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# ALMOST FLOQUET LINEAR DIFFERENCE EQUATIONS 

MILAN MEDVEĎ

The Floquet theorem for linear differential equations (see, e.g., [2] and [3]) is formulated as follows:

Theorem 1. Let $\Phi(t)$ be a fundamental matrix of the linear differential equation

$$
\begin{equation*}
\dot{x}=A(t) x \tag{1}
\end{equation*}
$$

where $x \in C^{n}, A: R \rightarrow M_{c}(n)\left(M_{c}(n)\right.$ is the set of matrices of type $n \times n$ with complex elements) is a piecewise continuous function which is $\tau$-periodic, i.e. $A(t+\tau)=A(t)$ for all $t \in R$. Then there exists a constant matrix $R$ and a $\tau$-periodic map $P: R \rightarrow M_{c}(n)$ such that

$$
\begin{equation*}
\Phi(t)=P(t) e^{R t} \quad \text { for all } \quad t \in R \tag{2}
\end{equation*}
$$

Is it possible to extend the class of matrices $A(t)$ of the system (1) for which a type of the Floquet theorem holds? This problem is solved in the papers [1], [4] and in the book [5]. A theorem analogical to the Floquet theorem (see, e.g., [7]) can also be formulated for linear difference equations as follows:

Theorem 2. Let $Y_{n}$ be the normed fundamental matrix of the linear $\tau$-periodic difference equation

$$
\begin{equation*}
y_{n+1}=A_{n} y_{n} \tag{3}
\end{equation*}
$$

(i.e. $A_{n+\tau}=A_{n}$ for all $n \geqq 0$ where $\tau$ is a natural number), i.e. $Y_{n+1}=A_{n} Y_{n}, n \geqq 0$, $Y_{0}=I$ - the unit matrix where all matrices $A_{n}, n \geqq 0$ are supposed to have complex elements. Then there exists a regular $\tau$-periodic, matrix valued function $T_{n}$ and a regular constant matrix $B$ such that

$$
\begin{equation*}
Y_{n}=T_{n} B^{n} \quad \text { for all } \quad n \geqq 0 . \tag{4}
\end{equation*}
$$

In the present paper we introduce a class of linear difference equations of the form (3) (nonperiodic in general) for which the normed fundamental matrix $Y_{n}$ ( $Y_{0}=I$ ) has the form (4) ( $T_{n}$ is not periodic in general). Results of such type are important for solving stability problems of linear as well as nonlinear difference
equations (see [7]). As a specimen of the application of our results we will prove a stability theorem concerning a linear perturbation of the difference system (3).
H. I. Freedman [4] has extended the Floquet theorem for the so-called almost Floquet systems (AFS) which are defined as follows: The system (1) is called an almost Floquet system if there exists a $\tau>0$ such that $[B(t, \tau), \Phi(t)]=0$ for all $t \in R$ where $[U, V]=U V-V U, \Phi(t)$ is a fundamental matrix of the system (1) and $B(t, \tau)=A(t+\tau)-A(t)$. Obviously, if the matrix function $A(t)$ is $\tau$-periodic, then the system (1) is almost a Floquet system.

Definition 1. Let all matrices $A_{n}, n \geqq 0$ in the equation (3) be regular, $\Phi_{n}$ be the normed fundamental matrix of this equation and let $\tau$ be a natural number. We shall say that the system (3) is a $\tau$-almost Floquet system ( $\tau$-AFS) if

$$
\begin{equation*}
\left[B_{n}(\tau), \Phi_{n}\right]=0 \tag{5}
\end{equation*}
$$

for all $n \geqq 0$ where $B_{n}(\tau)=A_{n}^{-1} A_{n+\tau}$ and $[U, V]=U V-V U$.
Obviously, if $A_{n+\tau}=A_{n}$ for all $n \geqq 0$, i.e. the equation (3) is $\tau$-periodic, then $B_{n}(\tau)=I$ for all $n \geqq 0$ and hence the condition (5) is satisfied. This means that every $\tau$-periodic system of difference equations of the form (3) with $A_{n}$ regular is a $\tau$-AFS.

Theorem 3. Let the system (3) be a $\tau$ - $\mathrm{AFS}, \Phi_{n}$ be its normed fundamental matrix and let $\Psi_{n}(\tau)$ be the normed fundamental matrix of the system

$$
\begin{equation*}
y_{n+1}=B_{n}(\tau) y_{n} . \tag{6}
\end{equation*}
$$

Then

$$
\begin{equation*}
\Phi_{n+\tau}=\Phi_{n} \Psi_{n}(\tau) \Phi_{\tau} \quad \text { for all } \quad n \geqq 0 \tag{7}
\end{equation*}
$$

Proof. Let us define $Y_{n}(\tau)=\Phi_{n}^{-1} \Phi_{n+\tau}, n \geqq 0$. Then

$$
Y_{n+1}(\tau)=\Phi_{n+1}^{-1} \Phi_{n+\tau+1}=\Phi_{n}^{-1} A_{n}^{-1} A_{n+\tau} \Phi_{n+\tau}=\left(\Phi_{n}^{-1} A_{n}^{-1} A_{n+\tau} \Phi_{n}\right) \Phi_{n}^{-1} \Phi_{n+\tau}
$$

From the equality (5) it follows that $\Phi_{n}^{-1} A_{n}^{-1} A_{n+\tau} \Phi_{n}=A_{n}^{-1} A_{n+\tau}=B_{n}(\tau)$ and thus we have $Y_{n+1}(\tau)=B_{n}(\tau) Y_{n}(\tau)$. Since $Y_{0}(\tau)=\Phi_{\tau}, \Psi_{0}(\tau)=I$ we obtain that $Y_{n}(\tau)=\Psi_{n}(\tau) \Phi_{\tau}$ and thus $\Phi_{n}^{-1} \Phi_{n+\tau}=\Psi_{n}(\tau) \Phi_{\tau}$, or $\Phi_{n+\tau}=\Phi_{n} \Psi_{n}(\tau) \Phi_{\tau}$.

Theorem 4. Let the system (3) be a $\tau$ - $\mathrm{AFS}, \Phi_{n}$ be its normed fundamental matrix and

$$
\begin{equation*}
\left[C(\tau), B_{n}(\tau)\right]=0 \quad \text { for all } \quad n \geqq 0 \tag{8}
\end{equation*}
$$

where $C(\tau)=\left(\Phi_{\tau}\right)^{1 / \tau}$. Then there exists a matrix function $T_{n}$ and a constant matrix B such that

$$
\begin{equation*}
\Phi_{n}=T_{n} B^{n} \tag{9}
\end{equation*}
$$

$$
\begin{equation*}
T_{n+\tau}=T_{n} \Psi_{n}(\tau) \tag{10}
\end{equation*}
$$

for all $n \geqq 0$ where $\Psi_{n} \tau$ ) is the normed fundamental matrix of the system (6). Moreover, $y_{n}=T_{n} x_{n}$ transforms the system (3) into the form

$$
\begin{equation*}
y_{n+1}=B y_{n} . \tag{11}
\end{equation*}
$$

We remark that the matrix $\Phi_{\tau}$ is regular and therefore from [6, Theorem 5. 4. 1] it follows that the matrix $C(\tau)=\left(\Phi_{\tau}\right)^{1 / \tau}$ is well defined.

If the system (3) is $\tau$-periodic, then the assumption (8) is satisfied, $\Psi_{n}(\tau)=I$ for all $n \geqq 0$ and thus the assertion of Theorem 4 is in coincidence with the assertion of Theorem 2.

Proof of Theorem 4. If we define $T_{n}=\Phi_{n} B^{-n}$ for $n \geqq 0$ where $B=$ $=C(\tau)$, then obviously $\Phi_{n}=T_{n} B^{n}$. Let $\omega_{n}=\left[B, \Psi_{n}(\tau)\right]$ where $\Psi_{n}(\tau)$ is the normed fundamental matrix of the system (6). The using the equality (8) we obtain that

$$
\begin{aligned}
\omega_{n+1} & =\left[B, \Psi_{n+1}(\tau)\right]=B \Psi_{n+1}(\tau)-\Psi_{n+1}(\tau) B= \\
& =B B_{n}(\tau) \Psi_{n}(\tau)-B_{n}(\tau) \Psi_{n}(\tau) B=B_{n}(\tau) B \Psi_{n}(\tau)- \\
& -B_{n}(\tau) \Psi_{n}(\tau) B=B_{n}(\tau) \omega_{n} .
\end{aligned}
$$

Since $\omega_{0}=\left[B, \Psi_{0}(\tau)\right]=0$, we obtain that $\left[B, \Psi_{n}(\tau)\right]=0$, i.e. $B \Psi_{n}(\tau)=\Psi_{n}(\tau) B$ for all $n \geqq 0$. This implies that

$$
\begin{equation*}
\Psi_{n}(\tau) B^{-n}=B^{-n} \Psi_{n}(\tau) \text { for all } n \geqq 0 \tag{12}
\end{equation*}
$$

Using (7) and (12) we obtain that

$$
\begin{aligned}
T_{n+\tau} & =\Phi_{n+\tau} B^{-n-\tau}=\Phi_{n} \Psi_{n}(\tau) \Phi_{\tau} B^{-\tau} B^{-n}= \\
& =\Phi_{n} \Psi_{n}(\tau) B^{\tau} B^{-\tau} B^{-n}=\Phi_{n} B^{-n} \Psi_{n}(\tau)=T_{n} \Psi_{n}(\tau),
\end{aligned}
$$

i.e. the equality (10) holds. If $y_{n}=T_{n} x_{n}$, then

$$
\left(T_{n+1}\right)^{-1} A_{n} T_{n}=\left(\Phi_{n+1} B^{-n} B^{-1}\right)^{-1} A_{n} \Phi_{n} B^{-n}=B \text { for all } n \geqq 0
$$

and thus the equality (11) holds.
Now we prove two theorems giving criteria for the system (3) to be a $\tau$-AFS, which are similar to these formulated by Freedman [4] for almost Floquet systems of differential equations.

Theorem 5. Let all matrices $A_{n}, n \geqq 0$ be regular, $\tau$ be a natural number and $\left[B_{m}(\tau), A_{n}\right]=0$ for all $m, n \geqq 0$ where $B_{m}(\tau)=A_{m}^{-1} A_{m+\tau}$. Then the system (3) is a $\tau$-AFS.

Proof. If we define $\alpha_{n}(m, \tau)=\left[B_{m}(\tau), \Phi_{n}\right]$ for $m, n \geqq 0$, then

$$
\begin{aligned}
\alpha_{n+1}(m, \tau) & =\left[B_{m}(\tau), \Phi_{n+1}\right]=B_{m}(\tau) A_{n} \Phi_{n}-A_{n} \Phi_{n} B_{m}(\tau)= \\
& =A_{n} B_{m}(\tau) \Phi_{n}-A_{n} \Phi_{n} B_{m}(\tau)=A_{n} \alpha_{n}(m, \tau) .
\end{aligned}
$$

Since $\alpha_{0}(m, \tau)=\left[B_{m}(\tau), I\right]=0$ for all $m \geqq 0$, we obtain that $\left[B_{m}(\tau), \Phi_{n}\right]=0$ for all $m, n \geqq 0$ and in particular $\left[B_{n}(\tau), \Phi_{n}\right]=0$ for all $n \geqq 0$, i.e. (3) is a $\tau$-AFS.

Theorem 6. Let all matrices $A_{n}, n \geqq 0$ be regular, $\tau$ be a natural number and let $B_{n}(\tau)=A_{n}^{-1} A_{n+\tau}$ be such that $\left[B_{n+i}(\tau), A_{n}\right]=0$ for all $n \geqq 0$ and $i=0,1, \ldots$, $\ldots, k$. Suppose that for any $n \geqq 0, B_{n}(\tau)$ satisfies the following difference equation:

$$
\begin{align*}
L_{n}\left(Z_{n}\right) & =C_{n}^{0} Z_{n+k}+C_{n}^{1} Z_{n+k-1}+\ldots+C_{n}^{k} Z_{n}+Z_{n+k} D_{n}^{0}+  \tag{13}\\
& +Z_{n+k-1} D_{n}^{1}+\ldots+Z_{n} D_{n}^{k}=F_{n}
\end{align*}
$$

where the matrices $C_{n}^{i}, D_{n}^{i}, F_{n}, i=0,1, \ldots, k$ commute with the normed fundamental matrix $\Phi_{n}$ of the system (3). Then the system (3) is a $\tau$-AFS.

Proof. Let $U_{n}(\tau)=\Phi_{n}^{-1} B_{n}(\tau) \Phi_{n}$ for $n \geqq 0$. Since $B_{n+1}(\tau) A_{n}=A_{n} B_{n+1}(\tau)$, we have that

$$
\begin{aligned}
U_{n+1}(\tau) & =\Phi_{n+1}^{-1} B_{n+1}(\tau) \Phi_{n+1}=\Phi_{n}^{-1} A_{n}^{-1} B_{n+1}(\tau) A_{n} \Phi_{n}= \\
& =\Phi_{n}^{-1} B_{n+1} \Phi_{n} .
\end{aligned}
$$

One can easily show by induction that

$$
\begin{equation*}
U_{n+i}(\tau)=\Phi_{n}^{-1} B_{n+i} \Phi_{n} \quad \text { for } \quad i=0,1, \ldots, k . \tag{14}
\end{equation*}
$$

Therefore from the commutability hypothesis we get

$$
L_{n}\left(U_{n}(\tau)\right)=\Phi_{n}^{-1} L_{n}\left(B_{n}(\tau)\right) \Phi_{n}=\Phi_{n}^{-1} F_{n} \Phi_{n}=F_{n}
$$

i.e. $U_{n}(\tau)$ is a solution of the difference equation (13) with the same initial conditions as $B_{n}(\tau)$ and hence $U_{n}(\tau)=B_{n}(\tau)$, or $\left[B_{n}(\tau), \Phi_{n}\right]=0$ for all $n \geqq 0$, i.e. (3) is a $\tau$-AFS.

Example. Let $B_{n}(\tau)=B_{0}$, i.e. $A_{n+\tau}=B_{0} A_{n}$ for all $n \geqq 0$, where $\tau$ is a natural number, $B_{0}$ is a constant matrix and assume that

$$
\begin{equation*}
\left[B_{0}, A_{n}\right]=0 \quad \text { for all } n \geqq 0 \tag{15}
\end{equation*}
$$

Then by Theorem 5 the system (3) is a $\tau$-AFS. Since the normed fundamental matrix of the system (6) with $B_{n}(\tau)=B_{0}$ is $\Psi_{n}(\tau)=B_{0}^{n}$, Theorem 3 implies the equality

$$
\begin{equation*}
\Phi_{n+\tau}=\Phi_{n} B_{0}^{n} \Phi_{\tau} \text { for all } n \geqq 0 \tag{16}
\end{equation*}
$$

where $\Phi_{n}$ is the normed fundamental matrix of the system (3). Using Theorem 3 and the equality (16) one can show by induction that

$$
\begin{equation*}
\Phi_{n+m \tau}=\Phi_{n} B_{0}^{n+\frac{1}{2} m(m-1) \tau} B^{m \tau} \text { for all } m, n \geqq 0 \tag{17}
\end{equation*}
$$

where $B=\left(\Phi_{\tau}\right)^{1 / \tau}$. This formula implies that the stability properties of the system
(3) substantially depend on whether the matrices $B_{0}$ and $B$ have eigenvalues inside or outside the unit circle.

As a specimen of application of the previous results we prove a theorem concerning a linear perturbation of the system (3). To state the theorem and give its proof we need to introduce one notion and then to prove a lemma.

Definition 2. A norm $\|\cdot\|$ on $R^{n}$ is called adapted to given continuous linear maps $P_{i}: R^{n} \rightarrow R^{n}, i=1,2$, if $\left\|P_{i}\right\| \leqq \max (\sigma, \varrho), i=1,2$ where $\sigma=\max \left(\left|\lambda_{1}\right|,\left|\lambda_{2}\right|, \ldots\right.$, $\left.\ldots,\left|\lambda_{n}\right|\right), \varrho=\max \left(\left|v_{1}\right|,\left|v_{2}\right|, \ldots,\left|v_{n}\right|\right), \lambda_{i}, v_{i}, i=1,2, \ldots, n$, are eigenvalues of $P_{1}$ and $P_{2}$, respectively and $\|S\|=\sup _{\|x\| \leqq 1}\|S x\|$.

Lemma 1. Let two linear and continuous maps $P_{i}: R^{n} \rightarrow R^{n}, i=1,2$, be given. Then there exists a norm on $R^{n}$ adapted to these maps.

Proof. By [8, p. 312] there exist norms $\|\cdot\|_{1},\|\cdot\|_{2}$ on $R^{n}$ such that $\left\|P_{1}\right\|_{1}=$
$=\sigma$ and $\left\|P_{2}\right\|_{2}=\varrho$ where $\|S\|_{1}=\sup _{\|x\| \leqq 1}\|S x\|, i=1,2$. The function $x \rightarrow \max$. $\cdot\left(\|x\|_{1},\|x\|_{2}\right)$ is the wanted norm on $R^{n}$.

Theorem 7. Let the system (3) be a $\tau$-AFS with $B_{n}=A_{n}^{-1} A_{n+\tau}=B_{0}$ for all $n \geqq 0$ where $B_{0}$ is a constant matrix. Assume that the matrices $B=\left(\Phi_{\tau}\right)^{1 / \tau}$ and $B_{0}$ have all their eigenvalues inside the open unit circle where $\Phi_{n}$ is the normed fundamental matrix of the system (3) and let $\left[B, B_{0}\right]=0$. Then the system

$$
\begin{equation*}
x_{n+1}=\left(A_{n}+D_{n}\right) x_{n} \tag{18}
\end{equation*}
$$

is asymptotically stable provided

$$
\begin{equation*}
\sum_{n=0}^{\infty} k^{\gamma(n)-\gamma(n+1)}\left\|D_{n}\right\|<\infty \tag{19}
\end{equation*}
$$

where $k=\max (\sigma, \varrho), \sigma=\max \left(\left|\lambda_{1}\right|,\left|\lambda_{2}\right|, \ldots,\left|\lambda_{n}\right|\right), \varrho=\max \left(\left|v_{1}\right|,\left|v_{2}\right|, \ldots,\left|v_{n}\right|\right)$, $\lambda_{i}, v_{i}, i=1,2, \ldots, n$ are eigenvalues of $B$ and $B_{0}$, respectively, $\|\cdot\|$ is a norm on $R^{n}$ adapted to the maps $B$ and $B_{0}, \gamma(n)=\beta(n) \tau+\frac{1}{2} \beta(n)[\beta(n)-1] \tau$ where $\alpha: N \rightarrow N \cap[0, \tau)$ and $\beta: N \rightarrow N$ are such functions defined on the set $N$ of natural numbers that any $n \in N$ can be written as $n=\alpha(n)+\beta(n) \tau$.

Proof. By [7, p. 36] the solution of the nonhomogeneous difference equation

$$
\begin{equation*}
x_{n+1}=A_{n} x_{n}+f_{n} \tag{20}
\end{equation*}
$$

satisfying the initial condition $x_{n_{0}}=\xi$ has the form

$$
\begin{equation*}
x_{n}=\Phi_{n} \Phi_{n_{0}}^{-1} \xi+\sum_{v=0}^{n-1} \Phi_{n} \Phi_{v+1}^{-1} f_{v} \tag{21}
\end{equation*}
$$

By this variation of the constant formula we can write the solution $x_{n}$ of (18) satisfying the condition $x_{n_{0}}=\xi$ as

$$
\begin{equation*}
x_{n}=\Phi_{n} \Phi_{n_{0}}^{-1} \xi+\sum_{v=0}^{n-1} \Phi_{n} \Phi_{v+1}^{-1} D_{v} x_{v} \tag{22}
\end{equation*}
$$

Let $M_{1}=\max _{0 \leqq n \leqq \tau}\left\|\Phi_{n}\right\|$ and $M_{2}=\max _{0 \leqq n \leqq \tau}\left\|\Phi_{n}^{-1}\right\|$ where $\|\cdot\|$ is a norm on $R^{n}$ adapted to the maps $B$ and $B_{0}$. By Lemma 1 such an adapted norm on $R^{n}$ exists. Using the equality (17) and the assumption $\left[B, B_{0}\right]=B B_{0}-B_{0} B=0$ we obtain that for any $m, n \geqq 0$

$$
\Phi_{n} \Phi_{m}^{-1}=\Phi_{\alpha(n)} B_{0}^{\alpha(n)+\frac{1}{2} \beta(n)[\beta(n)-1] \tau} \cdot B^{\beta(n) \tau} \cdot B^{-\beta(m) \tau} \cdot B_{0}^{-\alpha(m)-\frac{1}{2} \beta(m)[\beta(m)-1] \tau} \cdot \Phi_{\alpha(m)}^{-1},
$$

i.e.

$$
\begin{equation*}
\Phi_{n} \Phi_{m}^{-1}=\Phi_{\alpha(n)} B_{0}^{\alpha(n)-\alpha(m)} \cdot B^{[\beta(n)-\beta(m)] \tau} \cdot B_{0}^{\delta(n)-\delta(m)} \Phi_{\alpha(m)}^{-1} \tag{23}
\end{equation*}
$$

where the functions $\alpha, \beta$ are as in theorem and $\delta(i)=\frac{1}{2} \beta(i)[\beta(i)-1] \tau$. Since $\left\|B_{0}\right\| \leqq k<1$ and $\|B\| \leqq k<1$, we obtain from (23) that

$$
\begin{equation*}
\left\|\Phi_{n} \Phi_{m}^{-1}\right\| \leqq M_{1} M_{2} \cdot k^{\gamma(n)-\gamma(m)} \quad \text { for all } \quad m, n \geqq 0, n \geqq m \tag{24}
\end{equation*}
$$

where the function $\gamma$ is as in the theorem. Substituting (24) in (22) gives

$$
\left\|x_{n}\right\| \leqq M_{1} M_{2} \cdot k^{\gamma(n)-\gamma\left(n_{0}\right)}+\sum_{v=0}^{n-1} M_{1} M_{2} \cdot k^{\gamma(n)-\gamma(v+1)}\left\|D_{v}\right\|\left\|x_{v}\right\|
$$

for all $n \geqq n_{0}$ and this implies that

$$
k^{-\gamma(n)}\left\|x_{n}\right\| \leqq M_{1} M_{2} \cdot k^{-\gamma\left(n_{0}\right)}+\sum_{v=0}^{n-1} M_{1} M_{2} \cdot k^{\gamma(v)-\gamma(v+1)}\left\|D_{v}\right\|\left(k^{-\gamma(v)}\left\|x_{v}\right\|\right)
$$

From [7, Corollary 1], which is an analogy of the Gronwall inequality, it follows that

$$
k^{-\gamma(n)}\left\|x_{n}\right\| \leqq M_{1} M_{2} \cdot k^{-\gamma\left(n_{0}\right)} \cdot \exp \left[M_{1} M_{2}\left(\sum_{v=0}^{n-1} k^{\gamma(v)-\gamma(v+1)}\left\|D_{v}\right\|\right)\right]
$$

for all $n \geqq n_{0}$ and thus we have

$$
\begin{equation*}
\left\|x_{n}\right\| \leqq M \cdot k^{\gamma(n)} \quad \text { for all } \quad n \geqq n_{0} \tag{25}
\end{equation*}
$$

where $M=M_{1} M_{2} \cdot k^{-\gamma\left(n_{0}\right)} \cdot \exp \left[M_{1} M_{2}\left(\sum_{v=0}^{\infty} k^{\gamma(v)-\gamma(v+1)}\left\|D_{v}\right\|\right)\right]$. The assumption (19) implies that $M<\infty$. Therefore the theorem follows from the inequality (25).

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## СИСТЕМЫ ЛИНЕЙНЫХ РАЗНОСТНЫХ УРАВНЕНИИ ПОЧТИ ФЛОКЕ Milan Medved

## Резюме

В статье введен класс разностных линейных систем почти Флоке и доказано обобщение теоремы Флоке для линейных разностных систем. Использованием этой теоремы доказана одна теорема об устойчивости, которая касается линейного возмущения данной разностной системы почти Флоке.

