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# Stochastic Bilinear Equations with Fractional Gaussian Noise in Hilbert Space 

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#### Abstract

A fractional Gaussian noise is a formal derivative of a fractional Brownian motion. An explicit formula for a weak solution to the stochastic billinear equation in a separable Hilbert space with fractional Gaussian noise in the singular case $H<1 / 2$ is given. The stochastic integral is understood in the Skorokhod sense.


## 1. Introduction

It is well known that the unique solution to a stochastic bilinear equation

$$
\begin{align*}
\mathrm{d} X(t) & =A(t) X(t) \mathrm{d} t+B X(t) \mathrm{d} W(t) \\
X(0) & =x_{0}, \tag{1.1}
\end{align*}
$$

where $A$ is a real-valued bounded Borel function, $B, x_{0} \in \mathbb{R}$, and $W$ is a standard Brownian motion (Wiener process), is given by an explicit formula

$$
\begin{equation*}
X(t)=\exp \{B W(t)\} \exp \left\{\int_{0}^{t} A(u) \mathrm{d} u-\frac{1}{2} B^{2} t\right\} x_{0} \tag{1.2}
\end{equation*}
$$

Denoting by $U$ the fundamental solution to

$$
\frac{\mathrm{d}}{\mathrm{~d} t} x=\left(A(t)-\frac{1}{2} B^{2} t\right) x
$$

[^0]and by $S_{B}$ the group generated by $B, S_{B}(t)=\exp \{B t\}$, we may rewrite (1.2) as
\[

$$
\begin{equation*}
X(t)=S_{B}(W(t)) U(t, 0) x_{0} . \tag{1.3}
\end{equation*}
$$

\]

In this form, the result remains valid for the multidimensional generalizations of (1.1), when $A(t)$ and $B$ are commuting matrices, and for bilinear stochastic evolution equations in a Hilbert space (see Chapter 6 in [4] for a thorough discussion).
In the paper [5], a formula of the type (1.3) was established for solutions to a stochastic bilinear equation in a Hilbert space, driven by a fractional Brownian motion. Recall that a fractional Brownian motion on an interval $[0, T]$ with a Hurst parameter $H \in(0,1)$ is a real-valued centered Gaussian process $\left\{B^{H}(t), t \in[0, T]\right\}$, the covariance of which is given by

$$
\mathbb{E}\left[B^{H}(s) B^{H}(t)\right]=\frac{1}{2}\left(s^{2 H}+t^{2 H}-|s-t|^{2 H}\right), s, t \in[0, T] .
$$

Let $V$ be a separable Hilbert space, $A(t): \operatorname{Dom}(A(t)) \rightarrow V, t \in[0, T]$, closed linear operators generating on evolution system on $V$ and $B: \operatorname{Dom}(B) \rightarrow V$ a generator of a strongly continuous group $S_{B}$ on $V$, commuting with $A(t)$. Let us consider an equation

$$
\begin{align*}
\mathrm{d} X(t) & =A(t) X(t) \mathrm{d} t+B X(t) \mathrm{d} B^{H}(t)  \tag{1.4}\\
X(0) & =x_{0}
\end{align*}
$$

in $V$. If $H>1 / 2$, it is shown in [5] that (under some additional hypothesis upon $A(t)$ and $B$ ) the weak solution of (1.4) has again the form (1.3), where now $U$ denotes the evolution system generated by $\left\{A(t)-H t^{2 H-1} B^{2}, t \in[0, T]\right\}$.
We aim at extending the result from [5] to the singular case $H<1 / 2$. In this case, one faces at least two problems. First, stochastic integrals with respect to a fractional Brownian motion with $H<1 / 2$ behave much less regularly than those for $H>1 / 2$. In our paper, we use the Skorokhod-type stochastic integral introduced in [2], and the corresponding change of variables formula ([2], Corollary 4.8). Secondly, the function $t \mapsto H t^{2 H-1}$ blows up as $t \rightarrow 0+$ if $H<1 / 2$, so it is not obvious, whether $\left\{A(t)-H t^{2 H-1} B^{2}, t \in[0, T]\right\}$ still generates an evolution system, even if the operators $A(t)$ and $B$ are "nice". The corresponding evolution system $U$ is constructed in Section 2 of the paper. We do not know if $U$ is smooth enough, so one cannot apply the Itô formula directly to the right-hand side of (1.3) and one has to resort to a suitable approximation procedure; this is done in Section 3. In Section 4, two illustrative examples are given.
Finally, let us note that two particular cases of our result have been already studied. In [11], a one-dimensional space $V$ is dealt with. In [12], the space $V$ may be infinite-dimensional, but $A(t)$ and $B$ must be bounded.

## 2. Deterministic equations

We would like to use the methods from [5] where the system of linear operators $\left\{A(t)-H t^{2 H-1} B^{2}, t \in[0, T]\right\}$ (under additional assumptions) is well-defined and generates a strongly continuous evolution system and the standard one-dimensional Itô formula for a fractional Brownian motion can be applied. But in the case $H<\frac{1}{2}$ the system of operators $\left\{A(t)-H t^{2 H-1} B^{2}, t \in[0, T]\right\}$ has a singularity at $t=0$ because

$$
t^{2 H-1} \longrightarrow+\infty \quad \text { as } \quad t \rightarrow 0+
$$

so we use the approximating sequence $\left\{u_{n}, n \in \mathbb{N}\right\}$ of the function $u(t)=t^{2 H-1}, t>0$, defined as

$$
u_{n}(t)=\left\{\begin{array}{lll}
t^{2 H-1} & , \quad t>\frac{1}{n} \\
\left(\frac{1}{n}\right)^{2 H-1} & , \quad 0 \leq t \leq \frac{1}{n}
\end{array}\right.
$$

and pass to the limit in an appropriate sense.
The approximating sequence $\left\{u_{n}, n \in \mathbb{N}\right\}$ has the following important properties
(U1) for all $n \in \mathbb{N}$ the function $u_{n}$ is Lipschitz continuous on the interval [0,T]
(U2) $u_{n}$ converges to $u$ in the space $L^{1}([0, T])$
(U3) for all $n \in \mathbb{N}$ and $t>0 \quad 0 \leq u_{n}(t) \leq u(t)$.
We have to assume that the system of linear operators $\{A(t), t \in[0, T]\}$ on $V$ satisfies
(A1) for all $t \in[0, T]$ the operators $A(t)$ are closed and densely defined with the domain $D:=\operatorname{Dom}(A(t))$ independent of $t$
(A2) the resolvent set contains all $\lambda \in \mathbb{C}$ such that $\mathfrak{R}(\lambda) \geq \omega$ for some fixed $\omega \in \mathbb{R}$ and for some constant $M>0$ independent of $t$ the resolvent $R(\lambda, A(t))$ satisfies

$$
\|R(\lambda, A(t))\|_{\mathscr{L}(V)} \leq \frac{M}{|\lambda-\omega|+1}
$$

for all $\lambda \in \mathbb{C}, \mathfrak{R}(\lambda) \geq \omega, t \in[0, T]$.
(A3) there exist constants $L>0$ and $0<\gamma \leq 1$ such that

$$
\|A(t)-A(s)\|_{\mathscr{L}(D ; V)} \leq L|t-s|^{\gamma}
$$

where the space $D$ is equipped with the graph norm generated by the operator $A(0)-\omega I$, i.e.

$$
\|x\|_{V}+\|(A(0)-\omega I) x\|_{V} .
$$

These conditions (A1), (A2), (A3) imply that the system of operators $\{A(t), t \in[0, T]\}$ generates a strongly continuous evolution system $\left\{U_{A}(t, s), 0 \leq s \leq t \leq T\right\}$ satisfying (see e.g. [13], Theorem 5.2.1.)

$$
\begin{align*}
& \operatorname{Im}\left(U_{A}(t, s)\right) \subset D  \tag{2.1}\\
& \left\|U_{A}(t, s)\right\|_{\mathscr{L}(V)} \leq C  \tag{2.2}\\
& \left\|\frac{\partial}{\partial t} U_{A}(t, s)\right\|_{\mathscr{L}(V)}=\left\|A(t) U_{A}(t, s)\right\|_{\mathscr{L}(V)} \leq \frac{C}{t-s},  \tag{2.3}\\
& \left\|A(t) U_{A}(t, s)(A(s)-\omega I)^{-1}\right\|_{\mathscr{L}(V)} \leq C \tag{2.4}
\end{align*}
$$

for some constant $C>0$ and any $0 \leq s<t \leq T$.
For any $n \in \mathbb{N}$ we define the system of linear operators $\left\{A_{n}(t), t \in[0, T]\right\}$ on $V$ with the domain $D$ by

$$
A_{n}(t)=A(t)-H u_{n}(t) B^{2}, t \in[0, T],
$$

and we will show that this system generates a strongly continuous evolution system on $V$. For simplicity we can assume that $\omega<0$. Let us remind that since the operator $-A(0)$ is sectorial, the fractional powers $(-A(0))^{\alpha}$ for $\alpha \in(0,1]$ are well-defined (see e.g. [9]). Since the graph norms $\|x\|_{V}+\left\|\left(A(t)-\omega_{0} I\right) x\right\|_{V}, t \in[0, T], \omega_{0} \geq \omega$, generated by operators $A(t)-\omega_{0} I, t \in[0, T], \omega_{0} \geq \omega$, are equivalent, we can choose one fixed norm

$$
\|x\|_{D}=\|x\|_{V}+\|A(0) x\|_{V}
$$

on $D$.
Proposition 2.1 Assume that the conditions (A1), (A2), (A3) are satisfied for the system $\{A(t), t \in[0, T]\}$. Let $B: \operatorname{Dom}(B) \rightarrow V$ be a linear densely defined operator such that $B^{2}$ is closed and $\operatorname{Dom}\left(B^{2}\right) \supset \operatorname{Dom}\left((-A(0))^{\alpha}\right)$ for some $\alpha \in(0,1)$.
Then the conditions (A1), (A2), (A3) are satisfied for the system $\left\{A_{n}(t), t \in[0, T]\right\}$ with $\operatorname{Dom}\left(A_{n}(t)\right)=D$ and any fixed $n \in \mathbb{N}$. Thus the system of operators $\left\{A_{n}(t), t \in\right.$ $\in[0, T]\}$ generates strongly continuous evolution systems $\left\{U_{n}(t, s), 0 \leq s \leq t \leq T\right\}$ on $V$.

Proof. First note that the assumption (A3) is equivalent to

$$
\begin{equation*}
\left\|(A(t)-A(s)) A^{-1}(0)\right\|_{\mathscr{L}(V)} \leq L|t-s|^{\gamma} \tag{2.5}
\end{equation*}
$$

which implies that there exists a constant $C_{0}>0$ independent of $t$ such that

$$
\begin{equation*}
\|A(0) x\|_{V} \leq C_{0}\|A(t) x\|_{V} \tag{2.6}
\end{equation*}
$$

for all $t \in[0, T]$ and $x \in D$.
Indeed, (2.5) is equivalent to

$$
\left\|A(0)\left(A^{-1}(t)-A^{-1}(s)\right)\right\|_{\mathscr{L}(V)} \leq \tilde{L}|t-s|^{\gamma}
$$

for some constants $\tilde{L}>0$ and $0<\gamma \leq 1$ (see [3], p. 32). Thus for $s=0$ we get

$$
\left\|A(0) A^{-1}(t)-I\right\|_{\mathscr{L}(V)} \leq \tilde{L} T^{\gamma}, 0 \leq t \leq T
$$

So

$$
\left\|A(0) A^{-1}(t)\right\|_{\mathscr{L}(V)} \leq 1+\tilde{L} T^{\gamma}, 0 \leq t \leq T
$$

which is equivalent to (2.6).
Now we can use (2.6) and (A2) to get

$$
\begin{equation*}
\|A(0) R(\lambda, A(t)) x\|_{V} \leq C_{0}\|A(t) R(\lambda, A(t)) x\|_{V} \leq C_{0}(M(1+\omega)+1)\|x\|_{V} \tag{2.7}
\end{equation*}
$$

for any $x \in V$ and $\lambda \in \mathbb{C}, \mathfrak{R}(\lambda) \geq \omega$. By the Corollary 2.6.11 from [9] there exists a constant $C_{A(0)}>0$ depending on $A(0)$ such that for any $\rho>0$ and $x \in V$

$$
\left\|B^{2} R(\lambda, A(t)) x\right\|_{V} \leq C_{A(0)}\left[\rho^{\alpha}\|R(\lambda, A(t)) x\|_{V}+\rho^{\alpha-1}\|A(0) R(\lambda, A(t))\|_{V}\right] .
$$

Using (A2) and (2.7)

$$
\left\|B^{2} R(\lambda, A(t)) x\right\|_{V} \leq C_{A(0)}\left[\rho^{\alpha} \frac{M}{1+|\lambda-\omega|}\|x\|_{V}+\rho^{\alpha-1} C_{0}(M(1+\omega)+1)\|x\|_{V}\right]
$$

Thus
$\left\|H u_{n}(t) B^{2} R(\lambda, A(t))\right\|_{\mathscr{L}(V)} \leq H\left\|u_{n}\right\|_{\mathscr{C}([0, T])} C_{A(0)}\left[\rho^{\alpha} \frac{M}{1+|\lambda-\omega|}+\rho^{\alpha-1} C_{0}(M(1+\omega)+1)\right]$.
For $\rho>0$ enough large we get

$$
H\left\|u_{n}\right\|_{\mathscr{C}([0, T])} C_{A(0)} \rho^{\alpha-1} C_{0}(M(1+\omega)+1)<\frac{1}{2}
$$

hence

$$
\left\|H u_{n}(t) B^{2} R(\lambda, A(t))\right\|_{\mathscr{L}(V)} \leq H\left\|u_{n}\right\|_{\mathscr{C}([0, T])} C_{A(0)} \rho^{\alpha} \frac{M}{1+|\lambda-\omega|}+\frac{1}{2} .
$$

If we now choose some $\omega_{1} \geq \omega$ such that for all $\lambda \in \mathbb{C}, \mathfrak{R}(\lambda) \geq \omega_{1}$ and

$$
2 H\left\|u_{n}\right\|_{\mathscr{C}([0, T])} C_{A(0)} \rho^{\alpha} M-1+\omega<\mathfrak{R}(\lambda)
$$

then

$$
\left\|H u_{n}(t) B^{2} R(\lambda, A(t))\right\|_{\mathscr{L}(V)} \leq K<1
$$

for all $t \in[0, T]$, where $K>0$ is a constant strictly smaller than 1 .
Therefore

$$
\begin{aligned}
\left\|R\left(\lambda, A_{n}(t)\right)\right\|_{\mathscr{L}(V)} & =\left\|\left(\lambda I-A(t)+H u_{n}(t) B^{2}\right)^{-1}\right\|_{\mathscr{L}(V)} \\
& =\left\|\left[I(\lambda I-A(t))+H u_{n}(t) B^{2} R(\lambda, A(t))(\lambda I-A(t))\right]^{-1}\right\|_{\mathscr{L}(V)} \\
& =\left\|\left\{\left[I+H u_{n}(t) B^{2} R(\lambda, A(t))\right](\lambda I-A(t))\right\}^{-1}\right\|_{\mathscr{L}(V)} \\
& =\left\|R(\lambda, A(t))\left[I-\left(-H u_{n}(t) B^{2} R(\lambda, A(t))\right)\right]^{-1}\right\|_{\mathscr{L}(V)} \\
& \leq \frac{M}{1+|\lambda-\omega|} \times \frac{1}{1-K} \times \frac{1+\left|\lambda-\omega_{1}\right|}{1+\left|\lambda-\omega_{1}\right|} \\
& \leq \frac{M}{1-K} \times \frac{1}{1+\left|\lambda-\omega_{1}\right|} \times\left(\frac{1}{1+|\lambda-\omega|}+\frac{|\lambda-\omega|}{1+|\lambda-\omega|}+\frac{\left|\omega-\omega_{1}\right|}{1+|\lambda-\omega|}\right) \\
& \leq \frac{M\left(2+\left|\omega_{1}-\omega\right|\right)}{1-K} \times \frac{1}{1+\left|\lambda-\omega_{1}\right|}
\end{aligned}
$$

which is (A2) for the system of operators $\left\{A_{n}(t), t \in[0, T]\right\}$.
From (A3) and (U1) we have

$$
\begin{aligned}
\|A(t)-A(s)\|_{\mathscr{L}(D ; V)} & \leq L|t-s|^{\gamma} \\
\left|u_{n}(t)-u_{n}(s)\right| & \leq L_{u}|t-s|^{\gamma}
\end{aligned}
$$

for some constants $L, L_{u}>0$. Note that the norm $\|x\|_{V}+\left\|\left(A_{n}(t)-\omega_{1} I\right) x\right\|_{V}$ is dominated by the norm $\|x\|_{D}$. Thus

$$
\begin{aligned}
& \left\|A_{n}(t)-A_{n}(s)\right\|_{\mathscr{L}(D ; V)} \leq\|A(t)-A(s)\|_{\mathscr{L}(D ; V)}+H \mid u_{n}(t)-u_{n}(s)\| \|^{2} \|_{\mathscr{L}(D ; V)} \\
& \quad \leq L|t-s|^{\gamma}+H L_{u}|t-s|^{\gamma}\left\|B^{2}\right\|_{\mathscr{L}(D ; V)} \leq L_{A_{n}}|t-s|^{\gamma}
\end{aligned}
$$

for some finite constant $L_{A_{n}}>0$ because the operators $B^{2} A^{-1}(0) \in \mathscr{L}(V)$ by the closed graph theorem, so (A3) is satisfied for the system of operators $\left\{A_{n}(t), t \in\right.$ $\in[0, T]\}$.

Since $\left\{U_{n}(t, s), 0 \leq s \leq t \leq T\right\}$ is a strongly continuous evolution system for any $n \in \mathbb{N}$ it satisfies the equations

$$
\frac{\partial}{\partial t} U_{n}(t, s) x=\left(A(t)-H u_{n}(t) B^{2}\right) U_{n}(t, s) x
$$

and

$$
U_{n}(t, s) x=U_{A}(t, s) x-\int_{s}^{t} H u_{n}(r) U_{A}(t, r) B^{2} U_{n}(r, s) x \mathrm{~d} r
$$

for any $x \in V$ and $0 \leq s \leq t \leq T$.
Proposition 2.2 Let $\left\{U_{A}(t, s), 0 \leq s \leq t \leq T\right\}$ be a strongly continuous evolution system and $B: \operatorname{Dom}(B) \rightarrow V$ be a linear densely defined operator such that $B^{2}$ is closed and $\operatorname{Dom}\left(B^{2}\right) \supset D$. Moreover, assume that

$$
\begin{equation*}
\left\|U_{A}(t, s) B^{2}\right\|_{\mathscr{L}(V)} \leq \frac{C_{A}}{(t-s)^{\beta}} \tag{2.8}
\end{equation*}
$$

for some constants $C_{A}>0,0<\beta<2 H$ and $0 \leq s<t \leq T$.
Then for any $x \in V$ there exists unique continuous solution $\{U(t, 0) x, 0 \leq t \leq T\}$ to the equation

$$
\begin{equation*}
y(t)=U_{A}(t, 0) x-\int_{0}^{t} H r^{2 H-1} U_{A}(t, r) B^{2} y(r) \mathrm{d} r \tag{2.9}
\end{equation*}
$$

on the interval $[0, T]$.
Proof. Fix $x \in V$. We show that the mapping

$$
(\Phi(y))(t)=U_{A}(t, 0) x-\int_{0}^{t} H r^{2 H-1} U_{A}(t, r) B^{2} y(r) \mathrm{d} r
$$

is continuous from $\mathscr{C}([0, T] ; V)$ into $\mathscr{C}([0, T] ; V)$ (we denote by $\mathscr{C}([0, T] ; V)$ the space of all continuous functions from the interval $[0, T]$ to the space $V$ ) and that $\Phi$ is a contraction mapping.

Take $y \in \mathscr{C}([0, T] ; V)$ and $t_{1}, t_{2} \in[0, T], t_{1}<t_{2}$. Then

$$
\begin{aligned}
& \left\|(\Phi(y))\left(t_{2}\right)-(\Phi(y))\left(t_{1}\right)\right\|_{V} \leq\left\|U_{A}\left(t_{2}, 0\right) x-U_{A}\left(t_{1}, 0\right) x\right\|_{V} \\
& +\left\|\int_{0}^{t_{2}} H r^{2 H-1} U_{A}\left(t_{2}, r\right) B^{2} y(r) \mathrm{d} r-\int_{0}^{t_{1}} H r^{2 H-1} U_{A}\left(t_{1}, r\right) B^{2} y(r) \mathrm{d} r\right\|_{V} \\
& \quad \leq\left\|U_{A}\left(t_{2}, 0\right) x-U_{A}\left(t_{1}, 0\right) x\right\|_{V}+\left\|\int_{0}^{t_{1}} H r^{2 H-1}\left(U_{A}\left(t_{2}, r\right)-U_{A}\left(t_{1}, r\right)\right) B^{2} y(r) \mathrm{d} r\right\|_{V} \\
& +\left\|\int_{t_{1}}^{t_{2}} H r^{2 H-1} U_{A}\left(t_{2}, r\right) B^{2} y(r) \mathrm{d} r\right\|_{V}=T_{1}+T_{2}+T_{3} .
\end{aligned}
$$

Since $t \mapsto U_{A}(t, 0) x$ is continuous for any $x \in V$ we have

$$
T_{1}=\left\|U_{A}\left(t_{2}, 0\right) x-U_{A}\left(t_{1}, 0\right) x\right\|_{V} \longrightarrow 0
$$

as $t_{2} \rightarrow t_{1}+$ or $t_{1} \rightarrow t_{2}-$.
Since for any $0<r<t_{1}$ and some $r<t_{3}<t_{1}$

$$
\begin{aligned}
& \left\|H r^{2 H-1}\left(U_{A}\left(t_{2}, r\right)-U_{A}\left(t_{1}, r\right)\right) B^{2} y(r)\right\|_{V} \\
& \quad=\left\|H r^{2 H-1}\left(U_{A}\left(t_{2}, t_{3}\right) U_{A}\left(t_{3}, r\right)-U_{A}\left(t_{1}, t_{3}\right) U_{A}\left(t_{3}, r\right)\right) B^{2} y(r)\right\|_{V} \\
& \quad \leq H r^{2 H-1}\left\|U_{A}\left(t_{2}, t_{3}\right)-U_{A}\left(t_{1}, t_{3}\right)\right\|_{\mathscr{L}(V)}\left\|U_{A}\left(t_{3}, r\right) B^{2} y(r)\right\|_{V} \longrightarrow 0
\end{aligned}
$$

as $t_{2} \rightarrow t_{1}+$ or $t_{1} \rightarrow t_{2}-$ and by (2.8)

$$
\begin{aligned}
& \left\|\int_{0}^{t_{1}} H r^{2 H-1}\left(U_{A}\left(t_{2}, r\right)-U_{A}\left(t_{1}, r\right)\right) B^{2} y(r) \mathrm{d} r\right\|_{V} \\
& \quad \leq H\|y\|_{\mathscr{C}([0, T] ; V)} \int_{0}^{t_{1}} r^{2 H-1}\left[\left\|U_{A}\left(t_{2}, r\right) B^{2}\right\|_{\mathscr{L}(V)}+\left\|U_{A}\left(t_{1}, r\right) B^{2}\right\|_{\mathscr{L}(V)}\right] \mathrm{d} r
\end{aligned}
$$

$$
\leq H\|y\|_{\mathscr{C}([0, T] ; V)} C_{A} \int_{0}^{t_{1}}\left[\frac{r^{2 H-1}}{\left(t_{2}-r\right)^{\beta}}+\frac{r^{2 H-1}}{\left(t_{1}-r\right)^{\beta}}\right] \mathrm{d} r \leq 2 H\|y\|_{\mathscr{C}([0, T] ; V)} C_{A} \int_{0}^{t_{1}} \frac{r^{2 H-1}}{\left(t_{1}-r\right)^{\beta}} \mathrm{d} r
$$

$$
=2 H\|y\|_{\mathscr{C}([0, T] ; V)} C_{A} t_{1}^{2 H-\beta} \int_{0}^{1} r^{2 H-1}(1-r)^{-\beta} \mathrm{d} r
$$

$$
\leq 2 H\|y\|_{\mathscr{C}([0, T] ; V)} C_{A} T^{2 H-\beta} \mathrm{B}(2 H, 1-\beta)<+\infty
$$

thus

$$
T_{2}=\left\|\int_{0}^{t_{1}} H r^{2 H-1}\left(U_{A}\left(t_{2}, r\right)-U_{A}\left(t_{1}, r\right)\right) B^{2} y(r) \mathrm{d} r\right\|_{V} \longrightarrow 0
$$

as $t_{2} \rightarrow t_{1}+$ or $t_{1} \rightarrow t_{2}$ - by the Lebesgue dominated convergence theorem. Recall that $\mathrm{B}(a, b)=\int_{0}^{1} u^{a-1}(1-u)^{b-1} d u, a>0, b>0$, denotes the Beta function.
By (2.8) we get

$$
\begin{aligned}
T_{3} & =\left\|\int_{t_{1}}^{t_{2}} H r^{2 H-1} U_{A}\left(t_{2}, r\right) B^{2} y(r) \mathrm{d} r\right\|_{V} \leq H\|y\|_{\mathscr{C}([0, T] ; V)} C_{A} \int_{t_{1}}^{t_{2}} \frac{r^{2 H-1}}{\left(t_{2}-r\right)^{\beta}} \mathrm{d} r \\
& =H\|y\|_{\mathscr{C}([0, T] ; V)} C_{A} t_{2}^{2 H-\beta} \int_{\frac{t_{1}}{t_{2}}}^{1} r^{2 H-1}(1-r)^{-\beta} \mathrm{d} r \longrightarrow 0
\end{aligned}
$$

as $t_{2} \rightarrow t_{1}+$ or $t_{1} \rightarrow t_{2}-$. Therefore

$$
\left\|(\Phi(y))\left(t_{2}\right)-(\Phi(y))\left(t_{1}\right)\right\|_{V} \longrightarrow 0
$$

as $t_{2} \rightarrow t_{1}+$ or $t_{1} \rightarrow t_{2}$ - and the function $t \mapsto(\Phi(y))(t)$ is continuous on $[0, T]$ for any $y \in \mathscr{C}([0, T] ; V)$.
For any $y_{1}, y_{2} \in \mathscr{C}([0, T] ; V), t \in[0, T]$ and $T>0$ small enough there exists a constant $0<L_{T}<1$ depending only on $A, B, T, H$ such that

$$
\begin{aligned}
& \left\|\left(\Phi\left(y_{2}\right)\right)(t)-\left(\Phi\left(y_{1}\right)\right)(t)\right\|_{V}=\left\|\int_{0}^{t} H r^{2 H-1} U_{A}(t, r) B^{2}\left(y_{2}(r)-y_{1}(r)\right) \mathrm{d} r\right\|_{V} \\
& \quad \leq H\left\|y_{1}-y_{2}\right\|_{\mathscr{C}([0, T] ; V)} C_{A} \int_{0}^{t} \frac{r^{2 H-1}}{(t-r)^{\beta}} \mathrm{d} r \leq H\left\|y_{1}-y_{2}\right\|_{\mathscr{C}([0, T] ; V)} C_{A} T^{2 H-\beta} \mathrm{B}(2 H, 1-\beta) \\
& \quad \leq L_{T}\left\|y_{1}-y_{2}\right\|_{\mathscr{C}([0, T] ; V)}
\end{aligned}
$$

holds so $\Phi$ is a contraction. Hence, by the Banach fixed-point theorem there exists a unique solution to the equation (2.9) for $T$ enough small. Applying standard methods we get a unique continuous solution $(U(t, 0) x, t \in[0, T])$ to (2.9) for any $T>0$.

The next proposition describes the relation between $U_{n}$ and $U$.
Proposition 2.3 Let $\left\{U_{n}(t, s), 0 \leq s \leq t \leq T\right\}$ be strongly continuous evolution systems on $V$ associated with the operators $\left\{A_{n}(t), t \in[0, T]\right\}$. Suppose that the assumptions of Proposition 2.2 are satisfied. Then for any $x \in V$ there exists a constant $K_{U}>0$ depending only on $H, A, B$ and $T$ such that

$$
\begin{equation*}
\sup \left\{\left\|U_{n}(t, 0) x\right\|_{V} ; n \in \mathbb{N}, 0 \leq t \leq T\right\} \leq K_{U}\|x\|_{V} \tag{2.10}
\end{equation*}
$$

Moreover, the convergence

$$
\begin{equation*}
\left\|U_{n}(., 0) x-U(., 0) x\right\|_{\mathscr{C}([0, T] ; V)} \xrightarrow[n \rightarrow+\infty]{ } 0 \tag{2.11}
\end{equation*}
$$

holds for any $x \in V$.
Proof. Fix $x \in V$. For any $n \in \mathbb{N}$ and $t \in[0, T]$ using (2.2), (2.8) we obtain

$$
\begin{aligned}
\left\|U_{n}(t, 0) x\right\|_{V} & \leq\left\|U_{A}(t, 0) x\right\|+\left\|\int_{0}^{t} H u_{n}(r) U_{A}(t, r) B^{2} U_{n}(r, 0) x \mathrm{~d} r\right\|_{V} \\
& \leq C\|x\|_{V}+H C_{A} \int_{0}^{t} \frac{r^{2 H-1}}{(t-r)^{\beta}}\left\|U_{n}(r, 0) x\right\|_{V} \mathrm{~d} r .
\end{aligned}
$$

The generalized Gronwall inequality (see [8], Lemma 7.1.2) yields

$$
\left\|U_{n}(t, 0) x\right\|_{V} \leq K_{U}\|x\|_{V}
$$

for some finite constant $K_{U}>0$ independent of $n, t$ and the first part of the statement holds.

It remains to prove the second part. For any $x \in V$ and $t \in[0, T]$ using (2.10) and (2.8) we get

$$
\begin{aligned}
& \left\|U_{n}(t, 0) x-U(t, 0) x\right\|_{V} \\
& =\left\|\int_{0}^{t} H u_{n}(r) U_{A}(t, r) B^{2} U_{n}(r, 0) x \mathrm{~d} r-\int_{0}^{t} H r^{2 H-1} U_{A}(t, r) B^{2} U(r, 0) x \mathrm{~d} r\right\|_{V} \\
& \leq\left\|\int_{0}^{t} H\left(u_{n}(r)-r^{2 H-1}\right) U_{A}(t, r) B^{2} U_{n}(r, 0) x \mathrm{~d} r\right\|_{V} \\
& +\left\|\int_{0}^{t} H r^{2 H-1} U_{A}(t, r) B^{2}\left(U_{n}(r, 0) x-U(r, 0) x\right) \mathrm{d} r\right\|_{V} \\
& \leq H C_{A} K_{U}\|x\|_{V} \int_{0}^{t} \frac{r^{2 H-1}-u_{n}(r)}{(t-r)^{\beta}} \mathrm{d} r+H C_{A} \int_{0}^{t} \frac{r^{2 H-1}}{(t-r)^{\beta}}\left\|U_{n}(r, 0) x-U(r, 0) x\right\|_{V} \mathrm{~d} r .
\end{aligned}
$$

If we use the definition of $\left\{u_{n}, n \in \mathbb{N}\right\}$ we obtain the inequality

$$
\int_{0}^{t} \frac{r^{2 H-1}-u_{n}(r)}{(t-r)^{\beta}} \mathrm{d} r \leq\left(\frac{1}{n}\right)^{2 H-\beta} \mathrm{B}(2 H, 1-\beta)
$$

and hence

$$
\begin{aligned}
& \left\|U_{n}(t, 0) x-U(t, 0) x\right\|_{V} \\
& \quad \leq H C_{A} K_{U}\|x\|_{V}\left(\frac{1}{n}\right)^{2 H-\beta} \mathrm{B}(2 H, 1-\beta)+H C_{A} \int_{0}^{t} \frac{r^{2 H-1}}{(t-r)^{\beta}}\left\|U_{n}(r, 0) x-U(r, 0) x\right\|_{V} \mathrm{~d} r .
\end{aligned}
$$

Using again the generalized Gronwall inequality ([8], Lemma 7.1.2) we get

$$
\left\|U_{n}(t, 0) x-U(t, 0) x\right\|_{V} \leq H C_{A} K_{U}\|x\|_{V} \mathrm{~B}(2 H, 1-\beta)\left(\frac{1}{n}\right)^{2 H-\beta} K_{T}
$$

where $K_{T}>0$ is a finite constant independent of $n, t$, therefore

$$
\left\|U_{n}(., 0) x-U(., 0) x\right\|_{\mathscr{C}([0, T] ; V) \xrightarrow[n \rightarrow+\infty]{ } 0 . . ~}^{\text {. }}
$$

## 3. Stochastic bilinear equation

Throughout this section we assume that the hypothesis (A1), (A2), (A3), (2.8) and $\operatorname{Dom}\left(B^{2}\right) \supset \operatorname{Dom}\left((-A(0))^{\alpha}\right)$ for some $\alpha \in(0,1)$ are satisfied. Also let $A^{*}(t)$ be the adjoint operator to the operator $A(t)$ for each $t \in[0, T]$. Assume that the domain $\operatorname{Dom}\left(A^{*}(t)\right)=D^{*}$ of the operator $A^{*}(t)$ is independent of $t$. Moreover, assume that
(B1) $D^{*} \subset \operatorname{Dom}\left(\left(B^{*}\right)^{2}\right)$
(B2) linear operator $B$ on $V$ is closed and densely defined and generates a strongly continuous group $\left\{S_{B}(t), t \in \mathbb{R}\right\}$
and
(AB) the operators $A(t)$ and $\left\{S_{B}(u), u \in \mathbb{R}\right\}$ commute on the domain $D$ for all $t \in$ $\in[0, T]$
It is well known that (B2) yields an existence of constants $M_{B} \geq 1, \omega_{B} \geq 0$ such that the inequality

$$
\begin{equation*}
\left\|S_{B}(u)\right\|_{\mathscr{L}(V)} \leq M_{B} \exp \left\{\omega_{B}|u|\right\} \tag{3.1}
\end{equation*}
$$

holds for each $u \in \mathbb{R}$.
An explicit formula for the weak solution to the stochastic differential equation

$$
\begin{align*}
\mathrm{d} X(t) & =A(t) X(t) \mathrm{d} t+B X(t) \mathrm{d} B^{H}(t)  \tag{3.2}\\
X(0) & =x_{0}
\end{align*}
$$

on the interval $[0, T]$ is given in this section, where $x_{0} \in V$ is a deterministic initial value and $\left\{B^{H}(t), t \in[0, T]\right\}$ is a one-dimensional real-valued fractional Brownian motion with Hurst parameter $H<\frac{1}{2}$ on the interval $[0, T]$ defined on a complete probability space $(\Omega, \mathscr{F}, \mathbb{P})$.

Definition 3.1 $A(\mathscr{B}([0, T]) \otimes \mathscr{F})$-measurable stochastic process $\{X(t), t \in[0, T]\}$ is said to be
(I) a strong solution to the equation (3.2) if $X(t) \in D \quad \mathbb{P}$-a.s. for all $t \in[0, T]$ and

$$
X(t)=x_{0}+\int_{0}^{t} A(r) X(r) \mathrm{d} r+\int_{0}^{t} B X(r) \mathrm{d} B^{H}(r) \quad \mathbb{P}-\text { a.s. }
$$

for all $t \in[0, T]$.
(II) a weak solution to the equation (3.2) if for any $y \in D^{*}$

$$
\begin{aligned}
& \langle X(t), y\rangle_{V}=\left\langle x_{0}, y\right\rangle_{V}+\int_{0}^{t}\left\langle X(r), A^{*}(r) y\right\rangle_{V} \mathrm{~d} r+\int_{0}^{t}\left\langle X(r), B^{*} y\right\rangle_{V} \mathrm{~d} B^{H}(r) \quad \mathbb{P}-\text { a.s. } \\
& \quad \text { for all } t \in[0, T] .
\end{aligned}
$$

Let $U_{n}$ be the strongly continuous evolution system associated with the system of operators $\left\{A_{n}(t), t \in[0, T]\right\}$ constructed in Proposition 2.1. Define approximating processes $\left\{X_{n}(t), t \in[0, T]\right\}, n \in \mathbb{N}$, as

$$
X_{n}(t)=S_{B}\left(B^{H}(t)\right) U_{n}(t, 0) x_{0}, t \in[0, T]
$$

Proposition 3.2 If $x_{0} \in D$ then the process $\left\{X_{n}(t), t \in[0, T]\right\}$ is a strong solution to the equation

$$
\begin{align*}
\mathrm{d} X_{n}(t) & =\left(A(t)+H\left(t^{2 H-1}-u_{n}(t)\right) B^{2}\right) X_{n}(t) \mathrm{d} t+B X_{n}(t) \mathrm{d} B^{H}(t),  \tag{3.3}\\
X_{n}(0) & =x_{0}
\end{align*}
$$

If $x_{0} \in V$ and for some constant $C_{0}^{*}>0$ independent of $t$

$$
\begin{equation*}
\left\|A^{*}(t) x\right\|_{V} \leq C_{0}^{*}\left\|A^{*}(0) x\right\|_{V} \tag{3.4}
\end{equation*}
$$

holds for each $x \in D^{*}$ then the process $\left\{X_{n}(t), t \in[0, T]\right\}$ is a weak solution to the equation (3.3).

Proof. Fix $y \in \operatorname{Dom}\left(\left(B^{*}\right)^{2}\right)$. An idea of the proof is to apply the one-dimensional Itô formula for a fractional Brownian motion (see [2], Corollary 4.8) to the function

$$
f(t, x):=\left\langle S_{B}(x) U_{n}(t, 0) x_{0}, y\right\rangle_{V}=\left\langle U_{n}(t, 0) x_{0}, S_{B}^{*}(x) y\right\rangle_{V}, t \geq 0, x \in \mathbb{R}
$$

Clearly, $f \in \mathscr{C}^{1,2}([0, T] \times \mathbb{R})$,

$$
\begin{aligned}
\frac{\partial}{\partial t} f(t, x) & =\left\langle\left(A(t)-H u_{n}(t) B^{2}\right) U_{n}(t, 0) x_{0}, S_{B}^{*}(x) y\right\rangle_{V} \\
\frac{\partial}{\partial x} f(t, x) & =\left\langle U_{n}(t, 0) x_{0}, S_{B}^{*}(x) B^{*} y\right\rangle_{V} \\
\frac{\partial^{2}}{\partial x^{2}} f(t, x) & =\left\langle U_{n}(t, 0) x_{0}, S_{B}^{*}(x)\left(B^{*}\right)^{2} y\right\rangle_{V}
\end{aligned}
$$

We have to check that

$$
\begin{equation*}
\max \left\{\left|\frac{\partial}{\partial t} f(t, x)\right|,\left|\frac{\partial^{2}}{\partial x^{2}} f(t, x)\right|\right\} \leq C_{f} \mathrm{e}^{\lambda x^{2}} \tag{3.5}
\end{equation*}
$$

for some constants $C_{f}>0$ and $0<\lambda<1 / 4 T^{2 H}$.
Note that for all $b \in \mathbb{R}$ the inequality

$$
\exp \{b x\} \leq \exp \left\{C_{b}+\lambda x^{2}\right\}, x \in \mathbb{R}
$$

holds for some constant $C_{b} \geq 0$.
By (2.4) for $\left\{A_{n}(t), t \in[0, T]\right\}$ and (3.1) we get

$$
\begin{aligned}
& \left|\frac{\partial}{\partial t} f(t, x)\right|=\left|\left\langle\left(A(t)-H u_{n}(t) B^{2}\right) U_{n}(t, 0) x_{0}, S_{B}^{*}(x) y\right\rangle_{V}\right| \\
& \quad \leq\left|\left\langle\left(A(t)-H u_{n}(t) B^{2}\right) U_{n}(t, 0)\left(A(0)-H u_{n}(0) B^{2}\right)^{-1}\left(A(0)-H u_{n}(0) B^{2}\right) x_{0}, S_{B}^{*}(x) y\right\rangle_{V}\right| \\
& \quad \leq C\left\|\left(A(0)-H u_{n}(0) B^{2}\right) x_{0}\right\|_{V} M_{B} \exp \left\{\omega_{B}|x|\right\}\|y\|_{V} \leq C_{f} \mathrm{e}^{\lambda x^{2}}
\end{aligned}
$$

and by (2.10) and (3.1)

$$
\begin{aligned}
\left|\frac{\partial^{2}}{\partial x^{2}} f(t, x)\right| & =\left\langle U_{n}(t, 0) x_{0}, S_{B}^{*}(x)\left(B^{*}\right)^{2} y\right\rangle_{V} \leq\left\|U_{n}(t, 0) x_{0}\right\|_{V}\left\|S_{B}^{*}(x)\left(B^{*}\right)^{2} y\right\|_{V} \\
& \leq K_{U}\left\|x_{0}\right\|_{V} M_{B} \exp \left\{\omega_{B}|x|\right\}\left\|\left(B^{*}\right)^{2} y\right\|_{V} \leq C_{f} \mathrm{e}^{\lambda x^{2}}
\end{aligned}
$$

Now, Corollary 4.8 from [2] yields

$$
\begin{aligned}
\left\langle X_{n}(t), y\right\rangle_{V} & =f\left(t, B^{H}(t)\right)=f\left(0, B^{H}(0)\right)+\int_{0}^{t} \frac{\partial}{\partial r} f\left(r, B^{H}(r)\right) \mathrm{d} r \\
& +\int_{0}^{t} \frac{\partial}{\partial x} f\left(r, B^{H}(r)\right) \mathrm{d} B^{H}(r)+\int_{0}^{t} H r^{2 H-1} \frac{\partial^{2}}{\partial x^{2}} f\left(r, B^{H}(r)\right) \mathrm{d} r \\
& =\left\langle x_{0}, y\right\rangle_{V}+\int_{0}^{t}\left\langle\left(A(r)-H u_{n}(r) B^{2}\right) U_{n}(r, 0) x_{0}, S_{B}^{*}\left(B^{H}(r)\right) y\right\rangle_{V} \mathrm{~d} r \\
& +\int_{0}^{t}\left\langle B S_{B}\left(B^{H}(r)\right) U_{n}(r, 0) x_{0}, y\right\rangle_{V} \mathrm{~d} B^{H}(r) \\
& +\int_{0}^{t}\left\langle H r^{2 H-1} B^{2} S_{B}\left(B^{H}(r)\right) U_{n}(r, 0) x_{0}, y\right\rangle_{V} \mathrm{~d} r \quad \mathbb{P}-\text { a.s. }
\end{aligned}
$$

for all $t \in[0, T]$. Using the commutativity assumption (AB) we get

$$
\begin{aligned}
\left\langle X_{n}(t), y\right\rangle_{V} & =\left\langle x_{0}, y\right\rangle_{V}+\int_{0}^{t}\left\langle A(r) X_{n}(r), y\right\rangle_{V} \mathrm{~d} r+\int_{0}^{t}\left\langle B X_{n}(r), y\right\rangle_{V} \mathrm{~d} B^{H}(r) \\
& +\int_{0}^{t}\left\langle H\left(r^{2 H-1}-u_{n}(r)\right) B^{2} X_{n}(r), y\right\rangle_{V} \mathrm{~d} r \quad \mathbb{P}-\text { a.s. }
\end{aligned}
$$

for all $t \in[0, T]$ and $y \in \operatorname{Dom}\left(\left(B^{*}\right)^{2}\right)$. Taking a countable subset of the domain $\operatorname{Dom}\left(\left(B^{*}\right)^{2}\right)$ dense in $V$ we obtain that the process $\left\{X_{n}(t), t \in[0, T]\right\}$ is $D$-valued and it is a strong solution to the equation (3.3).
Let $x_{0} \in V$. To prove the second part take a sequence $\left\{x_{k}, k \in \mathbb{N}\right\}$ in $D$ converging to $x_{0}$ in $V$ and consider approximating processes $\left\{Y_{k}(t), t \in[0, T]\right\}, k \in \mathbb{N}$, of the process $\left\{X_{n}(t), t \in[0, T]\right\}$ defined as

$$
Y_{k}(t)=S_{B}\left(B^{H}(t)\right) U_{n}(t, 0) x_{k}
$$

By the previous part of the proof it is known that the process $\left\{Y_{k}(t), t \in[0, T]\right\}$ is a strong solution to the equation (3.3) with the initial value $Y_{k}(0)=x_{k}$ and for each $y \in D^{*}$

$$
\begin{align*}
\left\langle Y_{k}(t), y\right\rangle_{V} & =\left\langle x_{k}, y\right\rangle_{V}+\int_{0}^{t}\left\langle Y_{k}(r), A^{*}(r) y\right\rangle_{V} \mathrm{~d} r+\int_{0}^{t}\left\langle Y_{k}(r), B^{*} y\right\rangle_{V} \mathrm{~d} B^{H}(r)  \tag{3.6}\\
& +\int_{0}^{t}\left\langle H\left(r^{2 H-1}-u_{n}(r)\right) Y_{k}(r),\left(B^{*}\right)^{2} y\right\rangle_{V} \mathrm{~d} r \mathbb{P}-\text { a.s. }
\end{align*}
$$

for all $t \in[0, T]$.
Our aim is to pass to the limit in the equation (3.6) in the space $L^{2}(\Omega)$ for any fixed $t \in[0, T]$ and any fixed $y \in D^{*}$ and to use the closedness of the Skorokhod integral. By the Fernique theorem (see [7]) it is well-known that

$$
\begin{equation*}
\mathbb{E}\left[\exp \left\{\zeta \sup \left\{\left|B^{H}(t)\right| ; t \in[0, T]\right\}\right\}\right]<+\infty \tag{3.7}
\end{equation*}
$$

for any constant $\zeta>0$.
Using (3.1), (3.7) and (2.10)

$$
\begin{align*}
& \mathbb{E}\left|\left\langle Y_{k}(t), y\right\rangle_{V}-\left\langle X_{n}(t), y\right\rangle_{V}\right|^{2}=\mathbb{E}\left|\left\langle Y_{k}(t)-X_{n}(t), y\right\rangle_{V}\right|^{2} \\
& \quad=\mathbb{E}\left|\left\langle S_{B}\left(B^{H}(t)\right) U_{n}(t, 0)\left(x_{k}-x_{0}\right), y\right\rangle_{V}\right|^{2} \\
& \quad \leq M_{B}^{2} \mathbb{E}\left[\exp \left\{2 \omega_{B} \sup \left\{\left|B^{H}(r)\right| ; r \in[0, T]\right\}\right\}\right] K_{U}^{2}\|y\|_{V}^{2}\left\|x_{k}-x_{0}\right\|_{V}^{2} \xrightarrow[k \rightarrow+\infty]{ } 0,  \tag{3.8}\\
& \mathbb{E}\left|\left\langle x_{k}, y\right\rangle_{V}-\left\langle x_{0}, y\right\rangle_{V}\right|^{2}=\left\langle x_{k}-x_{0}, y\right\rangle_{V}^{2} \leq\|y\|_{V}^{2}\left\|x_{k}-x_{0}\right\|_{V}^{2} \xrightarrow[k \rightarrow+\infty]{ } 0,
\end{align*}
$$

by (3.4)

$$
\begin{aligned}
& \mathbb{E}\left|\int_{0}^{t}\left\langle\left(Y_{k}(r)-X_{n}(r)\right), A^{*}(r) y\right\rangle_{V} \mathrm{~d} r\right|^{2}=\mathbb{E}\left|\int_{0}^{t}\left\langle\left(S_{B}\left(B^{H}(t)\right) U_{n}(t, 0)\left(x_{k}-x_{0}\right)\right), A^{*}(r) y\right\rangle_{V} \mathrm{~d} r\right|^{2} \\
& \quad \leq M_{B}^{2} \mathbb{E}\left[\exp \left\{2 \omega_{B} \sup \left\{\left|B^{H}(r)\right| ; r \in[0, T]\right\}\right\}\right] K_{U}^{2} T^{2}\left\|x_{k}-x_{0}\right\|_{V}^{2}\left(C_{0}^{*}\right)^{2}\left\|A^{*}(0) y\right\|_{V}^{2} \xrightarrow[k \rightarrow+\infty]{ } 0,
\end{aligned}
$$

and by (U3)

$$
\begin{aligned}
\mathbb{E} & \left|\int_{0}^{t}\left\langle H\left(r^{2 H-1}-u_{n}(r)\right)\left(Y_{k}(r)-X_{n}(r)\right),\left(B^{*}\right)^{2} y\right\rangle_{V} \mathrm{~d} r\right|^{2} \\
& =\mathbb{E}\left|\int_{0}^{t}\left\langle H\left(r^{2 H-1}-u_{n}(r)\right) S_{B}\left(B^{H}(t)\right) U_{n}(t, 0)\left(x_{k}-x_{0}\right),\left(B^{*}\right)^{2} y\right\rangle_{V} \mathrm{~d} r\right|^{2} \\
& \leq M_{B}^{2} \mathbb{E}\left[\exp \left\{2 \omega_{B} \sup \left\{\left|B^{H}(r)\right| ; r \in[0, T]\right\}\right\}\right] K_{U}^{2} T^{4 H}\left\|x_{k}-x_{0}\right\|_{V}^{2}\left\|\left(B^{*}\right)^{2} y\right\|_{V}^{2} \xrightarrow[k \rightarrow+\infty]{ } 0 .
\end{aligned}
$$

Therefore we can pass to the limit in the equation (3.6) in the space $L^{2}(\Omega)$ and there exists a random variable $Y_{(n, y)}(t)$ such that

$$
\int_{0}^{t}\left\langle Y_{k}(r), B^{*} y\right\rangle_{V} \mathrm{~d} B^{H}(r) \xrightarrow[n \rightarrow+\infty]{ } Y_{(n, y)}(t) \quad \text { in } \quad L^{2}(\Omega)
$$

Analogous to (3.8) we get

$$
\int_{0}^{t} \mathbb{E}\left|\left\langle Y_{k}(r), B^{*} y\right\rangle_{V}-\left\langle X_{n}(r), B^{*} y\right\rangle_{V}\right|^{2} \mathrm{~d} r \underset{k \rightarrow+\infty}{ } 0
$$

and

$$
\left\{\left\langle Y_{k}(r), B^{*} y\right\rangle_{V}, r \in[0, t]\right\},\left\{\left\langle X_{n}(r), B^{*} y\right\rangle_{V}, r \in[0, t]\right\} \in L^{2}\left(\Omega ; L^{2}([0, t])\right)
$$

for any $k \in \mathbb{N}$ and by the Itô formula we know that the process $\left\{\left\langle Y_{k}(r), B^{*} y\right\rangle_{V}, r \in\right.$ $\in[0, t]\}$ is Skorokhod integrable with respect to the fractional Brownian motion. Hence by the closedness of the Skorokhod integral we have that the process $\left\{\left\langle X_{n}(r), B^{*} y\right\rangle_{V}, r \in[0, t]\right\}$ is Skorokhod integrable with respect to the fractional Brownian motion and

$$
Y_{(n, y)}(t)=\int_{0}^{t}\left\langle X_{n}(r), B^{*} y\right\rangle_{V} \mathrm{~d} B^{H}(r) \quad \mathbb{P}-\text { a.s. }
$$

(see [2], Remark 3.4.2) for any $t \in[0, T]$. Thus the process $\left\{X_{n}(t), t \in[0, T]\right\}$ is a weak solution to the equation (3.3).

Now we can define the process $\{X(t), t \in[0, T]\}$ as

$$
X(t)=S_{B}\left(B^{H}(t)\right) U(t, 0) x_{0}, t \in[0, T]
$$

and show the relation between processes $\left\{X_{n}(t), t \in[0, T]\right\}$ and $\{X(t), t \in[0, T]\}$.
Lemma 3.3 For any $y \in V$ and any $t \in[0, T]$ the random variables $\left\langle X_{n}(t), y\right\rangle_{V}$ converge to the random variable $\langle X(t), y\rangle_{V}$ in the space $L^{2}(\Omega)$.

Proof. Using (3.1), (3.7) and (2.11) we get

$$
\begin{aligned}
& \mathbb{E}\left|\left\langle X_{n}(t), y\right\rangle_{V}-\langle X(t), y\rangle_{V}\right|^{2}=\mathbb{E}\left|\left\langle X_{n}(t)-X(t), y\right\rangle_{V}\right|^{2} \\
& \quad=\mathbb{E}\left|\left\langle S_{B}\left(B^{H}(t)\right)\left(U_{n}(t, 0) x_{0}-U(t, 0)\right) x_{0}, y\right\rangle_{V}\right|^{2} \leq\left\|U_{n}(., 0) x_{0}-U(., 0) x_{0}\right\|_{\mathscr{C}([0, T] ; V)}^{2} \\
& \quad \times\|y\|_{V}^{2} M_{B}^{2} \mathbb{E}\left[\exp \left\{2 \omega_{B} \sup \left\{\left|B^{H}(t)\right| ; t \in[0, T]\right\}\right\}\right]_{n \rightarrow+\infty} 0 .
\end{aligned}
$$

Now we can prove that the process $\{X(t), t \in[0, T]\}$ is a weak solution to the equation (3.2).

Theorem 3.4 Assume that $\{A(t), t \in[0, T]\}$ and $B$ are linear operators on $V$ satisfying (A1), (A2), (A3) and (B1), (B2). Moreover, assume that $\operatorname{Dom}\left(B^{2}\right)$ ว $\supset \operatorname{Dom}\left((-A(0))^{\alpha}\right)$ for some $\alpha \in(0,1),(2.8),(\mathrm{AB})$ and (3.4) hold. Then for each $x_{0} \in V$ the process $\{X(t), t \in[0, T]\}$ is a weak solution to the equation

$$
\begin{align*}
\mathrm{d} X(t) & =A(t) X(t) \mathrm{d} t+B X(t) \mathrm{d} B^{H}(t)  \tag{3.9}\\
X(0) & =x_{0}
\end{align*}
$$

Proof. The proof is similar to the last part of the proof of Proposition 3.2. We pass to the limit in the equation

$$
\begin{align*}
\left\langle X_{n}(t), y\right\rangle_{V} & =\left\langle x_{0}, y\right\rangle_{V}+\int_{0}^{t}\left\langle X_{n}(r), A^{*}(r) y\right\rangle_{V} \mathrm{~d} r+\int_{0}^{t}\left\langle X_{n}(r), B^{*} y\right\rangle_{V} \mathrm{~d} B^{H}(r) \\
& +\int_{0}^{t}\left\langle H\left(r^{2 H-1}-u_{n}(r)\right) X_{n}(r),\left(B^{*}\right)^{2} y\right\rangle_{V} \mathrm{~d} r \tag{3.10}
\end{align*}
$$

in the space $L^{2}(\Omega)$ for any fixed $t \in[0, T]$ and any fixed $y \in D^{*}$. By (3.4), (3.7), (3.1) and (2.11) we have

$$
\begin{aligned}
\mathbb{E} \mid & \left.\int_{0}^{t}\left\langle\left(X_{n}(r)-X(r)\right), A^{*}(r) y\right\rangle_{V} \mathrm{~d} r\right|^{2} \\
& =\left.\mathbb{E}\left|\int_{0}^{t}\left\langle S_{B}\left(B^{H}(r)\right)\left(U_{n}(r, 0) x_{0}-U(r, 0) x_{0}\right)\right), A^{*}(r) y\right\rangle_{V}\right|^{2} \mathrm{~d} t \leq\left(C_{0}^{*}\right)^{2}\left\|A^{*}(0) y\right\|_{V}^{2} T^{2} \\
& \times M_{B}^{2} \mathbb{E}\left[\exp \left\{2 \omega_{B} \sup \left\{\left|B^{H}(r)\right| ; r \in[0, T]\right\}\right\}\right]\left\|U_{n}(., 0) x_{0}-U(., 0) x_{0}\right\|_{\mathscr{C}([0, T] ; V)}^{2} \xrightarrow[n \rightarrow+\infty]{ } 0 .
\end{aligned}
$$

Hence

$$
\int_{0}^{t}\left\langle X_{n}(r), A^{*}(r) y\right\rangle_{V} \mathrm{~d} r \underset{n \rightarrow+\infty}{ } \int_{0}^{t}\left\langle X(r), A^{*}(r) y\right\rangle_{V} \mathrm{~d} r \quad \text { in } \quad L^{2}(\Omega)
$$

Further, by (3.1), (2.10), (3.7), and (U2) we obtain

$$
\begin{aligned}
\mathbb{E} \mid & \left.\int_{0}^{t}\left\langle H\left(r^{2 H-1}-u_{n}(r)\right) X_{n}(r),\left(B^{*}\right)^{2} y\right\rangle_{V} \mathrm{~d} r\right|^{2} \\
& =\mathbb{E}\left|\int_{0}^{t}\left\langle H\left(r^{2 H-1}-u_{n}(r)\right) S_{B}\left(B^{H}(r)\right) U_{n}(r, 0) x_{0},\left(B^{*}\right)^{2} y\right\rangle_{V} \mathrm{~d} r\right|^{2} \\
& \leq H^{2}\left\|\left(B^{*}\right)^{2} y\right\|_{V}^{2} M_{B}^{2} \mathbb{E}\left[\exp \left\{2 \omega_{B} \sup \left\{\left|B^{H}(r)\right| ; r \in[0, T]\right\}\right\}\right] K_{U}^{2}\left\|x_{0}\right\|_{V}^{2} \\
& \times\left(\int_{0}^{T}\left(r^{2 H-1}-u_{n}(r)\right) \mathrm{d} r\right)^{2} \xrightarrow[n \rightarrow+\infty]{ } 0,
\end{aligned}
$$

thus

$$
\int_{0}^{t}\left\langle H\left(r^{2 H-1}-u_{n}(r)\right) X_{n}(r),\left(B^{*}\right)^{2} y\right\rangle_{V} \mathrm{~d} r_{n \rightarrow+\infty} 0 \quad \text { in } \quad L^{2}(\Omega)
$$

From the proof of the previous lemma also follows that the left-hand side of (3.10) converges to $\langle X(t), y\rangle_{V}$, therefore there exists a random variable $Y_{y}(t)$ such that

$$
\begin{equation*}
\int_{0}^{t}\left\langle X_{n}(r), B^{*} y\right\rangle_{V} \mathrm{~d} B^{H}(r) \xrightarrow[n \rightarrow+\infty]{ } Y_{y}(t) \quad \text { in } \quad L^{2}(\Omega) \tag{3.11}
\end{equation*}
$$

By Proposition 3.2 we have that the process $\left\{\left\langle X_{n}(r), B^{*} y\right\rangle_{V}, r \in[0, t]\right\}$ is Skorokhod integrable with respect to the fractional Brownian motion. Moreover, analogous to Lemma 3.3 we obtain

$$
\left\{\left\langle X_{n}(r), B^{*} y\right\rangle_{V}, r \in[0, t]\right\},\left\{\left\langle X(r), B^{*} y\right\rangle_{V}, r \in[0, t]\right\} \in L^{2}\left(\Omega ; L^{2}([0, t])\right)
$$

and

$$
\int_{0}^{t} \mathbb{E}\left|\left\langle X_{n}(r), B^{*} y\right\rangle_{V}-\left\langle X(r), B^{*} y\right\rangle_{V}\right|^{2} \mathrm{~d} r \underset{k \rightarrow+\infty}{ } 0
$$

for any $n \in \mathbb{N}$. Hence by the closedness of the Skorokhod integral we have that the process $\left\{\left\langle X(r), B^{*} y\right\rangle_{V}, r \in[0, t]\right\}$ is Skorokhod integrable with respect to the fractional Brownian motion and

$$
Y_{y}(t)=\int_{0}^{t}\left\langle X(r), B^{*} y\right\rangle_{V} \mathrm{~d} B^{H}(r) \quad \mathbb{P}-\text { a.s. }
$$

(see [2], Remark 3.4.2) for any $t \in[0, T]$. Thus the process $\{X(t), t \in[0, T]\}$ satisfies the equality

$$
\langle X(t), y\rangle_{V}=\left\langle x_{0}, y\right\rangle_{V}+\int_{0}^{t}\left\langle X(r), A^{*}(r) y\right\rangle_{V} \mathrm{~d} r+\int_{0}^{t}\left\langle X(r), B^{*} y\right\rangle_{V} \mathrm{~d} B^{H}(r) \quad \mathbb{P}-\text { a.s. }
$$

for any $t \in[0, T]$ and $y \in D^{*}$ and Theorem 3.4 follows.

## 4. Examples

In this section we give two examples of a stochastic partial differential equation illustrating the results obtained in the previous section.

Example 4.1 Consider the following stochastic parabolic equation of the second order

$$
\begin{align*}
\frac{\partial u}{\partial t}(t, x) & =L(t, x) u+b u(t, x) \frac{\mathrm{d} B^{H}}{\mathrm{~d} t},  \tag{4.1}\\
u(0, x) & =x_{0}(x), x \in \mathscr{O} \\
u(t, x) & =0,(t, x) \in[0, T] \times \partial \mathscr{O},
\end{align*}
$$

where $\mathscr{O} \subset \mathbb{R}^{d}$ is a bounded domain with the boundary of class $\mathscr{C}^{2}, b \in \mathbb{R} \backslash\{0\}$ and

$$
L(t, x) u=a_{0}(t, x) u(t, x)+\sum_{i=1}^{d} a_{i}(t, x) \frac{\partial u}{\partial x_{i}}(t, x)+\sum_{i, j=1}^{d} a_{i j}(t, x) \frac{\partial^{2} u}{\partial x_{i} \partial x_{j}}(t, x)
$$

is a uniformly strongly elliptic operator on $\mathscr{O}$, i.e. there exists a constant $\vartheta>0$ such that

$$
\sum_{i, j=1}^{d} a_{i j}(t, x) \zeta_{i} \zeta_{j}>\vartheta\| \| \|_{\mathbb{R}^{d}}^{2}
$$

for all $(t, x) \in[0, T] \times \overline{\mathscr{O}}$ and $0 \neq \zeta=\left(\zeta_{1}, \ldots, \zeta_{d}\right) \in \mathbb{R}^{d}$.
The functions $a_{0}(t,),. a_{i}(t,),. a_{i j}(t,.) \in \mathscr{C}^{\infty}(\overline{\mathscr{O}})$ for any $i, j=1, \ldots, d$ and $t \in[0, T]$. Equation (4.1) can be rewritten in the form

$$
\begin{align*}
\mathrm{d} X(t) & =A(t) X(t) \mathrm{d} t+B X(t) \mathrm{d} B^{H}(t)  \tag{4.2}\\
X(0) & =x_{0}
\end{align*}
$$

for $t \in[0, T]$, where $V=L^{2}(\mathscr{O})$,

$$
(A(t) u)(x)=L(t, x) u
$$

where $\operatorname{Dom}(A(t))=D=H^{2}(\mathscr{O}) \cap H_{0}^{1}(\mathscr{O})$ and $B=b I \in \mathscr{L}(V)$.
Assume that

$$
\sup _{x \in \mathscr{O}}\left\{\left|a_{0}(t, x)-a_{0}(s, x)\right|,\left|a_{i}(t, x)-a_{i}(s, x)\right|,\left|a_{i j}(t, x)-a_{i j}(s, x)\right|\right\} \leq M|t-s|^{\gamma}
$$

for any $s, t \in[0, T], i, j=1, \ldots, d$, and some constants $M>0,0<\gamma<1$ then the assumptions (A1), (A2), (A3) are satisfied (cf. Theorem 3.8.3, [13]). The adjoint operator $A^{*}(t)$ has the same form as the operator $A(t)$ only with other coefficients. So the domain $\operatorname{Dom}\left(A^{*}(t)\right)=D^{*}=D=\operatorname{Dom}(A(t))$ is independent of $t$. Also conditions $(\mathrm{B} 1),(\mathrm{B} 2),(2.8),(\mathrm{AB})$ and $\operatorname{Dom}\left(B^{2}\right) \supset \operatorname{Dom}\left((-A(0))^{\alpha}\right)$ for some $\alpha \in(0,1)$ are trivially satisfied. Moreover, we have to assume that (2.6) and (3.4). Then the assumption of Theorem 3.4 are satisfied thus there exists a weak solution to the equation (4.2).

Example 4.2 Consider the equation

$$
\begin{align*}
\frac{\partial u}{\partial t}(t, x) & =-\frac{\partial^{4} u}{\partial x^{4}}(t, x)-\alpha u(t, x)+\frac{\partial u}{\partial x}(t, x) \frac{\mathrm{d} B^{H}}{\mathrm{~d} t}  \tag{4.3}\\
u(0, x) & =x_{0}(x)
\end{align*}
$$

in the weighted space $V=L_{\rho}^{2}(\mathbb{R})$ with the weight $\mathrm{e}^{-\rho|x|}, x \in \mathbb{R}$, and some fixed positive constant $\rho$, where $(t, x) \in \mathbb{R}^{+} \times \mathbb{R}$. The operator $A=-\frac{\partial^{4}}{\partial x^{4}}-\alpha I$ defined on the domain $D=\operatorname{Dom}(A)=W^{4,2}(\mathbb{R})$ generates a strongly continuous semigroup $\left\{S_{A}(t), t \in[0, T]\right\}$ on $V$ which is exponentially stable for any fixed $\alpha>0$ (see e.g. [10]). The operator $B=\frac{\partial}{\partial x}$ with the domain $\operatorname{Dom}(B)=W^{1,2}(\mathbb{R})$ generates a strongly continuous group $\left\{S_{B}(t), t \in \mathbb{R}\right\}$ on $V$ which is a shift operator

$$
\left(S_{B}(t) u\right)(x)=u(t+x), t, x \in \mathbb{R} .
$$

Moreover, $D=D^{*}=\operatorname{Dom}\left(A^{*}\right), \operatorname{Dom}\left(B^{2}\right)=\operatorname{Dom}\left(\left(B^{*}\right)^{2}\right)=W^{2,2}(\mathbb{R})$ and $S_{B}(t)$ commute with $A$ on $D$ for each $t \in[0, T]$. The operators

$$
\left\{A_{n}(t)=-\frac{\partial^{4}}{\partial x^{4}}-\alpha I-H u_{n}(t) \frac{\partial^{2}}{\partial x^{2}}, t \in[0, T]\right\}
$$

are strongly elliptic and generate a strongly continuous evolution system $\left\{U_{n}(t, s), 0 \leq\right.$ $\leq s \leq t \leq T\}$.
It remains to show (2.8), i.e.

$$
\left\|S_{A}(t) B^{2}\right\|_{\mathscr{L}(V)} \leq \frac{C_{A}}{t^{\beta}}
$$

for some constants $C_{A}>0,0<\beta<2 H$ and $0 \leq t \leq T$.
Recall (see e.g. [6]) that there exists the fundamental solution $G \in \mathscr{C}^{\infty}\left(\mathbb{R}^{+} \times \mathbb{R} \times \mathbb{R}\right)$ to the operator $\frac{\partial}{\partial t}-A$ with the property

$$
\begin{equation*}
\left|\frac{\partial^{2}}{\partial x^{2}} G(t, x, y)\right| \leq K_{1} t^{-1 / 2} g\left(K_{2} t,|x-y|\right), t \in(0, T], x, y \in \mathbb{R} \tag{4.4}
\end{equation*}
$$

for some constants $K_{1}, K_{2}>0$, where

$$
g(t, z)=t^{-1 / 4} \exp \left\{-\left(\frac{z^{4}}{t}\right)^{1 / 3}\right\}, t>0, z \in \mathbb{R}
$$

Moreover, for any $u \in L^{2}(\mathbb{R})$

$$
\begin{equation*}
\left(S_{A}(t) u\right)(x)=\int_{\mathbb{R}} G(t, x, y) u(y) \mathrm{d} y, t>0, x \in \mathbb{R} \tag{4.5}
\end{equation*}
$$

Since the semigroup $\left\{S_{A}(t), t \geq 0\right\}$ is self-adjoint on $L^{2}(\mathbb{R})$ the equality

$$
\left\langle S_{A}(t) u, v\right\rangle_{L^{2}(\mathbb{R})}=\left\langle u, S_{A}(t) v\right\rangle_{L^{2}(\mathbb{R})}, u, v \in L^{2}(\mathbb{R}),
$$

holds, so using (4.5) and Fubini Theorem we obtain

$$
\left\langle S_{A}(t) u, v\right\rangle_{L^{2}(\mathbb{R})}=\int_{\mathbb{R}} \int_{\mathbb{R}} G(t, x, y) u(y) \mathrm{d} y v(x) \mathrm{d} x=\int_{\mathbb{R}^{2}} G(t, x, y) u(y) v(x) \mathrm{d} x \mathrm{~d} y
$$

and

$$
\left\langle u, S_{A}(t) v\right\rangle_{L^{2}(\mathbb{R})}=\int_{\mathbb{R}} u(y) \int_{\mathbb{R}} G(t, y, x) v(x) \mathrm{d} x \mathrm{~d} y=\int_{\mathbb{R}^{2}} G(t, y, x) u(y) v(x) \mathrm{d} x \mathrm{~d} y
$$

Thus $G(t, x, y)=G(t, y, x), t>0, x, y \in \mathbb{R}$.
Let $\vartheta_{\rho} \in \mathscr{C}^{\infty}(\mathbb{R})$ be a smooth approximation of the weight $\mathrm{e}^{-\rho|x|}, x \in \mathbb{R}$, such that $\vartheta_{\rho}(x)=\mathrm{e}^{-\rho|x|},|x| \geq 1$. Then

$$
\begin{equation*}
\left(g(t, .) * \vartheta_{\rho}\right)(x) \leq K_{3} \vartheta_{\rho}(x), t \in[0, T], x \in \mathbb{R} \tag{4.6}
\end{equation*}
$$

for some constant $K_{3}>0$.
Take $u \in \mathscr{C}_{0}^{\infty}(\mathbb{R})$. Then using (4.5), symmetry of $G$, (4.4), Jensen inequality and (4.6)

$$
\begin{aligned}
& \int_{\mathbb{R}}\left|\left(S_{A}(t) B^{2} u\right)(x)\right|^{2} \vartheta_{\rho}(x) \mathrm{d} x=\int_{\mathbb{R}}\left|\int_{\mathbb{R}} G(t, x, y) \frac{\partial^{2}}{\partial y^{2}} u(y) \mathrm{d} y\right|^{2} \vartheta_{\rho}(x) \mathrm{d} x \\
&=\int_{\mathbb{R}}\left|\int_{\mathbb{R}} G(t, y, x) \frac{\partial^{2}}{\partial y^{2}} u(y) \mathrm{d} y\right|^{2} \vartheta_{\rho}(x) \mathrm{d} x=\int_{\mathbb{R}}\left|\int_{\mathbb{R}} \frac{\partial^{2}}{\partial y^{2}} G(t, y, x) u(y) \mathrm{d} y\right|^{2} \vartheta_{\rho}(x) \mathrm{d} x \\
& \leq K_{1}^{2} t^{-1} \int_{\mathbb{R}}\left(\int_{\mathbb{R}} g\left(K_{2} t,|x-y|\right)|u(y)| \mathrm{d} y\right)^{2} \vartheta_{\rho}(x) \mathrm{d} x \\
& \leq K K_{1}^{2} t^{-1} \int_{\mathbb{R}} \int_{\mathbb{R}} g\left(K_{2} t,|x-y|\right)|u(y)|^{2} \mathrm{~d} y \vartheta_{\rho}(x) \mathrm{d} x \leq K K_{1}^{2} K_{3} t^{-1} \int_{\mathbb{R}}|u(y)|^{2} \vartheta_{\rho}(y) \mathrm{d} y \\
&=K K_{1}^{2} K_{3} t^{-1}\|u\|_{L_{\rho}^{2}(\mathbb{R})}^{2}
\end{aligned}
$$

Since $\mathscr{C}_{0}^{\infty}(\mathbb{R})$ is dense in $L_{\rho}^{2}(R)$ we obtain that

$$
\left\|S_{A}(t) B^{2}\right\|_{\mathscr{L}(V)} \leq \frac{\left(K K_{1}^{2} K_{3}\right)^{1 / 2}}{t^{1 / 2}}, t>0
$$

Hence the condition $1 / 2<2 H$ can be satisfied only for $H>1 / 4$. Therefore, under this hypothesis $H>1 / 4$ the equation (4.3) has a weak solution

$$
\left\{X(t)=S_{B}\left(B^{H}(t)\right) U(t, 0) u_{0}, t \in[0, T]\right\}
$$

for any initial value $u_{0} \in V$.

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