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# ON THE UNIQUE SOLVABILITY OF SEMI-LINEAR ELLIPTIC SYSTEMS 

Jaroslav Jaroš<br>(Communicated by Milan Medved')


#### Abstract

In this paper, we study the unique solvability of semi-linear elliptic systems of partial differential equations. Our method of the proof is based on the Banach fixed point theorem.


## 1. Introduction

In this paper, we study the unique solvability of semi-linear elliptic systems of partial differential equations of the form

$$
\begin{align*}
-\Delta u & =f(x, u, \nabla u) & & \text { in } \quad \Omega  \tag{b}\\
u & =0 & & \text { on } \quad \partial \Omega
\end{align*}
$$

where $\Omega$ is a smooth bounded domain in $\mathbb{R}^{n}, u: \bar{\Omega} \rightarrow \mathbb{R}^{M}, f: \Omega \times \mathbb{R}^{M}$ $\times \mathbb{R}^{M n} \rightarrow \mathbb{R}^{M}$.

It is known that the system (b) possesses multiple solutions if the nonlinearity $f$ interacts suitably with the spectrum of the operator $-\Delta_{D}$ (i.e., the operator $-\Delta$ with a homogeneous Dirichlet boundary condition) (see, e.g., $[\mathrm{AZ}]$ or $[\mathrm{H}]$ ). In this paper, we are concerned with the complementary case, where $f$ does not interact with this spectrum.

In his paper $[A], H$. A mann has given unique solvability results for semilinear systems in the case, where $f$ does not interact with the spectrum of $-\Delta_{D}$, and $f$ does not depend on the gradient:

$$
\begin{align*}
-\Delta u & =f(x, u) & & \text { in } \quad \Omega  \tag{a}\\
u & =0 & & \text { on } \quad \partial \Omega .
\end{align*}
$$

[^0]The gradient-dependent case $(b)$ is studied in [QŽ] for a single equation $(M=1)$. In this paper, $f$ satisfies
i) $a \leq \frac{f\left(x, u_{1}, p\right)-f\left(x, u_{2}, p\right)}{u_{1}-u_{2}} \leq b, \quad(a, b) \cap \sigma\left(-\Delta_{D}\right)=\emptyset$,
ii) $\left|f\left(x, u, p_{1}\right)-f\left(x, u, p_{2}\right)\right| \leq c\left|p_{1}-p_{2}\right|$, where $c>0$ is sufficiently small. The method of proof is based on the Banach fixed point theorem: it is shown that the mapping $w \mapsto u$, where $u$ is the weak solution of the problem

$$
\begin{aligned}
-\Delta u & =f(x, u, \nabla w) & & \text { in } \quad \Omega \\
u & =0 & & \text { on } \quad \partial \Omega
\end{aligned}
$$

is a contraction.
Our method of proof of unique solvability of $(b)$ is analogous to that in [QŽ], but the estimates are carried out in a more precise way. Moreover, using the uniform contraction theorem, we show the continuous dependence of solutions of systems of the form

$$
\begin{align*}
-\Delta u & =f(x, u, \nabla u, \lambda) & & \text { in } \quad \Omega \\
u & =0 & & \text { on } \partial \Omega
\end{align*}
$$

on the parameter $\lambda$. Our main result is formulated in Theorem 4.4.

## 2. Preliminaries

Let us first introduce some notation. By $\mathbb{R}$ we shall denote the set of all reals. $\Omega \subset \mathbb{R}^{n}$, for some $n \geq 1$, is a bounded domain with smooth boundary $\partial \Omega\left(C^{2}\right)$. For $p_{j}=\left(p_{j}^{1}, \ldots, p_{j}^{s}\right) \in \mathbb{R}^{s}, j=1,2$, we define the scalar product $\left(p_{1}, p_{2}\right)_{\mathbb{R}^{s}}=\sum_{i=1}^{s} p_{1}^{i} p_{2}^{i}$. The Lebesgue space $L_{2}\left(\Omega, \mathbb{R}^{M}\right)$ will be equipped with the usual scalar product $(u, v)_{0}=\int_{\Omega}(u(x), v(x))_{\mathbb{R}^{M}} \mathrm{~d} x$, while the Sobolev space $H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right)$ will be equipped with the scalar product

$$
\begin{aligned}
(u, v)_{1} & =\sum_{i=1}^{n}\left(\frac{\partial}{\partial x_{i}} u, \frac{\partial}{\partial x_{i}} v\right)_{0} \\
& =\sum_{i=1}^{n}\left(\left(\frac{\partial u_{1}}{\partial x_{i}}, \ldots, \frac{\partial u_{M}}{\partial x_{i}}\right),\left(\frac{\partial v_{1}}{\partial x_{i}}, \ldots, \frac{\partial v_{M}}{\partial x_{i}}\right)\right)_{0}
\end{aligned}
$$

The corresponding norms will be denoted by $|\cdot|_{\mathbb{R}^{s}},\|\cdot\|_{0}$ and $\|\cdot\|_{1}$, respectively. We define now a linear operator $A_{0}: \operatorname{dom}\left(A_{0}\right) \subset L_{2}(\Omega, \mathbb{R}) \rightarrow L_{2}(\Omega, \mathbb{R})$ by

$$
\begin{aligned}
\operatorname{dom}\left(A_{0}\right) & =H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right) \cap H^{2}\left(\Omega, \mathbb{R}^{M}\right) \quad \text { and } \\
A_{0} u & :=-\sum_{i=1}^{n} \frac{\partial^{2} u}{\partial x_{i}^{2}} \quad \text { for } \quad u \in \operatorname{dom}\left(A_{0}\right) .
\end{aligned}
$$

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It is well known that $A_{0}$ is self-adjoint, that it has a compact resolvent and that the spectrum of $A_{0}, \sigma\left(A_{0}\right)=\left\{\lambda_{i}\right\}_{i=1}^{\infty}$, where $0<\lambda_{1} \leq \lambda_{2} \leq \ldots$ and $\lambda_{i} \rightarrow \infty$. Let $\left\{\varphi_{i}\right\}_{i=1}^{\infty}$ be the corresponding sequence of eigenfunctions, which we assume to be normalized in $L_{2}(\Omega, \mathbb{R})$, i.e.,

$$
\left\|\varphi_{i}\right\|_{L_{2}(\Omega, \mathbb{R})}^{2}=\int_{\Omega} \varphi_{i}^{2} \mathrm{~d} x=1, \quad i=1,2, \ldots
$$

Thus it forms an orthonormal base in $L_{2}(\Omega, \mathbb{R})$ and it is also a complete orthogonal set in $H_{0}^{1}(\Omega, \mathbb{R})$ such that

$$
\left\|\varphi_{i}\right\|_{H_{0}^{1}(\Omega, \mathbb{R})}^{2}=\int_{\Omega}\left(\nabla \varphi_{i}, \nabla \varphi_{i}\right)_{\mathbb{R}^{n}} \mathrm{~d} x=\lambda_{i}, \quad i=1,2, \ldots
$$

Finally we define a self-adjoint linear operator with compact resolvent:

$$
A: \operatorname{dom}(A) \subset L_{2}\left(\Omega, \mathbb{R}^{M}\right) \rightarrow L_{2}\left(\Omega, \mathbb{R}^{M}\right)
$$

for some $M \geq 1$ by:

$$
\operatorname{dom}(A):=\left[\operatorname{dom}\left(A_{0}\right)\right]^{M} \quad \text { and } \quad A:=\operatorname{diag}\left(A_{0}, \ldots, A_{0}\right)
$$

Now we suppose that the function $f: \Omega \times \mathbb{R}^{M} \times \mathbb{R}^{M n} \rightarrow \mathbb{R}^{M}$ satisfies the hypothesis $(\mathrm{H})$ :
$(\mathrm{H})\left\{\begin{array}{l}\quad\left|f\left(x, u_{1}, p_{1}\right)-f\left(x, u_{2}, p_{2}\right)\right|_{\mathbb{R}^{M}} \leq c_{1}\left|u_{1}-u_{2}\right|_{\mathbb{R}^{M}} \\ \quad \text { for a.a. } x \in \Omega \text { and all } u_{1}, u_{2} \in \mathbb{R}^{M} \text { and } p_{1}, p_{2} \\ \text { iii) } \quad f(\cdot, 0,0) \in L_{2}\left(\Omega, \mathbb{R}^{M}\right) .\end{array}\right.$
Then, by a weak solution of the semi-linear elliptic system

$$
\begin{aligned}
-\Delta u & =f(x, u, \nabla u) & & \text { in } \quad \Omega \\
u & =0 & & \text { on } \quad \partial \Omega
\end{aligned}
$$

we mean a function $u \in H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right)$ such that

$$
\begin{gathered}
\sum_{i=1}^{n} \int_{\Omega}\left(\frac{\partial u}{\partial x_{i}}, \frac{\partial v}{\partial x_{i}}\right)_{\mathbb{R}^{M}} \mathrm{~d} x=\int_{\Omega}(f(x, u, \nabla u), v)_{\mathbb{R}^{M}} \mathrm{~d} x \\
\text { for all } \quad v \in H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right)
\end{gathered}
$$

We get from standard regularity theory that $u \in H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right) \cap H^{2}\left(\Omega, \mathbb{R}^{M}\right)$ and $u$ is a solution of the operator equation

$$
A u=F(u)
$$

where $F$ is the Nemytskii operator corresponding to $f$.

## 3. Apriori estimates

We introduce the following hypothesis:
(i) $h: \Omega \times \mathbb{R}^{M} \rightarrow \mathbb{R}^{M}$ is a Caratheodory function such that $h(x, \cdot) \in C^{1}\left(\mathbb{R}^{M}, \mathbb{R}^{M}\right)$ with a symmetric derivative $\mathrm{D}_{2} h(x, u):=$ $\frac{\partial}{\partial u} h(x, u)$ for a.a. $x \in \Omega$ and all $u \in \mathbb{R}^{M}$.
ii) There exist two symmetric $M \times M$-matrices $B^{+}, B^{-}$such that

$$
\begin{equation*}
B^{-} \leq \mathrm{D}_{2} h(x, u) \leq B^{+} \quad \text { and } \quad \bigcup_{i=1}^{M}\left[\mu_{i}^{-}, \mu_{i}^{+}\right] \cap \sigma(A)=\emptyset \tag{H1}
\end{equation*}
$$

where $\mu_{1}^{ \pm} \leq \mu_{2}^{ \pm} \leq \cdots \leq \mu_{M}^{ \pm}$are the eigenvalues of the matrices $B^{ \pm}$, respectively.
iii) $h(\cdot, 0) \in L_{2}\left(\Omega, \mathbb{R}^{M}\right)$.

The inequalities in ii) are to be understood in the sense that $B^{+} \geq B^{-}$means that $B^{+}-B^{-}$is positive semi-definite. From [VK; p. 109, Courant-Fischer theorem], we have the equalities $\mu_{i}^{ \pm}=\min _{\substack{\operatorname{dim}(V)=i \\ V \subset \mathbb{R}^{M}}} \max _{\substack{x \neq 0 \\ x \in V}} \frac{\left(B^{ \pm} x, x\right)}{(x, x)}$ for $i=1, \ldots, M$, which implies the inequalities $\mu_{i}^{-} \leq \mu_{i}^{+}$for $i=1, \ldots, M$.

Now we put

$$
\begin{align*}
& \nu:=\min \left\{\lambda_{i} \mid \lambda_{i} \in \sigma(A), \quad \lambda_{i}>\mu_{M}^{+}\right\} \\
& \varepsilon:= \begin{cases}\operatorname{dist}\left(\bigcup_{i=1}^{M}\left[\mu_{i}^{-}, \mu_{i}^{+}\right], \sigma(A)\right) & \text { for } \mu_{M}^{+} \geq 0 \\
\lambda_{1} & \text { for } \mu_{M}^{+}<0\end{cases} \tag{3.1}
\end{align*}
$$

Recall that (H1) ii) implies $\varepsilon>0$.
Let us formulate the apriori estimates lemma:
LEMMA 3.1. Let $B: \Omega \times \mathbb{R}^{M} \rightarrow \mathbb{R}^{M}$ satisfy $(\mathrm{H} 1)$ with $h$ replaced by $B$ and $B(x, 0)=0$ for a.a. $x \in \Omega$. Let $f: \Omega \times \mathbb{R}^{M} \rightarrow \mathbb{R}^{M}$ be a Caratheodory function, and let there exist $0 \leq \gamma<\frac{\varepsilon}{2}\left(\varepsilon\right.$ as in (3.1)) and $\rho \in L_{2}(\Omega, \mathbb{R})$ such that:

$$
\begin{equation*}
|f(x, u)|_{\mathbb{R}^{M}} \leq \gamma|u|_{\mathbb{R}^{M}}+\rho(x) \tag{3.2}
\end{equation*}
$$

for a.a. $x \in \Omega$ and all $u \in \mathbb{R}^{M}$. Let $z \in H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right) \cap H^{2}\left(\Omega, \mathbb{R}^{M}\right)$ be a solution of the equation

$$
\begin{equation*}
A z=G(z) \tag{3.3}
\end{equation*}
$$

where $G$ denotes the Nemytskii operator corresponding to $B+f$. Then

$$
\begin{equation*}
\|z\|_{0} \leq \frac{\|\rho\|_{0}}{\frac{\varepsilon}{2}-\gamma} \tag{3.4}
\end{equation*}
$$

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and

$$
\begin{equation*}
\|z\|_{1} \leq \frac{\sqrt{\nu}}{\frac{\epsilon}{2}-\gamma}\|\rho\|_{0} \tag{3.5}
\end{equation*}
$$

Proof. It is obvious that $\sigma(A)=\sigma\left(A_{0}\right)$. We put $H:=L_{2}\left(\Omega, \mathbb{R}^{M}\right)$ and

$$
\begin{gathered}
\sigma_{H^{-}}:=\left\{\lambda_{i} \in \sigma(A): \lambda_{i}<\mu_{1}^{-}\right\}, \quad \sigma_{H^{+}}:=\left\{\lambda_{i} \in \sigma(A): \mu_{M}^{+}<\lambda_{i}\right\} \\
\sigma_{Z}:=\left\{\lambda_{i} \in \sigma(A): \mu_{1}^{-}<\lambda_{i}<\mu_{M}^{+}\right\} .
\end{gathered}
$$

Let $H=H^{-} \oplus Z \oplus H^{+}$be the orthogonal decomposition of $H$ corresponding to the decomposition of the spectrum $\sigma(A)=\sigma_{H^{-}} \cup \sigma_{Z} \cup \sigma_{H^{+}}$. Let $e_{i}^{ \pm}$(for $i=1, \ldots, M)$ be the eigenvectors of $B^{ \pm}$corresponding to $\mu_{i}^{ \pm}$, respectively. We now put

$$
\begin{align*}
Z^{-} & =\operatorname{span}\left\{\varphi_{i} e_{j}^{-}: \mu_{1}^{-}<\lambda_{i}<\mu_{j}^{-}, \quad i \in \mathbb{N}, \quad j=1,2, \ldots, M\right\}  \tag{3.6}\\
Z^{+} & =\operatorname{span}\left\{\varphi_{i} e_{j}^{+}: \mu_{j}^{+}<\lambda_{i}<\mu_{M}^{+}, \quad i \in \mathbb{N}, \quad j=1,2, \ldots, M\right\}
\end{align*}
$$

Thus we have

$$
\begin{array}{lll}
\left(\left(A-B^{-}\right) u, u\right)_{0}<0 & \text { for all } & u \in Z^{-} \backslash\{0\} \\
\left(\left(A-B^{+}\right) u, u\right)_{0}>0 & \text { for all } & u \in Z^{+} \backslash\{0\}
\end{array}
$$

hence $Z^{+} \cap Z^{-}=\{0\}$. It also follows from (3.6) that $\operatorname{dim} Z=\operatorname{dim} Z^{+}+\operatorname{dim} Z^{-}$. Consequently,

$$
Z=Z^{+} \oplus Z^{-}
$$

Putting $X^{-}:=H^{-} \oplus Z^{-}$and $X^{+}:=H^{+} \oplus Z^{+}$we get the decomposition of $H$

$$
H=X^{+} \oplus X^{-}
$$

In $X^{+}, X^{-}$, we can choose the orthonormal bases

$$
\begin{aligned}
& \left\{\psi_{i j}^{-}=\varphi_{i} e_{j}^{-}: \lambda_{i}<\mu_{j}^{-}, \quad i \in \mathbb{N}, \quad j=1,2, \ldots, M\right\} \\
& \left\{\psi_{i j}^{+}=\varphi_{i} e_{j}^{+}: \lambda_{i}>\mu_{j}^{+}, \quad i \in \mathbb{N}, \quad j=1,2, \ldots, M\right\}
\end{aligned}
$$

respectively. Let $z \in H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right) \cap H^{2}\left(\Omega, \mathbb{R}^{M}\right)$ be a solution of (3.3). We have $z=z^{-}+z^{+}$, where $z^{ \pm} \in X^{ \pm}$respectively. Define also $\tilde{z}=-z^{-}+z^{+}$. For a.a. $x \in \Omega$, the mean value theorem implies the existence of $\xi(x) \in \mathbb{R}^{M}$ such that

$$
\begin{equation*}
A z(x)=B(x, z(x))+f(x, z(x))=\mathrm{D}_{2} B(x, \xi(x)) z(x)+f(x, z(x)) \tag{3.7}
\end{equation*}
$$

Since by (H1) i) $S(x):=\mathrm{D}_{2} B(x, \xi(x))$ is a symmetric $M \times M$-matrix, we get from (H1) ii) that

$$
\begin{align*}
(S(x) z(x), \tilde{z}(x))_{\mathbb{R}^{M}} & =\left(S(x) z^{+}(x), z^{+}(x)\right)_{\mathbb{R}^{M}}-\left(S(x) z^{-}(x), z^{-}(x)\right)_{\mathbb{R}^{M}} \\
& \leq\left(B^{+} z^{+}(x), z^{+}(x)\right)_{\mathbb{R}^{M}}-\left(B^{-} z^{-}(x), z^{-}(x)\right)_{\mathbb{R}^{M}} \tag{3.8}
\end{align*}
$$

for a.a. $x \in \Omega$. Testing the equation (3.7) by $\tilde{z}$ and using (3.2), (3.8) we get

$$
\begin{align*}
(A z, \tilde{z})_{0} & =\left(A z^{+}, z^{+}\right)_{0}-\left(A z^{-}, z^{-}\right)_{0}  \tag{3.9}\\
& \leq\left(B^{+} z^{+}, z^{+}\right)_{0}-\left(B^{-} z^{-}, z^{-}\right)_{0}+\gamma\|z\|_{0}\|\tilde{z}\|_{0}+\|\rho\|_{0}\|\tilde{z}\|_{0}
\end{align*}
$$

Let $z=\sum \bar{\sum} z_{i j}^{-} \psi_{i j}^{-}+\sum^{+} z_{i j}^{+} \psi_{i j}^{+}, z_{i j}^{ \pm} \in \mathbb{R}$, be the Fourier series of $z$ with respect to the base $\left\{\psi_{i j}^{-}\right\} \cup\left\{\psi_{i j}^{+}\right\}$in $L_{2}\left(\Omega, \mathbb{R}^{M}\right)$, where $\sum=\sum_{\substack{i \in \mathbb{N} \\ j=1, \ldots, M \\ \lambda_{i}<\mu_{j}^{-}}}$and $\sum \sum \sum_{\substack{i \in \mathbb{N} \\ j=1, \ldots, M \\ \lambda_{i}>\mu_{j}^{+}}}$. Then

$$
\begin{align*}
\varepsilon\left(\left\|z^{-}\right\|_{0}^{2}+\left\|z^{+}\right\|_{0}^{2}\right) & \leq \sum^{+}\left(\lambda_{i}-\mu_{j}^{+}\right) z_{i j}^{+2}+\sum^{-}\left(\mu_{j}^{-}-\lambda_{i}\right) z_{i j}^{-2} \\
& =\left(\left(A-B^{+}\right) z^{+}, z^{+}\right)_{0}-\left(\left(A-B^{-}\right) z^{-}, z^{-}\right)_{0}  \tag{3.10}\\
& \leq \gamma\|z\|_{0}\|\tilde{z}\|_{0}+\|\rho\|_{0}\|\tilde{z}\|_{0}
\end{align*}
$$

Now, since

$$
\begin{align*}
\left\|z^{+} \pm z^{-}\right\|_{\alpha}^{2} & =\left\|z^{+}\right\|_{\alpha}^{2} \pm 2\left(z^{+}, z^{-}\right)_{\alpha}+\left\|z^{-}\right\|_{\alpha}^{2} \\
& \leq\left\|z^{+}\right\|_{\alpha}^{2}+2\left\|z^{+}\right\|_{\alpha}\left\|z^{-}\right\|_{\alpha}+\left\|z^{-}\right\|_{\alpha}^{2}  \tag{3.11}\\
& \leq 2\left(\left\|z^{+}\right\|_{\alpha}^{2}+\left\|z^{-}\right\|_{\alpha}^{2}\right)
\end{align*}
$$

(for $\alpha=0$ or 1 ), we get from (3.10)

$$
\frac{\varepsilon}{2}\|z\|_{0}\|\tilde{z}\|_{0} \leq \gamma\|z\|_{0}\|\tilde{z}\|_{0}+\|\rho\|_{0}\|\tilde{z}\|_{0}
$$

which implies (3.4). Using the Young inequality $a b \leq \frac{a^{2}}{4 s}+s b^{2}$ and (3.11) we have from (3.10)

$$
\begin{equation*}
\sum^{+}\left(\lambda_{i}-\mu_{j}^{+}\right) z_{i j}^{+2}+\sum^{-}\left(\mu_{j}^{-}-\lambda_{i}\right) z_{i j}^{-2} \leq 2(\gamma+s)\left(\left\|z^{+}\right\|_{0}^{2}+\left\|z^{-}\right\|_{0}^{2}\right)+\frac{\|\rho\|_{0}^{2}}{4 s} \tag{3.12}
\end{equation*}
$$

for arbitrary $s \in\left(0, \frac{\varepsilon}{2}-\gamma\right)$. Hence,

$$
\sum^{+}\left[\frac{\lambda_{i}-\mu_{j}^{+}-2 \gamma-2 s}{\lambda_{i}}\right] \lambda_{i} z_{i j}^{+2}+\sum^{-}\left[\frac{\mu_{j}^{-}-\lambda_{i}-2 \gamma-2 s}{\lambda_{i}}\right] \lambda_{i} z_{i j}^{-2} \leq \frac{\|\rho\|_{0}^{2}}{4 s}
$$

Since

$$
\begin{aligned}
& {\left[\frac{\lambda_{i}-\mu_{j}^{+}-2 \gamma-2 s}{\lambda_{i}}\right] \geq \frac{\varepsilon-2(\gamma+s)}{\nu} \quad \text { for } \quad \lambda_{i}>\mu_{j}^{+} \text {, }} \\
& {\left[\frac{\mu_{j}^{-}-\lambda_{i}-2 \gamma-2 s}{\lambda_{i}}\right] \geq \frac{\varepsilon-2(\gamma+s)}{\nu} \quad \text { for } \quad \lambda_{i}<\mu_{j}^{-},}
\end{aligned}
$$

we get, using (3.11),

$$
\frac{\varepsilon-2(\gamma+s)}{2 \nu}\|z\|_{1}^{2} \leq \frac{\|\rho\|_{0}^{2}}{4 s} .
$$

Thus we have the inequality

$$
\|z\|_{1}^{2} \leq \min _{s \in\left(0, \frac{\varepsilon}{2}-\gamma\right)} \frac{\nu}{4 s\left[\left(\frac{\varepsilon}{2}-\gamma\right)-s\right]}\|\rho\|_{0}^{2}
$$

which implies (3.5).

## 4. Unique solvability results

In the following, we shall use the result of H . A mann [A; p. 166, Theorem 4.2] on the unique solvability of nonlinear elliptic systems.

LEMMA 4.1. Suppose that the function $g: \Omega \times \mathbb{R}^{M} \rightarrow \mathbb{R}^{M}$ satisfies (H1) with $h$ replaced by $g$. Then the semi-linear elliptic system $(a)$ (with $f$ replaced by $g$ ) possesses exactly one weak solution.

First we prove a more general existence and uniqueness theorem, in which we relax the assumptions on the function $g$.

Theorem 4.2. Let $g: \Omega \times \mathbb{R}^{M} \rightarrow \mathbb{R}^{M}$ be Caratheodory function such that $g(\cdot, 0) \in L_{2}\left(\Omega, \mathbb{R}^{M}\right)$. Suppose there exist $g_{i}: \Omega \times \mathbb{R}^{M} \rightarrow \mathbb{R}^{M}$ for $i=1,2$ such that $g=g_{1}+g_{2}$ and:
(G1) $g_{1}$ satisfies (H1) with $h$ replaced by $g_{1}$,
(G2) $g_{2}$ satisfies the Lipschitz condition in the second variable with Lipschitz constant $\delta$ :

$$
\begin{equation*}
\left|g_{2}\left(x, u_{1}\right)-g_{2}\left(x, u_{2}\right)\right|_{\mathbb{R}^{M}} \leq \delta\left|u_{1}-u_{2}\right|_{\mathbb{R}^{M}} \tag{4.1}
\end{equation*}
$$

for a.a. $x \in \Omega$ and all $u_{1}, u_{2} \in \mathbb{R}^{M}$.
If $0 \leq \delta<\frac{\varepsilon}{2}$, then the system ( $a$ ) (with $f$ replaced by $g$ ) has exactly one weak solution.

Proof. As a consequence of Lemma 4.1, we obtain that the mapping $T: L_{2}\left(\Omega, \mathbb{R}^{M}\right) \rightarrow L_{2}\left(\Omega, \mathbb{R}^{M}\right)$ defined by $u=T q$ and

$$
\begin{aligned}
-\Delta u & =g_{1}(x, u)+g_{2}(x, q) & & \text { in } \quad \Omega, \\
u & =0 & & \text { on } \partial \Omega
\end{aligned}
$$

is well defined. We show that $T$ is a contraction in the space $L_{2}\left(\Omega, \mathbb{R}^{M}\right)$, so that Theorem 4.2 will follow from the Banach fixed point theorem. So choose
arbitrary $q_{1}, q_{2} \in L_{2}\left(\Omega, \mathbb{R}^{M}\right)$, and let $u_{i}=T q_{i}, i=1,2$. Denote $h=q_{1}-q_{2}$, $z=u_{1}-u_{2}$. If we put $B(x, w)=g_{1}\left(x, w+u_{2}(x)\right)-g_{1}\left(x, u_{2}(x)\right)$ and $f(x)=$ $g_{2}\left(x, q_{2}(x)+h(x)\right)-g_{2}\left(x, q_{2}(x)\right)$, then $z$ is a solution of the semi-linear system

$$
\begin{aligned}
-\Delta z & =B(x, z)+f(x) & & \text { in } \quad \Omega \\
z & =0 & & \text { on } \quad \partial \Omega
\end{aligned}
$$

and the assumptions of Lemma 3.1 are fulfilled with $\gamma=0$. Hence we get

$$
\|z\|_{0} \leq \frac{2 \delta}{\varepsilon}\|h\|_{0}
$$

since

$$
|f(x)|_{\mathbb{R}^{M}} \leq \delta|h(x)|_{\mathbb{R}^{M}}
$$

for a.a. $x \in \Omega$ by (4.1). We see that the mapping $T$ is a contraction since $\frac{2 \delta}{\varepsilon}<1$.

In the sequel, we shall use the following classical generalization of Banach fixed point theorem.

LEMMA 4.3. (UNIFORM CONTRACTION THEOREM) Let $(X, d)$ be a complete metric space, $\left(\Lambda, d_{\Lambda}\right)$ a metric space, and let $U$ be an open subset of $\Lambda$. We assume that $K: X \times U \rightarrow X$ is a uniform contraction in the first variable, that is, there exist a constant $0 \leq k<1$ such that

$$
d(K(x, \lambda), K(y, \lambda)) \leq k d(x, y)
$$

for all $x, y \in X$ and $\lambda \in U$. Assume, moreover, that $K(x, \cdot): U \rightarrow X$ is continuous in $\lambda_{0}$ for all $x \in X$. Then for every $\lambda \in U$ there exists a unique $x_{\lambda}$ such that $x_{\lambda}=K\left(x_{\lambda}, \lambda\right)$. Moreover, the mapping $\lambda \mapsto x_{\lambda}: U \rightarrow X$ is continuous in $\lambda_{0}$.

After these preparations, we can now prove the main theorem.
THEOREM 4.4. Let $\Lambda$ be an open subset of a metric space $(X, d)$, and let the function $g: \Omega \times \mathbb{R}^{M} \times \mathbb{R}^{M n} \times \Lambda \rightarrow \mathbb{R}^{M}$ be such that:
i) for every $\lambda \in \Lambda, g_{\lambda}=g(\cdot, \cdot, \cdot, \lambda): \Omega \times \mathbb{R}^{M} \times \mathbb{R}^{M n} \rightarrow \mathbb{R}^{M}$ is a Caratheodory function, and
$\mathrm{D}_{2} g(x, u, p, \lambda):=\frac{\partial}{\partial u} g(x, u, p, \lambda), \mathrm{D}_{3} g(x, u, p, \lambda):=\frac{\partial}{\partial p} g(x, u, p, \lambda)$ exist for all $(x, u, p, \lambda) \in \Omega \times \mathbb{R}^{M} \times \mathbb{R}^{M n} \times \Lambda$;
ii) $\lambda \rightarrow \lambda_{0} \in \Lambda$ implies

$$
\begin{aligned}
\sup _{x, u, p}\left|\mathrm{D}_{2} g(x, u, p, \lambda)-\mathrm{D}_{2} g\left(x, u, p, \lambda_{0}\right)\right|_{\mathbb{R}^{M^{2}}} & \rightarrow 0 \\
\sup _{x, u, p}\left|\mathrm{D}_{3} g(x, u, p, \lambda)-\mathrm{D}_{3} g\left(x, u, p, \lambda_{0}\right)\right|_{\mathbb{R}^{M^{2}} n} & \rightarrow 0, \\
\left\|g(\cdot, 0,0, \lambda)-g\left(\cdot, 0,0, \lambda_{0}\right)\right\|_{0} & \rightarrow 0
\end{aligned}
$$

iii) there exist $\lambda_{0} \in \Lambda$ such that $g\left(\cdot, 0,0, \lambda_{0}\right) \in L_{2}\left(\Omega, \mathbb{R}^{M}\right)$ and $g_{\lambda_{0}}=$ $g_{1 \lambda_{0}}+g_{2 \lambda_{0}}$, where $g_{i \lambda_{0}}: \Omega \times \mathbb{R}^{M} \times \mathbb{R}^{M n} \rightarrow \mathbb{R}^{M}(i=1,2)$ and:
(G1) $g_{1 \lambda_{0}}(\cdot, \cdot, p)$ satisfies (H1) with $h$ replaced by $g_{1 \lambda_{0}}(\cdot, \cdot, p)$ for all $p \in \mathbb{R}^{M n}$ with $B^{ \pm}$independent of $p$,
(G2) $g_{2 \lambda_{0}}$ satisfies a Lipschitz condition in the second variable with constant $0 \leq \delta<\frac{\varepsilon}{2}$,
(G3) $g_{\lambda_{0}}$ satisfies a Lipschitz condition in the third variable with constant $0 \leq c<\frac{\frac{c}{2}-\delta}{\sqrt{\nu}}$.
Then there exists an open ball $B:=B\left(\lambda_{0}, r\right)$ in $(X, d)$ such that the system

$$
\begin{align*}
-\Delta u & =g(x, u, \nabla u, \lambda) & & \text { in } \Omega \\
u & =0 & & \text { on } \partial \Omega
\end{align*}
$$

has exactly one weak solution $u_{\lambda}$ for all $\lambda \in B$. Moreover, $\left\|u_{\lambda}-u_{\lambda_{0}}\right\|_{1} \rightarrow 0$ when $d\left(\lambda, \lambda_{0}\right) \rightarrow 0$.

Proof. It follows from iii) that there are symmetric matrices $B^{+}, B^{-}$and constants $\varepsilon, \delta, c, \nu$ such that

$$
\begin{gather*}
0 \leq \delta<\frac{\varepsilon}{2} \quad \text { and } \quad 0 \leq c<\frac{\frac{\varepsilon}{2}-\delta}{\sqrt{\nu}},  \tag{4.2}\\
B^{-} \leq \mathrm{D}_{2} g_{1 \lambda_{0}} \leq B^{+} \\
\left|g_{2 \lambda_{0}}\left(x, u_{1}, h\right)-g_{2 \lambda_{0}}\left(x, u_{2}, h\right)\right|_{\mathbb{R}^{M}} \leq \delta\left|u_{1}-u_{2}\right|_{\mathbb{R}^{M}}  \tag{4.3}\\
\left|g_{\lambda_{0}}\left(x, u, h_{1}\right)-g_{\lambda_{0}}\left(x, u, h_{2}\right)\right|_{\mathbb{R}^{M}} \leq c\left|h_{1}-h_{2}\right|_{\mathbb{R}^{M n}}
\end{gather*}
$$

for a.a. $x \in \Omega$ and all $\left(u_{i}, h\right) \in \mathbb{R}^{M} \times \mathbb{R}^{M n}$ or $\left(u, h_{i}\right) \in \mathbb{R}^{M} \times \mathbb{R}^{M n}$, respectively. Now, it follows from (4.2) that we can choose $L>0$ such that

$$
\begin{equation*}
0 \leq \delta+L<\frac{\varepsilon}{2} \quad \text { and } \quad 0 \leq c+L<\frac{\frac{\varepsilon}{2}-(\delta+L)}{\sqrt{\nu}} \tag{4.4}
\end{equation*}
$$

The assumption ii) implies the existence of $r>0$ such that $B\left(\lambda_{0}, r\right) \subset \Lambda$ and

$$
\begin{align*}
& \left|\mathrm{D}_{2} g(x, u, p, \lambda)-\mathrm{D}_{2} g\left(x, u, p, \lambda_{0}\right)\right|_{\mathbb{R}^{M^{2}}}<L,  \tag{4.5}\\
& \left|\mathrm{D}_{3} g(x, u, p, \lambda)-\mathrm{D}_{3} g\left(x, u, p, \lambda_{0}\right)\right|_{\mathbb{R}^{M^{2} n}}<L
\end{align*}
$$

for a.a. $x \in \Omega$ and all $(u, p) \in \mathbb{R}^{M} \times \mathbb{R}^{M n}$. For $\lambda \in B\left(\lambda_{0}, r\right)$ we define

$$
g_{1 \lambda}=g_{1 \lambda_{0}} \quad \text { and } \quad g_{2 \lambda}=g_{\lambda}-g_{1 \lambda_{0}} .
$$

From (4.3) and (4.5), we get

$$
\begin{align*}
\left|g_{2 \lambda}\left(x, u_{1}, h\right)-g_{2 \lambda}\left(x, u_{2}, h\right)\right|_{\mathbb{R}^{M}} & \leq(\delta+L)\left|u_{1}-u_{2}\right|_{\mathbb{R}^{M}}  \tag{4.6}\\
\left|g_{\lambda}\left(x, u, h_{1}\right)-g_{\lambda}\left(x, u, h_{2}\right)\right|_{\mathbb{R}^{M}} & \leq(c+L)\left|h_{1}-h_{2}\right|_{\mathbb{R}^{M n}}
\end{align*}
$$

Now we define the operator $T: H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right) \times B\left(\lambda_{0}, r\right) \rightarrow H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right)$ by $T(h, \lambda)=u$ and

$$
\begin{aligned}
-\Delta u & =g(x, u, \nabla h, \lambda) & & \text { in } \quad \Omega, \\
u & =0 & & \text { on } \quad \partial \Omega .
\end{aligned}
$$

It follows from (4.2) that $T$ is well defined. First we show the uniform contractivity of $T$. We choose arbitrary $\lambda \in B\left(\lambda_{0}, r\right), q_{1}, q_{2} \in H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right)$, and denote $u_{i}=T\left(q_{i}, \lambda\right)$ for $i=1,2, h=q_{1}-q_{2}$, and $z=u_{1}-u_{2}$. Then $z \in H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right)$ is a weak solution of

$$
\begin{aligned}
-\Delta z & =B(x, z)+f(x, z) & & \text { in } \quad \Omega \\
z & =0 & & \text { on } \quad \partial \Omega
\end{aligned}
$$

where

$$
\begin{aligned}
B(x, w)= & g_{1 \lambda}\left(x, w+u_{2}(x), \nabla q_{1}(x)\right)-g_{1 \lambda}\left(x, u_{2}(x), \nabla q_{1}(x)\right) \\
f(x, w)= & {\left[g_{2 \lambda}\left(x, w+u_{2}(x), \nabla q_{1}(x)\right)-g_{2 \lambda}\left(x, u_{2}(x), \nabla q_{1}(x)\right)\right] } \\
& +\left[g_{\lambda}\left(x, u_{2}(x), \nabla q_{1}(x)\right)-g_{\lambda}\left(x, u_{2}(x), \nabla q_{2}(x)\right)\right] .
\end{aligned}
$$

The functions $B$ and $f$ satisfy the assumptions of Lemma 3.1, so that we get

$$
\|z\|_{1} \leq \frac{(c+L) \sqrt{\nu}}{\frac{\varepsilon}{2}-(\delta+L)}\|h\|_{1}
$$

The inequality (4.4) implies the uniform contractivity of $T$. Now we put $u_{\lambda}=$ $T(h, \lambda), u_{\lambda_{0}}=T\left(h, \lambda_{0}\right)$ for $\lambda \in B\left(\lambda_{0}, r\right)$ and $h \in H_{0}^{1}\left(\Omega, \mathbb{R}^{M}\right)$. Then $z:=$ $u_{\lambda}-u_{\lambda_{0}}$ is a weak solution of the system

$$
\begin{aligned}
-\Delta z & =B(x, z)+f(x, z) & & \text { in } \quad \Omega \\
z & =0 & & \text { on } \quad \partial \Omega
\end{aligned}
$$

with

$$
\begin{aligned}
B(x, w)= & g_{1 \lambda}\left(x, w+u_{\lambda_{0}}(x), \nabla h(x)\right)-g_{1 \lambda}\left(x, u_{\lambda_{0}}(x), \nabla h(x)\right) \\
f(x, w)= & {\left[g_{2 \lambda}\left(x, w+u_{\lambda_{0}}(x), \nabla h(x)\right)-g_{2 \lambda}\left(x, u_{\lambda_{0}}(x), \nabla h(x)\right)\right] } \\
& +\left[\left(g_{\lambda}-g_{\lambda_{0}}\right)\left(x, u_{\lambda_{0}}(x), \nabla h(x)\right)-\left(g_{\lambda}-g_{\lambda_{0}}\right)(x, 0,0)\right] \\
& +\left[\left(g_{\lambda}-g_{\lambda_{0}}\right)(x, 0,0)\right] .
\end{aligned}
$$

From (4.5), (4.6), we get

$$
\begin{aligned}
& |f(x, w)|_{\mathbb{R}^{M}} \leq \\
\leq & (\delta+L)|w|_{\mathbb{R}^{M}}+L_{\lambda, \lambda_{0}}\left(\left|u_{\lambda_{0}}(x)\right|_{\mathbb{R}^{M}}+|\nabla h(x)|_{\mathbb{R}^{M n}}\right)+\left|\left(g_{\lambda}-g_{\lambda_{0}}\right)(x, 0,0)\right|_{\mathbb{R}^{M}}
\end{aligned}
$$

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with

$$
L_{\lambda, \lambda_{0}}:=\left[\sup _{x, u, p}\left|\mathrm{D}_{2}\left(g_{\lambda}-g_{\lambda_{0}}\right)\right|_{\mathbb{R}^{M^{2}}}+\sup _{x, u, p}\left|\mathrm{D}_{3}\left(g_{\lambda}-g_{\lambda_{0}}\right)\right|_{\mathbb{R}^{M^{2}}}\right]
$$

We recall that (ii) implies $L_{\lambda, \lambda_{0}} \rightarrow 0$ if $\lambda \rightarrow \lambda_{0}$. Now we have from Lemma 3.1

$$
\|z\|_{1} \leq \frac{\sqrt{\nu}}{\frac{\varepsilon}{2}-(\delta+L)}\left[L_{\lambda, \lambda_{0}}\left(\left\|u_{\lambda_{0}}\right\|_{0}+\|h\|_{1}\right)+\left\|\left(g_{\lambda}-g_{\lambda_{0}}\right)(\cdot, 0,0)\right\|_{0}\right] .
$$

So that, the assumptions of Lemma 4.3 are fulfilled.

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