{N}}=\Delta^{*-1} \Phi \Phi^{*} \tilde{\mathcal{N}}=\Theta \mathcal{A}
$$

We have proved one part of the theorem.
It is easy to see that $\mathcal{N}=\Theta^{*-1} \mathcal{A}$. Since $\mathcal{H}^{\perp} \dot{+} \mathcal{N}=\mathcal{N}$ the operator $P(\mathcal{H}) \mid \mathcal{N}$ is invertible according to Lemma 5. It follows from the intertwining relation

$$
(P(\mathcal{H}) V \mid \mathcal{H})(P(\mathcal{H}) \mid \mathcal{N})=(P(\mathcal{H}) \mid \mathcal{N})(V \mid \mathcal{N})
$$

that $T$ is similar to $V \mid \Theta^{*-1} \mathcal{A}$.
Suppose that there exists a closed subspace $\mathcal{A}$ of $\mathcal{K}$ which reduces $V$ and an invertible operator $\Theta$ on $\mathcal{K}$ which commutes with $V^{*}$ and such that $\mathcal{H}=\Theta \mathcal{A}$. Let us define an operator $X: \Theta^{*-1} \mathcal{A} \rightarrow \Theta \mathcal{A}$ as follows:

$$
X=P(\Theta \mathcal{A}) \mid \Theta^{*-1} \mathcal{A}
$$

The space $\Theta^{*-1} \mathcal{A}$ is invariant for $V$ since

$$
V \Theta^{*-1} \mathcal{A}=\Theta^{*-1} V \mathcal{A} \subset \Theta^{*-1} \mathcal{A}
$$

and, consequently,

$$
V(\Theta \mathcal{A})^{\perp} \subset(\Theta \mathcal{A})^{\perp}
$$

This inclusion can be rewritten as

$$
P(\Theta \mathcal{A}) V(I-P(\Theta \mathcal{A}))=0
$$

Restricting this relation to the space $\Theta^{*-1} \mathcal{A}$ we obtain

$$
(P(\Theta \mathcal{A}) V \mid \Theta \mathcal{A})\left(P(\Theta \mathcal{A}) \mid \Theta^{*-1} \mathcal{A}\right)=\left(P(\Theta \mathcal{A}) \mid \Theta^{*-1} \mathcal{A}\right)\left(V \mid \Theta^{*-1} \mathcal{A}\right)
$$

If we set $X=P(\Theta \mathcal{A}) \mid \Theta^{*-1} \mathcal{A}$ then

$$
T X=X\left(V \mid \Theta^{*-1} \mathcal{A}\right)
$$

According to Lemma 5 the operator $X$ is invertible if and only if

$$
(\Theta \mathcal{A})^{\perp}+\Theta^{*-1} \mathcal{A}=\mathcal{K}
$$

Since $(\Theta \mathcal{A})^{\perp}=\Theta^{*-1} \mathcal{A}^{\perp}$ the above condition is clearly satisfied. So we have proved that $T$ is similar to the isometry $V \mid \Theta^{*-1} \mathcal{A}$.

The assumption of minimality of the isometric dilation $V$ of $T$ does not play an important role.

Let $V \in B(\mathcal{K})$ be an isometry, let $\mathcal{H}$ be a $V^{*}$-invariant subspace of $\mathcal{K}$ such that the compression $T=P(\mathcal{H}) V \mid \mathcal{H}$ is similar to an isometry. If we set

$$
\mathcal{K}_{0}=\bigvee_{n=0}^{\infty} V^{n} \mathcal{H}
$$

then $\mathcal{K}_{0}$ is the $V$-reducing subspace of $\mathcal{K}$ and $V \mid \mathcal{K}_{0}$ is the minimal isometric dilation of $T$. According to Theorem 9 there exists a closed subspace $\mathcal{A}$ of $\mathcal{K}_{0} \subset \mathcal{K}$ which reduces $V \mid \mathcal{K}_{0}$, and an invertible operator $\Theta_{0}$ commuting with $\left(V \mid \mathcal{K}_{0}\right)^{*}=V^{*} \mid \mathcal{K}_{0}$ such that

$$
\mathcal{H}=\Theta_{0} \mathcal{A}
$$

If we define an operator $\Theta: \mathcal{K} \rightarrow \mathcal{K}$ by the formula

$$
\Theta k=\Theta_{0} P\left(\mathcal{K}_{0}\right) k+P\left(\mathcal{K}_{0}^{\perp}\right) k \quad(k \in \mathcal{K})
$$

then $\Theta$ is an invertible operator commuting with $V^{*}$ and

$$
\mathcal{H}=\Theta \mathcal{A}
$$

So we have proved

Corollary 10. Let $V \in B(\mathcal{K})$ be an isometry and $\mathcal{H}$ a $V^{*}$-invariant subspace of $\mathcal{K}$. Then an operator $T=P(\mathcal{H}) V \mid \mathcal{H}$ is similar to an isometry if and only if there exist a closed subspace $\mathcal{A}$ of $\mathcal{K}$ which reduces $V$ and an invertible operator $\Theta \in B(\mathcal{K})$ which commutes with $V^{*}$ such that

$$
\mathcal{H}=\Theta \mathcal{A}
$$

In the preceding theorem subspaces reducing an isometry play an important role. These subspaces can be described in the following way. If a subspace $\mathcal{A}$ reduces an isometry $V \in B(\mathcal{K})$ then both operators $V|\mathcal{A}, V| \mathcal{A}^{\perp}$ are isometries. If $\mathcal{A}=$ $\mathcal{S}_{\mathcal{A}} \oplus \mathcal{R}_{\mathcal{A}}, \mathcal{A}^{\perp}=\mathcal{S}_{\mathcal{A} \perp} \oplus \mathcal{R}_{\mathcal{A} \perp}$ are the Wold decompositions of these isometries then

$$
\mathcal{K}=\mathcal{S} \oplus \mathcal{R}=\left(\mathcal{S}_{\mathcal{A}} \oplus \mathcal{S}_{\mathcal{A}^{\perp}}\right) \oplus\left(\mathcal{R}_{\mathcal{A}} \oplus \mathcal{R}_{\mathcal{A}^{+}}\right)
$$

is the Wold decomposition of the isometry $V$. Since $V \mid \mathcal{S}_{\mathcal{A}}$ is a shift operator the space $\mathcal{S}_{\mathcal{A}}$ can be expressed as

$$
\mathcal{S}_{\mathcal{A}}=\mathcal{M} \oplus V \mathcal{M} \oplus V^{2} \mathcal{M} \oplus \ldots
$$

where

$$
\mathcal{M}=\operatorname{ker}\left(V \mid \mathcal{S}_{\mathcal{A}}\right)^{*}=\operatorname{ker} V^{*}\left|\mathcal{S}_{\mathcal{A}} \subset \operatorname{ker} V^{*}\right| \mathcal{S}=V \ominus V \mathcal{S}
$$

Thus any subspace $\mathcal{A}$ which reduces the isometry $V$ has the form

$$
\mathcal{A}=\left(\mathcal{M} \oplus V \mathcal{M} \oplus V^{2} \mathcal{M} \oplus \ldots\right) \oplus \mathcal{R}_{\mathcal{A}}
$$

where $\mathcal{M}$ is a subspace of the generating subspace $V \ominus V \mathcal{S}$ and $\mathcal{R}_{\mathcal{A}}$ is a subspace of $\mathcal{R}$ which reduces $V$.

## References

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