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# PARTICULAR TRACE DECOMPOSITIONS AND APPLICATIONS OF TRACE DECOMPOSITION TO ALMOST PROJECTIVE INVARIANTS 

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Abstract. First, by using the formulae of Krupka, the trace decomposition for some particular classes of tensors of types $(1,2)$ and $(1,3)$ is obtained. Second, it is proved that the traceless part of a tensor is an almost projective invariant of weight 1 . We apply this result to Weyl curvature tensors.

Keywords: traceless tensor, trace decomposition, almost projective invariant MSC 2000: 15A72, 53A55

## Introduction

Let $E$ be a real $n$-dimensional linear space, $n \geqslant 2, T_{q}^{p} E$ the linear space of tensors of type $(p, q)$ on $E$. A tensor is said to be traceless if its traces are all zeros. By [2], [3, p. 303] the trace decomposition problem consists in finding a decomposition of a tensor in which the first term is traceless and the other terms are linear combinations of Kronecker's $\delta$-tensors.

In [2], [3, p. 309] the following results are proved:

Theorem 0.1. If $A=\left(A_{k}^{i}\right) \in T_{1}^{1} E$, then there exists a unique traceless tensor $B=\left(B_{k}^{i}\right) \in T_{1}^{1} E$ and a unique scalar $C$ such that

$$
\begin{equation*}
A_{k}^{i}=B_{k}^{i}+\delta_{k}^{i} C \tag{0.1}
\end{equation*}
$$

We have $C=\frac{1}{n} A_{s}^{s}$ and $B_{k}^{i}=A_{k}^{i}-\frac{1}{n} \delta_{k}^{i} A_{s}^{s}$.

Theorem 0.2. If $A=\left(A_{k l}^{i}\right) \in T_{2}^{1} E$, then there exists a unique traceless tensor $B=\left(B_{k l}^{i}\right) \in T_{2}^{1} E$ and unique tensors $C=\left(C_{k}\right), D=\left(D_{k}\right) \in T_{1}^{0} E$ such that

$$
\begin{equation*}
A_{k l}^{i}=B_{k l}^{i}+\delta_{k}^{i} C_{l}+\delta_{l}^{i} D_{k} \tag{0.2}
\end{equation*}
$$

These tensors are defined by

$$
\begin{aligned}
C_{l} & =\varrho(n, 2)\left(n A_{t l}^{t}-A_{l t}^{t}\right) \\
D_{k} & =\varrho(n, 2)\left(-A_{t k}^{t}+n A_{k t}^{t}\right) \\
B_{k l}^{i} & =A_{k l}^{i}-\varrho(n, 2)\left[\delta_{k}^{i}\left(n A_{t l}^{t}-A_{l t}^{t}\right)+\delta_{l}^{i}\left(-A_{t k}^{t}+n A_{k t}^{t}\right)\right]
\end{aligned}
$$

where $\varrho(n, 2)=\frac{1}{n^{2}-1}$.
Theorem 0.3. If $n \geqslant 3$ and $A=\left(A_{k l m}^{i}\right) \in T_{3}^{1} E$, then there exists a unique traceless tensor $B=\left(B_{k l m}^{i}\right) \in T_{3}^{1} E$ and unique tensors $C=\left(C_{l m}\right), D=\left(D_{k m}\right), E=$ $\left(E_{k l}\right) \in T_{2}^{0} E$ such that

$$
\begin{equation*}
A_{k l m}^{i}=B_{k l m}^{i}+\delta_{k}^{i} C_{l m}+\delta_{l}^{i} D_{k m}+\delta_{m}^{i} E_{k l} . \tag{0.3}
\end{equation*}
$$

These tensors are defined by:

$$
\begin{aligned}
C_{k l}= & \varrho(n, 3) \\
& {\left[n\left(n^{2}-3\right) A_{t k l}^{t}+\left(-n^{2}+2\right) A_{k t l}^{t}+n A_{k l t}^{t}-2 A_{t l k}^{t}+n A_{l t k}^{t}+\left(-n^{2}+2\right) A_{l k t}^{t}\right], } \\
D_{k l}= & \varrho(n, 3) \\
& {\left[\left(-n^{2}+2\right) A_{t k l}^{t}+n\left(n^{2}-3\right) A_{k t l}^{t}+\left(-n^{2}+2\right) A_{k l t}^{t}+n A_{t l k}^{t}-2 A_{l t k}^{t}+n A_{l k t}^{t}\right], } \\
E_{k l}= & \varrho(n, 3) \\
& {\left[n A_{t k l}^{t}+\left(-n^{2}+2\right) A_{k t l}^{t}+n\left(n^{2}-3\right) A_{k l t}^{t}+\left(-n^{2}+2\right) A_{t l k}^{t}+n A_{l t k}^{t}-2 A_{l k t}^{t}\right], } \\
B_{k l m}^{i}= & A_{k l m}^{i}-\delta_{k}^{i} C_{l m}-\delta_{l}^{i} D_{k m}-\delta_{m}^{i} E_{k l},
\end{aligned}
$$

where $\varrho(n, 3)=\frac{1}{\left(n^{2}-1\right)\left(n^{2}-4\right)}$.
Remark 0.4. (i) For $n=2$ and $A \in T_{3}^{1} E$ the trace decomposition of $A$ is not unique (theorem 2 (a) of [2], [3, p. 309]).
(ii) In $[3, \mathrm{p} .305]$ it is proved that the traced decomposition problem has a solution for every $A \in T_{q}^{p}(M)$ and for every $p, q$ with $p \leqslant q$. Moreover, the traceless part is unique.
(iii) For the generalization of the trace decomposition problem to spaces with complex structure see [4] and for spaces with quaternionic structure see [5].

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## 1. The trace decomposition of some particular tensors of TYPES $(1,2)$ AND $(1,3)$

In this section we restrict our attention to tensors of types $(1,2)$ and $(1,3)$ because the most important tensors given by a linear connection, namely the torsion tensor and the curvature tensor, are of these types. After a straightforward computation we obtain

Proposition 1.1. If $A=\left(A_{k l}^{i}\right) \in T_{2}^{1} E$ has the form

$$
\begin{equation*}
A_{k l}^{i}=E_{\{k}^{i} F_{l\}}=E_{k}^{i} F_{l}+E_{l}^{i} F_{k} \tag{1.1}
\end{equation*}
$$

then the trace decomposition of $A$ is

$$
\begin{equation*}
A_{k l}^{i}=B_{k l}^{i}+\delta_{k}^{i} C_{l}+\delta_{l}^{i} C_{k} \tag{1.2}
\end{equation*}
$$

with $C_{l}=\frac{1}{n+1} A_{t l}^{t}$ and $B_{k l}^{i}=A_{k l}^{i}-\frac{1}{n+1}\left(\delta_{k}^{i} A_{t l}^{t}+\delta_{l}^{i} A_{t k}^{t}\right)$.
Corollary 1.2. If $A \in T_{2}^{1} E$ has the form (1.1) with $F=\delta$, i.e.

$$
\begin{equation*}
A_{k l}^{i}=\delta_{k}^{i} G_{l}+\delta_{l}^{i} G_{k} \tag{1.3}
\end{equation*}
$$

then in the trace decomposition (1.2) of $A$ we have $C_{k}=G_{k}, B_{k l}^{i}=0$.
Proposition 1.3. If $A=\left(A_{k l}^{i}\right) \in T_{2}^{1} E$ has the form

$$
\begin{equation*}
A_{k l}^{i}=E_{[k}^{i} F_{l]}=E_{k}^{i} F_{l}-E_{l}^{i} F_{k} \tag{1.4}
\end{equation*}
$$

then the trace decomposition of $A$ is

$$
\begin{equation*}
A_{k l}^{i}=B_{k l}^{i}+\delta_{k}^{i} C_{l}-\delta_{l}^{i} C_{k} \tag{1.5}
\end{equation*}
$$

with $C_{l}=\frac{1}{n-1} A_{t l}^{t}$ and $B_{k l}^{i}=A_{k l}^{i}-\frac{1}{n-1}\left(\delta_{k}^{i} A_{t l}^{t}+\delta_{l}^{i} A_{k t}^{t}\right)$.
Corollary 1.4. If $A \in T_{2}^{1} E$ has the form (1.4) with $F=\delta$, i.e.

$$
\begin{equation*}
A_{k l}^{i}=\delta_{k}^{i} G_{l}-\delta_{l}^{i} G_{k}, \tag{1.6}
\end{equation*}
$$

then in the trace decomposition (1.5) of $A$ we have $C_{l}=G_{l}, B_{k l}^{i}=0$.

Example 1.5.
(i) Let $\nabla, \widetilde{\nabla}$ be two linear connections on a smooth $n$-dimensional manifold $M$. Then $A=\widetilde{\nabla}-\nabla \in T_{2}^{1}(M)$. H. Weyl proved that $\nabla$ and $\widetilde{\nabla}$ have the same autoparallel curves if and only if $\exists \psi \in T_{1}^{0}(M)$ such that

$$
\begin{equation*}
A=\delta \otimes \psi+\psi \otimes \delta \tag{1.7}
\end{equation*}
$$

i.e. (1.3), and he called the transformation $\nabla \rightarrow \widetilde{\nabla}$ given by (1.7) a projective transformation ( $[6$, p. 178]) or sometimes a geodesic mapping. In particular, if $\nabla, \widetilde{\nabla}$ are the Levi-Civita connections for the Riemannian metrics $g, \tilde{g}$ on $M$ and $A$ is given by (1.7) then the Riemannian spaces $(M, g),(M, \tilde{g})$ are said to be in geodesic representation (or correspondence) ([6, p. 322]).

A generalization of (1.7) is

$$
\begin{equation*}
A=\delta \otimes \psi_{1}+\psi_{2} \otimes \delta \tag{1.8}
\end{equation*}
$$

with $\psi_{1}, \psi_{2} \in T_{1}^{0}(M)$, which is called an almost projective transformation. In the next section we define almost projective transformations for tensors of type $(p, q)$, $p \leqslant q$.
(ii) If $\nabla$ is a linear connection on a smooth $n$-dimensional manifold $M$ then the torsion $T$ of $\nabla$ is in $T_{2}^{1}(M) . \nabla$ is called semisymmetric if $\exists t \in T_{1}^{0}(M)$ such that

$$
T=\delta \otimes t-t \otimes \delta
$$

i.e. (1.6) holds ([7, p. 194]).

Proposition 1.6. If $n \geqslant 3$ and $A=\left(A_{k l m}^{i}\right) \in T_{3}^{1} E$ has the form

$$
\begin{equation*}
A_{k l m}^{i}=F_{\{k}^{i} G_{l m\}}=F_{k}^{i} G_{l m}+F_{l}^{i} G_{m k}+F_{m}^{i} G_{k l} \tag{1.9}
\end{equation*}
$$

then in the trace decomposition of $A$ (see Th. 0.3) we have

$$
\begin{aligned}
C_{k l} & =E_{k l}=\frac{1}{n^{2}-4}\left(n A_{t k l}^{t}-2 A_{k t l}^{t}\right) \\
D_{k l} & =\frac{1}{n^{2}-4}\left(-2 A_{t k l}^{t}+n A_{k t l}^{t}\right)
\end{aligned}
$$

Corollary 1.7. If $n \geqslant 3$ and $A \in T_{3}^{1} E$ has the form (1.9) with $F=\delta$, i.e.

$$
\begin{equation*}
A_{k l m}^{i}=\delta_{k}^{i} G_{l m}+\delta_{l}^{i} G_{m k}+\delta_{m}^{i} G_{k l} \tag{1.10}
\end{equation*}
$$

then in the trace decomposition of $A$ we have $C_{k l}=E_{k l}=G_{k l}, D_{k l}=G_{l k}, B_{k l m}^{i}=0$.
Proposition 1.8. If $n \geqslant 3$ and $A=\left(A_{k l m}^{i}\right) \in T_{3}^{1} E$ has the form:

$$
\begin{equation*}
A_{k l m}^{i}=F_{[k} G_{l m]}=F_{k}^{i} G_{l m}-F_{l}^{i} G_{m k}+F_{m}^{i} G_{k l} \tag{1.11}
\end{equation*}
$$

then in the trace decomposition of $A$ (see Th. 0.3) we have

$$
\begin{aligned}
\frac{C_{k l}}{\varrho(n, 3)}= & \left(n^{3}-3 n\right) F_{t}^{t} G_{k l}+\left(5 n-n^{3}\right) F_{k}^{t} G_{l t} \\
& +\left(n^{3}-3 n\right) F_{l}^{t} G_{t k}-2 F_{k}^{t} G_{t l}-2 F_{t}^{t} G_{l k}+\left(2-2 n^{2}\right) F_{l}^{t} G_{k t} \\
\frac{D_{k l}}{\varrho(n, 3)}= & \left(2-2 n^{2}\right) F_{t}^{t} G_{k l}-2 F_{k}^{t} G_{l t}-2 F_{l}^{t} G_{t k}+\left(n^{3}-3 n\right) F_{k}^{t} G_{t l} \\
& +\left(5 n-n^{3}\right) F_{t}^{t} G_{l k}+\left(n^{3}-3 n\right) F_{l}^{t} G_{k t} \\
\frac{E_{k l}}{\varrho(n, 3)}= & \left(n^{3}-3 n\right) F_{t}^{t} G_{k l}+\left(n^{3}-3 n\right) F_{k}^{t} G_{l t} \\
& +\left(5 n-n^{3}\right) F_{l}^{t} G_{t k}+\left(6-2 n^{2}\right) F_{k}^{t} G_{t l}-2 F_{t}^{t} G_{l k}-2 F_{l}^{t} G_{k t}
\end{aligned}
$$

Corollary 1.9. If $n \geqslant 3$ and $A \in T_{3}^{1} E$ has the form (1.11) with $F=\delta$, i.e.

$$
A_{k l m}^{i}=\delta_{k}^{i} G_{l m}-\delta_{l}^{i} G_{m k}+\delta_{m}^{i} G_{k l}
$$

then in the trace decomposition of $A$ we have $C_{k l}=E_{k l}=G_{k l}, D_{k l}=-G_{l k}$, $B_{k l m}^{i}=0$.

## 2. Applications to almost projective invariants

Let $M$ be a smooth $n$-dimensional manifold, $C^{\infty}(M)$ the ring of real-valued functions on $M, T_{q}^{p}(M)$ the vector space of tensors of type $(p, q)$ on $M, \mathcal{T}(M)$ the tensorial algebra of $M$.

For $p \leqslant q$ consider the subspace $\delta\left(T_{q}^{p}(M)\right)$ of $T_{q}^{p}(M)$ generated by the tensors fields $X=\left(X_{j_{1} \ldots j_{q}}^{i_{1} \ldots i_{p}}\right)$ of the form ([3, p. 306] $)$

$$
\begin{aligned}
X_{j_{1} \ldots j_{q}}^{i_{1} \ldots i_{p}}= & \delta_{j_{1}}^{i_{1}} X_{(1) j_{2} \ldots j_{q}}^{(1) i_{2} \ldots i_{p}}+\delta_{j_{2}}^{i_{1}} X_{(2) j_{1} j_{3} \ldots j_{q}}^{(1) i_{2} \ldots i_{p}}+\ldots+\delta_{j_{q}}^{i_{1}} X_{(q) j_{1} \ldots j_{q-1}}^{(1) i_{2} \ldots i_{q}} \\
& +\delta_{j_{1}}^{i_{2}} X_{(1) j_{2} \ldots j_{q}}^{(2) i_{1} i_{3} \ldots i_{p}}+\delta_{j_{2}}^{i_{2}} X_{(2) j_{1} j_{3} \ldots j_{q}}^{(2) i_{1} i_{2}}+\ldots+\delta_{j_{q}}^{i_{2}} X_{(q) j_{1} \ldots j_{q-1}}^{(2) i_{1} i_{1} \ldots i_{p}} \\
& \cdots \\
& +\delta_{j_{1}}^{i_{p}} X_{(1) j_{2} \ldots j_{q}}^{(p) i_{1} \ldots i_{p-1}}+\delta_{j_{2}}^{i_{p}} X_{(2) j_{1} j_{3} \ldots j_{q}}^{(p) i_{1} \ldots i_{p-1}}+\ldots+\delta_{j_{q}}^{i_{p}} X_{(q) j_{1} \ldots j_{q-1}}^{(p) i_{1} \ldots i_{p-1}} .
\end{aligned}
$$

Definition 2.1. (i) If $A \in T_{q}^{p}(M)$, a transformation

$$
\begin{equation*}
\widetilde{A}=\varrho A+X \tag{2.1}
\end{equation*}
$$

with $\varrho \in C^{\infty}(M)$ and $X \in \delta\left(T_{q}^{p}(M)\right)$ is called an almost projective transformation.
(ii) With respect to (2.1) a tensor field $N \in \mathcal{T}(M)$ derived from $A$ by any means is called an almost projective invariant of weight $k$ (a natural number) if

$$
\begin{equation*}
\widetilde{N}=\varrho^{k} N \tag{2.2}
\end{equation*}
$$

where $\widetilde{N}$ is derived from $\widetilde{A}$ in the same manner as $N$ is derived from $A$.
Proposition 2.2. If $A \in T_{q}^{p}(M)$ then the traceless part of $A$ is an almost projective invariant of weight 1.

Proof. Let $g=\left(g_{i j}\right)$ be a Riemannian metric on $M$. Then $g$ admits a lift, denoted by $\langle$,$\rangle , to T_{q}^{p}(M)$. It is a simple computation that $B \in T_{q}^{p}(M)$ is traceless if and only if $B$ is $\langle$,$\rangle -orthogonal to \delta\left(T_{q}^{p} t(M)\right)$. Then $A$ has the decomposition $A=B+X(A)$ where $B$ is the traceless part of $A$ (which is unique!) and $X(A) \in$ $\delta\left(T_{q}^{p}(M)\right)$.

Returning to (2.1) we get

$$
\widetilde{A}=\varrho A+X=\varrho(B+X(A))+X=\varrho B+(\varrho X(A)+X) .
$$

Obviously $\varrho X(A)+X \in \delta\left(T_{q}^{p}(M)\right)$ and the uniqueness of the traceless part yields that the traceless part of $\widetilde{A}$ is

$$
\widetilde{B}=\varrho B .
$$

Remark 2.3. For the case $p=1, q=2$ this result appears in [1].

## 3. Applications to Weyl curvature tensors

Let $g=\left(g_{i j}\right)$ be a semi-Riemannian metric on $M$ and $R=\left(R_{j k l}^{i}\right) \in T_{3}^{1}(M)$ the curvature tensor of $g$. In [3, p. 314] it is proved that the traceless part of $R$ is exactly the Weyl projective curvature tensor, and if we consider the tensor $R_{k l}^{i j}=g^{j s} R_{s k l}^{i} \in$ $T_{2}^{2}(M)$ then the traceless part of $\left(R_{k l}^{i j}\right)$ is exactly the Weyl conformal curvature tensor. Applying the result of the previous section we get

Proposition 3.1. For a semi-Riemannian metric the Weyl projective curvature tensor and the Weyl conformal curvature tensor are almost projective invariants of weight 1.

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