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# A CAUCHY-POMPEIU FORMULA IN SUPER DUNKL-CLIFFORD ANALYSIS 

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Abstract. Using a distributional approach to integration in superspace, we investigate a Cauchy-Pompeiu integral formula in super Dunkl-Clifford analysis and several related results, such as Stokes formula, Morera's theorem and Painlevé theorem for super Dunklmonogenic functions. These results are nice generalizations of well-known facts in complex analysis.

Keywords: super Dunkl-Dirac operator; Stokes formula; Cauchy-Pompeiu integral formula; Morera's theorem; Painlevé theorem

MSC 2010: 30G35, 26B20, 58C50

## 1. Introduction

Dunkl operators (also called differential-difference operators), introduced by Dunkl (see [7]), are invariant under a finite reflection group and are also pairwise commuting. These operators not only provide a useful tool in the study of special functions with root systems (see [8]), but also they are closely related to some particular representations of degenerated affine Hecke algebras (see [16]) and integrable systems of Calogero-Moser-Sutherland type (see [12]). In 2006, Cerejeiras, Kähler and Ren defined the Dunkl-Dirac operator (see [2]) and constructed the Stokes formula in Clifford analysis by Dunkl transforms (see [15]). The theory of Dunkl-Clifford analysis is further developed in [1], [10], [11], [14], [4] and [17]. In 2013, Fei investigated the fundamental solutions to the Dunkl-Dirac equation, and also obtained the Cauchy integral formula with a Dunkl-Cauchy kernel (see [9]).

[^0]Recently, Sommen, De Bie and others have studied a superspace of dimension $(m, 2 n)$ in the frame of Clifford analysis (see [5], [6], [3]). Superspaces are spaces equipped with both a set of commuting variables and a set of anti-commuting variables in order to describe the properties of bosons and fermions in quantum mechanics. In [5], they defined the super Dirac operator (i.e., the Dirac operator in superspace) by the Dirac operator in $\mathbb{R}^{m}$. In [3], using a distributional approach to integration in superspace, they investigated some properties of the super Dirac operator, such as Stokes formula, Cauchy integral formula and Morera's theorem. Then, we investigated Cauchy-Pompeiu formulas for iterates of Dirac operators and polynomial Dirac operators in superspace (see [18], [19]). Inspired by the abovementioned results, we want to develop further these ideas for the super Dunkl-Dirac operator.

The paper is organized as follows. In Section 2 we recall the necessary results on the super Dunkl-Clifford analysis (i.e., Dunkl-Clifford analysis in superspace). In Section 3, inspired by De Bie et al., we construct fundamental solutions for the super Dunkl-Laplace and super Dunkl-Dirac operators by the fundamental solutions of the natural powers of the Laplace operator in Dunkl-Clifford analysis. In Section 4, using a distributional approach to integration in superspace, combined with the Stokes formula in Dunkl-Clifford analysis, we consider the Stokes formula in super DunklClifford analysis. Applying this formula, we get the Cauchy-Pompeiu formula for the super Dunkl-Dirac operator and Morera's theorem for super Dunkl-monogenic functions. Furthermore, using Morera's theorem, we obtain the Painlevé theorem for super Dunkl-monogenic functions.

## 2. Preliminaries

2.1. Dunkl-Clifford analysis in $\mathbb{R}^{m}$. Denote by $\langle\cdot, \cdot\rangle$ the standard Euclidean scalar product in $\mathbb{R}^{m}$ and by $|x|=\langle x, x\rangle^{1 / 2}$ the associated norm. For $\alpha \in \mathbb{R}^{m} \backslash\{0\}$, the reflection $\sigma_{\alpha}$ in the hyperplane orthogonal to $\alpha$ is given by

$$
\sigma_{\alpha} x=x-2 \frac{\langle\alpha, x\rangle}{|\alpha|^{2}} \alpha, \quad x \in \mathbb{R}^{m} .
$$

A finite set $\mathrm{R} \subset \mathbb{R}^{m} \backslash\{0\}$ is called a root system if $\alpha \mathbb{R} \cap \mathrm{R}=\{\alpha,-\alpha\}$ and $\sigma_{\alpha} \mathrm{R}=\mathrm{R}$ for all $\alpha \in \mathbf{R}$. Each root system can be written as a disjoint union $\mathbf{R}=\mathbf{R}_{+} \cup\left(-\mathbf{R}_{+}\right)$, where $\mathrm{R}_{+}$and $-\mathrm{R}_{+}$are separated by a hyperplane through the origin. The subgroup $G \subset O(m)$ generated by the reflections $\left\{\sigma_{\alpha}: \alpha \in \mathrm{R}\right\}$ is called the finite reflection group associated with R. For more information on finite reflection groups we refer the reader to [13].

A multiplicity function $\kappa$ on the root system R is a $G$-invariant function $\kappa: \mathrm{R} \rightarrow \mathbb{C}$, i.e., $\kappa(\alpha)=\kappa(g \alpha)$ for all $g \in G$. We will denote $\kappa(\alpha)$ by $\kappa_{\alpha}$. For abbreviation, we introduce the index

$$
\gamma=\gamma_{\kappa}=\sum_{\alpha \in R_{+}} \kappa_{\alpha} .
$$

Moreover, let $h_{\kappa}(\underline{x})$ denote the weight function

$$
h_{\kappa}(\underline{x})=\prod_{\alpha \in \mathrm{R}_{+}}|\langle\alpha, \underline{x}\rangle|^{\kappa_{\alpha}} .
$$

In this paper, we will assume that $\kappa_{\alpha} \geqslant 0$ and $\gamma_{\kappa}>0$.
For each subsystem $\mathrm{R}_{+}$and multiplicity function $\kappa_{\alpha}$ we have the Dunkl operators

$$
T_{i} f(x)=\frac{\partial f(x)}{\partial x_{i}}+\sum_{\alpha \in \mathrm{R}_{+}} \kappa_{\alpha} \frac{f(x)-f\left(\sigma_{\alpha} x\right)}{\langle x, \alpha\rangle} \alpha_{i}, \quad i=1, \ldots, m
$$

for $f \in C^{1}\left(\mathbb{R}^{m}\right)$. An important consequence is that the operators $T_{i}$ are mutually commutating, that is, $T_{i} T_{j}=T_{j} T_{i}$.

We consider a function $f: \mathbb{R}^{m} \rightarrow \mathbb{R}_{0, m}$. Hereby $\mathbb{R}_{0, m}$ denotes the Clifford algebra over $\mathbb{R}^{m}$ generated by $\left\{e_{1}, e_{2}, \ldots, e_{m}\right\}$ satisfying the anti-commutation relationship $e_{i} e_{j}+e_{j} e_{i}=-2 \delta_{i j}$, where $\delta_{i j}$ is the Kronecker symbol. By $\underline{x}=\sum_{i=1}^{m} x_{i} e_{i}$ we denote the so-called vector variable. A Dunkl-Dirac operator in $\mathbb{R}^{m}$ for the corresponding reflection group $G$ is defined as $D_{h}=\sum_{i=1}^{m} e_{i} T_{i}$, where $T_{i}$ are Dunkl operators. Functions belonging to the kernel of the Dunkl-Dirac operator $D_{h}$ are called Dunkl-monogenic functions.

The classical Dunkl Laplacian is defined as

$$
\Delta_{h}=-D_{h}^{2}=\sum_{i=1}^{m} T_{i}^{2}
$$

When $\kappa=0$, the Dunkl Laplacian $\Delta_{h}$ is just the ordinary Laplacian. Functions belonging to the kernel of the Dunkl Laplacian $\Delta_{h}$ are called Dunkl-harmonic functions.
2.2. Dunkl-Clifford analysis in $\mathbb{R}^{m \mid 2 n}$. On a superspace of dimension $(m, 2 n)$, we have $m$ commuting (or bosonic) variables $x_{1}, \ldots, x_{m}$ and $2 n$ anti-commuting (or fermionic) variables $\grave{x}_{1}, \ldots, \grave{x}_{2 n}$ subject to

$$
\left\{\begin{array}{l}
x_{i} x_{j}=x_{j} x_{i} \\
\grave{x}_{i} \grave{x}_{j}=-\grave{x}_{j} \grave{x}_{i} \\
x_{i} \grave{x}_{j}=\grave{x}_{j} x_{i}
\end{array}\right.
$$

Furthermore, we have the Clifford algebra generators $e_{1}, \ldots, e_{m}$ and the symplectic Clifford algebra generators $\grave{e}_{1}, \ldots, \grave{e}_{2 n}$. They obey the following rules:

$$
\left\{\begin{array}{l}
e_{j} e_{k}+e_{k} e_{j}=-2 \delta_{j k}, \\
\grave{e}_{2 j} \grave{e}_{2 k}-\grave{e}_{2 k} \grave{e}_{2 j}=0, \\
\grave{e}_{2 j-1} \grave{e}_{2 k-1}-\grave{e}_{2 k-1} \grave{e}_{2 j-1}=0, \\
\grave{e}_{2 j-1} \grave{e}_{2 k}-\grave{e}_{2 k} \grave{e}_{2 j-1}=\delta_{j k}, \\
e_{j} \grave{e}_{k}+\grave{e}_{k} e_{j}=0 .
\end{array}\right.
$$

Taking the above relations into account, we study the superspace by the real algebra

$$
\operatorname{Alg}\left(x_{i}, e_{i} ; \grave{x}_{j}, \grave{e}_{j}\right)=\operatorname{Alg}\left(x_{i}, \grave{x}_{j}\right) \otimes \operatorname{Alg}\left(e_{i}, \grave{e}_{j}\right), \quad i=1, \ldots, m, j=1, \ldots, 2 n
$$

which is the tensor product of $\operatorname{Alg}\left(x_{i}, \grave{x}_{j}\right)$ and $\operatorname{Alg}\left(e_{i}, \grave{e}_{j}\right)$. The algebra $\operatorname{Alg}\left(x_{i}, \grave{x}_{j}\right)$ is called a scalar algebra, denoted by $\mathcal{P}$, and the algebra $\operatorname{Alg}\left(e_{i}, \grave{e}_{j}\right)$ is a Clifford algebra, denoted by $\mathcal{C}_{m \mid 2 n}$. Moreover, the elements of both these algebras can commute with each other. When $n=0$, we have that $\mathcal{P} \otimes \mathcal{C}_{m \mid 0}=\mathbb{R}\left[x_{1}, \ldots, x_{m}\right] \otimes \mathbb{R}_{0, m}$, where $\mathbb{R}\left[x_{1}, \ldots, x_{m}\right]$ is generated by the commuting variables $x_{i}$. In the case $\mathcal{C}_{m \mid 0} \cong \mathbb{R}_{0, m}$, $\mathbb{R}_{0, m}$ is the standard orthogonal Clifford algebra. When $m=0$, we have that $\mathcal{P} \otimes$ $\mathcal{C}_{0 \mid 2 n}=\Lambda_{2 n} \otimes \mathcal{W}_{2 n}$, with $\Lambda_{2 n}$ being the Grassmann algebra generated by $\grave{x_{j}}$. In the case $\mathcal{C}_{0 \mid 2 n} \cong \mathcal{W}_{2 n}, \mathcal{W}_{2 n}$ is the Weyl algebra generated by $\grave{e}_{j}$.

We define the super vector variable $x$ as follows:

$$
x=\underline{x}+\underline{\grave{x}},
$$

where $\underline{x}=\sum_{i=1}^{m} x_{i} e_{i}$ and $\underline{\grave{x}}=\sum_{j=1}^{2 n} \grave{x}_{j} \grave{e}_{j}$. By direct calculation, we obtain the square of $x$ :

$$
x^{2}=\underline{\grave{x}}^{2}+\underline{x}^{2}, \quad \text { where } \underline{\grave{x}}^{2}=\sum_{j=1}^{n} \grave{x}_{2 j-1} \grave{x}_{2 j} \text { and } \underline{x}^{2}=-\sum_{i=1}^{m} x_{i}^{2} .
$$

Note that $\underline{x}^{2}=-\sum_{i=1}^{m} x_{i}^{2}$ is the norm squared of a vector in Euclidean space.
Thus, we define a more general function space as

$$
C^{k}(\Omega) \otimes \Lambda_{2 n} \otimes \mathcal{C}_{m \mid 2 n}
$$

where $C^{k}(\Omega)$ denotes space of $k$-times continuously differentiable real-valued functions defined in some domain $\Omega \subset \mathbb{R}^{m}$. We use the notation

$$
C^{k}(\Omega)_{m \mid 2 n}=C^{k}(\Omega) \otimes \Lambda_{2 n}
$$

The super Dunkl-Dirac operator is defined to be

$$
D=-D_{h}+D_{f}=-\sum_{i=1}^{m} e_{i} T_{i}+2 \sum_{j=1}^{n}\left(\grave{e}_{2 j} \partial_{\grave{x}_{2 j-1}}-\grave{e}_{2 j-1} \partial_{\grave{x}_{2 j}}\right)
$$

where $D_{h}$ is the bosonic Dunkl-Dirac operator and $D_{f}$ is the fermionic Dunkl-Dirac operator.

If we let $D$ act on $x$, we see that

$$
M:=\frac{1}{2} D x=-n+\frac{m}{2}+\gamma_{\kappa},
$$

where $M$ is the Dunkl version of the super-dimension in contrast to the non-Dunkl case of the super-dimension in [6]. The numerical parameter $M$ is regarded as the ground level energy in physics.

As usual, functions belonging to the kernel of the super Dunkl-Dirac operator are called super Dunkl-monogenic functions.

The square of the left super Dunkl-Dirac operator is the super Dunkl-Laplace operator

$$
\Delta=D^{2}=-\Delta_{h}+\Delta_{f}=-\sum_{i=1}^{m} T_{i}^{2}+4 \sum_{j=1}^{n} \partial_{\grave{x}_{2 j-1}} \partial_{\grave{x}_{2 j}}
$$

where $\Delta_{h}$ is the Dunkl-Laplace operator and $\Delta_{f}$ is the fermionic Dunkl-Laplace operator.

Functions belonging to the kernel of the super Dunkl-Laplace operator are called super Dunkl-harmonic functions.
2.3. Integration in Dunkl superspace. The integration in Dunkl superspace is defined by

$$
\int_{\mathbb{R}^{m \mid 2 n}} \cdot=\int_{\mathbb{R}^{m}} h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) \int_{B} \cdot=\int_{B} \int_{\mathbb{R}^{m}} h_{\kappa}^{2}(\underline{x}) \cdot \mathrm{d} V(\underline{x}),
$$

where $\mathrm{d} V(\underline{x})=\mathrm{d} x_{1} \ldots \mathrm{~d} x_{m}$ is the usual Lebesgue measure in $\mathbb{R}^{m}$, and the integration

$$
\int_{B} \cdot=\pi^{-n} \partial_{\grave{x}_{2 n}} \ldots \partial_{\grave{x}_{1}} .
$$

used on $\Lambda^{2 n}$ is the so-called Berezin integration.

## 3. Fundamental solutions for the Dunkl-Laplace and Dunkl-Dirac operators in superspace

We introduce the Mehta-type constant

$$
c_{h}=\left(\int_{\mathbb{R}^{m}} \exp \left(-\|\underline{x}\|^{2}\right) h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})\right)^{-1}
$$

which is known for all Coxeter groups $W$ (see [8]).
Lemma 3.1 ([9]). If $0<s<\gamma+d / 2$, then the functions $K_{s}^{m \mid 0}(\underline{x})$ given by

$$
K_{s}^{m \mid 0}(\underline{x})=\frac{(-1)^{s} c_{h} \Gamma(\gamma+d / 2-s)}{4^{s} \Gamma(s)} \frac{1}{\|\underline{x}\|^{2 \gamma+d-2 s}}
$$

are fundamental solutions for the natural powers of the Dunkl-Laplace operator $\Delta_{h}$.
Concerning the refinement to Clifford analysis, we clearly have that $D_{h} K_{s}^{m \mid 0}(\underline{x})$ are fundamental solutions for the natural powers of the Dunkl-Dirac operator $D_{h}$.

Lemma 3.2 ([9]). For $l \in \mathbb{N}$, we denote by $K_{l}^{m \mid 0}(\underline{x})$ the fundamental solutions for the natural powers of the Dunkl-Dirac operator $D_{h}$.

For $2 \gamma+m$ odd,

$$
K_{l}^{m \mid 0}(\underline{x})= \begin{cases}c_{\kappa, m, l} \frac{\underline{x}}{\|\underline{x}\|^{2 \gamma+m-l+1}}, & l \text { odd } \\ c_{\kappa, m, l} \frac{\underline{x}}{\|\underline{x}\|^{2 \gamma+m-l}}, & l \text { even. }\end{cases}
$$

For $2 \gamma+m$ even,

$$
K_{l}^{m \mid 0}(\underline{x})= \begin{cases}c_{\kappa, m, l} \frac{\underline{x}}{\|\underline{x}\|^{2 \gamma+m-l+1}}, & l \text { odd and } l<2 \gamma+m-1, \\ c_{\kappa, m, l} \frac{\underline{x}}{\|\underline{x}\|^{2 \gamma+m-l}}, & l \text { even and } l<2 \gamma+m \\ \left(c_{\kappa, m, l} \log \|\underline{x}\|+c_{\kappa, m, l}^{\prime}\right) \frac{\underline{x}}{\|\underline{x}\|^{2 \gamma+m-l+1}}, & l \text { odd and } l \geqslant 2 \gamma+m-1 \\ \left(c_{\kappa, m, l} \log \|\underline{x}\|+c_{\kappa, m, l}^{\prime}\right) \frac{\underline{x}}{\|\underline{x}\|^{2 \gamma+m-l}}, & l \text { even and } l \geqslant 2 \gamma+m\end{cases}
$$

From the above lemmas, we have the fundamental solution for the super DunklLaplace operator as follows.

Theorem 3.3. The function $K_{2}^{m \mid 2 n}(x)$ given by

$$
K_{2}^{m \mid 2 n}(x)=\pi^{n} \sum_{k=0}^{n} \frac{4^{k} k!}{(n-k)!} K_{2 k+2}^{m \mid 0} \underline{\grave{x}}^{2 n-2 k},
$$

with $K_{2 k+2}^{m \mid 0}$ as in Lemma 3.1, is a fundamental solution for the operator $\Delta$.
Proof. From the definition of the super Dunkl-Laplace operator, we have

$$
\begin{aligned}
& \Delta \pi^{n} \sum_{k=0}^{n} \frac{4^{k} k!}{(n-k)!} K_{2 k+2}^{m \mid 0} \grave{x}^{2 n-2 k}=\left(-\Delta_{h}+\Delta_{f}\right) \pi^{n} \sum_{k=0}^{n} \frac{4^{k} k!}{(n-k)!} K_{2 k+2}^{m \mid 0} \grave{x}^{2 n-2 k} \\
& = \\
& \pi^{n} \sum_{k=0}^{n} \frac{4^{k} k!}{(n-k)!}\left(-\Delta_{h}\right) K_{2 k+2}^{m \mid 0} \grave{x}^{2 n-2 k} \\
& \quad+\pi^{n} \sum_{k=0}^{n-1} \frac{4^{k} k!}{(n-k)!} K_{2 k+2}^{m \mid 0}(2 n-2 k)(-2 k-2) \underline{x}^{2 n-2 k-2} \\
& =\delta(\underline{x}) \frac{\pi^{n}}{n!}(\grave{x})^{2 n}+\pi^{n} \sum_{k=1}^{n} \frac{4^{k} k!}{(n-k)!} K_{2 k}^{m \mid 0} \underline{\underline{x}}^{2 n-2 k} \\
& \quad+\pi^{n} \sum_{k=1}^{n} \frac{4^{k-1}(k-1)!}{(n-k+1)!} K_{2 k}^{m \mid 0}(2 n-2 k+2)(-2 k) \underline{\grave{x}}^{2 n-2 k} \\
& =\delta(\underline{x}) \frac{\pi^{n}}{n!}(\grave{x})^{2 n}+\pi^{n} \sum_{k=1}^{n}\left(\frac{4^{k} k!}{(n-k)!}+\frac{4^{k-1}(k-1)!}{(n-k+1)!}(2 n-2 k+2)(-2 k)\right) K_{2 k}^{m \mid 0} \grave{x}^{2 n-2 k} \\
& =\delta(x),
\end{aligned}
$$

where $\delta(x)=\delta(\underline{x}) \pi^{n} n!^{-1} \underline{\grave{x}}^{2 n}$ is the super distribution in $\mathbb{R}^{m \mid 2 n}$. Thus, we completed the proof.

Note that $\Delta K_{2}^{m \mid 2 n}(x)=\delta(x)$. It follows that a fundamental solution for the super Dunkl-Dirac operator $D$ is given by $D K_{2}^{m \mid 2 n}(x)$. This leads to the following statement.

Theorem 3.4. The function $K_{1}^{m \mid 2 n}(x)$ given by

$$
K_{1}^{m \mid 2 n}(x)=\pi^{n} \sum_{k=0}^{n-1} \frac{2 \cdot 4^{k} k!}{(n-k-1)!} K_{2 k+2}^{m \mid 0} \underline{\grave{x}}^{2 n-2 k-1}-\pi^{n} \sum_{k=0}^{n-1} \frac{4^{k} k!}{(n-k-1)!} K_{2 k+1}^{m \mid 0} \underline{\grave{x}}^{2 n-2 k},
$$

with $K_{2 k+2}^{m \mid 0}$ as in Lemma 3.1 and $K_{2 k+1}^{m \mid 0}=D_{h} K_{2 k+2}^{m \mid 0}$ as in Lemma 3.2, is a fundamental solution for the super Dunkl-Dirac operator $D$.

## 4. Fundamental theorems in super Dunkl-Clifford analysis

4.1. Stokes formula in super Dunkl-Clifford analysis. In [2], we see that the Stokes formula in Dunkl-Clifford analysis reads as follows.

Lemma $4.1([2])$. For $\varphi(\underline{x}), \psi(\underline{x}) \in C^{\infty}(\Omega) \otimes \mathbb{R}_{0, m}$,

$$
\begin{equation*}
\int_{\Omega}\left[\left(\varphi(\underline{x}) D_{h}\right) \psi(\underline{x})+\varphi(\underline{x})\left(D_{h} \psi(\underline{x})\right)\right] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=\int_{\partial \Omega} \varphi(\underline{x}) h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma(\underline{x}) \psi(\underline{x}), \tag{4.1}
\end{equation*}
$$

with the vector-valued surface element $\mathrm{d} \sigma_{\underline{x}}=\sum_{i=1}^{m}(-1)^{i} e_{i} \mathrm{~d} x_{1} \ldots \widehat{\mathrm{~d} x_{i}} \ldots \mathrm{~d} x_{m}$ and the volume element $\mathrm{d} V(\underline{x})=\mathrm{d} x_{1} \ldots \mathrm{~d} x_{m}$.

If we consider a distribution $\alpha$ with compact support and if $f(\underline{x}), g(\underline{x}) \in$ $C^{\infty}\left(\mathbb{R}^{m}\right) \otimes \mathbb{R}_{0, m}$, then

$$
\begin{equation*}
\int_{\mathbb{R}^{m}}\left[\left(f D_{h}\right) \alpha g+f D_{h}(\alpha) g+f \alpha\left(D_{h} g\right)\right] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=0 \tag{4.2}
\end{equation*}
$$

Thus, we have

$$
\begin{equation*}
\int_{\mathbb{R}^{m}}\left[\left(f D_{h}\right) \alpha g+f \alpha\left(D_{h} g\right)\right] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=-\int_{\mathbb{R}^{m}} f D_{h}(\alpha) g h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}), \tag{4.3}
\end{equation*}
$$

which is the most general form of the Stokes formula in Dunkl-Clifford analysis.
Lemma 4.2 (Fermionic Stokes formula, [3]). For $f, g \in \Lambda_{2 n} \otimes \mathcal{W}_{2 n}$ and $\alpha \in \Lambda_{2 n}$, the following holds:

$$
\begin{equation*}
-\int_{B}\left(f \widehat{\alpha} \partial_{\underline{\grave{x}}}\right) g+\int_{B} f \alpha\left(\partial_{\underline{\grave{x}}} g\right)=\int_{B} f\left(\alpha \partial_{\underline{\grave{x}}}\right) g . \tag{4.4}
\end{equation*}
$$

Using Lemmas 4.1 and 4.2, we obtain the Stokes formula in super Dunkl-Clifford analysis as follows.

Theorem 4.3. Let $\Omega \subset \mathbb{R}^{m}$. If $f, g \in C^{\infty}(\Omega)_{m \mid 2 n} \otimes \mathcal{C}_{m \mid 2 n}$, then

$$
\begin{equation*}
\int_{\mathbb{R}^{m \mid 2 n}}[(f \widehat{\alpha} D) g+f \alpha(D g)] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=-\int_{\mathbb{R}^{m \mid 2 n}} f(\alpha D) g h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) \tag{4.5}
\end{equation*}
$$

for $\alpha \in R\left[x_{1}, \ldots, x_{m}\right] \otimes \Lambda_{2 n}$ a distribution with compact support $\Sigma \subset \Omega$.
Proof. For $\alpha=\beta \gamma$ with $\beta \in R\left[x_{1}, \ldots, x_{m}\right]$ and $\gamma \in \Lambda_{2 n}$, we have (4.5) from (4.3) and Lemma 4.2.

Corollary 4.4. Let $\Sigma$ be a compact oriented differentiable $m$-dimensional manifold with smooth boundary $\partial \Sigma$. If $f, g \in C^{1}(\Sigma)_{m \mid 2 n} \otimes \mathcal{C}_{m \mid 2 n}$, then

$$
\begin{align*}
\int_{\Sigma} \int_{B} & {[(f \widehat{\beta} D) g+f \beta(D g)] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) }  \tag{4.6}\\
& =-\int_{\partial \Sigma} \int_{B} f \beta h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} g+\int_{\Sigma} \int_{B} f\left(\beta D_{f}\right) g h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}),
\end{align*}
$$

where $\beta \in \Lambda_{2 n}$.
Proof. This is a special case of Theorem 4.3 for $\alpha=H(\nu) \beta$, with $\nu(\underline{x})>0$ if $x \in \Sigma, \nu(\underline{x})<0$ if $\underline{x} \in \mathbb{R}^{m} \backslash \Sigma$. It is easy to see that (4.6) holds by Lemmas 4.1 and 4.2.
4.2. A Cauchy-Pompeiu formula for the super Dunkl-Dirac operator. First we introduce the translation operator (see [15])

$$
\begin{equation*}
\tau_{y} f(x)=\left(V_{h}\right)_{y}\left(V_{h}\right)_{x}\left[\left(V_{h}\right)^{-1}(f)(x+y)\right], \quad x, y \in \mathbb{R}^{m} \tag{4.7}
\end{equation*}
$$

where $V_{h}$ denotes the Dunkl-intertwining operator, i.e.,

$$
D_{j} V_{h}=V_{h} \frac{\partial}{\partial x_{j}}
$$

and $V_{h}(1)=1$. Then, using this translation operator we have the Dunkl-convolution defined by

$$
\begin{equation*}
f *_{D} g(y)=\int_{\mathbb{R}^{m}} \tau_{y} f(-x) g(x) h_{\kappa}^{2}(x) \mathrm{d} x \tag{4.8}
\end{equation*}
$$

Theorem 4.5. Let $\Omega \subset \mathbb{R}^{m}$ and let $\bar{\Omega}$ be a compact oriented differentiable $m$-dimensional manifold with smooth boundary $\partial \Omega$. Let $f(x) \in C^{\infty}(\Omega)_{m \mid 2 n} \otimes \mathcal{C}_{m \mid 2 n}$ and let the function $K_{1}^{m \mid 2 n}(x)$ be the fundamental solution for the super Dunkl-Dirac operator $D$. Then

$$
\begin{align*}
& \int_{\partial \Omega} \int_{B} \tau_{y} K_{1}^{m \mid 2 n}(-x) h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f(x)  \tag{4.9}\\
& +\int_{\Omega} \int_{B} \tau_{y} K_{1}^{m \mid 2 n}(-x)[D f(x)] h_{k}^{2}(\underline{x}) \mathrm{d} V(\underline{x})= \begin{cases}0, & \underline{y} \in \mathbb{R}^{m} \backslash \bar{\Omega} \\
-f(y), & \underline{y} \in \Omega\end{cases}
\end{align*}
$$

Proof. For $\underline{y} \in \mathbb{R}^{m} \backslash \bar{\Omega}$, it follows by Corollary 4.4 for $\beta=1$ that

$$
\begin{aligned}
& \int_{\partial \Omega} \int_{B} \tau_{y} K_{1}^{m \mid 2 n}(-x) h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f(x) \\
&=- {\left[\int_{\Omega} \int_{B}\left[\tau_{y} K_{1}^{m \mid 2 n}(-x) D\right] f(x) h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})\right.} \\
&\left.\quad+\int_{\Omega} \int_{B} \tau_{y} K_{1}^{m \mid 2 n}(-x)[D f(x)] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})\right] \\
&=- \int_{\Omega} \int_{B} \tau_{y} K_{1}^{m \mid 2 n}(-x)[D f(x)] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) .
\end{aligned}
$$

Thus, we have (4.9) for $\underline{y} \in \mathbb{R}^{m} \backslash \bar{\Omega}$. For $\underline{y} \in \Omega$,

$$
\begin{aligned}
& \int_{\partial \Omega} \int_{B} \tau_{y} K_{1}^{m \mid 2 n}(-x) h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f(x) \\
& =-\left[\int_{\Omega} \int_{B}\left[\tau_{y} K_{1}^{m \mid 2 n}(-x) D\right] f(x) h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})\right. \\
& \left.\quad+\int_{\Omega} \int_{B} \tau_{y} K_{1}^{m \mid 2 n}(-x)[D f(x)] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})\right] \\
& =-\int_{\Omega} \int_{B}\left[\tau_{y} \delta(-x)\right] f(x) h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})-\int_{\Omega} \int_{B} \tau_{y} K_{1}^{m \mid 2 n}(-x)[D f(x)] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) \\
& =-f(y)-\int_{\Omega} \int_{B} \tau_{y} K_{1}^{m \mid 2 n}(-x)[D f(x)] h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) .
\end{aligned}
$$

This implies that (4.9) holds for $\underline{y} \in \Omega$.
4.3. Morera's theorem for super Dunkl-monogenic functions. Applying the Stokes formula in Dunkl-Clifford analysis, we obtain Morera's theorem for Dunklmonogenic functions as follows.

Lemma 4.6. A function $f$ is left Dunkl-monogenic in the open set $\Omega \subset \mathbb{R}^{m}$ if and only if $f$ is continuous in $\Omega$ and

$$
\begin{equation*}
\int_{\partial I} h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f=0 \tag{4.10}
\end{equation*}
$$

for all intervals $I \subset \Omega$.
Furthermore, we have the following lemma, which is an extension of Lemma 4.6.

Lemma 4.7. Let $I \subset \Omega \subset \mathbb{R}^{m}$. If $f, g \in C^{1}(\Omega) \otimes \mathbb{R}_{0, m}$ and

$$
\begin{equation*}
\int_{\partial I} h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f=\int_{I} g h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}), \tag{4.11}
\end{equation*}
$$

then $D_{h} f=g$ in $\Omega$.
Proof. As $g \in C^{1}(\Omega) \otimes \mathbb{R}_{0, m}$, there exists $\varphi \in C^{1}(\Omega) \otimes \mathbb{R}_{0, m}$ such that $g=D_{h} \varphi$. Applying Lemma 4.1 and (4.11), we obtain

$$
\int_{\partial I} h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}}[f-\varphi]=\int_{\partial I} h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f-\int_{I} D_{h} \varphi h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=0 .
$$

It follows by Lemma 4.6 that $f-\varphi$ is left Dunkl-monogenic. Thus we have $D_{h} f=D_{h} \varphi$.

In order to obtain our main result in this section, we need the following lemma.
Lemma 4.8 ([3]). Let $p \in \Lambda_{2 n}$. If

$$
\begin{equation*}
\int_{B} p q=0 \tag{4.12}
\end{equation*}
$$

for any $q \in \Lambda_{2 n}$, then $p=0$.
Theorem 4.9. Let $\Omega \subset \mathbb{R}^{m}$. A function $f \in C^{0}(\Omega)_{m \mid 2 n} \otimes \mathcal{C}_{m \mid 2 n}$ is super Dunklmonogenic in $\Omega$ if and only if

$$
\begin{equation*}
\int_{\partial I} \int_{B} \alpha h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f-\int_{I} \int_{B}\left(\alpha D_{f}\right) f h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=0 \tag{4.13}
\end{equation*}
$$

for all intervals $I \subset \Omega$ and $\alpha \in \Lambda_{2 n}$.
Proof. Suppose that $f$ is super Dunkl-monogenic in $\Omega$. Then (4.13) holds by Corollary 4.4. To the contrary, we suppose that $f \in C^{0}(\Omega)_{m \mid 2 n} \otimes \mathcal{C}_{m \mid 2 n}$. Then

$$
\int_{\partial I} \int_{B} \alpha h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f=\int_{I} \int_{B}\left(\alpha D_{f}\right) f h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})
$$

for all intervals $I \subset \Omega$ and $\alpha \in \Lambda_{2 n}$. Using Lemma 4.2, we get

$$
\int_{I} \int_{B}\left(\alpha D_{f}\right) f h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=\int_{I} \int_{B} \alpha\left(D_{f} f\right) h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) .
$$

Thus, we have

$$
\begin{equation*}
\int_{\partial I} \int_{B} \alpha h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f=\int_{I} \int_{B} \alpha\left(D_{f} f\right) h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) \tag{4.14}
\end{equation*}
$$

If (4.14) holds for every $\alpha$, then it follows by Lemma 4.8 that

$$
\begin{equation*}
\int_{\partial I} h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f=\int_{I} D_{f} f h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) . \tag{4.15}
\end{equation*}
$$

Inspired by De Bie ([6]), we have the full decomposition

$$
f=\sum_{k=0}^{n} \sum_{j=0}^{2 n-2 k} \sum_{l} f_{j, k, l} \grave{\grave{x}} M_{k}^{l, j},
$$

where $M_{k}^{l, j}$ is the space of spherical monogenics of degree $k$ depending on the constants $l, j$. Thus, (4.15) can be rewritten as

$$
\begin{equation*}
\int_{\partial I} h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f_{j-1, k, l}=\int_{I} f_{j, k, l} h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}), \quad j=1, \ldots, 2 n-2 k, \forall I, \tag{4.16}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{\partial I} h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f_{2 n-2 k, k, l}=0, \quad \forall I \tag{4.17}
\end{equation*}
$$

Formula (4.17) implies that $f_{2 n-2 k, k, l}$ is Dunkl-monogenic in $\Omega$, and also implies that $f_{2 n-2 k, k, l} \in C^{\infty}(\Omega) \otimes \mathbb{R}_{0, m}$. Now we proceed by induction (from $j=2 n-2 k-1$ to $j=0$ ). Suppose that $D_{h} f_{j, k, l}=f_{j+1, k, l}$ and $f_{j, k, l}$ is Dunkl-polyharmonic in $\Omega$. Thus, using Lemma 4.7 and (4.16), we have $D_{h} f_{j-1, k, l}=f_{j, k, l}$. It follows that $f_{j-1, k, l}$ is Dunkl-polyharmonic in $\Omega$. Therefore, we obtain that $f$ is differentiable and that

$$
D f=-\sum_{k=0}^{n} \sum_{j=0}^{2 n-2 k-1} \underline{\underline{x}}^{j} \sum_{l} M_{k}^{l, j} D_{h} f_{j, k, l}+\sum_{k=0}^{n} \sum_{j=1}^{2 n-2 k} \sum_{l} \underline{\underline{x}}^{j-1} M_{k}^{l, j-1} f_{j, k, l}=0
$$

which implies that $f$ is super Dunkl-monogenic in $\Omega$.

### 4.4. Painlevé theorem for super Dunkl-monogenic functions.

Theorem 4.10. Let $\Omega$ be open in $\mathbb{R}^{m}$ and $\Omega^{\prime}$ be open in $\mathbb{R}^{m-1}$ such that $\Omega \cap \mathbb{R}^{m}=\Omega^{\prime}$. Let $f \in C^{0}(\Omega)_{m \mid 2 n} \otimes \mathcal{C}_{m \mid 2 n}$. If $f(x)$ is super Dunkl-monogenic in $\Omega \backslash \Omega^{\prime}$ and moreover continuous in $\Omega$, then $f(x)$ is super Dunkl-monogenic in $\Omega$.

Proof. Since $f(x)$ is super Dunkl-monogenic in $\Omega \backslash \Omega^{\prime}$, it follows by Theorem 4.9 that

$$
\begin{equation*}
\int_{\partial I} \int_{B} \alpha h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f-\int_{I} \int_{B}\left(\alpha D_{f}\right) f h_{k}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=0 \tag{4.18}
\end{equation*}
$$

for any closed interval $I \subset \Omega \backslash \Omega^{\prime}$. Suppose that a closed interval $I$ has the following form: $I=I^{\prime} \times\left[0, a_{0}\right]$, where $I^{\prime}$ is a closed interval contained in $\Omega^{\prime}$.

For $\varepsilon \in\left[0, a_{0}\right]$, we put $I_{\varepsilon}=I^{\prime} \times[0, \varepsilon]$. Then we have

$$
\begin{equation*}
\int_{\partial I_{\varepsilon}} \int_{B} \alpha h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f-\int_{I_{\varepsilon}} \int_{B}\left(\alpha D_{f}\right) f h_{k}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=0 . \tag{4.19}
\end{equation*}
$$

Due to linearity it suffices to prove this theorem for $f(x)=f_{1}(\underline{x}) f_{2}(\underline{x})$, where $f_{1}$ contains only commuting variables and $f_{2}$ contains only anti-commuting variables.

Then by the continuity of $f$, we have

$$
\begin{aligned}
\int_{\partial I_{\varepsilon}} \int_{B} \alpha h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f= & \int_{B} \alpha \int_{\partial I_{\varepsilon}} h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f_{1}(\underline{x}) f_{2}(\underline{\grave{x}}) \\
= & \int_{B} \alpha \int_{I^{\prime}}\left[f_{1}\left(\varepsilon+\underline{x}^{\prime}\right)-f_{1}\left(0+\underline{x}^{\prime}\right)\right] h_{\kappa}^{2}(\underline{x}) \mathrm{d} s f_{2}(\underline{\grave{x}}) \\
& +\int_{\partial I^{\prime} \times[0, \varepsilon]} \int_{B}\left(\alpha D_{f}\right) f h_{\kappa}^{2}(\underline{x}) \mathrm{d} V(\underline{x}),
\end{aligned}
$$

where $\mathrm{d} s=(-1)^{i-1} e_{i} \mathrm{~d} x_{1} \wedge \ldots \wedge \mathrm{~d} \hat{x}_{i} \ldots \wedge \mathrm{~d} x_{m}, i=1,2, \ldots, m$. It follows that

$$
\lim _{\varepsilon \rightarrow 0^{+}} \int_{\partial I_{\varepsilon}} \int_{B} \alpha h_{\kappa}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f=\int_{\partial I^{\prime}} \int_{B} \alpha h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f
$$

and

$$
\lim _{\varepsilon \rightarrow 0^{+}} \int_{I_{\varepsilon}} \int_{B}\left(\alpha D_{f}\right) f h_{k}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=\int_{I^{\prime}} \int_{B}\left(\alpha D_{f}\right) f h_{k}^{2}(\underline{x}) \mathrm{d} V(\underline{x}) .
$$

Thus, we have

$$
\begin{equation*}
\int_{\partial I^{\prime}} \int_{B} \alpha h_{k}^{2}(\underline{x}) \mathrm{d} \sigma_{\underline{x}} f-\int_{I^{\prime}} \int_{B}\left(\alpha D_{f}\right) f h_{k}^{2}(\underline{x}) \mathrm{d} V(\underline{x})=0 . \tag{4.20}
\end{equation*}
$$

It is easy to see that (4.20) holds for all $I^{\prime} \subset \Omega^{\prime}$. Therefore, we have the result from Theorem 4.9.

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