Bohdan Maslowski Stability and averaging properties of stochastic evolution equations

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## STABILITY AND AVERAGING PROPERTIES OF STOCHASTIC EVOLUTION EQUATIONS

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The theory of averaging for differential equations with quickly oscillating coefficients has been a subject of interest for many authors since early fifties, see e.g. [1] for ODE's, [2],[7] for stochastic differential equations. Recently the results from [7] on averaging in the quadratic mean have been extended to stochastic differential equations in a Hilbert space with unbounded drift terms and applied to stochastic PDE's ([5], [6]). In [5] some stability results are also included. They make it possible to find effective conditions guaranteeing the required averaging properties on an infinite time interval; however, they also may be of some independent interest.

In the present contribution the main results from [5],[6] are summarized. They are restated in a slightly less general, but more transparent form. Consider a parameter-dependent system of semilinear SDE's

$$\begin{array}{rcl} (1)_{\alpha} & dx_{\alpha}(t) = (Ax_{\alpha}(t) + f_{\alpha}(t, x_{\alpha}(t)))dt + \tilde{\varPhi}_{\alpha}(t, x_{\alpha}(t))dw_{t}, & t \geq t_{0}, \\ & & x_{\alpha}(t_{0}) = \varphi_{\alpha}, & \alpha \geq 0, \end{array}$$

in a real separable Hilbert space H, where A :  $H \rightarrow H$  is an infinitesimal generator of a strongly continuous semigroup  $S_t$ ,  $w_t$  is a K -- valued Wiener process on  $(\Omega, \mathcal{A}, \mathcal{P})$  with a nuclear covariance W (K - a real separable Hilbert space),  $f_{\alpha} : \mathbb{R}_+ \times H \rightarrow H$ ,  $\bar{\Phi}_{\alpha} : \mathbb{R}_+ \times H \rightarrow$  $\rightarrow \mathscr{L}(K, H)$  are measurable and satisfy

(2) 
$$\| f_{\alpha}(t,x) - f_{\alpha}(t,y) \| + \| \Phi_{\alpha}(t,x) - \Phi_{\alpha}(t,y) \| \leq \hat{k} \| x - y \| , \| f_{\alpha}(t,0) \| + \| \Phi_{\alpha}(t,0) \| \leq \hat{k} , t \in \mathbb{R}_{+}, x, y \in \mathbb{H} ,$$

for some  $\hat{K} > 0$  independent of  $\alpha$ . It is well known (see e.g. [3]) that under the above assumptions there exists a unique mild solution  $x_{\alpha}$  to (1) $_{\alpha}$ .

Theorem 1 ([6]). Assume

(3) 
$$\lim_{\alpha \to 0^+} \int_{t_1}^{t_2} S_{t_2-s}(f_{\alpha}(s+t_0,x)-f_0(s+t_0,x))ds = 0,$$

(4) 
$$\lim_{\alpha \to 0+} \int_{t_1}^{t_2} \operatorname{Tr}\left\{ (\Phi_{\alpha}(s+t_0,x) - \Phi_0(s+t_0,x)) W(\Phi_{\alpha}(s+t_0,x) - \Phi_0(s+t_0,x)) W(\Phi_{\alpha}(s+t_0,x) - \Phi_0(s+t_0,x))^* \right\} ds = 0$$

for all  $x \in H$ ,  $0 \leq t_1 \leq t_2$ , and  $\psi_{\alpha} \rightarrow \psi_0$ .

Then for any  $0 < T < \infty$  we have

(5)  $\lim_{\alpha \to 0^+} \sup_{t \in \langle t_{\alpha}, T \rangle} \mathbb{E} \| x_{\alpha}(t) - x_{\alpha}(t) \|^2 = 0 .$ 

In the finite-dimensional case it can be seen ([7]) that a similar statement is valid even for T = + $\infty$  provided the limit solution  $x_0$  is asymptotically stable. The proof from [7] fails for dim H =  $\infty$ , however, in [5] we prove the assertion imposing some restrictions on  $S_{\pm}$ .

<u>Definition.</u> A solution  $x_0$  of the equation (1)<sub>0</sub> is said to be asymptotically stable in the mean square if

- (i) for every  $\ell > 0$  there exists  $\delta > 0$  such that for all  $t_{\rho} \ge 0$  and all solutions  $\tilde{x}$  of (1) satisfying  $E \| \tilde{x}(t_{\rho}) x_{\rho}(t_{\rho}) \|^{2} < \delta$  we have  $E \| x(t) x_{\rho}(t) \|^{2} < \epsilon$ ,  $t \ge t_{\rho}$ ,
- (ii) there exists A>0 such that for all  $\varepsilon > 0$ ,  $\delta \in (0, A)$ there exists  $T = T(\varepsilon, \delta) > 0$  such that for all  $t_0 \ge 0$ ,  $\tilde{x}$ satisfying  $E \| \tilde{x}(t_0) - x_0(t_0) \|^2 < \delta$  we have  $E \| \tilde{x}(t) - x_0(t) \|^2 < \varepsilon$ ,  $t \ge t_0 + T$ .

<u>Theorem 2 ([5])</u>. Let (3), (4) be fulfilled uniformly w.r.t.  $t_0 \in \mathbb{R}_+$ and  $x \in \mathbb{H}$  and assume  $S_{(.)} \in \mathbb{C}((0, +\infty), \mathscr{L}(\mathbb{H})), \varphi_{x} \to \varphi_{0}$ . Then (5) is valid with  $T = +\infty$  provided  $x_0$  is asymptotically stable in the mean square and  $\mathbb{E} \| x_0(t) \|^2$  is bounded for  $t \ge t_0$ . In order to obtain effective results on infinite time intervals we still need verifiable criteria for mean-square asymptotic stability. The standard application of Liapunov method leads to some difficulties as the mild solutions of (1)<sub>0</sub> need not possess a stochastic differen-

tial. This can be overcome by approximating mild solutions by strong solutions similarly as in [4]. For  $v \in \mathfrak{l}_{1-2}(\mathbb{R}_+ \times \mathbb{H})$  set

$$\begin{split} &\mathcal{L}v(t,x,y) = \frac{\partial}{\partial t}v + \langle v_{x}(t,x-y), Ax-Ay+f_{0}(t,x)-f_{0}(t,y) \rangle + \frac{1}{2}\mathrm{Tr}(\Phi_{0}(t,x)-\Phi_{0}(t,y))^{*}v_{xx}(t,x-y)(\Phi_{0}(t,x)-\Phi_{0}(t,y))W , \quad (t,x,y) \in \mathbb{R}_{+} \times \mathcal{D}(A) \times \mathcal{D}(A) \end{split}$$

<u>Proposition 3.</u> Assume  $\mathcal{L}v(t,x,y) \leq \varphi(t,v(t,x-y))$ ,  $t \in \mathbb{R}_+$ ,  $x,y \in \mathcal{D}(A)$ , where  $v \in \mathbb{C}_{1,2}(\mathbb{R}_+ \times H)$  is such that

$$d_1 \| x \|^2 \leq v(t,x) \leq d_2 \| x \|^2 , \| v_x \| + \| v_{xx} \| \leq d_3 (1 + \| x \|^p), \quad x \in H ,$$

for some  $d_1$ ,  $d_2$ ,  $d_3$ , p > 0 and  $\varphi : \mathbb{R}^2_+ \to \mathbb{R}$  is measurable,  $\varphi(t, .)$  is Lipschitzian and concave,  $\varphi(t, 0) = 0$  for all  $t \ge 0$ . Then all solutions  $x_0$  of  $(1)_0$  are asymptotically stable in the mean square provided the trivial solution  $x \equiv 0$  of the equation  $\dot{x} = \varphi(t, x)$  is asymptotically stable.

Example. The stochastic parabolic problem described by

(6) 
$$\frac{\partial u_{\ell}}{\partial t} = \Delta u_{\ell} + \frac{r_1(t/\epsilon)u_{\ell}}{1+|u_{\ell}|} + \frac{r_2(t/\epsilon)u_{\ell}}{1+|u_{\ell}|}\dot{w}(t,x) , t \ge t_0 , x \in D$$

 $(D - a bounded region in <math>\mathbb{R}_n$  with  $\mathbb{C}_2$  boundary),  $u_{\epsilon}(0,x) = u_0(x)$ ,  $u_{\epsilon}|_{\partial D} = 0$  can be formally rewritten in the form

(7) 
$$dx_{\varepsilon}(t) = (Ax_{\varepsilon}(t) + f(t/\varepsilon, x_{\varepsilon}(t)))dt + \oint (t/\varepsilon, x_{\varepsilon}(t))dw_{t}, x_{\varepsilon}(t_{o}) = \varphi_{\varepsilon},$$

in the space H = L<sub>2</sub>(D), with K = H<sup>K</sup>(D) - valued Wiener process w<sub>t</sub> (k > 2n), where A =  $\Delta | H^2(D) \cap H_0^1(D)$ , f(t,x)(0) = r<sub>1</sub>(t)x(0). .(1+|x(0)|)<sup>-1</sup>,  $\Phi(t,x)h(0) = r_2(t)x(0)h(0)(1+|x(0)|)^{-1}$ ,  $0 \in D$ ,  $h \in K$ . Assume

$$\frac{1}{T} \int_{\beta T}^{\beta T+T} r_1(t) dt \rightarrow r_1 , \quad \frac{1}{T} \int_{\beta T}^{\beta T+T} (r_2(t)-r_2)^2 dt \rightarrow 0 , \quad T \rightarrow \infty$$

uniformly in  $\beta \ge 0$  for some  $r_1, r_2 \in \mathbb{R}$ , and  $-\lambda_0 + \max(0, r_1) + 1/2 r_2^2 k^2 Tr W < 0$ , where  $\lambda_0 > 0$  is the first eigenvalue of -A and k > 0 is such that  $\| \|_{\Gamma(D)} \le k \| \|_{K}$ . Then it can be checked that Theorem 2 and Proposition 3 yield

$$\sup_{\mathbf{t} \ge \mathbf{t}_0} \mathbb{E} \| \mathbf{x}_{\boldsymbol{\ell}}(\mathbf{t}) - \overline{\mathbf{x}}(\mathbf{t}) \|^2 \to 0 \quad \text{as} \quad \boldsymbol{\ell} \to 0 \quad , \quad \boldsymbol{\varphi}_{\boldsymbol{\ell}} \to \overline{\boldsymbol{\varphi}} \; ,$$

where  $\overline{x}$  is the solution of the limit equation  $d\overline{x} = (A\overline{x} + r_1\overline{x}/1 + |\overline{x}|)dt$ ,  $(r_2\overline{x}/1 + |\overline{x}|)dw_t$ ,  $\overline{x}(t_0) = \overline{\phi}$  (see [5] for a similar example).

<u>Remark.</u> Some extensions of the above results (e.g. averaging in  $L_p(\Omega)$  for  $p \ge 2$ , averaging in probability, statements analogous to Theorems 1, 2 for a cylindrical Wiener process, etc.) can be found in [5],[6].

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102