## Mathematic Bohemica

## Salvatore Bonafede <br> Existence results for a class of semilinear degenerate elliptic equations

Mathematica Bohemica, Vol. 128 (2003), No. 2, 187-198
Persistent URL: http://dml.cz/dmlcz/134032

## Terms of use:

© Institute of Mathematics AS CR, 2003

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.


This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project DML-CZ: The Czech Digital Mathematics Library http://dml.cz

# EXISTENCE RESULTS FOR A CLASS OF SEMILINEAR DEGENERATE ELLIPTIC EQUATIONS 

Salvatore Bonafede, Palermo
(Received February 12, 2002)

Abstract. We prove existence results for the Dirichlet problem associated with an elliptic semilinear second-order equation of divergence form. Degeneracy in the ellipticity condition is allowed.

Keywords: weak subsolution, degenerate equation, critical point, fixed-point theorems
MSC 2000: 35A05, 35J70, 47H10

## 1. Introduction

We consider the semilinear boundary value problem

$$
\left\{\begin{array}{l}
-\sum_{i, j=1}^{m} \frac{\partial}{\partial x_{i}}\left(a_{i j}(x) \frac{\partial u}{\partial x_{j}}\right)=f(u) \text { in } \Omega  \tag{1.0}\\
u=0 \text { on } \partial \Omega
\end{array}\right.
$$

where $\Omega$ is a bounded open subset of $\mathbb{R}^{m}, f$ is a real valued function defined on $\mathbb{R}$, and the coefficients $a_{i, j}(x)$ satisfy the ellipticity condition

$$
\sum_{i, j=1}^{m} a_{i j}(x) p_{i} p_{j} \geqslant \alpha \sum_{i=1}^{m} \nu_{i}(x) p_{i}^{2} \quad \text { for a.e. } x \in \Omega \text { and for any } p \in \mathbb{R}^{m}
$$

with $\nu_{i}(x)$ satisfying sufficiently general hypotheses.
We obtain some results of existence, uniqueness and boundedness for weak solutions of problem (1.0) with minimal hypotheses on $f$. Similar results, when $f$ has a natural polynomial growth, have been obtained in [3], [5], [7] and in [8] by pseudomonotone operators' theory, while our proof uses fixed-point theorems. The paper
is structured as follows. In Sections 2 and 3 we state hypotheses and results. In Section 4 we establish some useful lemmas and, finally, in Section 5 we prove our main theorems.

## 2. Functional spaces

Let $\mathbb{R}^{m}$ be the Euclidean $m$-space with a generic point $x=\left(x_{1}, x_{2}, \ldots, x_{m}\right), \Omega$ a bounded open subset of $\mathbb{R}^{m}$. The notation meas $x_{x}$ will indicate the $m$-dimensional Lebesgue measure.

If $u(x)$ is a measurable function defined in $\Omega$, we will denote by $|u|_{p}(1 \leqslant p \leqslant \infty)$ the usual norm in the space $L^{p}(\Omega)$.

Hypothesis 2.1. Let $\nu_{i}(x)(i=1,2, \ldots, m)$ be a positive and measurable function defined in $\Omega$ such that

$$
\nu_{i}(x) \in L^{1}(\Omega), \quad \nu_{i}^{-1}(x) \in L^{g_{i}}(\Omega)
$$

where $\sum_{i}^{m} \frac{1}{g_{i}}<2\left(g_{i}>1\right)$ if $m \geqslant 3 \quad(m=2)$.
The symbol $H^{1}\left(\nu_{i}, \Omega\right)$ stands for the completion of $C^{1}(\bar{\Omega})$ with respect to the norm

$$
\|u\|_{1}=\left(\int_{\Omega}\left(|u|^{2}+\sum_{i=1}^{m} \nu_{i}(x)\left|\frac{\partial u}{\partial x_{i}}\right|^{2}\right) \mathrm{d} x\right)^{\frac{1}{2}}
$$

$H_{0}^{1}\left(\nu_{i}, \Omega\right)$ denotes the closure of $C_{0}^{\infty}(\Omega)$ in $H^{1}\left(\nu_{i}, \Omega\right)$.
Finally, $H^{-1}\left(\nu_{i}^{-1}, \Omega\right)$ denotes the dual space of $H_{0}^{1}\left(\nu_{i}, \Omega\right)$ (see also [5], [6] and [10] for details concerning the weighted Sobolev spaces).

## 3. Hypotheses, problems and results

Hypothesis 3.1. The coefficients $a_{i j}(x)(i, j=1,2, \ldots, m)$ are functions defined and measurable in $\Omega$ satisfying

$$
\begin{aligned}
a_{i j}(x) & =a_{j i}(x) \\
\frac{a_{i j}(x)}{\sqrt{\nu_{i}(x) \nu_{j}(x)}} & \in L^{\infty}(\Omega) \quad(i, j=1,2, \ldots, m) .
\end{aligned}
$$

Hypothesis 3.2. There exists $\alpha>0$ such that for almost every $x$ in $\Omega$ we have

$$
\begin{equation*}
\sum_{i, j=1}^{m} a_{i j}(x) p_{i} p_{j} \geqslant \alpha \sum_{i=1}^{m} \nu_{i}(x) p_{i}^{2} \quad \text { for any } p \in \mathbb{R}^{m} \tag{3.1}
\end{equation*}
$$

Let $a: H_{0}^{1}\left(\nu_{i}, \Omega\right) \times H_{0}^{1}\left(\nu_{i}, \Omega\right) \rightarrow \mathbb{R}$ be such that

$$
a(u, v)=\int_{\Omega} \sum_{i j=1}^{m} a_{i j}(x) \frac{\partial u}{\partial x_{j}} \frac{\partial v}{\partial x_{i}} \mathrm{~d} x,
$$

and define

$$
\tau=\inf _{u \in H_{0}^{1}\left(\nu_{i}, \Omega\right) \backslash\{0\}} \frac{a(u, u)}{|u|_{2}} .
$$

In Section 4 we prove the following
Lemma 4.4. Let us assume that (2.1), (3.1), (3.2) hold. Then $\tau>0$ and there exists $u_{0} \in H_{0}^{1}\left(\nu_{i}, \Omega\right)$ such that $\tau=a\left(u_{0}, u_{0}\right)$ and

$$
a\left(u, u_{0}\right)=\tau \int_{\Omega} u u_{0} \mathrm{~d} x \quad \text { for any } u \in H_{0}^{1}\left(\nu_{i}, \Omega\right)
$$

moreover, we can choose $u_{0} \geqslant 0$.
Definition 3.2. Let $H$ be a Hilbert space, $f, g \in C^{1}(H, \mathbb{R})$, and let

$$
E=\left\{u \in H: g(u)=0, \quad g^{\prime}(u) \neq 0\right\} .
$$

A point $u_{0} \in H$ is a critical point of $\left.f\right|_{E}$ if $\left.\frac{\mathrm{d}}{\mathrm{d} t} f(h(t))\right|_{t=0}=0$ for all $C^{1}$ paths $h(t):]-\varepsilon, \varepsilon\left[\rightarrow E\right.$ such that $h(0)=u_{0}$.

Remark 3.3. If there exists $u_{0} \in E$ such that $f\left(u_{0}\right)=\min \{f(u): u \in E\}$, then $\left(\left.f\right|_{E}\right)^{\prime}\left(u_{0}\right)=0$.

Theorem 3.4 (see, e.g., [2]). A point $u_{0} \in E$ is a critical point of $\left.f\right|_{E}$ if and only if there exists $\lambda \in \mathbb{R}$ such that $f^{\prime}\left(u_{0}\right)=\lambda g^{\prime}\left(u_{0}\right)$.

Now, if $f \in C(\mathbb{R})$ satisfies the condition

$$
u \in H_{0}^{1}\left(\nu_{i}, \Omega\right) \Rightarrow f(u) \in H^{-1}\left(\nu_{i}, \Omega\right)
$$

we obtain the following well posed problem
Problem. Find a function $u(x) \in H_{0}^{1}\left(\nu_{i}, \Omega\right)$ such that

$$
\begin{equation*}
\int_{\Omega} \sum_{i j=1}^{m} a_{i j}(x) \frac{\partial u}{\partial x_{j}} \frac{\partial v}{\partial x_{i}} \mathrm{~d} x=(f(u), v)(1) \tag{3.1}
\end{equation*}
$$

for any $v(x) \in H_{0}^{1}\left(\nu_{i}, \Omega\right)$.
(1) We denote by $(\cdot, \cdot)$ the duality pairing between $H_{0}^{1}\left(\nu_{i}, \Omega\right)$ and $H^{-1}\left(\nu_{i}, \Omega\right)$.

A function $u(x)$ satisfying (3.1) is a weak solution of Problem (1.0).
Remark 3.5. When $f$ does not depend on $u, f \in H^{-1}\left(\nu_{i}, \Omega\right)$, the hypotheses (2.1), (3.1), (3.2) are sufficient to ensure existence and uniqueness of a weak solution of problem (1.0), moreover we have

$$
\|u\|_{1,0} \leqslant\|f\|_{H^{-1}\left(\nu_{i}, \Omega\right)} .
$$

Proof follows from Lemma 4.1 and the Lax-Milgram theorem (see Remark 4.2 for the definition of $\left.\|u\|_{1,0}\right)$.

In Section 5 we prove

Theorem 5.1 (Existence, uniqueness and boundedness). Let us assume that (2.1), (3.1), (3.2) hold and let $f$ be Lipschitz continuous with a Lipschitz constant $L<\tau$.

Then there exists a unique weak solution $u(x)$ of problem (1.0); moreover, $u(x) \in$ $L^{\infty}(\Omega)$ and

$$
\begin{equation*}
\|u\|_{\infty} \leqslant \gamma\left(L, g, m, \operatorname{meas}_{x} \Omega\right) \tag{5.0}
\end{equation*}
$$

Theorem 5.2. Let us assume that (2.1), (3.1), (3.2) hold and let $f$ be a bounded continuous function. Then Problem (1.0) has a weak solution $u(x)$. Moreover, $u(x) \in$ $L^{\infty}(\Omega)$ and (5.0) holds.

## 4. Preliminary lemmas

Lemma 4.1. If the hypothesis (2.1) is satisfied then there exists a constant $C=C\left(m, g_{i},\left|\nu_{i}^{-1}\right| g_{i}\right)$ such that

$$
\begin{equation*}
|u|_{2^{\star}} \leqslant C\left(\int_{\Omega} \sum_{i=1}^{m} \nu_{i}(x)\left|\frac{\partial u}{\partial x_{i}}\right|^{2} \mathrm{~d} x\right)^{\frac{1}{2}} \quad \text { for all } u \in H_{0}^{1}\left(\nu_{i}, \Omega\right) \tag{4.1}
\end{equation*}
$$

where $2^{\star}=2 m\left(m-2+\sum_{i=1}^{m} \frac{1}{g_{i}}\right)^{-1}$.
Moreover, the imbedding of $H_{0}^{1}\left(\nu_{i}, \Omega\right)$ into $L^{2}(\Omega)$ is compact.

Proof. Let us fix $m_{i}=\frac{2 g_{i}}{g_{i}+1}$. Then

$$
\begin{equation*}
\left|\frac{\partial u}{\partial x_{i}}\right|_{m_{i}} \leqslant\left|\nu_{i}^{-1}\right|_{g_{i}}^{\frac{1}{2}}\left|\nu_{i}^{\frac{1}{2}} \frac{\partial u}{\partial x_{i}}\right|_{2} \tag{4.2}
\end{equation*}
$$

Since $\sum_{i=1}^{m} \frac{1}{m_{i}}=\sum_{i=1}^{m} \frac{g_{i}+1}{2 g_{i}}=\frac{1}{2}\left(m+\sum_{i=1}^{m} \frac{1}{g_{i}}\right)>1$, Sobolev's imbedding theorem yields (see, for instance, [12])

$$
\begin{equation*}
|u|_{q} \leqslant C\left(m, m_{i}, q\right) \prod_{i=1}^{m}\left|\frac{\partial u}{\partial x_{i}}\right|_{m_{i}}^{\frac{1}{m}} \tag{4.3}
\end{equation*}
$$

where $q=m\left(-1+\sum_{i=1}^{m} \frac{1}{m_{i}}\right)^{-1}$.
From (4.2) and (4.3) we obtain

$$
|u|_{2^{\star}} \leqslant C \prod_{i=1}^{m}\left(\left|\nu_{i}^{-1}\right|_{g_{i}}^{\frac{1}{2 m}}\left|\nu_{i}^{\frac{1}{2}} \frac{\partial u}{\partial x_{i}}\right|_{2}^{\frac{1}{m}}\right) .
$$

Now, let $\left\{u_{n}\right\}$ be a sequence of functions of $H_{0}^{1}\left(\nu_{i}, \Omega\right)$ with equibounded norms and let $\left\{\Pi_{k}\right\}$ be a sequence of open intervals in $\Omega$ such that

1. $\Pi_{k} \subset \Pi_{k+1}$ for any $k \in \mathbb{N}$,
2. $\lim _{k \rightarrow+\infty} \Pi_{k}=\Omega$,
3. for any closed, bounded subset C of $\Omega$ there exists $\bar{k}: C \subset \Pi_{k}, k \geqslant \bar{k}$.

Let us denote by $W^{1,1}\left(\Pi_{1}\right)$ the usual Sobolev space on the set $\Pi_{1}$.
It follows that the norms of $\left\{u_{n}\right\}$ in $W^{1,1}\left(\Pi_{1}\right)$ are equibounded; in fact, applying the Hölder inequality we obtain the following estimate:

$$
\begin{aligned}
\left\|u_{n}\right\|_{W^{1,1}\left(\Pi_{1}\right)} & =\int_{\Pi_{1}}\left|u_{n}\right| \mathrm{d} x+\int_{\Pi_{1}} \sum_{i=1}^{m}\left|\frac{\partial u_{n}}{\partial x_{i}}\right| \mathrm{d} x \\
& \leqslant\left(\int_{\Pi_{1}}\left|u_{n}\right|^{2} \mathrm{~d} x\right)\left(\operatorname{meas} \Pi_{1}\right)^{\frac{1}{2}}+\sum_{i=1}^{m}\left(\int_{\Pi_{1}} \frac{1}{\nu_{i}(x)} \mathrm{d} x\right)^{\frac{1}{2}}\left\|u_{n}\right\|_{1} \\
& \leqslant \text { const }\left\|u_{n}\right\|_{1} .
\end{aligned}
$$

Due to the compact imbedding of $W^{1,1}\left(\Pi_{1}\right)$ into $L^{1}\left(\Pi_{1}\right)$ (see e.g. [1]) there is a subsequence $\left\{u_{1, n}\right\}$ from $\left\{u_{n}\right\}$ that converges a.e. in $\Pi_{1}$.

The same procedure can be done on each $\Pi_{j}$ for $j=2,3, \ldots$. Hence we get a system of sequences $\left\{u_{j, n}\right\}, n, j=1,2, \ldots$ (where $\left\{u_{j, n}\right\}$ is a subsequence of $\left\{u_{j-1, n}\right\}$ ) such that $\left\{u_{j, n}\right\}$ is convergent a.e. in $\Pi_{j}$ for $j=1,2, \ldots$.

By the diagonals method we obtain that $\left\{u_{n, n}\right\}$ converges a.e. in $\Omega$ and, by virtue (4.1), in $L^{2}(\Omega)$.

Remark 4.2. If the hypothesis (2.1) holds, then $\left(\int_{\Omega} \sum_{i=1}^{m} \nu_{i}(x)\left|\frac{\partial u}{\partial x_{i}}\right|^{2} \mathrm{~d} x\right)^{1 / 2}$ constitutes an equivalent norm in $H_{0}^{1}\left(\nu_{i}, \Omega\right)$. We will denote this norm by $\|u\|_{1,0}$.

Lemma 4.3. Let $u(x) \in H_{0}^{1}\left(\nu_{i}, \Omega\right)$ and $k \geqslant 0$, then the function $\min (u, k)$ belongs to $H_{0}^{1}\left(\nu_{i}, \Omega\right)$.

Proof. Define $v=\min (u, k)$ for $u \in H_{0}^{1}\left(\nu_{i}, \Omega\right)$ and let $\left\{\varphi_{n}\right\}$ be a sequence of functions of $C_{0}^{\infty}(\Omega)$ such that

$$
\lim _{n \rightarrow+\infty}\left\|\varphi_{n}-u\right\|_{1}=0
$$

Let $\psi_{n}=\min \left(\varphi_{n}, k\right)$ for any $n \in \mathbb{N}$.
By regularization, we can prove that $\psi_{n}$ belongs to $H_{0}^{1}\left(\nu_{i}, \Omega\right)$; moreover, because the norms of $\left\{\psi_{n}\right\}$ are equibounded in $H_{0}^{1}\left(\nu_{i}, \Omega\right)$, there exists a subsequence that weakly converges in $H_{0}^{1}\left(\nu_{i}, \Omega\right)$. On the other hand,

$$
\left|v(x)-\psi_{n}(x)\right| \leqslant\left|u(x)-\varphi_{n}(x)\right| \quad \text { a.e. in } \Omega,
$$

so $\left\{\psi_{n}\right\}$ converges to $v$ in $L^{2}(\Omega)$.
The conclusion now follows easily.
Proof of Lemma 4.4. We observe that

$$
\begin{equation*}
\tau=\inf \left\{a(u, u): u \in H_{0}^{1}\left(\nu_{i}, \Omega\right), \quad \int_{\Omega} u^{2} \mathrm{~d} x=1\right\} \tag{4.4}
\end{equation*}
$$

and we define $f, g: H_{0}^{1}\left(\nu_{i}, \Omega\right) \rightarrow \mathbb{R}$ as

$$
f(u)=a(u, u), \quad g(u)=\int_{\Omega} u^{2} \mathrm{~d} x-1
$$

Let

$$
E=\left\{u \in H_{0}^{1}\left(\nu_{i}, \Omega\right): g(u)=0\right\} .
$$

Then

$$
\tau=\inf _{u \in E} f(u)
$$

Let $\left\{u_{n}\right\}$ be a sequence such that $a\left(u_{n}, u_{n}\right) \rightarrow \tau$; from (3.2) and Remark 4.2 we have that $\left\{u_{n}\right\}$ is bounded in $H_{0}^{1}\left(\nu_{i}, \Omega\right)$, so there exist $\left\{u_{n_{k}}\right\}, u_{0} \in H_{0}^{1}\left(\nu_{i}, \Omega\right)$ such that $u_{n_{k}} \rightharpoonup u_{0}$ weakly in $H_{0}^{1}\left(\nu_{i}, \Omega\right)$. By the compact imbedding of $H_{0}^{1}\left(\nu_{i}, \Omega\right)$ into $L^{2}(\Omega)$ (Lemma 4.1), $u_{n_{k}} \rightarrow u_{0}$ strongly in $L^{2}(\Omega)$, which gives $\int_{\Omega} u_{0}^{2} \mathrm{~d} x=1$. Therefore $u_{0} \in E$.

Finally, by virtue of

$$
\tau \leqslant a\left(u_{0}, u_{0}\right) \leqslant \liminf _{k \rightarrow+\infty} a\left(u_{n_{k}}, u_{n_{k}}\right)=\tau
$$

we obtain

$$
\tau=a\left(u_{0}, u_{0}\right)
$$

and $f$ attains its minimum at $u_{0} \in E$. By Remark 3.3 we have

$$
\left(\left.f\right|_{E}\right)^{\prime}\left(u_{0}\right)=0
$$

Accordingly, Theorem 3.4 yields

$$
(f)^{\prime}\left(u_{0}\right)=\lambda(g)^{\prime}\left(u_{0}\right) \text { for some } \lambda \in \mathbb{R}
$$

or

$$
a\left(u, u_{0}\right)=\lambda \int_{\Omega} u u_{0} \mathrm{~d} x \quad \text { for any } u \in H_{0}^{1}\left(\nu_{i}, \Omega\right)
$$

Choosing $u=u_{0}$ we have

$$
\tau=a\left(u_{0}, u_{0}\right)=\lambda \int_{\Omega} u_{0}^{2} \mathrm{~d} x \Rightarrow \tau=\lambda
$$

Obviously $u_{0} \in H_{0}^{1}\left(\nu_{i}, \Omega\right)$ is such that

$$
a\left(u, u_{0}\right)=\tau \int_{\Omega} u u_{0} \mathrm{~d} x \quad \text { for any } u \in H_{0}^{1}\left(\nu_{i}, \Omega\right)
$$

Next, Lemma 4.3 implies that if $u$ satisfies (4.4) then $|u|$ also satisfies (4.4), therefore we can choose $u_{0}$ to be non-negative.

## 5. Proof of main results

Define $G: H^{-1}\left(\nu_{i}^{-1}, \Omega\right) \rightarrow H_{0}^{1}\left(\nu_{i}, \Omega\right)$ as

$$
G(g)=w \text { where } w \text { is a weak solution of }\left\{\begin{array}{l}
-\sum_{i, j=1}^{m} \frac{\partial}{\partial x_{i}}\left(a_{i j}(x) \frac{\partial w}{\partial x_{j}}\right)=g \text { in } \Omega \\
w=0 \text { on } \partial \Omega
\end{array}\right.
$$

Remark 3.5 ensures that $G$ is a linear continuous map. For $u \in H_{0}^{1}\left(\nu_{i}, \Omega\right)$ define $F(u)=G(f(u))$. Then a fixed point $u$ of $F$ is a solution of problem (1.0).

Proof of Theorem 5.1. We claim that

$$
u \in L^{2}(\Omega) \Rightarrow f(u) \in L^{2}(\Omega)
$$

Indeed,

$$
|f(u)| \leqslant|f(u)-f(0)|+|f(0)| \leqslant L|u|+|f(0)|
$$

thus

$$
\int_{\Omega}|f(u)|^{2} \mathrm{~d} x \leqslant 2 L^{2} \int_{\Omega}|u|^{2} \mathrm{~d} x+2|f(0)|^{2} \operatorname{meas}_{x} \Omega
$$

We proceed to show that $F$ is a contractive mapping. We see at once that

$$
|f(u)-f(v)|_{2} \leqslant L|u-v|_{2} \quad \text { for any } u, v \in H_{0}^{1}\left(\nu_{i}, \Omega\right)
$$

By (3.1) and Remark 4.2 we deduce that

$$
\alpha\|u\|_{1,0}^{2} \leqslant a(u, u)=(f(u), u) \leqslant c|f(u)|_{2}\|u\|_{1,0}
$$

or

$$
\|u\|_{1,0} \leqslant \frac{c}{\alpha}|f(u)|_{2}
$$

Consequently, $G$ is continuous from $L^{2}(\Omega) \rightarrow L^{2}(\Omega)$. Therefore

$$
\begin{align*}
|F(u)-F(v)|_{2}=|G(f(u)-f(v))|_{2} & \leqslant\|G\|_{\star}|f(u)-f(v)|_{2}  \tag{5.1}\\
& \leqslant L\|G\|_{\star}|u-v|_{2} .
\end{align*}
$$

Since $\tau|u|_{2}^{2} \leqslant a(u, u)=\int_{\Omega} f(u) u \mathrm{~d} x \leqslant|f(u)|_{2}|u|_{2}$ or

$$
\frac{|G(f(u))|_{2}}{|f(u)|_{2}} \leqslant \frac{1}{\tau}
$$

it results that

$$
\|G\|_{\star} \leqslant \frac{1}{\tau}
$$

We conclude from (5.1) that

$$
|F(u)-F(v)|_{2} \leqslant \frac{L}{\tau}|u-v|_{2}
$$

and finally that, since $L<\tau, F$ has a fixed point in $H_{0}^{1}\left(\nu_{i}, \Omega\right)$.
Now, let us fix $k \geqslant 0$, then from (3.1) for $v=u-\min (u, k)$ we get

$$
\begin{equation*}
\alpha\|v\|_{1,0}^{2} \leqslant L \int_{\Omega}\left|u\left\|v\left|\mathrm{~d} x+\int_{\Omega}\right| f(0)\right\| v\right| . \tag{5.2}
\end{equation*}
$$

Lemma 4.1 and the definition of $v$ imply

$$
\begin{aligned}
\int_{\Omega}|u||v| \mathrm{d} x & \leqslant \int_{\Omega(u>k)} v^{2} \mathrm{~d} x+k \int_{\Omega(u>k)} v \mathrm{~d} x \\
& \leqslant|v|_{2^{\star}}^{2}\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{1-\frac{2}{2^{\star}}}+k \int_{\Omega(u>k)} v \mathrm{~d} x \\
& \leqslant c^{2}\|v\|_{1,0}^{2}\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{1-\frac{2}{2^{\star}}}+k \int_{\Omega(u>k)} v \mathrm{~d} x .
\end{aligned}
$$

Therefore from (5.2) we obtain

$$
\begin{equation*}
\|v\|_{1,0}^{2}\left(\alpha-L c^{2}\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{1-\frac{2}{2^{*}}}\right) \leqslant(L k+|f(0)|) \int_{\Omega(u>k)} v \mathrm{~d} x . \tag{5.3}
\end{equation*}
$$

Recalling that

$$
\lim _{k \rightarrow+\infty} \operatorname{meas}_{x} \Omega(u>k)=0
$$

we can certainly choose $\tilde{k} \geqslant 0$ such that for any $k \geqslant \tilde{k}$ we have

$$
L c^{2}\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{1-\frac{2}{2^{*}}} \leqslant \frac{\alpha}{2} .
$$

We apply this inequality to (5.3) obtaining

$$
\begin{equation*}
\|v\|_{1,0} \leqslant \frac{2 c}{\alpha}\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{1-\frac{1}{2^{\star}}}(|f(0)|+L k) \text { for any } k \geqslant \tilde{k} \tag{5.4}
\end{equation*}
$$

Let $h, k$ be real numbers, $h>k \geqslant \tilde{k}$. Then one has

$$
|v|_{2^{\star}}=\left[\int_{\Omega(u>k)}|u-k|^{2^{\star}} \mathrm{d} x\right]^{\frac{1}{2^{\star}}} \geqslant(h-k)\left[\operatorname{meas}_{x} \Omega(u>h)\right]^{\frac{1}{2^{\star}}}
$$

furthermore, (5.4) and Lemma 4.1 yield

$$
\begin{equation*}
\left[\operatorname{meas}_{x} \Omega(u>h)\right]^{\frac{1}{2^{\star}}} \leqslant \frac{2 c^{2}}{\alpha(h-k)}(|f(0)|+L k)\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{1-\frac{1}{2^{\star}}} \tag{5.5}
\end{equation*}
$$

Next, if $k>0$, we get
$\operatorname{meas}_{x} \Omega(u>k) \leqslant \frac{1}{k^{2^{\star}}} \int_{\Omega(u>k)} u^{2^{\star}} \mathrm{d} x, \frac{2 c^{2}}{\alpha k}(|f(0)|+2 L k) 2^{\frac{2^{\star}-1}{2^{\star}-2}}\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{1-\frac{2}{2^{\star}}}$

$$
\leqslant \frac{2 c^{2}}{\alpha k^{2^{\star}-1}}(|f(0)|+2 L k) 2^{\frac{2^{\star}-1}{2^{\star-2}}}\left(\int_{\Omega(u>k)} u^{2^{\star}} \mathrm{d} x\right)^{1-\frac{2}{2^{\star}}}
$$

Now, the first term of the above inequality goes to zero as $k \rightarrow+\infty$, so we can fix $k_{1}(\geqslant \tilde{k})$ such that

$$
\begin{equation*}
\frac{2 c^{2}}{\alpha}\left(|f(0)|+2 L k_{1}\right)\left[\operatorname{meas}_{x} \Omega\left(u>k_{1}\right)\right]^{1-\frac{2}{2^{\star}}} 2^{2^{\star}-1} 2^{2^{\star-2}} \leqslant k_{1} . \tag{5.6}
\end{equation*}
$$

Moreover, one has

$$
\begin{equation*}
\frac{2 c^{2}}{\alpha(h-k)}(|f(0)|+L k) \leqslant \frac{2 c^{2}}{(h-k)}\left(|f(0)|+2 L k_{1}\right) \text { if } 0 \leqslant k \leqslant k_{1} . \tag{5.7}
\end{equation*}
$$

Combining (5.5) and (5.7) we obtain

$$
\left[\operatorname{meas}_{x} \Omega(u>h)\right]^{\frac{1}{2^{\star}}} \leqslant \frac{2 c^{2}}{\alpha(h-k)}\left(|f(0)|+2 L k_{1}\right)\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{1-\frac{1}{2^{\star}}}
$$

for any $h, k \in \mathbb{R}$ such that $k_{1} \leqslant k<h \leqslant 2 k_{1}$.
Assuming in $\left[k_{1},+\infty[\right.$ that

$$
\varphi(k)=\left\{\begin{array}{l}
{\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{\frac{1}{2^{*}}} \text { if } k_{1} \leqslant k \leqslant 2 k_{1}} \\
0 \text { if } k>2 k_{1}
\end{array}\right.
$$

we get

$$
\varphi(h) \leqslant \frac{2 c^{2}}{\alpha(h-k)}\left(|f(0)|+2 L k_{1}\right)[\varphi(k)]^{2^{\star}-1}
$$

for any $h, k \in \mathbb{R}$ such that $k_{1} \leqslant k<h \leqslant 2 k_{1}$, and from Stampacchia's lemma (see [11], p. 212) we deduce

$$
\varphi\left(k_{1}+d\right)=0
$$

where $d$ is the first term of (5.6).
We can obtain the same conclusion for $-u$, so the proof of the theorem is complete.
Proof of Theorem 5.2. Set $F$ as in Theorem 5.1. Since the imbedding of $H_{0}^{1}\left(\nu_{i}, \Omega\right)$ into $L^{2}(\Omega)$ is compact, we have that $F$ is also compact from $L^{2}(\Omega)$ into $L^{2}(\Omega)$; therefore, by Schaefer's fixed point theorem, it will be sufficient to prove that the set of all solutions of the equation

$$
\begin{equation*}
u=\mu F(u) \quad \text { for } 0<\mu<1 \tag{5.8}
\end{equation*}
$$

is unbounded.

Indeed, if $u$ satisfies (5.8), then $u$ is solution of

$$
\left\{\begin{array}{l}
-\sum_{i, j=1}^{m} \frac{\partial}{\partial x_{i}}\left(a_{i j}(x) \frac{\partial u}{\partial x_{j}}\right)=\mu f(u) \text { in } \Omega \\
u=0 \text { on } \partial \Omega
\end{array}\right.
$$

therefore

$$
\tau|u|_{2}^{2} \leqslant a(u, u)=\mu \int_{\Omega} f(u) u \mathrm{~d} x \leqslant M\left(\operatorname{meas}_{x} \Omega\right)^{\frac{1}{2}}|u|_{2}
$$

or

$$
|u|_{2} \leqslant \frac{M\left(\operatorname{meas}_{x} \Omega\right)^{\frac{1}{2}}}{\tau}
$$

Now, if we fix in (3.1) $v=u-\min (u, k), k \geqslant 0$ we get

$$
\alpha\|u\|_{1,0}^{2} \leqslant M \int_{\Omega} v \mathrm{~d} x \leqslant M|v|_{2^{\star}}\left[\operatorname{meas}_{x} \Omega(u>k)\right]^{\frac{2^{\star}-1}{2^{\star}}} .
$$

This inequality, as in the previous theorem, implies

$$
\|u\|_{\infty}<+\infty .
$$

Acknowledgements. Research was supported by the grant MURST $60 \%$ of Italy.

## References

[1] Adams, R. A.: Sobolev Spaces. Academic Press, New York, 1975.
[2] Ambrosetti, A.: Critical points and nonlinear variational problems. Mem. Soc. Math. France 49 (1992).
[3] Bonafede, S.: Quasilinear degenerate elliptic variational inequalities with discontinuous coefficients. Comment. Math. Univ. Carolin. 34 (1993), 55-61.
[4] Bonafede, S.: A weak maximum principle and estimates of ess $\sup _{\Omega} u$ for nonlinear degenerate elliptic equations. Czechoslovak Math. J. 121 (1996), 259-269.
[5] Drábek, P., Kufner, A., Nicolosi, F.: De Gruyter Series in Nonlinear Analysis and Applications, New York, 1997.
[6] Guglielmino, F., Nicolosi, F.: $W$-solutions of boundary value problems for degenerate elliptic operators. Ricerche di Matematica Suppl. 36 (1987), 59-72.
[7] Guglielmino, F., Nicolosi, F.: Existence theorems for boundary value problems associated with quasilinear elliptic equations. Ricerche di Matematica 37 (1988), 157-176.
[8] Ivanov, A. V., Mkrtycjan, P. Z.: On the solvability of the first boundary value problem for certain classes of degenerating quasilinear elliptic equations of second order. Boundary value problems of mathematical physics (O.A.Ladyzenskaja, ed.). Vol. 10, Proceedings of the Steklov Institute of Mathematics, A.M.S. Providence (1981, issue 2), pp. 11-35.
[9] Ladyzenskaja, O. A., Ural'tseva, N. N.: Linear and Quasilinear Elliptic Equations. Academic Press, New York, 1968.
[10] Murthy, M. K. V., Stampacchia, G.: Boundary value problems for some degener-ate-elliptic operators. Ann. Mat. Pura Appl. 80 (1968), 1-122.
[11] Stampacchia, G.: Le probleme de Dirichlet pour les equations elliptiques du second ordre a coefficients discontinus. Annal. Inst. Fourier 15 (1965), 187-257.
[12] Troisi, M.: Teoremi di inclusione per spazi di Sobolev non isotropi. Ricerche Mat. 18 (1989), 3-24.

Author's address: Salvatore Bonafede, Dipartimento di Economia dei Sistemi AgroForestali, University of Palermo, Viale delle Scienze, 90128 Palermo, Italy, e-mail: bonafede @dmi.unict.it.

